# CS 312: Artificial Intelligence Laboratory

# Task 2: Heuristic Search Algorithms

Choose a domain of your choice and compare, analyze and efficiently implement the following search algorithms:

Enter the domain opted <u>here</u>.

Note: Each group should select different domains. Domains will be allocated on FCFS basis. Deadline to finalize domains 6: 00 pm 16 Jan 2020.

#### 1. Best First Search:

Try out a minimum of 2-3 different heuristic functions and compare the results with valid reasoning. Use a priority queue for the OPEN list to make it computationally efficient.

## 2. Hill Climbing:

With a slight modification of code, implement Hill Climbing for the chosen domain.

3. Variable neighborhood descent:

Modify Hill-Climbing Search to switch to a denser neighborhood function when stuck at a local optimum.

#### 4. Beam Search:

Code for different beam lengths and find the optimum beam length in terms of:

- a. Time Complexity
- b. Space Complexity
- c. Closest to the goal node

#### 5. Tabu Search:

Implement tabu search and find an optimum tabu tenure value for your domain.

For tasks 3, 4, and 5: If the chosen domain is not compatible with Solution Space Search, implement for a basic SAT problem.

#### **Evaluation Criteria:**

Choosing an appropriate Domain: 5

Correctness: 15 Report: 20

Code Quality: 5

Viva: 5

Deadline: 11:59 PM 21 Jan 2020

**Late Submission Policy:** 5% of marks will be deducted per day late. **For Reference:** 

Heuristic search: <a href="https://youtu.be/dtGRmhZ6Cuo">https://youtu.be/ZOVRZ7UJMjk</a>
Beam Search: <a href="https://youtu.be/Fioj-Zx-PHA">https://youtu.be/Fioj-Zx-PHA</a>
Tabu Search: <a href="https://youtu.be/wrkMM6a4S-U">https://youtu.be/wrkMM6a4S-U</a>

## Report Format:

- 1. Brief description about the domain:
  - a. State space
  - b. Start node and goal node
  - c. MOVEGEN and GOALTEST algorithm
- 2. Heuristic functions considered (minimum of 2)
- 3. Best First search analysis and observation
- 4. Hill Climbing and Best First search comparison in terms of:
  - a. States explored
  - b. Time taken
  - c. Reaching the optimal solution.
- 5. Beam search analysis for different beam lengths
- 6. Tabu search for different values of tabu tenure
- 7. Comparison of Variable neighborhood descent, Beam Search, Tabu Search