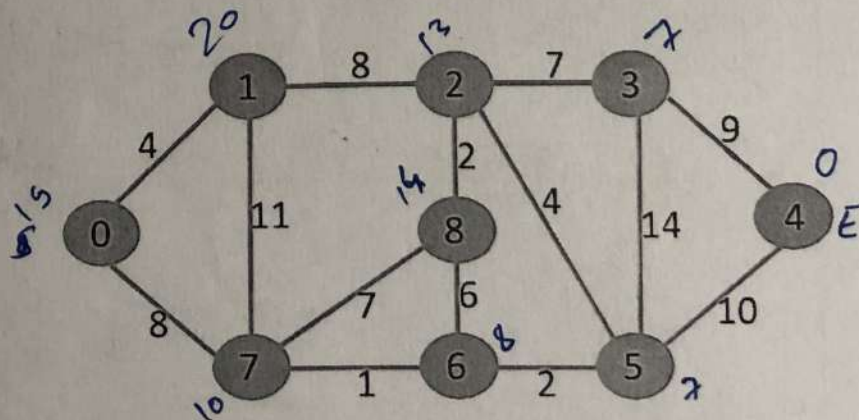


Section – A (10 x 5 = 50 Marks)

- | S.No. | Question |
|-------|---|
| 1 ✓ | Describe the task environment for self-driving car and part picking robot. Provide proper justification for your claims. |
| 2 ✓ | Consider the Water Jug problem as stated here: "You are given two jugs, a 4-gallon one and a 3-gallon one. Neither have any measuring markers on it. There is a pump that can be used to fill the jugs with water. How can you get exactly 2 gallons of water into the 4-gallon jug?" Represent this as a problem in State Space Search and state its Production Rules. Show at least one solution to this problem. Why is 'depth limited search' necessary in DFS? |
| 3 ✓ | Explain Steepest ascent Hill climbing algorithm. Discuss the situations under which Hill Climbing may fail to find a solution. What can be done to overcome these situations? |
| 4 ✓ | State the significance of using heuristic functions. Perform A* search algorithm on the graph given below taking node '0' as the starting node and give the proof of optimality. |



Heuristics: $h(0)=19$; $h(1)=20$; $h(2)=13$; $h(3)=7$; $h(4)=0$; $h(5)=7$; $h(6)=8$; $h(7)=10$; $h(8)=14$.

$\boxed{4}$ $\boxed{3}$

$S(x, y)$

$\frac{1}{2}$
 $\frac{1}{2}$
 $\frac{1}{2}$

5

Consider the game tree in which the static scores are from first player's point of view. Suppose the first player is maximizing player. Applying mini-max search, show the backed-up values in the tree. What move will the MAX choose? If the nodes are expanded from left to right, what nodes would not be visited using alpha-beta pruning.

