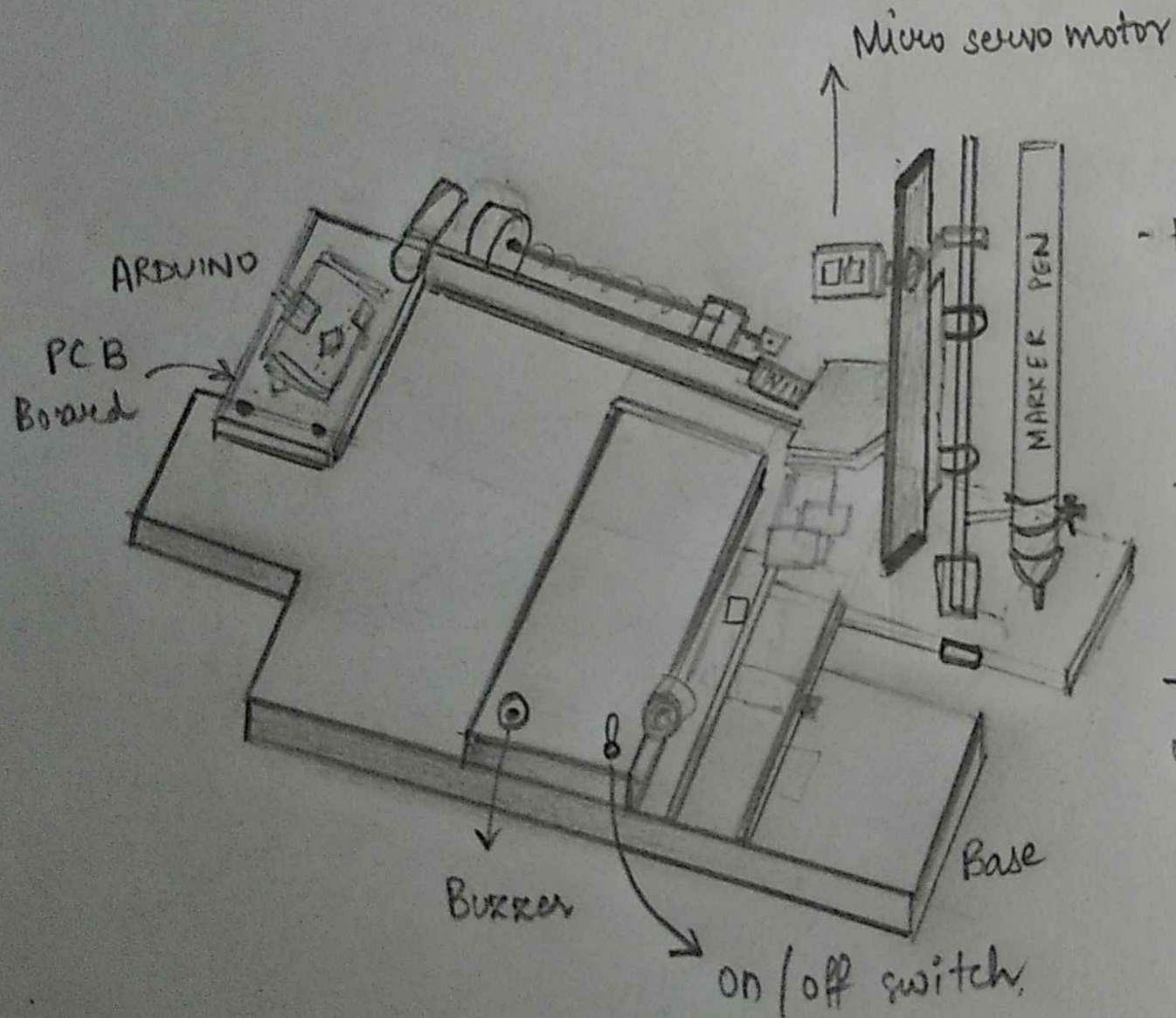


Name : Shashvi Jain

Roll no : 1512

Grv : '0'



- Holding pen using edge clamping
- movement of the bot using linear actuators

- IR sensor is used to sense the surface