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Training Session 1: Introduction to Modelica

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Oak Ridge, TN

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U.S. DEPARTMENT OF ENERGY

Modelica I (60 Minutes)

- Overview (5 min)
- Integrated Development Environments (5 min)
- Workflow (10 min)
- Model Creation: Equation and Parameters (10 min)
- Hands-On Example 1: A Simple ODE (30 min)

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Overview

- 5 minutes of general introduction to the Modelica programming language

The Future of "___" Covers a Large Array of Applications

What will be required of modeling and simulation tools?

Flexible and Adaptable

- Tools must be able to be used for a variety of applications
- Tools must be modifiable for new uses

- Advanced Reactor Technologies
  - HTGRs, LMRs, MSRs
- Integrated Energy Systems
  - Desalination, Hydrogen, Oil-recovery

Rapid Development

- Users need the ability to "fail fast" and mature analysis
- Modeler has control over level of fidelity

- Deployable on a range of machines
  - PCs, clusters
- Advanced languages and features
  - Python, Modelica
  - Acausal, object-oriented

Collaborative

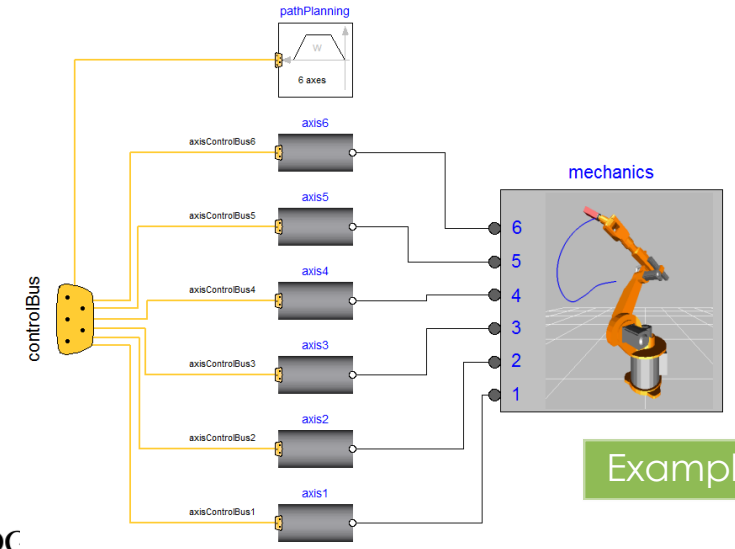
- Domain expertise shareable to leverage skill sets
- Models able to communicate with other tools and frameworks

- Models should be shareable/exportable
  - Open-source or "black-box" capable
- Ability to integrate at different "scales"
  - System, CFD

Modelica is …

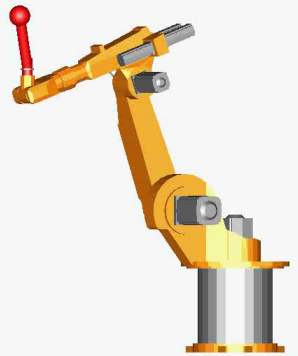
Equation Based (acausal)

- Order of computations is not decided at modeling time
- Equations do not specify input/outputs
  - $x + y = z^x + yz$
- Solutions direction adapts to data flow



Built for Dynamic Problems

- Time integration handled by solver
  - $der(v) = a + bx(t)$

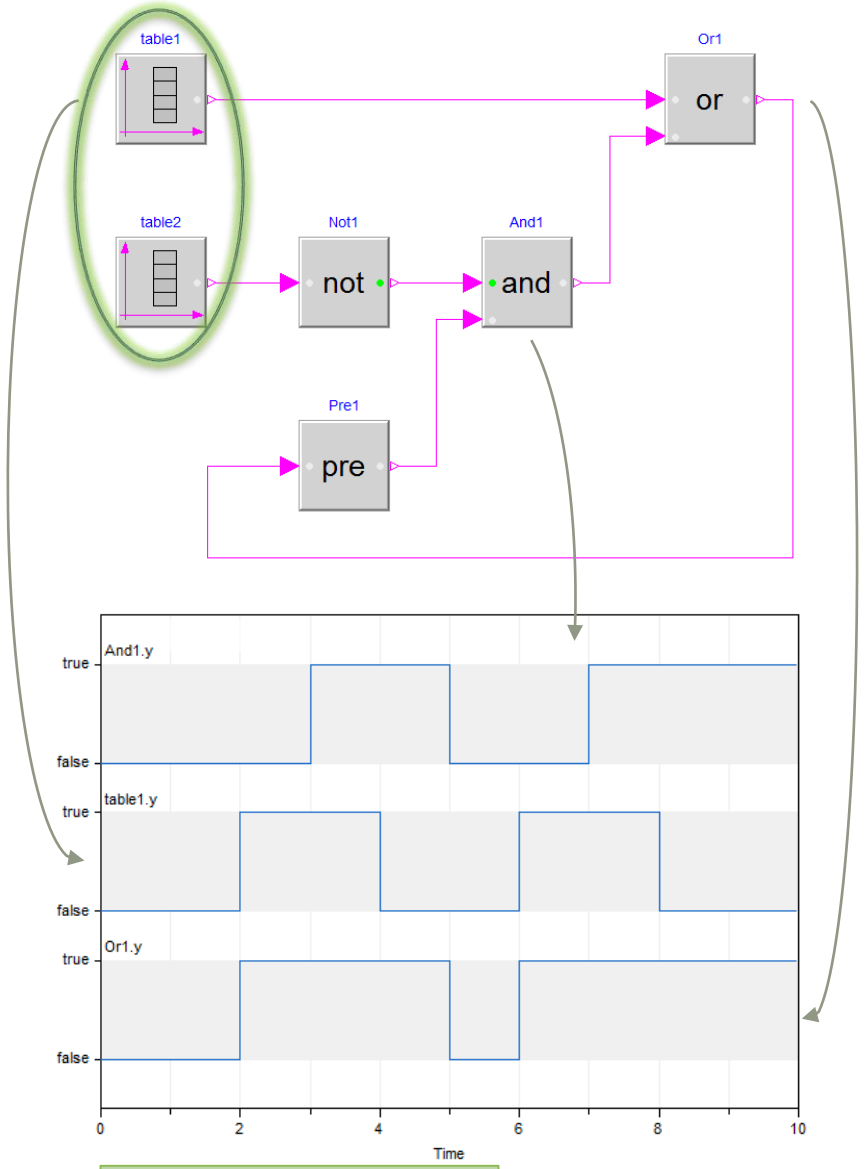


Example from the Modelica Standard Library

Simple Example of Dynamics

- Time dependent aspects of a system
- Concerned with concepts of:
  - States: Attributes described at a point in time
  - Events: Occurrences that trigger a state transition
  - Transitions: A change in the state of an object
  - Actions: Instantaneous operation that results due to an event
  - Activities: Ongoing operations upon the state of an object

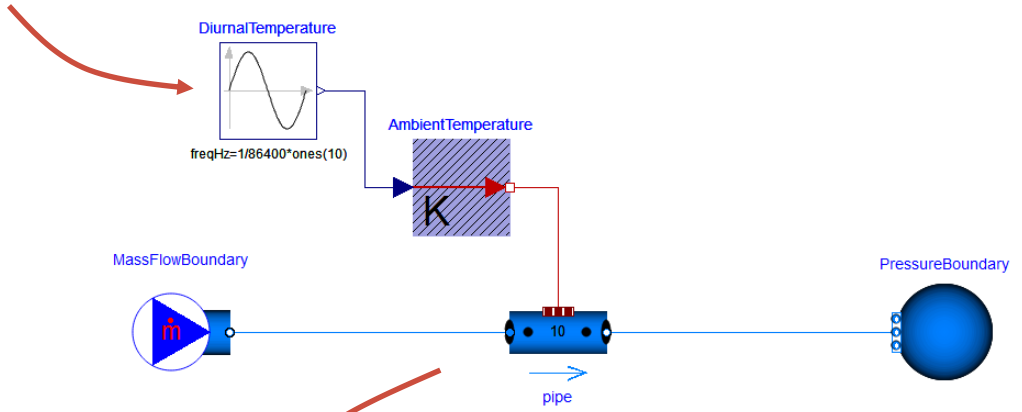
Table values change with time



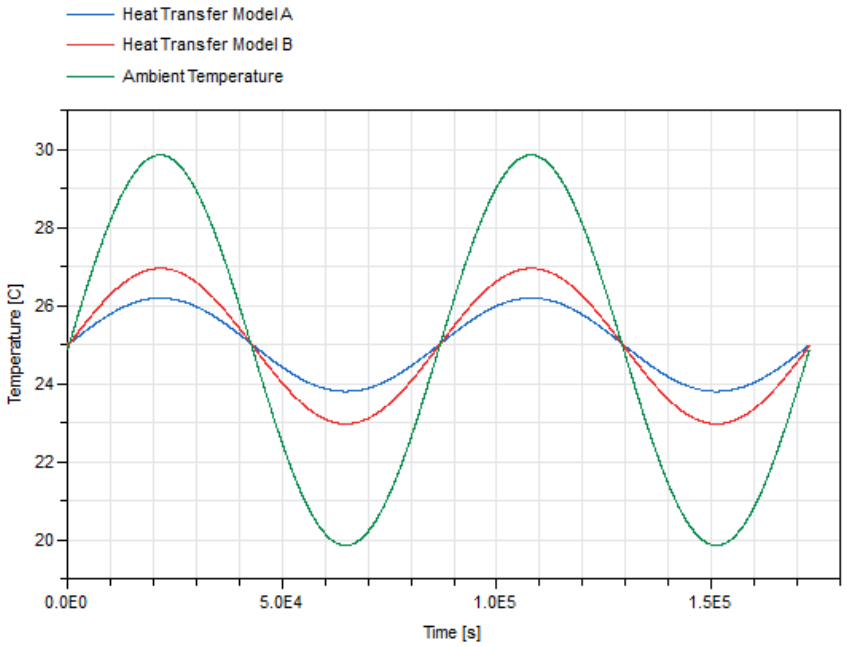
Example of a dynamic problem

“Replaceable” Model Concept

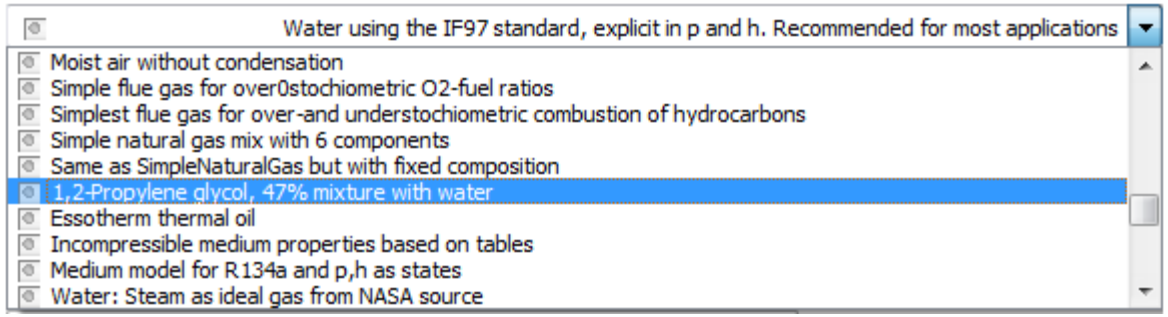
A pipe subjected to cyclic ambient temperature



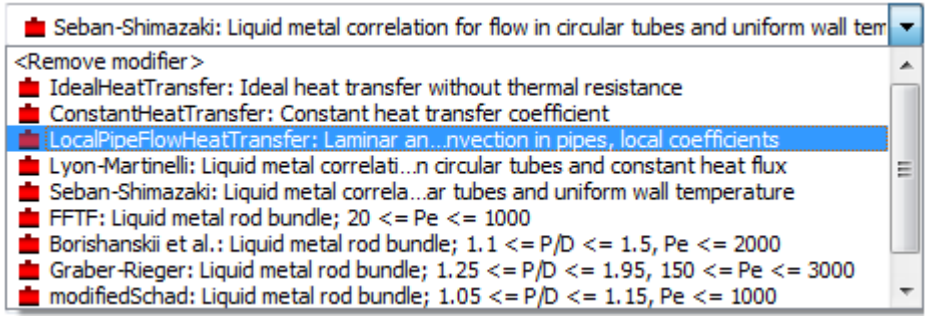
Simulate



Double click on the component of interest and change the fluid or heat transfer correlation



Fluid Media



Heat Transfer Correlation

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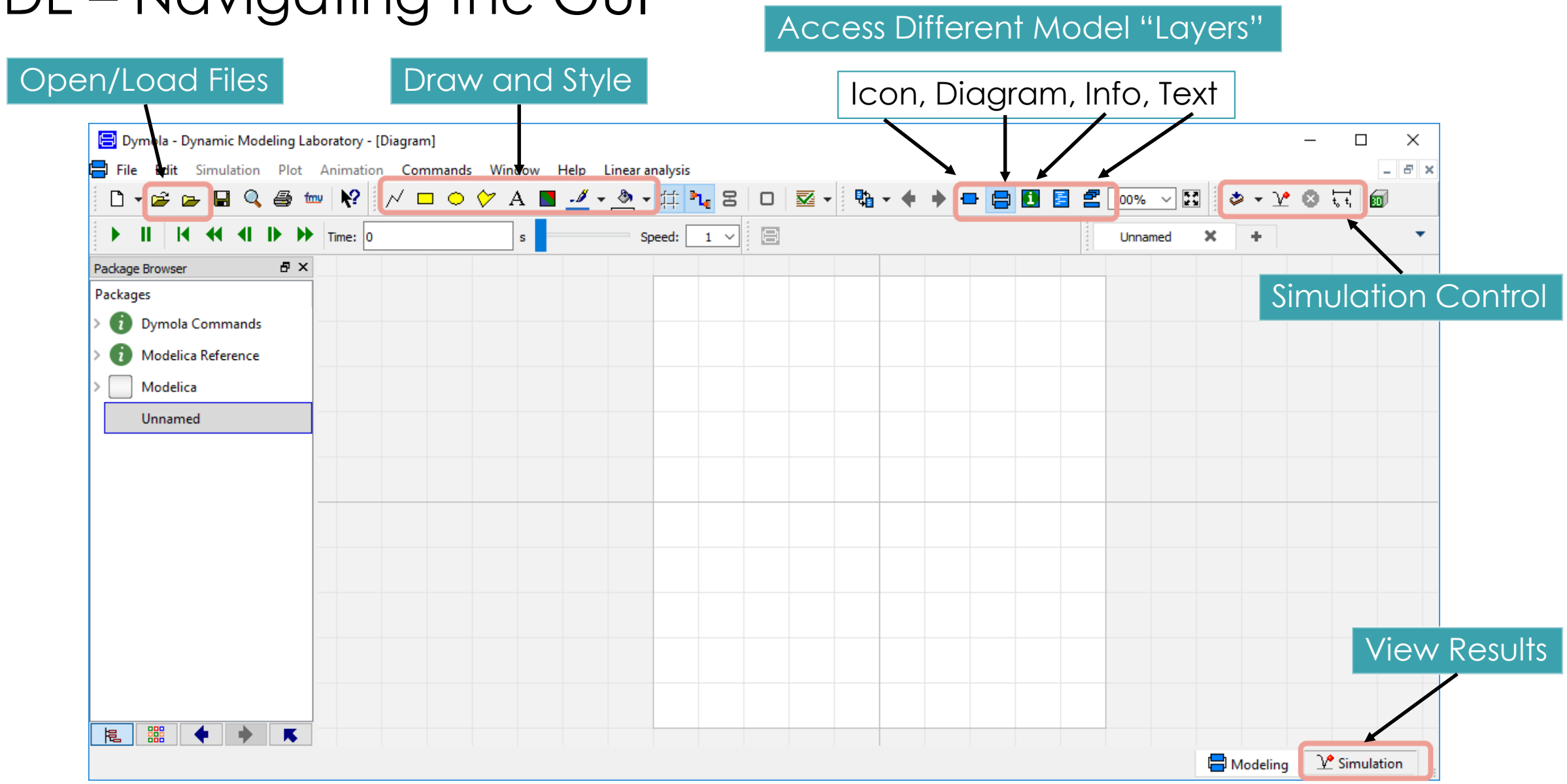
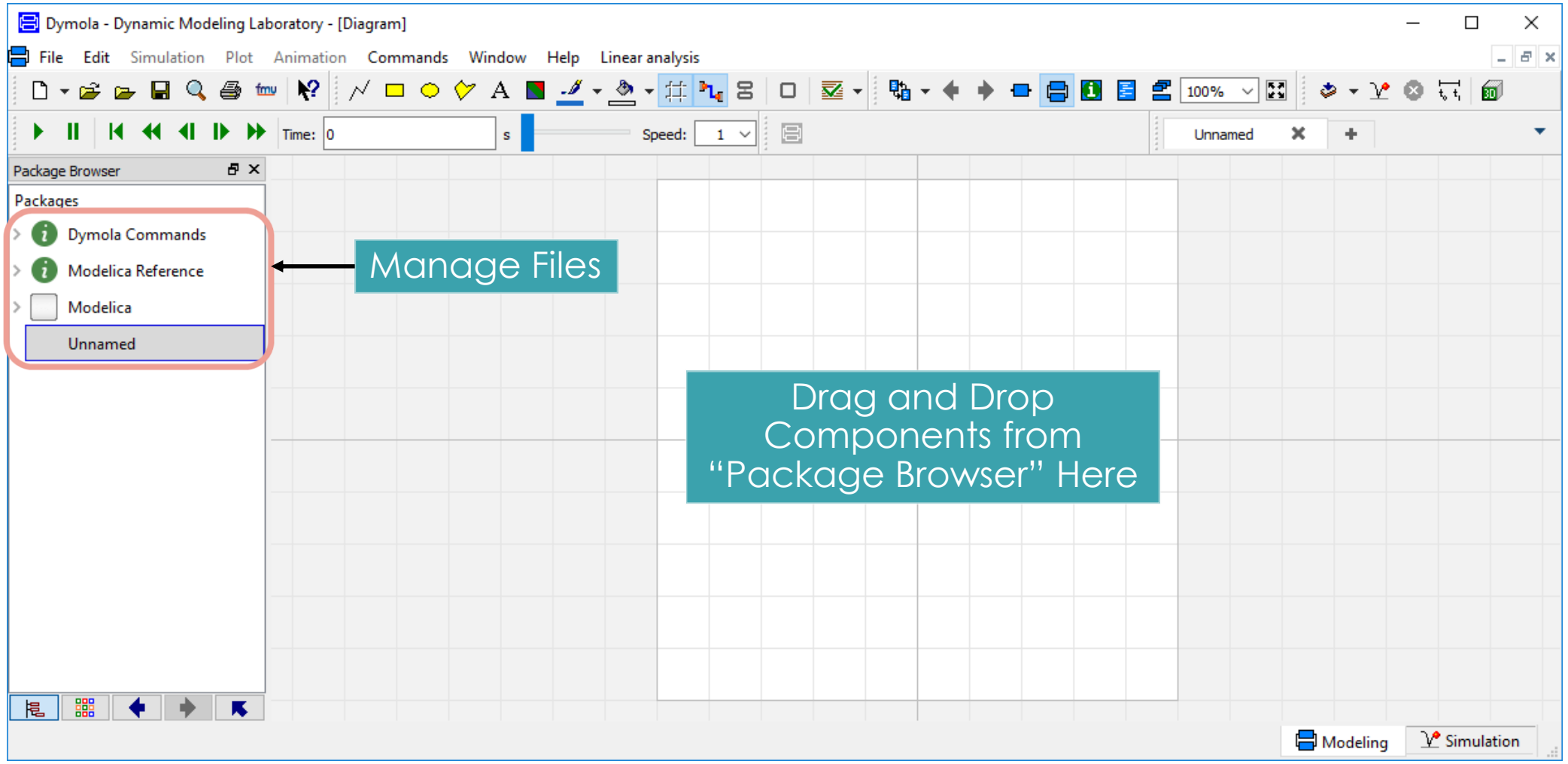
Integrated Development Environments

- 5 min - icon, diagram, info, code, GUI, parameter GUI, editor, command shell, package browser, result viewer, model creation
- Several modeling environments available
  - https://www.modelica.org/tools
- Dymola (Dassault Systemes)
  - The IDE used in this training

IDE – Navigating the GUI



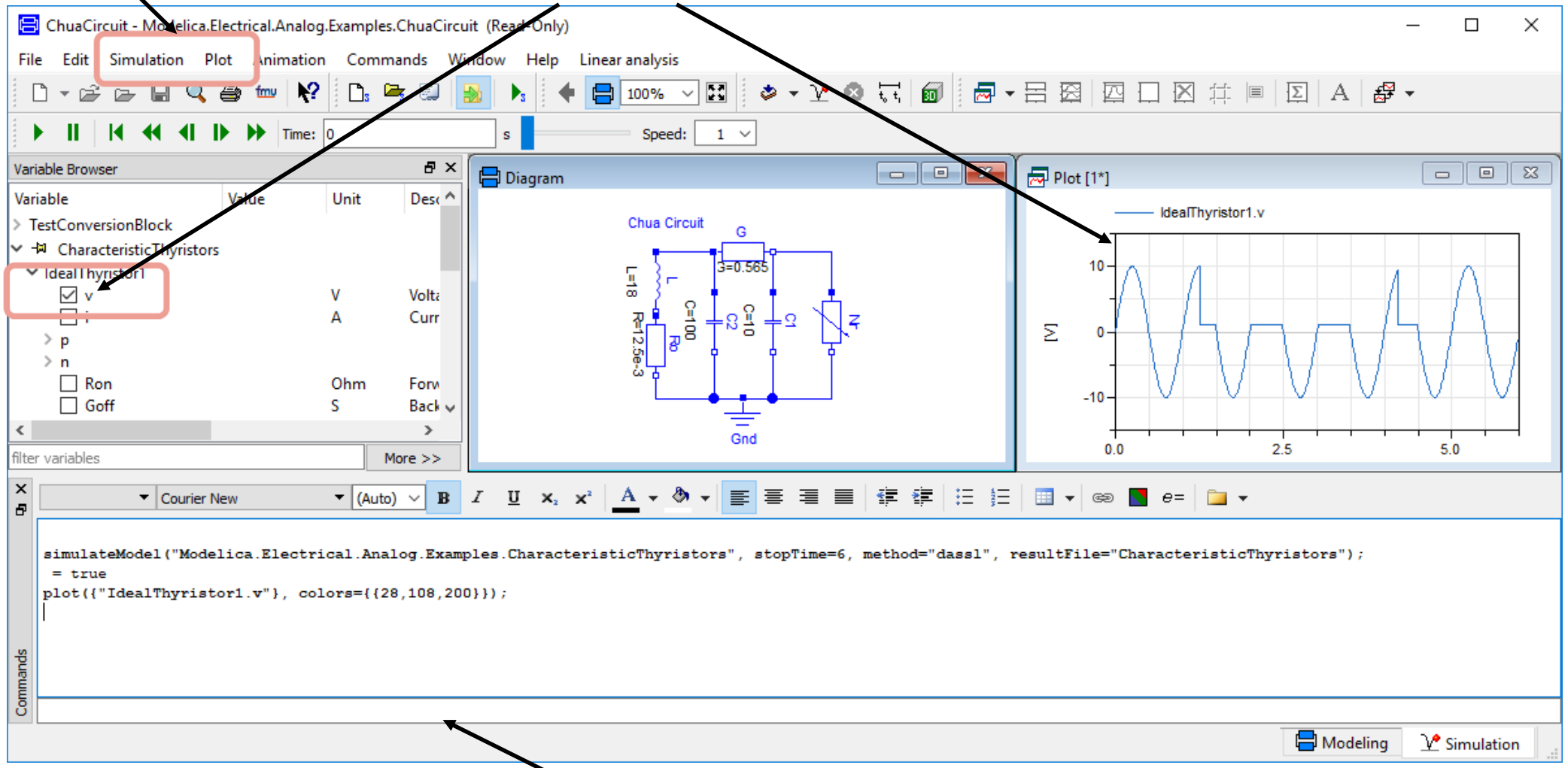
IDE – Navigating the GUI



IDE – Navigating the GUI

Load Results/Run Scripts

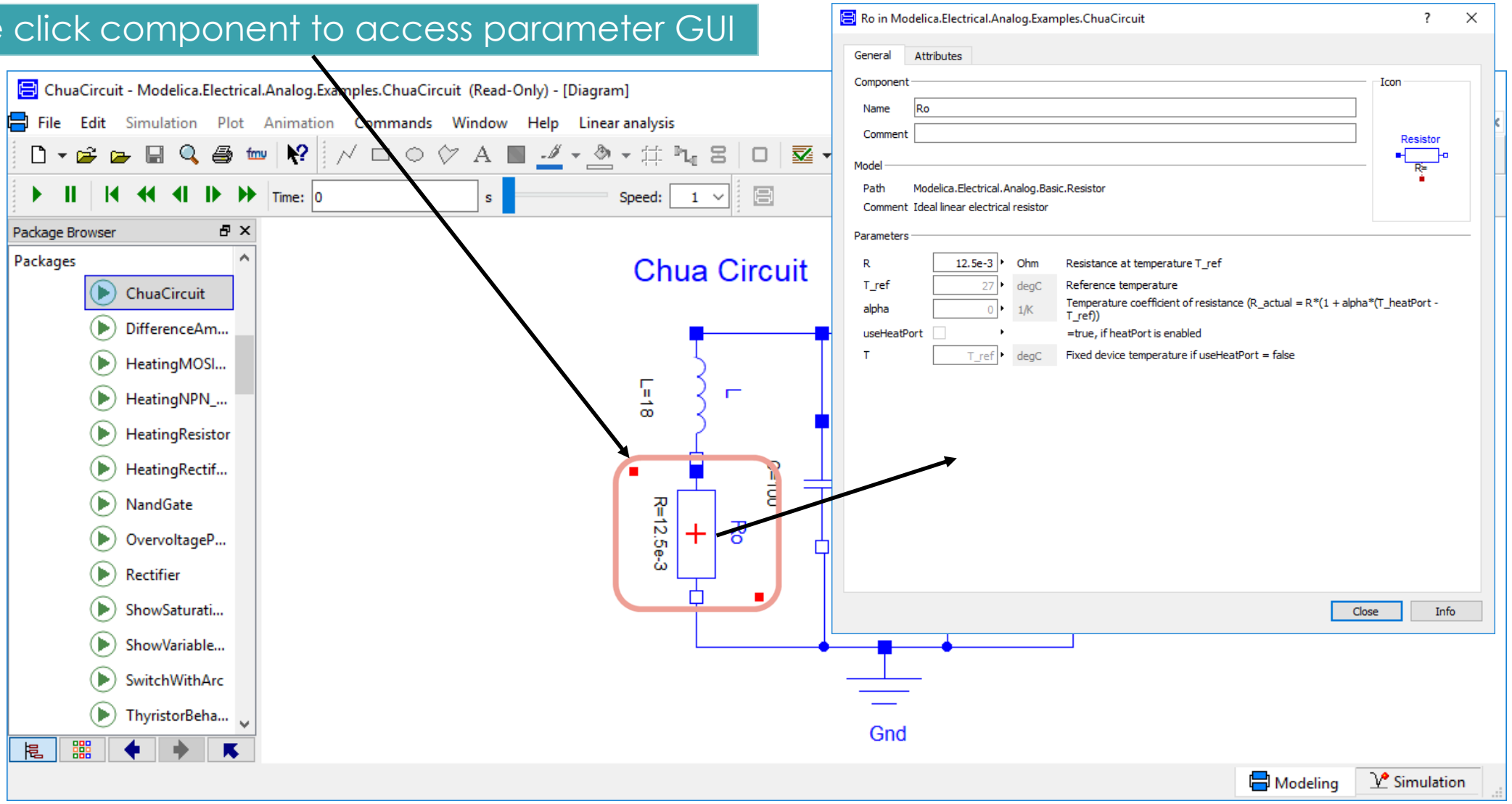
Plot Results



Command Terminal

IDE – Parameter GUI

Double click component to access parameter GUI



Workflow

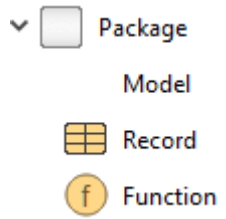
- 10 min - packages, code, translate, compile, sim settings, solve, view results

Workflow – Current Working Directory

- Current working directory
  - Upon simulation, all files are generated in the current working directory
  - Recommend a dedicated working directory for results (i.e., /Documents/Dymola)
- Open vs Load
  - Open: Changes the current working directory to the location of the file opened
  - Load: Adds the file to the path… keeps the current working directory unchanged

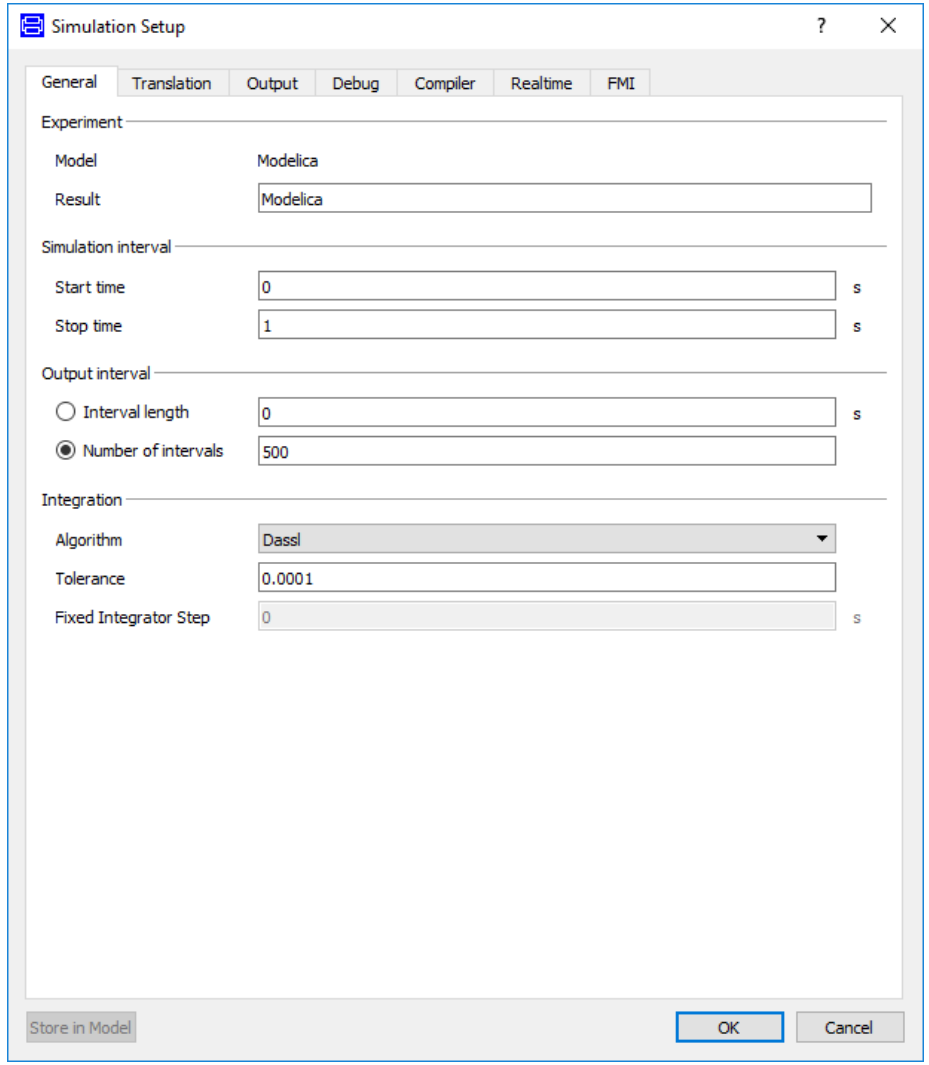
Workflow – Common Classes

- Difference between
  - Package
    - Analogous to folder or directory
  - Model
    - Principle method for creating models
    - Location of “equation” section
  - Function
    - Behaves similar to traditional programming languages (e.g., Matlab)
    - *imperative* – used only for special cases
    - Location of “algorithm” section
  - Record
    - Used to define common types that are reused in various locations
    - e.g., common input parameters to multiple models

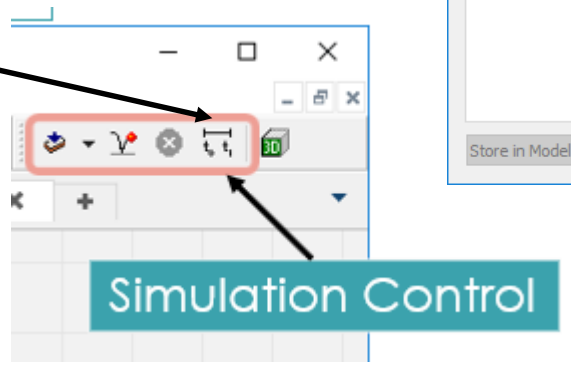


Workflow – Simulation Settings

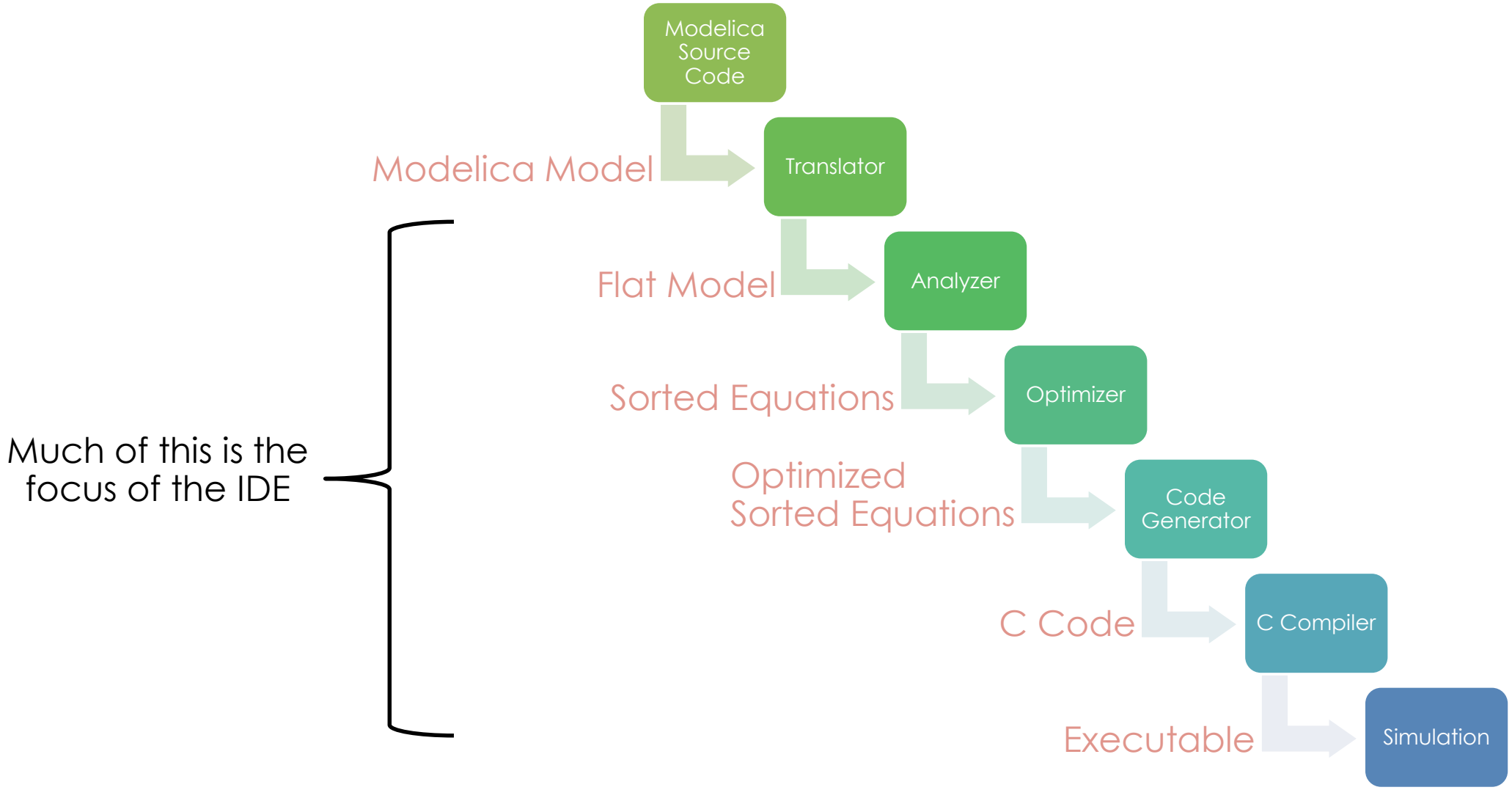
- Variety of options
  - Start/Stop, intervals, solver, global tolerance
  - Translation/Debug flags
  - Change compiler
  - Realtime and Model Export (FMI) options



Click here to control simulation settings



Workflow – What happens when you push "simulate"?



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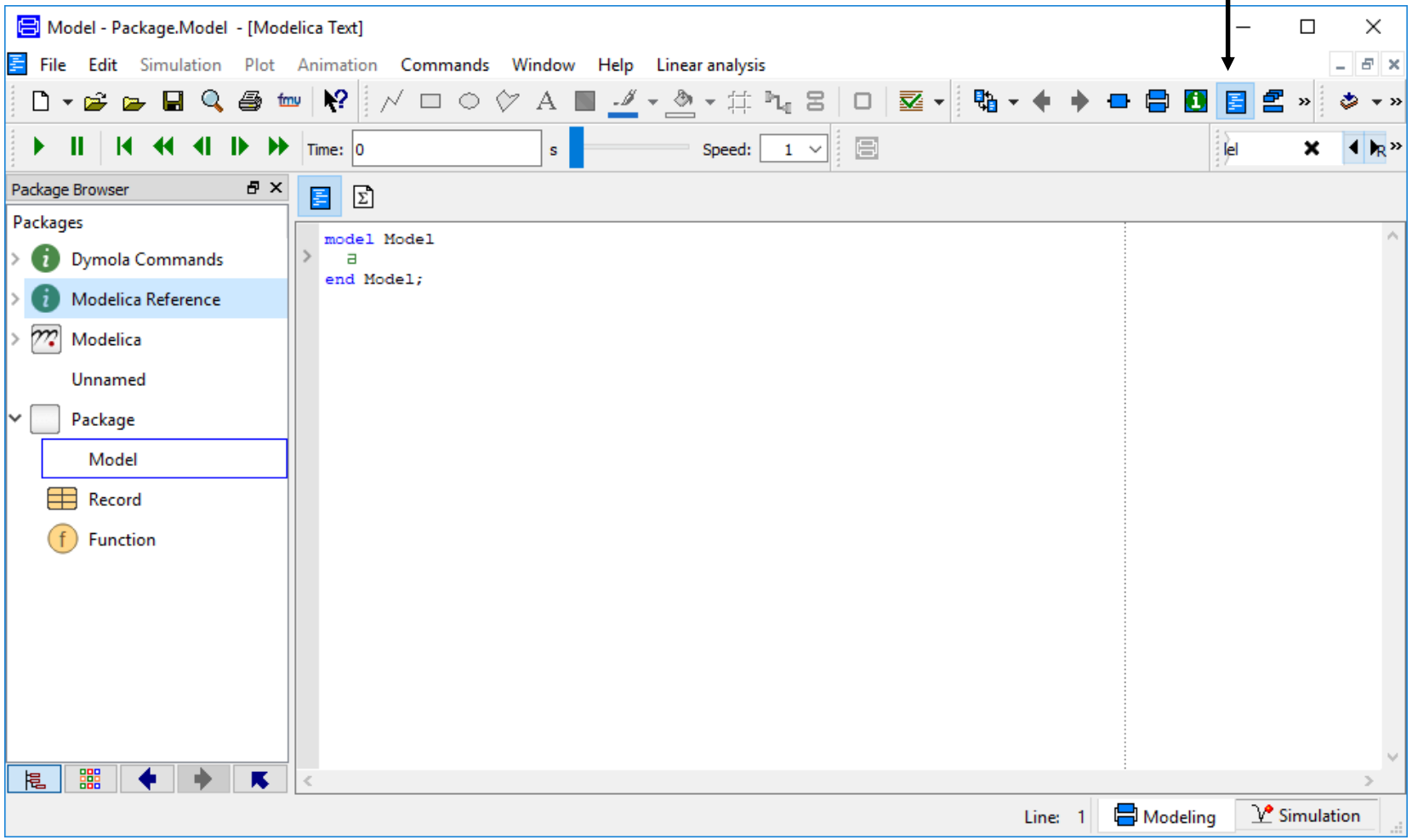
Model Creation: Equation and Parameters

- 10 min - code sections (param, init, eqn), defining parameters, units, equations, initial (start vs init eqn.), der()

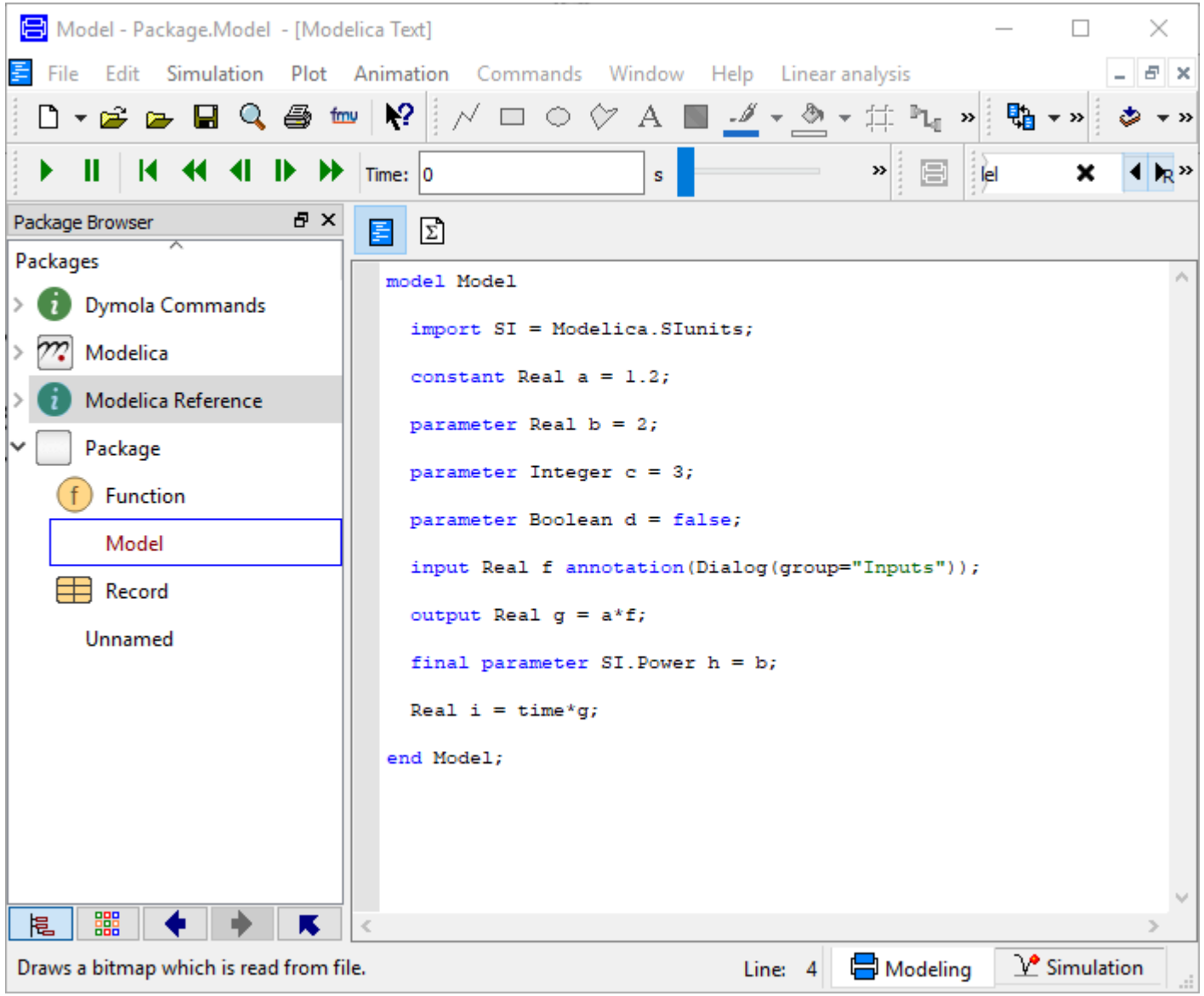
Model Creation: Working in the Text Editor

Click here to change to text editor



Model Creation: Variable classes and types

- Classes
  - constant
  - parameter
    - normal and “final”
  - input
  - output
  - unspecified
- Types
  - Real
    - Can define types for units
  - Boolean
  - Integer
- Annotations
  - GUI/translation related

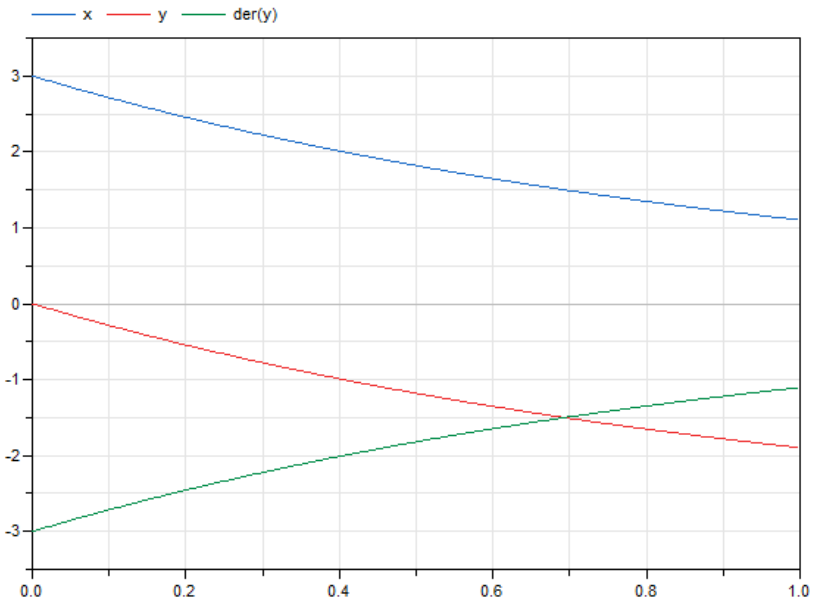


Model Creation: equation and algorithm section

- Equation:
  - Can be used in "model" class
  - Acausal (engineering type equation)
  - Allows translator/solver freedom to manipulate equations
  - Workhorse section for Modelica… default use this over algorithm/functions

```
model Demo

  Real x;
  Real y;

algorithm
  x := y+3;

equation

  der(y) = -x;

end Demo;
```

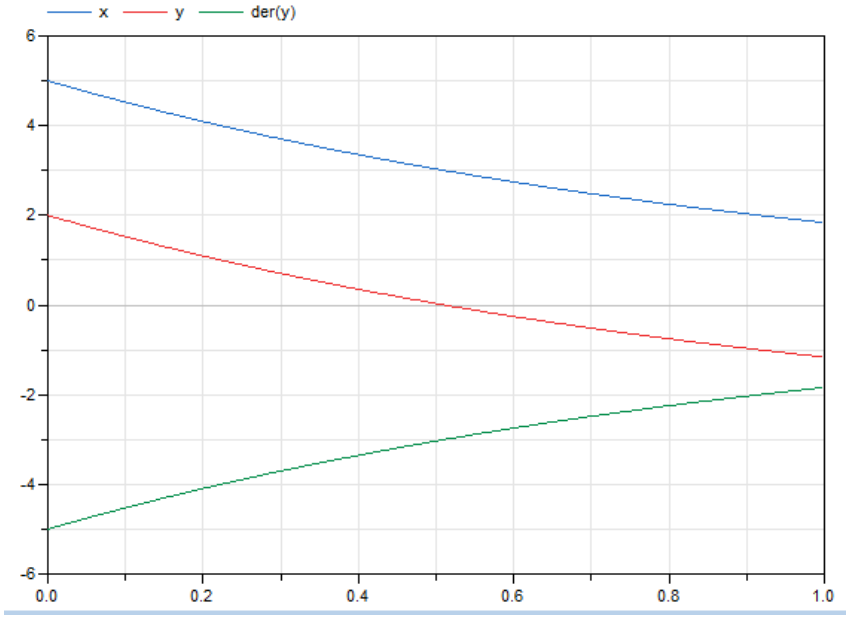
- Algorithm
  - Can be used in "model" and "function" class
  - Causal
  - Limits on what the translator can do with equations
  - Can increase solution time/reduce model robustness
  - Sometimes necessary (initialization)



Model Creation: der(), start, and initial equation

- der()
  - Built-in operator for specifying the derivative of the variable
  - "time" is the built-in/associated variable
- start
  - Allows the user to define the initial value
  - Can have a soft (guess) or fixed start value
- initial equation
  - Each variable with a derivative should have a start value
  - Default start value is 0 or der() = 0
  - This sections causes a "fixed" start value
  - Can have der() = 0 be defined

```
model Demo

  Real x(start=2,fixed=false); //false is default
  Real y;

algorithm
  x := y+3;

initial equation
  y = 2;

equation

  der(y) = -x;

end Demo;
```



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Hands-On Examples:

Code Based

- 30 min - attendees are given a description of a physical system and provided the mathematical expression and asked to convert to Modelica, practice with troubleshooting, view results, play with simulation settings

Guide to Modeling

- Start simple and gradually build complexity
  - Don't jump to the end!
- Steps:
  1. Define the equation
  2. Define the variables
  3. Set initial or "start" values
  4. Give values to parameters
  5. Simulate
  6. Extend/adapt as needed

Example 1: A Simple ODE

This example will introduce the user to:
- defining parameters and variables,
- initializing state variables,
- writing ODEs,
- specifying annotations, and
- controlling simulation length

- Try coding a Lorenz System:

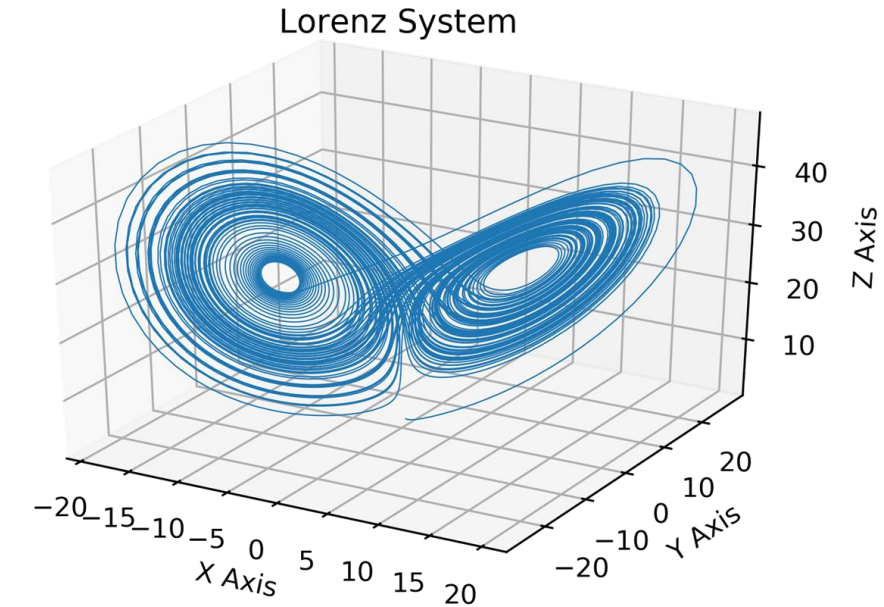
$$\frac{dx}{dt} = \sigma(y - x)$$

$$\frac{dy}{dt} = \rho x - y - xz$$

$$\frac{dz}{dt} = xy - \beta z$$

```
model LorenzSystem

  parameter Real sigma = 1;
  parameter Real rho = 1;
  parameter Real beta = 1;

  parameter Real x_start = 1 "Initial x-coordinate";
  parameter Real y_start = 1 "Initial y-coordinate";
  parameter Real z_start = 1 "Initial z-coordinate";

  Real x "x-coordinate";
  Real y "y-coordinate";
  Real z "z-coordinate";

initial equation
  x = x_start;
  y = y_start;
  z = z_start;

equation

  der(x) = sigma*(y-x);
  der(y) = rho*x - y - x*z;
  der(z) = x*y - beta*z;

end LorenzSystem;
```

$$\sigma = 10; \rho = 28; \beta = 8/3$$
$$x(0) = 0; y(0) = 1; z(0) = 1.05$$



Mathematical Model

Implementation in Modelica

Solution
(plotted with Python)

https://en.wikipedia.org/wiki/Lorenz_system

Example 2: Time to Cool Off

This example introduce the user to:
- specifying units (i.e., importing),
- using custom function (i.e., for unit conversions),
- providing comments to parameters and variables,
- booleans,
- adding components to models, and
- using "if" logic

- Try coding a Newton Cooling problem:

$$m * c_p * \frac{dT}{dt} = h * A * (T_{ambient} - T)$$

$m = mass$

$c_p = specific\ heat\ capacity$

$T = temperature\ of\ lumped\ mass$

$T_{ambient} = ambient\ temperature$

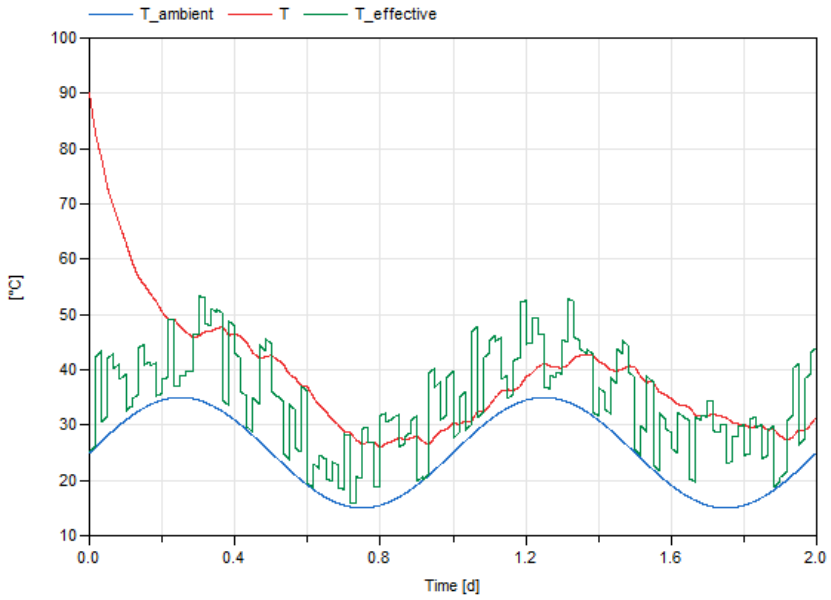
$t = time$

$h = heat\ transfer\ coefficient$

$A = surface\ area$

$h = heat\ transfer\ coefficient$

Challenge Problem:
Try adding a time dependent shape and noise to the ambient temperature?



Example 3: Let There Be decay!

This example will introduce the user to:
- arrays/matrices,
- "for loops", and
- alternative means to specify units

- Try coding Bateman Equations:

$$\frac{dN_1}{dt} = \phi\sigma_1 - \lambda N_1$$

$$\frac{dN_{i..n}}{dt} = \phi\sigma_i - \lambda N_i + \lambda_{i-1}N_{i-1} \qquad for\ i = 2 \ldots n$$

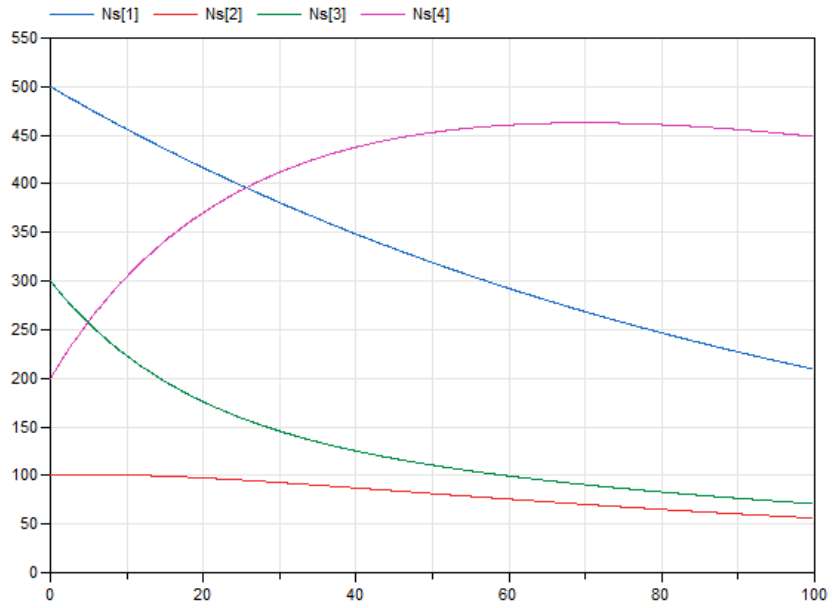
$N_i = atoms\ of\ isotope\ i$

$\phi = flux$

$\sigma = cross\ section$

$\lambda = decay\ constant$

$t = time$



This example will introduce the user to:
- Input connector

Example 4: Aliens vs. Predator!

- Try coding a Lotka-Volterra System:

$$\frac{dx}{dt} = \alpha x - \beta xy + u$$

$$\frac{dy}{dt} = \delta xy - \gamma y$$

$x = Prey\ (Aliens)$

$y = Predator$

$\alpha = prey\ population\ growth$

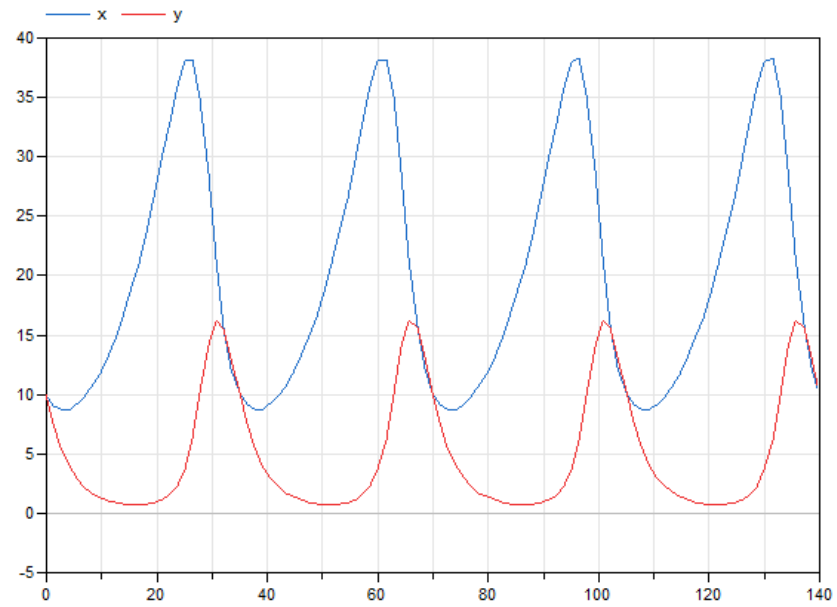
$\beta = predation$

$\delta = predator\ growth$

$\gamma = predator\ death$

$u = input\ connector$

Modelica.Blocks.Interfaces.RealInput



Hands-On Examples:

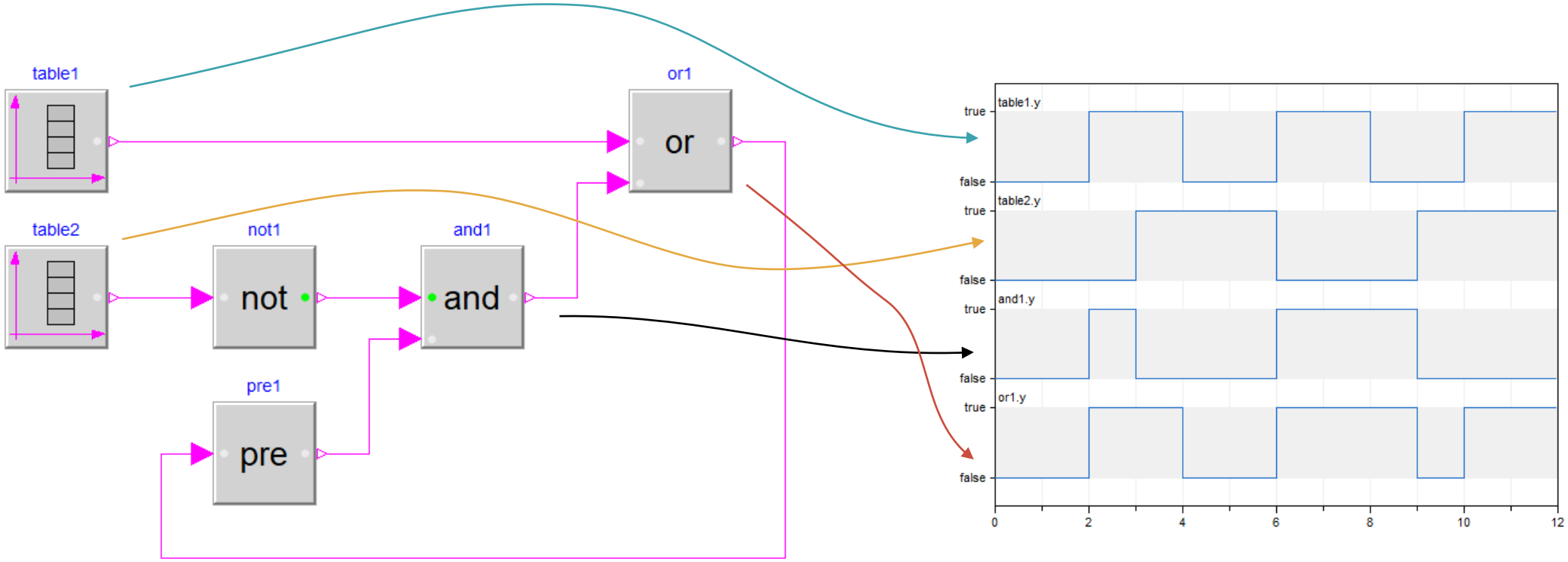
Component Based

- 10 min – attendees get familiar with navigating "packages" to select components and connect to solve simple problems

Example 1: True or False?

This example will introduce the user to:
- Drag and drop components
- Modelica.Blocks.*

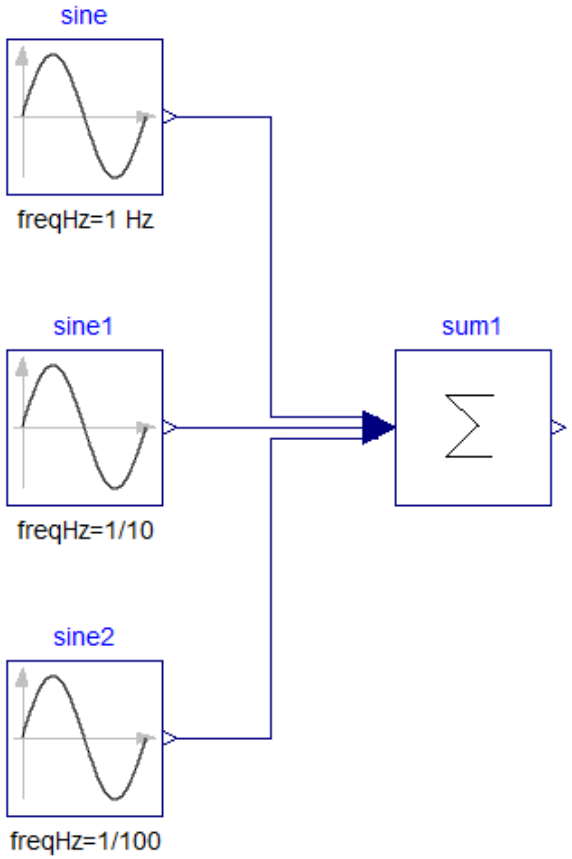
- Try creating a simple logic tree:

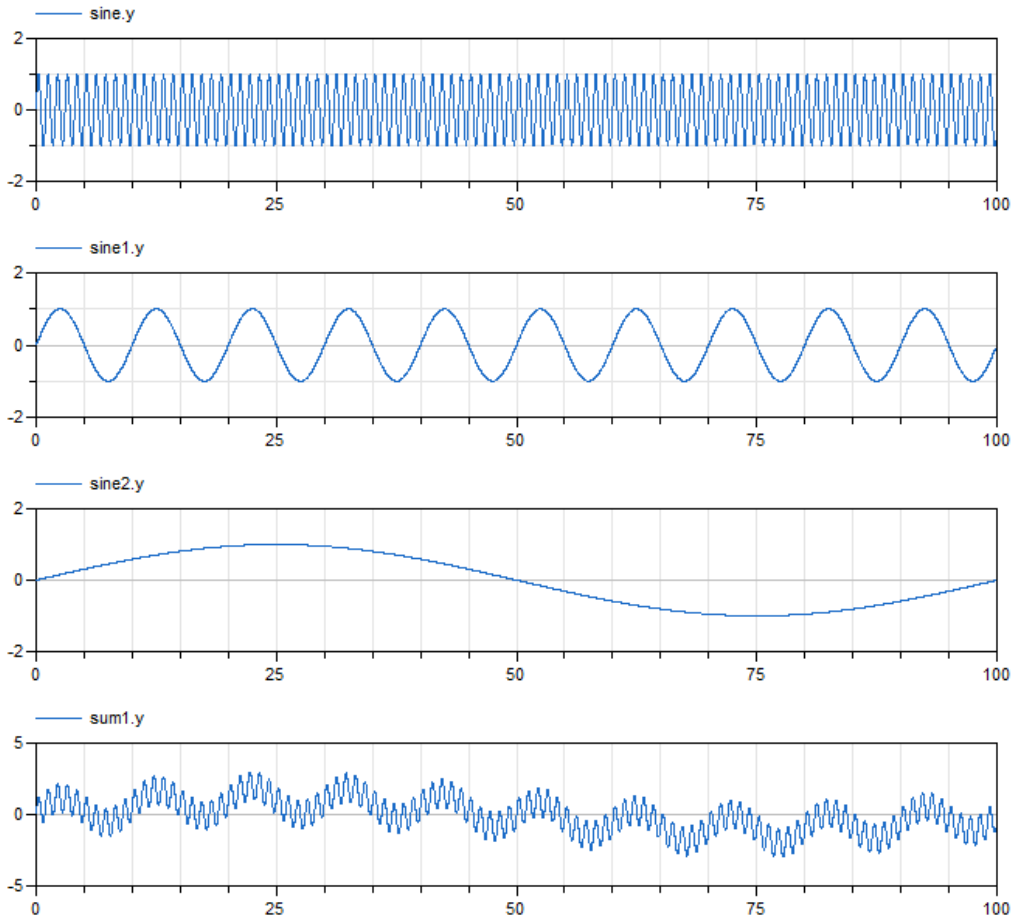


Example 2: Give me a sine!

This example will introduce the user to:
- Drag and drop components
- Modelica.Blocks.*

- Try creating a sum of sines:

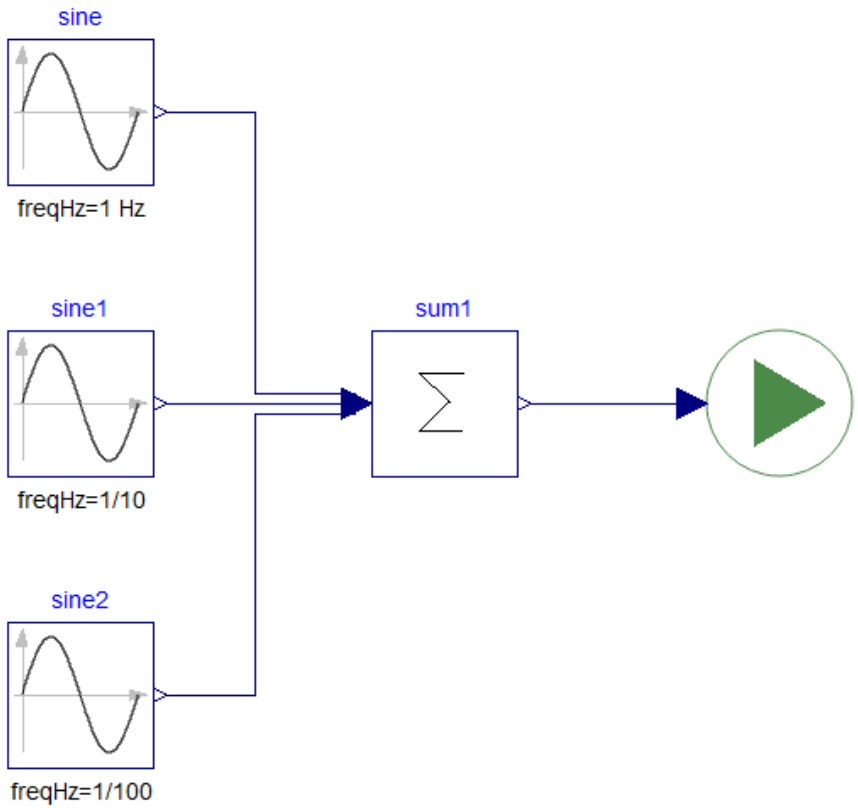


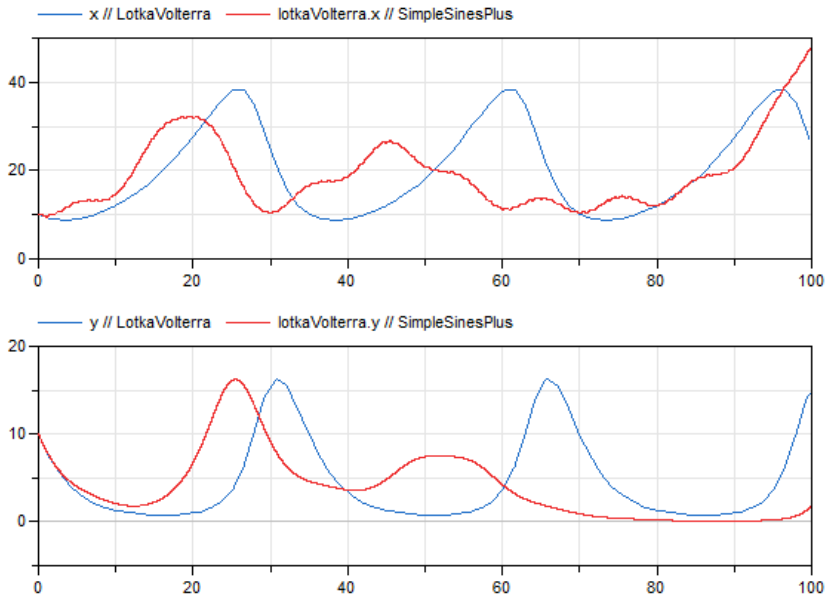


Example 3: The Circle of Life

This example will introduce the user to:
- Drag and drop components
- Modelica.Blocks.*
- Input connectors

- Use the sum of slides as input to the Lotka-Volterra example:





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Thank you.

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