view_frames Result Recorded at time: 777.675 odom Broadcaster: /gazebo Average rate: 20.305 Hz Most recent transform: 777.651 (0.024 sec old) Buffer length: 3.349 sec robot_footprint Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (777.675 sec old) Buffer length: 0.000 sec chassis Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10.303 Hz Average rate: 10.303 Hz Most recent transform: 0.000 (777.675 sec old) Most recent transform: 0.000 (777.675 sec old) Most recent transform: 777.600 (0.075 sec old) Most recent transform: 777.600 (0.075 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 3.300 sec Buffer length: 3.300 sec hokuyo left_wheel right_wheel camera