# Reality and Causality in the Microscopic World: A Discussion from Quantum Transport Theories

Chapter on "Physics and the Nature of Reality: Essays in Memory of Detlef Dürr".

#### Abstract

Paraphrasing Feynmann, perhaps, the main reason why the so-called Copenhagen (or orthodox) quantum theory is so popular among the physicists and engineers is because "I can safely say that nobody understands [it]". Many physicists and engineers take profit of the mathematical machinery of the Copenhagen theory without paying attention to its ontology, which implies that a quantum object has no microscopic properties (unless a property is measured, or the quantum object is an eigenstate of some property). Such an orthodox view of a microscopic world, empty of properties, is specially unsuitable to understand and to develop approaches to predict modern nanoelectronics, as we discuss along this chapter. As an alternative, physicists dealing with the foundations of quantum transport and open systems have developed different approaches in terms of some type of causal motion of electrons. When dealing with nanodevices, the Copenhagen ontology affirms that electrons are nowhere since their positions are undefined until measured, while causal motion approaches say that electrons can be perfectly understood as particles traversing a device with well-defined positions, independently of the measurement. This last view certainly holds true for treatments based on the Bohmian theory. Even for quantum phenomena of light, such as spontaneous emission or photon partition noise, the Bohmian theory allows an explanation from well-defined electromagnetic fields interacting with electrons, which is contrary to the standard Copenhagen approach. The above examples, developed in this chapter, emphasize that the main merit of the Bohmian theory is eliminating the observer/measurement as the "creator" of the microscopic reality, showing that a well-defined description at all times, of the microscopic properties of a quantum system, is available (where particles are particles and fields are fields at all times). Such a microscopic description does not only provide conceptual advantages, but also important numerical ones when electron devices are understood, in general, as non-Markovian open quantum systems.

In front of the incapacity of the standard quantum theory (so called Orthodox interpretation), to answer "when", "for how long" or whether the "are" electrons crossing the transistors of our phones at all, any physicist or engineer that needs to consider that this is indeed the case for the practical development of cutting edge devices, resorts to alternative explanations of quantum phenomena in terms of electrons that actually do cross their transistors [1]. The well known Bohmian explanation is one such alternative to the Orthodox interpretation [2, 3, 4, 5].

As an example of how impractical the interpretative limitation of the Orthodox view can arrive to be: in its terms, it is still obscure something as fundamental for modern electronics as is the current measurement for nano-devices operating at high frequencies [6]. Not for interpretative issues alone, but mainly due to practical issues like the search of an operator for the multi-electron current observable, or the requirement to treat a high frequency measuring apparatus as a non-Markovian environment. As we will discuss along the chapter, satisfying and practically useful explanations for these, apparently seem to demand the use of modal theories like Bohmian mechanics.

The essential tools for reaching these conclusions are the concepts of conditional wave-function (CWF) and effective wave-function (EWF) introduced by  $D\ddot{u}rr$  et al. in Ref [7], together with the understanding of the measurement dilemma they enlighten. Thus, we will first review all of these concepts, so we can naturally conclude solutions for the aforementioned practical limitations.

## The Conditional and Effective Wavefunctions

Given a quantum system of N degrees of freedom described by the real coordinate vector  $\vec{X} = (x_1, ..., x_N) \in \Omega_t \subseteq \mathbb{R}^N$ , we can describe its evolution in continuous time  $t \in \mathbb{R}$ , with the use of a complex wavefunction  $\Psi(\vec{X}, t) = \rho^{1/2}(\vec{X}, t)e^{iS(\vec{X}, t)/\hbar}$  (encoding the two real fields S and  $\rho$ ), and an associated Bohmian trajectory  $\vec{X}^{\vec{\xi}}(t) \equiv \vec{X}(\vec{\xi}, t)$  the initial condition of which is given by the label space vector  $\vec{\xi} \in \Omega_0 \subseteq \mathbb{R}^N$  such that  $\vec{X}^{\vec{\xi}}(t=0) = \vec{\xi}$ . This trajectory is guided by the wavefunction through the "guidance law", while the wavefunction itself is guided by the Schrödinger Equation [2, 3, 4, 5]. Respectively:

$$\frac{\mathrm{d}x_k^{\xi}(t)}{\mathrm{d}t} = v_k(\vec{X}, t) \Big|_{\vec{X} = \vec{X}^{\xi}(t)} := \frac{1}{m_k} \frac{\partial S(\vec{x}, t)}{\partial x_k} \Big|_{\vec{X} = \vec{X}^{\xi}(t)}$$
(1)

$$i\hbar \frac{\partial \Psi(\vec{X}, t)}{\partial t} = \left[ \sum_{k=1}^{N} \frac{\hbar^2}{2m_k} \frac{\partial^2}{\partial x_k^2} + U(\vec{X}) \right] \Psi(\vec{X}, t)$$
 (2)

where  $m_k$  is the mass associated with the k-th degree of freedom,  $v_k$  is the velocity field piloting the k-th degree of the Bohmian trajectories and U denotes the classical potential describing the interaction between the degrees of freedom (since we consider an isolated system we assume no time dependence, but we could describe in general a closed system by allowing it to vary in time).

The most general isolated system we could consider is the whole Universe, where  $\vec{X}$  would reflect its degrees of freedom or space of **configurations**. We can partition it in a subsystem of interest S, of say, n < N degrees of freedom, labeled by  $\vec{x} = (x_1, ..., x_n)$ , and its environment E, of configuration coordinates  $\vec{y} = (x_{n+1}, ..., x_N)$ , such that  $\vec{X} = (\vec{x}, \vec{y})$ . We could associate one wavefunction to S and one to E, both labeled by the initial global trajectory configuration  $\vec{\xi}$ , respectively as  $\psi^{\xi}(\vec{x}, t) := \Psi(\vec{x}, \vec{y}^{\xi}(t), t)$  and  $\phi^{\xi}(\vec{y}, t) := \Psi(\vec{x}^{\xi}(t), \vec{y}, t)$ . These are particular cases of the so called **conditional wavefunctions** (CWF-s). In general, a CWF is just evaluating some of the degrees of freedom of a wavefunction along a (Bohmian) trajectory for them, while leaving the rest un-evaluated [7, 5].

As proved in [8], the full Schrödinger Equation (2), ruling the dynamics of the whole SE system, can be re-written exactly into two coupled dynamical sets of equations ruling the motion of the two presented CWF-s. For the S (for the E they will be the same but changing the indexes and the CWF):

$$i\hbar \frac{\partial \psi^{\xi}(\vec{x},t)}{\partial t} = \left[ \sum_{k=1}^{n} \frac{\hbar^{2}}{2m_{k}} \frac{\partial^{2}}{\partial x_{k}^{2}} + U(\vec{x}, \vec{y}^{\xi}(t)) + G(\vec{x}, \vec{y}^{\xi}(t), t) + i J(\vec{x}, \vec{y}^{\xi}(t), t) \right] \psi^{\xi}(\vec{x}, t)$$
(3)

with G and J the real and complex parts of the so called **correlation potential**:

$$G(\vec{x}, \vec{y}^{\xi}(t), t) = \sum_{j=n+1}^{N} \left\{ -\frac{1}{2} m_{j} \left( v_{j}(\vec{x}, \vec{y}^{\xi}(t), t) \right)^{2} - \frac{\hbar^{2}}{2 m_{j} \rho^{1/2}(\vec{x}, \vec{y}^{\xi}(t), t)} \left( \frac{\partial^{2} \rho^{1/2}(\vec{x}, \vec{y}^{\xi}(t), t)}{\partial x_{k}^{2}} \right) \Big|_{\vec{y} = \vec{y}^{\xi}(t)} \right\}$$

$$(4)$$

$$J(\vec{x}, \vec{y}^{\xi}(t), t) = -\frac{\hbar}{2} \sum_{j=n+1}^{N} \frac{\partial}{\partial x_{j}} v_{j}(\vec{x}, \vec{y}, t) \Big|_{\vec{y}^{\xi}(t)}$$

where we recognize as G the difference between the quantum potential [5, 4] and the kinetic energies of the E (the Lagrangian of the E) and as J, the spatial variation of the Bohmian velocity of the E in its coordinates. All these are terms that involve a derivative of the phase S or the magnitude  $\rho$  of the full wavefunction  $\Psi$  in the E coordinates  $\vec{y}$  centered at the trajectory position  $\vec{y}^{\xi}(t)$ . This means that in order to compute them, we would not have enough with the two CWF-s  $\psi^{\xi}(\vec{x},t)$  and  $\phi^{\xi}(\vec{y},t)$ . We would require the information of the other adjacent CWF-s evaluated in  $\vec{y}$  close to but not exactly in  $\vec{y}^{\xi}(t)$ . This is an explicit manifestation of the so called quantum wholeness [5], by which the dynamics of a single Bohmian trajectory depend on the dynamics of the rest of possible trajectories. Thus, we see that while U introduces all the classical correlation between the S and the E, the responsible ones for their quantum interaction (and the interaction with the rest of possible Bohmian trajectories) are G and J.

Now, if the imaginary potential J vanished for the S, we see that the CWF  $\psi^{\xi}(\vec{x},t)$  would behave as if it was a closed quantum system wavefunction, ruled by the unitary evolution of a Schrödinger Equation (2), but where the potential energy would now be a time dependent one:  $V(\vec{x},t) = U(\vec{x},\vec{y}^{\xi}(t)) + G(\vec{x},\vec{y}^{\xi}(t),t)$ . Yet, computationally, we would still require a quantum description for the E in order to evaluate G. Thus, only if we also made G negligible, would the S behave exactly as an independent closed quantum system, only interacting with the E classically (through U). Whenever this is the case, we can say that the CWF of the S is the **effective wavefunction** (EWF) of the S.

The question is then: when are J and G (the quantum influences of the E on the S) negligible? When the full wavefunction's variation along the axes of the E  $\vec{y}$ , in the neighborhood of its trajectory  $\vec{y}^{\xi}(t)$ , is negligible:  $\frac{\partial \Psi(\vec{x}, \vec{y}, t)}{\partial x_j}\Big|_{\vec{y}=\vec{y}^{\xi}(t)} \simeq 0 \quad \forall j \in \{n+1, ..., N\}$ , both G and J will vanish, as they involve derivatives of the magnitude  $\rho^{1/2}$  and the phase S of the wavefunction  $\Psi$  in the axes of the E  $\vec{y}$ , around  $\vec{y}^{\xi}(t)$ . This happens for instance when the variation of the (normalized) CWF in the  $\vec{y}$  axes happens only if a macroscopically big distance is considered or when stackings (in  $\vec{y}$ ) of different (normalized) CWF-s have macroscopically distant disjoint supports.

#### Measurement understood as unitary evolution using Bohmian CWFs and EWFs

Given the initially closed quantum system S and its EWF  $\psi(\vec{x},t)$ , to do a projective measurement of its property G, as suggested by von Neumann [9] and explained in terms of Bohmian mechanics in Refs. [4, 5, 3], we can consider the position of the dial of a measuring apparatus M, or the generalized coordinate of such an indicator, which is what is observed by the experimenter. Lets call it  $z \equiv x_{n+1}$  (it is part of the environment of the S). We prepare the EWF of this dial to be a fiducial state that will make sure its Bohmian position at the first time of the measurement t=0, that is  $z^{\xi}(t=0)$ , is reliably around the macroscopic rest position of the dial z=0, with a high precision and accuracy. For example  $\varphi(z,t=0) = \alpha e^{z^2/4\sigma^2}$ , or in ket notation  $|\varphi(t=0)\rangle_M = \int_{\mathbb{R}} \varphi(z,t=0)|z\rangle dz$ , with  $\alpha$  a normalization constant and  $\sigma$  not macroscopically distinguishable. We now let the EWF of the S, which in ket notation is  $|\psi(0)\rangle_S = \int_{\mathbb{R}^N} \psi(\vec{x},0) |\vec{x}\rangle dx$ , interact with the measurement dial through

<sup>&</sup>lt;sup>1</sup>Note that while information about multiple stacked CWF-s for the S around  $\vec{y}^{\xi}(t)$  is required to compute G and J, the guidance for the trajectory of the S,  $\vec{x}^{\xi}(t)$ , is given entirely by the  $\vec{y}^{\xi}(t)$  CWF:  $\psi^{\xi}(\vec{x},t) = r^{\xi}(\vec{x},t)e^{is^{\xi}(\vec{x},t)/\hbar}$ , as  $\frac{\mathrm{d}}{\mathrm{d}t}x_k(t) = \frac{1}{m_k} \frac{\partial s^{\xi}(\vec{x},t)}{\partial x_k}\Big|_{\vec{x}=\vec{x}^{\xi}(t)}$  for  $k \in \{1,...,n\}$ . That is, if it was not for G and J, the CWF would behave itself as a wavefunction.

a Hamiltonian  $\hat{H}_{MS} = \mu(t)\hat{p}_M \otimes \hat{A}_S$ , where  $\hat{p}_M$  is the momentum operator of the dial z and  $\hat{A}_S$  is the operator related with the property of the subsystem we wish to measure.  $\mu(t)$  is the interaction strength which has support only in  $t \in (0,T)$  (the interaction time), such that  $\mu := \int_0^T \mu(t)dt$ .

If the observable G has countable spectrum, such that  $\hat{G}_S = \sum_k g_k |g_k\rangle_S \langle g_k|_S$  with  $\{|g_k\rangle_S\}_k$  an orthonormal basis of S and  $|\psi(0)\rangle_S = \sum_k \alpha_k(0) |g_k\rangle_S$ : at the last interaction time t = T, the unitary Schrödinger evolution  $\hat{U}_0^T = \exp(-i\mu T \hat{H}_{MS}/\hbar)$  will leave the composed state  $|\Phi(0)\rangle_{MS} = |\varphi(0)\rangle_M \otimes |\psi(0)\rangle_S$  as:

 $|\Phi(T)\rangle_{MS} = \sum_{k} \alpha_k(0) \left( \int e^{-\frac{(z - a_k \mu T)^2}{4\sigma^2}} |z\rangle_M dz \right) |g_k\rangle_S$  (6)

This means, as graphically shown in Figure ??, that if the interaction strength  $\mu$  or time T are big enough, or  $\sigma$  is small enough, the probability density for the Bohmian position of the dial z, will be exclusively concentrated in several roughly disjoint Gaussians of weights  $|\alpha_k(0)|^2$ , each centered in a different  $a_k\mu T$  position in z, around which, the (normalized) CWF for the S is roughly constantly  $|g_k\rangle$ . The different Gaussians enveloping each eigenstate for S are macroscopically disjoint in z, since other-wise the dial would not be able to let us know the result of the measurement. Therefore, the CWF obtained by evaluating the observed Bohmian trajectory of z at t=T is an EWF that is the eigenstate  $|g_k\rangle_S$  linked with the eigenvalue  $g_k$  indicated by z. Finally, the interaction between M and S is set off for times t > T, meaning the composite Hamiltonian becomes "factorisable" for t > T and as such the evolution of the (normalized) CWF for the S (which is an EWF) can be made as if it was a closed quantum system fully independent of the M [5].

If the observable G had a continuous spectrum, such that  $\hat{G}_S = \int g |g\rangle_S \langle g|_S dg$  with  $\{|g\rangle_S\}_g$  an improper-state rigged Hilbert space orthonormal basis for the S, such that  $|\psi(0)\rangle_S = \int \psi(g,0) |g\rangle dg$ , then the unitary coupling evolution will yield a composed state at time t = T:

$$|\Phi(T)\rangle_{MS} = \int \left( \int \psi(g,0) e^{-\frac{(g - \frac{z}{\mu T})^2}{4\Delta^2}} |g\rangle_S dg \right) |z\rangle_M dz \quad \text{with} \quad \Delta := \frac{\sigma}{\mu T}$$
 (7)

where, as graphically shown in Figure ??, if  $\mu$  or T are big enough, or  $\sigma$  is small enough, the resulting wavefunction is stretched in z such that the variation is so slow in z, that if the interaction between the S and M is stopped for t > T, the S will be in an EWF equal to the CWF sliced by evaluating z in the observed Bohmian position  $z^{\xi}(T)$ . This EWF will be a very narrow Gaussian (tending towards a Dirac delta), and will be the EWF of the S with a probability density roughly equal to  $|\psi(g,0)|^2$ . We know the state will need to be macroscopically stretched for our measuring dial to show significantly different positions.

In both cases, as seen from the S alone, it will have looked like the unitarily evolved state  $|\psi\rangle_S$  "collapsed" into one of the eigenstates of  $\hat{G}_S$ , with a probability equal to the pre-measurement state's projection magnitude squared  $|\alpha_k(0)|^2$  (or pdf  $|\psi(g,0)|^2$ ). This EWF will now continue to be unitarily and independently evolvable (for it will be an EWF with no interaction with M). The randomness of the measurement thus, arises due to the fact that we cannot know  $z^{\xi}(0)$  with an arbitrary precision, unless we made a projective measurement on it before the experiment. But such a measurement as seen, would require the coupling with another ancilla indicator and so on, until the chemicals in the perception of the observer, which is known as the von Neumann chain of observation [9].<sup>2</sup> The point is that a proper description of this chain (like the Bohmian one), allows us to decide where arbitrarily between the observer and the S we place the effective "collapse", which was a requirement placed by von Neumann himself [9, 10] over his axiomatization and is mainly ignored by the Orthodox<sup>3</sup>.

Now, either the assumption that for time t > T, M does not interact anymore with the S, or that the environment entanglement with the subsystem is lost by some sort of thermalization, mean that the information of the subsystem that was "leaked" to the environment (the so called "empty waves", which are the rest of CWF-s that are not sliced at  $z = z^{\xi}(T)^4$ ), do not interact back with the EWF of the subsystem. Any of these two assumptions thus imply that the environment effectively forgets the entanglement achieved with the S. This is an environment behavior we could call memory-less or Markovian.

Since the description of the E will only be useful for the measurement time interval (0,T), and we can then discard it (as we consider it for an ideal measurement to be Markovian), we can instead explain the projection of the state of the S to a subspace its Hilbert space, with a set of effective"collapse" orthogonal projectors  $\{\hat{\Pi}_k\}_k$  without the need to explicitly formalize M [4]. We shall not forget however that this is just a short-cut in the modeling.

If we were now interested on the post-measurement description of the S, but irrespective of the measured result, we could independently unitarily evolve each of the different possible projected states (EWF-s), remembering which was the probability for each of them. Then if a second measurement is performed at a later point, we could simply treat a measurement on each of the independent states and weight them with the joint probability of the previous and the current measurements. Perhaps more compactly, we could instead build a "matrix" of states where each ket-bra is preserved in its slot for any linear operation such that we save the probability due to each ket-bra EWF as its matrix coefficient. If we now apply a linear operation and its Hermitian conjugate at each side of the matrix (say a unitary evolution), we will be applying the operation to each state-vector independently of the rest. Just as we wanted. Thus, we define a "matrix", or more properly an operator on state-vectors, that will serve as a state-probability container:

$$\hat{\rho}_S(T) = \sum_k |\alpha_k(0)|^2 |g_k\rangle_S \langle g_k|_S \quad \text{or} \quad \hat{\rho}_S(T) = \int |\psi(g,0)|^2 |g\rangle_S \langle g|_S dg$$
 (8)

This is the so called **density matrix** of the S [9, 4, 3]. Notice that for subsequent unconditional measurements, the density matrix will get more and more mixed (the squared trace will diminish).<sup>5</sup>

<sup>&</sup>lt;sup>2</sup>In reality, we cannot really couple the apparatus dial M directly to the S, nor we as observers with organic detectors are directly coupled to the dial M. Yet, we can couple the S to an immediately close an order of magnitude bigger ancilla  $A_1$ , which will be coupled to a bigger ancilla  $A_2$ , and so on until M, and then until our perceptual observation, which due to the determinate Bohmian trajectory of its constituents, lets us know the result of the measurement.

<sup>&</sup>lt;sup>3</sup>He did not believe in a physical collapse [10], instead he believed an explanation of the measurement should be possible setting an apparent collapse at an arbitrary point of the measurement Neumann chain, which is what we allow with the Bohmian description.

<sup>&</sup>lt;sup>4</sup>These could technically interact back with the CWF selected by  $z^{\xi}(T)$  if their macroscopic separation was made microscopic again.

<sup>&</sup>lt;sup>5</sup>Also, note that these are "diagonal" representations of the density matrix but we could equivalently express it in other orthonormal bases, which means we can loose the microscopic deterministic detail of what is happening if we only specify a density matrix. For a probabilistic operational description of S (an epistemological description), this will suffice, but we have just seen that an ontologically meaningful view of the matrix is always available.

## A Bohmian Narrative for General Quantum Operations

At this point, notice that the effective-"collape" due to a macroscopic separation in configuration space for different CWF-s, is not necessary to be part of a measurement by an observer. It could also happen as the effect of a more general environment-coupling. As an example, this can happen because part of the environment, that gets entangled with S, is projectively measured. As a result, the S will also seem to suffer an effective-"collapse", but now into non-necessarily orthogonal nor linearly-independent states (nor a number of states limited by the dimensionality of its Hilbert space).

This example is in fact was is called a **generalized measurement** [11, 4]. We could couple states (not necessarily orthogonal to each other) of S in which we could decompose an initial state  $|\psi\rangle_S$ , each with a different state of an orthonormal basis  $\{|m\rangle_A\}_m$  of an ancilla A, employing a suitable coupling unitary evolution  $\hat{U}_{AS}$ . Beginning with the product of a fiducial ancilla state and the S state  $|\theta\rangle_A\otimes|\psi\rangle_S$ , we get the entangled state  $\hat{U}_{AS}|\theta\rangle_A\otimes|\psi\rangle_S=\sum_m|m\rangle_A\otimes|\psi_m\rangle_S$  where  $|\psi_m\rangle_S:=\langle m|_A\otimes\hat{I}d_S\big(\hat{U}_{AS}|\theta\rangle_A\otimes|\psi\rangle_S\big)$  is an unnormalized S state that we will call the **conditional state** for the m-th observation of the environment A. Then an ideal projective measurement on A for the  $\{|m\rangle_A\}_A$  basis (coupling a dial M to A and branching A in EWF-s consisting of the measured eigenstates), would generate ancillasubsystem (unnormalized) EFW-s  $|m\rangle_A\otimes|\psi_m\rangle_S$ , given by the Bohmian position of the dial. The m-th result would be observed with a probability equal to its projective result's norm  $N^2:=|\langle\psi_m|\psi_m\rangle|^2$ . If we then set off the interaction between A and S for all future times, the S will have seemed to "collapse" into the EWF  $|\psi_m\rangle_S/N$  with probability  $N^2$ , and would now be independent of the evolution of A.

If we wish, we could now shortcut the formalization of the A and its projective measurement, by just considering the general measurement operators (called POVM-s)  $\{\Omega_m := |m\rangle \otimes \hat{I}d\hat{U}_{AS} |\theta\rangle_A \otimes\}_m$  such that the only requirement for them is that since  $\Omega_m |\psi\rangle_S = |\psi_m\rangle_S$  will be the (unnormalized) post-measurement state and its squared norm will be the probability to observe m:  $\sum_m \Omega_m^{\dagger} \Omega_m = \hat{I}d_S$  (so that probabilities add up to one) [11, 4]. The reason why there exists for any  $\Omega_m$  linear operator, such an A and  $\hat{U}_{AS}$  will be seen in a moment. Note that we could describe the post-measurement S unconditionally, using the density matrix idea just the same way as with projective measurements, defining  $\hat{\rho}_S = \sum_m |\psi_m\rangle \langle \psi_m|_S$  (or an integral). A second measurement on S would then be defined by a more mixed matrix, straightforwardly.

Now, given a density matrix  $\hat{\rho}_{AS}$  for a composite  $A \otimes S$  (which can be pure if say  $\hat{\rho}_{AS} = |\Psi(T)\rangle_{AS} \langle \Psi(T)|_{AS}$ ), given an arbitrary orthonormal base of the  $A \{|m\rangle_A\}_m$ , its partial trace over A is defined as:  $tr_A[\hat{\rho}_{AS}] := \sum_k \langle m| \otimes \hat{I}_S(\hat{\rho}_{AS}) |m\rangle \otimes \hat{I}_S$  (or an integral if the "base" is made of uncountable improper states) [11, 4]. It can be easily proven that the resulting density matrix of S, so called **reduced density matrix**, is the same irrespective of the employed basis in the partial trace.

Notice how the partial trace of M on the pure state  $|\Psi(T)\rangle_{MS} \langle \Psi(T)|_{MS}$  of equations (6),(7), under the effective "collapse" conditions for  $g, T, \sigma$ , precisely yield the unconditional post-measurement density matrix of equation (8). The same happens for the post-measurement pure state (without considering effective-collapse) of the previous generalized measurement, if A is traced out. In general, this indicates that the partial trace of an ancilla partition A of a composite Hilbert space  $A \otimes S$  can always be interpreted as how the S would be left if an unconditional ideal projective measurement was performed on the A [11]. Note very importantly that if the traced out partition is not really projectively measured (coupling a measurement ancilla to it and evolving until macroscopic distinguish-ability is achieved) and the interaction between A and S is not thermalized or does not cease indeterminately, then the obtained reduced density matrix for S will not evolve unitarily and independently of A: each CWF of the S will still interact with the different adjacent slices of the full wavefunction. That is, these CWF-s we placed in independent "slots" of the matrix will not be EWF-s. It is still true though that for statistical predictions about the S at that time, the information in the reduced density matrix will be enough. Thus, under Bohmian mechanics, the reduced density matrix could just be understood as a structure that allows single-time measurement statistics on S to be predicted, but in general, the environment's effect will need to be taken into account in its time evolution.

In order to finish integrating the density matrix formalism and any general quantum operation with this Bohmian view (also the generality of the previous Bohmian view of a POVM), we can invoke the Gelfand-Naimark-Segal theorem [12, 11], following which, for any most general operation we can perform on a density matrix  $\hat{\rho}_S$  of a system S (any complete-positive, convex linear and not trace increasing superoperator acting on S), say, for the operation  $\mathfrak{S}$ , there exists at least an ancilla system A with a pure state  $|\theta\rangle_A$  and a coupling unitary evolution  $\hat{U}_{AS}$  such that:

$$\mathfrak{S}[\hat{\rho}_S] = tr_A \left[ (\hat{\Pi}_A \otimes \hat{I}d_S) \hat{U}_{AS} (|\theta\rangle_A \langle \theta|_A \otimes \hat{\rho}_S) \hat{U}_{AS}^{\dagger} \right]$$
(9)

which can be interpreted as a unitary coupling of the initially independent system and an ancilla, and posterior partially selective ideal projective measurement of A (where only the eigenstates of non-null eigenvalue of  $\hat{\Pi}_A$  are left and the rest are discarded). In particular, if the coupling of S and A perfectly entangles the eigenstates of  $\hat{\Pi}_A$  with some orthonormal basis of S, this will be a projective measurement of S. Else, it will be a generalized measurement of S. In the trivial case where  $\hat{U}_{AS} = \hat{U}_A \otimes \hat{U}_S$ , it will just be the Schrödinger unitary evolution.

#### Markovian to Non-Markovian measurement contexts

Following the Markovianity idea we pragmatically defined earlier, we could call a Markovian open quantum system, any evolution of the reduced density of the S that could be equivalently interpreted as if after each significant time  $\Delta t$  for S, a different portion of the environment (a different ancilla) in an insignificant time interacted with the S and was then ideally measured, in a way that this ancilla never again interacted with the system (or their entanglement was somehow "thermalized" before their next interaction). From the perspective of S, this is to perform a generalized measurement on S every  $\Delta t$ . Among others, the "Past-Future Independence" definition of Markovianity by Wiseman et al. [14], perfectly matches this view.

In fact, as shown by Ref [13], such a continuous monitorization of different ancillas coupled to the system at each time, can be used to derive one of the most general dynamical equations for the reduced density matrix of a subsystem in a Markovian environment. A general kind of so called Lindblad Master Equations [11, 14]. Generalizing them to an arbitrary Markovian environment, then requires considering several continuous measurements of different properties of the bath [13, 14], yet, the same idea in our narrative still holds.

The fact that the dynamics of the reduced density matrix of a subsystem can be understood in these terms means that instead of solving directly the non-linear Markovian Master Equation, we could do the following. Find an observable W for some (fictitious or not) environment ancillas, E, ancillas that get entangled with S and are then projectively measured, producing the same average (unconditional) effect on the reduced density of S as the predicted one by the Master equation. Then, we could evolve a pure state-vector of the S choosing at each projective measurement of the bath after each  $\Delta t$ , one of the possible stochastic conditional states. This would generate a linked in time S pure state  $|\psi_{w(t)}(t)\rangle_{S}$ , associated to the result of a certain continuous measurement (or unravelling) of the bath ancillas:  $w(t)^{6}$ . This pure state is called a **quantum trajectory**, linked to a "noise realization" w(t) for its environment [11, 14, 15]. As we saw previously that the reduced density matrix of a subsystem is how it would be left if an unconditional ideal measurement was performed on the rest of the system, this tells us that we should be able to obtain the reduced density for the S by averaging the ensemble of all possible quantum trajectories for the unraveling of the W observable of the bath ancillas [14, 15]:

$$\hat{\rho}_S(t) := tr_{ES}[\hat{\rho}_{ES}(t)] = \mathbb{E}_{w(t)} \left[ \left| \psi_{w(t)}(t) \right\rangle_S \left\langle \psi_{w(t)}(t) \right|_S \right]$$
(10)

<sup>&</sup>lt;sup>6</sup>Remember that at each time a different generalized measurement is performed on S, meaning this stochastic trajectory w(t) reflects the Bohmian positions of different measurement dials at each  $\Delta t$  step. Thus, its non-differentiable nature is not a problem for Bohmian mechanics.

Computationally, this means that if we got an equation ruling the stochastic time evolution of a pure quantum trajectory  $|\psi_{w(t)}\rangle_S$  and its noise realization w(t), we would be able to massively parallelize the computation of the reduced density matrix [14, 15]. A density matrix is a more complex data structure to be evolved than a bunch of state vectors. Additionally, the obtained reduced density matrix is necessarily positive definite by construction. Equations of these kind are so called, Stochastic Schrödinger Equations (SSE-s) [11, 13]. Note that such a pure state trajectory for a Markovian E, can always be physically interpreted in the Orthodox explanation, as a so called pure unravelling [14] (where one would invoke the collapse at each  $\Delta t$ ). In the Bohmian view a quantum trajectory is exactly a normalized S CWF (in ket notation), which every significant  $\Delta t$  is converted into an EWF (thus the normalization).

However, what if we had an E that gets entangled with S, but which never really allows us to consider a branching of the S in different EWF-s? What if the different CWF-s of S, were allowed to interact in any future time, and were not converted into EFW-s every  $\Delta t$ ? That is, what if the "quantum trajectories" could interact between them, such that the evolution of each of them depended on the rest? Then "the information leaked" onto the environment from S (the "empty waves"), would be able to affect back S in any significant future time for S. Such an environment with "memory" of the entanglement achieved with S would be called a non-Markovian environment [14]. Then, it turns out that from a Bohmian interpretation, we could still continue talking about "pure state quantum trajectories", which would be the CWF-s for S (in any desired representation), conditioned on any position for the environment interacting with S (or if one wished not to use the position, then conditioned on the position of a dial coupled with an observable of the bath interacting with S) [17, 16]. Since measurement and collapse are just described as another unitary evolution of the whole, while the positions and derived properties are ontologically real at all times, then there is no interpretative issue.

Contrarily, in the Orthodox view, a CWF (normalized or not, in any representation basis), does not have a physical interpretation, unless it is an EWF, say, unless the conditioning variable is projectively measured, in which case the CWF is the (unnormalized) post-measurement state. As a consequence, if a SSE is found for a non-Markovian dynamical equation ruling a reduced density matrix (a master equation), the conditional pure state evolved by the SSE in the Orthodox view can only be understood as the state in which S would be left on, if the E was measured...but since it is non-Markovian, we cannot assume the E is being projectively measured! If it was, the evolution of the state would be pretty different (we would neglect the interaction between the CWF-s stacked along the E axes). Thus, the linking of such states in time, can only be understood if we get out of the Orthodox and use concepts like the CWF of the Bohmian view [17, 16]. Of course, mathematically, one could derive such non-Markovian SSEs as pragmatical computational tools to reconstruct the reduced density matrix, but one would need to avoid any additional consideration for the quantum trajectory (like two-time correlation computations) unless one accepts some sort of ontological reality (independent of measurement) for the conditioning property of the environment.

From the Bohmian perspective it is easy to notice why SSE-s for non-Markovian environments will never be exact in general. One of the main properties a SSE needs to have is that it should allow the time evolution of a single conditional state independently of the rest of possible conditional states, which is precisely asking that there is no quantum influence by adjacent CWF-s, influence which as explained in the beginning is the main characteristic of quantum mechanics (the quantum wholeness). In fact, this is asking for these CWF-s to be EWF-s as we saw, which would then allow a Markovian interpretation for the SSE, and thus a contradiction. Yet, SSEs that approximate the dynamics for adhoc cases are indeed possible in non-Markovian environments [18, 19, 6]. This is because, an ensemble of CWF-s does not need to be an ensemble of EWF-s to allow the computation of the reduced density matrix at each time!

To see that this is so, independently of the nature of the environment, let us prove it for an arbitrary

<sup>&</sup>lt;sup>7</sup>In fact, a whole set of CWF-s, if the system state was not mixed, would also allow the reconstruction of the full wavefunction! In which case a reduced density matrix would not be necessary.

composed pure state (the generalization to mixed states is then trivial). Given the arbitrary state  $|\Psi\rangle_{ES}$  for the environment E and system S, with position observables  $\vec{y}$  and  $\vec{x}$  respectively, just as introduced in the beginning, in ket notation we would have that at each time<sup>8</sup>:

$$|\Psi(t)\rangle_{AS} = \int \left| \vec{y}^{\xi}(t) \right\rangle_{A} \otimes \left| \psi^{\xi}(t) \right\rangle_{S} d\xi = \int |\vec{y}\rangle_{A} \otimes \left| \psi^{y(\xi,t)}(t) \right\rangle_{S} dy \tag{11}$$

Then tracing out A in  $\hat{\rho}_{AS}(t)=\left|\Psi(t)\right\rangle_{AS}\left\langle\Psi(t)\right|_{AS}$ , we would get the reduced density for S:

$$tr_{E}[\hat{\rho}_{AS}(t)] = \int \langle \vec{y} | \hat{\rho}_{AS}(t) | \vec{y} \rangle dy = \int \left| \psi^{y(\xi,t)}(t) \right\rangle \left\langle \psi^{y(\xi,t)}(t) \right| dy = \mathbb{E}_{y(\xi,t)} \left[ \left| \psi^{y(\xi,t)}(t) \right\rangle \left\langle \psi^{y(\xi,t)}(t) \right| \right]$$

$$(12)$$

Thus, the ensemble average of the CWF-s reproduces the reduced density.

This clear narrative in terms of Bohmian CWF-s for non-Markovian open quantum systems is not only theoretically insightful, but is a practical tool to look for reasonable SSE-s. To exemplify this, let us describe two practical frameworks we developed.

## Non-Markovian SSE for two-terminal electronic devices operating at THz frequencies

Following Bohmian mechanics and Ref. [8], we have already shown a way to obtain SSE-s for arbitrary settings in equation (3). In principle, in these equations the dynamics of the S CWF and the E CWF are coupled at all times between them and with the rest of possible CWF-s (non-Markovianity). However, for specific scenarios, we can make educated guesses for the quantum correlation terms G and J, and the classical potential U, to render a SSE for individual CWF-s of the S.

For nano-scale electronic devices operating at very high frequencies (in the order of THz), both the relevant dynamics of the S and the "measurement" coupling times are below picoseconds time-scales, implying Markovian assumptions for this continous motorization are meaningless, since there is "no time for their entanglement to be forgotten" [6]. This problem for a two-terminal nano-electron device is approximated in the BITLLES simulator [20, 21, 6], as an application example of the mentioned method. For this, the classical potential is evaluated through the solution of the Poisson equation [21], while G and J are modeled by a proper injection model [22] as well as proper boundary conditions [23, 24] that include the correlations between the active region of the two-terminal nano-device and the reservoirs. Even electron-phonon decoherence effects can be included effectively [25].

The number of electrons contributing to the electrical current are mainly those in the active region of such a nano-device, which we consider the subsystem S of interest. This number n/3 fluctuates as there are electrons entering and leaving this region. Such "creation and destruction" of electrons from the point of view of S, leads to an abrupt change in the degrees of freedom of its CWF. This problem can be circumvented in Bohmian mechanics by decomposing the CWF of S,  $\psi^{y^{\xi}(t)}(\vec{x}, t)$ , into a set of CWF-s for each electron. That is, for each of the n/3 electrons of position  $\vec{x}_k := (x_{3k+1}, x_{3k+2}, x_{3k+3})$  with  $k \in \{0, ..., n/3 - 1\}$ , we define a single particle CWF  $\phi_k^{\xi}(\vec{x}_k, t) := \psi^{y^{\xi}(t)}(\vec{x}_k, \vec{x}_{\neg k} = \vec{x}_{\neg k}^{\xi}(t), t)$  with  $\vec{x}_{\neg k} = (\vec{x}_1, ..., \vec{x}_{k-1}, \vec{x}_{k+1}, ..., \vec{x}_{n/3})$ . Then, we can consider a set of n(t)/3 equations like (3), one for each of the electron, to evolve each CWF  $\phi_k^{\xi}$ . Note that what we have just done is to consider S, the subsystem of the non-Markovian open quantum system of interest, as itself composed of several open quantum systems that will interact with each other in a non-Markovian way.

Now, the active region of the electron device S, is connected by a macroscopic cable (representing the portion of the environment A that gets entangled with the S) to the ammeter (acting as a measuring apparatus M). The electrical current read by the Bohmian position of the dial in the ammeter

<sup>&</sup>lt;sup>8</sup>Note that since Bohmian trajectories do not cross each other in configuration space, if we sampled only Bohmian trajectories for which  $\vec{x}(t_0)$  is a single position, at each time, we would still have a CWF per each position in  $\vec{y}$ , thus, we have that the states  $\left\{\left|\psi^{y(\xi,t)}(t)\right\rangle_S := \left\langle y(\xi,t)\right|_A |\Psi(t)\rangle_{AS}\right\}_{y\in\mathbb{R}^{N-n}}$  are all the possible slices of the  $\vec{y}$  axis.

(correlated with the Bohmian trajectory of the charge carriers in the cable, which are correlated with the electrons in the active region) is the relevant observable we are interested to predict. Thus, in principle the evaluation of the electrical current should require keeping track of all the environment degrees of freedom. However, it is known that the total current density defined as the sum of the particle and displacement currents, is a divergenceless vector [26, 27], which makes the total current evaluated at the end of the active region be equal to the total current evaluated at the cables. It is additionally known [28] that since the cable, unlike the active region, has macroscopic dimensions, the current at the end of the active region is only due to the electrons in the active region (plus a source of nearly white noise). This is qualitatively because the electrons in the metallic cables have a very short screening time, meaning the electric field generated by an electron in the cable spatially decreases rapidly due to the presence of many other mobile charge carriers in the cable that screen it out. Thus, the contribution of these outer electrons to the displacement current at the border of the active region is negligible [30]. Therefore, the variable of the environment associated to the total current  $z(t) \equiv I(t)$  can indeed be equivalently computed at the boundary of the S. Finally, such a current (its expectated value), can be computed from the Bohmian trajectories of the electrons in the active region as we will later explain.

In Ref. [6] we provide some numerical results demonstrating the ability of the presented method, by simulating a two-terminal electron device whose active region is a graphene sheet, contacted to the outer by two (ohmic) contacts. Here, to further take into account the electromagnetic environment of the electron device, we model the interaction between the graphene device and the environment through a resistor and a capacitor in series through ideal cables. The details are found in the article.

#### Towards another general framework to look for position SSEs

We have developed a second framework to look for SSEs (equations to evolve CWF-s independently), based on the Born-Huang ansatz of the full wavefunction, at the cost of having a suitable guess for the conditional eigenstates of the relevant parts of the environment. For this, given the full, subsystem-environment Hamiltonian  $\hat{H}(\vec{x}, \vec{y}, t) = \sum_{k=1}^{N} \frac{-\hbar^2}{2m_k} \frac{\partial^2}{\partial x_k^2} + U(\vec{x}, \vec{y}, t) + V(\vec{x}, t)$ , we can define the transversal section Hamiltonian as  $\hat{H}_x(\vec{y}, t) := \sum_{k=m+1}^{N} \frac{-\hbar^2}{2m_k} \frac{\partial^2}{\partial x_k^2} + U(\vec{x}, \vec{y}, t)$ . Then, we define the set of eigenstates  $\{\Phi_x^j(\vec{y}, t)\}_j$  with eigenvalues  $\{\varepsilon_x^j(t)\}_j$ , parametrized by the chosen section  $\vec{x}$ , to be the solution of:  $\hat{H}_x(\vec{y}, t)\Phi_x^j(\vec{y}, t) = \varepsilon_x^j(t)\Phi_x^j(\vec{y}, t)$ . We could call these  $\Phi_x^j(\vec{y}, t)$ , transversal section eigenstates (TSE). Since the hermiticity of the operator  $\hat{H}_x(\vec{y}, t)$  implies the TSE-s form an orthonormal basis for the Hilbert space of  $\vec{y}$  at each  $\vec{x}$ , we could expand the ansatz:  $\Psi(\vec{x}, \vec{y}, t) = \sum_j \Lambda^j(\vec{x}, t)\Phi_x^j(\vec{y}, t) = \sum_j \varphi_j(\vec{x}, \vec{y}, t)$ , with  $\Lambda^j(\vec{x}, t) := \int \Phi_x^j(\vec{y}, t)\Psi(\vec{x}, \vec{y}, t)dy$  the projection coefficients and  $\varphi_j(\vec{x}, \vec{y}, t) := \Lambda^j(\vec{x}, t)\Phi_x^j(\vec{y}, t)$ .

Now, using this expansion in the Schrödinger Equation, and evaluating the full wavefunction along the trajectory for the environment  $\vec{y} = \vec{y}^{\xi}(t)^{10}$ , we can get by denoting  $\varphi_{\xi}^{k}(\vec{x},t) := \varphi^{k}(\vec{x},\vec{y}^{\xi}(t),t)$  that:

$$i\hbar \frac{\partial}{\partial t} \varphi_{\xi}^{k}(\vec{x}, t) = \left[ -\sum_{s=1}^{m} \frac{\hbar^{2}}{2m_{s}} \frac{\partial^{2}}{\partial x_{s}^{2}} + \varepsilon^{k}(\vec{x}, t) + V(\vec{x}, t) + i\hbar \frac{\mathrm{d}}{\mathrm{d}t} log(\Phi_{x}^{k}(\vec{y}^{\xi}(t), t)) \right] \varphi_{\xi}^{k}(\vec{x}, t) + (13)$$

$$+\sum_{j=0}^{\infty}\sum_{s=1}^{m}\frac{-\hbar}{2m_{s}}\Biggl(\frac{1}{\Phi_{x}^{j}(\vec{y}^{\xi}(t),t)}\frac{\partial^{2}\Phi_{x}^{j}(\vec{y}^{\xi}(t),t)}{\partial x_{s}^{2}}+2\frac{\partial}{\partial x_{s}}log(\Phi_{x}^{j}(\vec{y}^{\xi}(t),t))\Biggl[\frac{\partial}{\partial x_{s}}-\frac{\partial}{\partial x_{s}}log(\Phi_{x}^{j}(\vec{y}^{\xi}(t),t))\Biggr]\Biggr)\varphi_{\xi}^{j}(\vec{x},t)$$

Since the CWF for the subsystem can be recovered from  $\psi^{\xi}(\vec{x},t) = \sum_{j} \varphi_{\xi}^{j}(\vec{x},t)$ , we have obtained

<sup>&</sup>lt;sup>9</sup>The classical potentials are allowed to have a time dependence to account for classical interaction with the rest of the environment.

<sup>&</sup>lt;sup>10</sup>In reality, we could choose any trajectory we like for the environment if we are not interested in computing Bohmian trajectories. Thus, it could be the result of a measurement of the bath, or just a set of trajectories that leads us to the construction of the reduced density with the least number of them.

a set of exact linear equations involving only n dimensional states that allow the evolution of single CWF-s. In principle, since a general Hilbert space will need to have a countably infinite number of orthonormal states in a basis, it would be a set of infinite number of equations. However, we shall reasonably truncate the expansion of the CWF at a relatively low fixed point (at which for example the norm of the CWF surpasses a certain threshold), or even allow it to vary in time. If so, the difficulty of these equations would relay on the knowledge of the TSE-s  $\Phi_x^j(\vec{y},t)$ . The point is that providing educated guesses for them seems to be more reasonable than guessing for G and J, and might be a starting point for the derivation of ad hoc SSE-s for particular non-Markovian environments.

# Properties of the Pilot Wave or Properties of the Trajectory? Predicting observables using Wavefunctions vs using trajectories

From the provided narrative, we can see that a measurement operator  $\hat{G} = \sum_g g |g\rangle \langle g|$ , is just a way to gather an orthonormal basis  $\{|g\rangle\}_g$ , linked with a value g of each state  $|g\rangle$ . Now, one could ask: is this g a property of the system before or after the measurement? And is it a property of the pilot wave (or the wavefunction) alone or could we also assign it to the piloted trajectory? If we only considered as ontologically relevant the position of the Bohmian trajectory, then g would just be a number due to the particular von Neumann coupling Hamiltonian for the measurement. But, what if we could physically ground it?

When we measure projectively, we are determining the post-measurement state with a probability due to the pre-measurement state. Thus, one thing we do end up knowing about the pre-measurement wavefunction is the projection probabilities it had onto the possible post-measurement states (which indeed seems to be a property of the pilot wave -not the Bohmian trajectory  $per\ se$ -). Now, the question is: is g as well a determined property of the wavefunction? Well, since the post-measurement state  $|g\rangle$  if immediately measured again will yield the same g for sure, but not if we prepare and measure again the initial state, unless we allow a pilot-wave to have multiple uncertain values simultaneously, g does not seem to be a property of the wavefunction. In contrast, a property of the underlying Bohmian trajectory of the subsystem  $\vec{x}^{\xi}(t)$  (say, its velocity or associated Bohmian energy), has a definite and unique value at all times. Could we then say g is a property of the trajectory? This debate was not experimentally interesting until, very recently the community started to acknowledge that properties predicted for Bohmian trajectories can indeed be experimentally measured, when Wiseman proposed his protocol to operationally measure the velocity of a quantum particle [31].

More recently, some of the authors derived a very insightful observation that extends this concept, allowing, if wished, not only to consider and derive an Orthodox observable operator for any property of a Bohmian trajectory, but to consider that any Orthodox observable operator (commute with the position operator or not), is the observation of a property of the Bohmian trajectory [33, 34]. Consider it ontological or not, this leads to several practical advantages in the characterization of a quantum system in the abscense of observation, as we will explain now following [33, 34].

Given any arbitrary (Hermitian) operator  $\hat{G}$ , describing the observable property G for the subsystem S, with normalized EWF  $|\psi(t)\rangle$ , let us define the function  $G^{\psi}(x,t) := \frac{\langle \vec{x}|\hat{G}|\psi(t)\rangle}{\langle \vec{x}|\psi(t)\rangle}$ , which is the weak value [32] of  $\hat{G}$  for the state  $|\psi(t)\rangle$  at time t, post-selected at  $\vec{x}$  (we will discuss its meaning later on). Then, we could define a real function  $G_B^{\psi}(\vec{x},t) = \mathbb{R}e\{G^{\psi}(x,t)\}$ , which we could say is the property G of the Bohmian trajectory passing from  $\vec{x}$  at time t. Until here it seems just a cumbersome definition. Now, let us compute the expected value for  $\hat{G}$  and try to write it as a function of  $G^{\psi}(x,t)$ :

$$\langle \hat{G} \rangle(t) = \langle \psi(t) | \, \hat{G} | \psi(t) \rangle = \int \langle \psi(t) | \, |\vec{x}\rangle \, \langle \vec{x} | \, \hat{G} | \psi(t) \rangle \, dx = \int \langle \psi(t) | \vec{x}\rangle \, \langle \vec{x} | \psi(t) \rangle \, \frac{\langle \vec{x} | \, \hat{G} | \psi(t) \rangle}{\langle \vec{x} | \psi(t) \rangle} dx \tag{14}$$

$$\langle \hat{G} \rangle(t) = \int |\psi(\vec{x}, t)|^2 G^{\psi}(\vec{x}, t) dx \tag{15}$$

which means that the ensemble average of the (possibly complex) G(x,t) of the Bohmian trajectories (following quantum equilibrium [7]), gives the same expected value for the observable as using the operator. But here comes the most interesting point: since  $\hat{G}$  is an observable, its expected value will be a real number, meaning that  $\langle \hat{G} \rangle = \mathbb{R}e\{\langle \hat{G} \rangle\}$ , which means that:

$$\langle \hat{G} \rangle(t) = \int |\psi(\vec{x}, t)|^2 G_B^{\psi}(\vec{x}, t) dx \tag{16}$$

Such that the real property  $G_B^{\psi}(\vec{x}(\vec{\xi},t),t)$  of the  $\vec{\xi}$ -th Bohmian trajectory, seems to mean something relevant about G, since its ensemble average gives the same expected value as the operator expected value. What is even more: what if  $|\psi\rangle$  was an eigenstate of  $\hat{G}$  with eigenvalue g? What would the suggested Bohmian property related with G be in that case?

$$G_B^{\psi}(x) = \mathbb{R}e\left\{\frac{\langle \vec{x}|\hat{G}|\psi\rangle}{\langle \vec{x}|\psi\rangle}\right\} = \mathbb{R}e\left\{\frac{\langle \vec{x}|\psi\rangle\,g}{\langle \vec{x}|\psi\rangle}\right\} = g \tag{17}$$

which means that an eigenstate of  $\hat{G}$  must be a state for which every Bohmian trajectory has the same value for the property G. So not only this identification serves to compute the expected value  $\langle \hat{G} \rangle$ , or does it serve to say that effectively g is a property of the Bohmian trajectory, but it is even a tool to construct the whole  $\hat{G}$  operator itself! We could look for eigenstates of the observable G by looking for states where all Bohmian trajectories have the same value g for  $G_B^{\psi}$ . This will be useful, because there are observables, like the many electron current in a nano-electronic device, for which there is no clear measurement operator, yet there is a current property for the Bohmian trajectory [29, 28]. In fact, this could justify why any projective measurement is also interesting from the Bohmian view-point.

We will say it once again: since we placed no restriction on  $\hat{G}$ , this means that for **every** observable of a quantum system, we are mathematically safe (if wished), to assume that at all times, each Bohmian trajectory has an ontologically determined value for them. Not only that, these values, will in fact evolve continuously in time, as long as wavefunctions always evolve unitarily (which is the case in Bohmian mechanics for the Universal wavefunction), with all its implications.

As the icing of the cake, it turns out, as we proved in [33], that if we set as  $\hat{G}$ , the momentum operator  $\hat{p_k}$  of the k-th degree of freedom, the Bohmian trajectory property  $G_B^{\psi}(\vec{x},t)$  is exactly equal to the Bohmian momentum field  $m_k v_k(\vec{x},t)$ . If we set as  $\hat{G}$ , the Hamiltonian operator  $\hat{H}$ , the property  $G_B^{\psi}(\vec{x},t)$  turns out to be exactly equal to the Bohmian energy (kinetic plus classical and quantum potentials) of the trajectory crossing  $\vec{x}$ . And the list goes on. Even, if wished, for the three components of spin [35], with all the debate within Bohmian mechanics behind it.

As if all this was not already hard to digest, there is even an additional theoretical point to be remarked. It is about the definition we have made for the Bohmian property  $G_B^{\psi}$  associated with G, as the real part of the so called weak value, which we called the "local-in-position weak value" [33, 34]. It turns out, as is so well known [32], the real part of our weak value can be experimentally measured as follows. First couple an ancilla with the subsystem of EWF  $|\psi\rangle$ , through the von Neumann Hamiltonian explained in the beginning of the chapter, which if coupled with a big enough interaction strength  $\mu$ , produces the separation in macroscopically separated eigenstates of  $\hat{G}$ . Yet, let the interaction strength be very small, such that the system state is only slightly perturbed (just a little amount of information is leaked to the environment). Then, the ancilla position is strongly measured (through a strong coupling of a second ancilla, macroscopic separation etc.). The Neumann interaction is such that the position of the ancilla will always have the same expected value as the coupled observable (in our case  $\hat{G}$ ), no matter the sterngth  $\mu$ . But there is still a step more. Right after the weak measurement of  $\hat{G}$  has been performed, a third ancilla is rapidly coupled, now to the (only slightly perturbed) system, with a Neumann Hamiltonian to projectively measure the position of the system (which according to Bohmian mechanics, will let us know the Bohmia position of the system). Then, instead of computing the expected observed G by averaging the weak measurements, we could only average the weak measurements that after-wards led to a strong measurement (Bohmian position

for the system) at a certain  $\vec{x}$ . This procedure then, exactly gives the number  $G_B^{\psi}(x)$ , and is called a post-selected weak measurement. One could say, this is just juggling with numbers due to several observations, but, one could also perfectly legitimately assume (especially after what we have revealed) that this is the measured expected value for G, because all the times that our Bohmian trajectory was at  $\vec{x}$ , the system had indeed the property  $G_B^{\psi}(\vec{x})$ . Phenomenologically this does not "prove" Bohmian trajectories are ontologically real, yet, this leaves a yet more appealing interpretation for pragmatic experimentalist, in the opinion of some authors.

## Practical Applications of Local-In-Position Weak Values

This Bohmian discovery, as already anticipated, has several practical applications [33, 34]. On the one hand, this means that we can numerically predict the expected value for an observable without the need to have explicitly defined its formal operator. One can derive the observable  $G_B^{\psi}(x,t)$  in the language of Bohmian mechanics, which is very akin to classical mechanics, and compute the trajectory ensemble average of the property instead. This is how we achieved for example the capability to predict the total electrical current crossing the active region of a two-terminal nano-device operating at high frequencies (THz) [28, 29]. The total current at such frequencies needs to consider the displacement component (time-derivative of the electric field). This makes it hard to even ask what the operator should look like. However, we can define the total current for the Bohmian trajectory of a k-th electron  $\vec{x}_k^{\xi}(t)$  of charge q through a surface  $\sigma$  as:  $I_k^{\xi}(t) = \int_{\sigma} \vec{J}^{\xi}(\vec{r},t) \cdot d\vec{s} + \int_{\sigma} \varepsilon(\vec{r},t) \frac{\partial \vec{E}^{\xi}(\vec{r},t)}{\partial t} \cdot d\vec{s}$ , where  $\varepsilon(\vec{r},t)$  is the electric permittivity,  $\vec{J}^{\xi}(\vec{r},t) = q \frac{d\vec{x}_k^{\xi}(t)}{dt} \delta(\vec{r} - \vec{x}_k^{\xi}(t))$  the particle current density, and  $\vec{E}^{\xi}(\vec{r},t)$  is the electric field generated by the electron, as a solution to the Gauss equation. Then, as proven in [29], for two terminal devices of longitudinal length L with metallic contact surfaces  $\sigma$  of width and height w, h >> L, the total current contribution in the surfaces is:  $I_k^{\xi}(t) = \frac{q}{L} v_k^{\xi}(\vec{x} = \vec{x}_k(t), t)$  where  $v_x$  is the longitudinal direction Bohmian velocity of the electron. Then the total current at the surface  $\sigma$ , the sum of these contributions, will be the same as the one measured in the ammeter as explained before.

Yet, perhaps as the most sounded example of the application of this discovery: it provides an operational answer to the search of non-contextuality in the definitions of measurements involving two different times [33]. Saying that a property of a system is contextual means that its value depends on the environment employed to convey that information to the observer. It turns out that for a single-time (static) measurement of the expectation of a property G of a subsystem S, which-ever fiducial state we employ in a (either strong or weak) measurement, the expected value will be the same, and will be the value we can calculate by only knowing the pre-measurement EWF of the S (thus it is a non-contextual property). However, if we want to know the correlation information (say the expectation of the product of observables) between an observable F at time  $t_1$  and an observable G at time  $t_2$ , but attempting to avoid any particular apparatus to enter in the picture this will be impossible within the standard measurement theory [33, 34, 35]. To begin with, if their operators do not commute,  $\langle \hat{G}(t_2)\hat{F}(t_1)\rangle$  in the Heisenberg formalism will in general give a complex number. Instead, we could correlate the result of a strong measurement of F at time  $t_1$  and a strong measurement of G at time  $t_2$ , but since the measurements will project the state to EWF eigenstates, the backaction of the measuring device will be obvious. Alternatively, we could look for  $\mathbb{R}e\left\{\langle \hat{G}(t_2)\hat{F}(t_1)\rangle\right\}$ , which is the correlation of a weak measurement of F at time  $t_1$  and a strong measurement of G at time  $t_2$ , which seems to provide a more "unperturbing" view of a correlation of the dynamic variables. Yet, as shown in [35], even an ideally weak measurement does perturb the system in a way that is dependent for example, on the particular fiducial state employed for it.

This has led, for example in quantum thermodynamics, to a "no-go" theorem [36] stating that there cannot exist a work superoperator that simultaneously satisfies all the physical properties required from it, since work is a dynamical property implying at least two times. Other thermodynamic properties that are history dependent suffer from the same issue [37, 38]: any definition of them even

 $<sup>^{11}</sup>$ The legitimacy of a well defined electric field in Bohmian mechanics will be described in the last part of the chapter.

involving weak measurements are dependent on the particular measuring scheme employed, which causes as many quantum work definitions as measuring schemes exist.

A similar issue raises when trying to measure the maximum working frequency of state-of-the-art transistors and hence the performance of modern computers [39]. For this, the time spent by electrons in nano-scale transistors, the dwell time in the active region, must be measured. One could place position detectors in the two ends a and b of the active region, but this would result in a highly contextual measurement, when in operation no computer has such detectors in the ends of its transistors [40, 41].

All this calls for a way to paradoxically measure "unmeasured" dynamical properties of a quantum subsystem. Dynamical properties that could be predicted in a simulation without any explicit introduction of a particular measuring ancilla. It turns out, the Bohmian property  $G_N^{\psi}(\vec{x},t)$  is such a property, which "paradoxically" can indeed be measured, but is a property strictly belonging to the unmeasured system.

For example, the problem of non-contextual two-time correlations of dynamical variables for a system wavefunction  $|\psi(t)\rangle$ , can be simply circumvented by computing the expectation as would be operationally done by definition: for a system with homogeneously sampled trajectories  $\{\vec{x}^{\xi}(t)\}_{\xi\in\Sigma}$  and ontologically deterministic observables  $G_B^{\psi}(\vec{x},t)$  and  $F_B^{\psi}(\vec{x},t)$ , the frequentist definition (following quantum equilibrium [7]) would be:

$$\langle G(t_2)F(t_1)\rangle = \lim_{|\Sigma| \to \infty} \frac{1}{|\Sigma|} \sum_{\xi \in \Sigma} G_B^{\psi}(\vec{x}^{\xi}(t_2), t_2) F_B^{\psi}(\vec{x}^{\xi}(t_1), t_1) =$$
 (18)

$$= \int |\psi(\vec{\xi}, 0)|^2 \, \mathbb{R}e \left[ \frac{\left\langle \vec{x}^{\xi}(t_2) \middle| \hat{G} \middle| \psi(t_2) \right\rangle}{\left\langle \vec{x}^{\xi}(t_2) \middle| \psi(t_2) \right\rangle} \right] \mathbb{R}e \left[ \frac{\left\langle \vec{x}^{\xi}(t_1) \middle| \hat{G} \middle| \psi(t_1) \right\rangle}{\left\langle \vec{x}^{\xi}(t_1) \middle| \psi(t_1) \right\rangle} \right] d\xi$$

In a similar way, we can solve the problems concerning a quantum work definition as done by [42, 43], by first noting that given a general system Hamiltonian  $\hat{H} = \sum_k \frac{-\hbar^2}{2m_k} \frac{\partial^2}{\partial x_k^2} + V(\vec{x}, t)$ , it is immediate to obtain using the Hamilton-Jacobi equation encoded in the Schrödinger equation that:

$$E_B^{\psi}(\vec{x}^{\xi}(t), t) = \mathbb{R}e\left[\frac{\langle \vec{x}^{\xi}(t) | \hat{H} | \psi(t) \rangle}{\langle \vec{x}^{\xi}(t) | \psi(t) \rangle}\right] = \sum_{k=1}^{n} \frac{1}{2} m_k v_k (\vec{x}^{\xi}(t), t)^2 + V(\vec{x}^{\xi}(t), t) + Q(\vec{x}^{\xi}(t), t)$$
(19)

with Q the well known Bohmian quantum potential [3, 4, 5]. Proving  $E_B^{\psi}(\vec{x}^{\xi}(t), t)$  is as anticipated, the total Bohmian energy of the trajectory at time t. Then, following classical mechanics, we can compute its associated Bohmian work (if conservative) as the energy difference:  $W^{\xi}(t_1, t_2) = E_B^{\psi}(\vec{x}^{\xi}(t_2), t_2) - E_B^{\psi}(\vec{x}^{\xi}(t_1), t_1)$ , which is non-contextual for this trajectory. Therefore, the definition of the non-contextual quantum work would be the ensemble average of the trajectory works:

$$\langle W(t_1, t_2) \rangle = \lim_{|\Sigma| \to \infty} \frac{1}{|\Sigma|} \sum_{\xi \in \Sigma} \left( E_B^{\psi}(\vec{x}^{\xi}(t_2), t_2) - E_B^{\psi}(\vec{x}^{\xi}(t_1), t_1) \right)$$
(20)

Finally, we could give a reasonable Bohmian answer to the search of an "unmeasured" dwell time, as the expected time spent by the Bohmian trajectory of the electron within the active region  $\Gamma \subset \mathbb{R}^3$ . Mathematically, the dwell time  $\tau$  for the  $\xi$ -th trajectory of the k-th electron with EWF  $\psi^{\xi}(\vec{x}_k, t)$  is by definition given by the Lebesgue integral:

$$\tau_B^{\xi} = \int_0^\infty dt \int_{\Gamma} \delta(\vec{r} - \vec{x}_k^{\xi}(t)) dr \tag{21}$$

which makes the expected time  $\langle \tau \rangle$  be, by the quantum equilibrium hypothesis:

$$\langle \tau \rangle = \lim_{|\Sigma| \to \infty} \frac{1}{|\Sigma|} \sum_{\xi \in \Sigma} \tau_B^{\xi} = \int_0^\infty dt \int_{\Gamma} |\psi^{\xi}(\vec{r}, t)|^2 dr$$
 (22)

which turns out to be a well-known expression employed to predict the dwell time.

Can we understand light matter interaction through well defined "Bohmian-electromagnetic fields"?

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