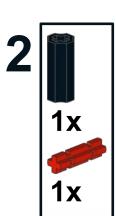
Part 1.

Model instructions by Dr. Olaf Filies Marcus Gordon Filies

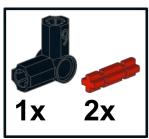
63 Parts

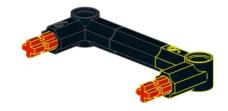
Driving pods for holonomic rama robot with Infineon XMC1100 mircocontoller and Infineon TLE94112 motor controller.

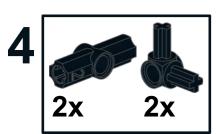


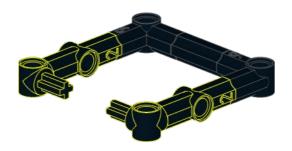


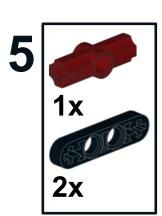


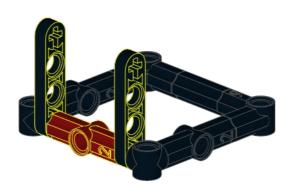


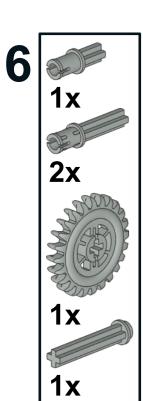


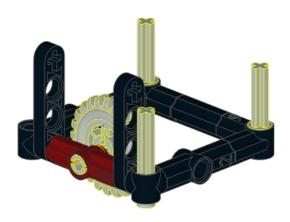


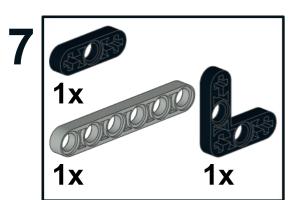


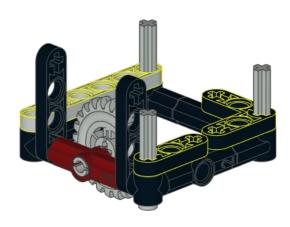


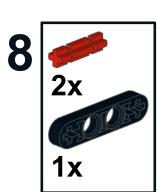


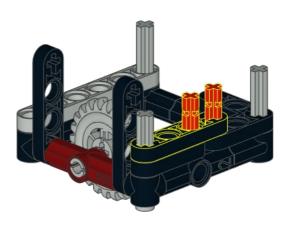






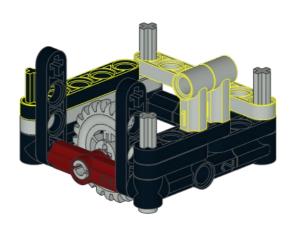


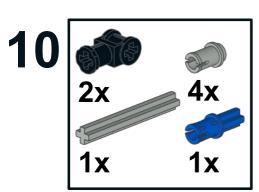


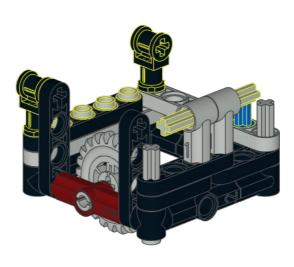


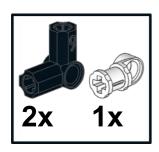
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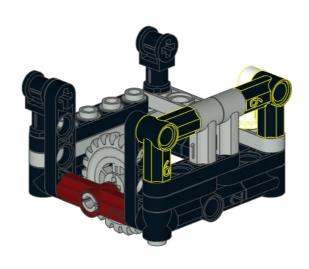
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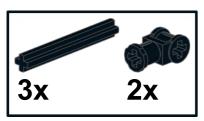


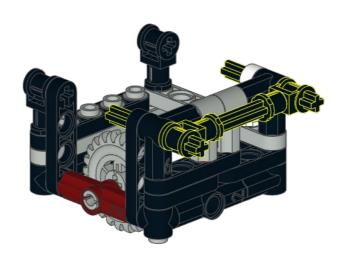


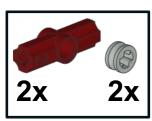


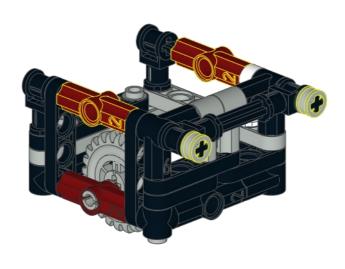


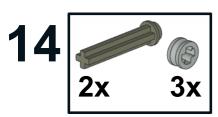


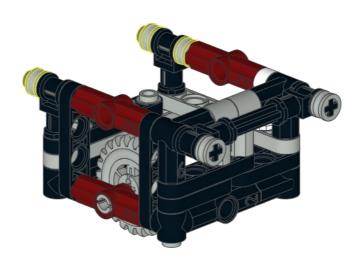




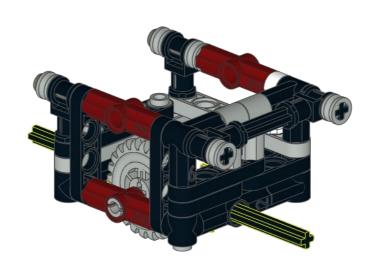






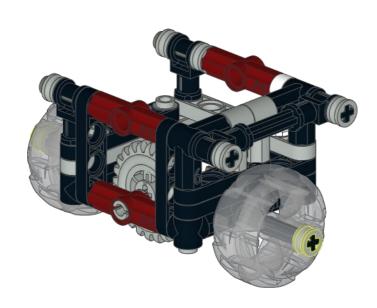




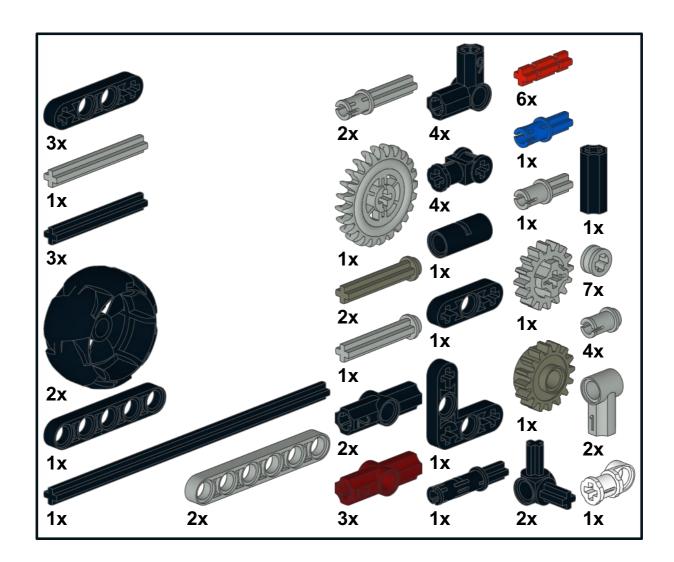




Exchange the wheels with: Rotacaster 35mm Double (35A) TPE Roller, ABS Body/ Lego or Vex Hub Adaptor







Model instructions by Dr. Olaf Filies, Marcus Gordon Filies

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