

Part 2.

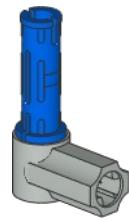
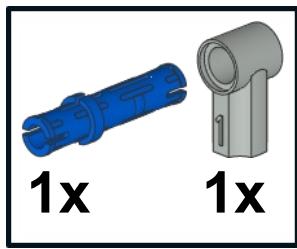
Model instructions by Dr. Olaf Filies Marcus Gordon Filies

125 Parts

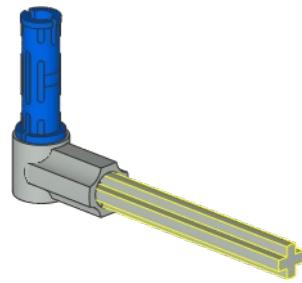
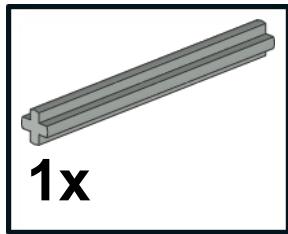
Dr. Olaf Filies, Marcus Gordon Filies

**Driving platform for holonomic rama robot
with Infineon XMC1100 mircocoontoller and Infineon TLE94112 motor controller.**

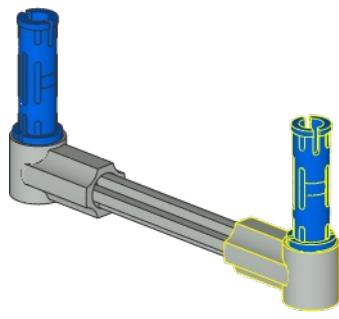
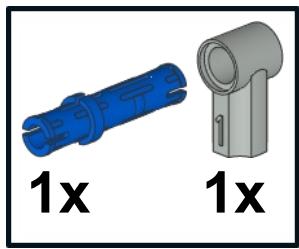
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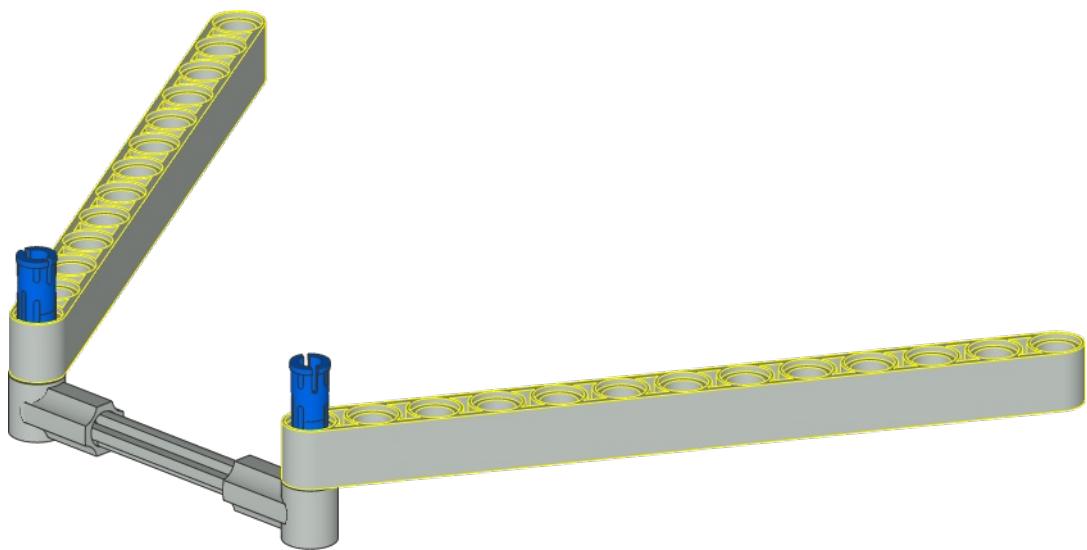
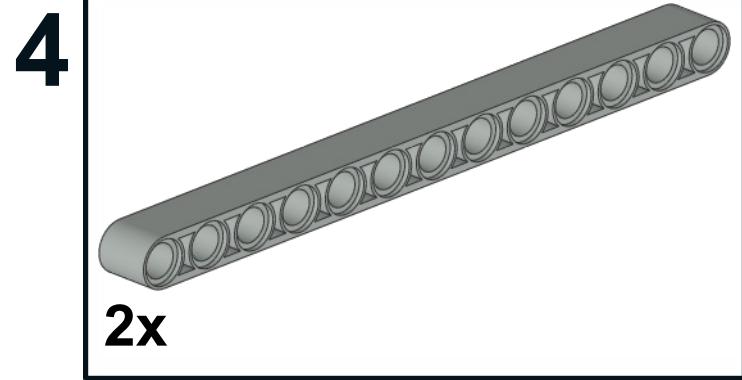


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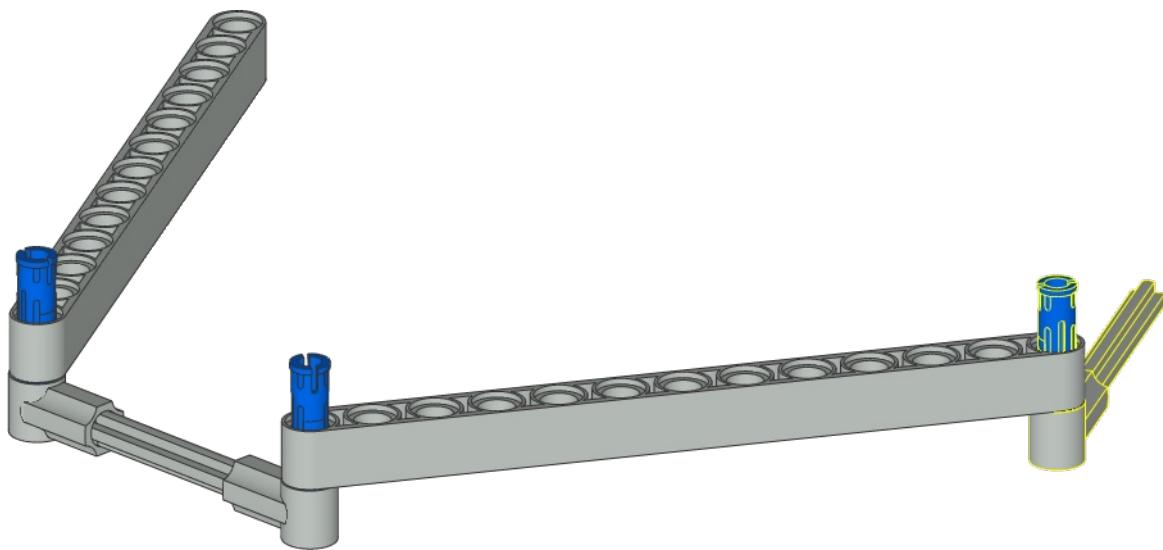
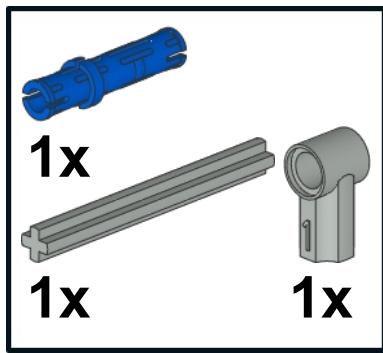


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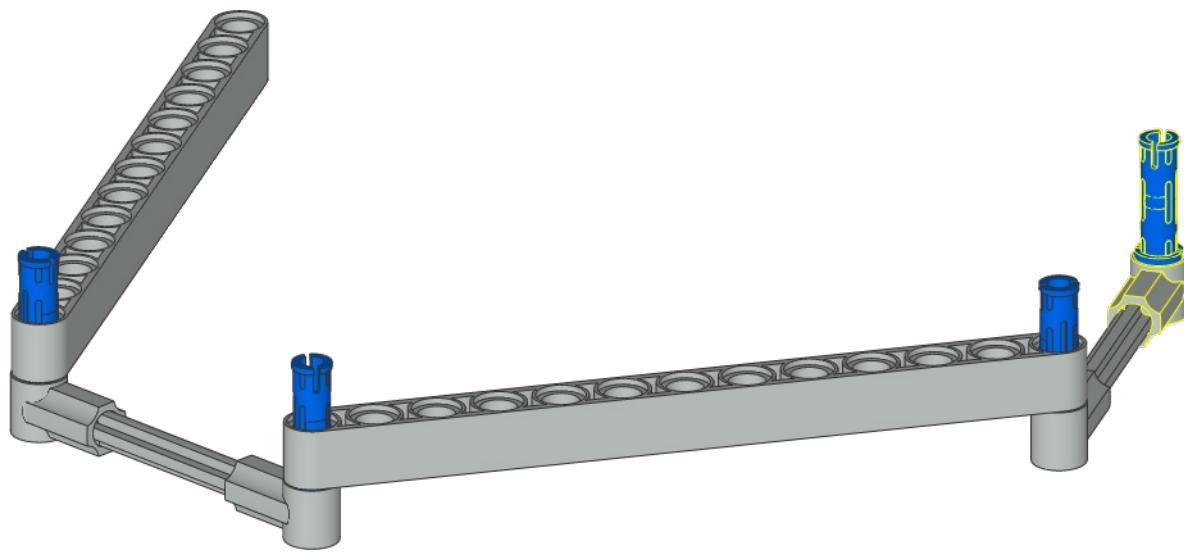
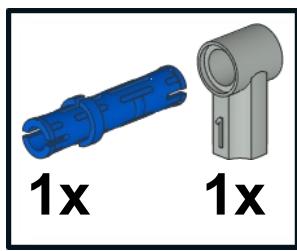


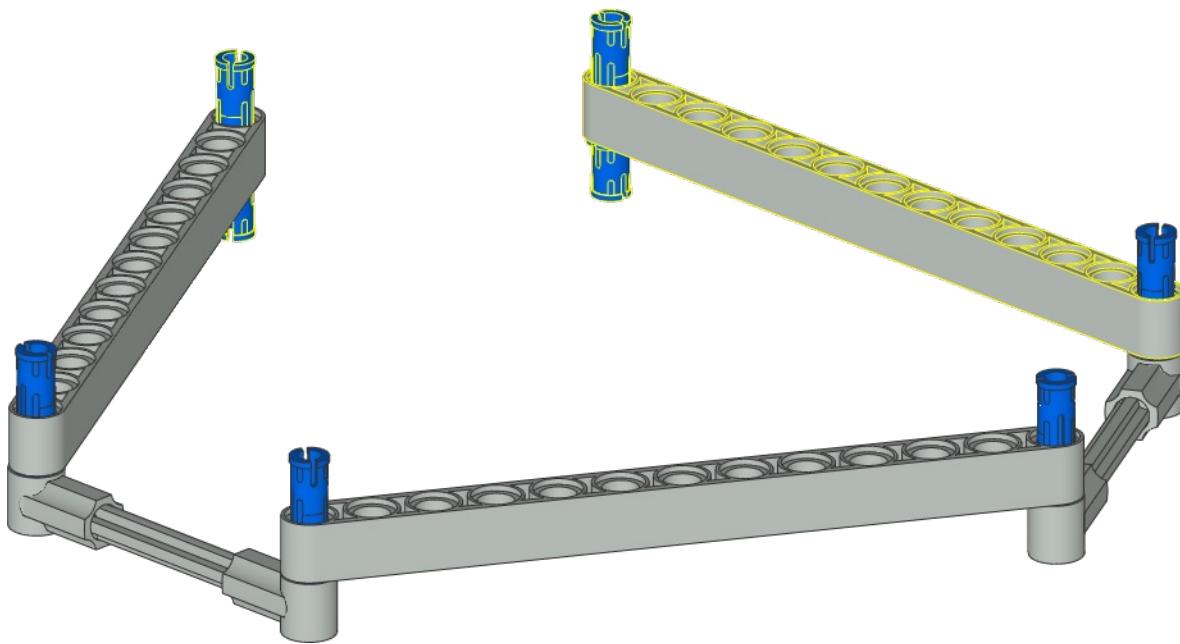
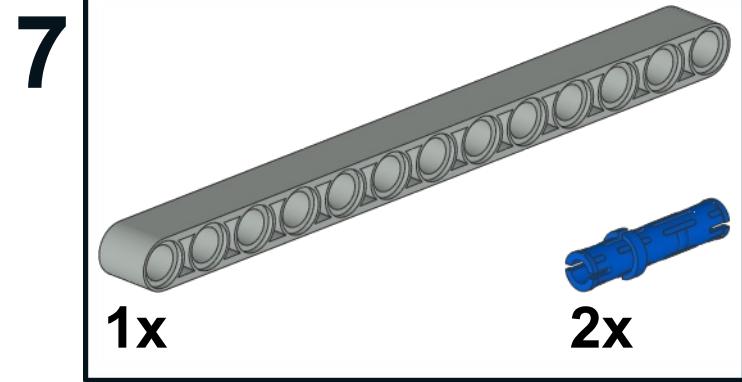


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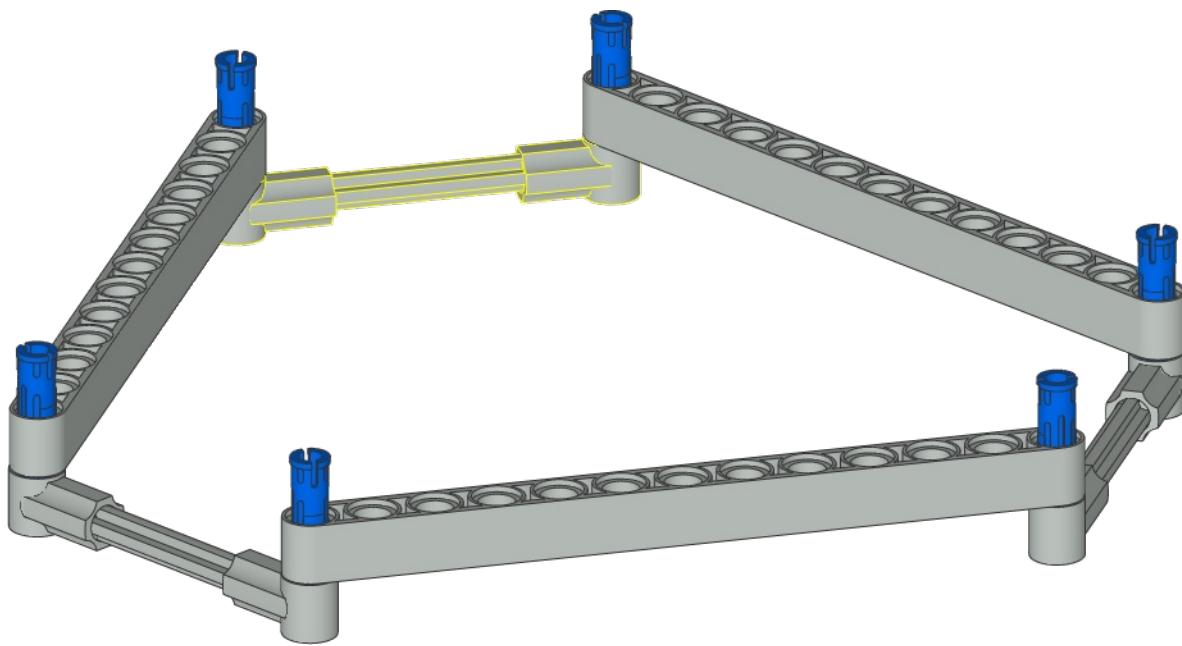
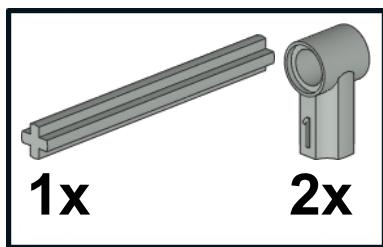


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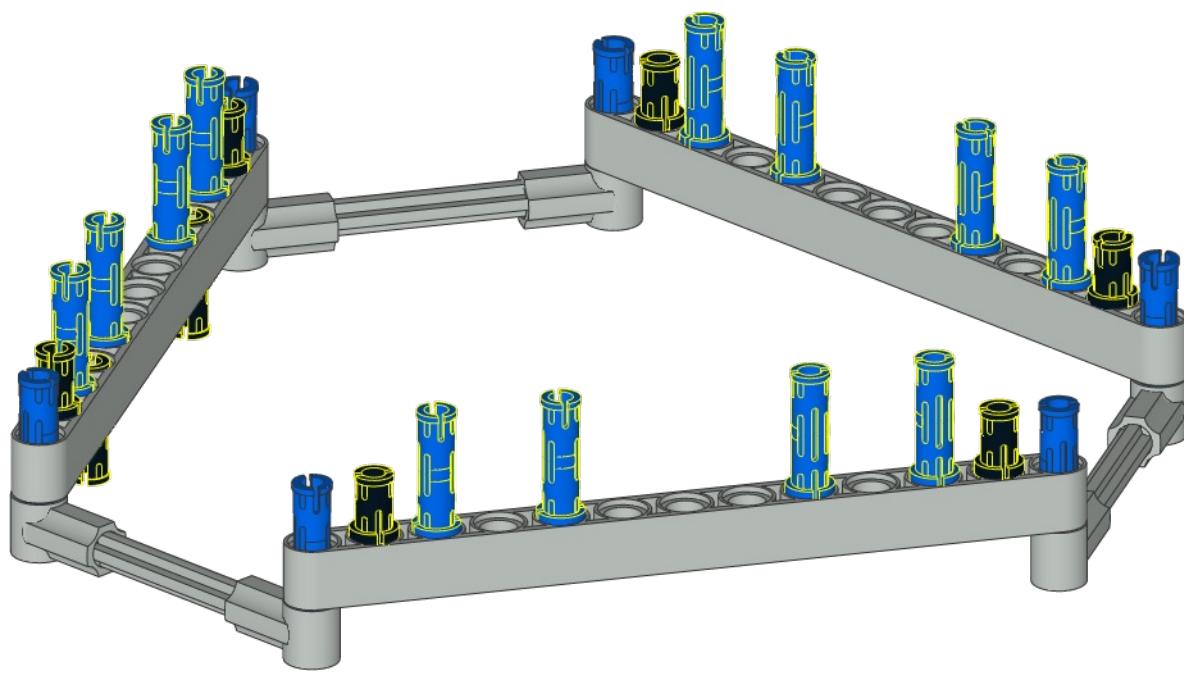
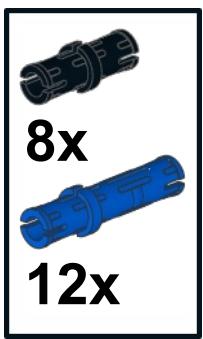




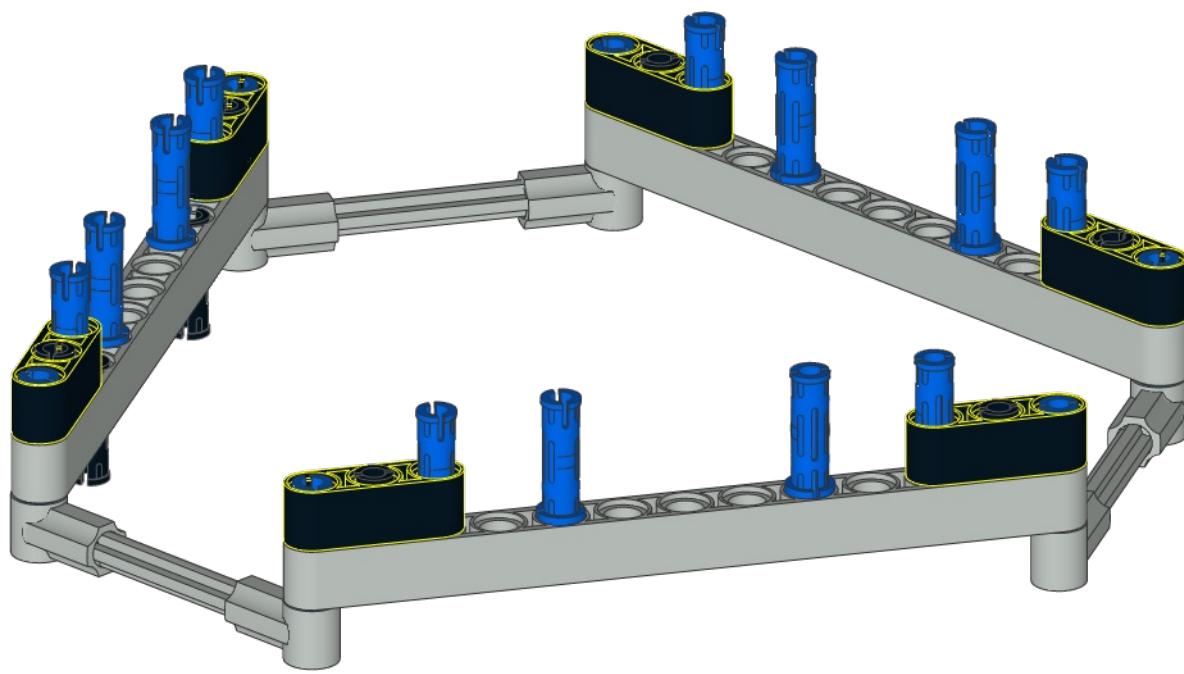
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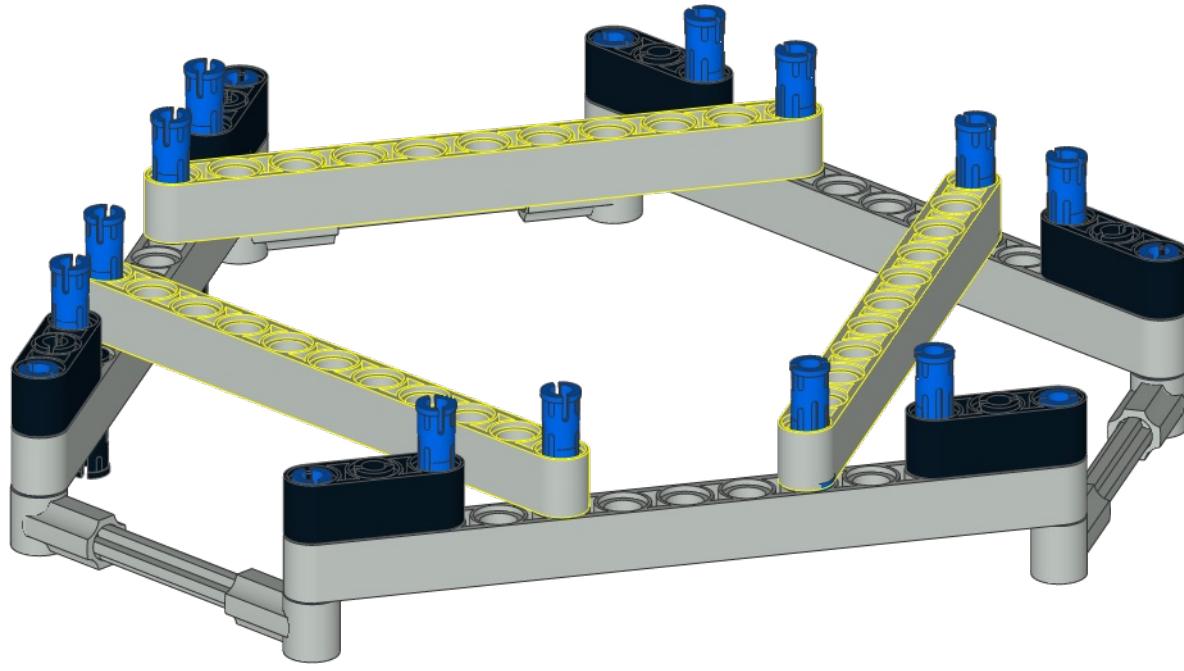
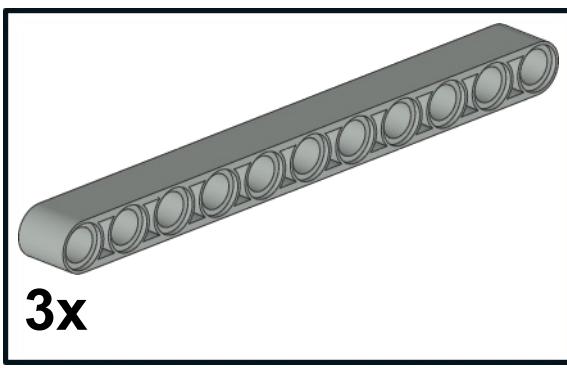
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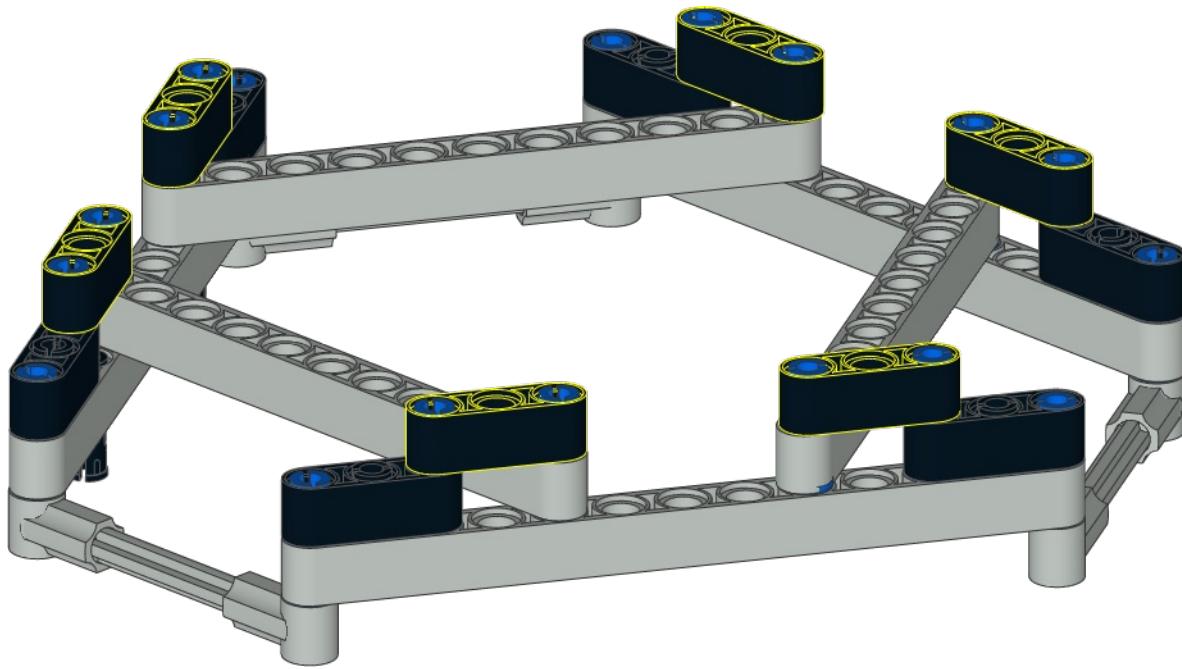
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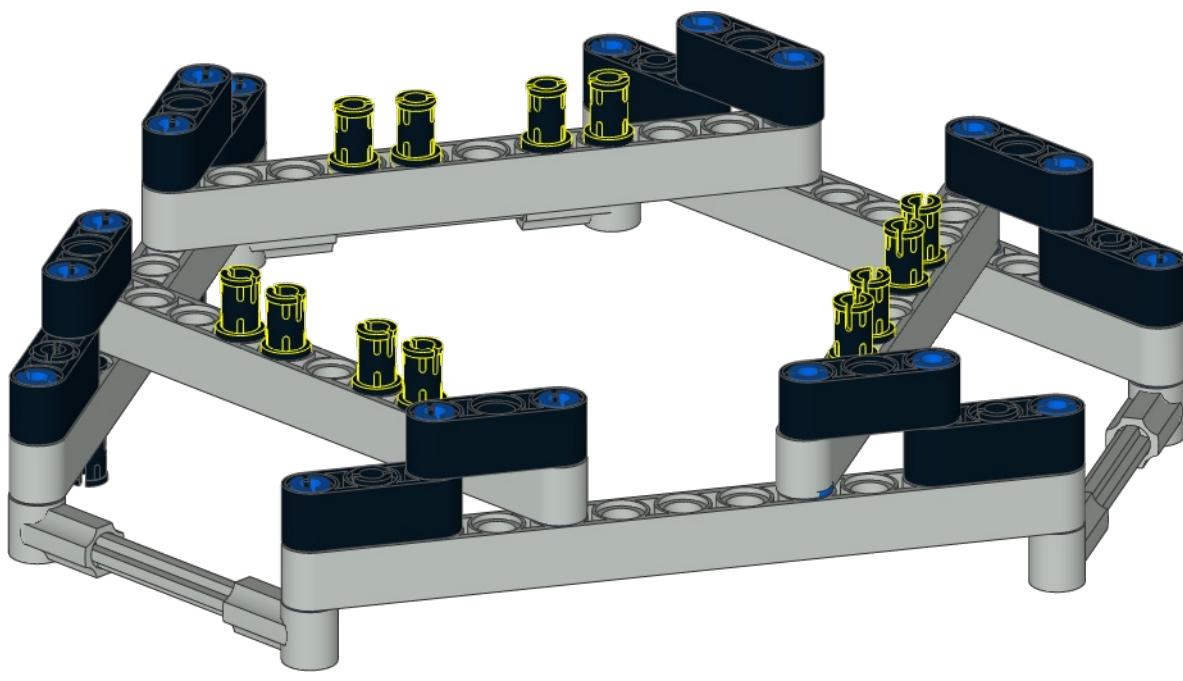
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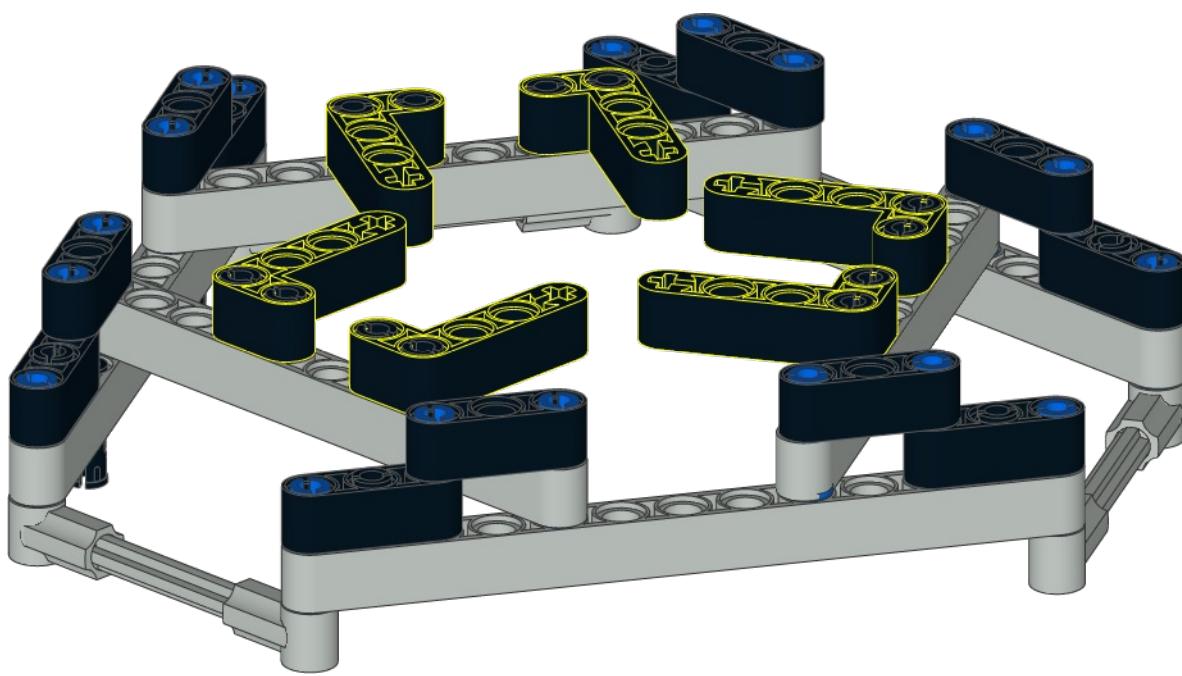
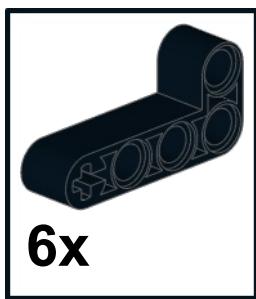
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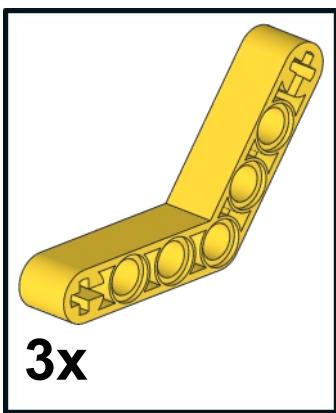
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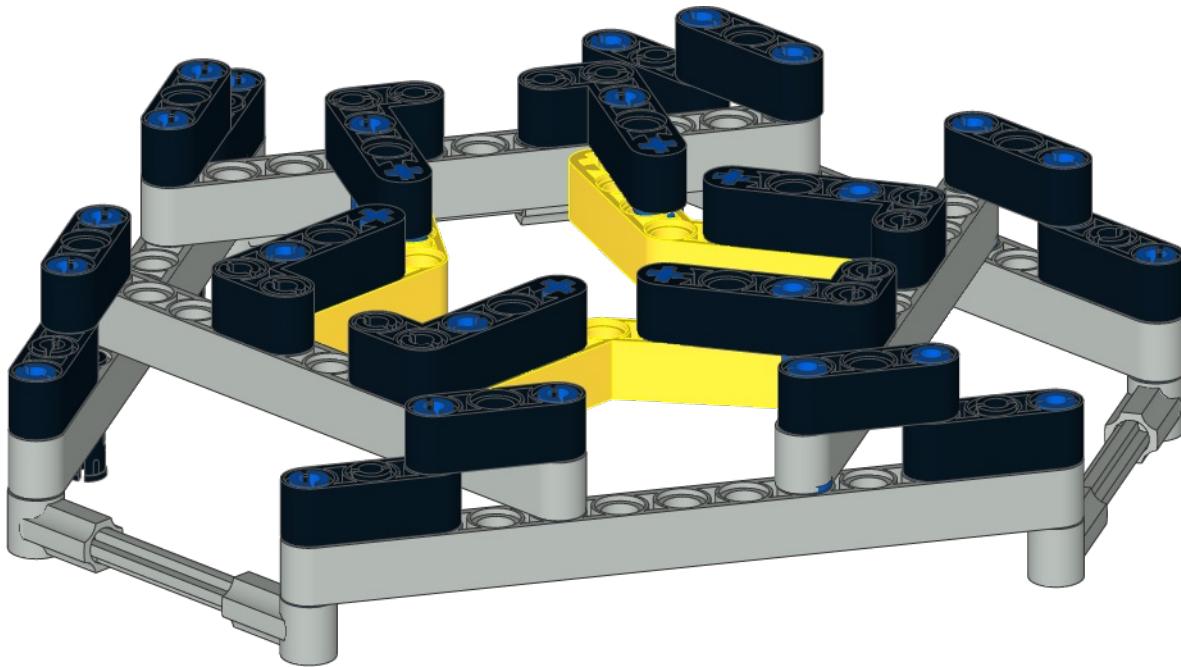
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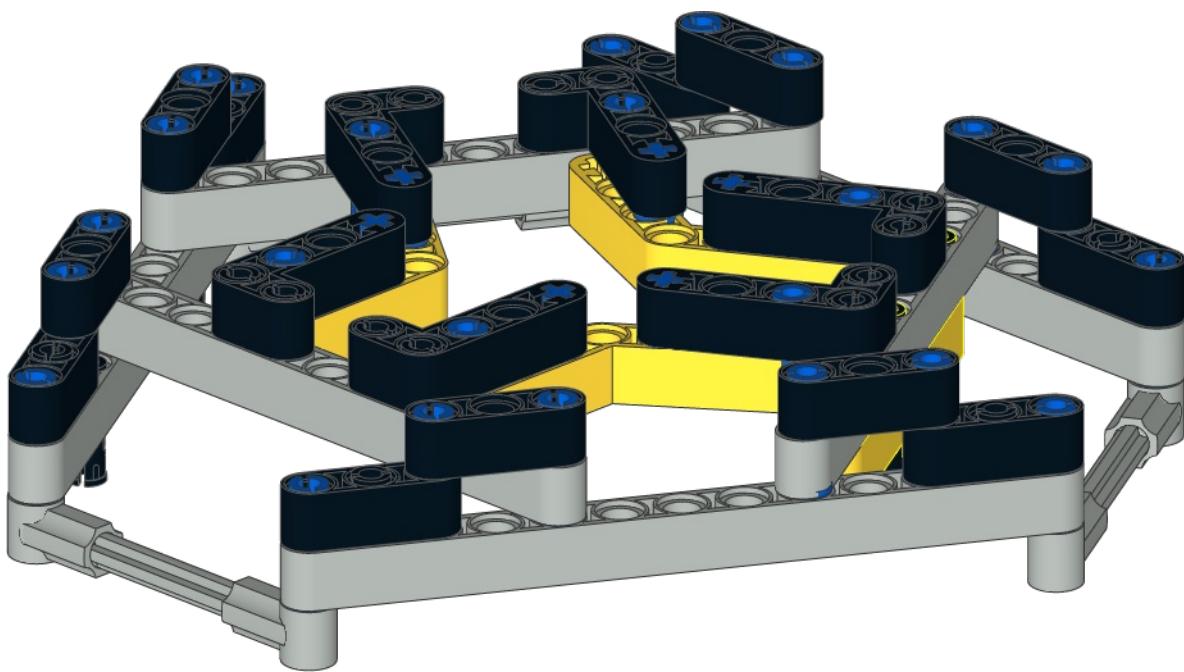
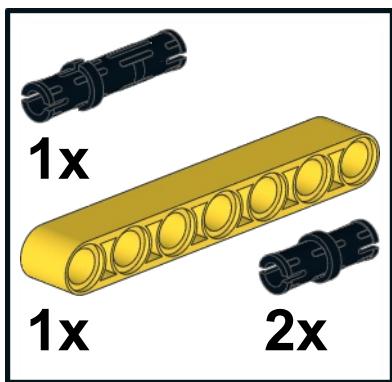
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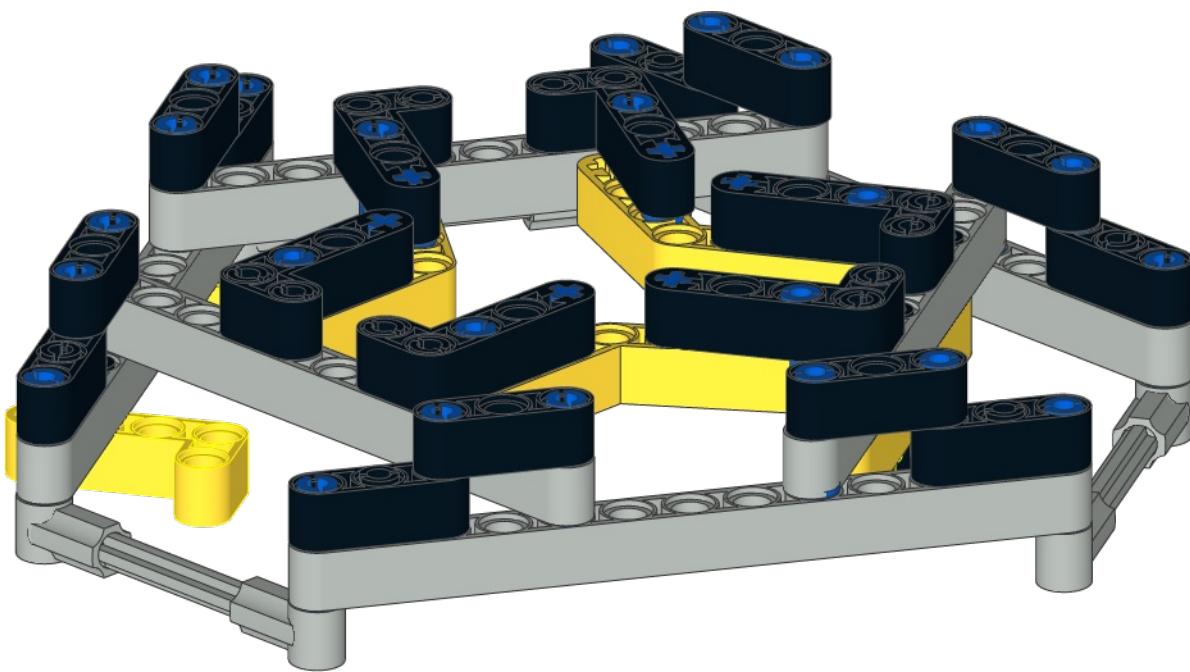
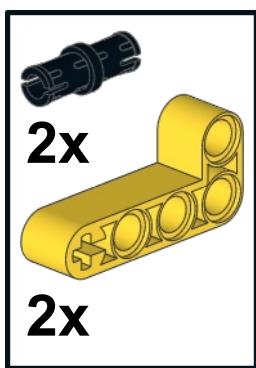
Bend and stretch carefully until lever fits.



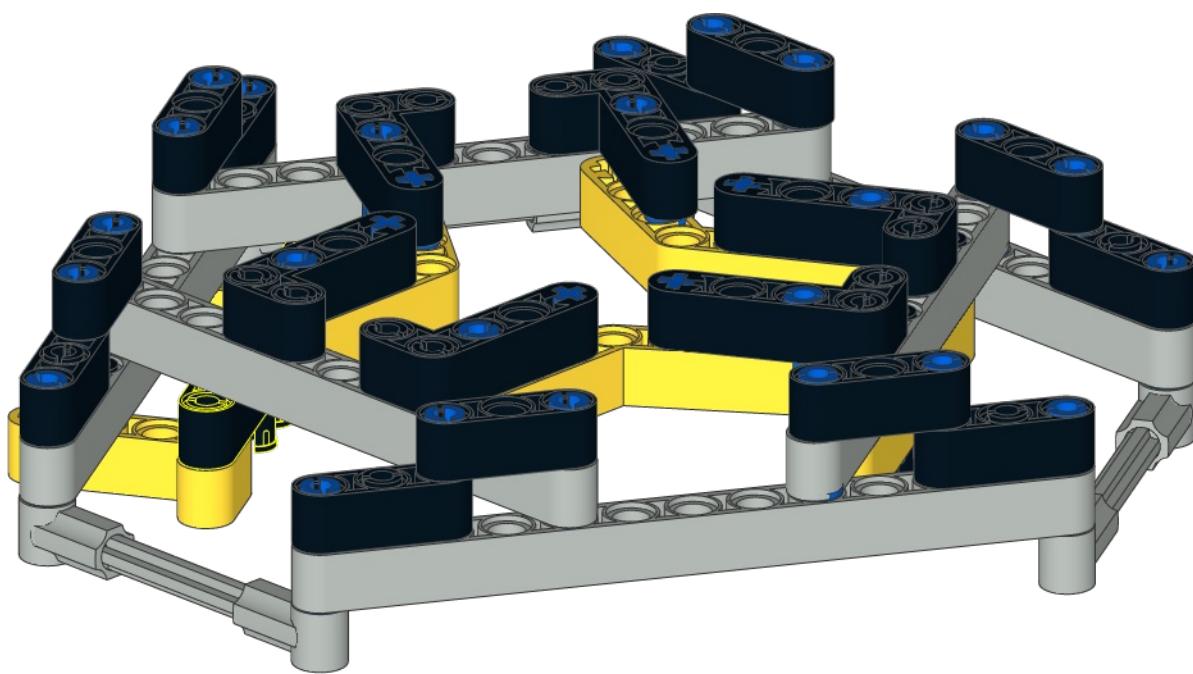
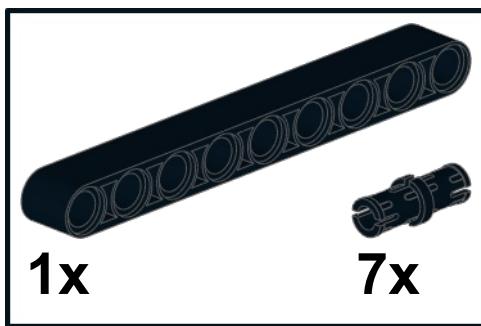
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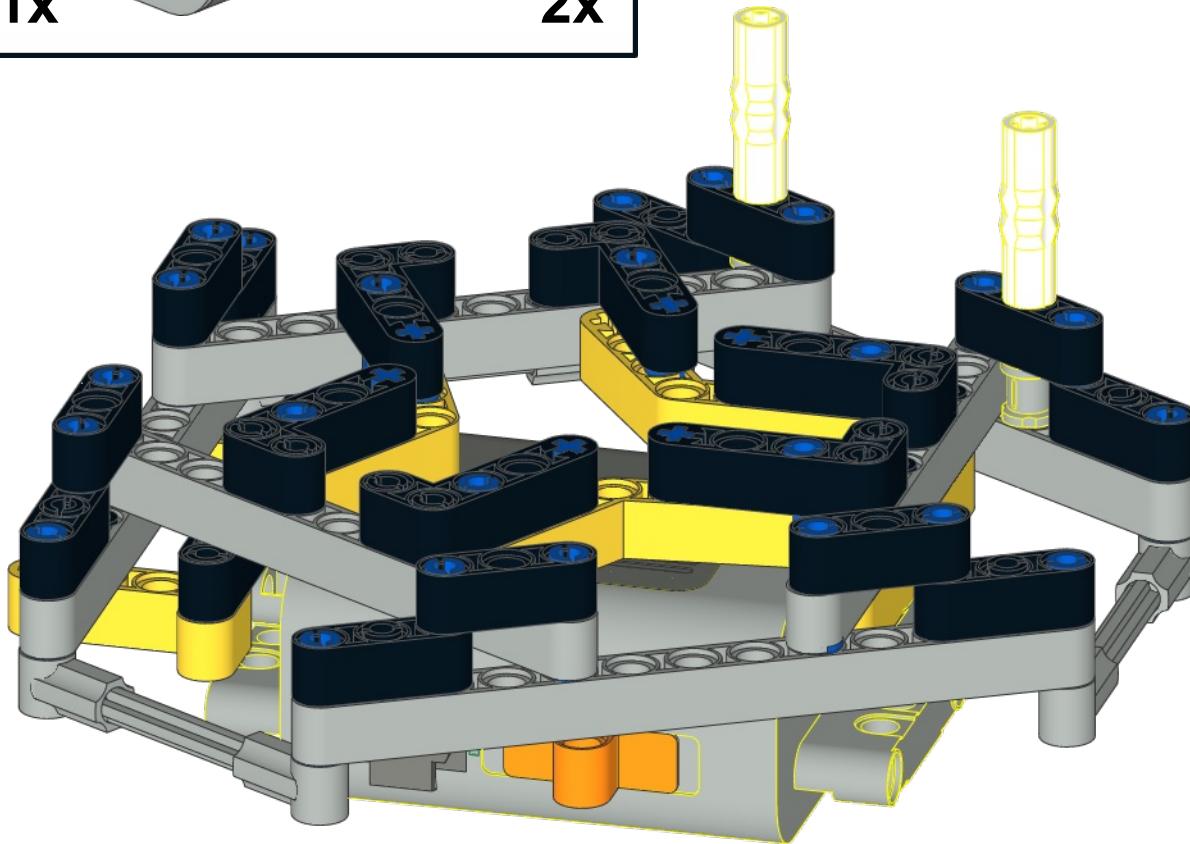
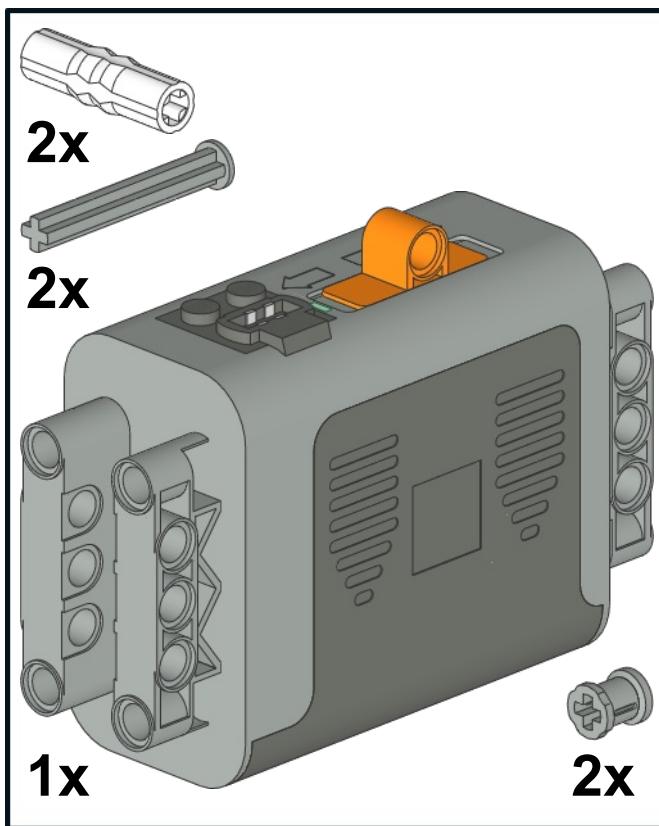
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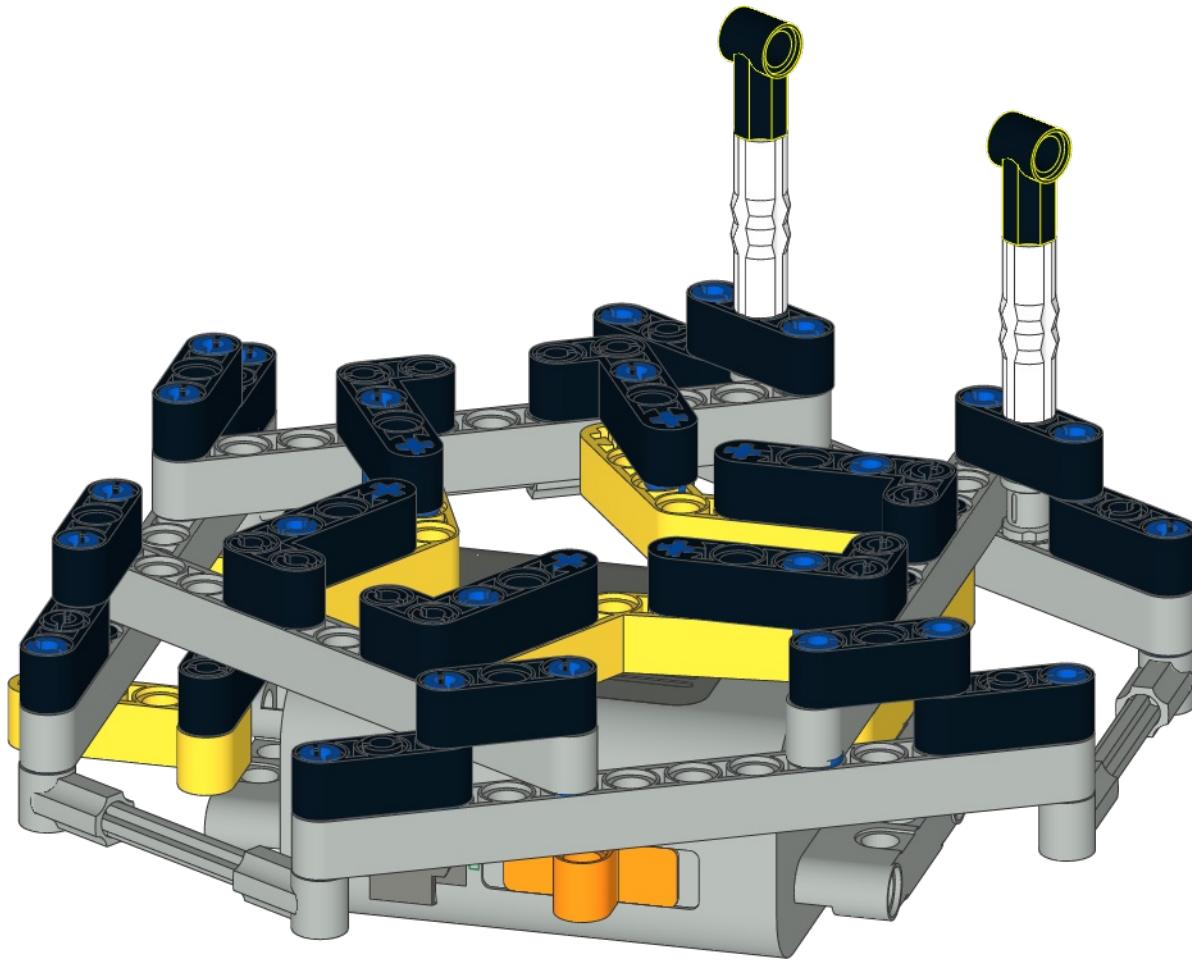
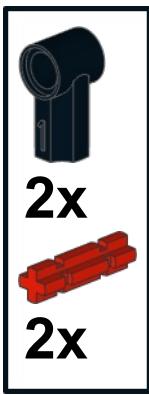
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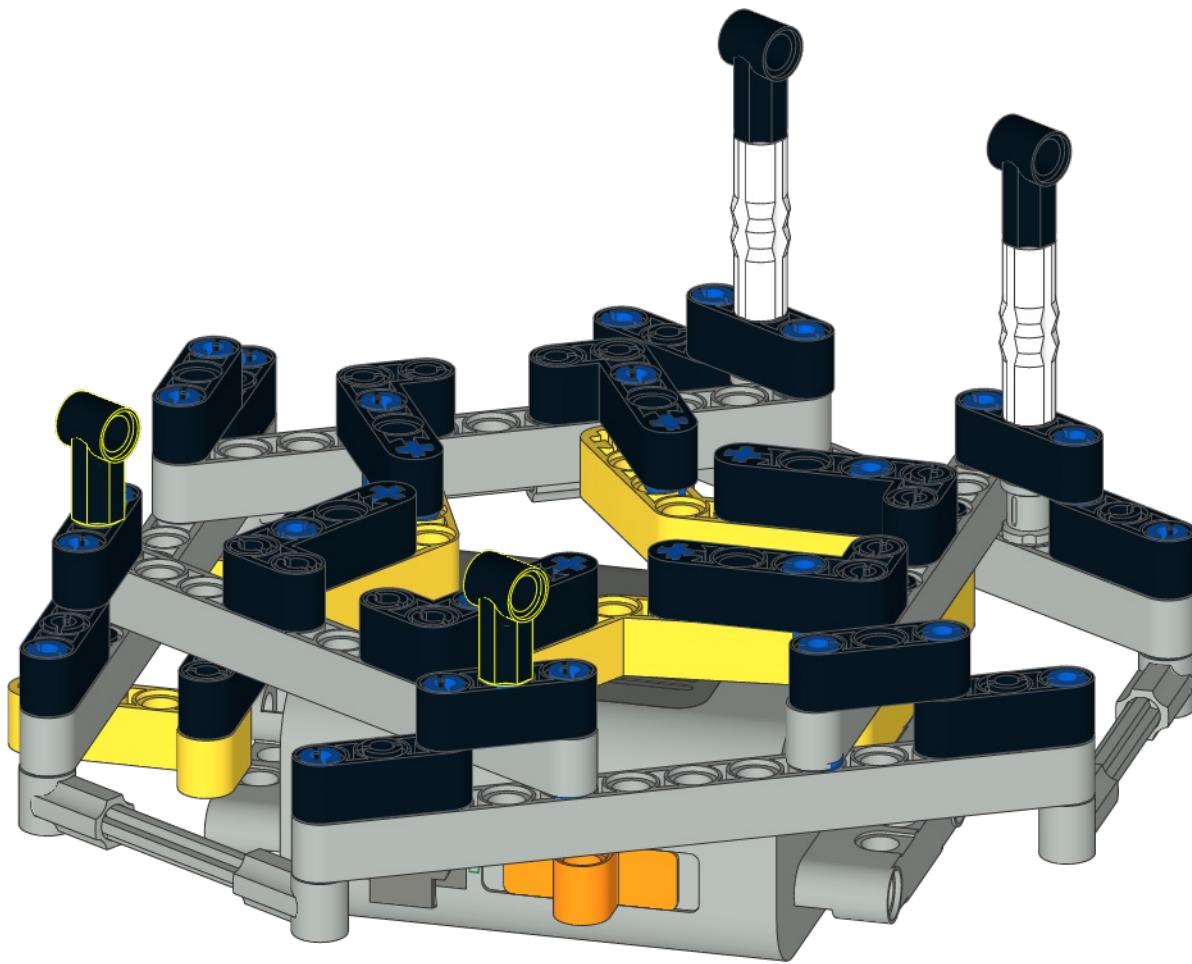
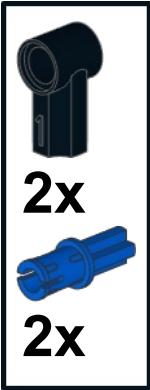
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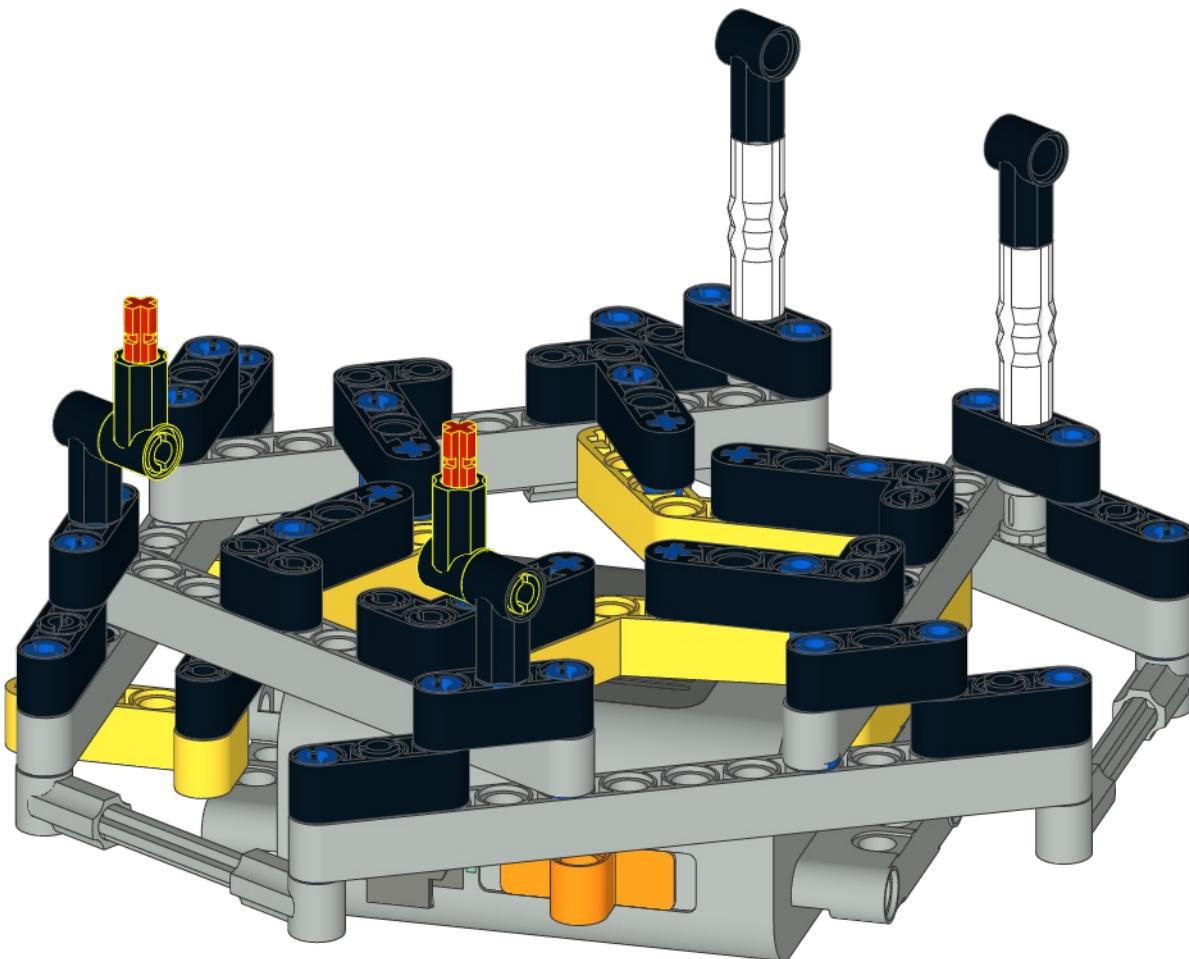
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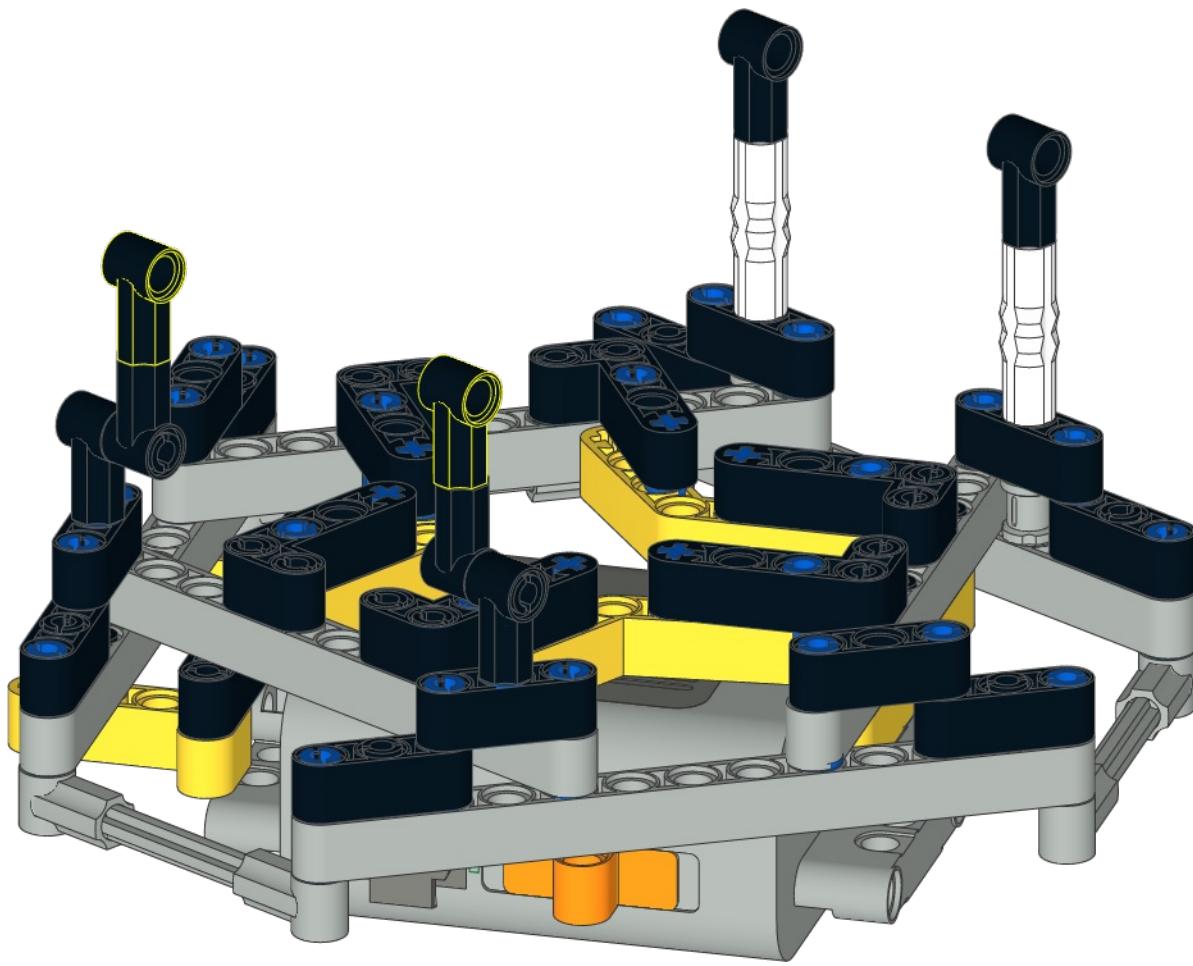
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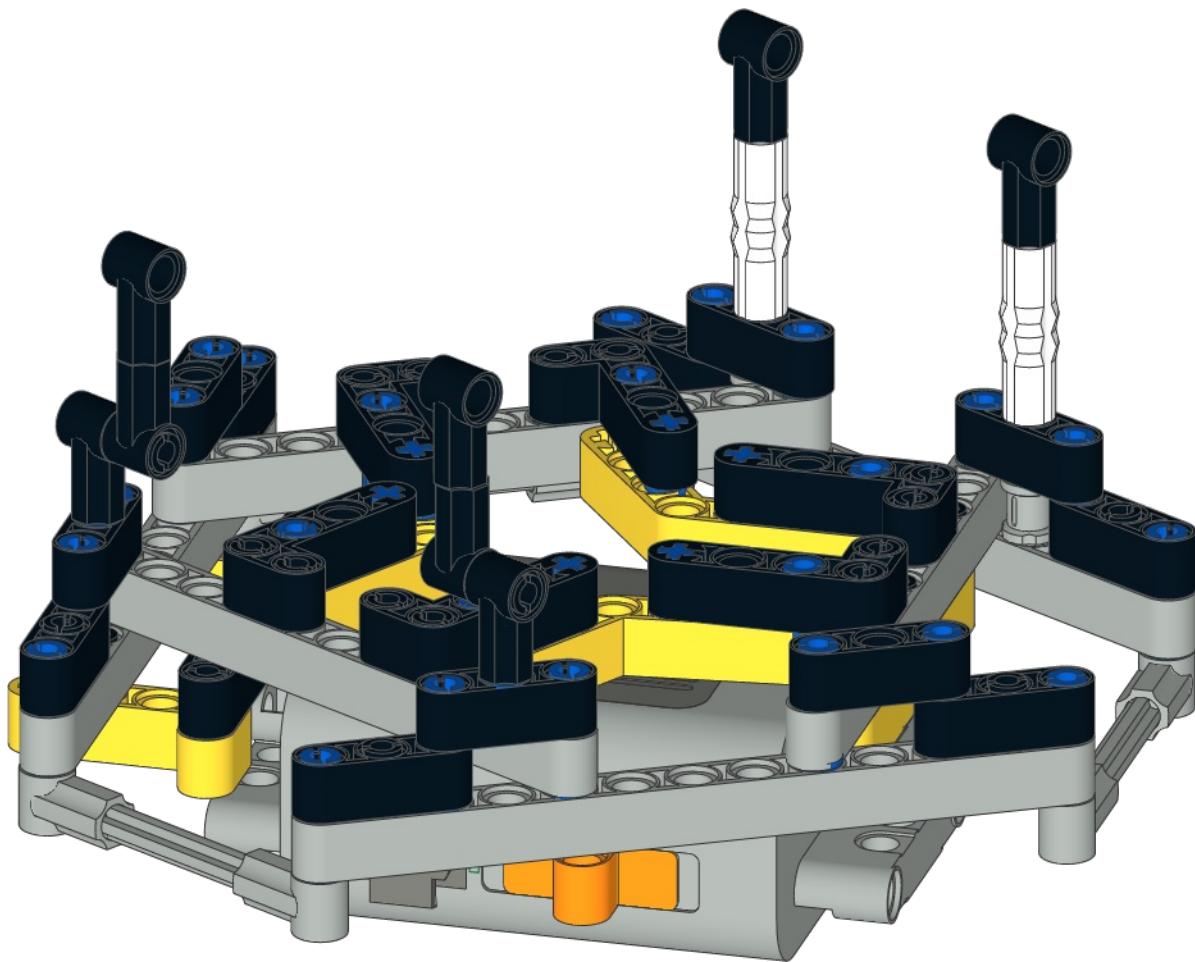
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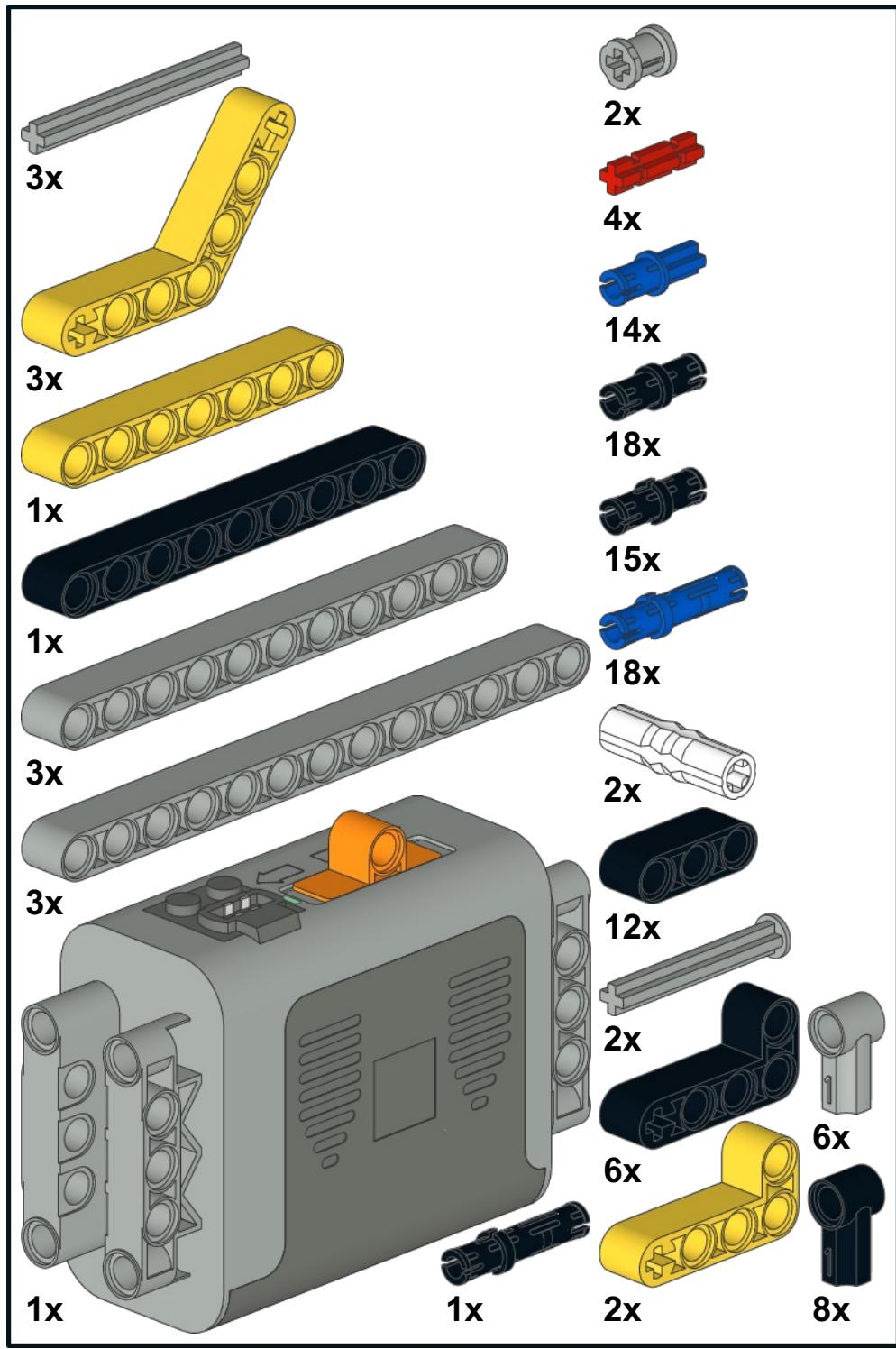


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Model instructions by Dr. Olaf Filies, Marcus Gordon Filies
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