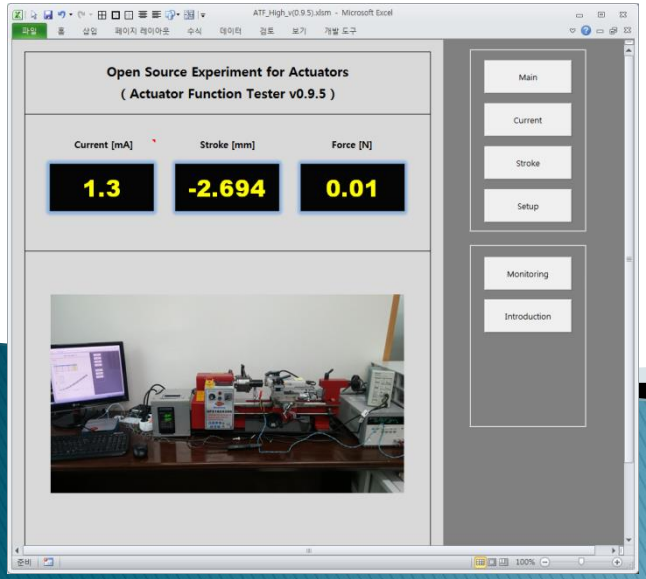
How to use AFT

(Actuator Function Tester)



2018-04-22

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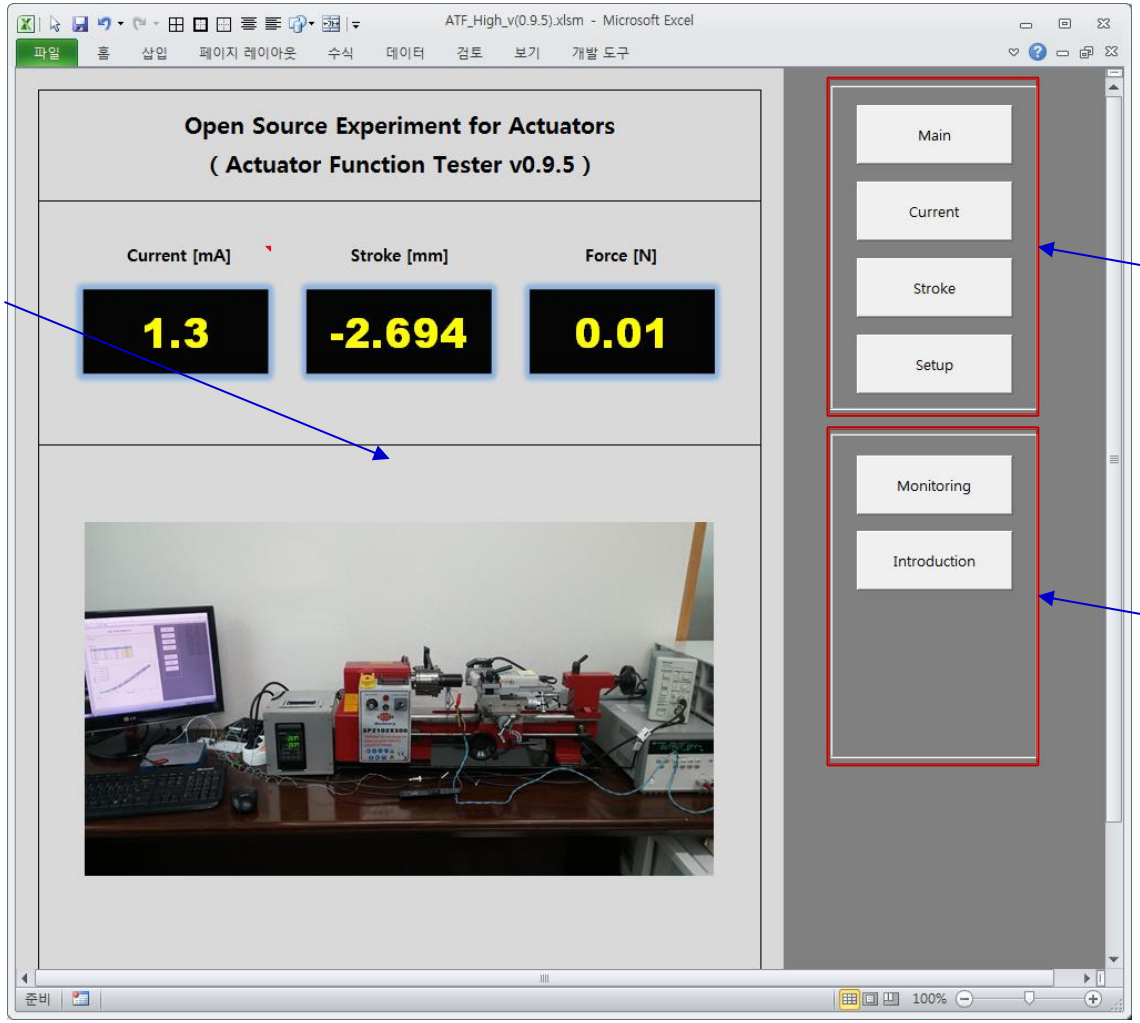
ATF Structure

Program Structure



Main Window

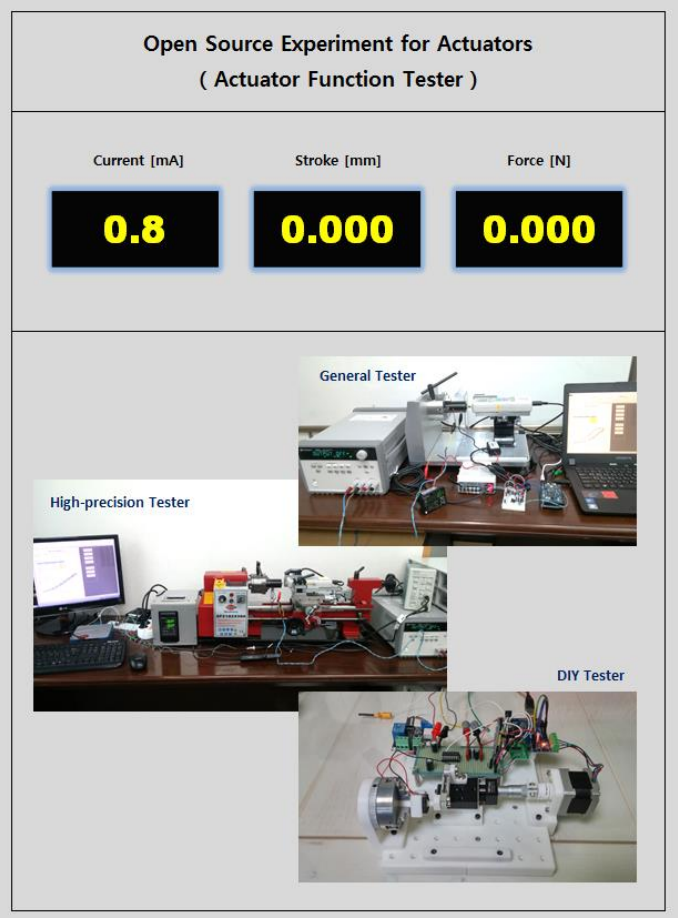
Move Page

Function Buttons

Pages

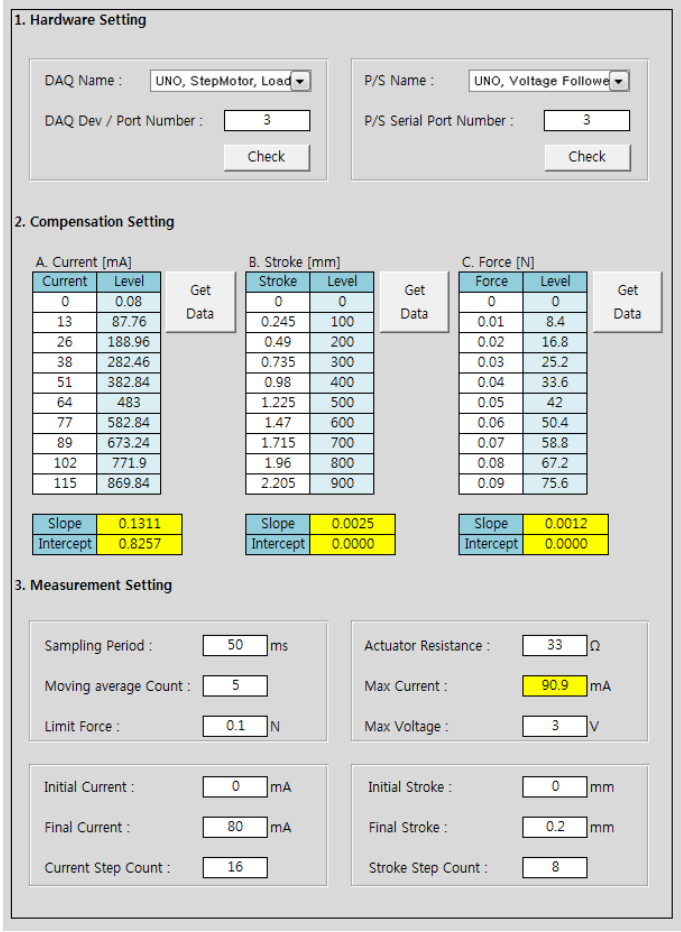
➢ Main Page

- Real time current, stoke and force data



➢ Settings Page

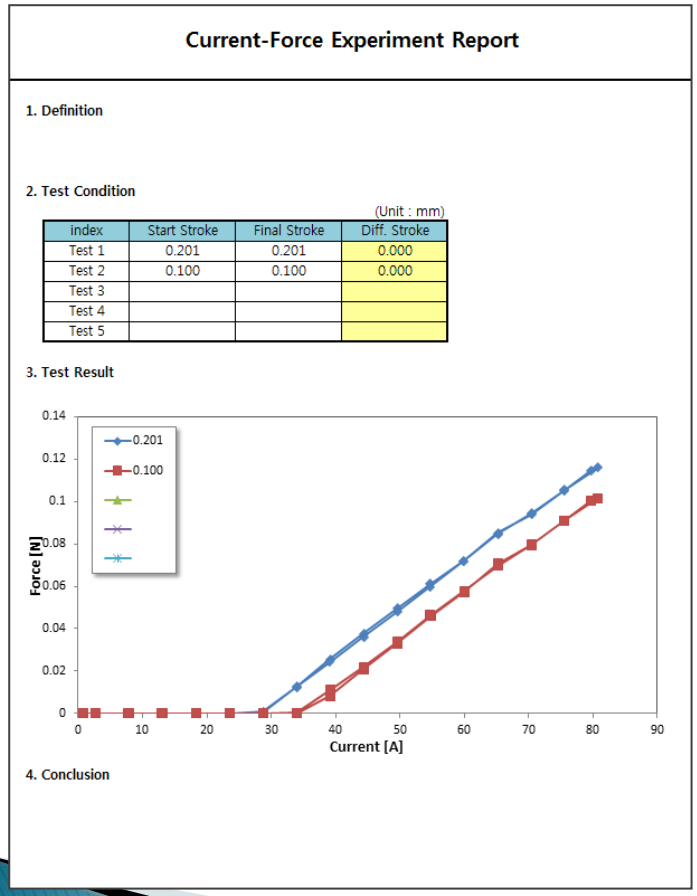
- Correction of physical values and setting hardware and measurement condition



Main Window

➢ Current Page

- Test of Current-Magnetic force



Current-Force Experiment Report

1. Definition

2. Test Condition

(Unit : mm)

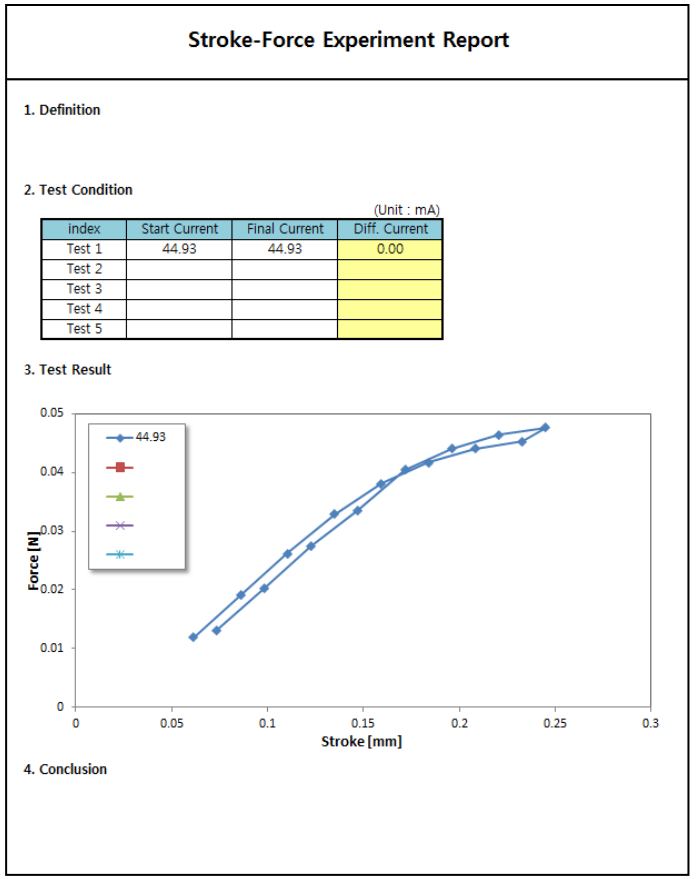
index	Start Stroke	Final Stroke	Diff. Stroke
Test 1	0.201	0.201	0.000
Test 2	0.100	0.100	0.000
Test 3			
Test 4			
Test 5			

3. Test Result

4. Conclusion

➢ Stroke Page

- Test of Stroke-Magnetic Force



Stroke-Force Experiment Report

1. Definition

2. Test Condition

(Unit : mA)

index	Start Current	Final Current	Diff. Current
Test 1	44.93	44.93	0.00
Test 2			
Test 3			
Test 4			
Test 5			

3. Test Result

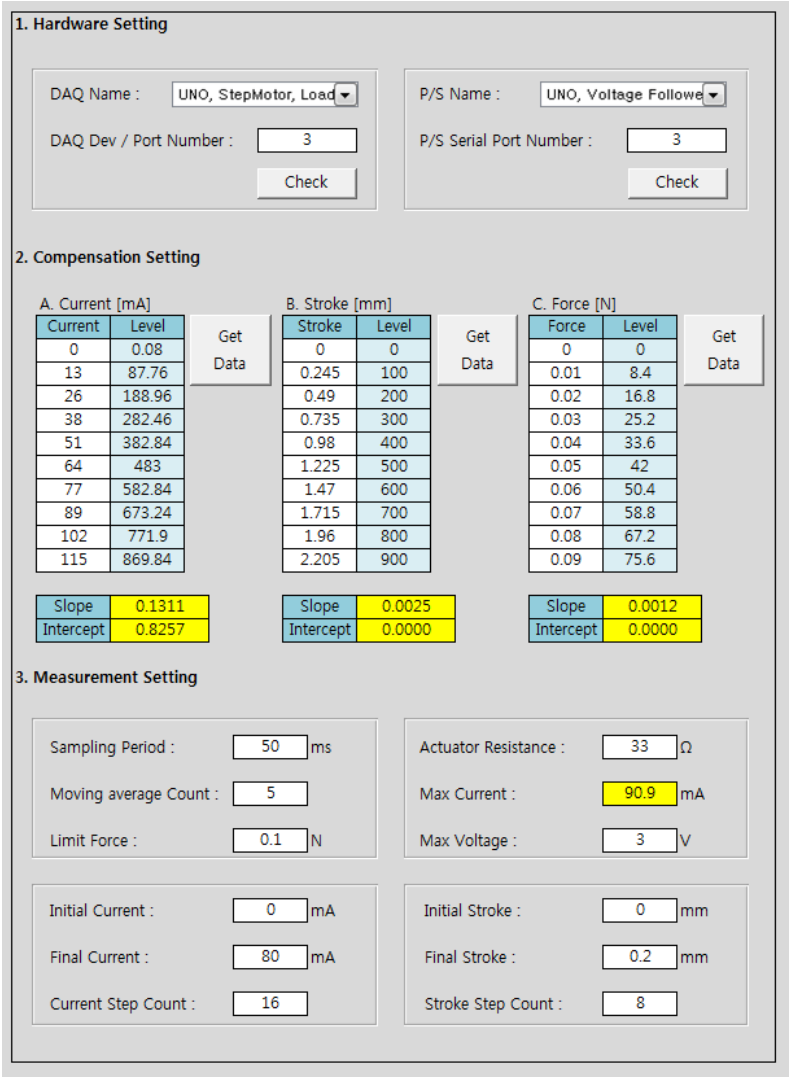
4. Conclusion

User Guide

Program Setting

➢ AFT Condition Setting

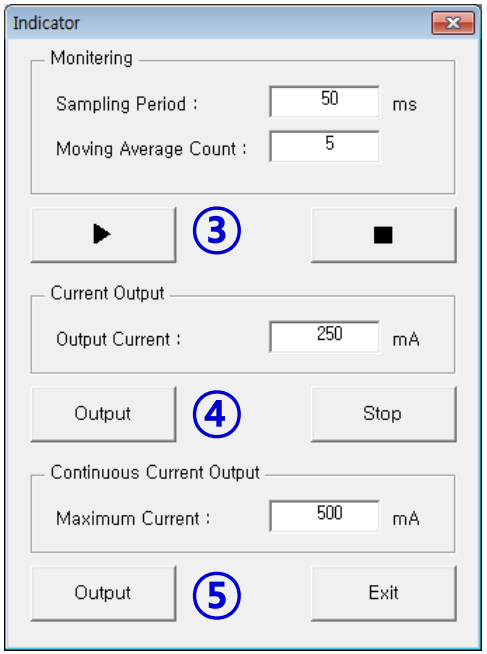
1. Refer the AFT Installation Manual

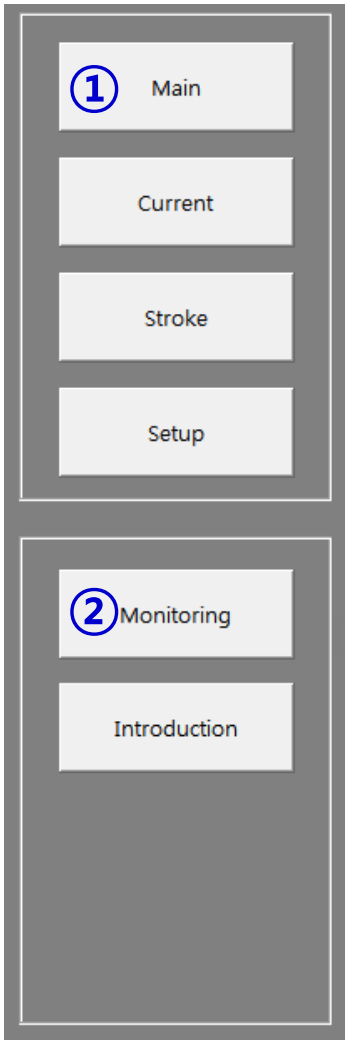


Data Monitoring

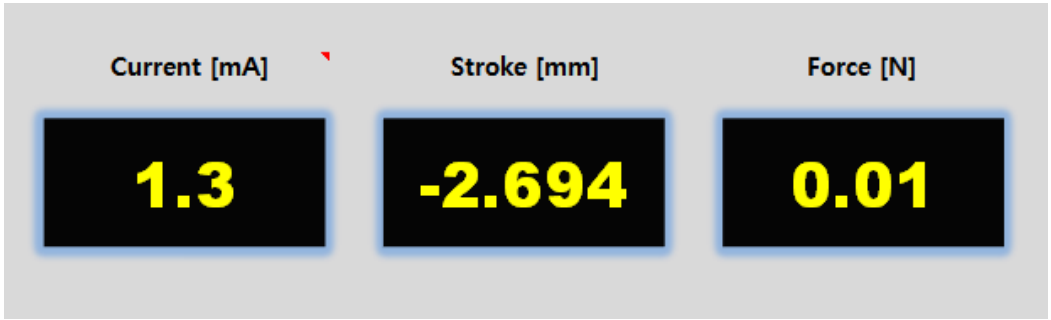
➢ Measurement explanation

1. Move to main page
2. Open the monitoring dialog
3. Start real time data and stop
4. Output current and stop
5. Output increasing and decreasing current
6. Real time sensing data





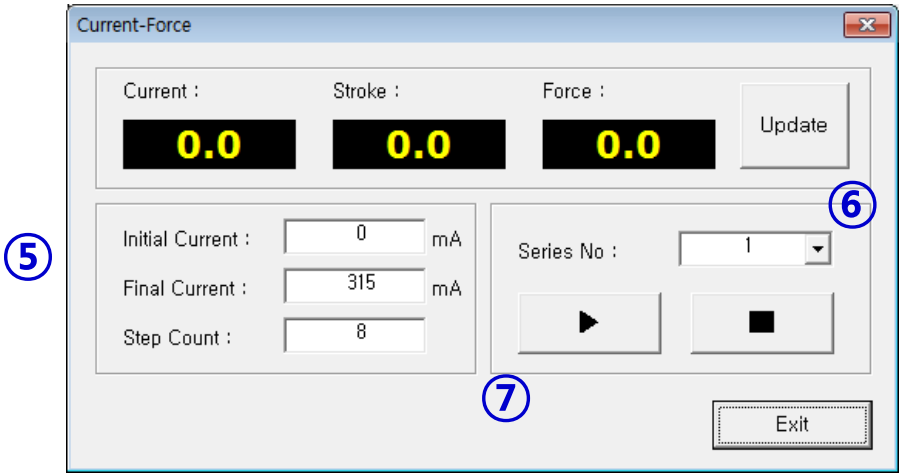
⑥

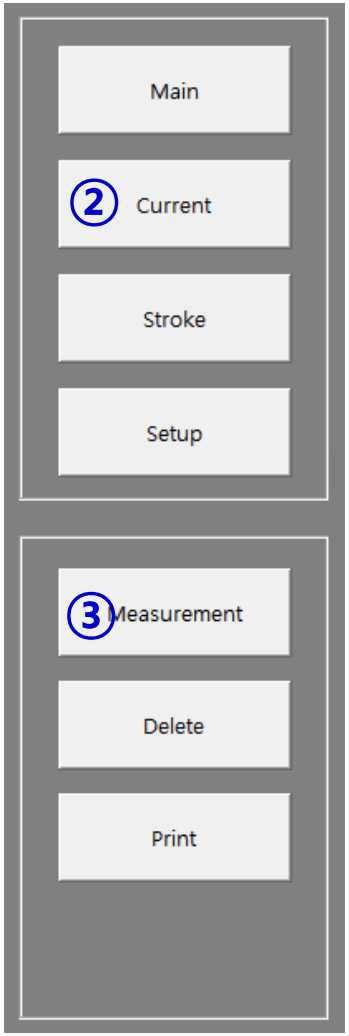


Current Measurement

➢ Measurement orders

1. First, Set zero position if stroke sensor doesn't set zero position
   - The position of zero is the start or final location of the moving parts
   - The zero position is sensed by confirming the contact via force sensor
2. Move to Current Page
3. Click "Measurement" button
4. Move the stroke sensor to the measured stroke
5. Input Initial Current, Final current and Step Count in the dialog
6. Set Series No. (Supports until five serial port)
7. Click the start button

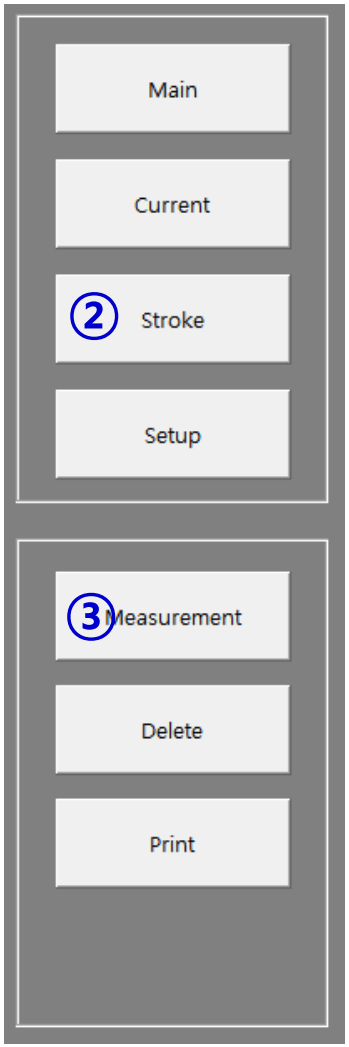


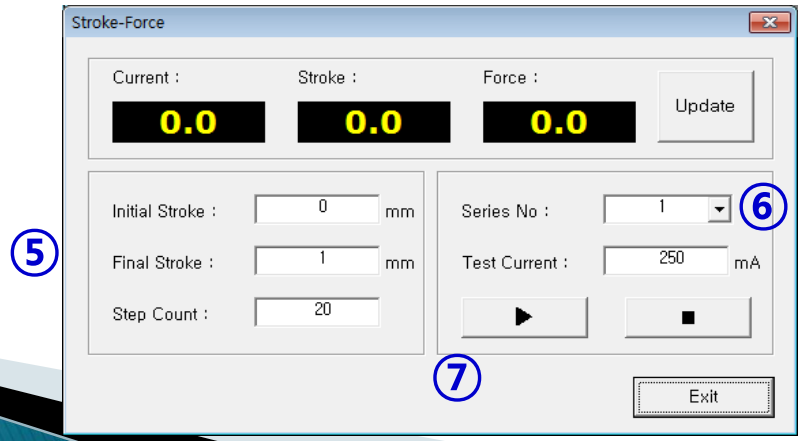


Stroke Measurement

➢ Measurement orders

1. First, Set zero position if stroke sensor doesn't set zero position
   - The position of zero is the start or final location of the moving parts
   - The zero position is sensed by confirming the contact via force sensor
2. Move to Stroke Page
3. Click "Measurement" button
4. Input Initial Stroke, final Stroke and Step Count in the dialog
5. Move the stroke sensor under initial stroke location
6. Set Series No. and input the measured current
7. Click the start button
8. Increase stroke by moving the stroke sensor until reaching final stroke
9. After reaching final stroke,
   decrease stroke by returning the stroke sensor until reaching zero position





Open Actuator Project

Thank You