19 UCS 181 - VAIBHAV



The LNM Institute of Information Technology Institute of

Department: Computer Science and Engineering
Knowledge Representation, Reasoning and Applications (CSE 0326)
End-Term Examination

Time: 180 mins

Date: 13/Dec/2021

Max. Marks: 180

Instruction:

1. All the questions are compulsory.

2. Make and State Appropriate Assumptions if and when required.

0.1.

(A) Explain the distinctive characteristics of the following KRR Schemes using an example for each [Marks 7]. And give one best suited application for each scheme [Marks 5].

- (i) Logic (PL and FOPL) Based KRR
- (ii) Fuzzy Logic Based KRR
- (iii) Frame-Based KRR
- (iv) CBR Based KRR
- (v) Semantic-net Based KRR [Total Marks 5 * (7 + 5) = 60].
- (B) Bring out the difference between Knowledge Based Reasoning and Statistical Data Based Reasoning using an example for each. [Marks 10].
- (C) Bring out the difference between Monotonic Reasoning and Non-monotonic Reasoning using an example for each. [Marks 10]
- **(D)** Bring out the difference between Semantic-net Based KRR and Taxonomy Based KRR using an example for each. [Marks 10]
- Q2. Case Study: Consider a Point-of-Sale (PoS) workbench of a Super Market Store. Each buyer is likely to have zero or more (i) Large sized items (LI), (ii) Medium sized items (MI) and (iii) Small sized items (SI) which will be on the workbench and will be put into one more bags after the payment. The rules of bagging are as follows: (a) Not more than 3 LI should be at the bottom of a bag; (b) Not more than 5 MI should be above LI in any bag; (c) Not more than 7 SI should be above MI in any bag; assume that there are enough number of empty bags available. Write FOPL based rules (using OPS5 like language) to bag an arbitrary number of LI, MI and SI. [Marks 40]. Show execution trace for (i) zero LI, zero MI and zero SI; (ii) 4 LI, 6 MI and 8 SI; [Marks 10]
- Q3. Case Study: Assume a competition of Autonomously Driven Toy Car in the Central Plaza (CP) of LNMIIT. The toy car needs to complete a "200 meter long white-path with a few smooth curves" painted on the floor of CP. The car has sensors and a controller loaded with fuzzy logic rules to autonomously drive it. Make suitable assumptions and design the fuzzy logic rules. [Marks 40]