Statistics of Solutions to Test Models for SPEKF

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Outline

- Introduction
 - Stochastic Parameterization Extended Kalman Filter (SPEKF)
 - Itô Integration
- 2 Statistics of b(t) and $\gamma(t)$, Gaussian
 - Mean
 - Variance
 - Covariance
- \bigcirc Statistics of u(t), Non-Gaussian
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- Numerical Simulation
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 - Results



Signals from nature can be modeled by Langevin equation:

Langevin Equation

$$\frac{\mathrm{d}u(t)}{\mathrm{d}t} = -\gamma(t)u(t) + \mathrm{i}\omega u(t) + \sigma \dot{W}(t) + f(t),$$

where $\dot{W}(t)$ is a Brownian motion, and f(t) is the external force.

B. Gershgorin, *et, al* proposed the Stochastic Parameterization Extended Kalman Filter (SPEKF) to cope with model errors.

Test Model

$$\begin{cases} \frac{du(t)}{dt} = (-\gamma(t) + i\omega)u(t) + b(t) + f(t) + \sigma W(t), \\ \frac{db(t)}{dt} = (-\gamma_b + i\omega_b)(b(t) - \hat{b}) + \sigma_b W_b(t), \\ \frac{d\gamma(t)}{dt} = -d\gamma(\gamma(t) - \hat{\gamma}) + \sigma_\gamma W_\gamma(t) \end{cases}$$

The initial values are complex random variables, with their first-order and second-order statistics known.

Solution

With knowledge of ODEs, solution of the SDE set is

$$\begin{cases} b(t) = \hat{b} + (b_0 - \hat{b})e^{\lambda_b(t - t_0)} + \sigma_b \int_{t_0}^t e^{\lambda_b(t - s)} dW_b(s) \\ \\ \gamma(t) = \hat{\gamma} + (\gamma_0 - \hat{\gamma})e^{-d\gamma(t - t_0)} + \sigma_{\gamma} \int_{t_0}^t e^{-d\gamma(t - s)} dW_{\gamma}(s) \\ \\ u(t) = e^{-J(t_0, t) + \hat{\lambda}(t - t_0)} u_0 + \int_{t_0}^t (b(s) + f(s))e^{-J(s, t) + \hat{\lambda}(s - t_0)} ds \\ \\ + \sigma \int_{t_0}^t e^{-J(s, t) + \hat{\lambda}(s - t_0)} dW(s) \end{cases}$$

with
$$\lambda_b = -\gamma_b + i\omega_b$$
, $\hat{\lambda} = -\hat{\gamma} + i\omega$, $J(s,t) = \int_s^t (\gamma(s') - \hat{\gamma})ds'$.



Itô Isometry

 $\forall f \in \mathcal{V}(S,T)$, B_t is a standard Brownian motion,

$$\mathbb{E}\left[\left(\int_{S}^{T} f(t, \boldsymbol{\omega}) dB_{t}\right)^{2}\right] = \mathbb{E}\left[\int_{S}^{T} f^{2}(t, \boldsymbol{\omega}) dt\right].$$

Linear property of Itô integration

(1)
$$\int_{S}^{T} f dB_{t} = \int_{S}^{U} f dB_{t} + \int_{U}^{T} f dB_{t}, \text{ a.e.}$$

(2)
$$\int_{S}^{T} (cf+g)dB_{t} = c \int_{S}^{T} f dB_{t} + \int_{S}^{T} g dB_{t}, \text{ a.e.}$$

(3)
$$E\left[\int_{S}^{T} f dB_{t}\right] = 0.$$



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Mean of b(t), $\gamma(t)$

Solution

$$\begin{cases} b(t) = \hat{b} + (b_0 - \hat{b})e^{\lambda_b(t-t_0)} + \sigma_b \int_{t_0}^t e^{\lambda_b(t-s)}dW_b(s) \\ \\ \gamma(t) = \hat{\gamma} + (\gamma_0 - \hat{\gamma})e^{-d\gamma(t-t_0)} + \sigma_\gamma \int_{t_0}^t e^{-d\gamma(t-s)}dW_\gamma(s) \end{cases}$$

With property of Itô integration (3), the last term in E[b(t)] is 0. Thus we find

$$E[b(t)] = \hat{b} + (E[b_0] - \hat{b})e^{\lambda_b(t-t_0)}$$

$$\mathbf{E}[\gamma(t)] = \hat{\gamma} + (\mathbf{E}[\gamma_0] - \hat{\gamma})e^{-d\gamma(t-t_0)}$$

Variance of b(t), $\gamma(t)$

According to definition,

$$\begin{aligned} \operatorname{Var}(b(t)) &= \operatorname{E}[(b(t) - \operatorname{E}[b(t)])(b(t) - \operatorname{E}[b(t)])^*] \\ &= e^{-2\gamma_b(t-t_0)} \operatorname{Var}(b_0) + \operatorname{E}\left[\sigma_b^2 \int_{t_0}^t e^{\lambda_b(t-s)} dW_b(s) \left(\int_{t_0}^t e^{\lambda_b(t-s)} dW_b(s)\right)^*\right] \\ &= e^{-2\gamma_b(t-t_0)} \operatorname{Var}(b_0) + \sigma_b^2 \operatorname{E}\left[\int_{t_0}^t e^{-2\gamma_b(t-s)} ds\right] \end{aligned}$$

The last step takes use of Itô isometry. Compute the integration in last term, we have

$$\begin{aligned} & \text{Var}(b(t)) = e^{-2\gamma_b(t-t_0)} \text{Var}(b_0) + \frac{\sigma_b^2}{2\gamma_b} (1 - e^{-2\gamma_b(t-t_0)}) \\ & \text{Var}(\gamma(t)) = e^{-2d\gamma(t-t_0)} \text{Var}(\gamma_0) + \frac{\sigma_\gamma^2}{2d\gamma} (1 - e^{-2d\gamma(t-t_0)}) \end{aligned}$$

Covariance of b(t), $\gamma(t)$

According to definition,

$$\begin{split} & \text{Cov}(b(t), b(t)^*) = \mathbb{E}[(b(t) - \mathbb{E}[b(t)])(b(t)^* - \mathbb{E}[b(t)^*])] \\ & = \mathbb{E}\left[(b_0 - \mathbb{E}[b_0])(b_0^* - \mathbb{E}[b_0^*])e^{2\lambda_b(t-t_0)}\right] + \sigma_b \mathbb{E}\left[(b_0 - \mathbb{E}[b_0])\int_{t_0}^t e^{\lambda_b(t-s)}dW_b(s)\right] \\ & + \sigma_b \mathbb{E}\left[(b_0^* - \mathbb{E}[b_0^*])e^{\lambda_b(t-t_0)}\int_{t_0}^t e^{\lambda_b(t-s)}dW_b(s)\right] + \sigma_b^2 \mathbb{E}\left[(\int_{t_0}^t e^{\lambda_b(t-s)}dW_b(s))^2\right] \end{split}$$

With property of Itô integration (3), the second and third term are both 0; with Itô isometry we know the last term is also 0. Accordingly,

$$Cov(b(t), b(t)^*) = E[(b_0 - E[b_0])(b_0^* - E[b_0^*])]e^{2\lambda_b(t - t_0)} = Cov(b_0, b_0^*)e^{2\lambda_b(t - t_0)}$$

$$Cov(b(t), \gamma(t)) = E[(b(t) - E[b(t)])(\gamma(t) - E[\gamma(t)])] = Cov(b_0, \gamma_0)e^{(\lambda_b - d\gamma)(t - t_0)}$$

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Mean of u(t)

Using the same properties, it is easy to find

$$\begin{split} \mathbf{E}[u(t)] &= e^{\hat{\lambda}(t-t_0)} \mathbf{E}\left[e^{-J_0(t_0,t)}u_0\right] + \int_{t_0}^t e^{\hat{\lambda}(t-s)} \mathbf{E}\left[b(s)e^{-J(s,t)}\right] ds \\ &+ \sigma \int_{t_0}^t e^{\hat{\lambda}(t-s)} f(s) \mathbf{E}\left[e^{-J(s,t)}\right] ds. \end{split}$$

We find it necessary to compute expectations of terms like

$$E[ze^{bx}],$$

where z is a complex-valued Gaussian random variable and x is a real-valued Gaussian variable. We propose two lemmas here.

Mean of u(t)

Lemma (1)

$$E\left[ze^{\mathrm{i}bx}\right] = (E[z] + \mathrm{i}bCov(z,x))e^{\mathrm{i}bE[x] - \frac{1}{2}b^2Var(x)},$$

with z being a complex-valued Gaussian, and x a real-valued Gaussian.

Corollary (1)

Under the condition of Lemma 1,

$$E\left[ze^{bx}\right] = (E[z] + bCov(z,x))e^{bE[x] + \frac{1}{2}b^2Var(x)}.$$

Proof of lemma 1 takes advantage of characteristic function of multivariable Gaussian distribution.



Proof

Let z = y + iw, $y, w \in \mathbb{R}$. Denote $\mathbf{v} = (x, y, w)^{\top}$, then \mathbf{v} satisfies the multivariable Gaussian distribution, with its characteristic function

$$\phi_{\mathbf{v}}(\mathbf{s}) = \exp(i\mathbf{s}^{\top}\mathbf{E}[\mathbf{v}] - \frac{1}{2}\mathbf{s}^{\top}\Sigma\mathbf{s}).$$

Let $g(\mathbf{v})$ being the PDF of \mathbf{v} , then one knows from that char. funcbeing Fourier transform of PDF,

$$\phi_{\mathbf{v}}(\mathbf{s}) = \frac{1}{(2\pi)^3} \int e^{\mathbf{i}\mathbf{s}^{\top}\mathbf{v}} g(\mathbf{v}) d\mathbf{v}.$$

According to the differential property of Fourier transform (Proposition 2.10),

$$\frac{\partial \phi_{\mathbf{v}}(\mathbf{s})}{\partial s_2} = \frac{1}{(2\pi)^3} \int i y_0 e^{i\mathbf{s}^{\top} \mathbf{v}} g(\mathbf{v}) d\mathbf{v} = i \mathbf{E} \left[y_0 e^{i\mathbf{s}^{\top} \mathbf{v}} \right].$$

Let
$$\mathbf{v} = (b, 0, 0)^{\top}$$
,

$$\mathbf{E}[y_0e^{\mathrm{i}bx_0}] = -\mathrm{i}\frac{\partial\phi_{\mathbf{v}}(s)}{\partial s_2}\bigg|_{\mathbf{s}=(b,0,0)^\top}, \ \mathbf{E}[w_0e^{\mathrm{i}bx_0}] = -\mathrm{i}\frac{\partial\phi_{\mathbf{v}}(s)}{\partial s_3}\bigg|_{\mathbf{s}=(b,0,0)^\top}$$

Proof

From PDF of multivariable Gaussian distribution, one knows

$$\frac{\partial \phi_{\mathbf{v}}(\mathbf{s})}{\partial s_2} = (iE[y_0] - Var(y_0)s_2 - Cov(x_0, y_0)s_1 - Cov(y_0, w_0)s_3)\phi_{\mathbf{v}}(s)$$

$$\frac{\partial \phi_{\mathbf{v}}(\mathbf{s})}{\partial s_3} = (iE[w_0] - Var(w_0)s_3 - Cov(x_0, w_0)s_1 - Cov(y_0, w_0)s_2)\phi_{\mathbf{v}}(s)$$

Compute the partial derivatives at $\mathbf{s} = (b, 0, 0)^{\mathsf{T}}$,

$$E\left[y_{0}e^{ibx_{0}}\right] = (E[y_{0}] + iCov(x_{0}, y_{0})b) \exp(ibE[x_{0}] - \frac{1}{2}Var(x_{0})b^{2})$$

$$E[w_0e^{ibx_0}] = (E[w_0] + iCov(x_0, w_0)b) \exp(ibE[x_0] - \frac{1}{2}Var(x_0)b^2)$$

Then

$$\mathbf{E}\left[ze^{\mathbf{i}bx}\right] = (\mathbf{E}[z] + \mathbf{i}b\mathbf{Cov}(z,x))e^{\mathbf{i}b\mathbf{E}[x] - \frac{1}{2}b^2\mathbf{Var}(x)}.$$



Mean of u(t)

Lemma (2)

$$E\left[zwe^{bx}\right] = \left[E[z]E[w] + Cov(z, w^*) + b(E[z]Cov(w, x)) + E[w]Cov(z, x) + b^2Cov(z, x)Cov(w, x)\right]e^{bE[x] + \frac{b^2}{2}Var(x)}.$$

with z,w being complex-valued Gaussian, and x real-valued Gaussian.

The proof of this lemma is the same as Lemma 1.



Mean of u(t)

We now make use of Lemma 1 to obtain mean of u(t).

$$\begin{split} \mathbf{E}[u(t)] &= e^{\hat{\lambda}(t-t_0)} (\mathbf{E}[u_0] - \mathbf{Cov}(u_0, J(t_0, t))) e^{-\mathbf{E}[J(t_0, t)] + \frac{1}{2} \mathbf{Var}(J(t_0, t))} \\ &+ \int_{t_0}^t e^{\hat{\lambda}(t-s)} (\hat{b} + e^{\lambda_b(s-t_0)} (\mathbf{E}[b_0] - \hat{b} - \mathbf{Cov}(b_0, J(s, t)))) e^{-\mathbf{E}[J(s, t)] + \frac{1}{2} \mathbf{Var}(J(s, t))} ds \\ &+ \int_{t_0}^t e^{\hat{\lambda}(t-s)} f(s) e^{-\mathbf{E}[J(s, t)] + \frac{1}{2} \mathbf{Var}(J(s, t))} ds \end{split}$$

The terms $Cov(u_0,J(s,t))$, $Cov(b_0,J(s,t))$, E[J(s,t)] and Var(J(s,t)) can be found using Itô isometry.

Variance of u(t)

Denote u(t) = A + B + C,

$$\begin{cases} A = e^{-J(t_0,t) + \hat{\lambda}(t-t_0)} u_0, \\ B = \int_{t_0}^t (b(s) + f(s)) e^{-J(s,t) + \hat{\lambda}(t-s)} ds, \\ C = \sigma \int_{t_0}^t e^{-J(s,t) + \hat{\lambda}(t-s)} dW(s). \end{cases}$$

By definition we find $Var(u(t)) = E[|u(t)|^2] - |E[u(t)]|^2$, with

$$E[|u(t)|^2] = E[|A|^2] + E[|B|^2] + E[|C|^2] + 2Re\{E[A^*B]\}.$$

We can obtain $\mathbb{E}\left[|A|^2\right]$ by Lemma 2, and $\mathbb{E}\left[|B|^2\right]$ by Itô isometry. Noticing that

$$Cov(J(s,t),J(r,t)) = Var(J(s,t)) + Cov(J(s,t),J(r,s)).$$

 $E[|C|^2]$ and $Re\{E[A^*B]\}$ can also be computed by Itô isometry and property of Itô integration.

Covariances

By definition,

$$\begin{aligned} & \text{Cov}(u(t), u^*(t)) = \text{E}\left[u(t)^2\right] - \text{E}[u(t)]^2 \\ & \text{Cov}(u(t), \gamma(t)) = \text{E}[u(t)(\gamma(t) - \hat{\gamma})] + \text{E}[u(t)](\hat{\gamma} - \text{E}[\gamma(t)]) \\ & \text{Cov}(u(t), b(t)) = \text{E}[u(t)b^*(t)] - \text{E}[u(t)]\text{E}[b(t)]^* \\ & \text{Cov}(u(t), b^*(t)) = \text{E}[u(t)b(t)] - \text{E}[u(t)]\text{E}[b(t)]. \end{aligned}$$

Each term can be obtained by Lemma 3 and Itô isometry.

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Parameters

As a real-world example, we choose a periodic external force

$$f(t) = \frac{3}{2}e^{\frac{1}{10}it},$$

and parameters of the equation set are given

$$\begin{cases} d = 1.5, & d_{\gamma} = 0.01d \\ \sigma = 0.1549, & \omega = 1.78 \\ \sigma_{\gamma} = 5\sigma, & \gamma_{b} = 0.1d \\ \sigma_{b} = 5\sigma, & \omega_{b} = \omega \\ \hat{b} = 0, & \hat{\gamma} = 0 \end{cases}$$

We assume that initial values satisfy

$$\begin{cases} \operatorname{Re}(u_0), \operatorname{Im}(u_0) \sim \mathcal{N}(0, \frac{1}{\sqrt{2}}), \text{ i.i.d.} \\ \operatorname{Re}(b_0), \operatorname{Im}(b_0) \sim \mathcal{N}(0, \frac{1}{\sqrt{2}}), \text{ i.i.d.} \\ \gamma_0 \sim \mathcal{N}(0, 1) \end{cases}$$

Euler-Maruyama Scheme

Itô integration can be simulated by E-M scheme:

$$X_{j} = X_{j-1} + f(X_{j-1})\Delta t + g(X_{t-1})(W(\tau_{j}) - W(\tau_{j-1})),$$

with

$$W(\tau_j) - W(\tau_{j-1}) = \sum_{k=jR-R+1}^{jR} \mathrm{d}W_k,$$

and R being the step length of E-M scheme,

$$\mathrm{d}W = \sqrt{\Delta t} \times \mathtt{randn}().$$

Revised Euler Scheme

Since we need to simulate a SDE set with three relevant equations, we choose the Revised Euler Scheme from numerical solution to ODE for simulating u(t):

$$x_n = x_{n-1} + \Delta t \phi(t_{n-1} + \frac{\Delta t}{2}, x_{n-1} + \frac{\Delta t}{2} \phi(t_{n-1}, x_{n-1})),$$

it is a second-order Runge-Kutta scheme with a locally quadratic convergence.

Result

Simulate 10^6 times with R = 1, the results are as follows:

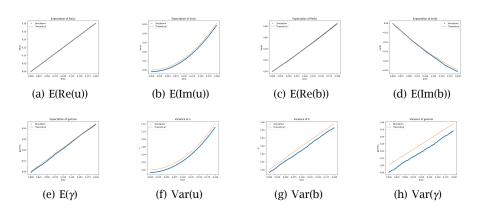


Figure: Simulation of Expectations and Variances, $n = 10^6$

Result

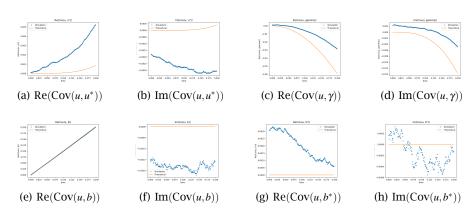


Figure: Simulation of Covariances, $n = 10^6$

Results

Simulate 10^7 times with R = 1, the results are as follows:

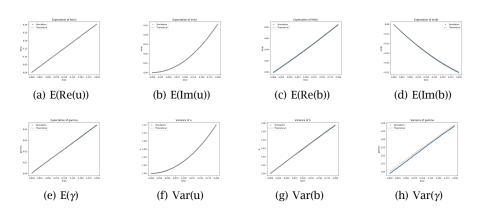


Figure: Simulation of Expectations and Variances, $n = 10^7$

Result

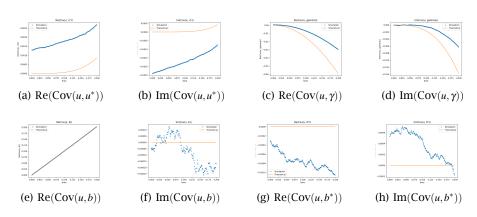


Figure: Simulation of Covariances, $n = 10^7$

Discussion

From the simulation results we find that the simulation of expectations fit the theoretical results satisfyingly. For the results of Variances and Covariances,

- When $n = 10^6$, the error of variances is about $O(10^{-2}) \sim O(10^{-3})$, error of covariances is about $O(10^{-2}) \sim O(10^{-3})$.
- When $n = 10^7$, the error of Var(u), Var(b) is about $O(10^{-5})$, and error of $Var(\gamma)$ is about $O(10^{-3}) \sim O(10^{-4})$, error of $Cov(u, u^*)$, $Cov(u, \gamma)$ is about $O(10^{-3})$, error of Cov(u, b), $Cov(u, b^*)$ is $O(10^{-4})$.

Discussion

One can find the simulation errors decrease with the growth of simulations. Thus one could believe that when $n \to \infty$, the simulation would converge to the theoretical result. In fact, error of simulation comes from that initial values are all random variables; according to Law of large numbers, the errors would converge to 0 when $n \to \infty$.

We can get third-order and fourth-order statistics of u,b,γ with the same methods, which could be written in a form of multiple integrals of statistics of initial values.

Thank you!