# Nordic probabilistic Al school Variational Inference and Optimization

Helge Langseth, Andrés Masegosa, and Thomas Dyhre Nielsen

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ProbAl - 2023

Stochastic Gradient Ascent

## A small side-step: Gradient Ascent

## Why do we talk about this?

We want a way to optimize ELBO using gradient methods. If we can do Bayesian inference as optimization it will play well with, e.g., deep learning frameworks.

#### Gradient ascent algorithm for maximizing a function $f(\lambda)$ :

- **1** Initialize  $\lambda^{(0)}$  randomly.
- ② For t = 1, ...:

$$\pmb{\lambda}^{(t)} \leftarrow \pmb{\lambda}^{(t-1)} + \rho \cdot \nabla_{\pmb{\lambda}} f\left(\pmb{\lambda}^{(t-1)}\right)$$

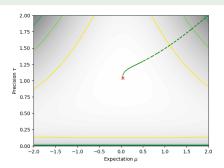
- $\lambda^{(t)}$  converges to a (local) optimum of  $f(\cdot)$  if:
  - f is "sufficiently nice";
  - The learning-rate  $\rho$  is "sufficiently small".

#### Example: Maximum log likelihood in a Gaussian model

We have access to N=1000 observations from a Gaussian distribution with unknown mean  $\mu$  and precision  $\tau=1/\sigma^2$ . Use  $\pmb{\lambda}=[\mu,\tau]^{\rm T}$ .

$$f(\lambda) = \sum_{i=1}^{N} \log p(x_i | \lambda) = \frac{N}{2} \log \tau - \frac{N}{2} \log(2\pi) - \frac{\tau}{2} \sum_{i=1}^{N} (x_i - \mu)^2$$

$$\nabla_{\lambda} f(\lambda) = \begin{bmatrix} -N\tau\mu + \tau \sum_{i=1}^{N} x_i \\ \frac{N}{2} - \frac{1}{2} \sum_{i=1}^{N} (x_i - \mu)^2 \end{bmatrix}$$



#### ... and Stochastic Gradient Ascent

## "Standard" gradient ascent is not enough for ELBO optimization

We won't be able to calculate  $\nabla_{\lambda} \mathcal{L}(q(\theta \mid \lambda))$  exactly for (at least) two reasons:

- We may have to resolve to mini-batching (gradient from "random subset")
- We may not be able to calculate the gradient exactly even for a mini-batch

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## Stochastic gradient ascent algorithm for maximizing a function $f(\lambda)$ :

If we have access to  $\mathbf{g}(\lambda)$  – an **unbiased estimate** of the gradient – it still works!

- Initialize  $\lambda^{(0)}$  randomly.
- ② For t = 1, ...:

$$\boldsymbol{\lambda}^{(t)} \leftarrow \boldsymbol{\lambda}^{(t-1)} + \rho_t \cdot \mathbf{g} \left( \boldsymbol{\lambda}^{(t-1)} \right)$$

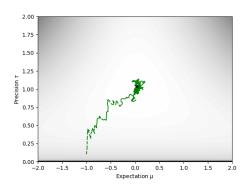
 $\lambda_t$  converges to a (local) optimum of  $f(\cdot)$  if:

- f is "sufficiently nice";
- $\mathbf{g}(\lambda)$  is a random variable with  $\mathbb{E}[\mathbf{g}(\lambda)] = \nabla_{\lambda} f(\lambda)$  and  $\operatorname{Var}[\mathbf{g}(\lambda)] < \infty$ .
- The learning-rates  $\{\rho_t\}$  is a Robbins-Monro sequence:
  - $\sum_{t} \rho_{t} = \infty$
  - $\sum_{t} \rho_t^2 < \infty$

#### Example: Maximum log likelihood in a Gaussian model

We consider the same maximum likelihood problem, but instead of the gradient based on the full sample, we only have a **mini-batch of a single example**  $x_t$  at iteration t:

$$\mathbf{g}(\boldsymbol{\lambda} \mid x_t) = N \cdot \begin{bmatrix} -\tau \mu + \tau x_t \\ \frac{1}{2\tau} - \frac{1}{2} (x_t - \mu)^2 \end{bmatrix}$$



Black Box Variational Inference

#### Main idea: Cast inference as an optimization problem

Optimize the ELBO by stochastic gradient ascent over the parameters  $\lambda$ . If that works, Bayesian inference can be **seamlessly integrated** with building-blocks from other gradient-based machine learning approaches (like deep learning).

## Algorithm: Maximize $\mathcal{L}\left(q\right)=\mathbb{E}_{q}\left[\log\frac{p(\theta,\mathcal{D})}{q(\theta|\lambda)}\right]$ by gradient ascent

- Initialization:
  - $t \leftarrow 0$ ;
  - $\hat{\lambda}_0 \leftarrow$  random initialization;
  - $\{\rho_t\} \leftarrow$  a Robbins-Monro sequence.
- Repeat until negligible improvement in terms of  $\mathcal{L}(q)$ :
  - $t \leftarrow t + 1$ ;
  - $\hat{\boldsymbol{\lambda}}_{t} \leftarrow \hat{\boldsymbol{\lambda}}_{t-1} + \rho_{t} \nabla_{\boldsymbol{\lambda}} \mathcal{L}(q)|_{\hat{\boldsymbol{\lambda}}_{t-1}};$

#### Important issue:

Can we calculate  $\nabla_{\lambda} \mathcal{L}(q)$  efficiently without adding new restrictive assumptions?

#### BBVI - calculating the gradient

The algorithm requires that we can find

$$\nabla_{\boldsymbol{\lambda}} \mathcal{L}\left(q\right) = \nabla_{\boldsymbol{\lambda}} \, \mathbb{E}_{\boldsymbol{\theta} \sim q_{\boldsymbol{\lambda}}} \left[ \log \frac{p(\boldsymbol{\theta}, \mathcal{D})}{q(\boldsymbol{\theta} \mid \boldsymbol{\lambda})} \right].$$

Tricky: How can we move the gradient inside the expectation?

• We would typically approximate an expectation by a sample average:

$$\mathbb{E}_{\boldsymbol{\theta} \sim q_{\boldsymbol{\lambda}}}\left[f(\boldsymbol{\theta}, \boldsymbol{\lambda})\right] \approx \frac{1}{M} \sum_{j=1}^{M} f(\boldsymbol{\theta}_{j}, \boldsymbol{\lambda}), \text{ with } \{\boldsymbol{\theta}_{1}, \dots \boldsymbol{\theta}_{M}\} \text{ sampled from } q_{\boldsymbol{\lambda}}(\boldsymbol{\theta} \,|\, \boldsymbol{\lambda}).$$

• This doesn't work when taking a gradient related to the sampling distribution.

#### BBVI - calculating the gradient

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$$\nabla_{\boldsymbol{\lambda}} \mathcal{L}\left(q\right) = \nabla_{\boldsymbol{\lambda}} \, \mathbb{E}_{\boldsymbol{\theta} \sim q_{\boldsymbol{\lambda}}} \left[ \log \frac{p(\boldsymbol{\theta}, \mathcal{D})}{q(\boldsymbol{\theta} \mid \boldsymbol{\lambda})} \right].$$

**Solution:** Use these properties to simplify the equation:

Now it follows that

$$\nabla_{\boldsymbol{\lambda}} \mathcal{L} \left( q \right) = \mathbb{E}_{\boldsymbol{\theta} \sim q_{\boldsymbol{\lambda}}} \left[ \log \frac{p(\boldsymbol{\theta}, \mathcal{D})}{q(\boldsymbol{\theta} \mid \boldsymbol{\lambda})} \cdot \nabla_{\boldsymbol{\lambda}} \log q(\boldsymbol{\theta} \mid \boldsymbol{\lambda}) \right].$$

This is the so-called **score-function gradient**.

$$\nabla_{\lambda} \mathcal{L}(q) = \mathbb{E}_{\theta \sim q} \left[ \log \frac{p(\theta, \mathcal{D})}{q(\theta \mid \lambda)} \cdot \left| \nabla_{\lambda} \log q(\theta \mid \lambda) \right| \right].$$

• We still only need access to the joint distribution  $p(\theta, D)$  – not  $p(\theta \mid D)$ .

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•  $q(\theta \mid \lambda)$  factorizes under MF, s.t. we can optimize per variable:  $q(\theta_i \mid \lambda_i)$ .

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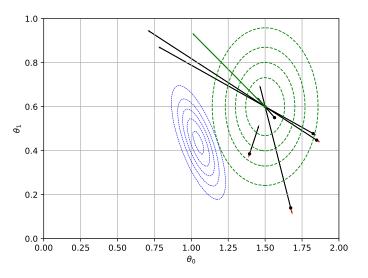
#### Calculating the gradient - in summary

We have observed the data  $\mathcal{D}$ , and our current estimate for  $\lambda$  is  $\hat{\lambda}$ . Then

$$\nabla_{\boldsymbol{\lambda}} \mathcal{L}(q)|_{\boldsymbol{\lambda} = \hat{\boldsymbol{\lambda}}} \approx \frac{1}{M} \sum_{j=1}^{M} \log \frac{p(\boldsymbol{\theta}_{j}, \mathcal{D})}{q(\boldsymbol{\theta}_{j} \mid \hat{\boldsymbol{\lambda}})} \cdot \nabla_{\boldsymbol{\lambda}} \log q(\boldsymbol{\theta}_{j} \mid \hat{\boldsymbol{\lambda}}),$$

where  $\{\boldsymbol{\theta}_1,\dots\boldsymbol{\theta}_M\}$  are samples from  $q(\cdot\,|\,\hat{\boldsymbol{\lambda}})$ . Typically M is small.

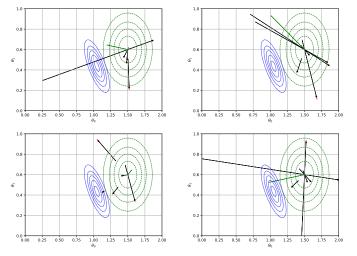
#### Does it work?



$$\nabla_{\boldsymbol{\lambda}} \log q(\boldsymbol{\theta}_i \,|\, \boldsymbol{\lambda}); \quad \log \frac{p(\boldsymbol{\theta}_i, \mathcal{D})}{q(\boldsymbol{\theta}_i \,|\, \boldsymbol{\lambda})} \cdot \nabla_{\boldsymbol{\lambda}} \log q(\boldsymbol{\theta}_i \,|\, \boldsymbol{\lambda}); \quad \frac{1}{M} \sum_{i=1}^m \log \frac{p(\boldsymbol{\theta}_i, \mathcal{D})}{q(\boldsymbol{\theta}_i \,|\, \boldsymbol{\lambda})} \cdot \nabla_{\boldsymbol{\lambda}} \log q(\boldsymbol{\theta}_i \,|\, \boldsymbol{\lambda})$$

Length of gradients increased for visibility. Graphics inspired by Arto Klami @ ProbAl2021.

#### Does it work?

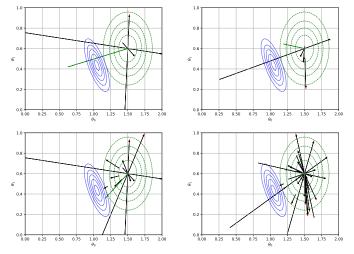


Different samples, each with M=5.

$$\nabla_{\boldsymbol{\lambda}} \log q(\boldsymbol{\theta}_i \,|\, \boldsymbol{\lambda}); \quad \log \frac{p(\boldsymbol{\theta}_i, \mathcal{D})}{q(\boldsymbol{\theta}_i \,|\, \boldsymbol{\lambda})} \cdot \nabla_{\boldsymbol{\lambda}} \log q(\boldsymbol{\theta}_i \,|\, \boldsymbol{\lambda}); \quad \frac{1}{M} \sum_{i=1}^m \log \frac{p(\boldsymbol{\theta}_i, \mathcal{D})}{q(\boldsymbol{\theta}_i \,|\, \boldsymbol{\lambda})} \cdot \nabla_{\boldsymbol{\lambda}} \log q(\boldsymbol{\theta}_i \,|\, \boldsymbol{\lambda})$$

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#### Does it work?



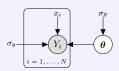
Different values of M (M=3, 5, 10,and 25)

$$\nabla_{\lambda} \log q(\theta_i \mid \lambda); \quad \log \frac{p(\theta_i, \mathcal{D})}{q(\theta_i \mid \lambda)} \cdot \nabla_{\lambda} \log q(\theta_i \mid \lambda); \quad \frac{1}{M} \sum_{i=1}^{m} \log \frac{p(\theta_i, \mathcal{D})}{q(\theta_i \mid \lambda)} \cdot \nabla_{\lambda} \log q(\theta_i \mid \lambda)$$

Length of gradients increased for visibility. Graphics inspired by Arto Klami @ ProbAl2021.



#### Code Task: Score-function gradient for linear regression



- $\bullet \ \boldsymbol{\theta} = \{w_0, w_1\}, \ \boldsymbol{\theta} \sim \mathcal{N}(\mathbf{0}, \sigma_{\theta} \cdot \mathbf{I}_{2 \times 2})$
- $Y_i | \{\boldsymbol{\theta}, x_i, \sigma_y\} \sim \mathcal{N}(w_0 + w_1 \cdot x_i, \sigma_y^2)$
- We choose  $q_j(\theta_j \,|\, \pmb{\lambda}_j) = \mathcal{N}(\theta_j \,|\, \mu_j, \sigma_j^2)$ , so  $\pmb{\lambda}_j = \{\mu_j, \sigma_j\}$

In this task you will implement the score-function gradient:

$$\nabla_{\boldsymbol{\lambda}} \mathcal{L}(q) = \mathbb{E}_{\boldsymbol{\theta} \sim q} \left[ \log \frac{p(\boldsymbol{\theta}, \mathcal{D})}{q(\boldsymbol{\theta} \,|\, \boldsymbol{\lambda})} \,\cdot\, \nabla_{\boldsymbol{\lambda}} \log q(\boldsymbol{\theta} \,|\, \boldsymbol{\lambda}) \right].$$

- Look at Exercise 1 in the notebook
  - Day2-AfterLunch/students\_BBVI.ipynb.
- Calculate  $\nabla_{\lambda} \log q(\boldsymbol{\theta} \,|\, \boldsymbol{\lambda})$ , i.e.,  $\frac{\partial}{\partial \mu} \, \log \mathcal{N}(\mu, \sigma^2)$  and  $\frac{\partial}{\partial \sigma} \, \log \mathcal{N}(\mu, \sigma^2)$  by hand.
- Implement your results in the function <code>score\_function\_gradient</code>.

#### Let's try to find another trick to compute:

$$\nabla_{\boldsymbol{\lambda}} \mathcal{L} \left( q \right) = \nabla_{\boldsymbol{\lambda}} \, \mathbb{E}_{\boldsymbol{\theta} \sim q} \left[ \log \frac{p_{\boldsymbol{\theta}}(\boldsymbol{\theta}, \mathcal{D})}{q(\boldsymbol{\theta} \, | \, \boldsymbol{\lambda})} \right].$$

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Let's assume  $q(\theta|\lambda)$  can be *reparametrized*:

$$\epsilon \sim \phi(\epsilon)$$
 $\theta = f(\epsilon, \lambda)$ 

where  $\phi(\epsilon)$  is some simple distribution that does not depend on  $\lambda$  and  $f(\epsilon, \lambda)$  is a deterministic transformation.

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The common example is  $q(\theta|\lambda) = \mathcal{N}(\mu, \sigma)$  reparametrized using

$$\epsilon \sim \mathcal{N}(0,1)$$

$$\theta = \mu + \sigma \epsilon$$

If  $q(\theta|\lambda)$  can be *reparametrized*:

$$egin{array}{lll} m{\epsilon} & \sim & \phi(m{\epsilon}) \\ m{\theta} & = & f(m{\epsilon}, m{\lambda}) \end{array}$$

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If  $q(\theta|\lambda)$  can be reparametrized:

$$\epsilon \sim \phi(\epsilon)$$
 $\theta = f(\epsilon, \lambda)$ 

Now we can do something different:

$$\begin{split} \nabla_{\lambda}\mathcal{L}\left(q\right) &= \nabla_{\lambda}\mathbb{E}_{\theta \sim q}\left[\log\frac{p(\theta,\mathcal{D})}{q(\theta\mid\lambda)}\right] \\ &= \nabla_{\lambda}\mathbb{E}_{\epsilon \sim \phi}\left[\log\frac{p(f(\epsilon,\lambda),\mathcal{D})}{q(f(\epsilon,\lambda)\mid\lambda)}\right] \\ &= \mathbb{E}_{\epsilon \sim \phi}\left[\nabla_{\lambda}\log\frac{p(f(\epsilon,\lambda),\mathcal{D})}{q(f(\epsilon,\lambda)\mid\lambda)}\right] \\ &= \mathbb{E}_{\epsilon \sim \phi}\left[\nabla_{\theta}\log\frac{p(\theta,\mathcal{D})}{q(\theta\mid\lambda)}\nabla_{\lambda}f(\epsilon,\lambda) + \nabla_{\lambda}\log q(\theta\mid\lambda)\right] \quad \text{(slide 7 - point 3)} \end{split}$$

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#### Monte-Carlo Estimation:

$$\nabla_{\lambda} \mathcal{L}(q) = \mathbb{E}_{\epsilon \sim \phi} \left[ \nabla_{\theta} \log \frac{p(\theta, \mathcal{D})}{q(\theta \mid \lambda)} \nabla_{\lambda} f(\epsilon, \lambda) \right]$$

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• While the score function estimator does not.

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#### This gradient estimator directly uses model's gradients

- While the score function estimator does not.
- $\log p(\theta, \mathcal{D})$  needs to be differentiable wrt  $\theta$  (i.e. **no discrete variables**).
- $q(\theta|\lambda)$  needs to be differentiable and reparametrizable

## Reparametrizable Distributions

# Reparameterization can be done for a (growing) set of distributions:

Target	$p(z;\theta)$	Base $p(\epsilon)$	One-liner $g(\epsilon; \theta)$
Exponential	$\exp(-x); x > 0$	$\epsilon \sim [0; 1]$	$ln(1/\epsilon)$
Cauchy	$\frac{1}{\pi(1+x^2)}$	$\epsilon \sim [0;1]$	$\tan(\pi\epsilon)$
Laplace	$\mathcal{L}(0; 1) = \exp(- x )$	$\epsilon \sim [0;1]$	$\ln(\frac{\epsilon_1}{\epsilon_2})$
Laplace	$\mathcal{L}(\mu;b)$	$\epsilon \sim [0;1]$	$\mu - bsgn(\epsilon) \ln (1 - 2 \epsilon )$
Std Gaussian	$\mathcal{N}(0;1)$	$\epsilon \sim [0;1]$	$\sqrt{\ln(\frac{1}{e_1})}\cos(2\pi\epsilon_2)$
Gaussian	$\mathcal{N}(\mu; RR^{\top})$	$\epsilon \sim \mathcal{N}(0; 1)$	$\mu + R\epsilon$
Rademacher	$Rad(\frac{1}{2})$	$\epsilon \sim \textit{Bern}(\frac{1}{2})$	2e-1
Log-Normal	$\ln \mathcal{N}(\mu; \sigma)$	$\epsilon \sim \mathcal{N}(\mu;\sigma^2)$	$\exp(\epsilon)$
Inv Gamma	$i\mathcal{G}(k;\theta)$	$\epsilon \sim \mathcal{G}(k;\theta^{-1})$	$\frac{1}{\epsilon}$

Table from http://blog.shakirm.com/2015/10/ machine-learning-trick-of-the-day-4-reparameterisation-tricks/

## Reparametrizable Distributions

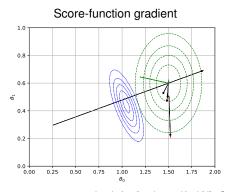
### Reparameterization can be done for a **(growing) set of distributions**:

Target	$p(z;\theta)$	Base $p(\epsilon)$	One-liner $g(\epsilon; \theta)$
Exponential	$\exp(-x); x > 0$	$\epsilon \sim [0; 1]$	$ln(1/\epsilon)$
Cauchy	$\frac{1}{\pi(1+x^2)}$	$\epsilon \sim [0;1]$	$\tan(\pi\epsilon)$
Laplace	$\mathcal{L}(0; 1) = \exp(- x )$	$\epsilon \sim [0;1]$	$\ln(\frac{\epsilon_1}{\epsilon_2})$
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Gaussian	$\mathcal{N}(\mu; RR^{\top})$	$\epsilon \sim \mathcal{N}(0; 1)$	$\mu + R\epsilon$
Rademacher	$Rad(\frac{1}{2})$	$\epsilon \sim \textit{Bern}(\frac{1}{2})$	$2\epsilon - 1$
Log-Normal	$\ln \mathcal{N}(\mu; \sigma)$	$\epsilon \sim \mathcal{N}(\mu;\sigma^2)$	$\exp(\epsilon)$
Inv Gamma	$i\mathcal{G}(k;\theta)$	$\epsilon \sim \mathcal{G}(k;\theta^{-1})$	$\frac{1}{\epsilon}$

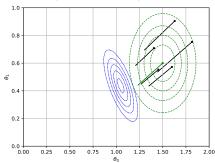
Table from http://blog.shakirm.com/2015/10/ machine-learning-trick-of-the-day-4-reparameterisation-tricks/

## A nice survey with more recent developments (very active area of research)

Zhang, Cheng, et al. "Advances in variational inference." IEEE transactions on pattern analysis and machine intelligence 41.8 (2018): 2008-2026.



## Reparameterized gradient

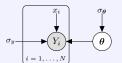


Length of gradients increased for visibility. Graphics inspired by Arto Klami @ ProbAl2021.

Notice the direction of each sample's gradient:

- Score-function gradient: Towards the mode of q
- Reparameterization-gradient: (Approximately) towards high density region of the exact posterior  $p(\theta|D)$ .

### Code Task: Reparameterization-gradient for linear regression



$$\bullet \ \theta = \{w_0, w_1\}, \ \theta \sim \mathcal{N}(\mathbf{0}, \sigma_{\theta} \cdot \mathbf{I}_{2 \times 2})$$

• 
$$Y_i | \{ \boldsymbol{\theta}, x_i, \sigma_y \} \sim \mathcal{N}(w_0 + w_1 \cdot x_i, \sigma_y^2)$$

In this task you will implement the score-function gradient:

$$\nabla_{\boldsymbol{\lambda}} \mathcal{L} \left( q \right) = \underset{\boldsymbol{\epsilon} \sim \boldsymbol{\phi}}{\mathbb{E}} \left[ \left( \nabla_{\boldsymbol{\theta}} \log p(\boldsymbol{\theta}, \mathcal{D}) - \nabla_{\boldsymbol{\theta}} \log q(\boldsymbol{\theta} \,|\, \boldsymbol{\lambda}) \right) \nabla_{\boldsymbol{\lambda}} f(\boldsymbol{\epsilon}, \boldsymbol{\lambda}) \right]$$

- We provide  $\nabla_{\theta} \log p(\theta, \mathcal{D})$ ,  $\nabla_{\theta} \log q(\theta \mid \lambda)$  and  $\nabla_{\lambda} f(\epsilon, \lambda)$  for this model.
- Go to Exercise 2 in

  Day2-AfterLunch/students\_BBVI.ipynb.
- ullet Experiment with the number of Monte-Carlo samples M per iteration, the learning-rate, and the number of iterations. Compare with the output of the Score Function Gradient.

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## Takeaway Message

Score Function is more general, but Reparametrization is better if applicable.

(Manual) Define your data model and the prior.

$$p(\mathcal{D}, \boldsymbol{\theta}) = p(\mathcal{D}|\boldsymbol{\theta})p(\boldsymbol{\theta})$$

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$$\boldsymbol{\lambda}_{t+1} = \boldsymbol{\lambda}_t + \rho \nabla_{\boldsymbol{\lambda}} \mathcal{L}(\boldsymbol{\lambda}_t)$$

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- Automatic-Differentiation engines take care of gradients.

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- Using either score-funtion or reparametrization gradients.
- Automatic-Differentiation engines take care of gradients.
- (Automatic) Approximate inference result

$$q(\boldsymbol{\theta}|\boldsymbol{\lambda}^*) = \arg\min_{q} \mathrm{KL}\left(q(\boldsymbol{\theta}|\boldsymbol{\lambda})||p(\boldsymbol{\theta}|\mathcal{D})\right)$$

Probabilistic programming: Variational inference in Pyro

#### Pyro

Pyro (pyro.ai) is a Python library for probabilistic modeling, inference, and criticism, integrated with PyTorch.

- **Modeling:** Directed graphical models
  - Neural networks (via nn. Module)
  - ...
- Inference: Variational inference including BBVI, SVI
  - Monte Carlo including Importance sampling and Hamiltonian Monte Carlo
  - ...
- Criticism: 

  Point-based evaluations
  - Posterior predictive checks
  - ...

## ... and there are also many other possibilities

Tensorflow is integrating probabilistic thinking into its core, InferPy is a local alternative, etc.

## Pyro models

## Simple example

$$\begin{aligned} & \mathsf{temp} & & \sim \mathcal{N}(15, 2) \\ & \mathsf{sensor} & & \sim \mathcal{N}(\mathsf{temp}, 1) \\ \\ & p(\mathsf{sensor} = 18, \mathsf{temp}) \end{aligned}$$

## Pyro models

## Simple example

$$\begin{array}{ll} \mathsf{temp} & \sim \mathcal{N}(15,2) \\ \mathsf{sensor} & \sim \mathcal{N}(\mathsf{temp},1) \\ \\ p(\mathsf{sensor} = 18,\mathsf{temp}) \end{array}$$

#### Pyro models:

- random variables ⇔ pyro.sample
- observations ⇔ pyro.sample with the obs argument

## Pyro models

## Simple example

```
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```

#### Pyro models:

- random variables ⇔ pyro.sample
- $\bullet$  observations  $\Leftrightarrow {\tt pyro.sample}$  with the obs argument

```
#The observations
obs = {'sensor': torch.tensor(18.0)}

def model(obs):
    temp = pyro.sample('temp', dist.Normal(15.0, 2.0))
    sensor = pyro.sample('sensor', dist.Normal(temp, 1.0), obs=obs['sensor'])
```

#### **Inference Problem**

$$p(\mathsf{temp}|\mathsf{sensor}=18)$$

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$$p(\mathsf{temp}|\mathsf{sensor} = 18)$$

#### **Variational Solution**

$$\min_{\mathbf{q}} \operatorname{KL}\left(\mathbf{q}(\mathsf{temp}) || p(\mathsf{temp}|\mathsf{sensor} = 18)\right)$$

#### **Inference Problem**

$$p(\mathsf{temp}|\mathsf{sensor} = 18)$$

#### **Variational Solution**

$$\min_{q} \operatorname{KL}\left( {q(\mathsf{temp})} || p(\mathsf{temp}|\mathsf{sensor} = 18) \right)$$

### **Pyro Guides:**

• Define the *q* **distributions** in variational settings.

#### **Inference Problem**

$$p(\mathsf{temp}|\mathsf{sensor} = 18)$$

#### **Variational Solution**

```
\min_{q} \mathrm{KL}\left(\frac{q(\mathsf{temp})}{||p(\mathsf{temp}|\mathsf{sensor}=18))}\right)
```

#### **Pyro Guides:**

- Define the *q* **distributions** in variational settings.
- Build proposal distributions in importance sampling, MCMC.
- ...

## **Pyro Guides:**

- Guides are arbitrary stochastic functions.
- Guides produces samples for those variables of the model which are not observed.

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- Guides are arbitrary stochastic functions.
- Guides produces samples for those variables of the model which are not observed.

### **Guide requirements**

- the guide has the same input signature as the model
- ② all unobserved sample statements that appear in the model appear in the guide.

## Example

```
#The observations
obs = {'sensor': torch.tensor(18.0)}

def model(obs):
    temp = pyro.sample('temp', dist.Normal(15.0, 2.0))
    sensor = pyro.sample('sensor', dist.Normal(temp, 1.0), obs=obs['sensor'])
```

```
#The guide
def guide(obs):
    a = pyro.param("mean", torch.tensor(0.0))
    b = pyro.param("scale", torch.tensor(1.), constraint=constraints.positive)
    temp = pyro.sample('temp', dist.Normal(a, b))
```

## Code-task: VB for a simple Gaussian model

### Exercise: Pyro implementation for a simple Gaussian model

Day2-AfterLunch/student\_simple\_gaussian\_model\_pyro.ipynb



- $X_i \mid \{\mu, \gamma\} \sim \mathcal{N}(\mu, 1/\gamma)$
- $\bullet \ \mu \sim \mathcal{N}(0,\tau)$
- $\gamma \sim \text{Gamma}(\alpha, \beta)$
- Implement a pyro guide for the graphical model above.
- Specify suitable variational approximation in the form of a Pyro guide.

$$q(\mu, \gamma) = \dots$$

• Check the differences with the following notebook (no Pyro implementation).

Day2-BeforeLunch/student\_simple\_model.ipynb