

Introduction to

# Algorithm Design and Analysis

[16] Dynamic Programming 1

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# In the last class...

- Single-source shortest paths
  - From BFS to the Dijkstra algorithm
- All-pairs shortest paths
  - BF1, BF2, BF3
  - Floyd-Warshall algorithm

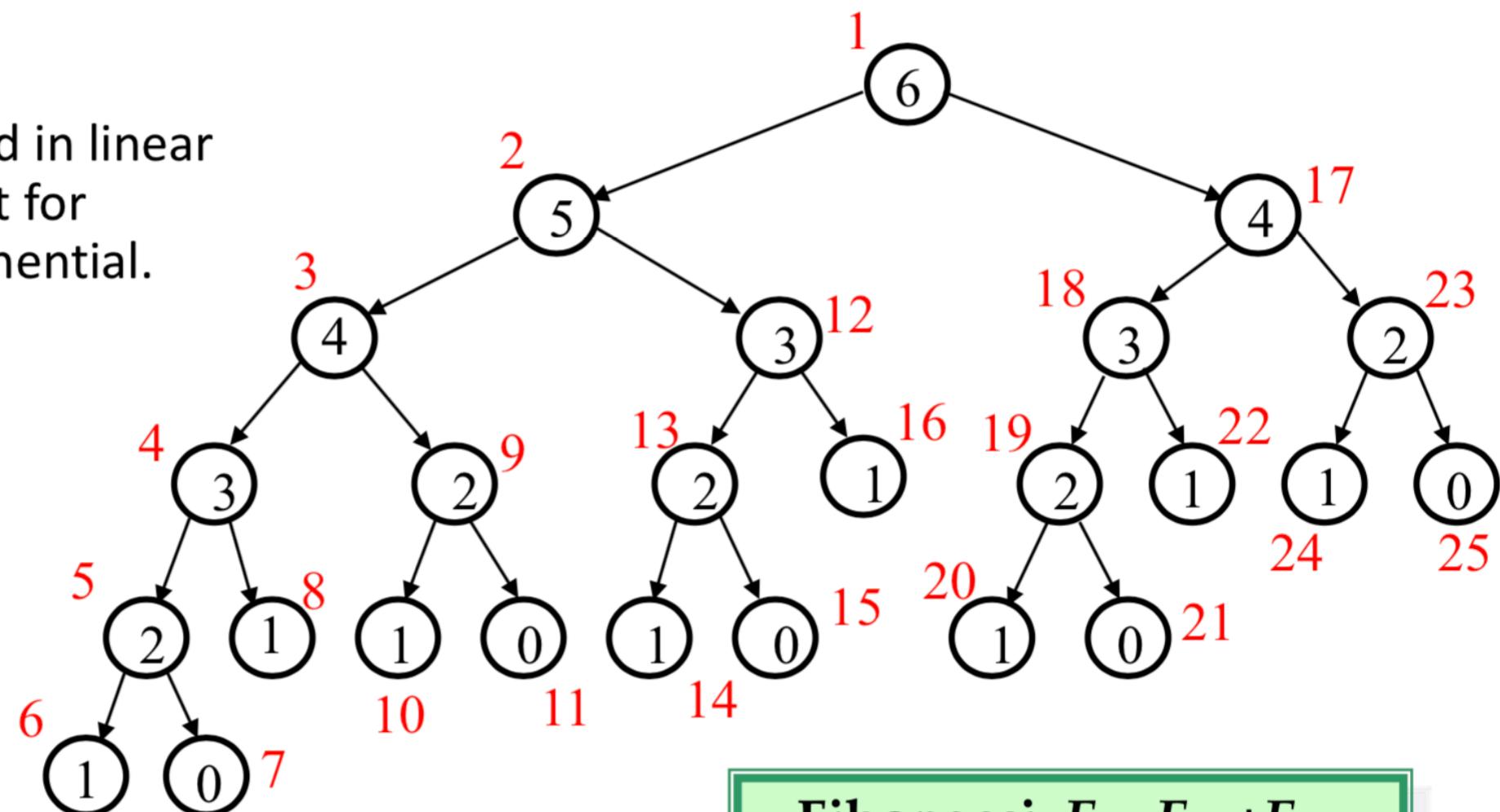
# Dynamic Programming

- Basic Idea of Dynamic Programming (DP)
  - Smart scheduling of subproblems
- Minimum Cost Matrix Multiplication
  - BF1, BF2
  - A DP solution
- Weighted Binary Search Tree
  - The “same” DP with matrix multiplication

# Brute Force Recursion

The  $F_n$  can be computed in linear time easily, but the cost for recursion may be exponential.

The number of activation frames are  
 $2F_{n+1} - 1$



**Fibonacci:**  $F_n = F_{n-1} + F_{n-2}$

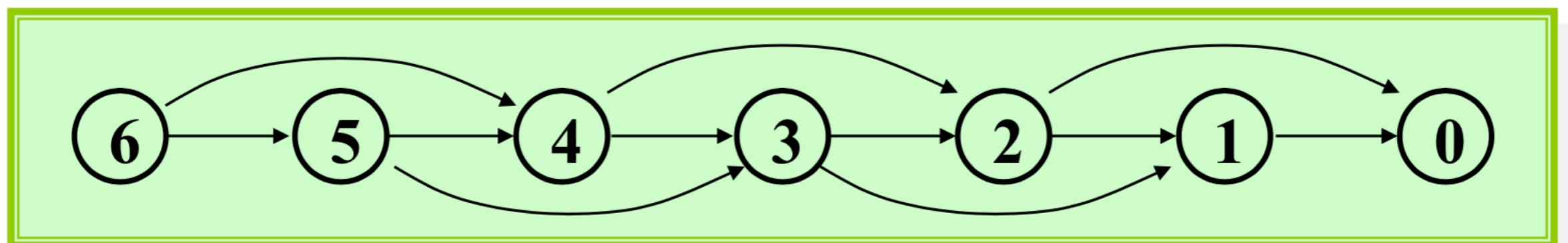
## For your reference

$$F_n = \frac{1}{\sqrt{5}} \left[ \left( \frac{1 + \sqrt{5}}{2} \right)^n - \left( \frac{1 - \sqrt{5}}{2} \right)^n \right]$$

0, 1, 1, 2, 3, 5, 8, 13, 21, 35, ...

# Subproblem Graph

- The subproblem graph for a recursive algorithm A of some problem is defined as:
  - vertex: the instance of the problem
  - directed edge: I->J if and only if when A invoked on I, it makes a recursive call directly on instance J.
- Portion A(P) of the subproblem graph for Fibonacci function: [here is fib\(6\)](#)



# Properties of Subproblem Graph

- If A always terminates, the subproblem graph for A is a DAG.
  - For each path in the tree of activation frames of a particular call of A,  $A(P)$ , there is a corresponding path in the subproblem graph of A connecting vertex P and a base-case vertex.
  - The subproblem graph can be viewed as a dependency graph of subtasks to be solved.
- A top-level recursive computation traverse the entire subproblem graph in some **memoryless** style.

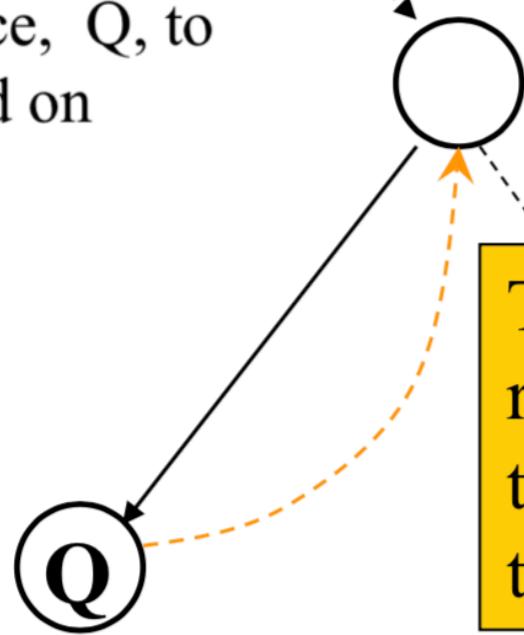
# Basic Idea of DP

- Smart recursion
  - Compute each subproblem **only once**
- Basic process of a “smart” recursion
  - Find a reverse **topological order** for the subproblem graph
    - In most cases, the order can be determined **by particular knowledge** of the problem
    - General method based on DFS is available
  - Scheduling the subproblems according to the reverse topological order
  - **Record** the subproblem solutions in a **dictionary**

# Recursion by DP

## Case 1: White Q

a instance,  $Q$ , to be called on

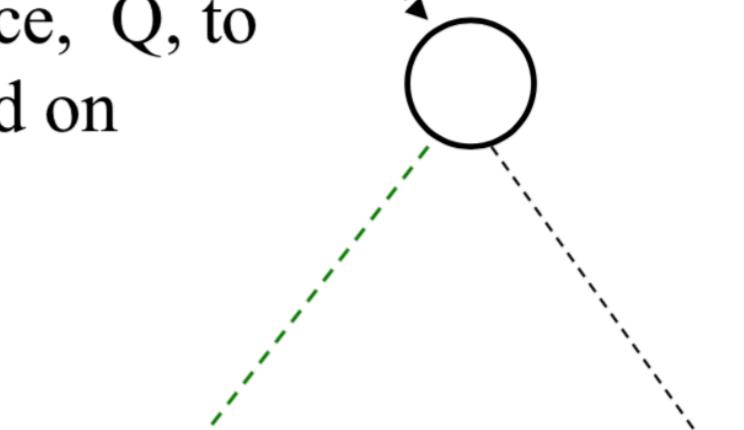


$Q$  is undiscovered (white), go ahead with the recursive call

To backtracking,  
record the result into  
the dictionary ( $Q$ ,  
turned black)

## Case 2: Black Q

a instance,  $Q$ , to be called on



$Q$  is finished (black), only “checking” the edge, retrieve the result from the dictionary

**Note: for DAG, no gray vertex will be met**

# Fibonacci by DP

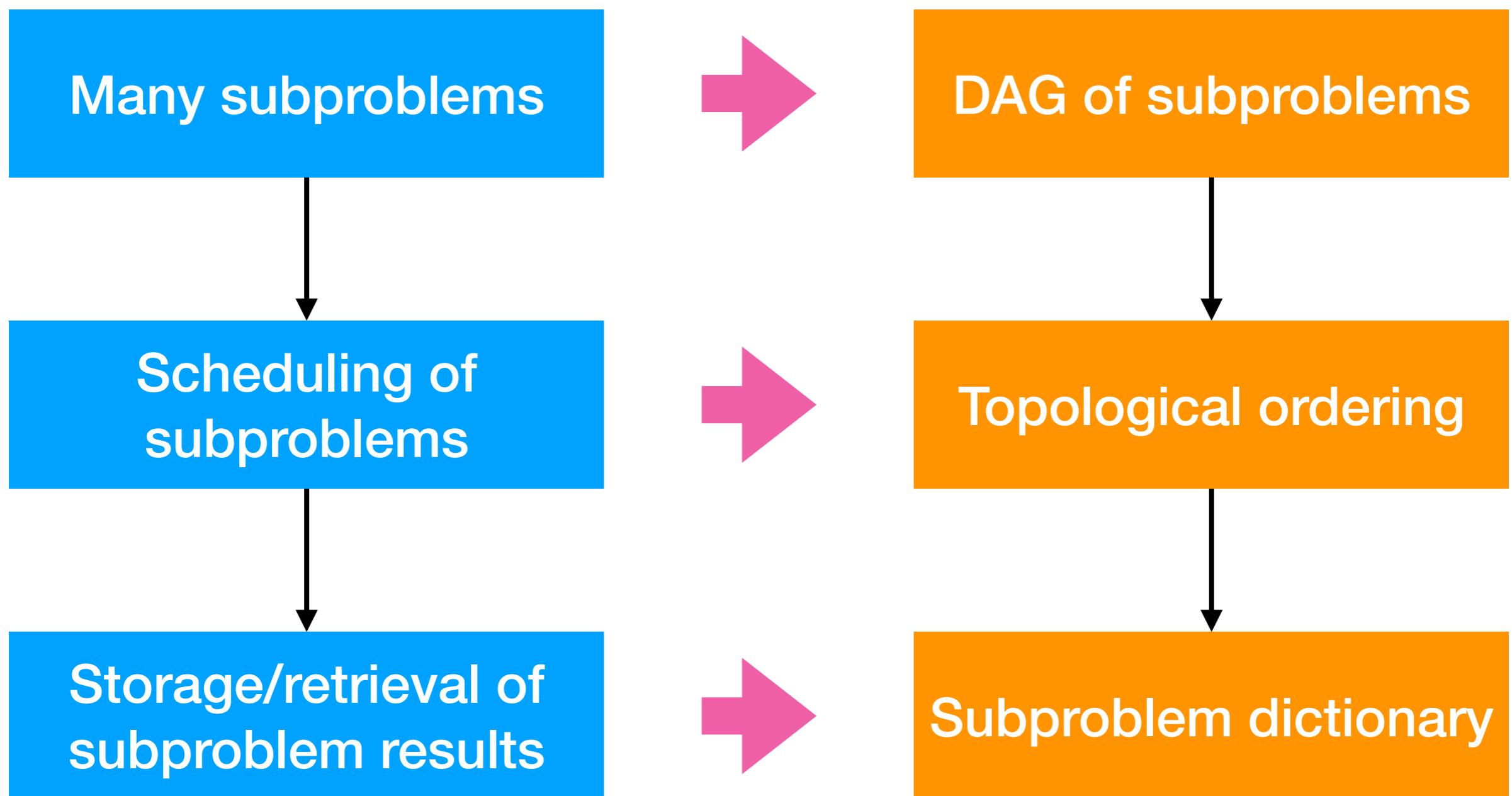
```
fibDPwrap(n)
```

```
Dict soln=create(n);  
return fibDP(soln,n)
```

This is the wrapper, which will contain processing existing in original recursive algorithm wrapper.

```
fibDP(soln,k)  
int fib, f1, f2;  
if (k<2) fib=k;  
else  
    if (member(soln, k-1)==false)  
        f1=fibDP(soln, k-1);  
    else  
        f1= retrieve(soln, k-1);  
    if (member(soln, k-2)==false)  
        f2=fibDP(soln, k-2);  
    else  
        f2= retrieve(soln, k-2);  
    fib=f1+f2;  
    store(soln, k, fib);  
return fib
```

# DP: New Concept Recursion



# Matrix Multiplication Order Problem

- The task:

- Find the product:  $A_1 \times A_2 \times \dots \times A_{n-1} \times A_n$
- $A_i$  is 2-dimensional array of different legal sizes

- The issues:

- Matrix multiplication is associative
- Different computing order results in great difference in the number of operations

- The problem:

- Which is the best computing order

# Cost for Matrix Multiplication

Let  $C = A_{pxq} \times B_{qxr}$

$$c_{i,j} = \sum_{k=1}^q a_{ik} b_{kj}$$

There are q multiplication

$C$  has  $pxr$  elements as  $c_{i,j}$

So,  $pqr$  multiplications altogether

# Cost for Matrix Multiplication

Let  $C = A_{pxq} \times B_{qxr}$

$$c_{i,j} = \sum_{k=1}^q a_{ik} b_{kj}$$

An example:  $A_1 \times A_2 \times A_3 \times A_4$   
 $30 \times 1 \quad 1 \times 40 \quad 40 \times 10 \quad 10 \times 25$   
 $((A_1 \times A_2) \times A_3) \times A_4: 20700$  multiplications  
 $A_1 \times (A_2 \times (A_3 \times A_4)): 11750$   
 $(A_1 \times A_2) \times (A_3 \times A_4): 41200$   
 $A_1 \times ((A_2 \times A_3) \times A_4): 1400$

$C$  has  $pxr$  elements as  $c_{i,j}$

So,  $pqr$  multiplications altogether

# Looking for a Greedy Solution

- Strategy 1: “cheapest multiplication first”
  - Success:  $A_{30 \times 1} \times ((A_{1 \times 40} \times A_{40 \times 10}) \times A_{10 \times 25})$
  - Fail:  $(A_{4 \times 1} \times A_{1 \times 100}) \times A_{100 \times 5}$
- Strategy 2: “largest dimension first”
  - Correct for the second example above
  - $A_{1 \times 10} \times A_{10 \times 10} \times A_{10 \times 2}$ : two results

# Intuitive Solution

- Matrices:  $A_1, A_2, \dots, A_n$
- Dimension: dim:  $d_0, d_1, d_2, \dots, d_{n-1}, d_n$ , for  $A_i$  is  $d_{i-1} \times d_i$
- Sub-problem: seq:  $s_0, s_1, s_2, \dots, s_{k-1}, s_{len}$ , which means the multiplication of  $k$  matrices, with the dimensions:  $d_{s0} \times d_{s1}, d_{s1} \times d_{s2}, \dots, d_{s[ len ] - 1} \times d_{s[ len ]}$ .
  - Note: the original problem is: seq=(0,1,2,...,n)

# Intuitive Solution

```
mmTry1(dim, len, seq)
if (len<3) bestCost=0
else
    bestCost=∞;
    for (i=1; i≤len-1; i++)
        c=cost of multiplication at position seq[i];
        newSeq=seq with ith element deleted;
        b=mmTry1(Dim, len-1, newSeq);
        bestCost=min(bestCost, b+c);
    return bestCost
```

Recursion on index sequence:  
(seq): 0, 1, 2, ..., n (len=n)  
with the  $k$ th matrix is  $A_k$  ( $k \neq 0$ ) of the size  
 $d_{k-1} \times d_k$ ,  
and the  $k$ th ( $k < n$ ) multiplication is  $A_k \times A_{k+1}$ .

$$T(n)=(n-1)T(n-1)+n, \quad \text{in } \Theta((n-1)!)$$

# Subproblem Graph

- Key issue
  - How can a subproblem be denoted using a **concise identifier**?
  - For mmTry1, the difficulty originates from the **varied intervals** in each newSeq.
- If we look at the **last** (contrast to the **first**) multiplication, the **two** (not one) resulted subproblems are both contiguous subsequences, which can be uniquely determined by the pair:
  - <head-index, tail index>

# Improved Recursion

```
mmTry2(dim, low, high)
```

Only one matrix

```
if (high-low==1) bestCost=0
```

```
else
```

```
    bestCost=∞;
```

```
    for (k=low+1; k≤high-1; k++)
```

```
        a=mmTry2(dim, low, k);
```

```
        b=mmTry2(dim, k, high);
```

```
        c=cost of multiplication at position k;
```

```
        bestCost=min(bestCost, a+b+c);
```

```
return bestCost
```

with dimensions:  
dim[low], dim[k], and  
dim[high]

Still in  $\Omega(2^n)$ !

# Smart Recursion by DP

- DFS can traverse the subproblem graph in time  $O(n^3)$ 
  - At most  $n^{2/2}$  vertices, as  $\langle i,j \rangle$ ,  $0 \leq i < j \leq n$ .
  - At most  $2n$  edges leaving a vertex

```
mmTry2DP(dim, low, high, cost)
```

```
.....
```

```
for (k=low+1; k≤high-1; k++)  
    if (member(low,k)==false) a=mmTry2(dim, low, k);  
        else a=retrieve(cost, low, k);  
    if (member(k,high)==false) b=mmTry2(dim, k, high);  
        else b=retrieve(cost, k, high);  
.....
```

```
store(cost, low, high, bestCost);  
return bestCost
```

Corresponding to the recursive procedure of DFS

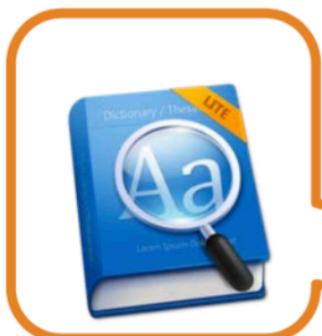
# Order of Computation

- Dependency between subproblems

**matrixOrder( $n$ , cost, last)**

- **for ( $low=n-1$ ;  $low \geq 1$ ;  $low--$ )**
- **for ( $high=low+1$ ;  $high \leq n$ ;  $high++$ )**

DP dict



Compute solution of subproblem ( $low$ ,  $high$ ) and store it in  $cost[low][high]$  and  $last[low][high]$

- **return  $cost[0][n]$**

# Multiplication Order

- Input: array **dim** = $(d_0, d_1, \dots, d_n)$ , the dimension of the matrices.
- Output: array **multOrder**, of which the  $i$ th entry is the index of the  $i$ th multiplication in an optimum sequence.

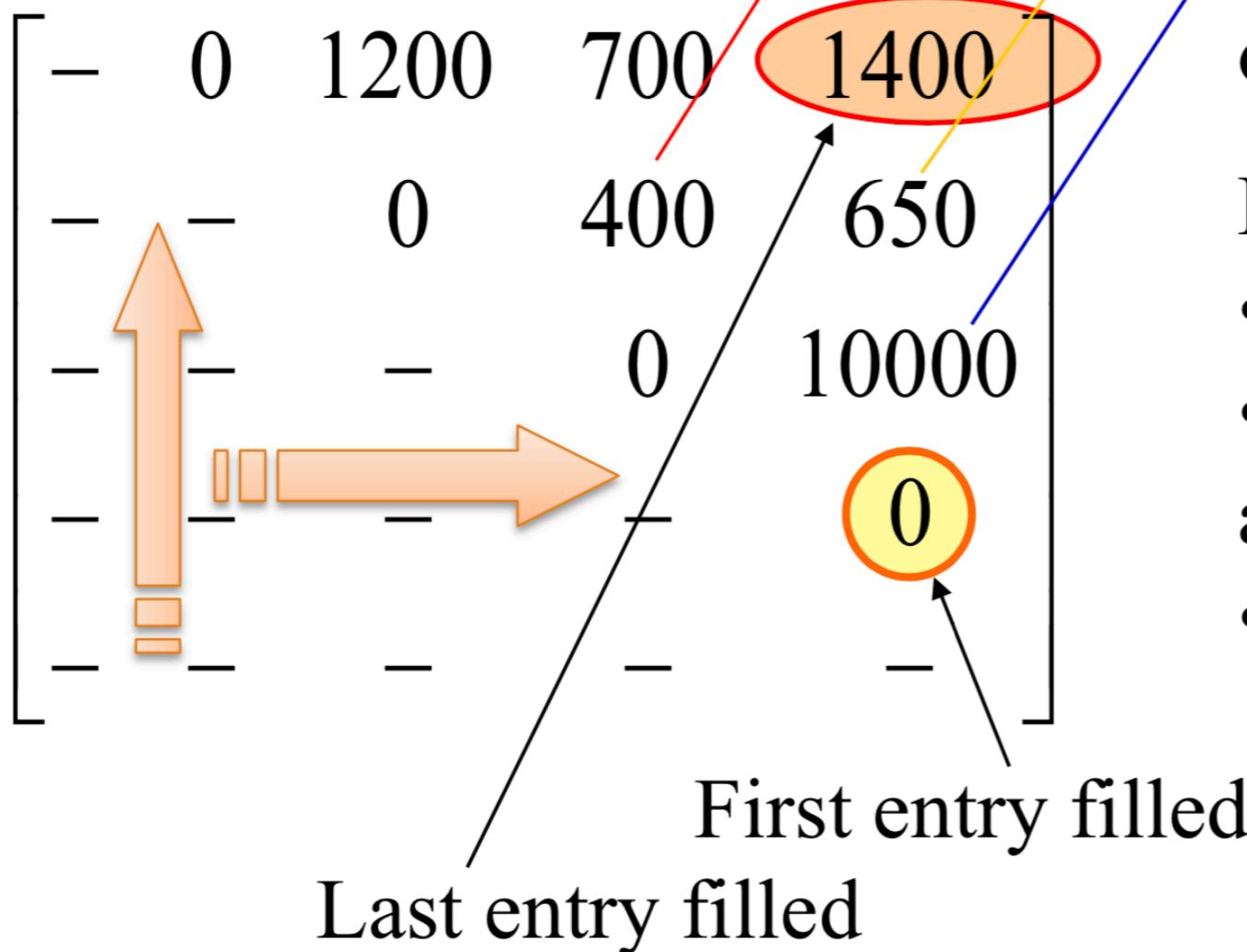
Using the stored results

```
float matrixOrder(int[] dim, int n, int[] multOrder)
<initialization of last,cost,bestcost,bestlast...>
for (low=n-1; low≥1; low--)
    for (high=low+1; high≤n; high++)
        if (high-low==1) <base case>
        else bestcost=∞;
        for (k=low+1; k≤high-1; k++)
            a=cost[low][k];
            b=cost[k][high]
            c=multCost(dim[low], dim[k],
dim[high]);
            if (a+b+c<bestCost)
                bestCost=a+b+c; bestLast=k;
            cost[low][high]=bestCost;
            last[low][high]=bestLast;
extractOrderWrap(n, last, multOrder)
return cost[0][n]
```

# An Example

- Input:  $d_0=30, d_1=1, d_2=40, d_3=10, d_4=25$

*cost as finished*



Note:  $\text{cost}[i][j]$  is the least cost of  $A_{i+1} \times A_{i+2} \times \dots \times A_j$ .

For each selected  $k$ , retrieving:

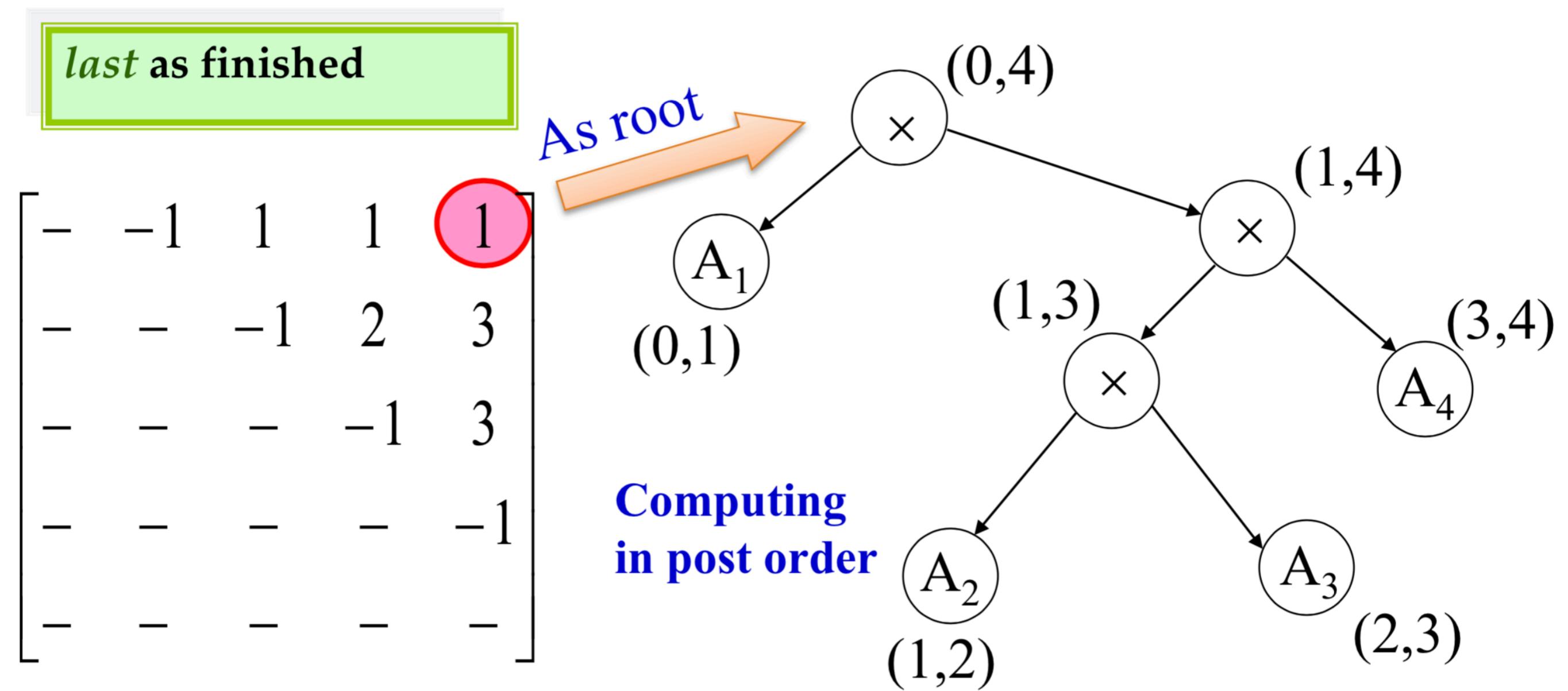
- least cost of  $A_{i+1} \times \dots \times A_k$ .
- least cost of  $A_{k+1} \times \dots \times A_j$ .

and computing:

- cost of the last multiplication

# Arithmetic Expression Tree

- Example input:  $d_0=30, d_1=1, d_2=40, d_3=10, d_4=25$



# Getting the optimal Order

- The core procedure is `extractOrder`, which fills the `multiOrder` array for subproblem `(low, high)`, using information in the `last` array.

```
extractOrder(low, high, last, multOrder)
```

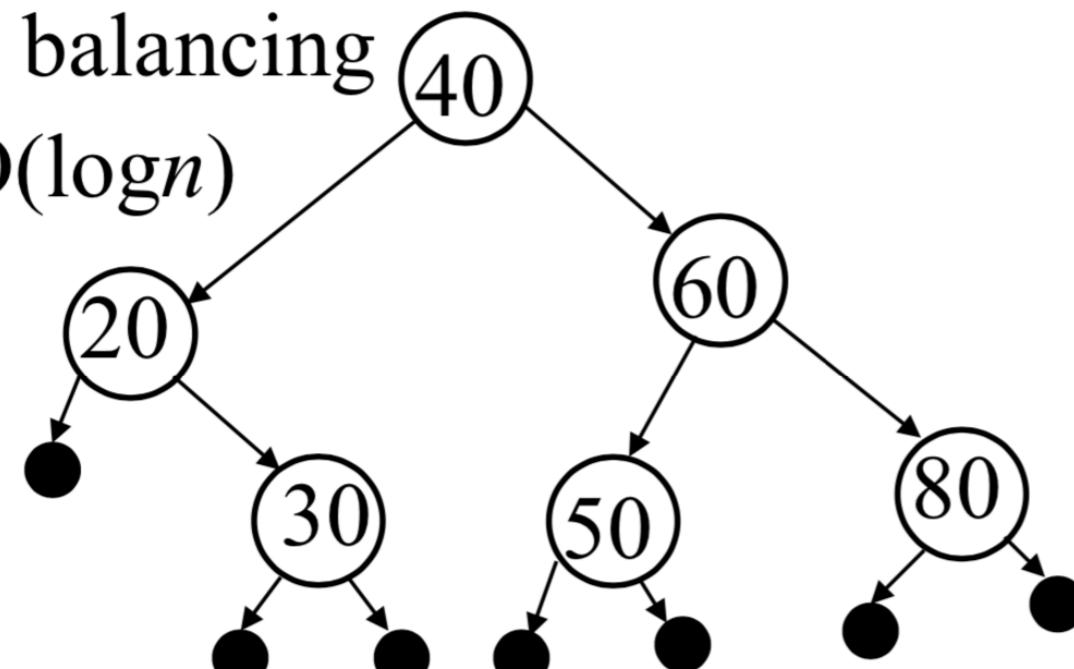
```
int k;  
if (high-low>1)  
    k=last[low][high];           Just a post-order traversal  
    extractOrder(low, k, last, multOrder);  
    extractOrder(k, high, last, multOrder);  
    multOrder[multOrderNext]=k;  
    multOrderNext++;
```

*initialized in the wrapper*

# Binary Search Tree

Good balancing

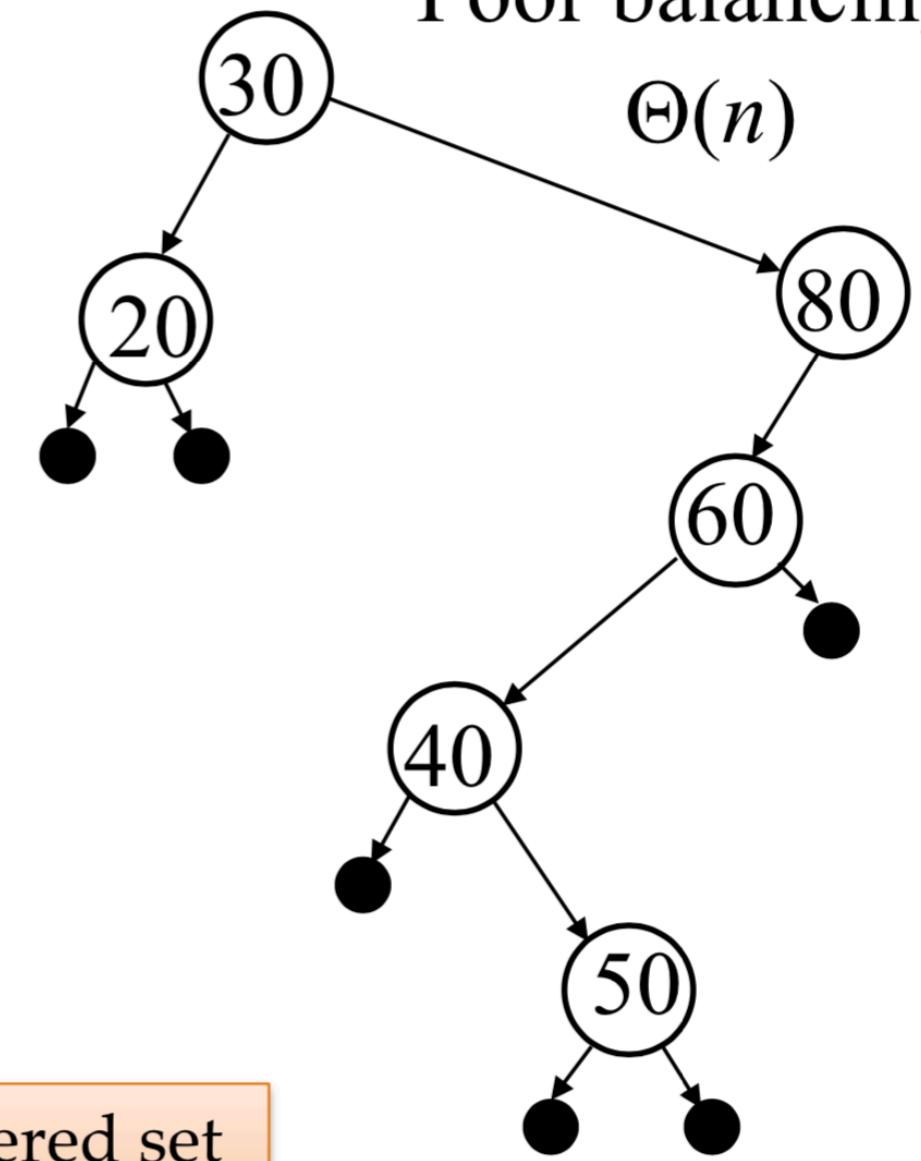
$\Theta(\log n)$



*In a properly drawn tree, pushing forward to get the ordered list.*

Poor balancing

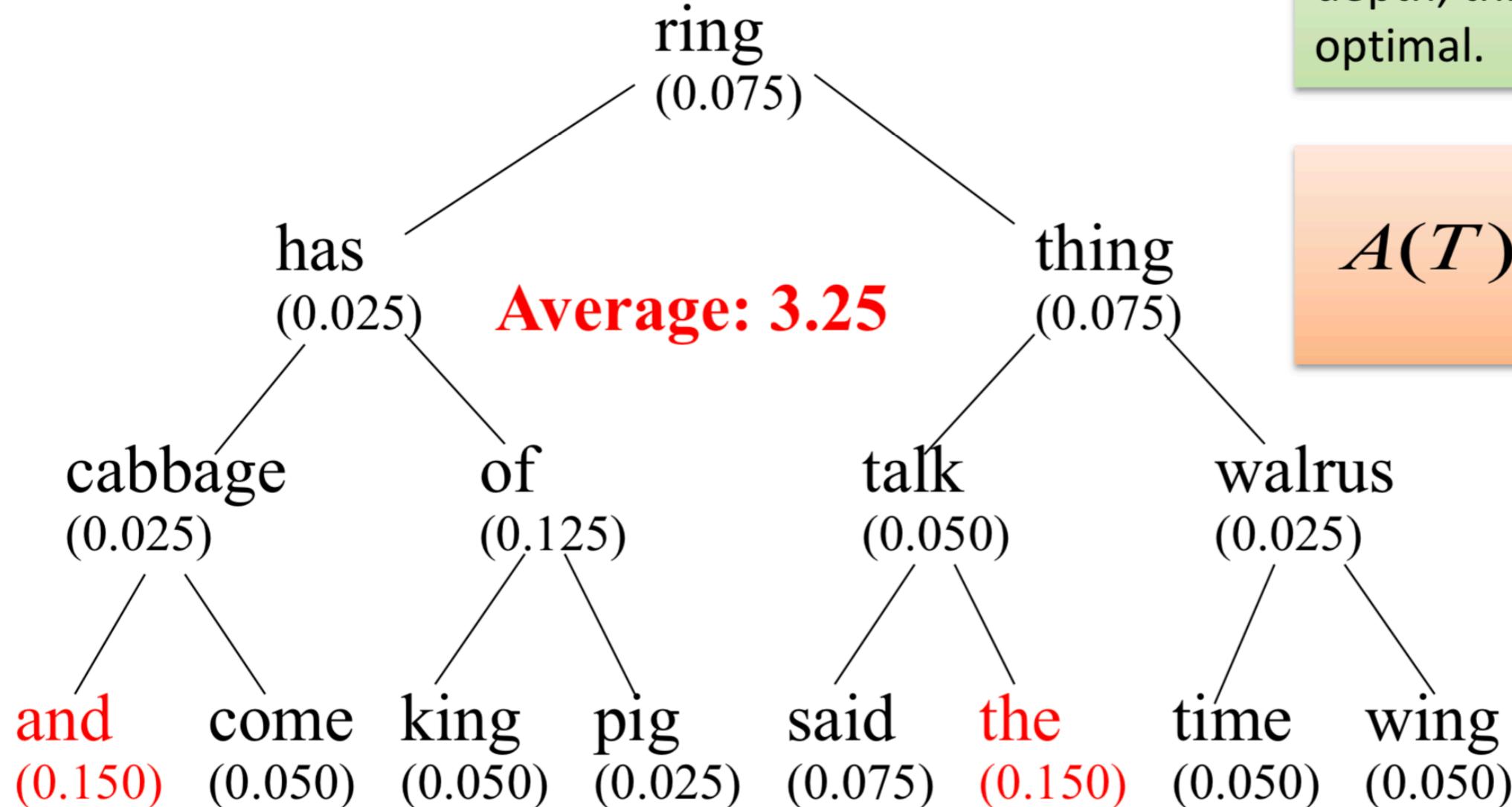
$\Theta(n)$



- Each node has a key, belonging to a linear ordered set
- An inorder traversal produces a sorted list of the keys

# Key with Different Frequencies

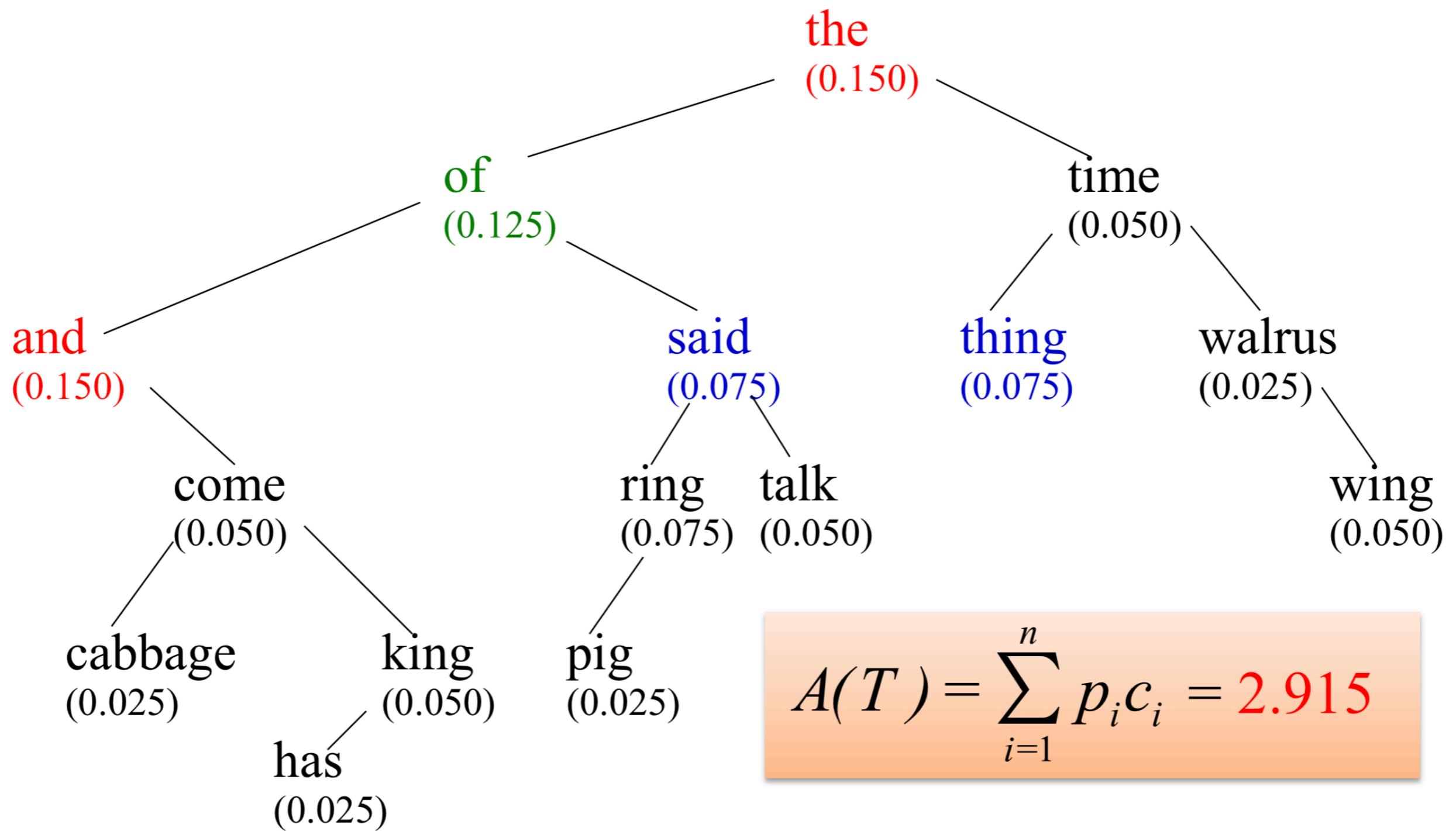
A binary search tree perfectly balanced



Since the keys with larger frequencies have larger depth, this tree is not optimal.

$$A(T) = \sum_{i=1}^n p_i c_i$$

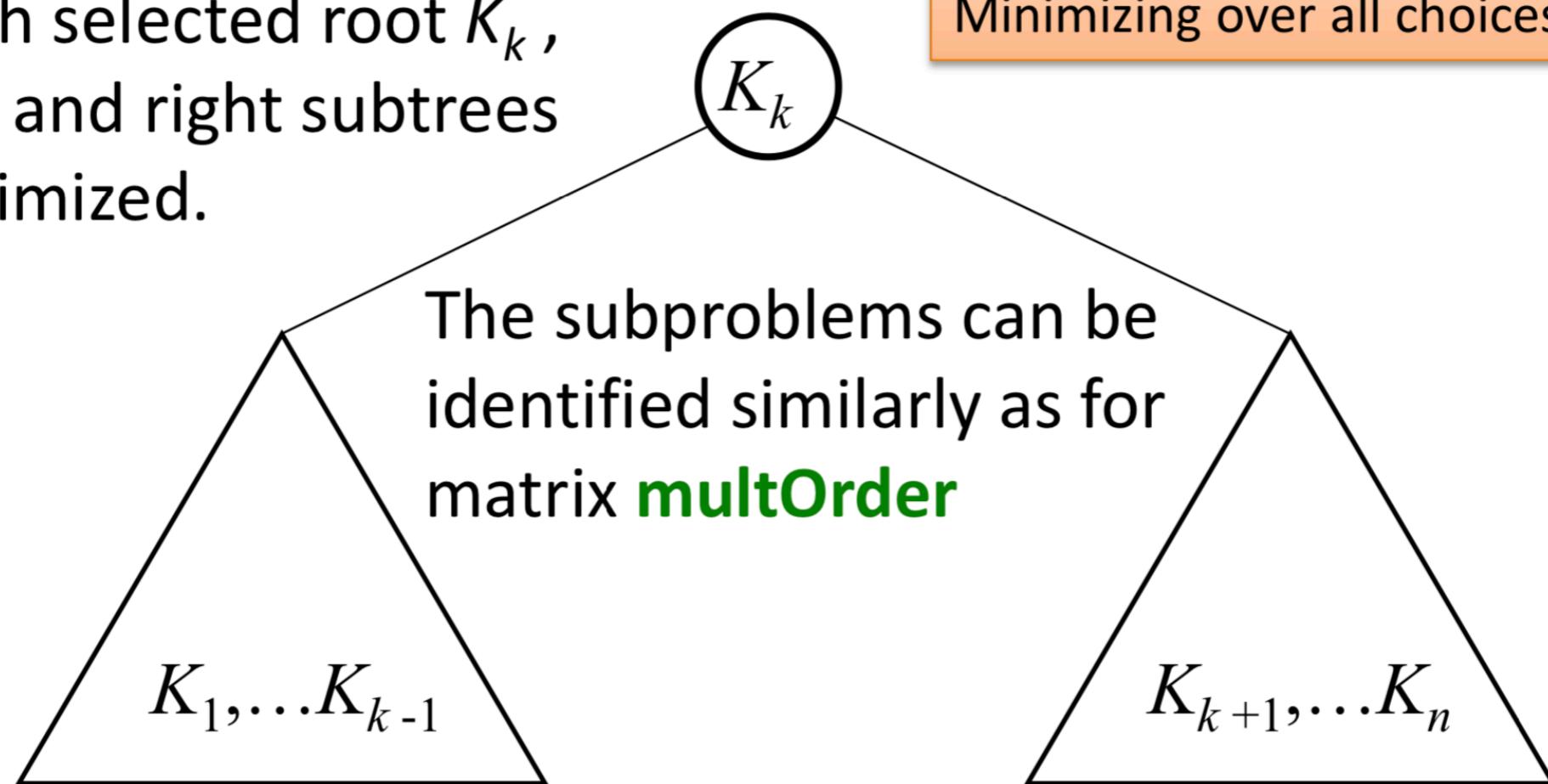
# Unbalanced but Improved



# Optimal Binary Tree

For each selected root  $K_k$ ,  
the left and right subtrees  
are optimized.

The problem is decomposes by the  
choices of the root.  
Minimizing over all choices



Subproblems as left and right subtrees

# Problem Rephrased

- Subproblem identification
  - The keys are in sorted order.
  - Each subproblem can be identified as a pair of index (low, high)
- Expected solution of the subproblem
  - For each key  $K_i$ , a weight  $p_i$  is associated.
    - Note:  $p_i$  is the probability that the key is searched for.
  - The subproblem (low, high) is to find the binary search tree with **minimum weighted retrieval cost**.

# Minimum Weighted Retrieval Cost

- $A(\text{low}, \text{high}, r)$  is the minimum weighted retrieval cost for subproblem  $(\text{low}, \text{high})$  when  $K_r$  is chosen as the root of its binary search tree.
- $A(\text{low}, \text{high})$  is the minimum weighted retrieval cost for subproblem  $(\text{low}, \text{high})$  over all choices of the root key.
- $p(\text{low}, \text{high})$ , equal to  $p_{\text{low}} + p_{\text{low}+1} + \dots + p_{\text{high}}$ , is the weight of the subproblem  $(\text{low}, \text{high})$ .
  - Note:  $p(\text{low}, \text{high})$  is the probability that the key searched for is in this interval.

# Subproblem Solutions

- Weighted retrieval cost of a subtree
  - $T$  contains  $K_{\text{low}}, \dots, K_{\text{high}}$ , and the weighted retrieval cost of  $T$  is  $W$ , with  $T$  being a whole tree.
  - As a subtree with the root at level 1, the weighted retrieval cost of  $T$  will be:  $W+p(\text{low}, \text{high})$
- So, the recursive relations are:
  - $A(\text{low}, \text{high}, r) = p_r + p(\text{low}, r-1) + A(\text{low}, r-1) + p(r+1, \text{high}) + A(r+1, \text{high}) = p(\text{low}, \text{high}) + A(\text{low}, r-1) + A(r+1, \text{high})$
  - $A(\text{low}, \text{high}) = \min\{A(\text{low}, \text{high}, r) \mid \text{low} \leq r \leq \text{high}\}$

# Using DP

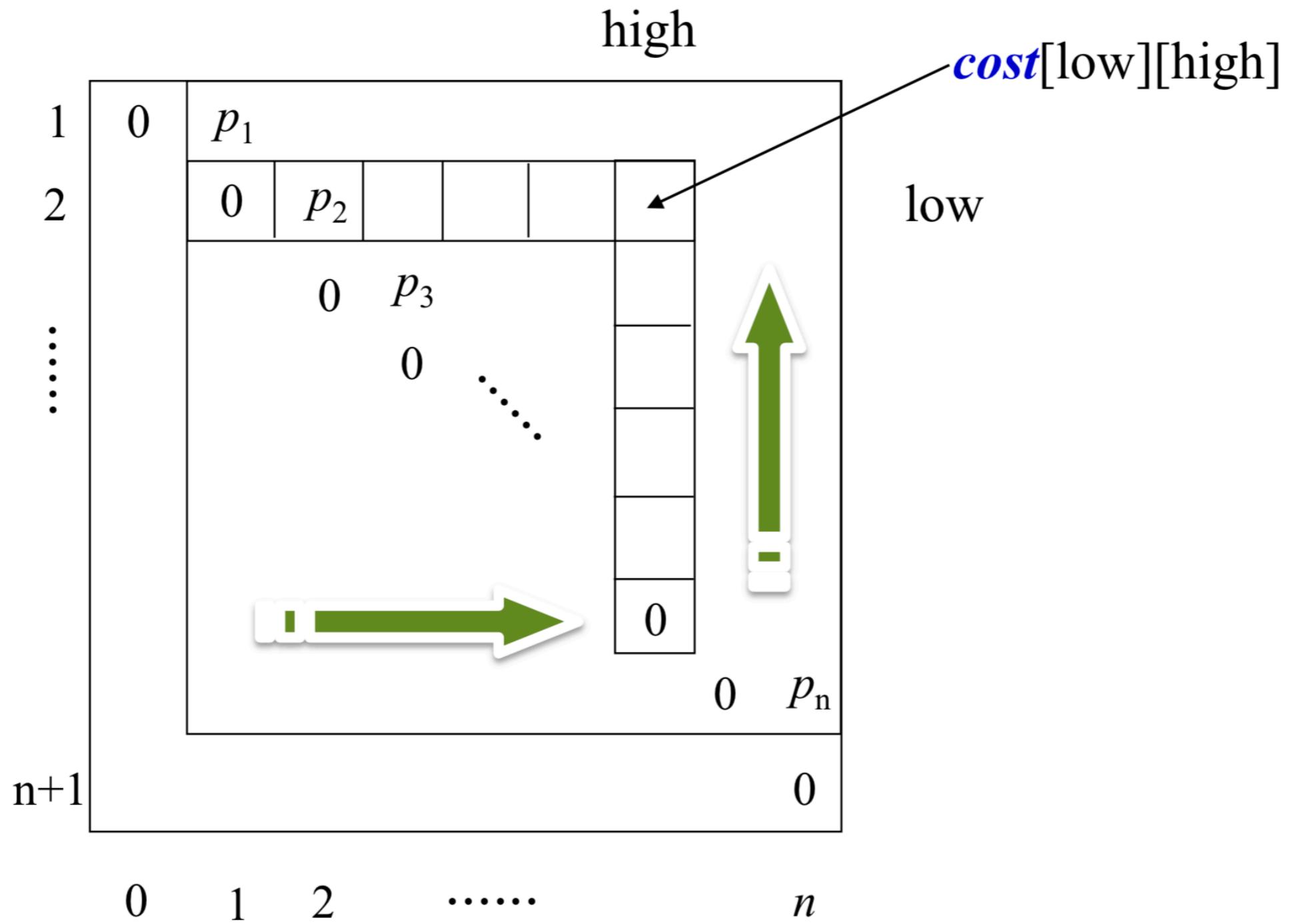
- Array **cost**

- $\text{Cost}[\text{low}][\text{high}]$  gives the minimum weighted search cost of subproblem ( $\text{low}$ ,  $\text{high}$ ).
- The  $\text{cost}[\text{low}][\text{high}]$  depends upon subproblems with **higher first index** (row number) and **lower second index** (column number)

- Array **root**

- $\text{root}[\text{low}][\text{high}]$  gives the best choice of root for subproblem ( $\text{low}$ ,  $\text{high}$ )

# Array cost



# Optimal BST by DP

```
bestChoice(prob, cost, root, low, high)
```

```
    if (high<low)
```

```
        bestCost=0;
```

```
        bestRoot=-1;
```

```
    else
```

```
        bestCost=∞;
```

```
        for (r=low; r≤high; r++)
```

```
            rCost=p(low,high)+cost[low][r-1]+cost[r+1][high];
```

```
            if (rCost<bestCost)
```

```
                bestCost=rCost;
```

```
                bestRoot=r;
```

```
                cost[low][high]=bestCost;
```

```
                root[low][high]=bestRoot;
```

```
    return
```

```
optimalBST(prob,n,cost,root)
```

```
    for (low=n+1; low≥1; low--)
```

```
        for (high=low-1; high≤n; high++)
```

```
            bestChoice(prob,cost,root,low,high)
```

```
    return cost
```

in  $\Theta(n^3)$

**Thank you!**  
**Q & A**