

Implicit integration

in static case:

$$F(u) = F_{ext}$$

At each j F_{ext}^{j+1} can be expanded based on Taylor expansion:

$$f(u)^{j+1} = f(u)^j + \frac{\partial f}{\partial u} \bigg|_u (u^{j+1} - u^j) + \dots$$

therefore; truncating to the first 2 terms:

$$F(u)^{j+1} = F(u)^j + K^j \Delta u = F_{ext}$$

$$K^j \Delta u = F_{ext} - F_{int} = \text{Residual}$$

K^j is the tangent stiffness matrix

dynamic case with Newmark:

$$(F_i)_{t_{n+1}} = F_{ext,t_{n+1}}$$

$$m \ddot{u}_{t_{n+1}} + c \dot{u}_{t_{n+1}} + (F_i)_{t_{n+1}} = F_{ext,t_{n+1}}$$

$$(F_i)_{t_{n+1}} = F_{int,t_{n+1}}$$

1/3

$$\begin{aligned} (F_i)^{j+1}_{t_{n+1}} &= \frac{1}{\beta} \frac{F_i^j}{\Delta t^2} + \frac{\partial F_i^j}{\partial u_{t_{n+1}}} \Delta u^j = F_{ext,t_{n+1}} \\ \ddot{u}^j &= u_{t_{n+1}}^{j+1} - u_{t_n}^j \end{aligned}$$

$$\frac{\partial (F_i)^j}{\partial u_{t_{n+1}}} = \frac{\partial \ddot{u}^j}{\partial u_{t_{n+1}}} + c \frac{\partial \dot{u}^j}{\partial u_{t_{n+1}}} + \frac{\partial F_i}{\partial u_{t_{n+1}}}$$

$$\ddot{u}^j_{t_{n+1}} = \frac{1}{\beta \Delta t^2} \Delta u - \frac{1}{\beta \Delta t} \dot{u}_t + \left(\frac{1}{2\beta} - 1 \right) \ddot{u}_t$$

$$\frac{\partial \ddot{u}}{\partial \dot{u}_{t_{n+1}}} = \frac{1}{\beta \Delta t^2}$$

$$\dot{u}_{t_{n+1}} = \frac{1}{\beta \Delta t} \Delta u + \left(1 - \frac{1}{\beta} \right) \dot{u}_t + \left(1 - \frac{1}{2\beta} \right) \Delta t \ddot{u}_t$$

$$\frac{\partial \dot{u}}{\partial \dot{u}_{t_{n+1}}} = \frac{1}{\beta \Delta t}$$

$$\begin{aligned} \frac{\partial (F_i)^j}{\partial u_{t_{n+1}}} &= M \frac{\ddot{u}}{\partial \Delta t^2} + c \frac{\dot{u}}{\partial \Delta t} + \frac{\partial F_i}{\partial u_{t_{n+1}}} \\ \ddot{u}_{t_{n+1}} &= \ddot{u}_{t_{n+1}} \end{aligned}$$

Pressure

$$(\hat{F}_i)_{t+1}^j \rightarrow \frac{\partial \hat{F}_i}{\partial u_{t+1}} \Delta u_{t+1}^j = F_{ext, t+1}^j$$

~~$(\hat{F}_i)_{t+1}^j \rightarrow \frac{\partial \hat{F}_i}{\partial u_{t+1}} \Delta u_{t+1}^j = F_{ext, t+1}^j$~~

~~$(K)_{t+1}^j$~~

$$(K)_{t+1}^j \Delta u_{t+1}^j = F_{ext, t+1}^j - (\hat{F}_i)_{t+1}^j = \text{Residual} = R_{t+1}^j$$

$$R_{t+1}^j = F_{ext, t+1}^j - (K)_{t+1}^j \Delta u_{t+1}^j = (\hat{F}_i)_{t+1}^j = M \ddot{u}_{t+1} + (\dot{u}_{t+1})^T (F_i)_{t+1}^j \quad (K_r)_{t+1}^j$$

$$R_{t+1}^j = F_{ext, t+1}^j - (K_r)_{t+1}^j \Delta u_{t+1}^j = M \left[\frac{1}{\rho \Delta t^2} \Delta u - \frac{1}{\rho \Delta t} \dot{u}_t - \left(\frac{1}{2\beta} - 1 \right) \ddot{u}_t \right]$$

$$= \left[\frac{\gamma}{\rho \Delta t} \Delta u + \left(1 - \frac{\gamma}{\beta} \right) \dot{u}_t + \left(1 - \frac{\gamma}{2\beta} \right) \Delta t \ddot{u}_t \right]$$

$$= K \Delta u_{t+1}$$

$$\hat{R}_{t+1}^i = F_{x_{t+1}}^i - F_{i, t+1}^i - M \left[\frac{1}{\beta \Delta t^2} v_{t+1} - \frac{1}{\beta \Delta t^2} \dot{v}_t - \left(\frac{1}{2\beta} - 1 \right) \ddot{v}_t \right]$$

$$= C \left[\frac{\gamma}{\beta \Delta t} v_{t+1} - \frac{\gamma}{\beta \Delta t} v_t + \left(1 - \frac{\gamma}{\beta} \right) \dot{v}_t + \left(1 - \frac{\gamma}{2\beta} \right) \Delta t \ddot{v}_t \right]$$

$$- k \Delta v_{t+1}$$

$$\frac{\text{Residual}}{0} = F_{i, t+1}^i - F_{i, t}^i - \Delta u \left[\frac{1}{\beta \Delta t^2} \pi + \frac{\gamma}{\beta \Delta t} \dot{\pi} + \dot{v}_t + \frac{1}{\beta \Delta t} \pi - \left(1 - \frac{\gamma}{\beta} \right) \ddot{v}_t \right] + \ddot{v}_t \left[-\frac{1}{2\beta} \pi + \left(1 - \frac{\gamma}{2\beta} \right) \Delta t \ddot{v}_t \right]$$

$$\hat{k} \Delta v = F_{i, t+1}^i - F_{i, t}^i + \dot{v}_t \left[-\frac{1}{\beta \Delta t} \pi - \left(1 - \frac{\gamma}{\beta} \right) \dot{\pi} + \ddot{v}_t \left[-\left(\frac{1}{2\beta} - 1 \right) \pi + \left(1 - \frac{\gamma}{2\beta} \right) \Delta t \ddot{v}_t \right] \right]$$