

# Mask R-CNN - Visualize Trash detection

In [31]:

```
import os
import sys
import random
import math
import re
import time
import glob
import skimage
import numpy as np
import tensorflow as tf
import matplotlib
import matplotlib.pyplot as plt
import matplotlib.patches as patches

ROOT_DIR = os.getcwd()
print(ROOT_DIR)

# Import Mask RCNN
sys.path.append(ROOT_DIR)
from mrcnn import utils
from mrcnn import visualize
from mrcnn.visualize import display_images
import mrcnn.model as modellib
from mrcnn.model import log

from trash import trash

%matplotlib inline

# Directory to save logs and trained model
MODEL_DIR = os.path.join(ROOT_DIR, "logs")

# Path to Trash trained weights
TRASH_WEIGHTS_PATH = "weights/mask_rcnn_trash_0200_030519_large.h5" #the best

print('Weights being used: ', TRASH_WEIGHTS_PATH)
```

C:\Users\91740\Desktop\wade-ai-master\Trash\_Detection  
 Weights being used: weights/mask\_rcnn\_trash\_0200\_030519\_large.h5

## Configurations

In [32]:

```
config = trash.TrashConfig()
TRASH_DIR = 'trash'
TRASH_DIR
```

Out[32]: 'trash'

In [33]:

```
# Override the training configurations with a few
# changes for inferencing.
class InferenceConfig(config.__class__):
    # Run detection on one image at a time
    GPU_COUNT = 1
```

```
IMAGES_PER_GPU = 1
```

```
config = InferenceConfig()
config.display()
```

Configurations:

```
BACKBONE                resnet101
BACKBONE_STRIDES        [4, 8, 16, 32, 64]
BATCH_SIZE              1
BBOX_STD_DEV            [0.1 0.1 0.2 0.2]
COMPUTE_BACKBONE_SHAPE  None
DETECTION_MAX_INSTANCES 100
DETECTION_MIN_CONFIDENCE 0.95
DETECTION_NMS_THRESHOLD 0.3
FPN_CLASSIF_FC_LAYERS_SIZE 1024
GPU_COUNT               1
GRADIENT_CLIP_NORM      5.0
IMAGES_PER_GPU          1
IMAGE_CHANNEL_COUNT      3
IMAGE_MAX_DIM            1024
IMAGE_META_SIZE         14
IMAGE_MIN_DIM            1024
IMAGE_MIN_SCALE          0
IMAGE_RESIZE_MODE        square
IMAGE_SHAPE              [1024 1024   3]
LEARNING_MOMENTUM        0.9
LEARNING_RATE            0.001
LOSS_WEIGHTS             {'rpn_class_loss': 1.0, 'rpn_bbox_loss': 1.0, 'mrcnn_
class_loss': 1.0, 'mrcnn_bbox_loss': 1.0, 'mrcnn_mask_loss': 1.0}
MASK_POOL_SIZE          14
MASK_SHAPE              [28, 28]
MAX_GT_INSTANCES        100
MEAN_PIXEL              [123.7 116.8 103.9]
MINI_MASK_SHAPE         (56, 56)
NAME                    trash
NUM_CLASSES              2
POOL_SIZE                7
POST_NMS_ROIS_INFERENCE 1000
POST_NMS_ROIS_TRAINING   2000
PRE_NMS_LIMIT            6000
ROI_POSITIVE_RATIO       0.33
RPN_ANCHOR_RATIOS        [0.5, 1, 2]
RPN_ANCHOR_SCALES        (32, 64, 128, 256, 512)
RPN_ANCHOR_STRIDE        1
RPN_BBOX_STD_DEV         [0.1 0.1 0.2 0.2]
RPN_NMS_THRESHOLD        0.7
RPN_TRAIN_ANCHORS_PER_IMAGE 256
STEPS_PER_EPOCH          17
TOP_DOWN_PYRAMID_SIZE    256
TRAIN_BN                 False
TRAIN_ROIS_PER_IMAGE     200
USE_MINI_MASK            True
USE_RPN_ROIS             True
VALIDATION_STEPS         50
WEIGHT_DECAY             0.0001
```

## Notebook Preferences

In [34]:

```
# Device to load the neural network on.
# Useful if you're training a model on the same
# machine, in which case use CPU and leave the
# GPU for training.
DEVICE = "/cpu:0" # /cpu:0 or /gpu:0
```

```
# Inspect the model in training or inference modes
# values: 'inference' or 'training'
# TODO: code for 'training' test mode not ready yet
TEST_MODE = "inference"
```

```
In [35]: def get_ax(rows=1, cols=1, size=16):
        """Return a Matplotlib Axes array to be used in
        all visualizations in the notebook. Provide a
        central point to control graph sizes.

        Adjust the size attribute to control how big to render images
        """
        _, ax = plt.subplots(rows, cols, figsize=(size*cols, size*rows))
        return ax
```

## Load Validation Dataset

```
In [36]: # Load validation dataset
dataset = trash.TrashDataset()
dataset.load_trash(TRASH_DIR, "val")

# Must call before using the dataset
dataset.prepare()

print("Images: {}\nClasses: {}".format(len(dataset.image_ids), dataset.class_names))
```

```
Images: 0
Classes: ['BG', 'trash']
```

## Load Model

```
In [37]: # Create model in inference mode
with tf.device(DEVICE):
    model = modellib.MaskRCNN(mode="inference", model_dir=MODEL_DIR, config=config)
```

```
In [38]: # Load the weights you trained
weights_path = os.path.join(ROOT_DIR, TRASH_WEIGHTS_PATH)
model.load_weights(weights_path, by_name=True)
print("Loading weights ", TRASH_WEIGHTS_PATH)
```

```
Loading weights weights/mask_rcnn_trash_0200_030519_large.h5
```

## Select test images

```
In [39]: # Get images from the directory of all the test images
jpg = glob.glob("images/*.jpg")
jpeg = glob.glob("images/*.jpeg")
jpg.extend(jpeg)
jpg
```

```
Out[39]: ['images\\319.jpg',
          'images\\roadside_garbage.jpg',
          'images\\sample_test.jpg',
          'images\\urban_cctv_garbage.jpg']
```

# Run detection on images

In [40]:

```

for image in jpg:
    print(image)
    image = skimage.io.imread('{}'.format(image))

    # Run object detection
    results = model.detect([image], verbose=1)

    print("-----")
    print("Number of Trash elements detected: ", len(r['scores']))
    for j in range(len(r['scores'])):
        print("Element",j,r['scores'][j])
    print("-----")

    # Display results
    ax = get_ax(1)
    r = results[0]
    visualize.display_instances(image, r['rois'], r['masks'], r['class_ids'],
                               dataset.class_names, r['scores'], ax=ax,
                               title="Predictions")

```

```

images\319.jpg
Processing 1 images
image                shape: (640, 640, 3)          min:    0.00000  max:   255.000
00  uint8
molded_images        shape: (1, 1024, 1024, 3)      min: -123.70000  max:   147.100
00  float64
image metas         shape: (1, 14)                  min:    0.00000  max:  1024.000
00  float64
anchors             shape: (1, 261888, 4)          min:   -0.35390  max:    1.291
34  float32

```

```

-----
Number of Trash elements detected:  1
Element 0 0.99703836
-----

```

```

*** No instances to display ***

```

```

images\roadside_garbage.jpg
Processing 1 images
image                shape: (1334, 2000, 3)        min:    0.00000  max:   255.000
00  uint8
molded_images        shape: (1, 1024, 1024, 3)      min: -123.70000  max:   151.100
00  float64
image metas         shape: (1, 14)                  min:    0.00000  max:  2000.000
00  float64
anchors             shape: (1, 261888, 4)          min:   -0.35390  max:    1.291
34  float32

```

```

-----
Number of Trash elements detected:  0
-----

```

```

images\sample_test.jpg
Processing 1 images
image                shape: (1907, 4031, 3)        min:    0.00000  max:   255.000
00  uint8
molded_images        shape: (1, 1024, 1024, 3)      min: -123.70000  max:   151.100
00  float64
image metas         shape: (1, 14)                  min:    0.00000  max:  4031.000
00  float64
anchors             shape: (1, 261888, 4)          min:   -0.35390  max:    1.291
34  float32

```

```

-----
Number of Trash elements detected:  1
Element 0 0.98225456

```

```
-----
images\urban_cctv_garbage.jpg
Processing 1 images
image          shape: (533, 800, 3)      min:  0.00000  max: 255.000
00  uint8
molded_images  shape: (1, 1024, 1024, 3)  min: -123.70000 max: 151.100
00  float64
image metas    shape: (1, 14)             min:  0.00000  max: 1024.000
00  float64
anchors        shape: (1, 261888, 4)     min:  -0.35390 max:  1.291
34  float32
-----

Number of Trash elements detected:  4
Element 0 0.9974147
Element 1 0.99541014
Element 2 0.99172735
Element 3 0.9753823
-----
```

Predictions





Predictions



Predictions







In [ ]: