

Mathematics

P. Tansuntorn

Last updated July 11, 2019

Contents

I	Part IA	1
1	Numbers and Sets	3
2	Groups	5
2.1	Examples of Groups	5
2.1.1	Axioms for groups	5
2.1.2	Examples from geometry	6
2.1.3	Permutation on a set	6
2.1.4	Subgroups and homomorphisms	7
2.1.5	Symmetry groups	8
2.1.6	The Möbius group	8
2.2	Lagrange's Theorem	10
2.2.1	Cosets	10
2.2.2	Lagrange's theorem	11
2.2.3	Group of small order (up to 8)	11
2.2.4	Quaternions	11
2.2.5	Fermat-Euler theorem	11
2.3	Group actions	11
2.3.1	Group actions	12
2.3.2	Orbit-stabilizer theorem	12
2.3.3	Cayley's theorem	12
2.3.4	Conjugacy classes	12
2.3.5	Cauchy's theorem	12
2.4	Quotient groups	12
2.4.1	Normal subgroups	12
2.4.2	Quotient groups	12
2.4.3	The isomorphism theorem	12
2.5	Matrix groups	12
2.5.1	The general and special linear groups	12
2.5.2	The orthogonal and special orthogonal groups	12
2.5.3	Basis change	12
2.6	Permutations	12
2.6.1	Permutations, Cycles and Transpositions	12
2.6.2	Sign of Permutations	14

2.6.3	Conjugacy in S_n and A_n	14
2.6.4	Simple Groups	14
3	Vectors and Matrices	15
3.1	Vectors	15
3.1.1	Vector Algebra in \mathbb{R}^3	15
3.1.2	Vectors in \mathbb{R}^n and \mathbb{C}^n	15
3.1.3	Concepts in linear algebra	16
3.2	Matrices	16
3.2.1	Algebra of Matrices	16
3.2.2	Matrix as linear transformation	16
3.3	Eigenvalues and Eigenvectors	16
4	Differential Equations	17
4.1	Basic Calculus	17
4.2	1st-order LDEs	17
4.2.1	Equations with constant coefficients	17
4.2.2	Equations with non-constant coefficients	17
4.3	Nonlinear first-order equations	17
4.4	Higher-order LDEs	17
4.5	Multivariate Functions	17
5	Analysis I	19
5.1	Limit and Convergences	20
5.1.1	Series and sequences in \mathbb{R} and \mathbb{C}	20
5.1.2	Sums, products and quotients	21
5.1.3	Absolute convergence	22
5.1.4	Bolzano-Weierstrass theorem	22
5.1.5	Comparison and ratio test	22
5.1.6	Alternating series test	22
5.2	Continuity	22
5.2.1	Continuity of real and complex function	22
5.2.2	The intermediate value theorem	22
5.3	Differentiability	22
5.3.1	Differentiability of functions from \mathbb{R} to \mathbb{R}	22
5.3.2	Derivative of sums and products	22
5.4	Power series	22
5.5	Integration	22
5.5.1	Integrability of monotonic functions	22
6	Probability	23
6.1	Basic concepts	23
6.2	Axiomatic approach	23
6.3	Discrete random variables	23

6.4	Continuous random variables	23
6.5	Inequalities and limits	23
6.5.1	Markov's and Chebyshev's inequality	23
6.5.2	Weak law of large numbers	23
6.5.3	Convexity and Jensen's inequality	23
6.5.4	AM-GM inequality	23
7	Vector Calculus	25
7.1	Curves in \mathbb{R}^3	25
II	Part IB	27
8	Linear Algebra	29
8.1	Vector Spaces	29
8.2	Linear maps	29
8.3	Determinant	29
8.4	Eigenvalues and Eigenvectors	29
8.5	Duals	29
8.6	Bilinear Forms	29
8.7	Inner Product Spaces	29
9	Groups, Rings and Modules	31
9.1	Groups	31
9.1.1	Basics concepts	31
9.1.2	Normal subgroups	31
9.1.3	Sylow subgroups and Sylow theorems	31
9.2	Rings	31
9.2.1	Definition	31
9.2.2	Ideals	32
9.2.3	Fields	32
9.2.4	Factorisation in rings	32
9.2.5	Rings $\mathbb{Z}[a]$ of algebraic integers	32
9.3	Modules	32
9.3.1	Definition	32
9.3.2	Submodules	32
9.3.3	Equivalence of matrices	32
9.3.4	Finitely generated modules over Euclidean domains	32
10	Analysis II	33
10.1	Uniform Convergence	33
10.2	Uniform Continuity and Integration	33
10.3	\mathbb{R}^n as a Normed Space	33
10.4	Differentiation from \mathbb{R}^m to \mathbb{R}^n	33

10.5	Metrice Spaces	33
10.6	The Contraction Mapping Theorem	33
11	Metric and Topological Spaces	35
11.1	Metrics	35
11.1.1	Definition and examples	35
11.1.2	Limits and continuity	35
11.1.3	Open sets and neighbourhoods	35
11.1.4	Characterising limits and continuity	35
11.2	Topology	35
11.2.1	Metric topologies	35
11.3	Connectedness	35
11.4	Compactness	35
12	Complex Analysis	37
12.1	Analytic Functions	37
12.2	Contour Integration and Cauchy's Theorem	37
12.3	Expansions and Singularities	37
12.4	The Residue Theorem	37
13	Complex Methods	39
13.1	Analytic Functions	39
13.2	Contour Integration and Cauchy's Theorem	39
13.3	Residue Calculus	39
13.4	Fourier and Laplace Transforms	39
14	Geometry	41
III	Part II	43
15	Number Theory	45
15.1	Basics	45
15.2	Chinese Remainder Theorem	45
15.3	Law of Quadratic Reciprocity	45
15.4	Binary Quadratic Forms	45
15.5	Distribution of the Primes	45
15.6	Continued fractions and Pell's equation	45
15.7	Primality testing	45
15.8	Factorisation	45
16	Topics in Analysis	47
17	Coding and Cryptography	49

18 Automata and Formal Languages	51
18.1 Register machines	51
18.2 Regular languages and finite-state automata	51
18.3 Pushdown automata and context-free languages	51
19 Logic and Set Theory	53
19.1 Ordinals and Cardinals	53
19.1.1 Well-orderings and order-types	53
19.2 Posets and Zorn's Lemma	53
19.3 Propositional Logic	53
19.4 Predicate Logic	53
19.5 Set Theory	53
19.6 Consistency	53
20 Graph Theory	55
20.1 Introduction	55
20.2 Connectivity and matchinhs	55
20.3 Extremal graph theory	55
20.4 Eigenvalue methods	55
20.5 Graph colouring	55
20.6 Ramsey theory	55
20.7 Probabilistic methods	55
21 Galois Theory	57
21.1 Fields extensions	57
22 Representation Theory	59
22.1 Representations of Finite Groups	59
22.1.1 Representations on vector spaces	59
22.2 Character Theory	59
22.3 Arithmetic Properties of Characters	59
22.4 Tensor Products	59
22.5 Representations of S^1 and SU_2	59
22.6 Further Worked Examples	59
23 Number Fields	61
23.1 Algebraic Number Fields	61
23.2 Ideals	61
23.3 Units	61
23.4 Ideal classes	61
23.5 Dedekind's theorem on the factorisation of primes	61

24 Algebraic Topology	63
24.1 The Fundamental Group	63
24.2 Covering Spaces	63
24.3 The Seifert-Van Kampen Theorem	63
24.4 Simplicial Complexes	63
24.5 Homology	63
24.6 Homology Calculations	63
25 Linear Analysis	65
26 Analysis of Functions	67
27 Riemann Surfaces	69
28 Algebraic Geometry	71
29 Differential Geometry	73
30 Probability and Measure	75

Part I

Part IA

Chapter 1

Numbers and Sets

Chapter 2

Groups

2.1 Examples of Groups

2.1.1 Axioms for groups

Definition 2.1.1. A *group* is a set G , together with a binary operation $*$ on G with the following properties.

1. (Closure axiom) for all g and h in G , $g * h \in G$;
2. (Associativity) for all f, g and h in G , $g * h \in G$, $f * (g * h) = (f * g) * h$;
3. (Existence of identity) there is a unique e in G such that for all g in G , $g * e = g = e * g$;
4. (Existence of inverse) if $g \in G$ there is some h in G such that $g * h = e = h * g$.

These results follow nicely.

Lemma 2.1.1. Let G be any group. Then, given $g \in G$, there is only one element h such that $g * h = e = h * g$. Particularly $(g^{-1})^{-1} = g$.

Lemma 2.1.2 (Cancellation law). Suppose that a, b and x are in a group G . If $a * x = b * x$ then $a = b$.

Lemma 2.1.3. Suppose that a and b are in a group G . Then the equation $a * x = b$ has a unique solution $x = a^{-1} * b$.

Lemma 2.1.4. In any group G , e is the unique solution of $x * x = x$.

Notice that we do not include the familiar assumption that $f * g = g * f$ normally found in arithmetic. In fact, for some interesting groups this equality does not hold.

Definition 2.1.2. Let G be a group with respect to $*$. The elements f and g *commute* if $f * g = g * f$. We call G *abelian* if for all f and g in G , we have $f * g = g * f$.

We adopt the notation gh as equivalent to $g * h$ for simplicity.

2.1.2 Examples from geometry

In this section we examine the idea of group in geometry, using polygons.

2.1.3 Permutation on a set

In this section we will show that permutations of a non-empty set X , in fact, form a group. We start with the definition of permutations acting on a set, although only for finite sets, before developing the idea further into arbitrary sets.

Definition 2.1.3. A *permutation* $\alpha: X \rightarrow X$ is a bijection from X to itself. We say that α acts on the set X . The set of all permutations of X is denoted $\mathcal{P}(X)$.

This set is indeed a group.

Theorem 2.1. The set $\mathcal{P}(X)$ forms a group under composition of functions. We shall write $\alpha\beta(x)$ in place of $\alpha(\beta(x))$.

Proof. We will show that all group axioms are satisfied.

1. It is obvious that if α, β are permutations, then $\alpha\beta$ is also a permutation. Thus the set $\mathcal{P}(X)$ is closed under composition.
2. For any permutations α, β, γ , let $\mu = \alpha\beta$ and $\nu = \beta\gamma$. Then for every x in X ,

$$\begin{aligned}
 (\alpha(\beta\gamma))(x) &= (\alpha\nu)(x) \\
 &= \alpha(\nu(x)) \\
 &= \alpha(\beta(\gamma(x))) \\
 &= \mu(\gamma(x)) \\
 &= (\mu\gamma)(x) \\
 &= ((\alpha\beta)\gamma)(x).
 \end{aligned} \tag{2.1}$$

Thus the permutations are commutative under composition.

3. The identity permutation $\iota(x) = x$ is the identity of $\mathcal{P}(X)$, since $\alpha\iota(x) = \alpha(x) = \iota\alpha(x)$.
4. For any element α of X , the inverse is simply its functional inverse α^{-1} . Direct verification shows that $\alpha\alpha^{-1} = \iota = \alpha^{-1}\alpha$.

□

The above proof lets us write $\alpha\beta\gamma$ for any composition of three or more permutations without any confusion.

Setting $X = \{1, \dots, n\}$, the study of permutation groups is simpler. We shall give a name for such group.

Definition 2.1.4. The *symmetric group* S_n is a set of permutations of $\{1, \dots, n\}$. We say that the group is of degree n .

Theorem 2.2. The order of S_n is $n!$.

Proof. Evidently, there are $n!$ permutations on a set with n elements. □

We now introduce a customary notation for permutation $\rho(x)$ in the form

$$\rho = \begin{pmatrix} 1 & 2 & 3 & \cdots & n \\ \rho(1) & \rho(2) & \rho(3) & \cdots & \rho(n) \end{pmatrix},$$

which mean that the image of the permutation $\rho(i)$ is underneath i in the first row. For example, let α be a permutation on $\{1, 2, 3, 4\}$ with $\alpha(1) = 1, \alpha(2) = 4, \alpha(3) = 2$ and $\alpha(4) = 3$, then

$$\alpha = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 1 & 4 & 2 & 3 \end{pmatrix}.$$

Example 2.1.1. There are 6 permutations in S_3 , they are

$$\begin{pmatrix} 1 & 2 & 3 \\ 1 & 2 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix}.$$

Note that

$$\begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 3 & 1 & 2 \end{pmatrix} \neq \begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 3 \end{pmatrix} \begin{pmatrix} 1 & 2 & 3 \\ 1 & 3 & 2 \end{pmatrix}.$$

Therefore S_3 is not abelian. More generally S_n is not abelian for $n \geq 3$. We will study permutations in more details later on.

2.1.4 Subgroups and homomorphisms

Definition 2.1.5. A *subgroup* of a group G is a subset of G which itself form a group under the operation taken from G .

Theorem 2.3. Let H be a subgroup of G , then the identity element of H is that of G .

A group G always at least admits two subgroup, namely G and the singleton $\{e\}$. We call $\{e\}$ the *trivial subgroup* of G , and we say that H is the *non-trivial subgroup* of G if $H \neq \{e\}$. We say that H is a *proper subgroup* of G if $H \neq G$.

We now give a test for a subset to be a subgroup.

Theorem 2.4 (A test for subgroup). Let G be a group, and H be a non-empty subset of G . Then H is a subgroup of G if and only if

1. if $g \in H$ and $h \in H$, then $gh \in H$, and
2. if $g \in H$ then $g^{-1} \in H$.

Another test is similar and follows from the above theorem.

Theorem 2.5. Let G be a group, and H be a non-empty subset of G . Then H is a subgroup of G if and only if $xy^{-1} \in H$ whenever $x, y \in H$.

The following property of the class of subsets of G is important.

Theorem 2.6. Let G be any group, then the intersection of any collection of subgroups of G is itself a subgroup of G .

Proof. Note that the intersection $\cap_t H_t$ of the subgroups of G , defined as H_t for some t in the index set T , is not empty. Then for every elements $g \in \cap_t H_t$ and $h \in \cap_t H_t$, they also lie in H_t for every t . And thus $gh \in H_t$, so $gh \in \cap_t H_t$. Any element $g \in \cap_t H_t$ also has its inverse in every subgroup H_t . It then follows that $g^{-1} \in \cap_t H_t$. Therefore $\cap_t H_t$ forms a subgroup under the operation of G . \square

As a consequence, we see that for any non-empty subset G_0 of G , we can consider the intersection of the collection of all subgroups H of G than contain G_0 . The collection is not empty, since G is itself in the collection. It follows that the intersection is itself not empty, and is a subgroup of G that contain G_0 . In fact, it is the *smallest subgroup* to contain G_0 . This allows us to propose the next definition.

Definition 2.1.6. Let G_0 be a non-empty subset of a group G . The subgroup of G *generated by* G_0 is the smallest subgroup of G that contains G_0 .

The idea of subgroup is expanded into the notion of a **coset**, which will be explored later.

Definition 2.1.7. Let G, G' be groups. A function $\phi: G \rightarrow G'$ is a *homomorphism* if it takes the action of G to that of G' , namely

$$\phi(gh) = \phi(g)\phi(h),$$

for all $g, h \in G$.

2.1.5 Symmetry groups

2.1.6 The Möbius group

We first begin with the definition of Möbius transformation.

Definition 2.1.8. A *Möbius transformation* is a function f of a complex variable z in the form

$$f(z) = \frac{az + b}{cz + d},$$

for some complex numbers a, b, c and d , with the condition that $ad - bc \neq 0$.

The condition $ad - bc \neq 0$ might not be obvious, but it follows from the fact that

$$f(z) - f(w) = \frac{(ad - bc)(z - w)}{(cz + d)(cw + d)}.$$

If $ad - bc = 0$, then f is constant. This also shows that f is injective.

This definition of the Möbius transformation has two problems. First, a Möbius transformation f is not unique. As for example, the 4-tuples (a, b, c, d) and (ma, mb, mc, md) with $m \neq 0$ will all map a complex number z to a same number. Thus, given f , we *cannot* say what are the coefficients.

The second problem stems from the fact that, for example $1/(z - z_0)$ is not defined at the point z_0 . This means that there is no subset of \mathbb{C} on which all Möbius maps are defined.

Here is an example of this.

Example 2.1.2. Let $f(z) = (z + 2)/z$ and $g(z) = (z + 1)/(z - 1)$. Then,

$$f(g(z)) = \frac{g(z) + 2}{g(z)} = \frac{(z + 1) + 2(z - 1)}{z + 1} = \frac{3z - 1}{z + 1},$$

so that fg fixes the point 1. However, g is not defined when $z = 1$. What's worse is that, if $h(z) = 1/z$ then $hfg(z) = (z + 1)/(3z - 1)$, although g is not defined when $z = 1$, $fg(z)$ is not defined when $z = -1$, and $hfg(z)$ is not defined when $z = 1/3$. More generally, a composition $f_1 \cdots f_n$ of Möbius maps will not be defined at n distinct points in the complex plane.

The following theorem addresses the first problem.

Theorem 2.7. Suppose that $a, b, c, d, \alpha, \beta, \gamma$ and δ are complex numbers with $(ad - bc)(\alpha\delta - \beta\gamma) \neq 0$, and such that for at least three distinct values of z in \mathbb{C} , $cz + d \neq 0$, $\gamma z + \delta \neq 0$, and

$$\frac{az + b}{cz + d} = \frac{\alpha z + \beta}{\gamma z + \delta}.$$

Then there is some non-zero complex number λ such that

$$\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = \lambda \begin{pmatrix} a & b \\ c & d \end{pmatrix}. \quad (2.2)$$

Proof. Consider the quadratic polynomial

$$(az + b)(\gamma z + \delta) = (\alpha z + \beta)(cz + d).$$

The polynomial has three distinct roots, and so it must be a zero polynomial. Therefore, $a\gamma = c\alpha$, $b\gamma + a\delta = c\beta + d\alpha$ and $b\delta = d\beta$, which is equivalent to

$$\begin{pmatrix} d & -b \\ -c & a \end{pmatrix} \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = \begin{pmatrix} \mu & 0 \\ 0 & \mu \end{pmatrix},$$

where $\mu^2 = (ad - bc)(\alpha\delta - \beta\gamma) \neq 0$. We then have

$$\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} = \frac{\mu}{ad - bc} \begin{pmatrix} a & b \\ c & d \end{pmatrix}.$$

□

The first problem is then resolved by showing that the 4-tuple (a, b, c, d) determines f , up to non-zero multiple. The second problem will be resolved differently, by joining an extra point, which is called *the point at infinity* to \mathbb{C} . This point is denoted ∞ .

2.2 Lagrange's Theorem

2.2.1 Cosets

We have introduced the idea of subgroup in the previous section. Now we come to the idea of constructing a subset of any group G from its subgroup. For example, we could define a new subset XY of G by

$$XY = \{xy : x \in X, y \in Y\}$$

for any subgroup X, Y of G . If X is a singleton, that is $X = \{x\}$, we shall adopt a notation $XY = xY$. Such constructions which we shall consider are of the form

$$gH = \{gh : h \in H\} \text{ or } Hg = \{hg : h \in H\}$$

for some $g \in G$, and H is a subgroup of G . The set gH is called the *left coset* of H with respect to g , similarly, Hg is the *right coset* of H with respect to g . Some constructions of this type might turn out to be the same set H . This is illustrated below.

Theorem 2.8. Let H be a subgroup of G , and $g \in G$. Then $g \in H$ if and only if $gH = H$ (or $Hg = H$).

Thus we concern ourselves to the study of gH when $g \notin H$. We will adopt an additive notation $g + H$ in place of gH when such subgroups employ addition. The next results show that a group can be divided into disjoint cosets. This is called the *coset decomposition* of G .

Theorem 2.9. Let H be a subgroup of a group G , then G is a union of its left (or right) cosets.

Proof. Clearly, for any $g \in G$, $g \in gH$. So g is contained in the union. □

Theorem 2.10. Let H be a subgroup of a group G , then any two left cosets of G are either equal or disjoint.

Proof. Let $f, g \in G$ and fH, gH are the two left cosets. Suppose that fH and gH are disjoint, that is, the set $fH \cap gH$ is not empty. Then there exists an element $x \in fH \cap gH$, and so $fy_1 = gy_2$ for some $y_1, y_2 \in H$. Thus $g^{-1}f = y_2y_1^{-1} \in H$ and so $g^{-1}fH = H$; hence $gH = gg^{-1}fH = fH$, hereby proving the theorem. □

Corollary 2.2.1. If $fH = gH$, then $g^{-1}f \in H$.

2.2.2 Lagrange's theorem

Recall the definition of an *order* of a group, denoted $|G|$. The next theorem shows the connection between the orders of a group and its subgroup.

Theorem 2.11 (Lagrange's theorem). Let H be a subgroup of a finite group G . Then $|H|$ divides $|G|$, and $|G|/|H|$ is the number of distinct left (or right) cosets of H in G .

Proof. From the previous theorem we can write a group G as a union of the pairwise disjoint coset left of H . Therefore $G = g_1H \cup g_2H \cup \cdots \cup g_rH$. Consequently,

$$|G| = |g_1H| + |g_2H| + \cdots + |g_rH|.$$

It remains to show that $|g_1H| = |g_2H| = \cdots = |g_rH| = |H|$. Notice that the map $x \mapsto g_jx$ is a bijection from H to g_jH , and so $|g_1H| = |g_2H| = \cdots = |g_rH| = |H|$. Therefore $|G| = r|H|$ and the results follow. \square

One of the corollary of Lagrange's theorem is the following result.

Corollary 2.2.2. Let g be an element of a finite group G . Then the order of g divides the order of G .

Proof. Let d be the order of g . The subgroup $H = \{e, g, g^1, \dots, g^{d-1}\}$ is a subgroup of order d . By Lagrange's Theorem, $|H| \mid |G|$. \square

2.2.3 Group of small order (up to 8)

2.2.4 Quaternions

2.2.5 Fermat-Euler theorem

2.3 Group actions

This section studies **group actions**.

2.3.1 Group actions**2.3.2 Orbit-stabilizer theorem****2.3.3 Cayley's theorem****2.3.4 Conjugacy classes****2.3.5 Cauchy's theorem****2.4 Quotient groups****2.4.1 Normal subgroups****2.4.2 Quotient groups****2.4.3 The isomorphism theorem****2.5 Matrix groups****2.5.1 The general and special linear groups****2.5.2 The orthogonal and special orthogonal groups****2.5.3 Basis change****2.6 Permutations****2.6.1 Permutations, Cycles and Transpositions**

We have given the definition of permutations before.

Definition 2.6.1. Any permutations α, β are said to be *disjoint* if, for every k in $\{1, 2, \dots, n\}$, either $\alpha(k) = k$ or $\beta(k) = k$.

Theorem 2.12. Two permutations commute if they are disjoint.

Proof. Let the two permutations be α and β . For any $k \in \{1, \dots, n\}$, suppose that α fixes k , the case for β can be argued similarly.

Let $\beta(k) = k'$. Then $\alpha\beta(k) = \alpha(k')$ and $\beta\alpha(k) = \beta(k) = k'$. We shall prove that indeed $\alpha(k') = k$.

If $\beta(k') \neq k'$ then we are done by the premise. So suppose $\beta(k') = k'$, but then $\beta(k') = k' = \beta(k)$. This implies $k = k'$ and so $\alpha(k') = \alpha(k) = k'$ as required. \square

We shall further simplify the notation, by introducing fixed points.

Definition 2.6.2. We call that k is a *fixed point* of α , and that α fixes k , if $\alpha(k) = k$.

And so, by convention, we shall left out any integers fixed by α . For example, the permutation

$$\alpha = \begin{pmatrix} 1 & 3 \\ 3 & 1 \end{pmatrix}$$

interchanges 1 and 3, and fixes 2. This notation is still too cumbersome for large n , this drives us to find a new notation. Let us start by noticing that, if we repeatedly apply any permutation α , any elements in $\{1, 2, \dots, n\}$ must eventually return. For example, let

$$\alpha = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 \\ 5 & 3 & 4 & 2 & 1 \end{pmatrix},$$

then $\alpha^2(1) = 1, \alpha^3(2) = 1, \alpha^3(3) = 3, \alpha^3(4) = 4$ and $\alpha^2(5) = 5$. This is easily proven using the pigeonhole principle. Notice that 1 and 5 form a *cycle* between each other, as α sends 1 to 5 and also send 5 to 1; this is also the case for 2, 3, 4. The permutation α sends 2 to 3, 3 to 4, and 4 to 2. This is the motivation to define *cycles*.

Definition 2.6.3. A *cycle* between n_1, n_2, \dots, n_q is the permutation

$$\begin{pmatrix} n_1 & n_2 & \cdots & n_q \\ n_2 & n_3 & \cdots & n_1 \end{pmatrix}.$$

It is denoted by $(n_1 n_2 \cdots n_q)$. The cycle is said to be of length q .

The integers n_1, n_2, \dots, n_q need not be in an increasing order. By inspection, $\alpha = (1\ 5)(2\ 3\ 4) = (2\ 3\ 4)(1\ 5)$. We will show that any permutation can be written in this manner, as the compositions of cycles.

Theorem 2.13. Any permutation α in the symmetric group S_n can be written as a composition of disjoint cycles.

Proof. This will employ the similar strategy used above. For any integer $k \in \{1, \dots, n\}$, we apply α repeatedly, and so we have the sequence $k, \alpha(k), \alpha^2(k), \dots$, and so some elements of this sequence must coincide. Let the two such elements be $\alpha^p(k) = \alpha^q(k)$, with $p < q$. Thus $\alpha^{q-p}(k) = k$. Now there exists a smallest positive number u such that $\alpha^u(k) = k$.

The sequence $k, \alpha(k), \alpha^2(k), \dots, \alpha^{u-1}(k)$ must be distinct. Construct the cycle

$$\gamma_k = (k, \alpha k, \alpha^2(k), \dots, \alpha^{u-1}(k)).$$

Now, two cycles are either disjoint or identical. For if $y = \alpha^d(x)$ for some integer d , then $\gamma_x = \gamma_y$, and we say that x and y belong to the same cycle. Continue doing this for all elements of $\{1, \dots, n\}$, we will have a collection of cycles $\{\gamma_{k_1}, \gamma_{k_2}, \dots, \gamma_{k_m}\}$, all of them are pairwise disjoint.

Now consider the composition $\gamma_{k_1} \gamma_{k_2} \cdots \gamma_{k_m}$. For any $x \in \{1, \dots, n\}$, then $\gamma_{k_d}(x) = \alpha(x)$ if x and k_d belong to the same cycle; else $\gamma_{k_d}(x) = x$. And so $\alpha = \gamma_{k_1} \gamma_{k_2} \cdots \gamma_{k_m}$. \square

The proof above use the idea of constructing the sequence $k, \alpha k, \alpha^2(k), \dots, \alpha^{u-1}(k)$ of elements of a group. This will be studied further in the notion of **orbits**. This decomposition is also unique up to the order of y_{k_i} , and it is called the *standard representation* of α .

Let's try to decompose a permutation using the theorem. Consider

$$\alpha = \begin{pmatrix} 1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 \\ 3 & 5 & 4 & 1 & 8 & 2 & 7 & 6 \end{pmatrix}$$

with $\alpha \in S_8$. The cycle formed by 1 is $\gamma_1 = (134)$. Continuing this, we have the collection $\{(134), (2586), (7)\}$, and the standard representation of α is $(1\ 3\ 4)(2\ 5\ 8\ 6)(7)$

Finally, consider a cycle α of length n , then $\alpha^n = \iota$. Furthermore, for any positive integer d ,

$$\alpha^d = (\gamma_{k_1} \gamma_{k_2} \cdots \gamma_{k_m})^d = \gamma_{k_1}^d \gamma_{k_2}^d \cdots \gamma_{k_m}^d.$$

It follows that if d is the least common multiple of $n_{k_1}, n_{k_2}, \dots, n_{k_m}$, where n_{k_i} is the length of γ_{k_i} , then $\alpha^d = \iota$. The least common multiple is indeed the smallest positive integer with such property.

2.6.2 Sign of Permutations

2.6.3 Conjugacy in S_n and A_n

2.6.4 Simple Groups

Chapter 3

Vectors and Matrices

3.1 Vectors

3.1.1 Vector Algebra in \mathbb{R}^3

Combining two vectors

3.1.2 Vectors in \mathbb{R}^n and \mathbb{C}^n

Let us consider the vector in \mathbb{R}^n , the natural generalisation of \mathbb{R}^3 .

Definition 3.1.1. Using the standard basis e_1, \dots, e_n of \mathbb{R}^n , if $x = \sum_j x_j e_j$ and $y = \sum_j y_j e_j$, we write

$$x \cdot y = \sum_{j=1}^n x_j y_j, \|x\|^2 = x \cdot x = \sum_{j=1}^n x_j^2,$$

and $x \perp y$ when $x \cdot y = 0$.

Note that $\|x\| = \|-x\|$. The distance $\|x - y\|$ between the points x and y is given by the natural extension of Pythagoras' theorem, and importantly, satisfies the *triangle inequality*.

Theorem 3.1 (The triangle inequality for \mathbb{R}^n). For all x, y, z in \mathbb{R}^n ,

$$\|x - y\| \leq \|x - y\| + \|y - z\|. \quad (3.1)$$

To prove this assertion, it is sufficient to show that $|x \cdot y| \leq \|x\|\|y\|$, so that we have $\|x + y\| \leq \|x\| + \|y\|$, which readily implies the triangle inequality. Thus we seek to prove

Theorem 3.2 (the Cauchy-Schwarz inequality). For all $x, y \in \mathbb{R}^n$,

$$|x \cdot y| \leq \|x\|\|y\|. \quad (3.2)$$

The equality holds if and only if $\|x\|y = \pm\|y\|x$, i.e. one vector is a multiple of one another.

Proof. Let $x = (x_1, \dots, x_n)$ and $y = (y_1, \dots, y_n)$. The equation holds true when $x = 0$ and when $y = 0$. So we assume that $\|x\|\|y\| > 0$.

Consider the equation

$$0 \leq \sum_{j=1}^n (\|x\|y_j - \|y\|x_j)^2 = 2\|x\|\|y\| (\|x\|\|y\| - xy),$$

so $x \cdot y \leq \|x\|\|y\|$; similarly, put $-x$ as x and we have $-x \cdot y \leq \|x\|\|y\|$. Therefore $|x \cdot y| \leq \|x\|\|y\|$. Equality holds if $\sum_{j=1}^n (\|x\|y_j - \|y\|x_j)^2$ or $\sum_{j=1}^n (\|x\|y_j + \|y\|x_j)^2$ is equal to zero, which implies $\|x\|y = \pm\|y\|x$. \square

3.1.3 Concepts in linear algebra

3.2 Matrices

Definition 3.2.1. An $n \times m$ matrix is an array of numbers of the form

$$\begin{pmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & a_{22} & \dots & a_{2m} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nm} \end{pmatrix}.$$

Sometimes it will be denoted by (a_{ij}) , where a_{ij} is the general element of the matrix.

Notice that i is the *row* of the element, and j is the *column* of the element.

3.2.1 Algebra of Matrices

3.2.2 Matrix as linear transformation

We start with the definition of linear transformations.

Definition 3.2.2. A map $\alpha: V \rightarrow W$ between vector spaces V and W is *linear* if, for all scalars $\lambda_1, \dots, \lambda_n$, and all vectors v_1, \dots, v_n ,

$$\alpha(\lambda_1 v_1 + \dots + \lambda_n v_n) = \lambda_1 \alpha(v_1) + \dots + \lambda_n \alpha(v_n).$$

If α is linear we say that it is a *linear transformation*, or a *linear map*, if for all scalars λ and all vectors u and v , $\alpha(\lambda x) = \lambda \alpha(x)$ and $\alpha(x + y) = \alpha(x) + \alpha(y)$.

The two definitions are equivalent.

Theorem 3.3 (Rank-nullity theorem). content...

3.3 Eigenvalues and Eigenvectors

Chapter 4

Differential Equations

4.1 Basic Calculus

4.2 First-order Linear Differential Equations

4.2.1 Equations with constant coefficients

4.2.2 Equations with non-constant coefficients

4.3 Nonlinear first-order equations

4.4 Higher-order Linear Differential Equations

4.5 Multivariate Functions

Chapter 5

Analysis I

A rigorous theory of mathematical analysis must take an axiomatic approach as its foundation. Thus it is preferable to start from the construction of real numbers, and then discover their properties, as not to take them for granted. This foundational rigour is, fortunately, available for us by Dedekind and his model for the real number.

What are the essential properties of \mathbb{R} ? We have learnt that \mathbb{R} is a field, with the usual addition and multiplication; the usual subtraction and division is also possible.

Secondly, there is a *total order* on \mathbb{R} , that is, if $x, y \in \mathbb{R}$ then either $x \leq y$ or $y \leq x$, and only $x = y$ when both condition are satisfied. Furthermore, if $x \leq y$ and $y \leq z$ then $x \leq z$. This means \mathbb{R} is an *ordered field* and that is, if $x \leq y$ then $x + z \leq y + z$, and if $w \geq 0$ then $xw \leq yw$.

Of course, \mathbb{Q} is also an ordered field, but it is not *complete*. This is the most important property of \mathbb{R} to keep in mind. Let's start by a notion of an *upper bound*. If A is a non-empty subset of \mathbb{R} and $b \in \mathbb{R}$, then b is an upper bound for A if $b \geq a$ for all $a \in A$. By saying that \mathbb{R} is complete, this means that, if A is a non-empty set of \mathbb{R} with an upper bound, then A has a *least upper bound*, or *supremum* $\sup A$. This translates to, for any upper bound b of a set $A \subset \mathbb{R}$, should it exist, we have $\sup A \leq b$.

Another central theme of analysis regards *absolute value*, that is the function

$$|x| = \begin{cases} x & \text{if } x \geq 0 \\ 0 & \text{if } x = 0 \\ -x & \text{if } x \leq 0 \end{cases} . \quad (5.1)$$

Note that $|x - y| = |y - x|$ and $|x| \geq 0$ for all $x \in \mathbb{R}$.

Theorem 5.1. For all $x, y \in \mathbb{R}$, $|x + y| \leq |x| + |y|$, with equality when $xy \geq 0$.

Proof. Trivial proof by case. □

Theorem 5.2. (Triangle Inequality) For all $x, y, z \in \mathbb{R}$, we have

$$|x - z| \leq |x - y| + |y - z|. \quad (5.2)$$

Proof. Simply substitute $x - y$ and $y - z$ in place of x and y , respectively. □

5.1 Limit and Convergences

5.1.1 Series and sequences in \mathbb{R} and \mathbb{C}

Definition 5.1.1. A sequence s_n is a *null sequence* if, to every positive number ϵ , there corresponds an integer N such that

$$|s_n| < \epsilon \text{ for all values of } n \text{ greater than } N.$$

We can adapt the definition to any sequence whose terms approach any number s .

Definition 5.1.2. A sequence s_n is said to tend to the limit s if, given any positive number ϵ , there is an integer N (depending on ϵ) such that

$$|s_n - s| < \epsilon \text{ for all } n > N.$$

We then write $\lim s_n = s$.

A more clear notation $\lim_{n \rightarrow \infty} s_n = s$ can be given.

Note. 1. Clearly, $\lim s_n = s$ if and only if $s_n - s$ is a null sequence.

2. The inequality $|s_n - s| < \epsilon$ is equivalent to the two inequalities

$$s - \epsilon < s_n < s + \epsilon.$$

This is clear that s_n is bounded.

3. A short notation $s_n \rightarrow s$ stands for $\lim s_n = s$. A further symbolism for the above definition may be given:

$$s_n \rightarrow s \text{ if } \epsilon > 0; \quad \exists N. |s_n - s| < \epsilon \text{ for all } n > N.$$

If limits exist, they are unique.

Theorem 5.3. If $a_n \rightarrow s$ as $n \rightarrow \infty$ and $a_n \rightarrow l$ as $n \rightarrow \infty$, then $s = l$.

Proof. We will prove this theorem by contradiction. Suppose $s \neq l$. Let $\epsilon = |s - l|/3 > 0$. There exists n_0 such that $|a_n - s| < \epsilon$ for $n \geq n_0$, and there exists m_0 such that $|a_n - l| < \epsilon$ for $n \geq m_0$. Let $N = \max(n_0, m_0)$. Then if $n \geq N$,

$$|l - s| \leq |a_n - l| + |a_n - s| < 2\epsilon = 2|l - s|/3,$$

a contradiction. □

We have discussed on upper bound and lower bound of a set, it is time to introduce a notion of *boundedness*, and expand it to those of sequences in general.

Definition 5.1.3. A subset A of \mathbb{R} is *bounded* if it is bounded above and bounded below. A sequence s_n is bounded if the set $\{s_n : n \in \mathbb{Z}^+\}$ is bounded.

Theorem 5.4. If a sequence tends to a limit, then it is bounded.

Proof. Let the sequence a_n tends to the limit l . We choose an arbitrary ϵ so that for any $n \geq n_0$ the difference $|a_n - l|$ is less than ϵ .

Let $\epsilon = 1$, so that $|a_n - l| < 1$ for all $n \geq n_0$. Choose

$$M = \max\{|a_1|, |a_2|, \dots, |a_{n_0}|, |l| + 1\}.$$

Then for all $n \geq n_0$ $|a_n| \leq |a_n - l| + |l| < 1 + |l|$. Clearly, $|a_n| \leq M$ and we are set. \square

Note that the converse of the theorem might not be true; if a sequence is bounded, then it *might not* tends to a limit. Consider the sequence $a_n = \cos n\pi$. It is bounded, but a_n does not tend to a limit.

Theorem 5.5. Suppose that a_n is an increasing sequence of real numbers. If it is bounded then $a_n \rightarrow \sup\{a_n : n \in \mathbb{Z}^+\}$ as $n \rightarrow \infty$; otherwise $a_n \rightarrow +\infty$.

Similarly, for any decreasing sequence a_n ; and if it is bounded, then $a_n \rightarrow \inf\{a_n : n \in \mathbb{Z}^+\}$; otherwise $a_n \rightarrow -\infty$.

One sequence worth considering is the sequence $a_n = r^n$. The convergence of the sequence depends on the value of r .

1. If $r = 1$ then $a_n \rightarrow 1$, and if $r = 0$ then $a_n \rightarrow 0$.
2. If $r > 1$ then $r = 1 + k$ for some $k > 0$, so we have

$$a_n = (1 + k)^n > 1 + kn$$

by considering the first two terms in the binomial expansion. And so $a_n \rightarrow +\infty$.

5.1.2 Sums, products and quotients

Theorem 5.6. If s_n and t_n are null sequences, so is $s_n + t_n$.

Theorem 5.7. If s_n is a null sequence and t_n is a bounded sequence, then $s_n t_n$ is a null sequence.

Corollary 5.1.1. If s_n is a null sequence and c is a constant, then cs_n is a null sequence.

We then now extend the results to general sequences.

Theorem 5.8. If $s_n \rightarrow s$ and $t_n \rightarrow t$, then

1. $s_n + t_n \rightarrow s + t$,
2. $s_n t_n \rightarrow st$.

Theorem 5.9. If $s_n \rightarrow s$ and $t_n \rightarrow t$ with $t \neq 0$, then

$$\frac{s_n}{t_n} \rightarrow \frac{s}{t}$$

Theorem 5.10. If $s_n \rightarrow s$ and $t_n \rightarrow t$ and $s_n \leq b_n$ for all n , then $s \leq b$.

Theorem 5.11. If $s_n \rightarrow s$ and s_{n_k} is a subsequence, then $s_{n_k} \rightarrow s$.

5.1.3 Absolute convergence

5.1.4 Bolzano-Weierstrass theorem

Theorem 5.12. (Bolzano-Weierstrass theorem) Suppose that a_n is a bounded sequence of real numbers. There there is a subsequence a_{n_k} which converges.

5.1.5 Comparison and ratio test

5.1.6 Alternating series test

5.2 Continuity

5.2.1 Continuity of real and complex function

5.2.2 The intermediate value theorem

5.3 Differentiability

5.3.1 Differentiability of functions from \mathbb{R} to \mathbb{R}

5.3.2 Derivative of sums and products

5.4 Power series

Definition 5.4.1. An infinite series of the form

$$\sum_{n=0}^{\infty} a_n z^n = a_0 + a_1 z + a_2 z^2 + \cdots$$

composed of multiples of powers of z is called a *power series*. Both the variable z and the coefficients a_n might be real or complex.

There are three possibilities with convergence of a power series.

1. The series converges for all $z \in \mathbb{C}$.

5.5 Integration

5.5.1 Integrability of monotonic functions

Chapter 6

Probability

6.1 Basic concepts

6.2 Axiomatic approach

6.3 Discrete random variables

6.4 Continuous random variables

6.5 Inequalities and limits

6.5.1 Markov's and Chebyshev's inequality

6.5.2 Weak law of large numbers

6.5.3 Convexity and Jensen's inequality

6.5.4 AM-GM inequality

Chapter 7

Vector Calculus

7.1 Curves in \mathbb{R}^3

Part II

Part IB

Chapter 8

Linear Algebra

8.1 Vector Spaces

8.2 Linear maps

8.3 Determinant

8.4 Eigenvalues and Eigenvectors

8.5 Duals

8.6 Bilinear Forms

8.7 Inner Product Spaces

Chapter 9

Groups, Rings and Modules

9.1 Groups

We have gone into details of groups in Part IA.

9.1.1 Basics concepts

9.1.2 Normal subgroups

9.1.3 Sylow subgroups and Sylow theorems

9.2 Rings

9.2.1 Definition

Rings are abstraction of systems with addition and multiplication. The prototype of rings are the set \mathbb{Z} of integers.

We define the general notion of ring in a similar way. We say that a set R with two operations, addition and multiplication, denoted $x + y$ and $x \cdot y$, respectively. We write $x \cdot y$ as xy for comprehensiveness.

Definition 9.2.1. A set R is a ring if the following properties are satisfied:

1. R forms an abelian group under addition.
2. R forms a monoid under multiplication.
3. The distributive laws hold true, i.e.

$$x(y + z) = xy + xz, (y + z)x = yx + zx.$$

9.2.2 Ideals**9.2.3 Fields****9.2.4 Factorisation in rings****9.2.5 Rings $\mathbb{Z}[a]$ of algebraic integers****9.3 Modules****9.3.1 Definition****9.3.2 Submodules****9.3.3 Equivalence of matrices****9.3.4 Finitely generated modules over Euclidean domains**

Chapter 10

Analysis II

10.1 Uniform Convergence

10.2 Uniform Continuity and Integration

10.3 \mathbb{R}^n as a Normed Space

10.4 Differentiation from \mathbb{R}^m to \mathbb{R}^n

10.5 Metric Spaces

10.6 The Contraction Mapping Theorem

Chapter 11

Metric and Topological Spaces

11.1 Metrics

11.1.1 Definition and examples

11.1.2 Limits and continuity

11.1.3 Open sets and neighbourhoods

11.1.4 Characterising limits and continuity

11.2 Topology

11.2.1 Metric topologies

11.3 Connectedness

11.4 Compactness

Chapter 12

Complex Analysis

12.1 Analytic Functions

12.2 Contour Integration and Cauchy's Theorem

12.3 Expansions and Singularities

12.4 The Residue Theorem

Chapter 13

Complex Methods

13.1 Analytic Functions

13.2 Contour Integration and Cauchy's Theorem

13.3 Residue Calculus

13.4 Fourier and Laplace Transforms

Chapter 14

Geometry

Part III

Part II

Chapter 15

Number Theory

15.1 Basics

15.2 Chinese Remainder Theorem

15.3 Law of Quadratic Reciprocity

15.4 Binary Quadratic Forms

15.5 Distribution of the Primes

15.6 Continued fractions and Pell's equation

15.7 Primality testing

15.8 Factorisation

Chapter 16

Topics in Analysis

Chapter 17

Coding and Cryptography

Chapter 18

Automata and Formal Languages

18.1 Register machines

18.2 Regular languages and finite-state automata

18.3 Pushdown automata and context-free languages

Chapter 19

Logic and Set Theory

19.1 Ordinals and Cardinals

19.1.1 Well-orderings and order-types

19.2 Posets and Zorn's Lemma

19.3 Propositional Logic

19.4 Predicate Logic

19.5 Set Theory

19.6 Consistency

Chapter 20

Graph Theory

20.1 Introduction

20.2 Connectivity and matchings

20.3 Extremal graph theory

20.4 Eigenvalue methods

20.5 Graph colouring

20.6 Ramsey theory

20.7 Probabilistic methods

Chapter 21

Galois Theory

21.1 Fields extensions

Chapter 22

Representation Theory

22.1 Representations of Finite Groups

22.1.1 Representations on vector spaces

22.2 Character Theory

22.3 Arithmetic Properties of Characters

22.4 Tensor Products

22.5 Representations of S^1 and SU_2

22.6 Further Worked Examples

Chapter 23

Number Fields

23.1 Algebraic Number Fields

23.2 Ideals

23.3 Units

23.4 Ideal classes

23.5 Dedekind's theorem on the factorisation of primes

Chapter 24

Algebraic Topology

24.1 The Fundamental Group

24.2 Covering Spaces

24.3 The Seifert-Van Kampen Theorem

24.4 Simplicial Complexes

24.5 Homology

24.6 Homology Calculations

Chapter 25

Linear Analysis

Chapter 26

Analysis of Functions

Chapter 27

Riemann Surfaces

Chapter 28

Algebraic Geometry

Chapter 29

Differential Geometry

Chapter 30

Probability and Measure

Index

Fixed point, 12

Group, 5

Symmetric group, 6