CSE 221 Algorithms: Ch2

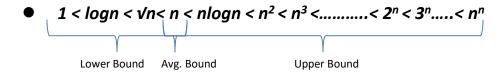
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Asymptotic Notations

O-notation:

When we have only an *asymptotic upper bound*, we use O-notation. For a given function g(n), we denote by O(g(n)) (pronounced "big-oh of g of n" or sometimes just "oh of g of n") the set of functions

 $O(g(n)) = \{ f(n) : \text{ there exist positive constants } c \text{ and } n_0 \text{ such that } 0 \le f(n) \le c * g(n) \} \text{ for all } n \ge n_0 \}$



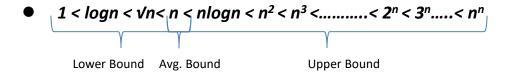
• Example:

$$f(n) = 2n+3$$
 [$f(n) = O(n)$]
 $2n+3 <= 2n^2+3n^2$
 $2n+3 <= 5n^2$ [$n>=1$]
 $f(n) = O(n^2)$

Asymptotic Notations Cont.

Ω-notation:

When we have only an **asymptotic lower bound**, we use Ω -notation. For a given function g(n), we denote by $\Omega(g(n))$ (pronounced "big omega of g of n" or sometimes just "omega of g of n") the set of functions $\Omega(g(n)) = \{ f(n) : \text{ there exist positive constants } c \text{ and } n_0 \text{ such that } 0 \le c*g(n) \} \le f(n) \text{ for all } n \ge n_0 \}$



• Example:

$$f(n) = 2n+3 \dots [f(n) = \Omega(n)]$$

$$2n+3 \ge 1*logn \dots [for all n \ge 1]$$

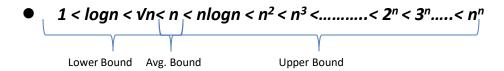
$$f(n) c g(n)$$

$$f(n) = \Omega(logn)$$

Asymptotic Notations Cont.

Θ Notation:

When we have only an *asymptotic average bound*, we use Θ -notation. For a given function g(n), we denote by $\Theta(g(n))$ (pronounced "big theta of g of n" or sometimes just "theta of g of n") the set of functions $\Theta(g(n)) = \{ f(n) : \text{there exist positive constants } c1, c2 \text{ and } n_0 \text{ such that } 0 \le c1 * g(n) \} \le f(n) \le c2 * g(n) \}$ for all $n \ge n_0 \}$



- c1*g(n) <= f(n) <= c2*g(n)
- Example:

$$f(n) = 2n+3$$

 $1*n <= 2n+3 <= 5*n$
 $f(n) = \Theta(n)$

Properties of Asymptotic Function

General Properties:

Properties of Asymptotic Notations

General Properties

if
$$f(n)$$
 is $O(g(n))$ then $a*f(n)$ is $O(g(n))$

eg: $f(n) = 2n^2 + 5$ is $O(n^2)$

then $7 \cdot f(n) = 7(2n^2 + 5)$
 $= 14(n^2 + 35)$ is $O(n^2)$

Properties of Asymptotic Function Cont.

Reflexive

Reflexive

if
$$f(n)$$
 is given then $f(n) = O(f(n))$

eg: $f(n) = n^2 O(n^2)$

Transitive

Transitive

if
$$f(n)$$
 is $O(g(n))$ and $g(n)$ is $O(h(n))$

then $f(n) = O(h(n))$

eg: $f(n) = n$ $g(n) = n^2$ $h(n) = n^3$
 $n = 0$ $n^2 = 0$ n

Properties of Asymptotic Function Cont.

Symmetric

Symmetric

if
$$f(n)$$
 is $O(g(n))$ the $g(n)$ is $O(f(n))$

eg: $f(n) = n^2$ $g(n) = n^2$
 $f(n) = O(n^2)$
 $g(n) = O(n^2)$

Transpose Symmetric

Transpose Symmétric

if
$$f(n) = O(g(n))$$
 then $g(n)$ is $\Omega(f(n))$

eq: $f(n) = n$ $g(n) = n^2$

then $n = 0$ is $\Omega(n^2)$ and n^2 is $\Omega(n)$

Properties of Asymptotic Function Cont.

Example:

if
$$f(n) = O(g(n))$$

and $f(n) = \Omega(g(n))$
 $g(n) \le -f(n) \le g'(n)$
 $f(n) = O(g(n))$

Comparison of functions(Time/Space)

- First Method
 - Smaller/Greater/Equal

n	n^2 <	γ^3
2	2=4	23=8
3	3=9	3=27
4	4=16	43=64

- Second Method
 - Using logarithm

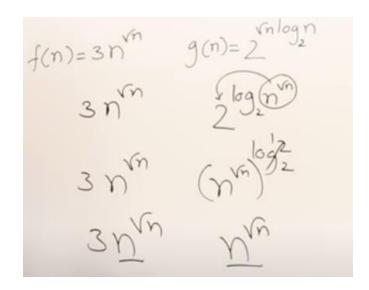
Comparison of functions(Time/Space) Cont.

• Logarithm Laws : $a^{\log_c b} = b^{\log_c a}$

Logarithmic laws				
Products:	log _b mn =	log _b m + log _b n		
Ratios:	$\log_b \frac{m}{n} =$	$\log_b m - \log_b n$		
Powers:	$log_b n^p =$	$p \log_b n$		
Roots:	$\log_b \sqrt[q]{n} =$	$= \frac{1}{q} \log_b n$		
Change of bases:	log _b n =	log _a n log _b a		

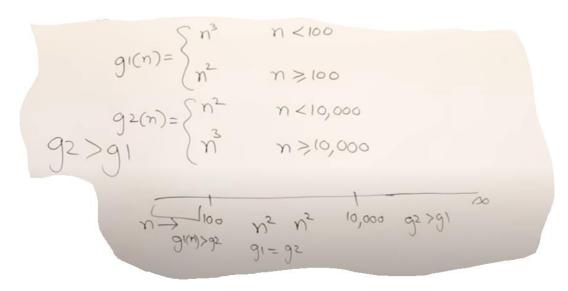
Exponent and Logarithm Rules $(a > 0, a \neq 1)$				
	Exponent	Logarithm $(m, n > 0)$		
Product Rule	$a^m \cdot a^n = a^{m+n}$	$\log_a(m \cdot n) = \log_a m + \log_a n$		
Quotient Rule	$\frac{a^m}{a^n} = a^{m-n}$	$\log_a\left(\frac{m}{n}\right) = \log_a m - \log_a n$		
Power Rule	$(a^m)^n = a^{m \cdot n}$	$\log_a(m^n) = n \cdot \log_a m$		

Examples:



Comparison of functions(Time/Space) Cont.

 g2(n) is going to be always greater than g1(n) because of the last condition of n value.



• Find out the True/False.

True on False

1.
$$(n+k)^m = O(n^m)$$

2. $2^{n+1} = O(2^n)$

3. $2^n = O(2^n)$

4. $\sqrt{\log n} = O(\log \log n)$

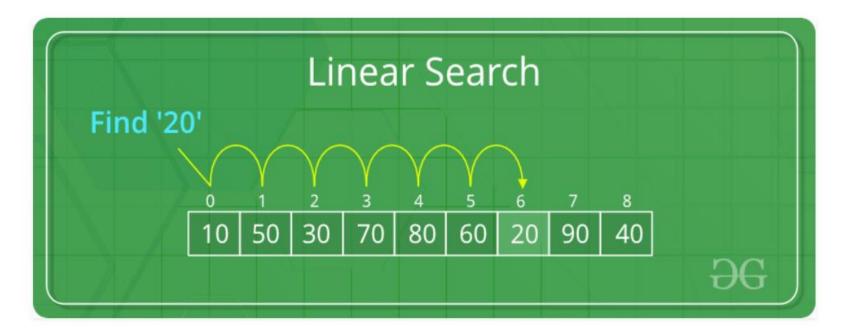
5. $n^{\log n} = O(2^n)$

Best, Worst & Average Case

- Linear Search
- Binary Search Tree

Linear Search

- A simple approach to do a linear search is, i.e.
 - Start from the leftmost element of arr[] and one by one compare x(key element) with each element of arr[]
 - If x matches with an element, return the index.
 - If x doesn't match with any of elements, return -1.
- Example:



Linear Search Cont.

- Best Case: Searching key element present at first index.
 - Best Case Time: will be constant. B(n) = O(1)
- Worst Case: Searching key element present at last index.
 - Worst Case Time: will be n. W(n) = O(n)
- Average Case: (All possible case time/number of cases). Rarely being used.
 - Average Case Time: (1+2+3+....+n)/n = (n(n+1)/2)/n = (n+1)/2. A(n) = (n+1)/2

Linear Search Cont.

Asymptotic Notations:

$$B(n) = 1$$

 $B(n) = O(1)$
 $B(n) = S2(1)$
 $B(n) = O(1)$

$$\omega(n) = n$$

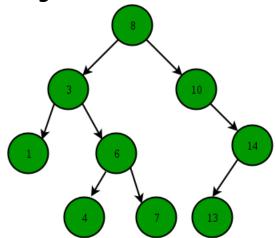
$$\omega(n) = O(n)$$

$$\omega(n) = \Omega(n)$$

$$\omega(n) = O(n)$$

Binary Search Tree

- Binary Search Tree is a node-based binary tree data structure which has the following properties:
 - The left subtree of a node contains only nodes with keys lesser than the node's key.
 - The right subtree of a node contains only nodes with keys greater than the node's key.
 - The left and right subtree each must also be a binary search tree.
 - Height of the tree is h = logn.



Binary Search Tree Cont.

- Best Case: Searching for the root element.
 - Best Case Time: will be constant. B(n) = O(1)
- Worst Case: Searching for element present at the leaf.
 - Worst Case Time: Depends on the height of the Binary Search Tree. So,
 W(n) = h.
- We can apply the same asymptotic notations here like Linear Search.

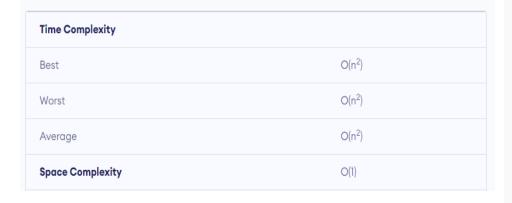
Sorting: Bubble Sort, Insertion Sort, Selection Sort

- Selection sort: repeatedly pick the smallest element to append to the result.
 - Divides the array into two parts: sorted (left) and unsorted (right) subarray.
 - Selects the smallest element from unsorted subarray and places in the first position of that subarray (ascending order). Search and swap.

```
SelectionSort (Arr, N) // Arr is an array of size N.
{
    For ( I:= 1 to (N-1) ) // N elements \Rightarrow (N-1) pass
    // I=N is ignored, Arr[N] is already at proper place.
    // Arr[1:(I-1)] is sorted subarray, Arr[I:N] is undorted subarray
    // smallest among { Arr[I], Arr[I+1], Arr[I+2], ..., Arr[N] } is at place min index
        min_index = I;
        For ( J:= I+1 to N ) // Search Unsorted Subarray (Right lalf)
            If ( Arr [J] < Arr[min index] )</pre>
                min index = J; // Current minimum
        // Swap I-th smallest element with current I-th place element
        If (min Index != I)
              Swap ( Arr[I], Arr[min_index] );
```

Selection Sort (Example)

• Selection sort is an in-place algorithm. It performs all computation in the original array and no other array is used. Hence, the space complexity works out to be O(1).



```
arr[] = 64 25 12 22 11
// Find the minimum element in arr[0...4]
// and place it at beginning
11 25 12 22 64
// Find the minimum element in arr[1...4]
// and place it at beginning of arr[1...4]
11 12 25 22 64
// Find the minimum element in arr[2...4]
// and place it at beginning of arr[2...4]
11 12 22 25 64
// Find the minimum element in arr[3...4]
// and place it at beginning of arr[3...4]
11 12 22 25 64
```

Sorting:Cont.

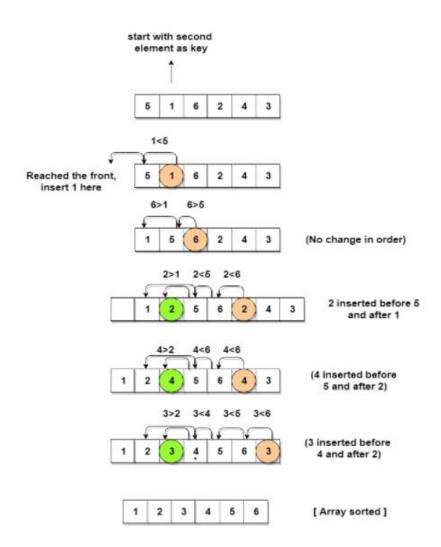
- Insertion sort: repeatedly add new element to the sorted result. Shifting and sorting
 - Take the first element as a sorted sub-array.
 - Insert the second element into the sorted sub-array (shift elements if needed).
 - Insert the third element into the sorted sub-array.
 - Repeat until all elements are inserted.

```
InsertionSort (Arr, N) // Arr is an array of size N.
{
    For (I:= 2 \text{ to } N) // N \text{ elements} \Rightarrow (N-1) \text{ pass}
    // Pass 1 is trivially sorted, hence not considered
    // Subarray { Arr[1], Arr[2], ..., Arr[I-I] } is already sorted
        insert at = I; // Find suitable position insert at, for Arr[I]
        // Move subarray Arr [ insert at: I-1 ] to one position right
        item = Arr[I]; J=I-1;
        While ( J ? 1 && item < Arr[J] )
        {
                 Arr[J+1] = Arr[J]; // Move to right
                 // insert_at = J;
                 J--;
            }
            insert at = J+1; // Insert at proper position
            Arr[insert at] = item; // Arr[J+1] = item;
        }
    }
```

Insertion sort(example)

- Insertion sort is an in-place algorithm. It performs all computation in the original array and no other array is used. Hence, the space complexity works out to be O(1).
- The Best Case Time Complexity will be O(n) instead of $O(n^2)$

Time Complexity	
Best	$O(n^2)$
Worst	$O(n^2)$
Average	O(n²)
Space Complexity	O(1)



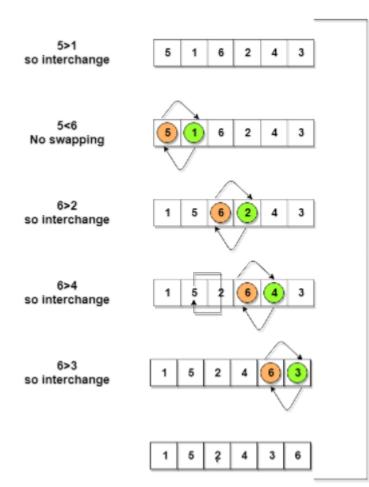
Sorting:Cont.

• **Bubble sort**: repeatedly compare neighbor pairs and swap if necessary.

```
BubbleSort (Arr, N) // Arr is an array of size N.
{
    For ( I:= 1 to (N-1) ) // N elements \Rightarrow (N-1) pass
    // Swap adjacent elements of Arr[1:(N-I)]such that
    // largest among { Arr[1], Arr[2], ..., Arr[N-I] } reaches to Arr[N-I]
        noSwap = true; // Check occurrence of swapping in inner loop
        For ( J:= 1 to (N-I) ) // Execute the pass
        {
            If (Arr [J] > Arr[J+1])
                Swap( Arr[j], Arr[J+1] );
                noSwap = false;
            }
        If (noSwap) // exit the loop
            break;
```

Bubble sort(example)

Time Complexity	
Best	O(n)
Worst	O(n ²)
Average	O(n ²)
Space Complexity	O(1)



This is first insertion

similarly, after all the iterations, the array gets sorted