CSE 221 Algorithms: Ch4

Instructor: Saraf Anika

CSE, SoSET, EDU Summer 2021

Greedy Method

What is a 'Greedy Algorithm'?

A greedy algorithm, as the name suggests, always makes the choice that seems to be the best at that moment. This means that it makes a locally-optimal choice in the hope that this choice will lead to a globally-optimal solution.

How do you decide which choice is optimal?

Assume that you have an objective function that needs to be optimized (either maximized or minimized) at a given point. A Greedy algorithm makes greedy choices at each step to ensure that the objective function is optimized. The Greedy algorithm has only one shot to compute the optimal solution so that it never goes back and reverses the decision.

Greedy Method Cont.

Components of Greedy Algorithm

Greedy algorithms have the following five components -

- A candidate set A solution is created from this set.
- → A selection function Used to choose the best candidate to be added to the solution.
- → A feasibility function Used to determine whether a candidate can be used to contribute to the solution.

minimum Cos

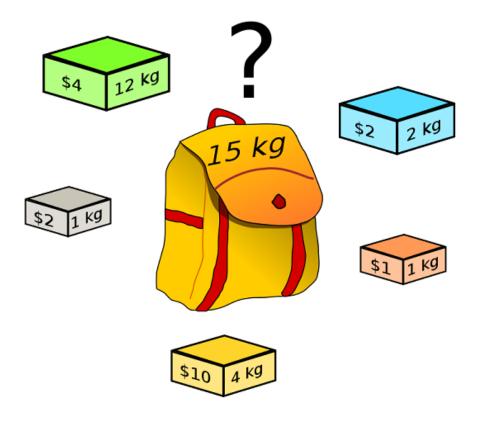
- → An objective function Used to assign a value to a solution or a partial solution.
- → A solution function Used to indicate whether a complete solution has been reached.

Greedy Method Cont.

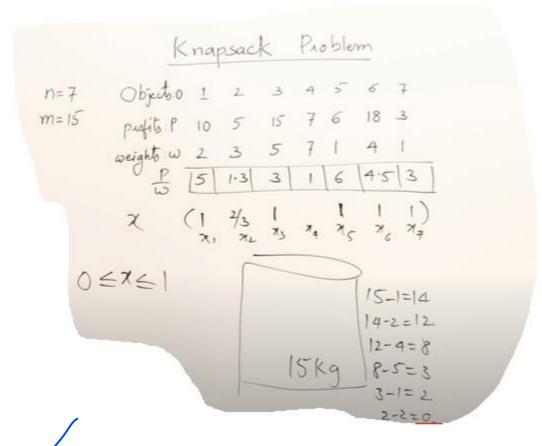
```
11=5
Feasible(x) Then
Solution = Solution + x;
```

Knapsack Problem

Given a Knapsack of a maximum capacity of W and N items each with its own value and weight, throw in items inside the Knapsack such that the final contents has the maximum value. Yikes !!



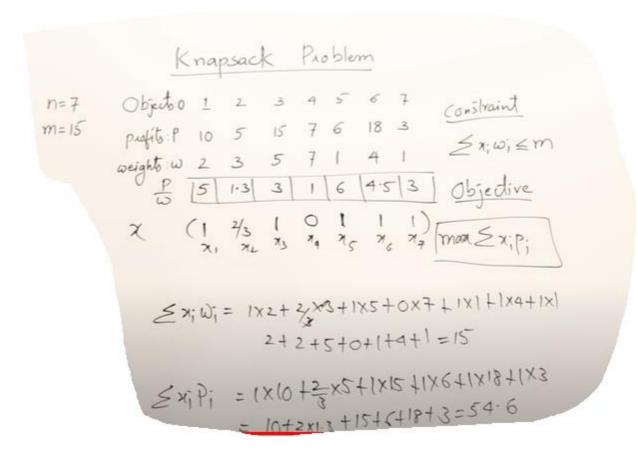
Knapsack Problem



P/W high to low calculate. That means sorted value. I choose = object 5, 1, 4.5, 3, 7, 2. (set by the P/W) Then,

15 - (P/W is weight) = ans

.....

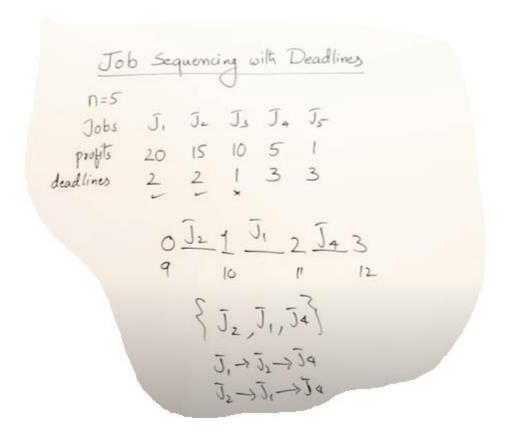


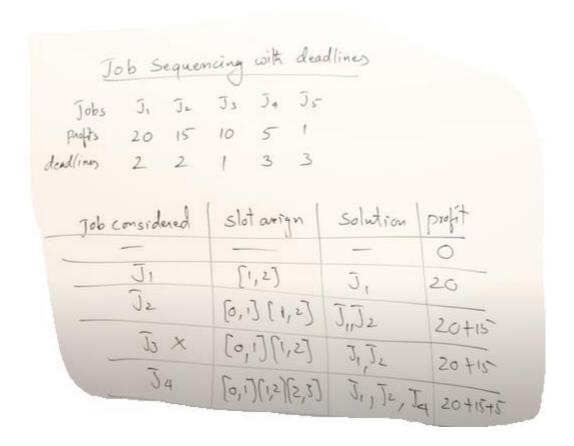
Job Sequencing with Deadlines

- The sequencing of jobs on a single processor with deadline constraints is called as Job Sequencing with Deadlines.
- Here-
 - You are given a set of jobs.
 - Each job has a defined deadline and some profit associated with it.
 - The profit of a job is given only when that job is completed within its deadline.
 - Only one processor is available for processing all the jobs.
 - Processor takes one unit of time to complete a job.
- Greedy Algorithm is adopted to determine how the next job is selected for an optimal solution.

Job Sequencing with Deadlines

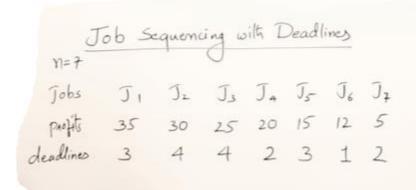
Example 1:





Job Sequencing with Deadlines

DIY: Practice



Job Sequencing with Deadlines

YI=7

Jobs J1 J2 J3 J4 J5 J6 J4

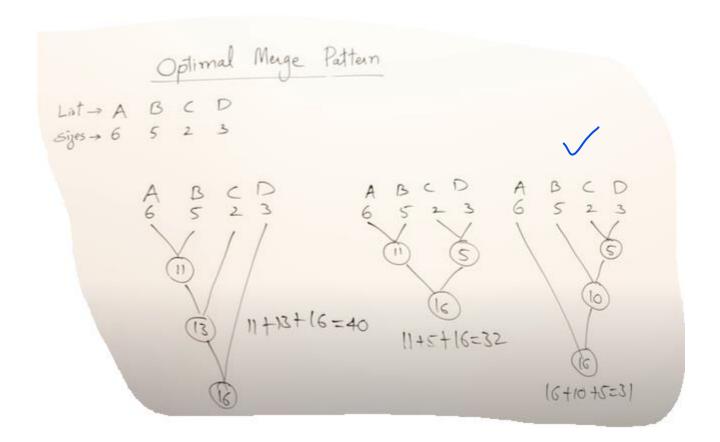
profits 35 30 25 20 15 12 5

deadlines 3 4 4 2 3 1 2

$$0\overline{)}4 1\overline{)}3 2\overline{)}1 3\overline{)}2 4$$

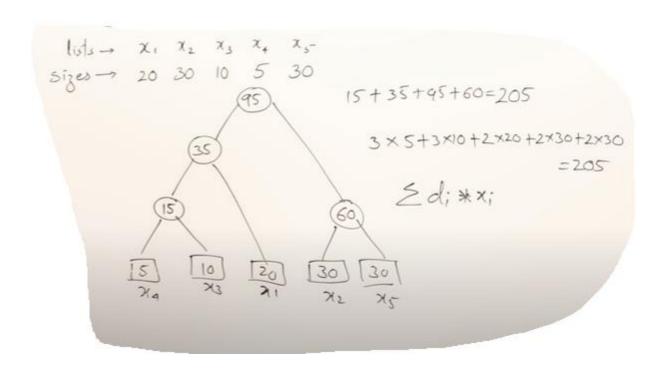
20 25 35 30 = 110

Optimal Merge Pattern



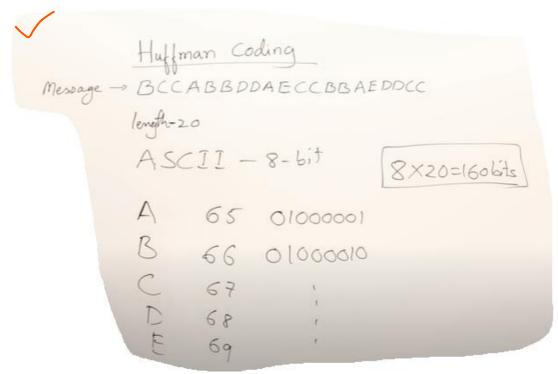
A	B	<u>C</u>
3	5	3
8	9	5
12	11,	8
- 20	16.	9
		12
		20

Optimal Merge Pattern



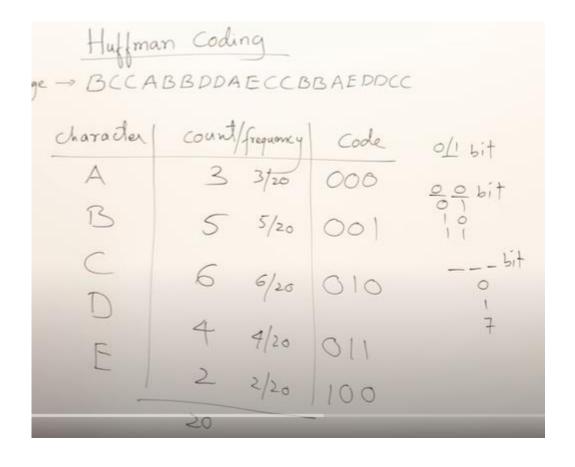
Huffman Coding

- Huffman Coding is a technique of compressing data to reduce its size without losing any of the details. It was first developed by David Huffman.
- Huffman Coding is generally useful to compress the data in which there are frequently occurring characters.
- The most frequent character gets the smallest code and the least frequent character gets the largest code.



Huffman Coding Cont.

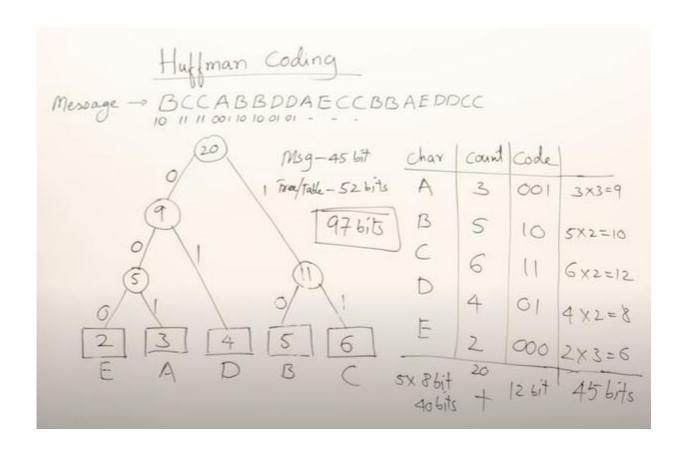
For Fixed Sized Codes: (Method 1)

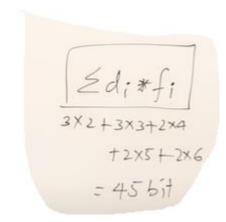


Huffman Coding → BCCABBDDAECCBBAEDDCC OOI 010						
charader	count	frequency	Code	20×3=606ts		
A	3	3/20	000	sxabit sxa		
B		5/20		Thereader codes		
		6/20	010	40 115=55		
E	4	4/20	011	Msg - 60 bits Table - 55 bits 115 bits		
	2	2/20	100	lable _ 55 612 115 6Hs		

Huffman Coding Cont.

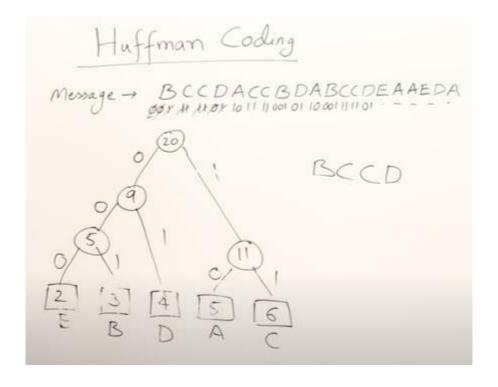
- For Variable Sized Codes: (Method 2)
- From Root to Leaf





Huffman Decoding

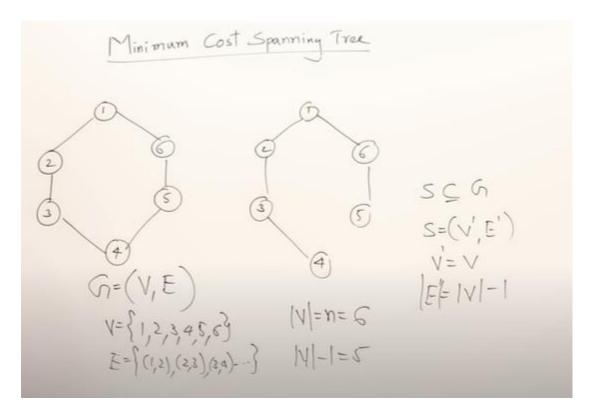
From root to leaf

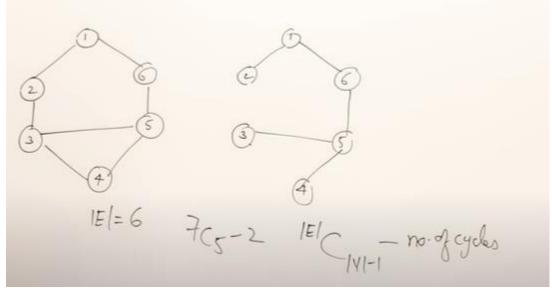


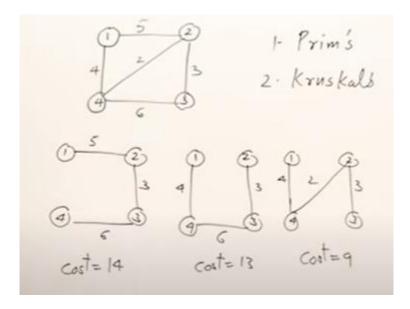
Minimum Spanning Tree

- Given an undirected and connected graph G=(V,E), a spanning tree of the graph G is a tree that spans G (that is, it includes every vertex of G) and is a sub-graph of G (every edge in the tree belongs to G)
- The cost of the spanning tree is the sum of the weights of all the edges in the tree.
- Minimum spanning tree is the spanning tree where the cost is minimum among all the spanning trees.
- There are two famous algorithms for finding the Minimum Spanning Tree:
 - Prim's Algorithm
 - Kruskal's Algorithm

Minimum Spanning Tree







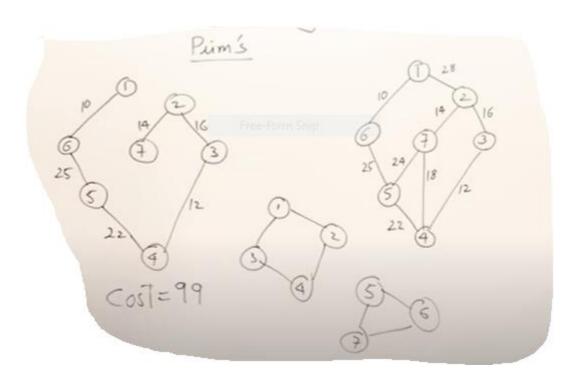
Prim's Algorithm

• It falls under a class of algorithms called Greedy Algorithms that find the local optimum in the hopes of finding a global optimum.

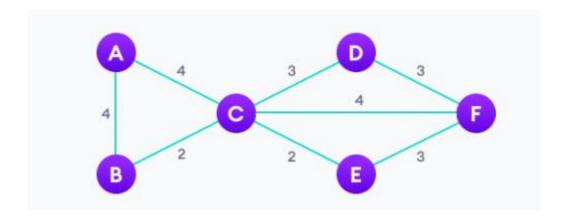
 We start from one vertex and keep adding edges with the lowest weight until we reach our goal.

- The steps for implementing Prim's algorithm are as follows:
 - Initialize the minimum spanning tree with a vertex chosen at random.
 - Find all the edges that connect the tree to new vertices, find the minimum and add it to the tree
 - Keep repeating step 2 until we get a minimum spanning tree

Prim's Algorithm



DIY:

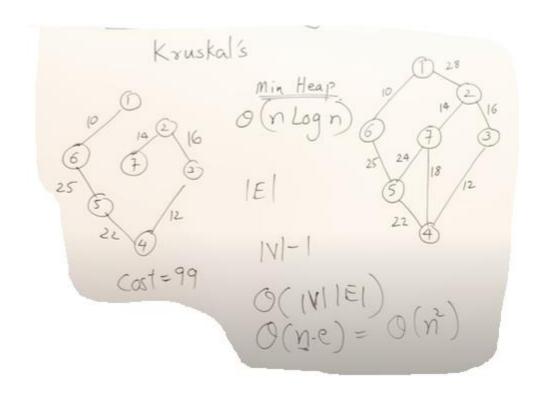


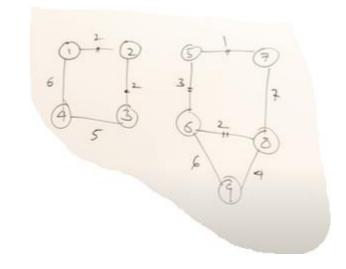
Cost = 14

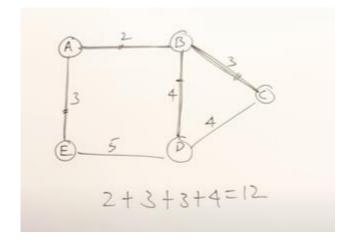
Kruskal's Algorithm

- It falls under a class of algorithms called Greedy Algorithm that find the local optimum in the hopes of finding a global optimum.
- We start from the edges with the lowest weight and keep adding edges until we reach our goal.
- The steps for implementing Kruskal's algorithm are as follows:
 - Sort all the edges from low weight to high
 - Take the edge with the lowest weight and add it to the spanning tree. If adding the edge created a cycle, then reject this edge.
 - Keep adding edges until we reach all vertices.

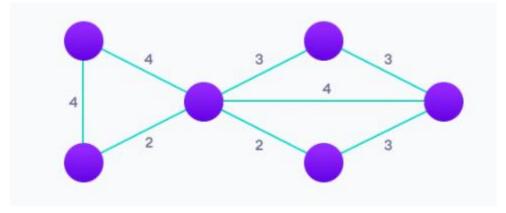
Kruskal's Algorithm



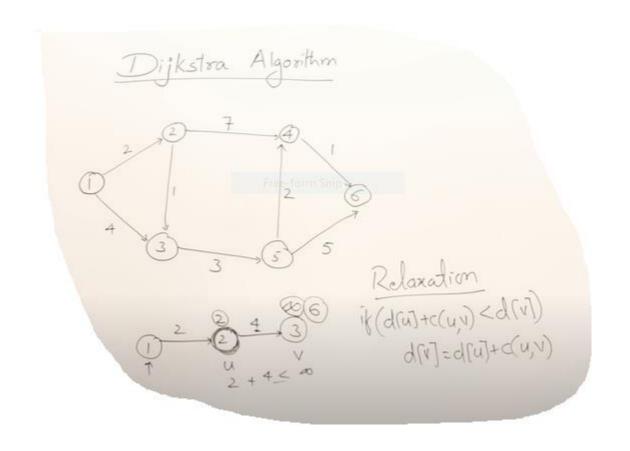


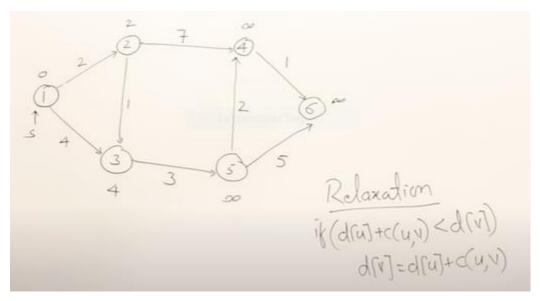


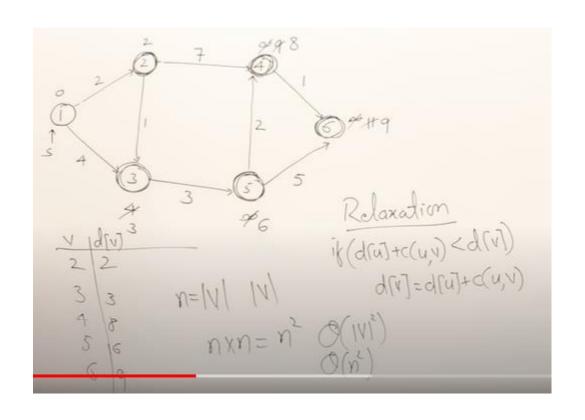
DIY:

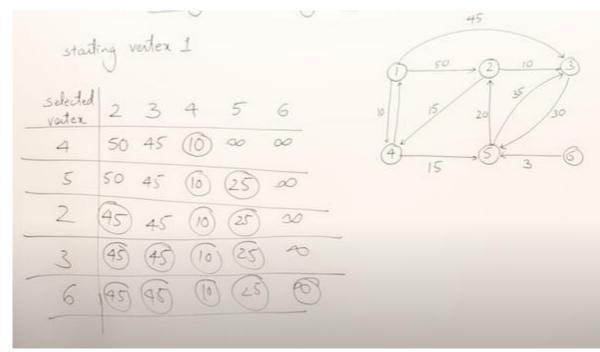


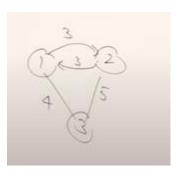
- It is a greedy algorithm that solves the single-source shortest path problem for a directed graph G = (V, E) with nonnegative edge weights, i.e., $w(u, v) \ge 0$ for each edge $(u, v) \in E$.
- Dijkstra's Algorithm maintains a set S of vertices whose final shortest path weights from the source s have already been determined. That's for all vertices $v \in S$; we have $d[v] = \delta(s, v)$. The algorithm repeatedly selects the vertex $u \in V$ S with the minimum shortest path estimate, insert u into S and relaxes all edges leaving u.











Disadvantage:

