

COMPUTER GRAPHICS LECTURE-3 (SCAN CONVERSION-1)

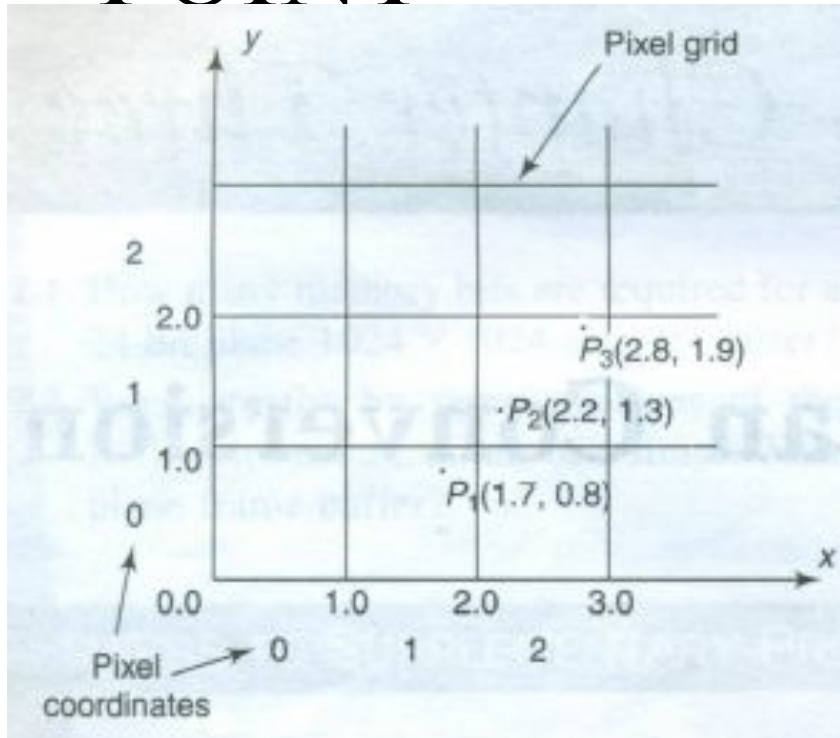


SCAN CONVERSION

- **Rasterisation** (or **rasterization**) is the task of taking an image described in a vector graphics format (shapes) and converting it into a raster image (pixels or dots) for output on a video display or printer, or for storage in a bitmap file format.
- This is also known as **scan conversion**.



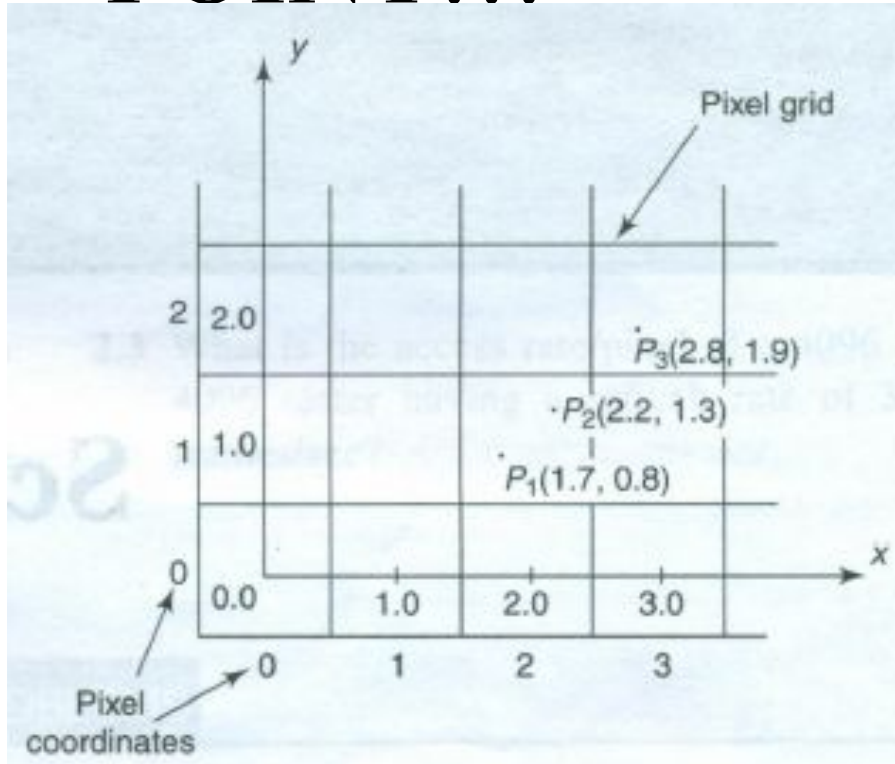
SCAN CONVERSION OF A POINT



- A point (x, y) within an image area, scan converted to a pixel at location (x', y') .
- $x' = \text{Floor}(x)$ and $y' = \text{Floor}(y)$.
- All points satisfying
and $y' \leq y < y' + 1$ are mapped to 1 pixel (x', y')
- Point $P_1(1.7, 0.8)$ is represented by pixel $(1, 0)$ and points $P_2(2.2, 1.3)$ and $P_3(2.8, 1.9)$ are both represented by pixel $(2, 1)$.



SCAN CONVERSION OF A POINT...



- Another approach is to align the integer values in the co-ordinate system for (x, y) with the pixel co-ordinates.
- Here $x' = \text{Floor}(x + 0.5)$ and $y' = \text{Floor}(y + 0.5)$
- Points P_1 and P_2 both are now represented by pixel (2, 1) and P_3 by pixel (3, 2).



LINE DRAWING ALGORITHM

- Need algorithm to figure out which intermediate pixels are on line path
- Pixel (x, y) values constrained to integer values
- Actual computed intermediate line values may be floats
- Rounding may be required. Computed point
 $(10.48, 20.51)$ rounded to $(10, 21)$
- Rounded pixel value is off actual line path (jaggy!!)
- Sloped lines end up having jaggies
- Vertical, horizontal lines, no jaggies

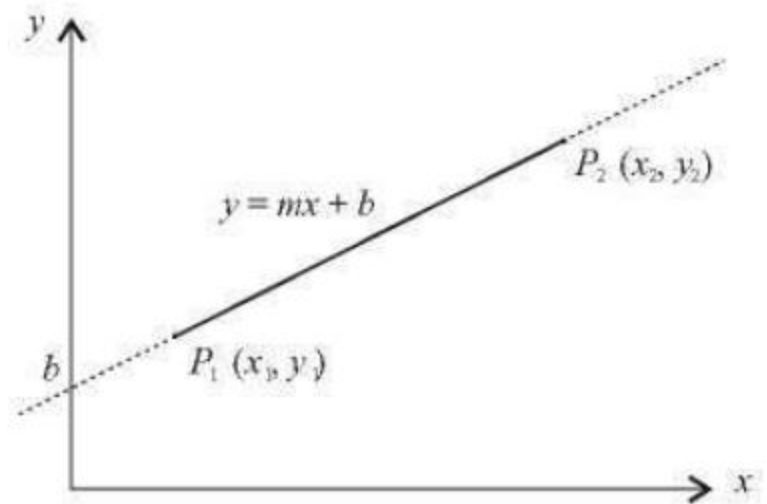


LINE DRAWING ALGORITHM

- Line is defined by its two endpoints and the line equation $y = mx + b$
 - where m is called the slope
 - In Fig. 3-2 the two endpoints are described by $P_1(x_1, y_1)$ and $P_2(x_2, y_2)$.
 - The line equation describes the coordinates of all the points that lie between the two endpoints.
- Given two end points (x_0, y_0) , (x_1, y_1) , how to compute m and b ?

$$m = \frac{dy}{dx} = \frac{y_1 - y_0}{x_1 - x_0}$$

$$b = y_0 - m * x_0$$



DIRECT USE OF THE LINE EQUATION

A simple approach to scan-converting a line is to first scan-convert P_1 and P_2 to pixel coordinates (x'_1, y'_1) and (x'_2, y'_2) , respectively; then set $m = (y'_2 - y'_1)/(x'_2 - x'_1)$ and $b = y'_1 - mx'_1$. If $|m| \leq 1$, then for every integer value of x between and excluding x'_1 and x'_2 , calculate the corresponding value of y using the equation and scan-convert (x, y) . If $|m| > 1$, then for every integer value of y between and excluding y'_1 and y'_2 , calculate the corresponding value of x using the equation and scan-convert (x, y) .





DISADVANTAGE OF DIRECT USE OF THE LINE EQUATION

- It involves floating-point computation (multiplication and addition) in every step that uses the line equation since m and b are generally real numbers.
- The challenge is to find a way to achieve the same goal as quickly as possible.



DIGITAL DIFFERENTIAL ANALYZER (DDA): LINE DRAWING ALGORITHM

- The digital differential analyzer (DDA) algorithm is an incremental scan-conversion method.
- Such an approach is characterized by performing calculations at each step using results from the preceding step.

Suppose at step i we have calculated (x_i, y_i) to be a point on the line. Since the next point (x_{i+1}, y_{i+1}) should satisfy $\Delta y / \Delta x = m$ where $\Delta y = y_{i+1} - y_i$ and $\Delta x = x_{i+1} - x_i$, we have

$$y_{i+1} = y_i + m\Delta x$$

or

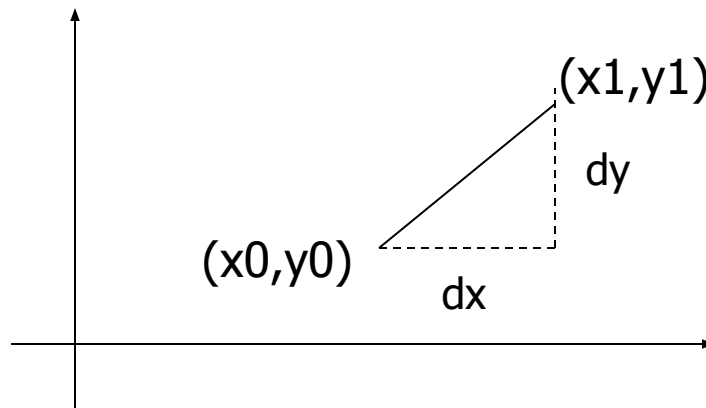
$$x_{i+1} = x_i + \Delta y / m$$

These formulas are used in the DDA algorithm as follows. When $|m| \leq 1$, we start with $x = x'_1$ (assuming that $x'_1 < x'_2$) and $y = y'_1$, and set $\Delta x = 1$ (i.e., unit increment in the x direction). The y coordinate of each successive point on the line is calculated using $y_{i+1} = y_i + m$. When $|m| > 1$, we start with $x = x'_1$ and $y = y'_1$ (assuming that $y'_1 < y'_2$), and set $\Delta y = 1$ (i.e., unit increment in the y direction). The x coordinate of each successive point on the line is calculated using $x_{i+1} = x_i + 1/m$. This process continues until x reaches x'_2 (for the $|m| \leq 1$ case) or y reaches y'_2 (for the $|m| > 1$ case) and all points found are scan-converted to pixel coordinates.

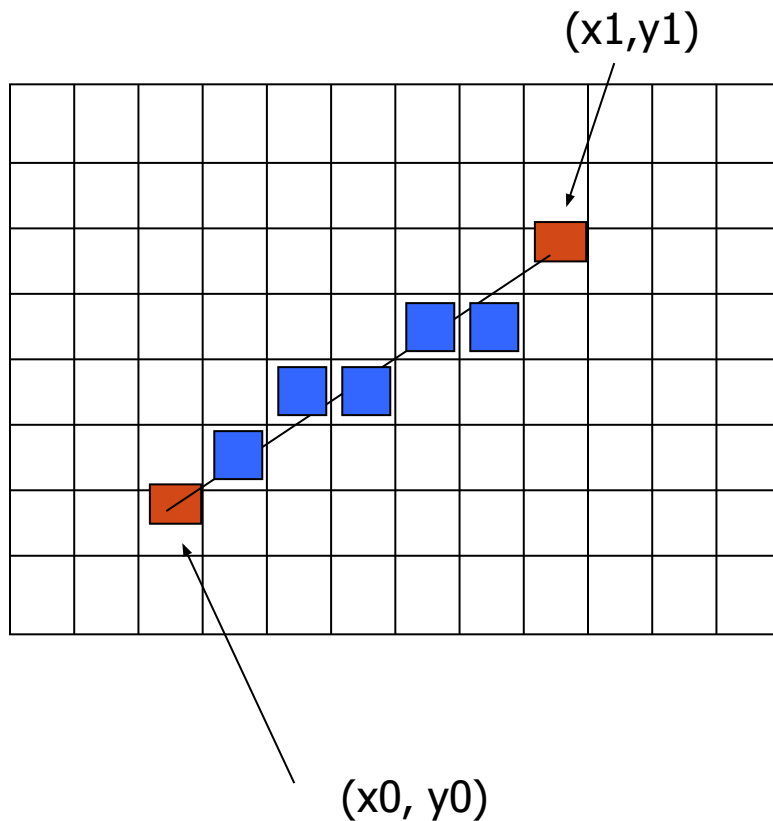


DIGITAL DIFFERENTIAL ANALYZER (DDA): LINE DRAWING ALGORITHM

- Walk through the line, starting at (x_0, y_0)
- Constrain x, y increments to values in $[0, 1]$ range
- Case a: x is incrementing faster ($m < 1$)
 - Step in $x=1$ increments, compute and round y
- Case b: y is incrementing faster ($m > 1$)
 - Step in $y=1$ increments, compute and round x



DDA LINE DRAWING ALGORITHM (CASE A: $M < 1$)



$x = x_0$ $y = y_0$

Illuminate pixel $(x, \text{round}(y))$

$x = x_0 + 1$ $y = y_0 + 1 * m$

Illuminate pixel $(x, \text{round}(y))$

$x = x + 1$ $y = y + 1 * m$

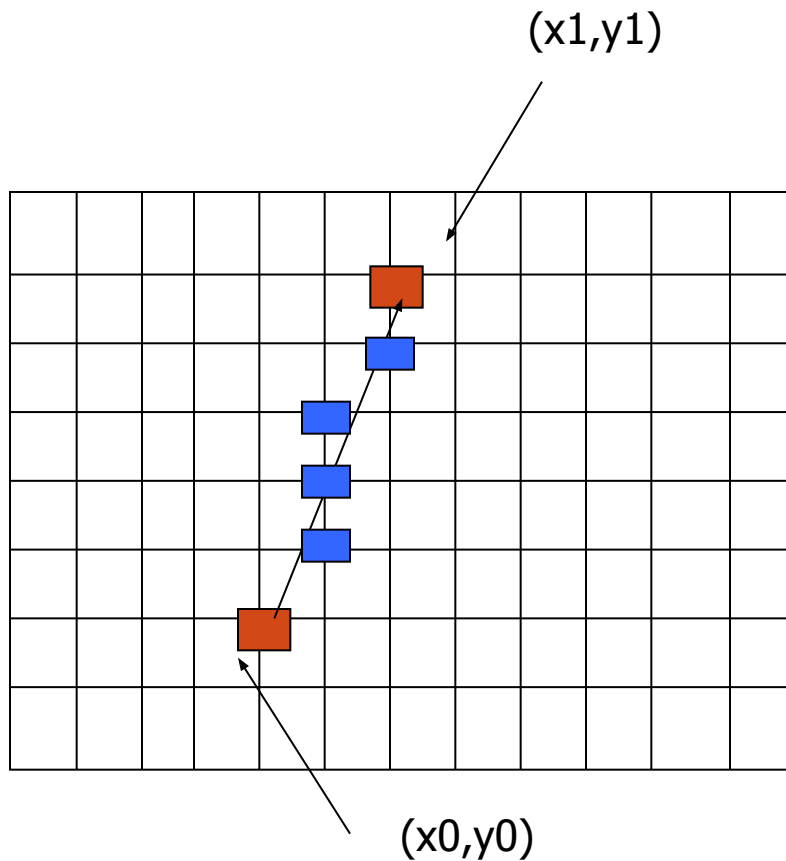
Illuminate pixel $(x, \text{round}(y))$

...

Until $x == x_1$



DDA LINE DRAWING ALGORITHM (CASE B: $M > 1$)



$$x = x_0 \quad y = y_0$$

Illuminate pixel (round(x), y)

$$y = y_0 + 1 \quad x = x_0 + 1 * 1/m$$

Illuminate pixel (round(x), y)

$$y = y + 1 \quad x = x + 1 / m$$

Illuminate pixel (round(x), y)

...

Until $y == y_1$



DDA LINE DRAWING ALGORITHM PSEUDOCODE

```
compute m;  
if m < 1:  
{  
    float y = y0;          // initial value  
    for(int x = x0; x <= x1; x++, y += m)  
        setPixel(x, round(y));  
}  
else // m > 1  
{  
    float x = x0;          // initial value  
    for(int y = y0; y <= y1; y++, x += 1/m)  
        setPixel(round(x), y);  
}
```

- Note: **setPixel(x, y)** writes current color into pixel in column x and row y in frame buffer



DDA EXAMPLE (CASE A: $M < 1$)

- Suppose we want to draw a line starting at pixel (2,3) and ending at pixel (12,8).
- What are the values of the variables x and y at each timestep?
- What are the pixels colored, according to the DDA algorithm?

t	x	y	R(x)	R(y)
0	2	3	2	3
1	3	3.5	3	4
2	4	4	4	4
3	5	4.5	5	5
4	6	5	6	5
5	7	5.5	7	6
6	8	6	8	6
7	9	6.5	9	7
8	10	7	10	7
9	11	7.5	11	8
10	12	8	12	8



DDA ALGORITHM DRAWBACKS

- DDA is the simplest line drawing algorithm
 - Not very efficient
 - Floating point operations and rounding operations are expensive.

