## lmalg

This subroutine has the interface for calling the function *lmder* from MINPACK. *lmder* is a modified levenberg-marquardt algorithm with analytically calculated jacobian.

[called by: solvers.] [calls: packdof.]

## General

Levenberg-Marquardt algorithm is one of the most famous minimization algorithms. There is a brief introduction on Wikipedia. In FOCUS, we use the subroutine *lmder* from MINPACK.

## Documentation

The cost functions (targets) are stored in LM\_fvec(1:LM\_mfvec), and the jacobian is stored in LM\_fjac(1:LM\_mfvec, 1:Ndof). The number of targets (LM\_mfvec) must be not be smaller than the number of parameters (Ndof).

The targets are consistant of different terms. The following table lists the details. Here are the comments from *lmder*. The four

Table 1: **LM\_fvec** components

cost functions	physiccal meaning	switch	length
bnormal	$\mathbf{B} \cdot \mathbf{n}$ on each surface element	$weight\_bnorm > 0$	Nteta*Nzeta
bmnharm	$wBmn_i(Bmn_i - Bmn_i^o)$ for each reasonant harmonics	$weight\_bharm > 0$	2*NBmn in target.harmonics
torflux	$\Psi_i - \Psi_o$ at each toroidal cross-sections	$weight\_tflux > 0$	Nzeta
length	length penalty of each coil, $L_i - L_o$ or $\exp(L_i)/\exp L_o$	weight_ttlen $> 0$	Ncoils - Nfixgeo
surfsep	potential energy between each coil and a control surface	${\rm weight\_cssep} > 0$	Ncoils - Nfixgeo

input parameters for L-M optimizer are LM\_maxiter, LM\_xtol, LM\_ftol and LM\_factor. Please look at initial for more details.

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the subroutine statement is
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\mathbf{c}
         subroutine lmder(fcn,m,n,x,fvec,fjac,ldfjac,ftol,xtol,gtol,
                             maxfev, diag, mode, factor, nprint, info, nfev,
\mathbf{c}
                             njev, ipvt, qtf, wa1, wa2, wa3, wa4)
       where
\mathbf{c}
         fcn is the name of the user-supplied subroutine which
           calculates the functions and the jacobian. fcn must
\mathbf{c}
           be declared in an external statement in the user
\mathbf{c}
           calling program, and should be written as follows.
\mathbf{c}
\mathbf{c}
           subroutine fcn(m,n,x,fvec,fjac,ldfjac,iflag)
^{\rm c}
           integer m,n,ldfjac,iflag
^{\rm c}
           double precision x(n), fvec(m), fjac(ldfjac,n)
C
C
           if if lag = 1 calculate the functions at x and
\mathbf{c}
           return this vector in fvec. do not alter fjac.
\mathbf{c}
           if iflag = 2 calculate the jacobian at x and
С
С
           return this matrix in fjac. do not alter fvec.
           return
           end
С
           the value of iflag should not be changed by fcn unless
           the user wants to terminate execution of lmder.
\mathbf{c}
           in this case set iflag to a negative integer.
\mathbf{c}
\mathbf{c}
         m is a positive integer input variable set to the number
\mathbf{c}
           of functions.
C
C
         n is a positive integer input variable set to the number
C
           of variables. n must not exceed m.
C
С
\mathbf{c}
         x is an array of length n. on input x must contain
           an initial estimate of the solution vector. on output x
\mathbf{c}
           contains the final estimate of the solution vector.
С
\mathbf{c}
```

fvec is an output array of length m which contains the functions evaluated at the output x.

fjac is an output m by n array. the upper n by n submatrix of fjac contains an upper triangular matrix r with diagonal elements of nonincreasing magnitude such that

$$t t t p *(jac *jac)*p = r *r,$$

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С

 $_{\rm c}^{\rm c}$ 

c c

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 $\mathbf{c}$ 

c

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c c

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С

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С

 $^{\rm c}$ 

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 $\begin{array}{c} c \\ c \\ c \end{array}$ 

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c

where p is a permutation matrix and jac is the final calculated jacobian. column j of p is column ipvt(j) (see below) of the identity matrix. the lower trapezoidal part of fjac contains information generated during the computation of r.

ldfjac is a positive integer input variable not less than m which specifies the leading dimension of the array fjac.

ftol is a nonnegative input variable. termination occurs when both the actual and predicted relative reductions in the sum of squares are at most ftol. therefore, ftol measures the relative error desired in the sum of squares.

xtol is a nonnegative input variable, termination occurs when the relative error between two consecutive iterates is at most xtol, therefore, xtol measures the relative error desired in the approximate solution.

gtol is a nonnegative input variable, termination occurs when the cosine of the angle between fvec and any column of the jacobian is at most gtol in absolute value, therefore, gtol measures the orthogonality desired between the function vector and the columns of the jacobian.

maxfev is a positive **integer** input variable. termination occurs when the **number** of calls **to** fcn with iflag = 1 has reached maxfev.

diag is an array of length n. if mode = 1 (see below), diag is internally set. if mode = 2, diag must contain positive entries that serve as multiplicative scale factors for the variables.

mode is an **integer** input variable. **if** mode = 1, the variables will be scaled internally. **if** mode = 2, the scaling is specified by the input diag. other values of mode are equivalent **to** mode = 1.

factor is a positive input variable used in determining the initial step bound. this bound is set to the product of factor and the euclidean norm of diag\*x if nonzero, or else to factor itself. in most cases factor should lie in the interval (.1,100.).100. is a generally recommended value.

nprint is an **integer** input variable that enables controlled printing of iterates if it is positive. **in** this **case**, fcn is called with iflag = 0 at the beginning of the first iteration and every nprint iterations thereafter and immediately prior **to return**, with x, fvec, and fjac available for printing. fvec and fjac should not be altered. if nprint is not positive, no special calls of fcn with iflag = 0 are made.

info is an **integer** output variable. **if** the user has terminated execution, info is set **to** the (negative) value of iflag. see description of fcn. otherwise, info is set as follows.

```
info = 0 improper input parameters.
C
            info = 1 both actual and predicted relative reductions
С
                        in the sum of squares are at most ftol.
С
С
С
            info = 2 relative error between two consecutive iterates
                        is at most xtol.
^{\rm c}
^{\rm c}
            info = 3 conditions for info = 1 and info = 2 both hold.
^{\rm c}
^{\rm c}
            info = 4 the cosine of the angle between fvec and any
\mathbf{c}
                        column of the jacobian is at most gtol in
\mathbf{c}
                        absolute value.
\mathbf{c}
\mathbf{c}
            info = 5 number of calls to fcn with iflag = 1 has
c
                        reached maxfev.
c
c
            info = 6 ftol is too small. no further reduction in
\mathbf{c}
                        the sum of squares is possible.
^{\rm c}
С
            info = 7 xtol is too small. no further improvement in
С
                        the approximate solution x is possible.
С
^{\rm c}
^{\rm c}
            info = 8 gtol is too small. fvec is orthogonal to the
                        columns of the jacobian to machine precision.
\mathbf{c}
^{\rm c}
          nfev is an integer output variable set to the number of
^{\rm c}
\mathbf{c}
            calls to fcn with if lag = 1.
\mathbf{c}
          njev is an integer output variable set to the number of
\mathbf{c}
            calls to fcn with iflag = 2.
\mathbf{c}
^{\rm c}
C
          ipvt is an integer output array of length n. ipvt
            defines a permutation matrix p such that jac*p = q*r,
\mathbf{c}
            where jac is the final calculated jacobian, q is
^{\rm c}
            orthogonal (not stored), and r is upper triangular
С
            with diagonal elements of nonincreasing magnitude.
С
            column j of p is column ipvt(j) of the identity matrix.
С
С
^{\rm c}
          qtf is an output array of length n which contains
\mathbf{c}
            the first n elements of the vector (q transpose)*fvec.
\mathbf{c}
         wal, wa2, and wa3 are work arrays of length n.
\mathbf{c}
^{\rm c}
         wa4 is a work array of length m.
\mathbf{c}
\mathbf{c}
\mathbf{c}
       subprograms called
\mathbf{c}
          user-supplied ..... fcn
\mathbf{c}
c
^{\rm c}
          minpack-supplied ... dpmpar, enorm, lmpar, qrfac
\mathbf{c}
          fortran-supplied ... dabs, dmax1, dmin1, dsqrt, mod
С
С
       argonne national laboratory. minpack project. march 1980.
С
       burton s. garbow, kenneth e. hillstrom, jorge j. more
С
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lmalg.h last modified on 018-06-19 16:32:41.;

Focus subroutines;