

# Real-time simulation

This notebook introduces quantum simulation, and explores simulating the real-time dynamics of a spin-ring Ising system. We demonstrate classical analytic and numerical treatments, then study Trotterisation in the absence and presence of decoherence.

## Contents:

- *Analytic*
- *Numerical*
- *Trotterisation*
  - *Pure*
  - *Noisy*

Tyson Jones, 2024  
Department of Materials, University of Oxford  
tyson.jones.input@gmail.com

```
Import["https://qtechtheory.org/questlink.m"];  
CreateDownloadedQuESTEnv[];
```

## Analytic

In quantum simulation, we are interested in studying the properties of a time-dependent state  $|\psi(t)\rangle$  as it evolves according to the physics of some Hamiltonian  $\hat{H}$ . Consider this arbitrary 3-qubit Hamiltonian specified in the Pauli basis:

```
nQb = 3;
```

```
h = X0 Y1 + 2 Y2 Z0 - 3 Z0 Z1 Z2;
```

```
hMatr = CalcPauliExpressionMatrix[h]
```

```
MatrixForm @ Normal @ %
```

```
SparseArray[ Specified elements: 24  
Dimensions: {8, 8}]
```

$$\begin{pmatrix} -3 & 0 & 0 & -i & -2i & 0 & 0 & 0 \\ 0 & 3 & -i & 0 & 0 & 2i & 0 & 0 \\ 0 & i & 3 & 0 & 0 & 0 & -2i & 0 \\ i & 0 & 0 & -3 & 0 & 0 & 0 & 2i \\ 2i & 0 & 0 & 0 & 3 & 0 & 0 & -i \\ 0 & -2i & 0 & 0 & 0 & -3 & -i & 0 \\ 0 & 0 & 2i & 0 & 0 & i & -3 & 0 \\ 0 & 0 & 0 & -2i & i & 0 & 0 & 3 \end{pmatrix}$$

We'll study the evolution of  $|\psi(t)\rangle$  from initial state  $|\psi(0)\rangle = |0\rangle$  initial state.

```
 $\psi_0 = \text{UnitVector}[2^{n_{\text{Qb}}}, 1]$ 
```

```
{1, 0, 0, 0, 0, 0, 0, 0}
```


One way to obtain the future states  $|\psi(t)\rangle$  is to numerically solve the Schrödinger equation:

$$i \hbar \frac{d}{dt} |\psi(t)\rangle = \hat{H} |\psi(0)\rangle$$

```
NDSolve[{i \psi'[t] == hMatr . \psi[t], \psi[0] == \psi0}, \psi, {t, 0, 4}];
```

```
\psi = %[[1, 1, 2]]
```

... NDSolve: Encountered non-numerical value for a derivative at t == 0.``

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$\psi[0]$  // Chop

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R[2.90144, Z0 Z1], R[11.7785, Z2], R[2.90144, Z1 Z2], R[12.315, Z3],
R[2.90144, Z2 Z3], R[10.7582, Z4], R[2.90144, Z3 Z4], R[14.4127, Z5],
R[2.90144, Z4 Z5], R[10.8217, Z6], R[2.90144, Z0 Z6], R[5.80287, Z5 Z6],
R[2.90144, Z0 Z6], R[10.8217, Z6], R[2.90144, Z4 Z5], R[14.4127, Z5],
R[2.90144, Z3 Z4], R[10.7582, Z4], R[2.90144, Z2 Z3], R[12.315, Z3],
R[2.90144, Z1 Z2], R[11.7785, Z2], R[2.90144, Z0 Z1], R[11.1418, Z1],
R[14.445, Z0], R[2.90144, Y5 Y6], R[2.90144, Y0 Y6], R[2.90144, Y4 Y5],
R[2.90144, Y3 Y4], R[2.90144, Y2 Y3], R[2.90144, Y1 Y2], R[2.90144, Y0 Y1],
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R[2.90144, X2 X3], R[2.90144, X1 X2], R[2.90144, X0 X1], R[2.90144, X0 X1],
R[2.90144, X1 X2], R[2.90144, X2 X3], R[2.90144, X3 X4], R[2.90144, X4 X5],
R[2.90144, X0 X6], R[2.90144, X5 X6], R[2.90144, Y0 Y1], R[2.90144, Y1 Y2],
R[2.90144, Y2 Y3], R[2.90144, Y3 Y4], R[2.90144, Y4 Y5], R[2.90144, Y0 Y6],
R[2.90144, Y5 Y6], R[14.445, Z0], R[11.1418, Z1], R[2.90144, Z0 Z1],
R[11.7785, Z2], R[2.90144, Z1 Z2], R[12.315, Z3], R[2.90144, Z2 Z3],
R[10.7582, Z4], R[2.90144, Z3 Z4], R[14.4127, Z5], R[2.90144, Z4 Z5],
R[10.8217, Z6], R[2.90144, Z0 Z6], R[5.80287, Z5 Z6], R[2.90144, Z0 Z6],
R[10.8217, Z6], R[2.90144, Z4 Z5], R[14.4127, Z5], R[2.90144, Z3 Z4],

```

$R[10.7582, Z_4]$ ,  $R[2.90144, Z_2 Z_3]$ ,  $R[12.315, Z_3]$ ,  $R[2.90144, Z_1 Z_2]$ ,  
 $R[11.7785, Z_2]$ ,  $R[2.90144, Z_0 Z_1]$ ,  $R[11.1418, Z_1]$ ,  $R[14.445, Z_0]$ ,  
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 $R[-4.60574, X_2 X_3]$ ,  $R[-4.60574, X_3 X_4]$ ,  $R[-4.60574, X_4 X_5]$ ,  $R[-4.60574, X_0 X_6]$ ,  
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 $R[-4.60574, Y_2 Y_3]$ ,  $R[-4.60574, Y_3 Y_4]$ ,  $R[-4.60574, Y_4 Y_5]$ ,  
 $R[-4.60574, Y_0 Y_6]$ ,  $R[-4.60574, Y_5 Y_6]$ ,  $R[-22.93, Z_0]$ ,  $R[-17.6866, Z_1]$ ,  
 $R[-4.60574, Z_0 Z_1]$ ,  $R[-18.6972, Z_2]$ ,  $R[-4.60574, Z_1 Z_2]$ ,  $R[-19.5488, Z_3]$ ,  
 $R[-4.60574, Z_2 Z_3]$ ,  $R[-17.0776, Z_4]$ ,  $R[-4.60574, Z_3 Z_4]$ ,  $R[-22.8787, Z_5]$ ,  
 $R[-4.60574, Z_4 Z_5]$ ,  $R[-17.1783, Z_6]$ ,  $R[-4.60574, Z_0 Z_6]$ ,  $R[-9.21148, Z_5 Z_6]$ ,  
 $R[-4.60574, Z_0 Z_6]$ ,  $R[-17.1783, Z_6]$ ,  $R[-4.60574, Z_4 Z_5]$ ,  $R[-22.8787, Z_5]$ ,  
 $R[-4.60574, Z_3 Z_4]$ ,  $R[-17.0776, Z_4]$ ,  $R[-4.60574, Z_2 Z_3]$ ,  $R[-19.5488, Z_3]$ ,  
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 $R[-4.60574, Y_3 Y_4]$ ,  $R[-4.60574, Y_2 Y_3]$ ,  $R[-4.60574, Y_1 Y_2]$ ,  $R[-4.60574, Y_0 Y_1]$ ,  
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 $R[2.90144, Y_0 Y_6]$ ,  $R[2.90144, Y_5 Y_6]$ ,  $R[14.445, Z_0]$ ,  $R[11.1418, Z_1]$ ,  
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 $R[2.90144, Z_2 Z_3]$ ,  $R[10.7582, Z_4]$ ,  $R[2.90144, Z_3 Z_4]$ ,  $R[14.4127, Z_5]$ ,  
 $R[2.90144, Z_4 Z_5]$ ,  $R[10.8217, Z_6]$ ,  $R[2.90144, Z_0 Z_6]$ ,  $R[5.80287, Z_5 Z_6]$ ,  
 $R[2.90144, Z_0 Z_6]$ ,  $R[10.8217, Z_6]$ ,  $R[2.90144, Z_4 Z_5]$ ,  $R[14.4127, Z_5]$ ,  
 $R[2.90144, Z_3 Z_4]$ ,  $R[10.7582, Z_4]$ ,  $R[2.90144, Z_2 Z_3]$ ,  $R[12.315, Z_3]$ ,  
 $R[2.90144, Z_1 Z_2]$ ,  $R[11.7785, Z_2]$ ,  $R[2.90144, Z_0 Z_1]$ ,  $R[11.1418, Z_1]$ ,  
 $R[14.445, Z_0]$ ,  $R[2.90144, Y_5 Y_6]$ ,  $R[2.90144, Y_0 Y_6]$ ,  $R[2.90144, Y_4 Y_5]$ ,  
 $R[2.90144, Y_3 Y_4]$ ,  $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_1 Y_2]$ ,  $R[2.90144, Y_0 Y_1]$ ,  
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 $R[2.90144, X_2 X_3]$ ,  $R[2.90144, X_1 X_2]$ ,  $R[2.90144, X_0 X_1]$ ,  $R[2.90144, X_0 X_1]$ ,  
 $R[2.90144, X_1 X_2]$ ,  $R[2.90144, X_2 X_3]$ ,  $R[2.90144, X_3 X_4]$ ,  $R[2.90144, X_4 X_5]$ ,  
 $R[2.90144, X_0 X_6]$ ,  $R[2.90144, X_5 X_6]$ ,  $R[2.90144, Y_0 Y_1]$ ,  $R[2.90144, Y_1 Y_2]$ ,  
 $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_3 Y_4]$ ,  $R[2.90144, Y_4 Y_5]$ ,  $R[2.90144, Y_0 Y_6]$ ,  
 $R[2.90144, Y_5 Y_6]$ ,  $R[14.445, Z_0]$ ,  $R[11.1418, Z_1]$ ,  $R[2.90144, Z_0 Z_1]$ ,  
 $R[11.7785, Z_2]$ ,  $R[2.90144, Z_1 Z_2]$ ,  $R[12.315, Z_3]$ ,  $R[2.90144, Z_2 Z_3]$ ,  
 $R[10.7582, Z_4]$ ,  $R[2.90144, Z_3 Z_4]$ ,  $R[14.4127, Z_5]$ ,  $R[2.90144, Z_4 Z_5]$ ,  
 $R[10.8217, Z_6]$ ,  $R[2.90144, Z_0 Z_6]$ ,  $R[5.80287, Z_5 Z_6]$ ,  $R[2.90144, Z_0 Z_6]$ ,  
 $R[10.8217, Z_6]$ ,  $R[2.90144, Z_4 Z_5]$ ,  $R[14.4127, Z_5]$ ,  $R[2.90144, Z_3 Z_4]$ ,  
 $R[10.7582, Z_4]$ ,  $R[2.90144, Z_2 Z_3]$ ,  $R[12.315, Z_3]$ ,  $R[2.90144, Z_1 Z_2]$ ,  
 $R[11.7785, Z_2]$ ,  $R[2.90144, Z_0 Z_1]$ ,  $R[11.1418, Z_1]$ ,  $R[14.445, Z_0]$ ,  
 $R[2.90144, Y_5 Y_6]$ ,  $R[2.90144, Y_0 Y_6]$ ,  $R[2.90144, Y_4 Y_5]$ ,  $R[2.90144, Y_3 Y_4]$ ,  
 $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_1 Y_2]$ ,  $R[2.90144, Y_0 Y_1]$ ,  $R[2.90144, X_5 X_6]$ ,  
 $R[2.90144, X_0 X_6]$ ,  $R[2.90144, X_4 X_5]$ ,  $R[2.90144, X_3 X_4]$ ,  $R[2.90144, X_2 X_3]$ ,

$$R[2.90144, X_1 X_2], R[2.90144, X_0 X_1] \} [t] \cdot \{1, 0, 0, 0, 0, 0, 0, 0\} \Bigg) [0.3]$$

We could instead obtain an analytic expression for  $|\psi(t)\rangle = \hat{U}(t) |\psi(0)\rangle$  by symbolically constructing the unitary time evolution operator  $\hat{U}(t) = e^{-it\hat{H}}$

```
u[t_] = MatrixExp[-i t CalcPauliExpressionMatrix[h]];
```

Set: Tag List in

```
{R[2.90144, X0 X1], R[2.90144, X1 X2], R[2.90144, X2 X3], R[2.90144, X3 X4], R[2.90144, X4 X5], R[2.90144, <<1>>],  
R[2.90144, X5 X6], R[2.90144, Y0 Y1], R[2.90144, Y1 Y2], R[2.90144, Y2 Y3], <<265>>}[t_] is  
Protected.
```

MatrixForm @ u[t]

```
{R[2.90144, X0 X1], R[2.90144, X1 X2], R[2.90144, X2 X3], R[2.90144, X3 X4],  
R[2.90144, X4 X5], R[2.90144, X0 X6], R[2.90144, X5 X6], R[2.90144, Y0 Y1],  
R[2.90144, Y1 Y2], R[2.90144, Y2 Y3], R[2.90144, Y3 Y4], R[2.90144, Y4 Y5],  
R[2.90144, Y0 Y6], R[2.90144, Y5 Y6], R[14.445, Z0], R[11.1418, Z1],  
R[2.90144, Z0 Z1], R[11.7785, Z2], R[2.90144, Z1 Z2], R[12.315, Z3],  
R[2.90144, Z2 Z3], R[10.7582, Z4], R[2.90144, Z3 Z4], R[14.4127, Z5],  
R[2.90144, Z4 Z5], R[10.8217, Z6], R[2.90144, Z0 Z6], R[5.80287, Z5 Z6],  
R[2.90144, Z0 Z6], R[10.8217, Z6], R[2.90144, Z4 Z5], R[14.4127, Z5],  
R[2.90144, Z3 Z4], R[10.7582, Z4], R[2.90144, Z2 Z3], R[12.315, Z3],  
R[2.90144, Z1 Z2], R[11.7785, Z2], R[2.90144, Z0 Z1], R[11.1418, Z1], R[14.445, Z0],  
R[2.90144, Y5 Y6], R[2.90144, Y0 Y6], R[2.90144, Y4 Y5], R[2.90144, Y3 Y4],  
R[2.90144, Y2 Y3], R[2.90144, Y1 Y2], R[2.90144, Y0 Y1], R[2.90144, X5 X6],  
R[2.90144, X0 X6], R[2.90144, X4 X5], R[2.90144, X3 X4], R[2.90144, X2 X3],  
R[2.90144, X1 X2], R[2.90144, X0 X1], R[2.90144, X0 X1], R[2.90144, X1 X2],  
R[2.90144, X2 X3], R[2.90144, X3 X4], R[2.90144, X4 X5], R[2.90144, X0 X6],  
R[2.90144, X5 X6], R[2.90144, Y0 Y1], R[2.90144, Y1 Y2], R[2.90144, Y2 Y3],  
R[2.90144, Y3 Y4], R[2.90144, Y4 Y5], R[2.90144, Y0 Y6], R[2.90144, Y5 Y6],  
R[14.445, Z0], R[11.1418, Z1], R[2.90144, Z0 Z1], R[11.7785, Z2], R[2.90144, Z1 Z2],  
R[12.315, Z3], R[2.90144, Z2 Z3], R[10.7582, Z4], R[2.90144, Z3 Z4], R[14.4127, Z5],  
R[2.90144, Z4 Z5], R[10.8217, Z6], R[2.90144, Z0 Z6], R[5.80287, Z5 Z6],  
R[2.90144, Z0 Z6], R[10.8217, Z6], R[2.90144, Z4 Z5], R[14.4127, Z5],  
R[2.90144, Z3 Z4], R[10.7582, Z4], R[2.90144, Z2 Z3], R[12.315, Z3],  
R[2.90144, Z1 Z2], R[11.7785, Z2], R[2.90144, Z0 Z1], R[11.1418, Z1], R[14.445, Z0],  
R[2.90144, Y5 Y6], R[2.90144, Y0 Y6], R[2.90144, Y4 Y5], R[2.90144, Y3 Y4],  
R[2.90144, Y2 Y3], R[2.90144, Y1 Y2], R[2.90144, Y0 Y1], R[2.90144, X5 X6],  
R[2.90144, X0 X6], R[2.90144, X4 X5], R[2.90144, X3 X4], R[2.90144, X2 X3],  
R[2.90144, X1 X2], R[2.90144, X0 X1], R[-4.60574, X0 X1], R[-4.60574, X1 X2],  
R[-4.60574, X2 X3], R[-4.60574, X3 X4], R[-4.60574, X4 X5], R[-4.60574, X0 X6],  
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R[-4.60574, Y3 Y4], R[-4.60574, Y4 Y5], R[-4.60574, Y0 Y6], R[-4.60574, Y5 Y6],  
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R[-4.60574, Z1 Z2], R[-19.5488, Z3], R[-4.60574, Z2 Z3], R[-17.0776, Z4],  
R[-4.60574, Z3 Z4], R[-22.8787, Z5], R[-4.60574, Z4 Z5], R[-17.1783, Z6],  
R[-4.60574, Z0 Z6], R[-9.21148, Z5 Z6], R[-4.60574, Z0 Z6], R[-17.1783, Z6],
```

```

R[-4.60574, Z4 Z5], R[-22.8787, Z5], R[-4.60574, Z3 Z4], R[-17.0776, Z4],
R[-4.60574, Z2 Z3], R[-19.5488, Z3], R[-4.60574, Z1 Z2], R[-18.6972, Z2],
R[-4.60574, Z0 Z1], R[-17.6866, Z1], R[-22.93, Z0], R[-4.60574, Y5 Y6],
R[-4.60574, Y0 Y6], R[-4.60574, Y4 Y5], R[-4.60574, Y3 Y4], R[-4.60574, Y2 Y3],
R[-4.60574, Y1 Y2], R[-4.60574, Y0 Y1], R[-4.60574, X5 X6], R[-4.60574, X0 X6],
R[-4.60574, X4 X5], R[-4.60574, X3 X4], R[-4.60574, X2 X3], R[-4.60574, X1 X2],
R[-4.60574, X0 X1], R[2.90144, X0 X1], R[2.90144, X1 X2], R[2.90144, X2 X3],
R[2.90144, X3 X4], R[2.90144, X4 X5], R[2.90144, X0 X6], R[2.90144, X5 X6],
R[2.90144, Y0 Y1], R[2.90144, Y1 Y2], R[2.90144, Y2 Y3], R[2.90144, Y3 Y4],
R[2.90144, Y4 Y5], R[2.90144, Y0 Y6], R[2.90144, Y5 Y6], R[14.445, Z0],
R[11.1418, Z1], R[2.90144, Z0 Z1], R[11.7785, Z2], R[2.90144, Z1 Z2], R[12.315, Z3],
R[2.90144, Z2 Z3], R[10.7582, Z4], R[2.90144, Z3 Z4], R[14.4127, Z5],
R[2.90144, Z4 Z5], R[10.8217, Z6], R[2.90144, Z0 Z6], R[5.80287, Z5 Z6],
R[2.90144, Z0 Z6], R[10.8217, Z6], R[2.90144, Z4 Z5], R[14.4127, Z5],
R[2.90144, Z3 Z4], R[10.7582, Z4], R[2.90144, Z2 Z3], R[12.315, Z3],
R[2.90144, Z1 Z2], R[11.7785, Z2], R[2.90144, Z0 Z1], R[11.1418, Z1], R[14.445, Z0],
R[2.90144, Y5 Y6], R[2.90144, Y0 Y6], R[2.90144, Y4 Y5], R[2.90144, Y3 Y4],
R[2.90144, Y2 Y3], R[2.90144, Y1 Y2], R[2.90144, Y0 Y1], R[2.90144, X5 X6],
R[2.90144, X0 X6], R[2.90144, X4 X5], R[2.90144, X3 X4], R[2.90144, X2 X3],
R[2.90144, X1 X2], R[2.90144, X0 X1], R[2.90144, X0 X1], R[2.90144, X1 X2],
R[2.90144, X2 X3], R[2.90144, X3 X4], R[2.90144, X4 X5], R[2.90144, X0 X6],
R[2.90144, X5 X6], R[2.90144, Y0 Y1], R[2.90144, Y1 Y2], R[2.90144, Y2 Y3],
R[2.90144, Y3 Y4], R[2.90144, Y4 Y5], R[2.90144, Y0 Y6], R[2.90144, Y5 Y6],
R[14.445, Z0], R[11.1418, Z1], R[2.90144, Z0 Z1], R[11.7785, Z2], R[2.90144, Z1 Z2],
R[12.315, Z3], R[2.90144, Z2 Z3], R[10.7582, Z4], R[2.90144, Z3 Z4],
R[14.4127, Z5], R[2.90144, Z4 Z5], R[10.8217, Z6], R[2.90144, Z0 Z6],
R[5.80287, Z5 Z6], R[2.90144, Z0 Z6], R[10.8217, Z6], R[2.90144, Z4 Z5],
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R[12.315, Z3], R[2.90144, Z1 Z2], R[11.7785, Z2], R[2.90144, Z0 Z1],
R[11.1418, Z1], R[14.445, Z0], R[2.90144, Y5 Y6], R[2.90144, Y0 Y6],
R[2.90144, Y4 Y5], R[2.90144, Y3 Y4], R[2.90144, Y2 Y3], R[2.90144, Y1 Y2],
R[2.90144, Y0 Y1], R[2.90144, X5 X6], R[2.90144, X0 X6], R[2.90144, X4 X5],
R[2.90144, X3 X4], R[2.90144, X2 X3], R[2.90144, X1 X2], R[2.90144, X0 X1]}[t]

```

We can then obtain analytic expressions for the Z-basis amplitudes of  $|\psi(t)\rangle$  as functions of  $t$

```
Clear[ψ]
```

```
ψ[t] = u[t].ψ0 // Simplify
```

```

{R[2.90144, X0 X1], R[2.90144, X1 X2], R[2.90144, X2 X3], R[2.90144, X3 X4],
R[2.90144, X4 X5], R[2.90144, X0 X6], R[2.90144, X5 X6], R[2.90144, Y0 Y1],
R[2.90144, Y1 Y2], R[2.90144, Y2 Y3], R[2.90144, Y3 Y4], R[2.90144, Y4 Y5],
R[2.90144, Y0 Y6], R[2.90144, Y5 Y6], R[14.445, Z0], R[11.1418, Z1],
R[2.90144, Z0 Z1], R[11.7785, Z2], R[2.90144, Z1 Z2], R[12.315, Z3],
R[2.90144, Z2 Z3], R[10.7582, Z4], R[2.90144, Z3 Z4], R[14.4127, Z5],
R[2.90144, Z4 Z5], R[10.8217, Z6], R[2.90144, Z0 Z6], R[5.80287, Z5 Z6],
R[2.90144, Z0 Z6], R[10.8217, Z6], R[2.90144, Z4 Z5], R[14.4127, Z5],
R[2.90144, Z3 Z4], R[10.7582, Z4], R[2.90144, Z2 Z3], R[12.315, Z3],

```



$R[2.90144, Z_1 Z_2]$ ,  $R[11.7785, Z_2]$ ,  $R[2.90144, Z_0 Z_1]$ ,  $R[11.1418, Z_1]$ ,  
 $R[14.445, Z_0]$ ,  $R[2.90144, Y_5 Y_6]$ ,  $R[2.90144, Y_0 Y_6]$ ,  $R[2.90144, Y_4 Y_5]$ ,  
 $R[2.90144, Y_3 Y_4]$ ,  $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_1 Y_2]$ ,  $R[2.90144, Y_0 Y_1]$ ,  
 $R[2.90144, X_5 X_6]$ ,  $R[2.90144, X_0 X_6]$ ,  $R[2.90144, X_4 X_5]$ ,  $R[2.90144, X_3 X_4]$ ,  
 $R[2.90144, X_2 X_3]$ ,  $R[2.90144, X_1 X_2]$ ,  $R[2.90144, X_0 X_1]$ ,  $R[2.90144, X_0 X_1]$ ,  
 $R[2.90144, X_1 X_2]$ ,  $R[2.90144, X_2 X_3]$ ,  $R[2.90144, X_3 X_4]$ ,  $R[2.90144, X_4 X_5]$ ,  
 $R[2.90144, X_0 X_6]$ ,  $R[2.90144, X_5 X_6]$ ,  $R[2.90144, Y_0 Y_1]$ ,  $R[2.90144, Y_1 Y_2]$ ,  
 $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_3 Y_4]$ ,  $R[2.90144, Y_4 Y_5]$ ,  $R[2.90144, Y_0 Y_6]$ ,  
 $R[2.90144, Y_5 Y_6]$ ,  $R[14.445, Z_0]$ ,  $R[11.1418, Z_1]$ ,  $R[2.90144, Z_0 Z_1]$ ,  
 $R[11.7785, Z_2]$ ,  $R[2.90144, Z_1 Z_2]$ ,  $R[12.315, Z_3]$ ,  $R[2.90144, Z_2 Z_3]$ ,  
 $R[10.7582, Z_4]$ ,  $R[2.90144, Z_3 Z_4]$ ,  $R[14.4127, Z_5]$ ,  $R[2.90144, Z_4 Z_5]$ ,  
 $R[10.8217, Z_6]$ ,  $R[2.90144, Z_0 Z_6]$ ,  $R[5.80287, Z_5 Z_6]$ ,  $R[2.90144, Z_0 Z_6]$ ,  
 $R[10.8217, Z_6]$ ,  $R[2.90144, Z_4 Z_5]$ ,  $R[14.4127, Z_5]$ ,  $R[2.90144, Z_3 Z_4]$ ,  
 $R[10.7582, Z_4]$ ,  $R[2.90144, Z_2 Z_3]$ ,  $R[12.315, Z_3]$ ,  $R[2.90144, Z_1 Z_2]$ ,  
 $R[11.7785, Z_2]$ ,  $R[2.90144, Z_0 Z_1]$ ,  $R[11.1418, Z_1]$ ,  $R[14.445, Z_0]$ ,  
 $R[2.90144, Y_5 Y_6]$ ,  $R[2.90144, Y_0 Y_6]$ ,  $R[2.90144, Y_4 Y_5]$ ,  $R[2.90144, Y_3 Y_4]$ ,  
 $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_1 Y_2]$ ,  $R[2.90144, Y_0 Y_1]$ ,  $R[2.90144, X_5 X_6]$ ,  
 $R[2.90144, X_0 X_6]$ ,  $R[2.90144, X_4 X_5]$ ,  $R[2.90144, X_3 X_4]$ ,  $R[2.90144, X_2 X_3]$ ,  
 $R[2.90144, X_1 X_2]$ ,  $R[2.90144, X_0 X_1]$ ,  $R[-4.60574, X_0 X_1]$ ,  $R[-4.60574, X_1 X_2]$ ,  
 $R[-4.60574, X_2 X_3]$ ,  $R[-4.60574, X_3 X_4]$ ,  $R[-4.60574, X_4 X_5]$ ,  $R[-4.60574, X_0 X_6]$ ,  
 $R[-4.60574, X_5 X_6]$ ,  $R[-4.60574, Y_0 Y_1]$ ,  $R[-4.60574, Y_1 Y_2]$ ,  $R[-4.60574, Y_2 Y_3]$ ,  
 $R[-4.60574, Y_3 Y_4]$ ,  $R[-4.60574, Y_4 Y_5]$ ,  $R[-4.60574, Y_0 Y_6]$ ,  $R[-4.60574, Y_5 Y_6]$ ,  
 $R[-22.93, Z_0]$ ,  $R[-17.6866, Z_1]$ ,  $R[-4.60574, Z_0 Z_1]$ ,  $R[-18.6972, Z_2]$ ,  
 $R[-4.60574, Z_1 Z_2]$ ,  $R[-19.5488, Z_3]$ ,  $R[-4.60574, Z_2 Z_3]$ ,  $R[-17.0776, Z_4]$ ,  
 $R[-4.60574, Z_3 Z_4]$ ,  $R[-22.8787, Z_5]$ ,  $R[-4.60574, Z_4 Z_5]$ ,  $R[-17.1783, Z_6]$ ,  
 $R[-4.60574, Z_0 Z_6]$ ,  $R[-9.21148, Z_5 Z_6]$ ,  $R[-4.60574, Z_0 Z_6]$ ,  $R[-17.1783, Z_6]$ ,  
 $R[-4.60574, Z_4 Z_5]$ ,  $R[-22.8787, Z_5]$ ,  $R[-4.60574, Z_3 Z_4]$ ,  $R[-17.0776, Z_4]$ ,  
 $R[-4.60574, Z_2 Z_3]$ ,  $R[-19.5488, Z_3]$ ,  $R[-4.60574, Z_1 Z_2]$ ,  $R[-18.6972, Z_2]$ ,  
 $R[-4.60574, Z_0 Z_1]$ ,  $R[-17.6866, Z_1]$ ,  $R[-22.93, Z_0]$ ,  $R[-4.60574, Y_5 Y_6]$ ,  
 $R[-4.60574, Y_0 Y_6]$ ,  $R[-4.60574, Y_4 Y_5]$ ,  $R[-4.60574, Y_3 Y_4]$ ,  $R[-4.60574, Y_2 Y_3]$ ,  
 $R[-4.60574, Y_1 Y_2]$ ,  $R[-4.60574, Y_0 Y_1]$ ,  $R[-4.60574, X_5 X_6]$ ,  $R[-4.60574, X_0 X_6]$ ,  
 $R[-4.60574, X_4 X_5]$ ,  $R[-4.60574, X_3 X_4]$ ,  $R[-4.60574, X_2 X_3]$ ,  $R[-4.60574, X_1 X_2]$ ,  
 $R[-4.60574, X_0 X_1]$ ,  $R[2.90144, X_0 X_1]$ ,  $R[2.90144, X_1 X_2]$ ,  $R[2.90144, X_2 X_3]$ ,  
 $R[2.90144, X_3 X_4]$ ,  $R[2.90144, X_4 X_5]$ ,  $R[2.90144, X_0 X_6]$ ,  $R[2.90144, X_5 X_6]$ ,  
 $R[2.90144, Y_0 Y_1]$ ,  $R[2.90144, Y_1 Y_2]$ ,  $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_3 Y_4]$ ,  
 $R[2.90144, Y_4 Y_5]$ ,  $R[2.90144, Y_0 Y_6]$ ,  $R[2.90144, Y_5 Y_6]$ ,  $R[14.445, Z_0]$ ,  
 $R[11.1418, Z_1]$ ,  $R[2.90144, Z_0 Z_1]$ ,  $R[11.7785, Z_2]$ ,  $R[2.90144, Z_1 Z_2]$ ,  
 $R[12.315, Z_3]$ ,  $R[2.90144, Z_2 Z_3]$ ,  $R[10.7582, Z_4]$ ,  $R[2.90144, Z_3 Z_4]$ ,  
 $R[14.4127, Z_5]$ ,  $R[2.90144, Z_4 Z_5]$ ,  $R[10.8217, Z_6]$ ,  $R[2.90144, Z_0 Z_6]$ ,  
 $R[5.80287, Z_5 Z_6]$ ,  $R[2.90144, Z_0 Z_6]$ ,  $R[10.8217, Z_6]$ ,  $R[2.90144, Z_4 Z_5]$ ,  
 $R[14.4127, Z_5]$ ,  $R[2.90144, Z_3 Z_4]$ ,  $R[10.7582, Z_4]$ ,  $R[2.90144, Z_2 Z_3]$ ,  
 $R[12.315, Z_3]$ ,  $R[2.90144, Z_1 Z_2]$ ,  $R[11.7785, Z_2]$ ,  $R[2.90144, Z_0 Z_1]$ ,  
 $R[11.1418, Z_1]$ ,  $R[14.445, Z_0]$ ,  $R[2.90144, Y_5 Y_6]$ ,  $R[2.90144, Y_0 Y_6]$ ,  
 $R[2.90144, Y_4 Y_5]$ ,  $R[2.90144, Y_3 Y_4]$ ,  $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_1 Y_2]$ ,  
 $R[2.90144, Y_0 Y_1]$ ,  $R[2.90144, X_5 X_6]$ ,  $R[2.90144, X_0 X_6]$ ,  $R[2.90144, X_4 X_5]$ ,  
 $R[2.90144, X_3 X_4]$ ,  $R[2.90144, X_2 X_3]$ ,  $R[2.90144, X_1 X_2]$ ,  $R[2.90144, X_0 X_1]$ ,  
 $R[2.90144, X_0 X_1]$ ,  $R[2.90144, X_1 X_2]$ ,  $R[2.90144, X_2 X_3]$ ,  $R[2.90144, X_3 X_4]$ ,

```

R[2.90144, X4 X5], R[2.90144, X0 X6], R[2.90144, X5 X6], R[2.90144, Y0 Y1],
R[2.90144, Y1 Y2], R[2.90144, Y2 Y3], R[2.90144, Y3 Y4], R[2.90144, Y4 Y5],
R[2.90144, Y0 Y6], R[2.90144, Y5 Y6], R[14.445, Z0], R[11.1418, Z1],
R[2.90144, Z0 Z1], R[11.7785, Z2], R[2.90144, Z1 Z2], R[12.315, Z3],
R[2.90144, Z2 Z3], R[10.7582, Z4], R[2.90144, Z3 Z4], R[14.4127, Z5],
R[2.90144, Z4 Z5], R[10.8217, Z6], R[2.90144, Z0 Z6], R[5.80287, Z5 Z6],
R[2.90144, Z0 Z6], R[10.8217, Z6], R[2.90144, Z4 Z5], R[14.4127, Z5],
R[2.90144, Z3 Z4], R[10.7582, Z4], R[2.90144, Z2 Z3], R[12.315, Z3],
R[2.90144, Z1 Z2], R[11.7785, Z2], R[2.90144, Z0 Z1], R[11.1418, Z1],
R[14.445, Z0], R[2.90144, Y5 Y6], R[2.90144, Y0 Y6], R[2.90144, Y4 Y5],
R[2.90144, Y3 Y4], R[2.90144, Y2 Y3], R[2.90144, Y1 Y2], R[2.90144, Y0 Y1],
R[2.90144, X5 X6], R[2.90144, X0 X6], R[2.90144, X4 X5], R[2.90144, X3 X4],
R[2.90144, X2 X3], R[2.90144, X1 X2], R[2.90144, X0 X1]}[t].{1, 0, 0, 0, 0, 0, 0, 0}

```

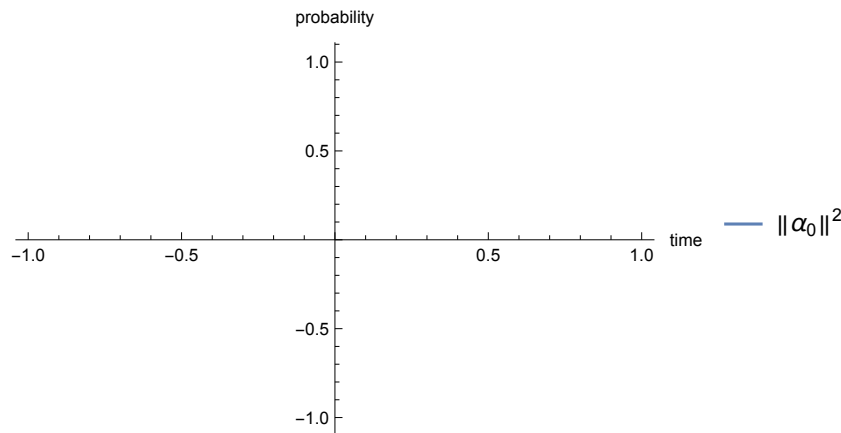
Here's how the probability of the basis states, with amplitudes  $\alpha_i$ , evolve from  $\delta_{i,0}$

```
probs = Abs[u[t] .  $\psi_0$ ]2;
```

```

Plot[probs, {t, 0, 4},
  PlotRange -> All,
  AxesLabel -> {"time", "probability"},
  PlotLegends -> Table[Norm[ $\alpha_i$ ]2, {i, 0, 2nqb - 1}]]

```



In quantum simulation, we are more often interested in the time evolution of the expectation value of some observable  $\langle \sigma(t) \rangle = \langle \psi(t) | \hat{\sigma} | \psi(t) \rangle$ . Consider this arbitrary Pauli operator:

```
 $\sigma = X_0 X_1 X_2$ ;
```

```
v = Simplify[
```

```

  Conjugate[ $\psi[t]$ ] . CalcPauliExpressionMatrix[ $\sigma$ ] .  $\psi[t]$ ,
  t >= 0]

```

```

Conjugate[{R[2.90144, X0 X1], R[2.90144, X1 X2], R[2.90144, X2 X3], R[2.90144, X3 X4],
R[2.90144, X4 X5], R[2.90144, X0 X6], R[2.90144, X5 X6], R[2.90144, Y0 Y1],
R[2.90144, Y1 Y2], R[2.90144, Y2 Y3], R[2.90144, Y3 Y4], R[2.90144, Y4 Y5],
R[2.90144, Y0 Y6], R[2.90144, Y5 Y6], R[14.445, Z0], R[11.1418, Z1],

```

$R[2.90144, Z_0 Z_1], R[11.7785, Z_2], R[2.90144, Z_1 Z_2], R[12.315, Z_3],$   
 $R[2.90144, Z_2 Z_3], R[10.7582, Z_4], R[2.90144, Z_3 Z_4], R[14.4127, Z_5],$   
 $R[2.90144, Z_4 Z_5], R[10.8217, Z_6], R[2.90144, Z_0 Z_6], R[5.80287, Z_5 Z_6],$   
 $R[2.90144, Z_0 Z_6], R[10.8217, Z_6], R[2.90144, Z_4 Z_5], R[14.4127, Z_5],$   
 $R[2.90144, Z_3 Z_4], R[10.7582, Z_4], R[2.90144, Z_2 Z_3], R[12.315, Z_3],$   
 $R[2.90144, Z_1 Z_2], R[11.7785, Z_2], R[2.90144, Z_0 Z_1], R[11.1418, Z_1],$   
 $R[14.445, Z_0], R[2.90144, Y_5 Y_6], R[2.90144, Y_0 Y_6], R[2.90144, Y_4 Y_5],$   
 $R[2.90144, Y_3 Y_4], R[2.90144, Y_2 Y_3], R[2.90144, Y_1 Y_2], R[2.90144, Y_0 Y_1],$   
 $R[2.90144, X_5 X_6], R[2.90144, X_0 X_6], R[2.90144, X_4 X_5], R[2.90144, X_3 X_4],$   
 $R[2.90144, X_2 X_3], R[2.90144, X_1 X_2], R[2.90144, X_0 X_1], R[2.90144, X_0 X_1],$   
 $R[2.90144, X_1 X_2], R[2.90144, X_2 X_3], R[2.90144, X_3 X_4], R[2.90144, X_4 X_5],$   
 $R[2.90144, X_0 X_6], R[2.90144, X_5 X_6], R[2.90144, Y_0 Y_1], R[2.90144, Y_1 Y_2],$   
 $R[2.90144, Y_2 Y_3], R[2.90144, Y_3 Y_4], R[2.90144, Y_4 Y_5], R[2.90144, Y_0 Y_6],$   
 $R[2.90144, Y_5 Y_6], R[14.445, Z_0], R[11.1418, Z_1], R[2.90144, Z_0 Z_1],$   
 $R[11.7785, Z_2], R[2.90144, Z_1 Z_2], R[12.315, Z_3], R[2.90144, Z_2 Z_3],$   
 $R[10.7582, Z_4], R[2.90144, Z_3 Z_4], R[14.4127, Z_5], R[2.90144, Z_4 Z_5],$   
 $R[10.8217, Z_6], R[2.90144, Z_0 Z_6], R[5.80287, Z_5 Z_6], R[2.90144, Z_0 Z_6],$   
 $R[10.8217, Z_6], R[2.90144, Z_4 Z_5], R[14.4127, Z_5], R[2.90144, Z_3 Z_4],$   
 $R[10.7582, Z_4], R[2.90144, Z_2 Z_3], R[12.315, Z_3], R[2.90144, Z_1 Z_2],$   
 $R[11.7785, Z_2], R[2.90144, Z_0 Z_1], R[11.1418, Z_1], R[14.445, Z_0],$   
 $R[2.90144, Y_5 Y_6], R[2.90144, Y_0 Y_6], R[2.90144, Y_4 Y_5], R[2.90144, Y_3 Y_4],$   
 $R[2.90144, Y_2 Y_3], R[2.90144, Y_1 Y_2], R[2.90144, Y_0 Y_1], R[2.90144, X_5 X_6],$   
 $R[2.90144, X_0 X_6], R[2.90144, X_4 X_5], R[2.90144, X_3 X_4], R[2.90144, X_2 X_3],$   
 $R[2.90144, X_1 X_2], R[2.90144, X_0 X_1], R[-4.60574, X_0 X_1], R[-4.60574, X_1 X_2],$   
 $R[-4.60574, X_2 X_3], R[-4.60574, X_3 X_4], R[-4.60574, X_4 X_5], R[-4.60574, X_0 X_6],$   
 $R[-4.60574, X_5 X_6], R[-4.60574, Y_0 Y_1], R[-4.60574, Y_1 Y_2], R[-4.60574, Y_2 Y_3],$   
 $R[-4.60574, Y_3 Y_4], R[-4.60574, Y_4 Y_5], R[-4.60574, Y_0 Y_6], R[-4.60574, Y_5 Y_6],$   
 $R[-22.93, Z_0], R[-17.6866, Z_1], R[-4.60574, Z_0 Z_1], R[-18.6972, Z_2],$   
 $R[-4.60574, Z_1 Z_2], R[-19.5488, Z_3], R[-4.60574, Z_2 Z_3], R[-17.0776, Z_4],$   
 $R[-4.60574, Z_3 Z_4], R[-22.8787, Z_5], R[-4.60574, Z_4 Z_5], R[-17.1783, Z_6],$   
 $R[-4.60574, Z_0 Z_6], R[-9.21148, Z_5 Z_6], R[-4.60574, Z_0 Z_6], R[-17.1783, Z_6],$   
 $R[-4.60574, Z_4 Z_5], R[-22.8787, Z_5], R[-4.60574, Z_3 Z_4], R[-17.0776, Z_4],$   
 $R[-4.60574, Z_2 Z_3], R[-19.5488, Z_3], R[-4.60574, Z_1 Z_2], R[-18.6972, Z_2],$   
 $R[-4.60574, Z_0 Z_1], R[-17.6866, Z_1], R[-22.93, Z_0], R[-4.60574, Y_5 Y_6],$   
 $R[-4.60574, Y_0 Y_6], R[-4.60574, Y_4 Y_5], R[-4.60574, Y_3 Y_4], R[-4.60574, Y_2 Y_3],$   
 $R[-4.60574, Y_1 Y_2], R[-4.60574, Y_0 Y_1], R[-4.60574, X_5 X_6], R[-4.60574, X_0 X_6],$   
 $R[-4.60574, X_4 X_5], R[-4.60574, X_3 X_4], R[-4.60574, X_2 X_3], R[-4.60574, X_1 X_2],$   
 $R[-4.60574, X_0 X_1], R[2.90144, X_0 X_1], R[2.90144, X_1 X_2], R[2.90144, X_2 X_3],$   
 $R[2.90144, X_3 X_4], R[2.90144, X_4 X_5], R[2.90144, X_0 X_6], R[2.90144, X_5 X_6],$   
 $R[2.90144, Y_0 Y_1], R[2.90144, Y_1 Y_2], R[2.90144, Y_2 Y_3], R[2.90144, Y_3 Y_4],$   
 $R[2.90144, Y_4 Y_5], R[2.90144, Y_0 Y_6], R[2.90144, Y_5 Y_6], R[14.445, Z_0],$   
 $R[11.1418, Z_1], R[2.90144, Z_0 Z_1], R[11.7785, Z_2], R[2.90144, Z_1 Z_2],$   
 $R[12.315, Z_3], R[2.90144, Z_2 Z_3], R[10.7582, Z_4], R[2.90144, Z_3 Z_4],$   
 $R[14.4127, Z_5], R[2.90144, Z_4 Z_5], R[10.8217, Z_6], R[2.90144, Z_0 Z_6],$   
 $R[5.80287, Z_5 Z_6], R[2.90144, Z_0 Z_6], R[10.8217, Z_6], R[2.90144, Z_4 Z_5],$   
 $R[14.4127, Z_5], R[2.90144, Z_3 Z_4], R[10.7582, Z_4], R[2.90144, Z_2 Z_3],$   
 $R[12.315, Z_3], R[2.90144, Z_1 Z_2], R[11.7785, Z_2], R[2.90144, Z_0 Z_1],$

```

R[11.1418, Z1], R[14.445, Z0], R[2.90144, Y5 Y6], R[2.90144, Y0 Y6],
R[2.90144, Y4 Y5], R[2.90144, Y3 Y4], R[2.90144, Y2 Y3], R[2.90144, Y1 Y2],
R[2.90144, Y0 Y1], R[2.90144, X5 X6], R[2.90144, X0 X6], R[2.90144, X4 X5],
R[2.90144, X3 X4], R[2.90144, X2 X3], R[2.90144, X1 X2], R[2.90144, X0 X1],
R[2.90144, X0 X1], R[2.90144, X1 X2], R[2.90144, X2 X3], R[2.90144, X3 X4],
R[2.90144, X4 X5], R[2.90144, X0 X6], R[2.90144, X5 X6], R[2.90144, Y0 Y1],
R[2.90144, Y1 Y2], R[2.90144, Y2 Y3], R[2.90144, Y3 Y4], R[2.90144, Y4 Y5],
R[2.90144, Y0 Y6], R[2.90144, Y5 Y6], R[14.445, Z0], R[11.1418, Z1],
R[2.90144, Z0 Z1], R[11.7785, Z2], R[2.90144, Z1 Z2], R[12.315, Z3],
R[2.90144, Z2 Z3], R[10.7582, Z4], R[2.90144, Z3 Z4], R[14.4127, Z5],
R[2.90144, Z4 Z5], R[10.8217, Z6], R[2.90144, Z0 Z6], R[5.80287, Z5 Z6],
R[2.90144, Z0 Z6], R[10.8217, Z6], R[2.90144, Z4 Z5], R[14.4127, Z5],
R[2.90144, Z3 Z4], R[10.7582, Z4], R[2.90144, Z2 Z3], R[12.315, Z3],
R[2.90144, Z1 Z2], R[11.7785, Z2], R[2.90144, Z0 Z1], R[11.1418, Z1],
R[14.445, Z0], R[2.90144, Y5 Y6], R[2.90144, Y0 Y6], R[2.90144, Y4 Y5],
R[2.90144, Y3 Y4], R[2.90144, Y2 Y3], R[2.90144, Y1 Y2], R[2.90144, Y0 Y1],
R[2.90144, X5 X6], R[2.90144, X0 X6], R[2.90144, X4 X5], R[2.90144, X3 X4],
R[2.90144, X2 X3], R[2.90144, X1 X2], R[2.90144, X0 X1] } [t].

```

```

{1, 0, 0, 0, 0, 0, 0, 0}].SparseArray[ Specified elements: 8  
Dimensions: {8, 8}] .

```

```

{R[2.90144, X0 X1], R[2.90144, X1 X2], R[2.90144, X2 X3],
R[2.90144, X3 X4], R[2.90144, X4 X5],
R[2.90144, X0 X6], R[2.90144, X5 X6],
R[2.90144, Y0 Y1], R[2.90144, Y1 Y2],
R[2.90144, Y2 Y3], R[2.90144, Y3 Y4],
R[2.90144, Y4 Y5], R[2.90144, Y0 Y6],
R[2.90144, Y5 Y6], R[14.445, Z0], R[11.1418, Z1],
R[2.90144, Z0 Z1], R[11.7785, Z2],
R[2.90144, Z1 Z2], R[12.315, Z3], R[2.90144, Z2 Z3],
R[10.7582, Z4], R[2.90144, Z3 Z4], R[14.4127, Z5],
R[2.90144, Z4 Z5], R[10.8217, Z6], R[2.90144, Z0 Z6],
R[5.80287, Z5 Z6], R[2.90144, Z0 Z6], R[10.8217, Z6],
R[2.90144, Z4 Z5], R[14.4127, Z5], R[2.90144, Z3 Z4],
R[10.7582, Z4], R[2.90144, Z2 Z3], R[12.315, Z3],
R[2.90144, Z1 Z2], R[11.7785, Z2], R[2.90144, Z0 Z1],
R[11.1418, Z1], R[14.445, Z0], R[2.90144, Y5 Y6],
R[2.90144, Y0 Y6], R[2.90144, Y4 Y5], R[2.90144, Y3 Y4],
R[2.90144, Y2 Y3], R[2.90144, Y1 Y2], R[2.90144, Y0 Y1],
R[2.90144, X5 X6], R[2.90144, X0 X6], R[2.90144, X4 X5],
R[2.90144, X3 X4], R[2.90144, X2 X3], R[2.90144, X1 X2],
R[2.90144, X0 X1], R[2.90144, X0 X1], R[2.90144, X1 X2],
R[2.90144, X2 X3], R[2.90144, X3 X4], R[2.90144, X4 X5],
R[2.90144, X0 X6], R[2.90144, X5 X6], R[2.90144, Y0 Y1],
R[2.90144, Y1 Y2], R[2.90144, Y2 Y3], R[2.90144, Y3 Y4],
R[2.90144, Y4 Y5], R[2.90144, Y0 Y6], R[2.90144, Y5 Y6],
R[14.445, Z0], R[11.1418, Z1], R[2.90144, Z0 Z1],

```

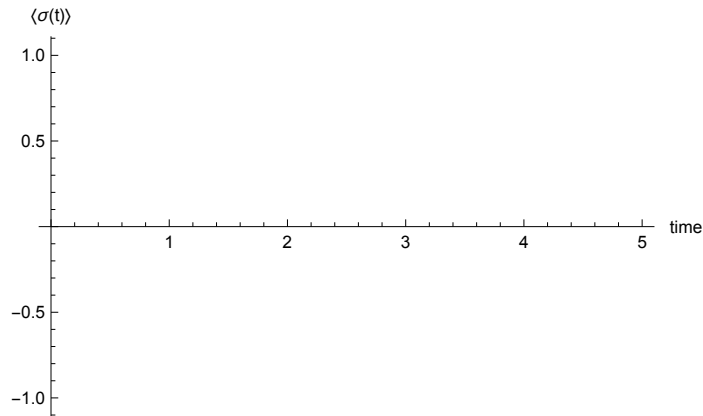
$R[11.7785, Z_2]$ ,  $R[2.90144, Z_1 Z_2]$ ,  $R[12.315, Z_3]$ ,  
 $R[2.90144, Z_2 Z_3]$ ,  $R[10.7582, Z_4]$ ,  $R[2.90144, Z_3 Z_4]$ ,  
 $R[14.4127, Z_5]$ ,  $R[2.90144, Z_4 Z_5]$ ,  $R[10.8217, Z_6]$ ,  
 $R[2.90144, Z_0 Z_6]$ ,  $R[5.80287, Z_5 Z_6]$ ,  $R[2.90144, Z_0 Z_6]$ ,  
 $R[10.8217, Z_6]$ ,  $R[2.90144, Z_4 Z_5]$ ,  $R[14.4127, Z_5]$ ,  
 $R[2.90144, Z_3 Z_4]$ ,  $R[10.7582, Z_4]$ ,  $R[2.90144, Z_2 Z_3]$ ,  
 $R[12.315, Z_3]$ ,  $R[2.90144, Z_1 Z_2]$ ,  $R[11.7785, Z_2]$ ,  
 $R[2.90144, Z_0 Z_1]$ ,  $R[11.1418, Z_1]$ ,  $R[14.445, Z_0]$ ,  
 $R[2.90144, Y_5 Y_6]$ ,  $R[2.90144, Y_0 Y_6]$ ,  $R[2.90144, Y_4 Y_5]$ ,  
 $R[2.90144, Y_3 Y_4]$ ,  $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_1 Y_2]$ ,  
 $R[2.90144, Y_0 Y_1]$ ,  $R[2.90144, X_5 X_6]$ ,  $R[2.90144, X_0 X_6]$ ,  
 $R[2.90144, X_4 X_5]$ ,  $R[2.90144, X_3 X_4]$ ,  $R[2.90144, X_2 X_3]$ ,  
 $R[2.90144, X_1 X_2]$ ,  $R[2.90144, X_0 X_1]$ ,  $R[-4.60574, X_0 X_1]$ ,  
 $R[-4.60574, X_1 X_2]$ ,  $R[-4.60574, X_2 X_3]$ ,  $R[-4.60574, X_3 X_4]$ ,  
 $R[-4.60574, X_4 X_5]$ ,  $R[-4.60574, X_0 X_6]$ ,  $R[-4.60574, X_5 X_6]$ ,  
 $R[-4.60574, Y_0 Y_1]$ ,  $R[-4.60574, Y_1 Y_2]$ ,  $R[-4.60574, Y_2 Y_3]$ ,  
 $R[-4.60574, Y_3 Y_4]$ ,  $R[-4.60574, Y_4 Y_5]$ ,  $R[-4.60574, Y_0 Y_6]$ ,  
 $R[-4.60574, Y_5 Y_6]$ ,  $R[-22.93, Z_0]$ ,  $R[-17.6866, Z_1]$ ,  
 $R[-4.60574, Z_0 Z_1]$ ,  $R[-18.6972, Z_2]$ ,  $R[-4.60574, Z_1 Z_2]$ ,  
 $R[-19.5488, Z_3]$ ,  $R[-4.60574, Z_2 Z_3]$ ,  $R[-17.0776, Z_4]$ ,  
 $R[-4.60574, Z_3 Z_4]$ ,  $R[-22.8787, Z_5]$ ,  $R[-4.60574, Z_4 Z_5]$ ,  
 $R[-17.1783, Z_6]$ ,  $R[-4.60574, Z_0 Z_6]$ ,  $R[-9.21148, Z_5 Z_6]$ ,  
 $R[-4.60574, Z_0 Z_6]$ ,  $R[-17.1783, Z_6]$ ,  $R[-4.60574, Z_4 Z_5]$ ,  
 $R[-22.8787, Z_5]$ ,  $R[-4.60574, Z_3 Z_4]$ ,  $R[-17.0776, Z_4]$ ,  
 $R[-4.60574, Z_2 Z_3]$ ,  $R[-19.5488, Z_3]$ ,  $R[-4.60574, Z_1 Z_2]$ ,  
 $R[-18.6972, Z_2]$ ,  $R[-4.60574, Z_0 Z_1]$ ,  $R[-17.6866, Z_1]$ ,  
 $R[-22.93, Z_0]$ ,  $R[-4.60574, Y_5 Y_6]$ ,  $R[-4.60574, Y_0 Y_6]$ ,  
 $R[-4.60574, Y_4 Y_5]$ ,  $R[-4.60574, Y_3 Y_4]$ ,  $R[-4.60574, Y_2 Y_3]$ ,  
 $R[-4.60574, Y_1 Y_2]$ ,  $R[-4.60574, Y_0 Y_1]$ ,  $R[-4.60574, X_5 X_6]$ ,  
 $R[-4.60574, X_0 X_6]$ ,  $R[-4.60574, X_4 X_5]$ ,  $R[-4.60574, X_3 X_4]$ ,  
 $R[-4.60574, X_2 X_3]$ ,  $R[-4.60574, X_1 X_2]$ ,  $R[-4.60574, X_0 X_1]$ ,  
 $R[2.90144, X_0 X_1]$ ,  $R[2.90144, X_1 X_2]$ ,  $R[2.90144, X_2 X_3]$ ,  
 $R[2.90144, X_3 X_4]$ ,  $R[2.90144, X_4 X_5]$ ,  $R[2.90144, X_0 X_6]$ ,  
 $R[2.90144, X_5 X_6]$ ,  $R[2.90144, Y_0 Y_1]$ ,  $R[2.90144, Y_1 Y_2]$ ,  
 $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_3 Y_4]$ ,  $R[2.90144, Y_4 Y_5]$ ,  
 $R[2.90144, Y_0 Y_6]$ ,  $R[2.90144, Y_5 Y_6]$ ,  $R[14.445, Z_0]$ ,  
 $R[11.1418, Z_1]$ ,  $R[2.90144, Z_0 Z_1]$ ,  $R[11.7785, Z_2]$ ,  
 $R[2.90144, Z_1 Z_2]$ ,  $R[12.315, Z_3]$ ,  $R[2.90144, Z_2 Z_3]$ ,  
 $R[10.7582, Z_4]$ ,  $R[2.90144, Z_3 Z_4]$ ,  $R[14.4127, Z_5]$ ,  
 $R[2.90144, Z_4 Z_5]$ ,  $R[10.8217, Z_6]$ ,  $R[2.90144, Z_0 Z_6]$ ,  
 $R[5.80287, Z_5 Z_6]$ ,  $R[2.90144, Z_0 Z_6]$ ,  $R[10.8217, Z_6]$ ,  
 $R[2.90144, Z_4 Z_5]$ ,  $R[14.4127, Z_5]$ ,  $R[2.90144, Z_3 Z_4]$ ,  
 $R[10.7582, Z_4]$ ,  $R[2.90144, Z_2 Z_3]$ ,  $R[12.315, Z_3]$ ,  
 $R[2.90144, Z_1 Z_2]$ ,  $R[11.7785, Z_2]$ ,  $R[2.90144, Z_0 Z_1]$ ,  
 $R[11.1418, Z_1]$ ,  $R[14.445, Z_0]$ ,  $R[2.90144, Y_5 Y_6]$ ,  
 $R[2.90144, Y_0 Y_6]$ ,  $R[2.90144, Y_4 Y_5]$ ,  $R[2.90144, Y_3 Y_4]$ ,  
 $R[2.90144, Y_2 Y_3]$ ,  $R[2.90144, Y_1 Y_2]$ ,  $R[2.90144, Y_0 Y_1]$ ,

```

R[2.90144, X5 X6], R[2.90144, X0 X6], R[2.90144, X4 X5],
R[2.90144, X3 X4], R[2.90144, X2 X3], R[2.90144, X1 X2],
R[2.90144, X0 X1], R[2.90144, X0 X1], R[2.90144, X1 X2],
R[2.90144, X2 X3], R[2.90144, X3 X4], R[2.90144, X4 X5],
R[2.90144, X0 X6], R[2.90144, X5 X6], R[2.90144, Y0 Y1],
R[2.90144, Y1 Y2], R[2.90144, Y2 Y3], R[2.90144, Y3 Y4],
R[2.90144, Y4 Y5], R[2.90144, Y0 Y6], R[2.90144, Y5 Y6],
R[14.445, Z0], R[11.1418, Z1], R[2.90144, Z0 Z1], R[11.7785, Z2],
R[2.90144, Z1 Z2], R[12.315, Z3], R[2.90144, Z2 Z3],
R[10.7582, Z4], R[2.90144, Z3 Z4], R[14.4127, Z5],
R[2.90144, Z4 Z5], R[10.8217, Z6], R[2.90144, Z0 Z6],
R[5.80287, Z5 Z6], R[2.90144, Z0 Z6], R[10.8217, Z6],
R[2.90144, Z4 Z5], R[14.4127, Z5], R[2.90144, Z3 Z4],
R[10.7582, Z4], R[2.90144, Z2 Z3], R[12.315, Z3], R[2.90144, Z1 Z2],
R[11.7785, Z2], R[2.90144, Z0 Z1], R[11.1418, Z1], R[14.445, Z0],
R[2.90144, Y5 Y6], R[2.90144, Y0 Y6], R[2.90144, Y4 Y5],
R[2.90144, Y3 Y4], R[2.90144, Y2 Y3], R[2.90144, Y1 Y2],
R[2.90144, Y0 Y1], R[2.90144, X5 X6], R[2.90144, X0 X6],
R[2.90144, X4 X5], R[2.90144, X3 X4], R[2.90144, X2 X3],
R[2.90144, X1 X2], R[2.90144, X0 X1] } [t] . {1, 0, 0, 0, 0, 0, 0, 0}

```

```
Plot[v, {t, 0, 5}, AxesLabel → {"time", "⟨σ(t)⟩"}]
```



## Numerical

Let's switch to numerical simulation and choose a more interesting, physically-meaningful problem. We will simulate an Ising spin-ring, nominated for its potential utility in demonstrating quantum advantage, with (periodic) Hamiltonian:

$$\hat{H} = \sum_{i=0}^{n_{\text{Qb}}-1} \vec{\sigma}_i \cdot \vec{\sigma}_{i+1} + B \hat{Z}_i + d_i \hat{Z}_i$$

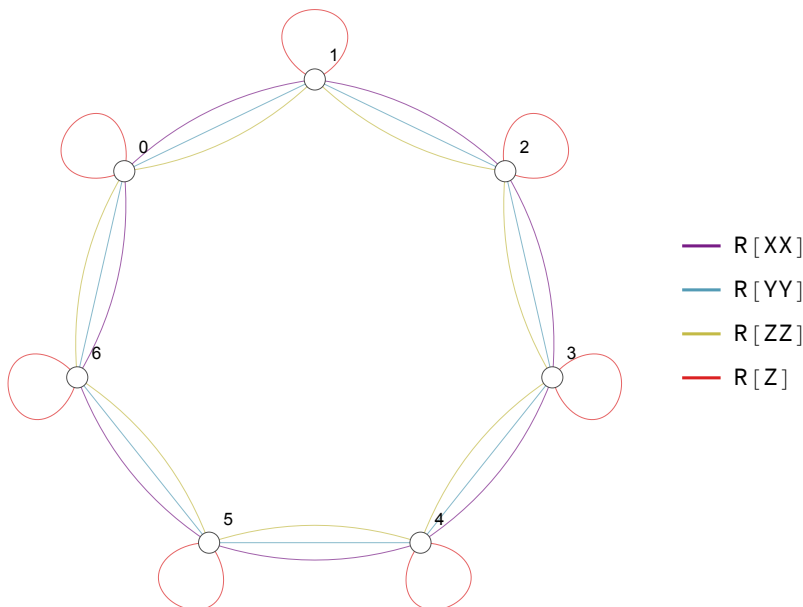
where  $B = 4$  is the strength of a transverse magnetic field, and  $d_i \in [-d, d]$

```
nQb = 7;
Clear[h]
```

```
h[d_] = Expand[
  Sum[(4 + d RandomReal[{-1, 1}]) Zi, {i, 0, nQb - 1}] +
  Sum[si sMod[i+1,nQb], {i, 0, nQb - 1}, {s, {X, Y, Z}}]]
X0 X1 + X1 X2 + X2 X3 + X3 X4 + X4 X5 + X0 X6 + X5 X6 + Y0 Y1 + Y1 Y2 + Y2 Y3 + Y3 Y4 +
Y4 Y5 + Y0 Y6 + Y5 Y6 + 4 Z0 + 0.78744 d Z0 + 4 Z1 - 0.117855 d Z1 + Z0 Z1 + 4 Z2 +
0.359771 d Z2 + Z1 Z2 + 4 Z3 + 0.914525 d Z3 + Z2 Z3 + 4 Z4 - 0.790871 d Z4 +
Z3 Z4 + 4 Z5 - 0.258145 d Z5 + Z4 Z5 + 4 Z6 + 0.769056 d Z6 + Z0 Z6 + Z5 Z6
```

A quick way to confirm the ring topology of this system is to plot the connectivity of its Trotter circuit.

```
DrawCircuitTopology @ GetKnownCircuit["Trotter", h[1], 1, 1, t]
```



The uniformly random real scalars  $d_i \in [-d, d]$  in  $\hat{H}$  vary the effective magnetic field experienced by the spins. The scalar  $d > 0$  is the strength of the *disorder* of the field.

```
CalcPauliStringMinEigVal @ h[1]
```

```
-22.6639
```

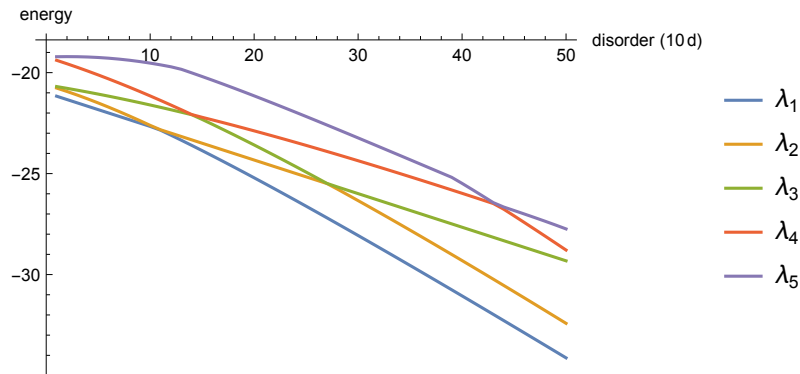
```
CalcPauliStringMinEigVal @ h[10]
```

```
-49.9362
```

This greatly affects the spectrum  $\lambda_j$

```
vals = Transpose @ Table[
  - Eigenvalues[
    - CalcPauliExpressionMatrix @ h[d], 5,
    Method → {"Arnoldi", "Criteria" → "RealPart"}],
  {d, .1, 5, .1}];
```

```
ListLinePlot[
  vals,
  AxesLabel → {"disorder (10 d)", "energy"},
  PlotLegends → Table[ $\lambda_i$ , {i, 5}]]
```



To simulate time evolution under  $\hat{H}$ , we will make use of its Z-basis matrix representation. Here we use a Mathematica trick to save the matrix being computed for a given value of  $d$  so that repeated calls to `hMatr[d]` below don't repeat the computation.

```
Clear[hMatr]
hMatr[d_] := hMatr[d] = CalcPauliExpressionMatrix @ h[d]

First @ Timing @ hMatr[.1]
0.070674

First @ Timing @ hMatr[.1]
First @ Timing @ hMatr[.1]
First @ Timing @ hMatr[.1]
8. × 10-6
5. × 10-6
4. × 10-6
```

Let's consider an initial state whereby *half* of the spins are excited against the external field; this is the "Néel ordered state".

```
inψ = CreateQureg[nQb];
ApplyCircuit[inψ, Table[Xq, {q, 0, nQb - 1, 2}]];

GetQuregState[inψ, "ZBasisKets"]
|1010101⟩
```



We now *numerically* construct the time evolution operator in order to obtain future states.

```
trueψ = CreateQureg[nQb];
```

```
setTrueState[trueψ_, inψ_, hMatr_, t_] :=  
  SetQuregMatrix[trueψ, MatrixExp[-i t hMatr] . GetQuregState[inψ]]
```

Time evolution under this Hamiltonian quickly excites the other spins:

```
setTrueState[trueψ, inψ, hMatr[.1], 0];  
GetQuregState[trueψ, "ZBasisKets"]  
|1010101⟩  
  
setTrueState[trueψ, inψ, hMatr[.1], 10-6];  
GetQuregState[trueψ, "ZBasisKets"] // Chop  
(0. - 2. × 10-6 i) |0110101⟩ - (0. + 2. × 10-6 i) |1001101⟩ -  
(0. + 2. × 10-6 i) |1010011⟩ + (1. + 9.05869 × 10-6 i) |1010101⟩ -  
(0. + 2. × 10-6 i) |1010110⟩ - (0. + 2. × 10-6 i) |1011001⟩ - (0. + 2. × 10-6 i) |1100101⟩  
  
setTrueState[trueψ, inψ, hMatr[.1], 1];  
GetQuregState[trueψ, "ZBasisKets"] // Chop  
(-0.0136532 + 0.0297343 i) |0001111⟩ - (0.0847831 + 0.191806 i) |0010111⟩ +  
(0.0643967 - 0.00517651 i) |0011011⟩ - (0.0375359 + 0.126292 i) |0011101⟩ -  
(0.106854 - 0.0125772 i) |0011110⟩ - (0.0920545 - 0.038742 i) |0100111⟩ -  
(0.0489765 - 0.118921 i) |0101011⟩ - (0.214832 - 0.36877 i) |0101101⟩ +  
(0.156766 - 0.0217606 i) |0101110⟩ + (0.0075156 - 0.0859561 i) |0110011⟩
```

In this system, we are interested in the single-site magnetisation of the spins,  $\langle Z_i \rangle$ .

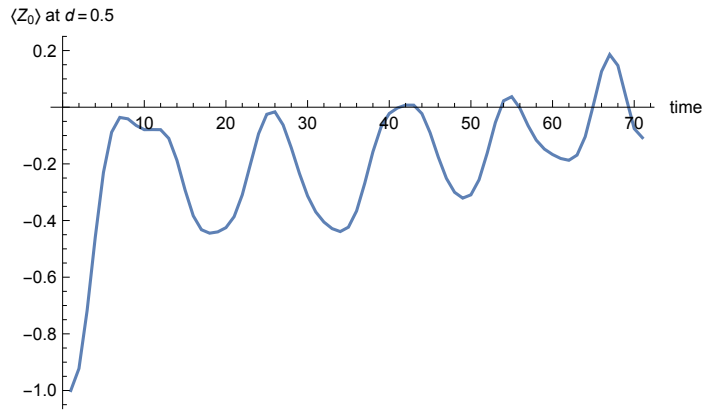
```
φ = CreateQureg[nQb];  
CalcExpecPauliString[trueψ, Z0, φ]  
-0.157639
```

Let's check how the magnetisation of the first qubit (which started *anti*-aligned with the transverse magnetic field) evolves in time, for a specific choice of disorder  $d$ .

```
pureData = Table[
  setTrueState[trueψ, inψ, hMatr[.5], t];
  CalcExpecPauliString[trueψ, Z0, ϕ],
  {t, 0, nQb, .1}];

ListLinePlot[pureData, AxesLabel → {"time", "<Z0

```

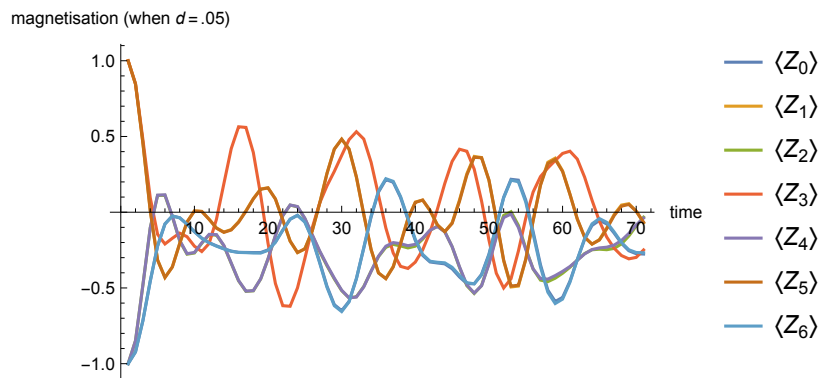


Here's how the magnetisation of *all* spins evolve in time, when the field has small disorder.

```
data = Transpose@ Table[
  setTrueState[trueψ, inψ, hMatr[.01], t];
  CalcExpecPauliString[trueψ, Zq, ϕ],
  {t, 0, nQb, .1},
  {q, 0, nQb - 1}];

ListLinePlot[data,
  AxesLabel → {"time", "magnetisation (when d = .05)"},
  PlotLegends → Table[Row@{"<Zi

```



We see that the strong  $\pm 1$  magnetisation of our initial state is quickly thermalized, and averages around zero. As reported here, the reason that this system is interesting is because as the disorder  $d$  of the transverse magnetic field is increased, the spins take significantly *longer* to thermalize. A strongly disordered external field sees the spins remain *localized*, retaining information about their original magnetisation. Here's the magnetisation in-time when the disorder is  $d = 3...$

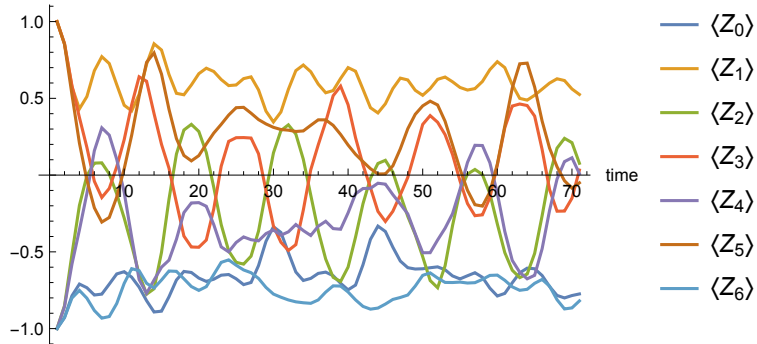
```

data = Transpose@ Table[
  setTrueState[true $\psi$ , in $\psi$ , hMatr[5], t];
  CalcExpecPauliString[true $\psi$ , Zq,  $\phi$ ],
  {t, 0, nQb, .1},
  {q, 0, nQb - 1}];

ListLinePlot[data,
  AxesLabel → {"time", "magnetisation (when d = 3)"},
  PlotLegends → Table[Row@{"<", Zi, ">"}, {i, 0, nQb - 1}]]

```

magnetisation (when  $d=3$ )



and when  $d = 10$ ...

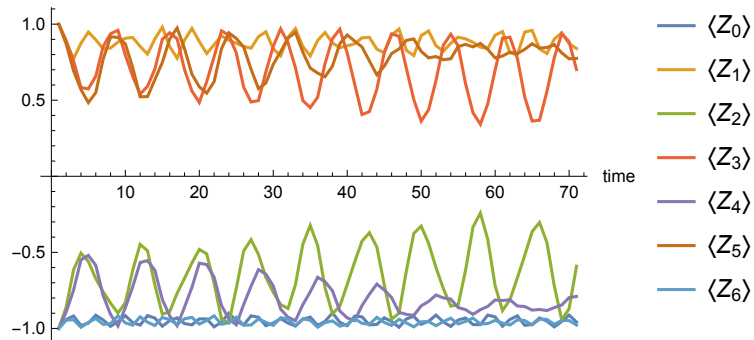
```

data = Transpose@ Table[
  setTrueState[true $\psi$ , in $\psi$ , hMatr[10], t];
  CalcExpecPauliString[true $\psi$ , Zq,  $\phi$ ],
  {t, 0, nQb, .1},
  {q, 0, nQb - 1}];

ListLinePlot[data,
  AxesLabel → {"time", "magnetisation (when d = 10)"},
  PlotLegends → Table[Row@{"<", Zi, ">"}, {i, 0, nQb - 1}]]

```

magnetisation (when  $d=10$ )



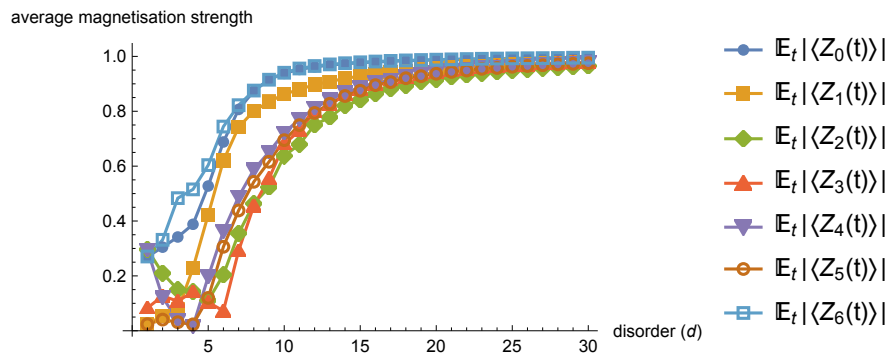
There is in fact a *phase transition* in the magnetisation occurring over  $d$ .

```

data = Transpose @ Table[
  Abs /@ Mean /@ Transpose @ Table[
    setTrueState[trueψ, inψ, hMatr[d], t];
    CalcExpecPauliString[trueψ, Zq, ϕ],
    {t, 0, nQb / 2, .1},
    {q, 0, nQb - 1}],
  {d, .01, 30, 1}];

ListLinePlot[data,
  AxesLabel → {"disorder (d)", "average magnetisation strength"},
  PlotLegends → Table[Row@{" $\mathbb{E}_t | \langle Z_i(t) \rangle |$ "}, {i, 0, nQb - 1}],
  PlotMarkers → Automatic
]

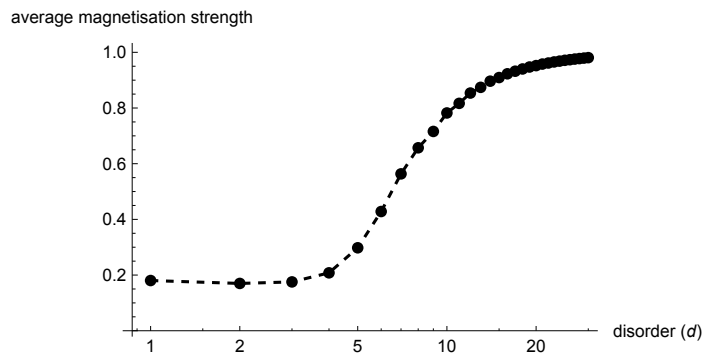
```



```

ListLogLinearPlot[
  Mean @ data,
  AxesLabel → {"disorder (d)", "average magnetisation strength"},
  Joined → True, PlotMarkers → Automatic,
  PlotStyle → Directive[Black, Dashed]
]

```



## Trotterisation

### Pure


Let's pretend the previous section's spin-ring Hamiltonian was sadly *too big* to process by the classical numerics above, though it remains tractable to describe as a Pauli string:

```
h1 = h[1]
```

```
X0 X1 + X1 X2 + X2 X3 + X3 X4 + X4 X5 + X0 X6 + X5 X6 + Y0 Y1 + Y1 Y2 + Y2 Y3 + Y3 Y4 + Y4 Y5 +
Y0 Y6 + Y5 Y6 + 4.78744 Z0 + 3.88215 Z1 + Z0 Z1 + 4.35977 Z2 + Z1 Z2 + 4.91452 Z3 +
Z2 Z3 + 3.20913 Z4 + Z3 Z4 + 3.74185 Z5 + Z4 Z5 + 4.76906 Z6 + Z0 Z6 + Z5 Z6
```

Suppose the Z-basis representation of  $\hat{H}$  is classically computationally intractable, so we could *not* evaluate this:

```
h1Matr = CalcPauliExpressionMatrix[h1]
```

```
SparseArray[  Specified elements: 1024  
Dimensions: {128, 128} ]
```

Imagine that we fortunately we have a quantum computer at our disposal, with which to perform quantum simulation! The canonical method of quantumly simulating the real-time unitary dynamics of a system is to evaluate the circuit produced by *Trotterising* its unitary time evolution operator:

$$e^{-i t \hat{H}} \approx \prod_i \hat{U}_i[t]$$

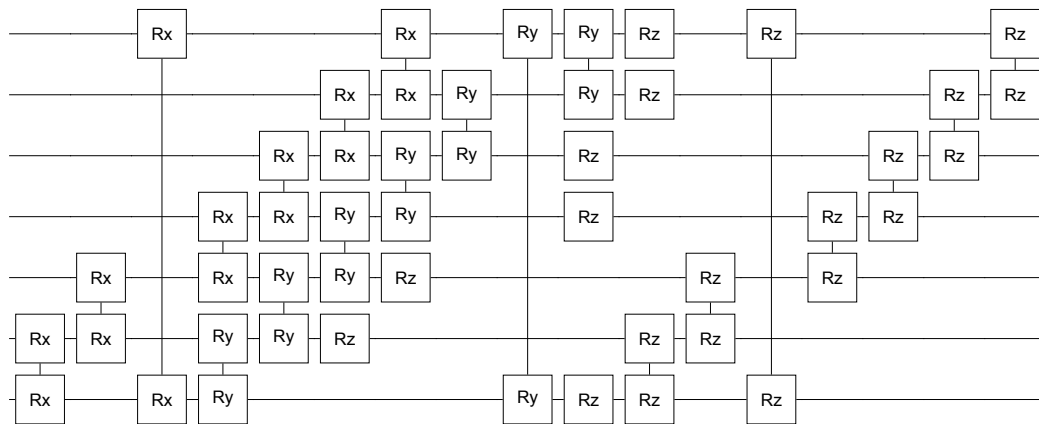
```
Clear[u]
```

```
u[t_] = GetKnownCircuit["Trotter", h1, 1, 1, t]
```

```
{R[2 t, X0 X1], R[2 t, X1 X2], R[2 t, X2 X3], R[2 t, X3 X4], R[2 t, X4 X5],
R[2 t, X0 X6], R[2 t, X5 X6], R[2 t, Y0 Y1], R[2 t, Y1 Y2], R[2 t, Y2 Y3],
R[2 t, Y3 Y4], R[2 t, Y4 Y5], R[2 t, Y0 Y6], R[2 t, Y5 Y6], R[9.57488 t, Z0],
R[7.76429 t, Z1], R[2 t, Z0 Z1], R[8.71954 t, Z2], R[2 t, Z1 Z2],
R[9.82905 t, Z3], R[2 t, Z2 Z3], R[6.41826 t, Z4], R[2 t, Z3 Z4],
R[7.48371 t, Z5], R[2 t, Z4 Z5], R[9.53811 t, Z6], R[2 t, Z0 Z6], R[2 t, Z5 Z6]}
```

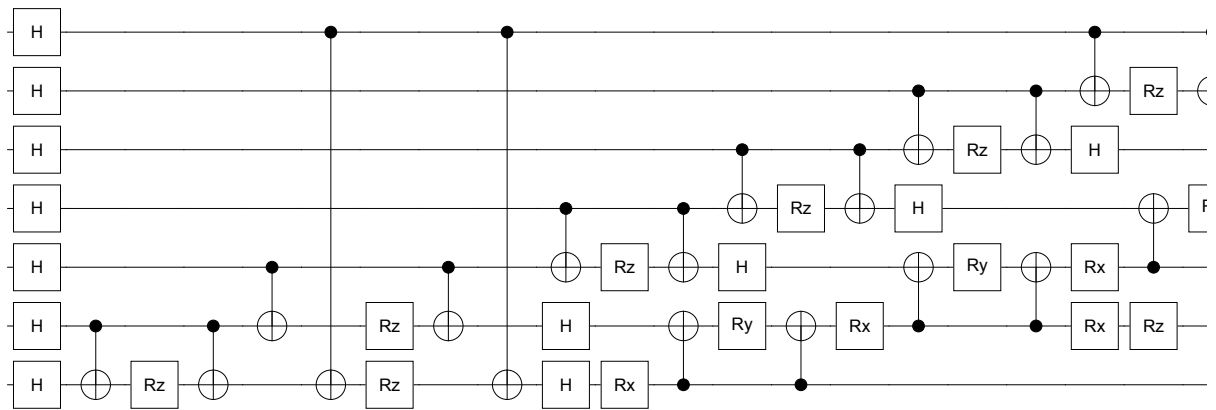
This is a circuit with gate parameters dependent upon the coefficients of our Hamiltonian, and the target simulation time  $t$ .

```
DrawCircuit @ u[t]
```

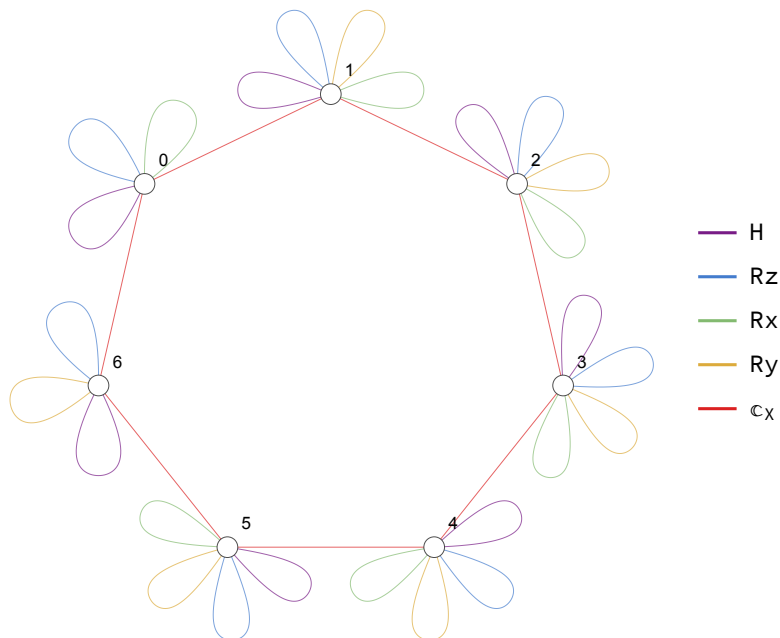


If necessary, we could recompile this circuit into the native operations of our hardware...

```
v = SimplifyCircuit @ RecompileCircuit[u[t], "SingleQubitAndCNOT"];
DrawCircuit[v]
```



```
DrawCircuitTopology @ v
```



but for convenience, let's assume our hardware can perform the original two-qubit Pauli gadgets. The Trotter circuit  $\hat{U}$ , applied to the initial state  $|\psi(0)\rangle$ , produces a direct approximation to the state  $|\psi(t)\rangle = e^{-it\hat{H}} |\psi(0)\rangle$

```
 $\psi$  = CreateQureg[nQb];
CloneQureg[ $\psi$ , in $\psi$ ];
GetQuregState[ $\psi$ , "ZBasisKets"]
|1010101>
```

```

τ = 0.1;
ApplyCircuit[ψ, u[τ]];
setTrueState[trueψ, inψ, h1Matr, τ];

```

```
CalcFidelity[ψ, trueψ]
```

```
0.994143
```

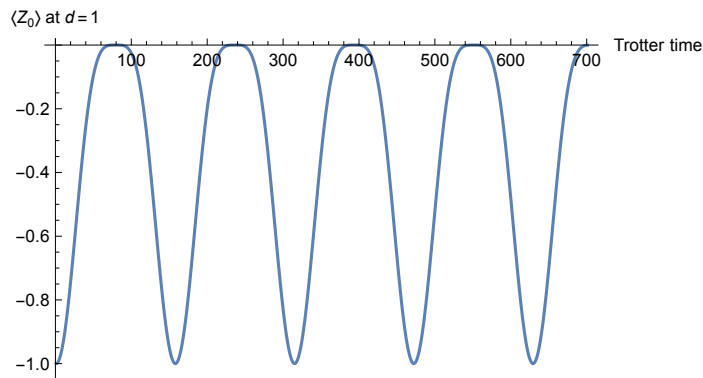
An experimentalist can ergo apply circuit  $\hat{U}(t)$ , with rotations informed by the desired simulation time  $t$ , and thereafter measure their observable of interest, like the spin-ring magnetisation.

```

data = Table[
  CloneQureg[ψ, inψ];
  ApplyCircuit[ψ, u[t]];
  CalcExpecPauliString[ψ, Z0, ϕ],
  {t, 0, nQb, .01}];

```

```
ListLinePlot[data, AxesLabel → {"Trotter time", "<Z0> at d = 1"}]
```



This doesn't look how we expected - it is suspiciously periodic (as the Trotter circuit *is* as a function of  $t$ ), whereas we earlier witnessed thermalisation. Indeed the fidelity is imperfect - Trotterisation can only *approximate* the evolution when the Hamiltonian contains non-commuting terms.

```

τ = 0.3;
ApplyCircuit[CloneQureg[ψ, inψ], u[τ]];
setTrueState[trueψ, inψ, h1Matr, τ];

```

```
CalcFidelity[ψ, trueψ]
```

```
0.768705
```

The fidelity  $\left| \langle \psi(0) | e^{it\hat{H}} \hat{U}(t) | \psi(0) \rangle \right|^2$  drops quickly with increasing  $t$ .

```
Bra[ψ]
```

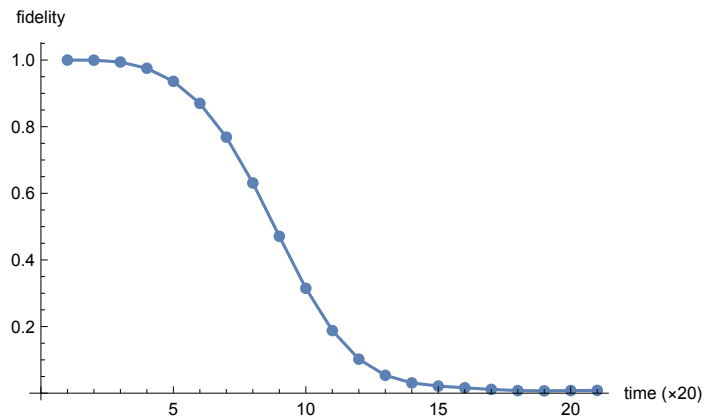
```
<3|
```

```

fid = Table[
  ApplyCircuit[CloneQureg[ψ, inψ], u[t]];
  setTrueState[trueψ, inψ, h1Matr, t];
  CalcFidelity[ψ, trueψ],
  {t, 0, 1, .05}];

ListLinePlot[fid,
  AxesLabel → {"time (x20)", "fidelity"},
  PlotMarkers → Automatic
]

```



We can improve the fidelity by using more Trotter *repetitions*, or using a *higher order* method.

```

order = 4;
reps = 3;
u[t_] = GetKnownCircuit["Trotter", h1, order, reps, t]

```

$\left\{ R\left[\frac{t}{3(4-2^{2/3})}, X_0 X_1\right], R\left[\frac{t}{3(4-2^{2/3})}, X_1 X_2\right], R\left[\frac{t}{3(4-2^{2/3})}, X_2 X_3\right], R\left[\frac{t}{3(4-2^{2/3})}, X_3 X_4\right], \right.$   
 $\left. \dots 818 \dots, R\left[\frac{t}{3(4-2^{2/3})}, X_2 X_3\right], R\left[\frac{t}{3(4-2^{2/3})}, X_1 X_2\right], R\left[\frac{t}{3(4-2^{2/3})}, X_0 X_1\right] \right\}$

large output

show less

show more

show all

set size limit...



```

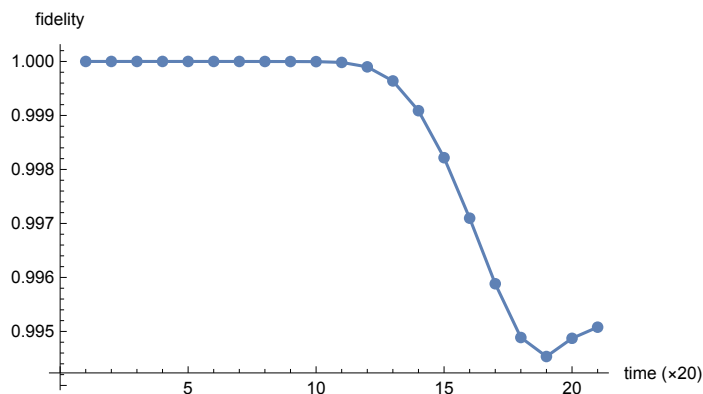
fid = Table[
  ApplyCircuit[CloneQureg[ $\psi$ , in $\psi$ ], u[t]];
  setTrueState[true $\psi$ , in $\psi$ , h1Matr, t];
  CalcFidelity[ $\psi$ , true $\psi$ ,
    {t, 0, 1, .05}];

```

```

ListLinePlot[fid,
  AxesLabel → {"time (x20)", "fidelity"},
  PlotMarkers → Automatic
]

```



Of course, this means increasing the number of gates in the circuit.

```

Length @ GetKnownCircuit["Trotter", h1, 4, 1, t]
275

```

```

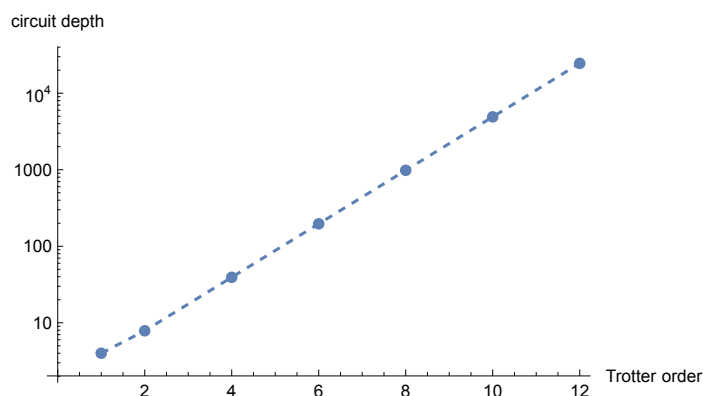
cost = Table[
  {order, Length @ GetKnownCircuit["Trotter", h1, order, 1, t] / nQb},
  {order, {1, 2, 4, 6, 8, 10, 12}}];

```

```

ListLogPlot[cost,
  AxesLabel → {"Trotter order", "circuit depth"},
  Joined → True, PlotMarkers → Automatic,
  PlotStyle → Directive[Dashed]
]

```



Let's simulate to fixed time  $t = nQb/2$ , and record the costs and performance of using Trotter

circuits of different order and repetitions.

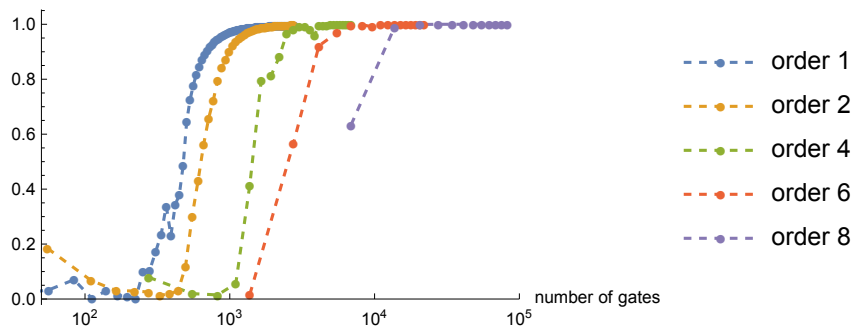
```
 $\tau$  = nQb / 2;
setTrueState[true $\psi$ , in $\psi$ , h1Matr,  $\tau$ ];

data = Table[
  u = GetKnownCircuit["Trotter", h1, order, reps, N@ $\tau$ ];
  ApplyCircuit[CloneQureg[ $\psi$ , in $\psi$ ], u];
  {Length[u], CalcFidelity[ $\psi$ , true $\psi$ ]},
  {order, {1, 2, 4, 6, 8}},
  {reps, 1, Floor[100 / order]}];
```

We can see that higher-order Trotter quickly becomes *expensive*:

```
ListLogLinearPlot[data,
  AxesLabel → {"number of gates", "fidelity at t=nQb/2"},
  Joined → True, PlotRange → {{.5 × 102, 105}, All},
  PlotStyle → Dashed, PlotMarkers → {"●", 7},
  Ticks → {Table[{10i, "10"i}, {i, 1, 5}], Automatic},
  PlotLegends → Table["order " <> ToString[i], {i, {1, 2, 4, 6, 8}}]
]
```

fidelity at t=nQb/2



yet it is our only hope if we wish to simulate *far* into the future!

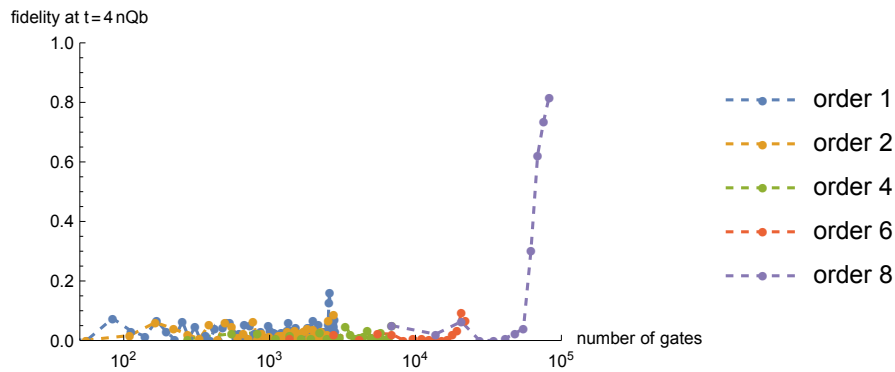
```

τ = 4 nQb;
setTrueState[trueψ, inψ, h1Matr, τ];

data = Table[
  u = GetKnownCircuit["Trotter", h1, order, reps, N@τ];
  ApplyCircuit[CloneQureg[ψ, inψ], u];
  {Length[u], CalcFidelity[ψ, trueψ]},
  {order, {1, 2, 4, 6, 8}},
  {reps, 1, Floor[100 / order]}}];

ListLogLinearPlot[data,
  AxesLabel → {"number of gates", "fidelity at t=4 nQb"},
  Joined → True, PlotRange → {{.5 × 102, 105}, {0, 1}},
  PlotStyle → Dashed, PlotMarkers → {"●", 7},
  Ticks → {Table[{10i, "10"i}, {i, 1, 5}], Automatic},
  PlotLegends → Table["order " <> ToString[i], {i, {1, 2, 4, 6, 8}}]
]

```



## Noisy

There is yet another problem - what happens if our quantum hardware is *imperfect* and susceptible to decoherence? Let's now assume that parameter-dependent dephasing noise of probability  $\xi \mid \theta \mid$  follows every  $R_z[\theta]$  gate, and fixed two-qubit depolarising noise of strength  $\xi$  follows every two-qubit Pauli gadget.

```

noisify[u_, ξ_] := u /. {
  g : R[θ_, Z_t_] => Sequence[g, Deph_t[Abs[θ] ξ]],
  g : R[θ_, Verbatim[Times][_t1_, _t2_]] => Sequence[g, Depol_t1,t2[ξ]]
}

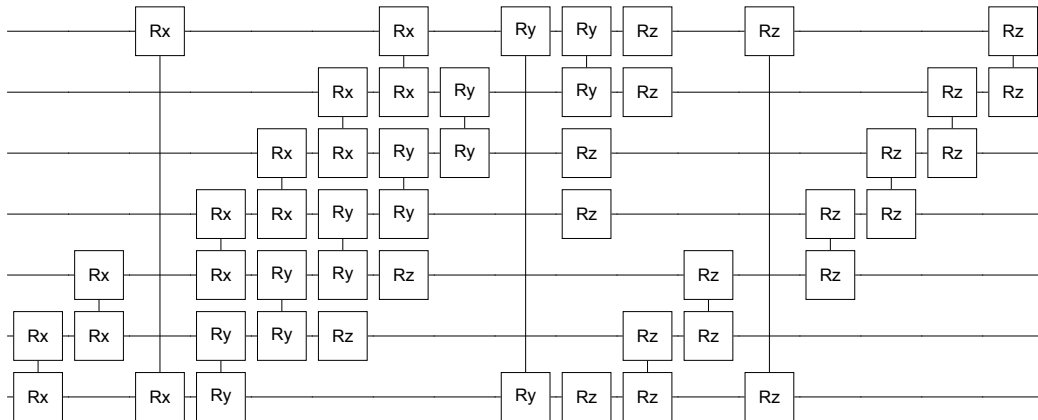
```

Attempting to perform the first-order single-repetition unitary Trotter circuit...

```

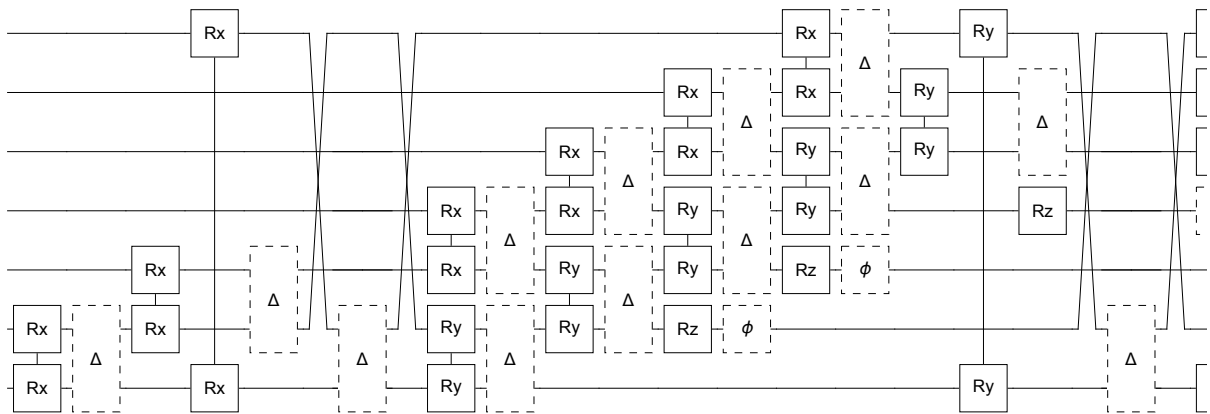
τ = 0.1;
u = GetKnownCircuit["Trotter", h1, 1, 1, τ];
DrawCircuit[u]

```



would instead invoke the channel:

```
DrawCircuit @ noisify[u, ξ]
```



Simulating this channel will require we switch our quantum registers to be *density matrices*.

```

ρ = CreateDensityQureg[nQb];
InitPureState[ρ, inψ];
ApplyCircuit[ρ, noisify[u, 10-3]];
CalcPurity[ρ]
0.963436

```

The decoherence (*physical error*) worsens our fidelity, compounding the existing inaccuracy of our Trotter truncation (*algorithmic error*)

```
setTrueState[trueψ, inψ, h1Matr, τ];
```

```
InitPureState[ρ, inψ];
```

```
ApplyCircuit[ρ, noisify[u, 10-2]];
```

```
CalcFidelity[ρ, trueψ]
```

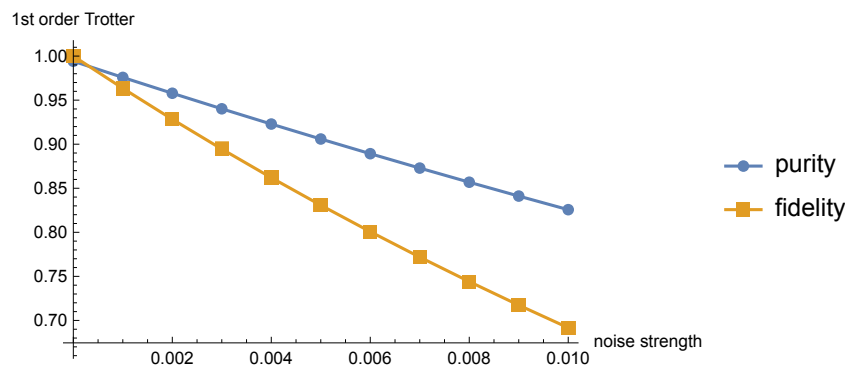
```
0.825693
```

Here's first-order single-repetition Trotter simulation succumbing to increasing decoherence.

```
noise = Range[0, 10-2, 10-3];
```

```
data = Transpose @ Table[
  InitPureState[ρ, inψ];
  ApplyCircuit[ρ, noisify[u, ξ]];
  {CalcFidelity[ρ, trueψ], CalcPurity[ρ]},
  {ξ, noise}];
```

```
ListLinePlot[
  Transpose[{noise, #}] & /@ data,
  AxesLabel → {"noise strength", "1st order Trotter"},
  PlotLegends → {"purity", "fidelity"},
  PlotMarkers → Automatic
]
```



While the algorithmic Trotter error worsens for increasing  $t$ , the physical error of decoherence worsens the fidelity at *all times*. Even a measly  $t=1$  simulation is quickly ruined!

```
Clear[u];
```

```
u[t_] = GetKnownCircuit["Trotter", h1, 4, 1, t];
```

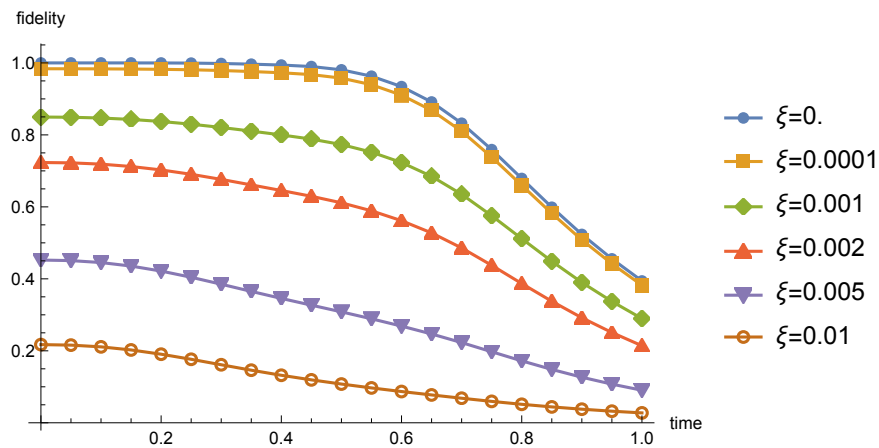
```
ch[t_, ξ_] := noisify[u[t], ξ];
```

```
time = Range[0, 1, 0.05];
```

```
noise = {0, 10-4, 10-3, 2 × 10-3, 5 × 10-3, 10-2};
```

```
fid = Transpose @ Table[
  setTrueState[trueψ, inψ, h1Matr, t];
  ApplyCircuit[InitPureState[ρ, inψ], ch[t, ξ]];
  CalcFidelity[ρ, trueψ],
  {t, time},
  {ξ, noise}];
```

```
ListLinePlot[
  Transpose[{time, #}] & /@ fid,
  AxesLabel → {"time", "fidelity"},
  PlotLegends → Table["ξ=" <> ToString[N@ξ], {ξ, noise}],
  PlotMarkers → Automatic
]
```



Let's repeat our earlier resource-aware simulations of time  $t = nQb/2$  using increasing Trotter orders and repetitions, but this time incorporating a modest physical error rate of  $\xi = 10^{-4}$ .

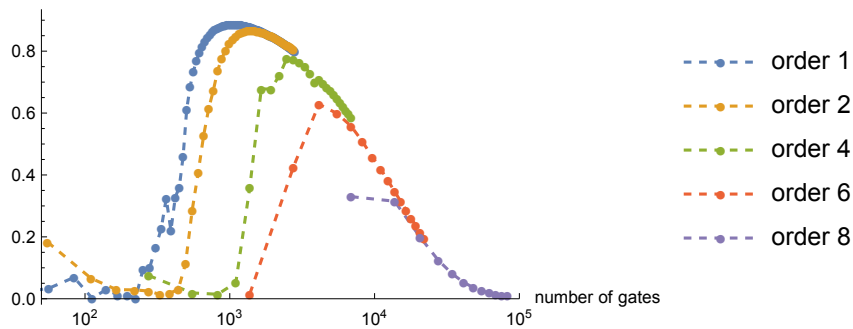
```
τ = nQb / 2;
ξ = 10-4;
setTrueState[trueψ, inψ, h1Matr, τ];

data = Table[
  u = GetKnownCircuit["Trotter", h1, order, reps, N@τ];
  ApplyCircuit[InitPureState[ρ, inψ], noisify[u, ξ]];
  {Length[u], CalcFidelity[ρ, trueψ]},
  {order, {1, 2, 4, 6, 8}},
  {reps, 1, Floor[100 / order]}}];
```

This reveals increasing the Trotter repetitions and order can actually *worsen* performance, because the additional gates introduce more opportunities for physical error:

```
ListLogLinearPlot[data,
  AxesLabel → {"number of gates", "fidelity at t=nQb/2"},
  Joined → True, PlotRange → {{.5 × 102, 105}, All},
  PlotStyle → Dashed, PlotMarkers → {"●", 7},
  Ticks → {Table[{10i, "10"i}, {i, 1, 5}], Automatic},
  PlotLegends → Table["order " <> ToString[i], {i, {1, 2, 4, 6, 8}}]
]
```

fidelity at t=nQb/2



This is why Trotterisation is believed to be incompatible with near-future noisy quantum hardware. It prescribes deep circuits leveraging precise interference effects, which are easily damaged by noise and the imperfections of near-future quantum computers.

How would the experimentalist fair attempting to use this hardware to study the dynamics of magnetisation in our spin-ring system?

```
 $\mu$  = CreateDensityQureg[nQb];
data = Table[
  u = GetKnownCircuit["Trotter", h1, 4, 1, t];
  ApplyCircuit[InitPureState[ $\rho$ , in $\psi$ ], noisify[u, 10-4]];
  CalcExpecPauliString[ $\rho$ , Z0,  $\mu$ ],
  {t, 0, nQb, .1}];
```

Well at least it more closely resembles thermalization!  $\sim \langle \psi \rangle / \sim$

```
ListLinePlot[
  {data, pureData},
  AxesLabel → {"time (×10)", "⟨Z0⟩ at d = 1"},
  PlotMarkers → Automatic,
  PlotLegends → {"ξ=10-4", "ξ=0"}]
```

