

Efficient Allocation of Working Memory Resource for Utility Maximization in Humans and Recurrent Neural Networks



Qingqing Yang (yang.6118@osu.edu) and Hsin-Hung Li



Department of Psychology, The Ohio State University

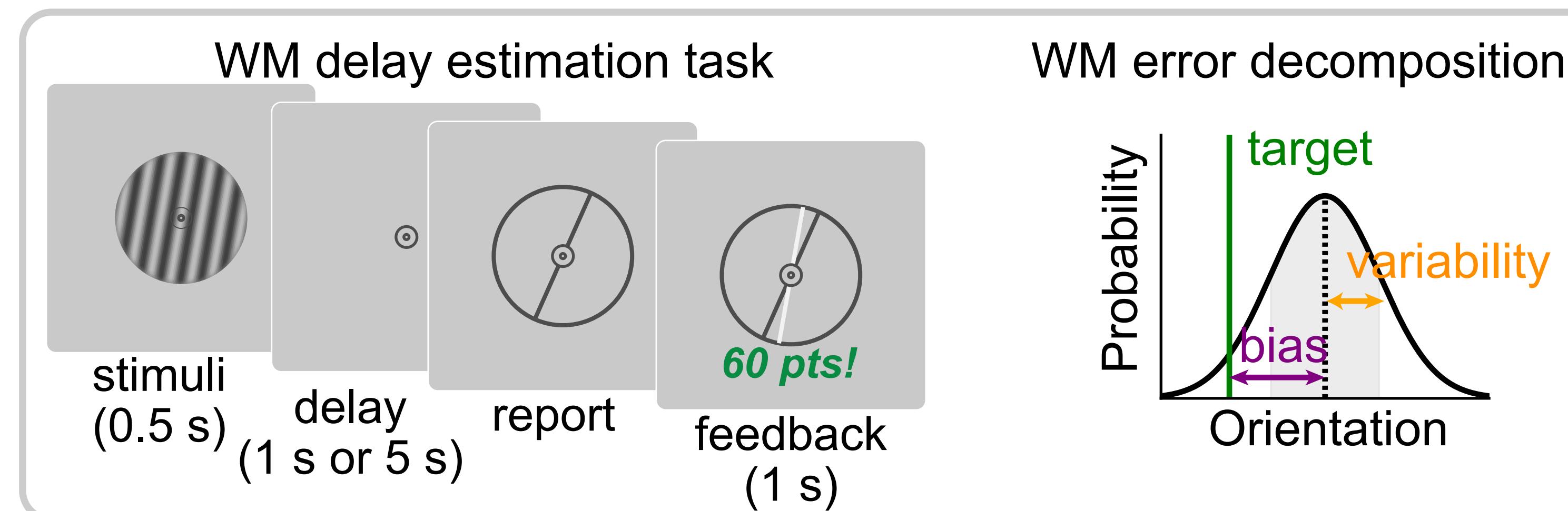
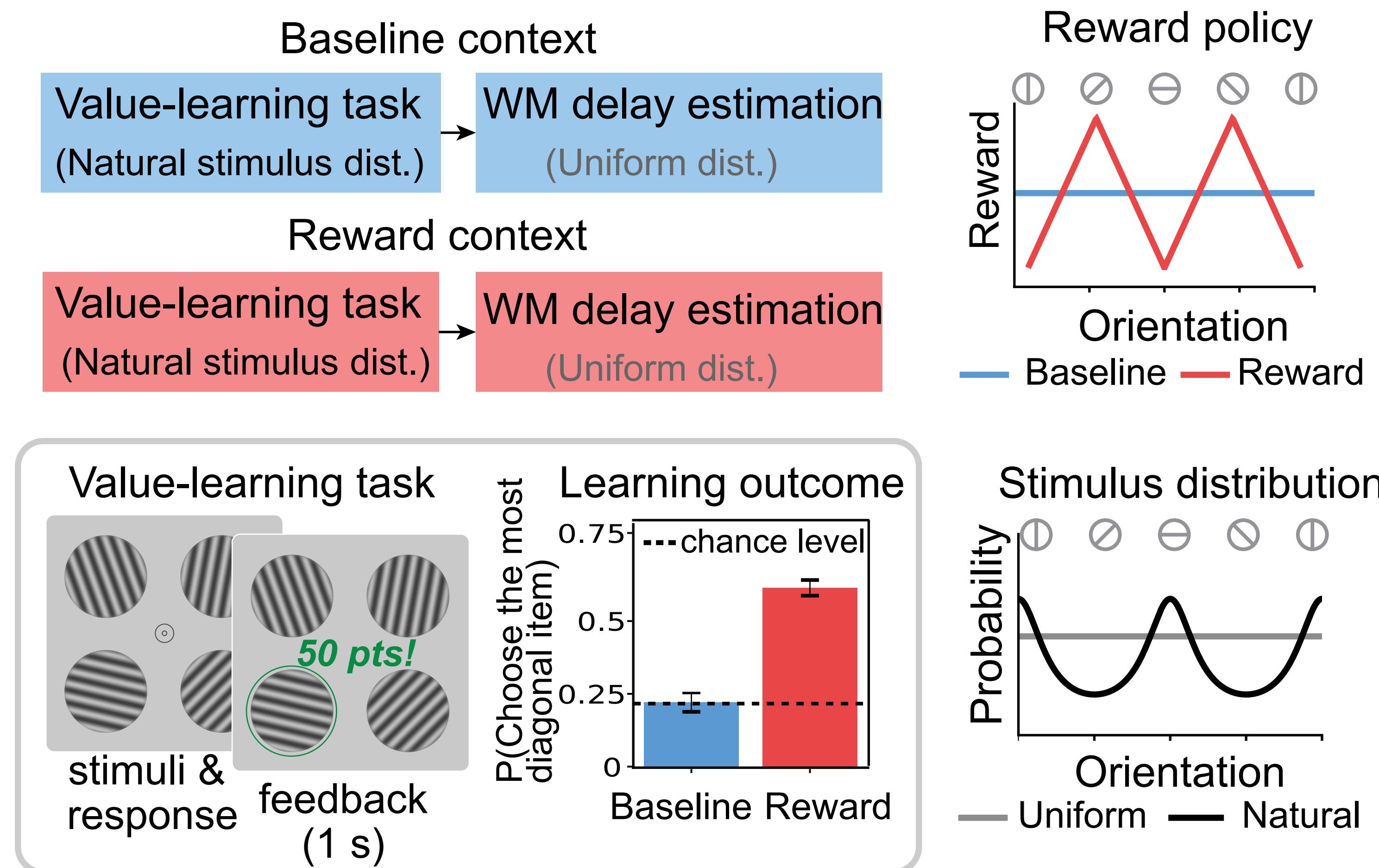
Background

- Working memory (WM) resource is highly limited [1,2]. However, the effect of reward incentives alone on WM resource allocation is mixed [3-5].
- In perception, resource distribution appears to be optimized with respect to natural stimulus distribution and cost functions [6-9].

Whether WM resource is allocated efficiently to maximize reward?

Procedure

- On each day (context), a value-learning task was followed by a WM delay estimation task ($N=14$). The contexts were counterbalanced.

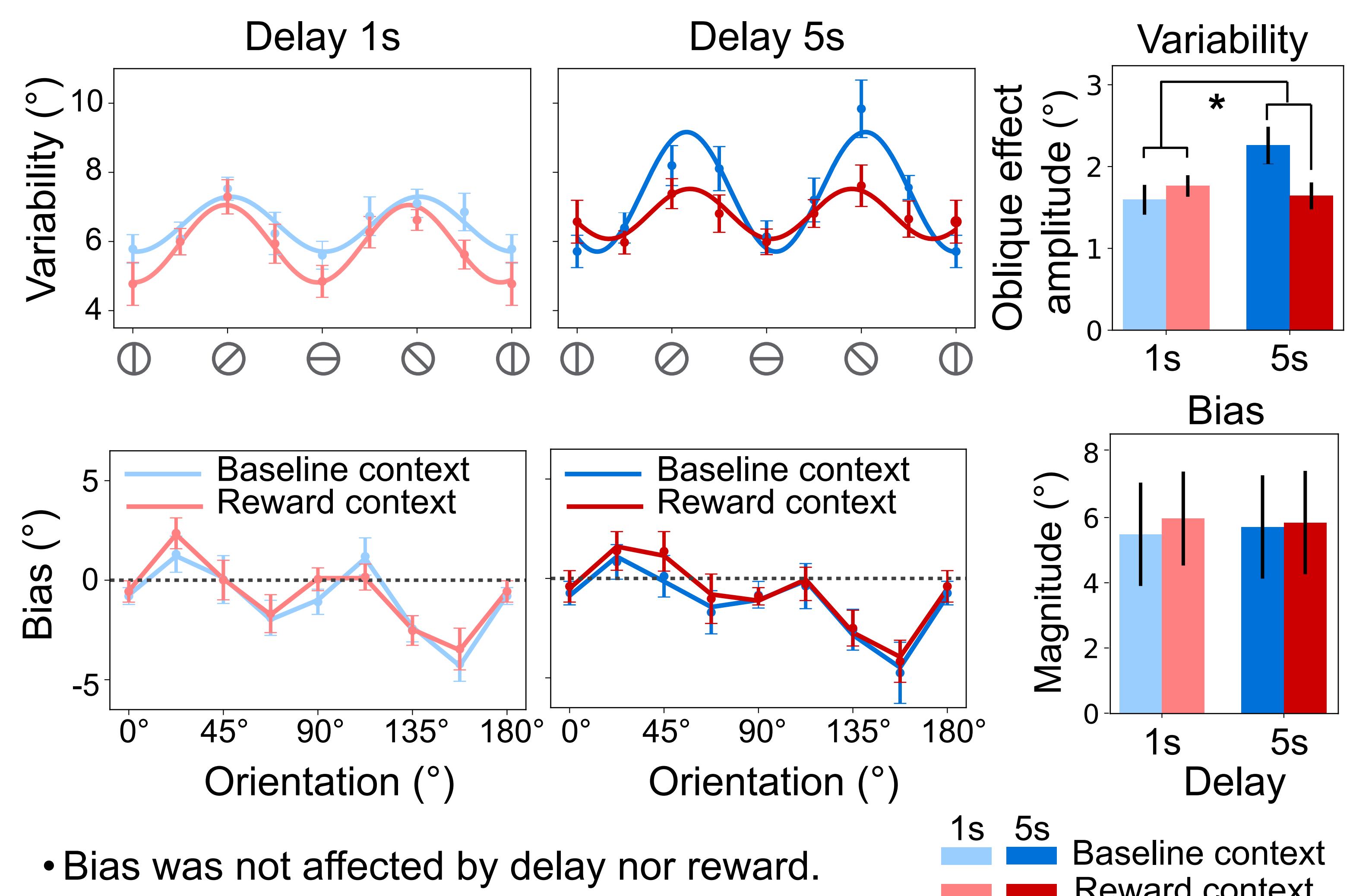


Takeaways

- Humans and RNNs efficiently allocate the WM resource based on prior stimulus distribution and reward.
- We extended efficient coding theory to the time domain and reformulated the objective, offering a normative account of how WM resource is allocated over time to maximize expected utility.

Reward stabilizes human WM representations

- Variability was affected by delay and reward (a 2-way interaction, $p < .05$).
 - Delay = 1s: Frequent (cardinal) orientations are maintained better.
 - Delay = 5s: High-reward (diagonal) stimuli are maintained better compared to the baseline.

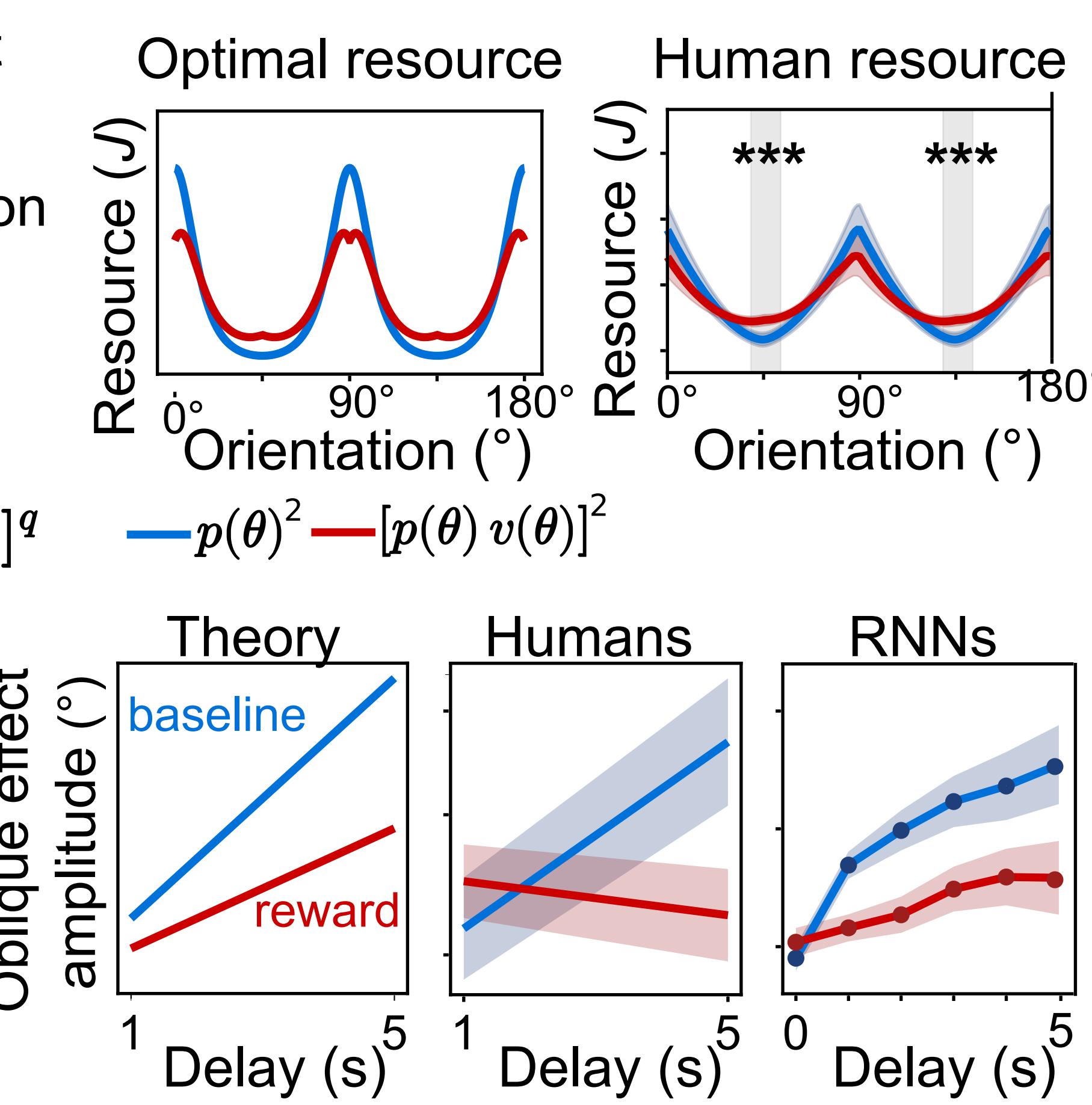


Efficient coding for utility maximization in WM

- We extended previous efficient coding theory by shifting the objective from error minimization [6-9] to reward maximization, and updated the optimal resource allocation solution:

$$J_{\text{opt}} \propto p(\theta)^q \rightarrow J_{\text{opt}} \propto [p(\theta) v(\theta)]^q$$

- After incorporating the time domain, we found that the optimal solution is stable across time.



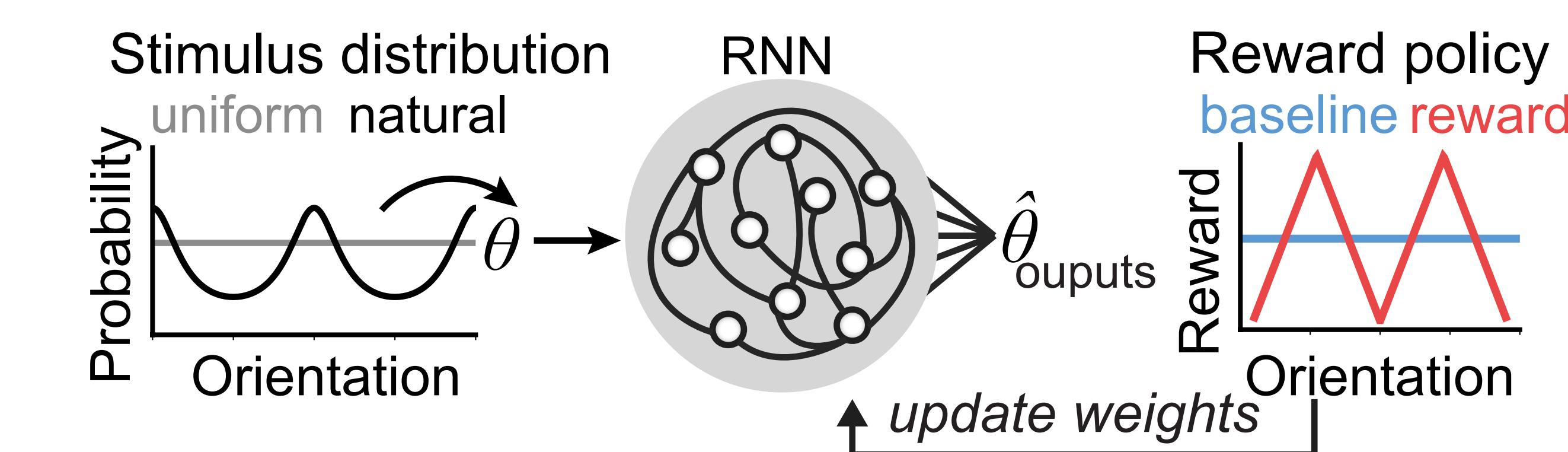
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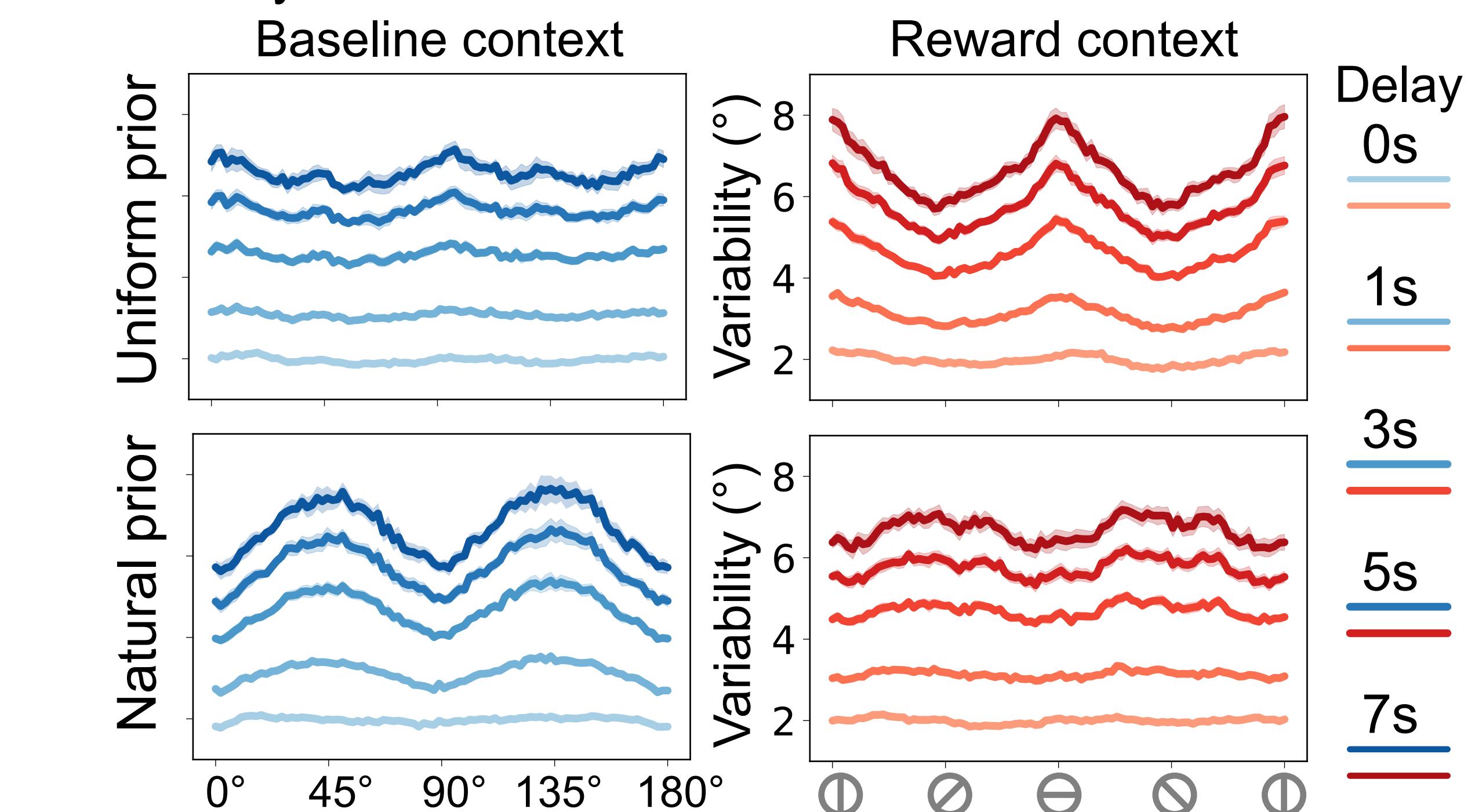
Joint effect of prior and reward on WM in RNNs

RNNs were trained in a 2x2 design:

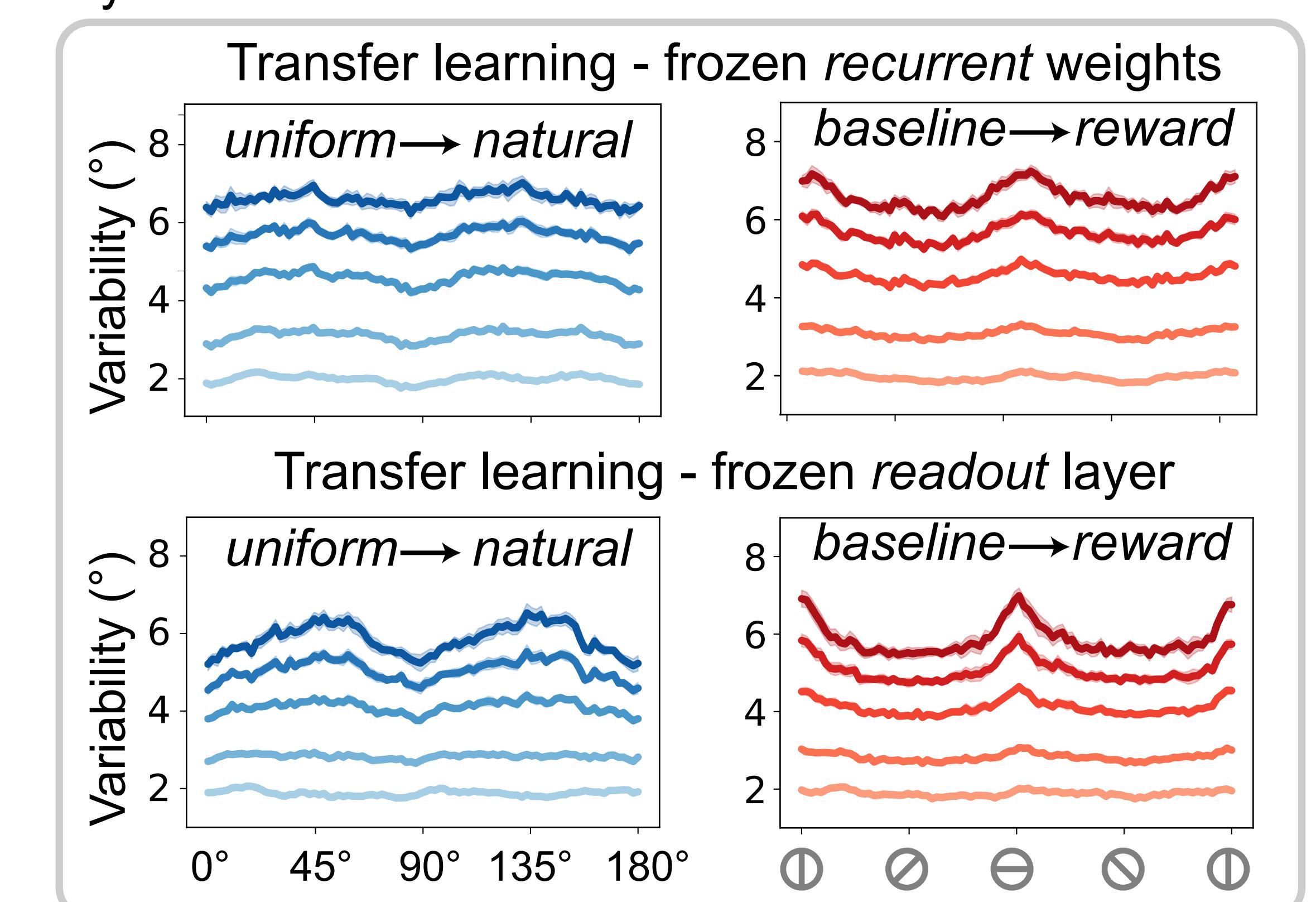
- Training stimulus distribution (uniform or natural dist.);
- Loss function (minimize error or maximize reward).



- Both prior and reward improved WM by reducing its variability.



- The effect of prior and reward was carried in recurrent dynamics.



- The results were robust with RNN sizes, initializations, and can be generalized to untrained delays.