

# HORIZONTAL TAIL PARAMETERS INITIALIZATION

Hidden Area --> Import of Excel INPUT H-Tail Data

Hidden Area --> Preliminary Mapping of imported Data

Hidden Area --> Import and preliminary mapping of OTHER Excel Data

## INPUT H-TAIL PARAMETERS LIST

### Input parameters

$$b_H = 21.96 \text{ m}$$

$$\eta_H = 0.9$$

$$\Lambda_{H_{LE}} = 39 \text{ deg}$$

$$\Gamma_H = 8.5 \text{ deg}$$

$$i_H = -3 \text{ deg}$$

$$\xi_{tmax_H} = 0.35$$

$$c_{H_r} = 7.2 \text{ m}$$

$$c_{H_t} = 2.4 \text{ m}$$

$$\eta_{e_{in}} = 0.2$$

$$t_{over\_c_{H_r}} = 0.1$$

$$t_{over\_c_{H_t}} = 0.08$$

$$\eta_{e_{out}} = 0.9$$

$$\alpha_{0l_{H_r}} = -0.05$$

$$\alpha_{0l_{H_t}} = -0.05$$

$$c_e = 1.55 \text{ m}$$

$$C_{l\alpha_{H_r}} = 6.303$$

$$C_{l\alpha_{H_t}} = 6.303$$

$$C_{m_{ac_{H_r}}} = 0$$

$$C_{m_{ac_{H_t}}} = 0$$

$$\xi_{ac_{H_r}} = 0.25$$

$$\xi_{ac_{H_t}} = 0.25$$

$$M_{cr_{H_{2D_r}}} = 0.7$$

$$M_{cr_{H_{2D_t}}} = 0.7$$

$$\varepsilon_{H_t} = 0$$

### Imported parameters

$$M_1 = 0.65$$

$$X_{ac_W} = 9.3 \text{ m}$$

$$S_W = 468.83 \text{ m}^2$$

$$MAC_W = 9.505 \text{ m}$$

$$K_{MAC4_{WH}} = 0.914$$

$$c_{W_r} = 15.57 \text{ m}$$

$$\Delta X_{HT_{LE\_W_{LE}}} = 38.35 \text{ m}$$

$$\Delta X_{HT_{LE\_Nose}} = 63.4 \text{ m}$$

# HTAIL PARAMETERS CALCULATIONS

## H-Tail basic parameters

$$\lambda_H := \frac{c_{H,t}}{c_{H,r}} = 0.333$$

$$\lambda_H = 0.333$$

$$S_H := \frac{b_H}{2} \cdot c_{H,r} \cdot (1 + \lambda_H) = 105.408 \text{ m}^2$$

$$S_H = 105.408 \text{ m}^2$$

$$AR_H := \frac{b_H^2}{S_H} = 4.575$$

$$AR_H = 4.575$$

$$MAC_H := \frac{2}{3} \cdot c_{H,r} \cdot \left( \frac{1 + \lambda_H^2 + \lambda_H}{1 + \lambda_H} \right) = 5.2 \text{ m}$$

$$MAC_H = 5.2 \text{ m}$$

$$X_{MAC\_LE\_H} := \frac{b_H}{6} \cdot \frac{(1 + 2 \cdot \lambda_H)}{(1 + \lambda_H)} \cdot \tan(\Lambda_{H\_LE}) = 3.705 \text{ m}$$

$$X_{MAC\_LE\_H} = 3.705 \text{ m}$$

$$Y_{MAC\_H} := \frac{b_H}{6} \cdot \frac{1 + 2 \cdot \lambda_H}{1 + \lambda_H} = 4.575 \text{ m}$$

$$Y_{MAC\_H} = 4.575 \text{ m}$$

$$Z_{MAC\_H} := Y_{MAC\_H} \cdot \tan(\Gamma_H) = 0.684 \text{ m}$$

$$Z_{MAC\_H} = 0.684 \text{ m}$$

## H-Tail, sweep angles

$${}_f\Lambda(x, \Lambda_{le}, AR, \lambda) := \text{if} \left( AR = 0, \Lambda_{le}, \text{atan} \left( \tan(\Lambda_{le}) - \frac{4 \cdot x \cdot (1 - \lambda)}{AR \cdot (1 + \lambda)} \right) \right)$$

• Sweep angle function

$$\Lambda_{H\_LE} := {}_f\Lambda(0, \Lambda_{H\_LE}, AR_H, \lambda_H) = 0.681$$

$$\Lambda_{H\_LE} = 39 \text{ deg}$$

$$\Lambda_{H\_TE} := {}_f\Lambda(1, \Lambda_{H\_LE}, AR_H, \lambda_H) = 0.357$$

$$\Lambda_{H\_TE} = 20.437 \text{ deg}$$

$$\Lambda_{H\_c4} := {}_f\Lambda(0.25, \Lambda_{H\_LE}, AR_H, \lambda_H) = 0.611$$

$$\Lambda_{H\_c4} = 35.011 \text{ deg}$$

$$\Lambda_{H\_c2} := {}_f\Lambda(0.5, \Lambda_{H\_LE}, AR_H, \lambda_H) = 0.534$$

$$\Lambda_{H\_c2} = 30.592 \text{ deg}$$

$$\Lambda_{H\_tmax} := {}_f\Lambda(\xi_{tmax\_H}, \Lambda_{H\_LE}, AR_H, \lambda_H) = 0.581$$

$$\Lambda_{H\_tmax} = 33.296 \text{ deg}$$

## Hidden Area --> H-Tail, linear laws coefficients

## H-Tail, linear laws defined over the whole semi-span

$${}_fC_H(y) := A_{c\_H} \cdot y + B_{c\_H}$$

$${}_fC_{l\alpha\_H}(y) := A_{Cl\alpha\_H} \cdot y + B_{Cl\alpha\_H}$$

$${}_f\overline{t}_{over\_cH}(y) := A_{tc\_H} \cdot y + B_{tc\_H}$$

$${}_fC_{m\_ac\_2D\_H}(y) := A_{Cm0\_H} \cdot y + B_{Cm0\_H}$$

$${}_f\epsilon_g(y) := A_{\epsilon\_H} \cdot y + B_{\epsilon\_H}$$

$${}_f\xi_{ac\_2D\_H}(y) := A_{\xi_{ac\_H}} \cdot y + B_{\xi_{ac\_H}}$$

$${}_f\alpha_{0l\_H\_2D}(y) := A_{\alpha0\_H} \cdot y + B_{\alpha0\_H}$$

$${}_fM_{cr\_H\_2D}(y) := A_{Mcr\_H} \cdot y + B_{Mcr\_H}$$

## H-Tail, 2D mean quantities

$$t_{over\_c_{H\_mean}} := \frac{2}{S_H} \cdot \int_0^{\frac{b_H}{2}} f_{c_H}(y) \cdot f_{t_{over\_c_H}}(y) \, dy = 0.092$$

$$t_{over\_c_{H\_mean}} = 0.092$$

$$C_{m\_ac\_H\_mean} := \frac{2}{S_H \cdot MAC_H} \cdot \int_0^{\frac{b_H}{2}} f_{c_H}(y)^2 \cdot f_{C_{m\_ac\_2D\_H}}(y) \, dy = 0$$

$$C_{m\_ac\_H\_mean} = 0$$

$$C_{l_{\alpha\_H\_mean}} := \frac{2}{S_H} \cdot \int_0^{\frac{b_H}{2}} f_{c_H}(y) \cdot f_{C_{l_{\alpha\_H}}}(y) \, dy = 6.303$$

$$C_{l_{\alpha\_H\_mean}} = 0.11 \, \text{deg}^{-1}$$

$$\alpha_{0l\_H\_mean} := \frac{2}{S_H} \cdot \int_0^{\frac{b_H}{2}} f_{c_H}(y) \cdot f_{\alpha_{0l\_H\_2D}}(y) \, dy = -0.05 \, \text{rad}$$

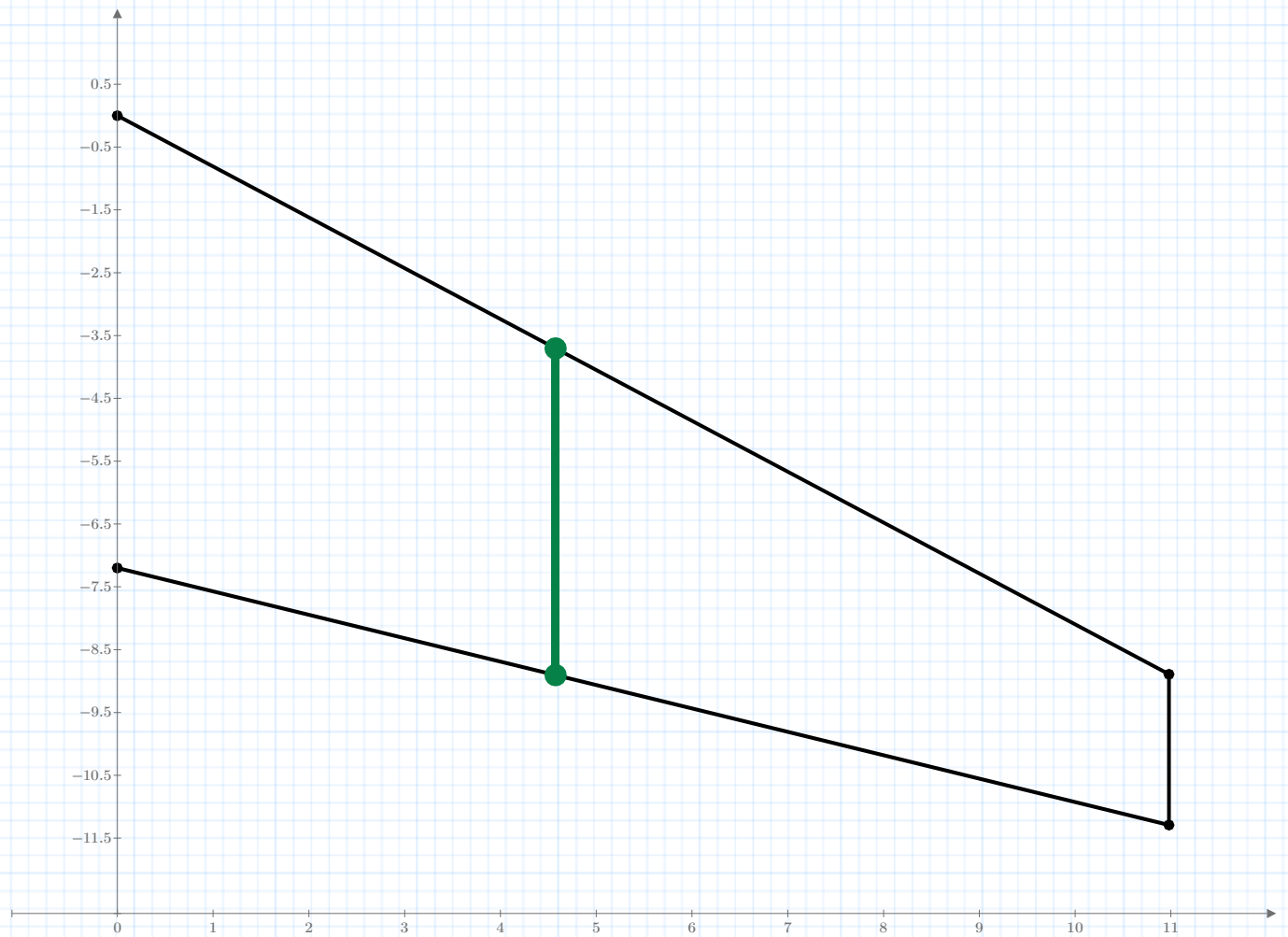
$$\alpha_{0l\_H\_mean} = -2.865 \, \text{deg}$$

## H-Tail, 3D alpha-zero-lift

$$\alpha_{0L\_H} := \frac{2}{S_H} \cdot \int_0^{\frac{b_H}{2}} f_{c_H}(y) \cdot (f_{\alpha_{0l\_H\_2D}}(y) - f_{\epsilon_{g\_H}}(y)) \, dy = -0.05 \, \text{rad}$$

$$\alpha_{0L\_H} = -2.865 \, \text{deg}$$

## H-Tail planform with Mean Aerodynamic Chord



# MISCELLANEOUS DATA CALCULATIONS

Induced drag factors, only due to geometric effects

$$e_{H\_alt} := \frac{2}{2 - AR_H + \sqrt{4 + AR_H^2 \left(1 + \tan(\Lambda_{H\_tmax})^2\right)}} = 0.615$$

$$e_{H\_alt} = 0.615$$

$$e_{H\_alt\_A0} := 1.78 \cdot \left(1 - 0.045 \cdot AR_H^{0.68}\right) - 0.64 = 0.915$$

• Alternative formula: valid for unswept wings

$$e_{H\_alt\_A} := 4.61 \cdot \left(1 - 0.045 \cdot AR_H^{0.68}\right) \cdot \cos(\Lambda_{H\_LE})^{0.15} - 3.1 = 0.777$$

• Alternative formula: valid for swept wings

3d critical Mach number at mean aerodynamic chord

$$M_{cr\_H\_3D\_@MAC\_H} := \frac{fM_{cr\_H\_2D}(Y_{MAC\_H})}{\cos(\Lambda_{H\_LE})} = 0.901$$

$$M_{cr\_H\_3D\_@MAC\_H} = 0.901$$

Elevator inner and outer stations and area

$$y_{e\_in} := \eta_{e\_in} \cdot \frac{b_H}{2} = 2.196 \text{ m}$$

$$y_{e\_in} = 2.196 \text{ m}$$

$$y_{e\_out} := \eta_{e\_out} \cdot \frac{b_H}{2} = 9.882 \text{ m}$$

$$y_{e\_out} = 9.882 \text{ m}$$

$$c_{H\_mean\_@e} := r_{cH} \left( \frac{y_{e\_in} + y_{e\_out}}{2} \right) = 4.56 \text{ m}$$

$$c_{H\_mean\_@e} = 4.56 \text{ m}$$

$$S_e := 2 \cdot c_e \cdot (y_{e\_out} - y_{e\_in}) = 23.827 \text{ m}^2$$

$$S_e = 23.827 \text{ m}^2$$

@Aerodynamic Database ---> (control\_surface)\_tau\_e\_vs\_c\_control\_surface\_over\_c\_horizontal\_tail

$$\tau_e = 0.552$$

@Aerodynamic Database ---> (control\_surface)\_C\_h\_alpha\_vs\_flap\_chord\_over\_airfoil\_chord

$$C_{h\_alpha\_e} = -0.007$$

$$C_{h\_alpha\_e} = -1.269 \cdot 10^{-4} \text{ deg}^{-1}$$

@Aerodynamic Database ---> (control\_surface)\_C\_h\_delta\_vs\_flap\_chord\_over\_airfoil\_chord

$$C_{h\_delta\_e} = -0.013$$

$$C_{h\_delta\_e} = -2.277 \cdot 10^{-4} \text{ deg}^{-1}$$

# H-TAIL LIFT CURVE SLOPE

## H-Tail Lift Curve Slope, function definitions

$$f_{k_{Polhamus}}(M, M_{cr\_3D}, \Lambda_{LE}, \lambda, AR) := \begin{cases} \text{if } (M < M_{cr\_3D}) \wedge (\Lambda_{LE} < 32 \text{ deg}) \wedge (\lambda > 0.4) \wedge (\lambda < 1) \wedge (AR > 3) \wedge (AR < 8) \\ \quad \text{if } AR < 4 \\ \quad \quad \text{return } 1 + \frac{AR \cdot (1.87 - 0.000233 \cdot \Lambda_{LE})}{100} \\ \quad \text{else} \\ \quad \quad \text{return } 1 + \frac{((8.2 - 2.3 \cdot \Lambda_{LE}) - AR \cdot (0.22 - 0.153 \cdot \Lambda_{LE}))}{100} \\ \quad \text{else} \\ \quad \quad \text{return } 100 \end{cases}$$

• Polhamus Formula Coefficient

$$f_{C_{L\alpha\_H}}(M, k_P, AR, \Lambda_{c2}, C_{l\alpha@MAC}, \Lambda_{LE}) := \begin{cases} \text{if } k_P \neq 100 \\ \quad \text{return } \frac{2 \cdot \pi \cdot AR}{2 + \sqrt{\left( \left( \frac{AR^2 \cdot (1 - M^2)}{k_P^2} \right) \left( 1 + \frac{\tan(\Lambda_{c2})}{(1 - M^2)} \right) \right) + 4}} \\ \quad \text{else} \\ \quad \quad a_0 \leftarrow \frac{C_{l\alpha@MAC}}{\sqrt{1 - M^2 \cdot \cos(\Lambda_{LE})}} \\ \quad \quad \text{return } \frac{a_0 \cdot \cos(\Lambda_{LE})}{\sqrt{1 - (M \cdot \cos(\Lambda_{LE}))^2 + \left( \frac{a_0 \cdot \cos(\Lambda_{LE})}{\pi \cdot AR} \right)^2} + \frac{a_0 \cdot \cos(\Lambda_{LE})}{\pi \cdot AR}} \end{cases}$$

• General Formula for Lift Curve Slope

## H-Tail Lift Curve Slope, classic formula

$$C_{L\alpha\_H\_classic} := \frac{C_{l\alpha\_H\_mean}}{\sqrt{1 - M_1^2} + \frac{C_{l\alpha\_H\_mean}}{\pi \cdot AR_H \cdot e_{H\_alt}}} = 4.279$$

$$C_{L\alpha\_H\_classic} = 0.075 \text{ deg}^{-1}$$

## H-Tail Lift Curve Slope, general formula for inner/outer panel and whole wing

$$k_{Polhamus\_H} := f_{k_{Polhamus}}(M_1, M_{cr\_H\_3D@MAC\_H}, \Lambda_{H\_LE}, \lambda_H, AR_H) = 100$$

$$k_{Polhamus\_H} = 100$$

$$C_{l\alpha\_H@MAC\_H} := f_{C_{l\alpha\_H}}(Y_{MAC\_H}) = 6.303$$

$$C_{l\alpha\_H@MAC\_H} = 0.11 \text{ deg}^{-1}$$

$$C_{L\alpha\_H@M0} := f_{C_{L\alpha\_H}}(0, k_{Polhamus\_H}, AR_H, \Lambda_{H\_c2}, C_{l\alpha\_H@MAC\_H}, \Lambda_{H\_LE})$$

$$C_{L\alpha\_H@M0} = 3.505 \text{ rad}^{-1}$$

$$C_{L\alpha\_H@M0} = 0.061 \text{ deg}^{-1}$$

$$C_{L\alpha\_H} := f_{C_{L\alpha\_H}}(M_1, k_{Polhamus\_H}, AR_H, \Lambda_{H\_c2}, C_{l\alpha\_H@MAC\_H}, \Lambda_{H\_LE})$$

$$C_{L\alpha\_H} = 4.223 \text{ rad}^{-1}$$

$$C_{L\alpha\_H} = 0.074 \text{ deg}^{-1}$$

## H-Tail lift coefficient at initial conditions

$$C_{L0\_H} := C_{L\alpha\_H} \cdot (i_H - \alpha_{0L\_H} - \varepsilon_{0\_W}) = -0.072$$

$$C_{L0\_H} = -0.072$$

Induced drag factor, due to both geometric and aerodynamic effects

$$e(C_{L\alpha}, AR, \lambda, \Lambda_{LE}) := \left\| \begin{array}{l} \lambda_e \leftarrow \frac{AR \cdot \lambda}{\cos(\Lambda_{LE})} \\ R \leftarrow 0.0004 \cdot \lambda_e^3 - 0.008 \cdot \lambda_e^2 + 0.0501 \cdot \lambda_e + 0.8642 \\ \text{return if } (AR = 0, 0, \frac{1.1 \cdot C_{L\alpha}}{R \cdot C_{L\alpha} + (1-R) \pi \cdot AR}) \end{array} \right\|$$

- Function for calculating wing induced drag factor, including aerodynamic and geometric effects

$$e_H := e(C_{L\alpha_H}, AR_H, \lambda_H, \Lambda_{H\_LE}) = 0.951$$

$$e_H = 0.951$$

## H-TAIL AERODYNAMIC CENTER - GRAPHICAL METHOD (DATCOM/NAPOLITANO)

@Aerodynamic Database ---> (x\_bar\_ac\_w)\_k1\_vs\_lambda

$$K1_{ac\_H\_Datcom} = 1.38$$

@Aerodynamic Database ---> (x\_bar\_ac\_w)\_k2\_vs\_L\_LE\_(AR)\_(lambda)

$$K2_{ac\_H\_Datcom} = 0.527$$

@Aerodynamic Database ---> (x\_bar\_ac\_w)\_x'\_ac\_over\_root\_chord\_vs\_tan(L\_LE)\_over\_beta\_(AR\_times\_tan(L\_LE))\_(lambda)

$$X_{ac\_over\_c_r\_H\_Datcom} = 0.728$$

Aerodynamic center positions

$$\xi_{ac\_H} := K1_{ac\_H\_Datcom} \cdot (X_{ac\_over\_c_r\_H\_Datcom} - K2_{ac\_H\_Datcom}) = 0.277$$

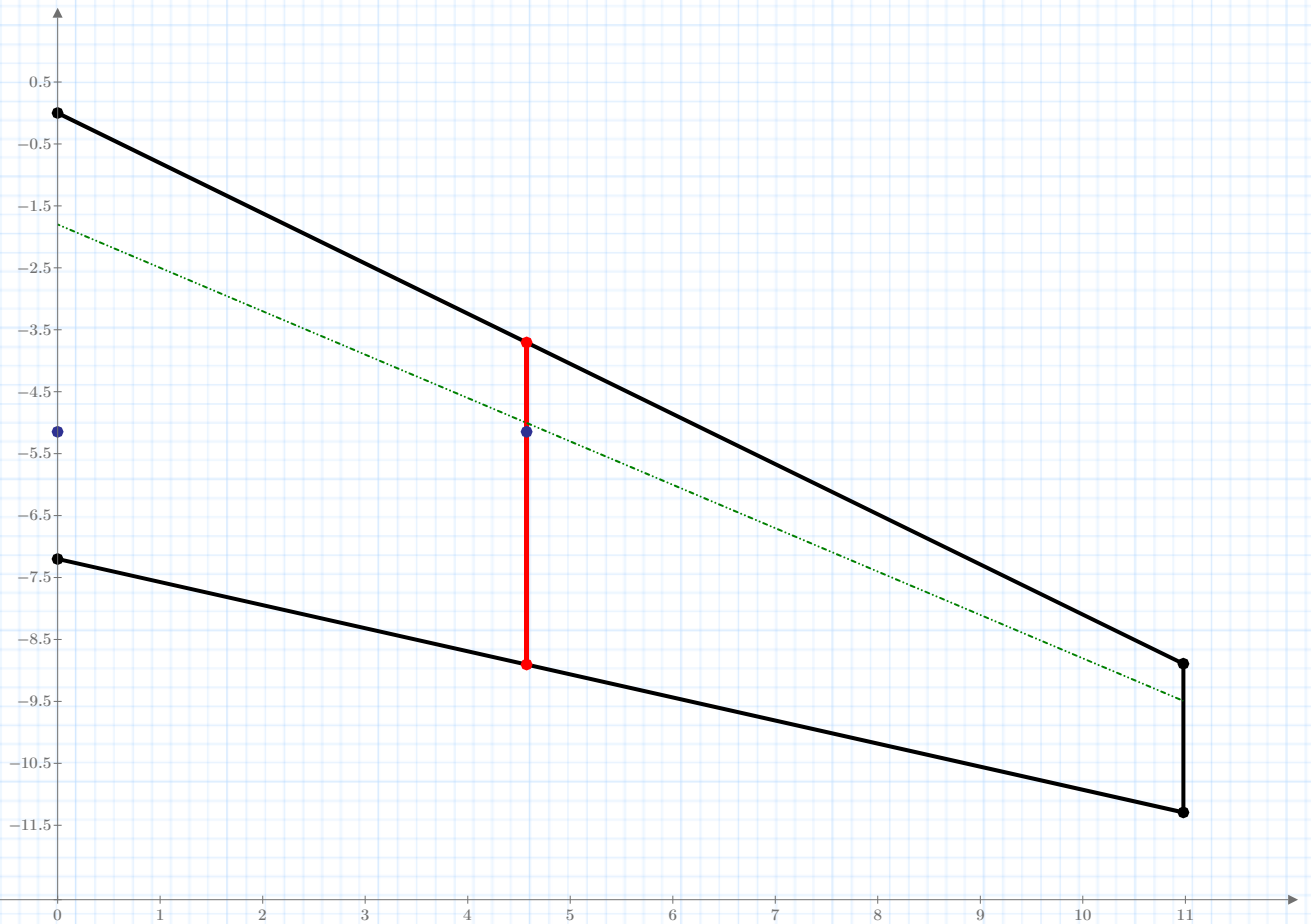
$$X_{ac\_H} := \xi_{ac\_H} \cdot MAC_H + X_{MAC\_LE\_H} = 5.147 \text{ m}$$

$$X_{ac\_H} = 5.147 \text{ m}$$

$$x_{ac\_H} := X_{ac\_H} - X_{MAC\_LE\_H} = 1.442 \text{ m}$$

$$x_{ac\_H} = 1.442 \text{ m}$$

## H-Tail planform with 2D aerodynamic center distribution and 3D aerodynamic center



## H-Tail Volume Ratio based on aerodynamic centers distance

$$\Delta X_{HT_{ac-W_{ac}}} := \Delta X_{HT_{LE-W_{LE}}} - X_{ac_W} + X_{ac_H} = 34.197 \text{ m}$$

$$VolumeRatio_{H_{ac}} := \frac{S_H}{S_W} \cdot \frac{\Delta X_{HT_{ac-W_{ac}}}}{MAC_W} = 0.809$$



# SHRENK'S METHOD FOR BASIC AND ADDITIONAL H-TAIL LOADING

Loading function definitions and remarkable values

$$f_{c_{eff}}(y) := \frac{f_{c_H}(y) \cdot f_{c_{l\alpha_H}}(y)}{C_{l\alpha_H_{mean}}}$$

$$c_{ell_0} := \frac{4 \cdot S_H}{\pi \cdot b_H} \quad f_{c_{ell}}(y) := c_{ell_0} \cdot \sqrt{1 - \left(\frac{y}{\frac{b_H}{2}}\right)^2}$$

$$f_{\alpha_b}(y) := \alpha_{0L_H} - (f_{\alpha_{0L_H_{2D}}}(y) - f_{\varepsilon_{g_H}}(y))$$

$$f_{cC_{l_b}}(y) := \frac{1}{2} \cdot f_{c_H}(y) \cdot f_{c_{l\alpha_H}}(y) \cdot f_{\alpha_b}(y)$$

$$f_{cC_{l_a}}(y) := \frac{1}{2} \cdot (f_{c_{eff}}(y) + f_{c_{ell}}(y))$$

$$f_{cC_l}(y) := f_{cC_{l_b}}(y) + f_{cC_{l_a}}(y)$$

$$C_{L_b} := \frac{2}{S_W} \cdot \int_0^{\frac{b_H}{2}} f_{cC_{l_b}}(y) dy = 0$$

$$C_{L_a} := \frac{2}{S_W} \cdot \int_0^{\frac{b_H}{2}} f_{cC_{l_a}}(y) dy = 0.225$$

- Effective chord distribution function

- Elliptic chord distribution function

- "Basic" angle of attack function

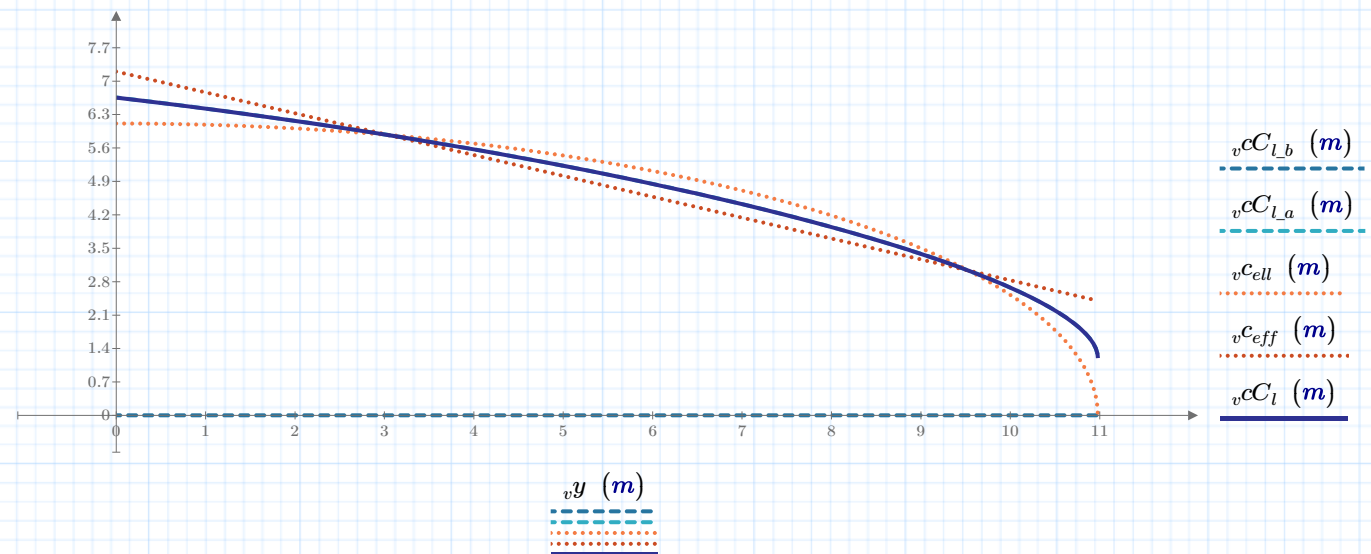
- Basic wing loading

- Additional wing loading function

- Wing loading function

- REMARK: the effects of wing sweep angle are neglected

Spanwise loading curve plots



# 3D PITCHING MOMENT COEFFICIENT ABOUT H-TAIL AERODYNAMIC CENTER

## Exact formulation

$$\mathbf{r}^{X_{b_H}}(y) := X_{ac_H} - (y \cdot \tan(\Lambda_{H_{LE}}) + \mathbf{r}^{c_H}(y) \cdot \mathbf{f}^{\xi_{ac_{2D_H}}}(y))$$

• Moment arm from section's aerodynamic center to wing 3D aerodynamic center

$$C_{M_{ac_H_b}} := \frac{2}{S_H \cdot MAC_H} \cdot \int_0^{\frac{b_H}{2}} \mathbf{r}^{c_{l_b}}(y) \cdot \mathbf{r}^{X_{b_H}}(y) \, dy = 0$$

$$C_{M_{ac_H_b}} = 0$$

$$C_{M_{ac_H_a}} := \frac{2}{S_H \cdot MAC_H} \cdot \int_0^{\frac{b_H}{2}} \mathbf{r}^{c_{m_{ac_{2D_H}}}}(y) \cdot \mathbf{r}^{c_H}(y)^2 \, dy = 0$$

$$C_{M_{ac_H_a}} = 0$$

$$C_{M_{ac_H}} := C_{M_{ac_H_b}} + C_{M_{ac_H_a}} = 0$$

$$C_{M_{ac_H}} = 0$$

## Approximated formulation (Roskam)

$$C_{M_{ac_H_b\_Roskam}} := \frac{2 \cdot \pi}{S_H \cdot MAC_H} \cdot \int_0^{\frac{b_H}{2}} \mathbf{r}^{\alpha_b}(y) \cdot \mathbf{r}^{c_H}(y) \cdot \mathbf{r}^{X_{b_H}}(y) \, dy = 0$$

$$C_{M_{ac_H_b\_Roskam}} = 0$$

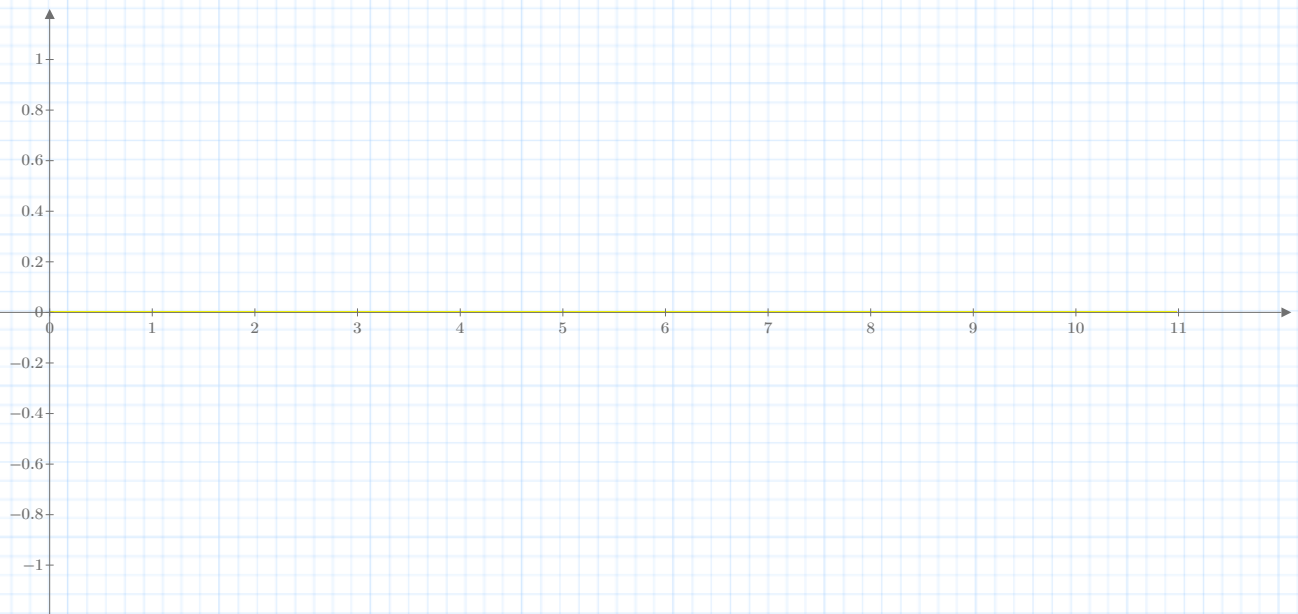
$$C_{M_{ac_H\_Roskam}} := C_{M_{ac_H_b\_Roskam}} + C_{M_{ac_H_a}} = 0$$

$$C_{M_{ac_H\_Roskam}} = 0$$

$$\underline{\underline{vIC_{M_{ac}H_bRoskam} \left( m^2 \right)}}$$

$$\underline{\underline{vIC_{M_{ac}H_b} \left( m^2 \right)}}$$

$$\underline{\underline{vIC_{M_{ac}H_a} \left( m^2 \right)}}$$



$$\underline{\underline{vy \left( m \right)}}$$

## DOWNWASH

### Lifting Line Theory

$$f_{\epsilon_{\alpha_{LLT_H}}(C_{L\alpha}, AR, e, M) := \text{if} \left( AR = 0, 0, 2 \cdot \frac{C_{L\alpha}}{\pi \cdot AR \cdot e} \cdot \frac{1}{\sqrt{1 - M^2}} \right)$$

• Downwash gradient according to linear theory

$$\epsilon_{\alpha_{LLT\_@M0\_H}} := f_{\epsilon_{\alpha_{LLT\_H}}(C_{L\alpha\_H}, AR_H, e_H, 0) = 0.618$$

$$\epsilon_{\alpha_{LLT\_@M0\_H}} = 0.618$$

$$\epsilon_{\alpha_{LLT\_H}} := f_{\epsilon_{\alpha_{LLT\_H}}(C_{L\alpha\_H}, AR_H, e_H, M_1) = 0.813$$

$$\epsilon_{\alpha_{LLT\_H}} = 0.813$$

$$\epsilon_{0_{LLT\_H}} := \epsilon_{\alpha_{LLT\_H}} \cdot (i_H - \alpha_{0L\_H}) = -0.002$$

$$\epsilon_{0_{LLT\_H}} = -0.11 \text{ deg}$$

$$fK_{AR}(AR) := \frac{1}{AR} - \frac{1}{1 + (AR)^{1.7}}$$

$$fK_{\lambda}(\lambda) := \frac{10 - 3 \cdot \lambda}{7}$$

• Empirical  
coefficients  
function  
definitions

$$K_M(M, C_{L\alpha\_@M0}, C_{L\alpha}) := \begin{cases} \text{return } \sqrt{1 - M^2} & \text{if } M \leq 0.7 \\ \text{return } \frac{C_{L\alpha}}{C_{L\alpha\_@M0}} & \text{else} \end{cases}$$

$$fK_{MAC4}(\Delta Z', \Delta X', b) := \frac{1 - \frac{\Delta Z'}{b}}{\sqrt[3]{2 \cdot \frac{\Delta X'}{b}}}$$

$$K_{AR\_H} := fK_{AR}(AR_H) = 0.148$$

$$K_{AR\_H} = 0.148$$

$$K_{\lambda\_H} := fK_{\lambda}(\lambda_H) = 1.286$$

$$K_{\lambda\_H} = 1.286$$

$$K_{MAC4\_WH} = 0.914$$

$$K_{MAC4\_WH} = 0.914$$

$$K_{M\_H} := K_M(M_1, C_{L\alpha\_H\_@M0}, C_{L\alpha\_H}) = 0.76$$

$$K_{M\_H} = 0.76$$

$$\varepsilon_{\alpha\_@M0\_H} := 4.44 \cdot (K_{AR\_H} \cdot K_{\lambda\_H} \cdot K_{MAC4\_WH} \cdot \sqrt{\cos(\Lambda_{H\_c4})})^{1.19} = 0.494$$

$$\varepsilon_{\alpha\_@M0\_H} = 0.494$$

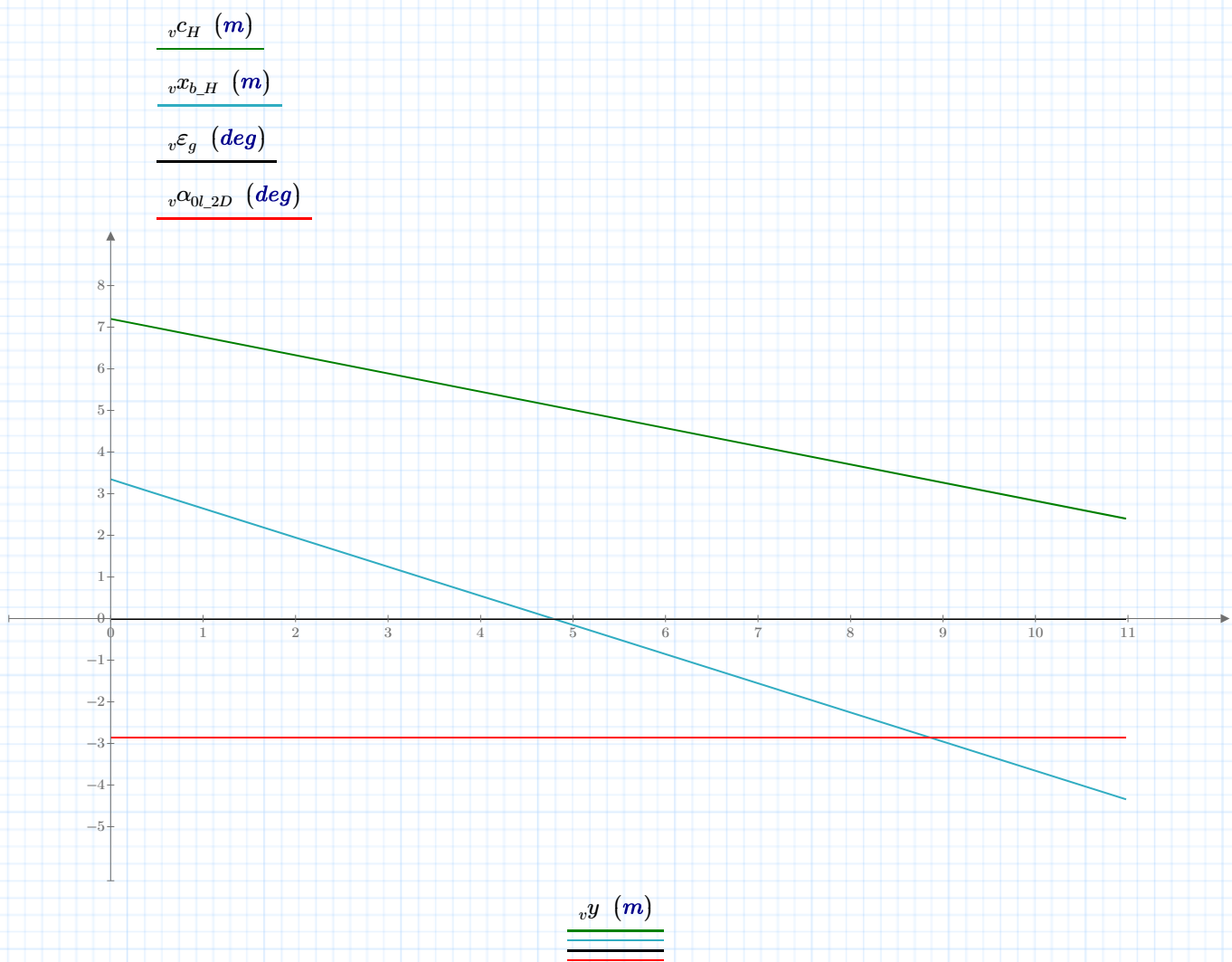
$$\varepsilon_{\alpha\_H} := \varepsilon_{\alpha\_@M0\_H} \cdot \sqrt{1 - M_1^2}$$

$$\varepsilon_{\alpha\_H} = 0.375$$

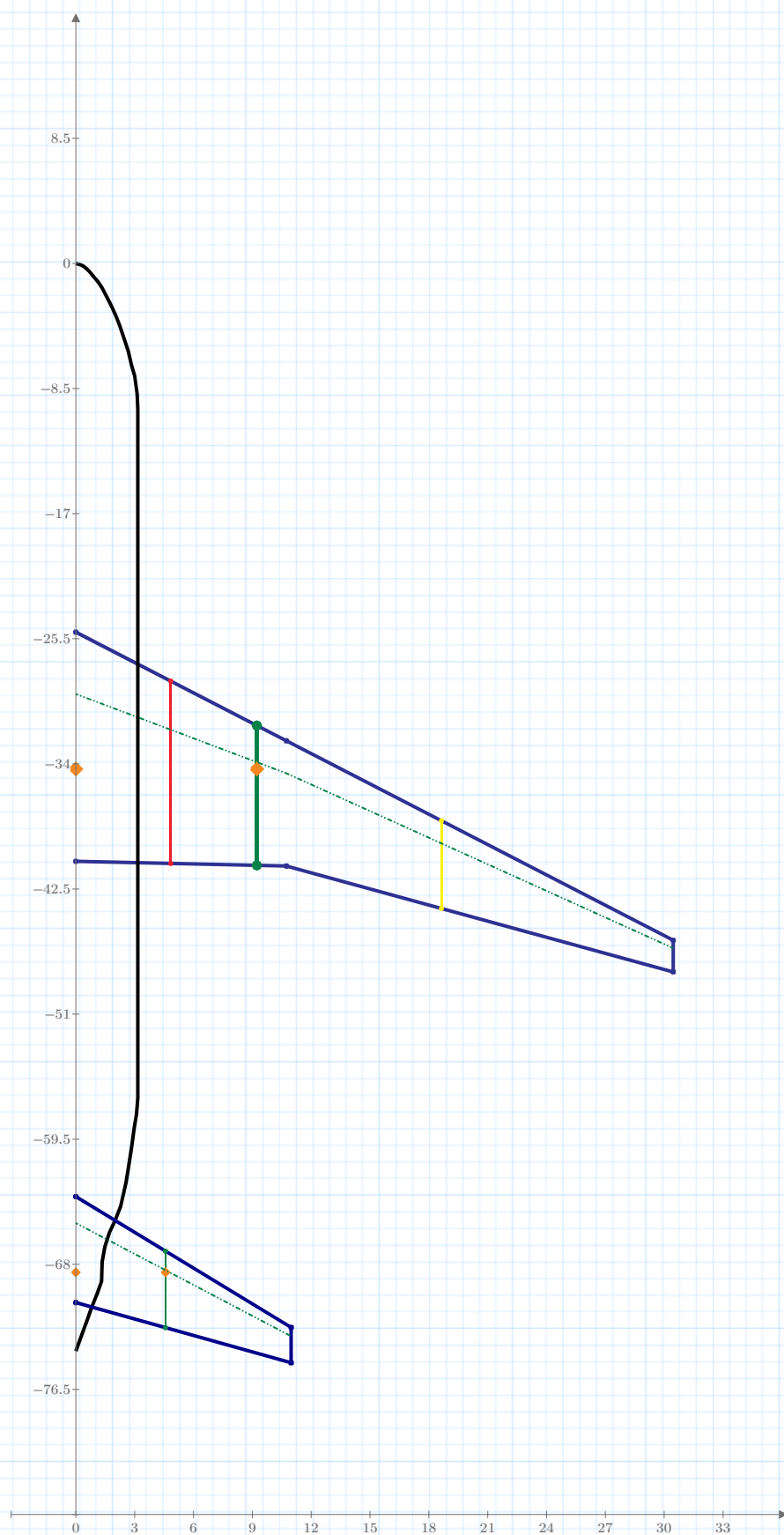
$$\varepsilon_{0\_H} := \varepsilon_{\alpha\_H} \cdot (i_H - \alpha_{0L\_H}) = -8.854 \cdot 10^{-4}$$

$$\varepsilon_{0\_H} = -0.051 \text{ deg}$$

# MISCELLANEOUS PARAMETERS PLOT



# WING-BODY-HTAIL PLANFORM



# MAPPING AND OUTPUT CREATION

Includi << ../Default\_Map\_HTail.mcdx

## Excel Writing

$First\_Row_{H\_1} := 4$

$Block_{H\_1} := \text{map\_matrix\_transform} \left( {}_m HTail\_Data\_Map_{imported} \right)$

$Excel\_Output_{H\_1} := \text{write\_full\_output} \left( {}_s Output\_Excel\_File, Block_{H\_1}, n_{sheet}, First\_Row_{H\_1} \right)$

$First\_Row_{H\_2} := First\_Row_{H\_1} + \text{rows} \left( Block_{H\_1} \right) + 2 = 20$

$Block_{H\_2} := \text{map\_matrix\_transform} \left( {}_m HTail\_Data\_Map_{input} \right)$

$Excel\_Output_{H\_2} := \text{write\_full\_output} \left( {}_s Output\_Excel\_File, Block_{H\_2}, n_{sheet}, First\_Row_{H\_2} \right)$

$First\_Row_{H\_3} := First\_Row_{H\_2} + \text{rows} \left( Block_{H\_2} \right) + 2 = 58$

$Block_{H\_3} := \text{map\_matrix\_transform} \left( {}_m HTail\_Data\_Map \right)$

$Excel\_Output_{H\_3} := \text{write\_full\_output} \left( {}_s Output\_Excel\_File, Block_{H\_3}, n_{sheet}, First\_Row_{H\_3} \right)$

$First\_Row_{H\_4} := First\_Row_{H\_3} + \text{rows} \left( Block_{H\_3} \right) + 2 = 143$

$Block_{H\_4} := \text{map\_matrix\_transform} \left( {}_m HTail\_Data\_Map_{LLCcoeffs} \right)$

$Excel\_Output_{H\_4} := \text{write\_full\_output} \left( {}_s Output\_Excel\_File, Block_{H\_4}, n_{sheet}, First\_Row_{H\_4} \right)$

$First\_Row_{H\_5} := First\_Row_{H\_4} + \text{rows} \left( Block_{H\_4} \right) + 2 = 178$

$Block_{H\_5} := \text{map\_matrix\_transform} \left( {}_m HTail\_Data\_Map_{Misc} \right)$

$Excel\_Output_{H\_5} := \text{write\_full\_output} \left( {}_s Output\_Excel\_File, Block_{H\_5}, n_{sheet}, First\_Row_{H\_5} \right)$

## CSV Tabs Writing

${}_m CSV_{H\_1} := \text{augment} \left( {}_v y, {}_v c_{ell}, {}_v c_{eff}, {}_v c_{Cl\_a}, {}_v c_{Cl\_b} \right) \cdot \frac{1}{m}$

$CSV\_Output_{H\_1} := \text{WRITECSV} \left( \text{"\Output\H-TAIL\_shrenk\_loading(y,c\_ell,c\_eff,cCl\_a,cCl\_b).csv"}, {}_m CSV_{H\_1} \right)$

${}_m CSV_{H\_2} := \text{augment} \left( {}_v y \cdot \frac{1}{m}, {}_v x_{b\_H} \cdot \frac{1}{m}, {}_v IC_{M\_ac\_H\_b} \cdot \frac{1}{m^2}, {}_v IC_{M\_ac\_H\_b\_Roskam} \cdot \frac{1}{m^2} \right)$

$CSV\_Output_{H\_2} := \text{WRITECSV} \left( \text{"\Output\H-TAIL\_shrenk-roskam\_loading(y,x\_b,IC\_M\_b,IC\_M\_b\_Roskam).csv"}, {}_m CSV_{H\_2} \right)$

${}_m CSV_{H\_3} := \text{augment} \left( {}_v y \cdot \frac{1}{m}, {}_v c_H \cdot \frac{1}{m}, {}_v \alpha_{0L\_2D}, {}_v \varepsilon_g, {}_v C_{l\alpha\_H}, {}_v C_{m\_ac\_2D\_H}, {}_v \xi_{ac\_2D\_H} \right)$

$CSV\_Output_{H\_3} := \text{WRITECSV} \left( \text{"\Output\H-TAIL\_linear\_laws(y,c,alpha,z,epsilon,Clalpha,Cmac,Csiac).csv"}, {}_m CSV_{H\_3} \right)$

${}_m CSV_{H\_4} := \text{augment} \left( {}_v X_H, {}_v Y_H \right) \cdot \frac{1}{m}$

$CSV\_Output_{H\_4} := \text{WRITECSV} \left( \text{"\Output\H-TAIL\_planform(X\_H,Y\_H).csv"}, {}_m CSV_{H\_4} \right)$

$${}_mCSV_{H_5} := \text{augment} \left( {}_vX_{mac.H}, {}_vY_{mac.H}, {}_vX_{ac.H}, {}_vY_{ac.H} \right) \cdot \frac{1}{\textcolor{blue}{m}}$$

$$CSV\_Output_{H_5} := \text{WRITECSV} \left( “.\backslash\text{Output}\backslash\text{H-TAIL\_planform\_MAC\_and\_AC}(XmacH,YmacH,Xac,Yac).csv”, {}_mCSV_{H_5} \right)$$

$${}_mCSV_{H_6} := \text{augment} \left( {}_vX_{ac.2D.H}, {}_vY_{ac.2D.H} \right) \cdot \frac{1}{\textcolor{blue}{m}}$$

$$CSV\_Output_{H_6} := \text{WRITECSV} \left( “.\backslash\text{Output}\backslash\text{H-TAIL\_planform\_ac2D}(Xac2D\_H,Yac2D\_H).csv”, {}_mCSV_{H_6} \right)$$

TeX Macro writing on .tex

$${}_vcomplete\_macros_H := \text{stack} \left( Block_{H_1}^{(2)}, Block_{H_2}^{(2)}, Block_{H_3}^{(2)}, Block_{H_4}^{(2)}, Block_{H_5}^{(2)} \right)$$

$${}_vte_H := \text{write\_matrix} \left( “.\backslash\text{Output}\backslash\text{HTAIL\_TeX\_Macros.tex”, }{}_vcomplete\_macros_H, “ ” \right)$$