

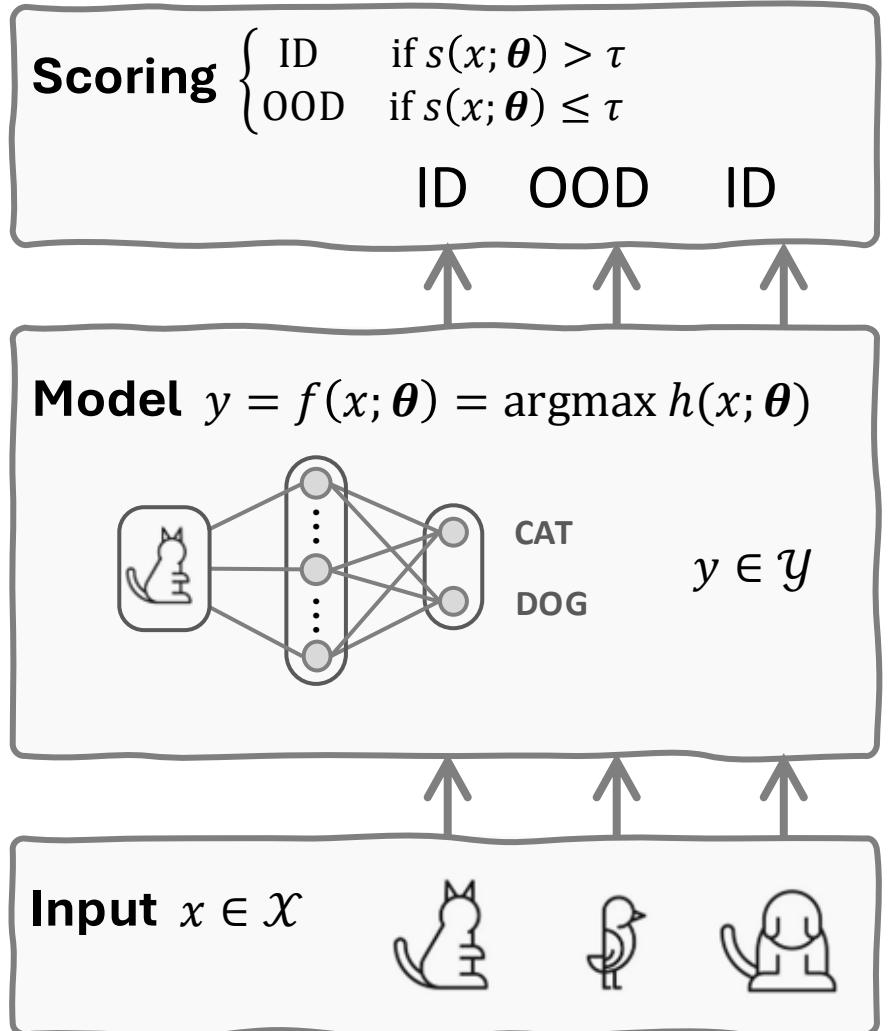
On the Insights and Strategies for OOD Detection Learning

Dr. Qizhou WANG
RIKEN AIP

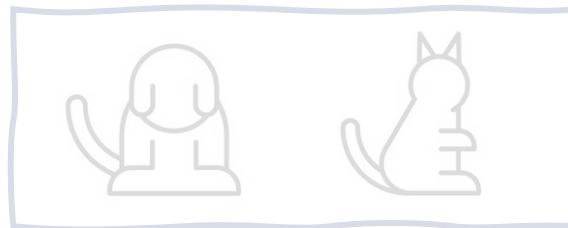
<https://qizhouwang.github.io/homepage>



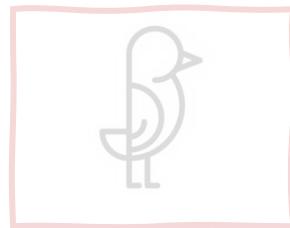
Post-hoc OOD Detection: Review



Semantic Shift: semantic relationship between inputs and labels changes.

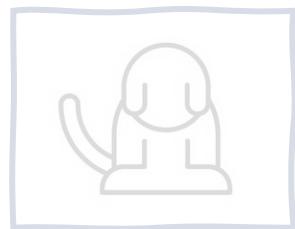


ID

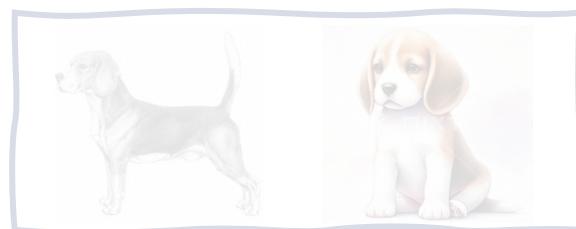


OOD

Covariate Shift: feature distribution changes while labels stay within the label space.



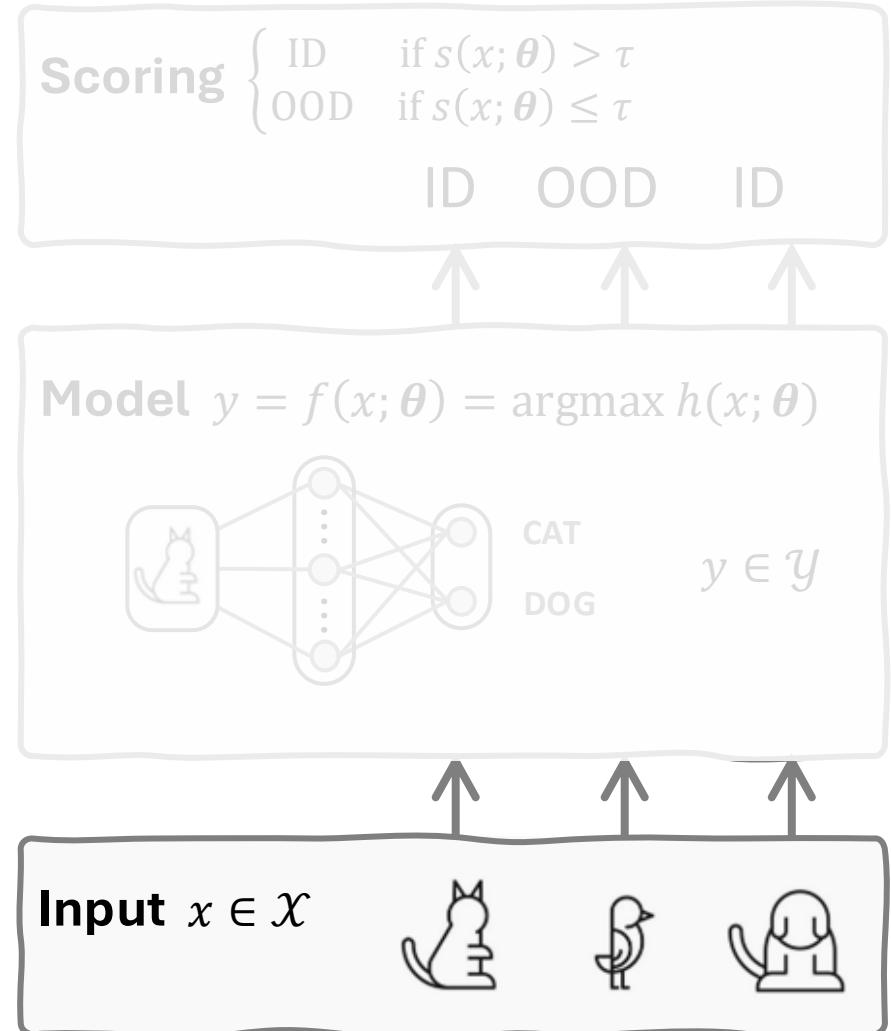
ID



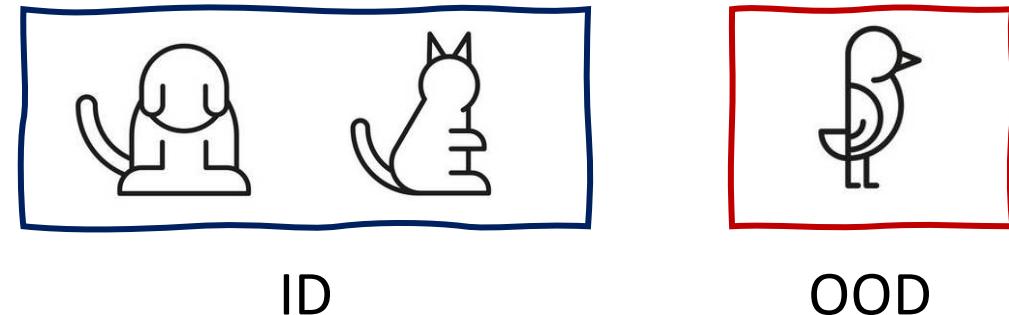
OOD

Post-hoc OOD Detection: Review

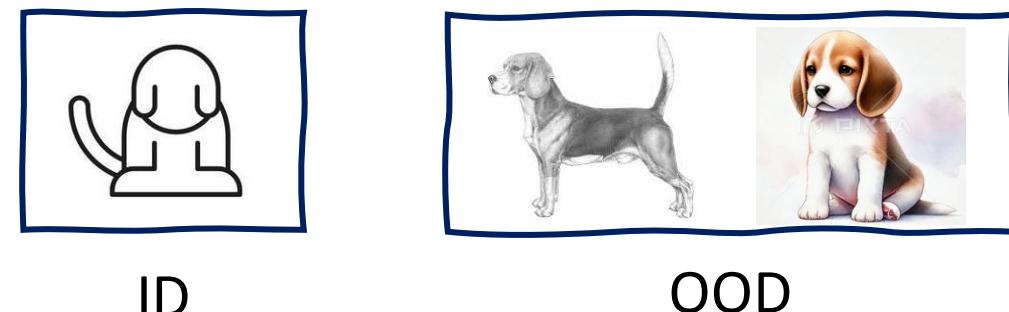
Interests of OOD detection



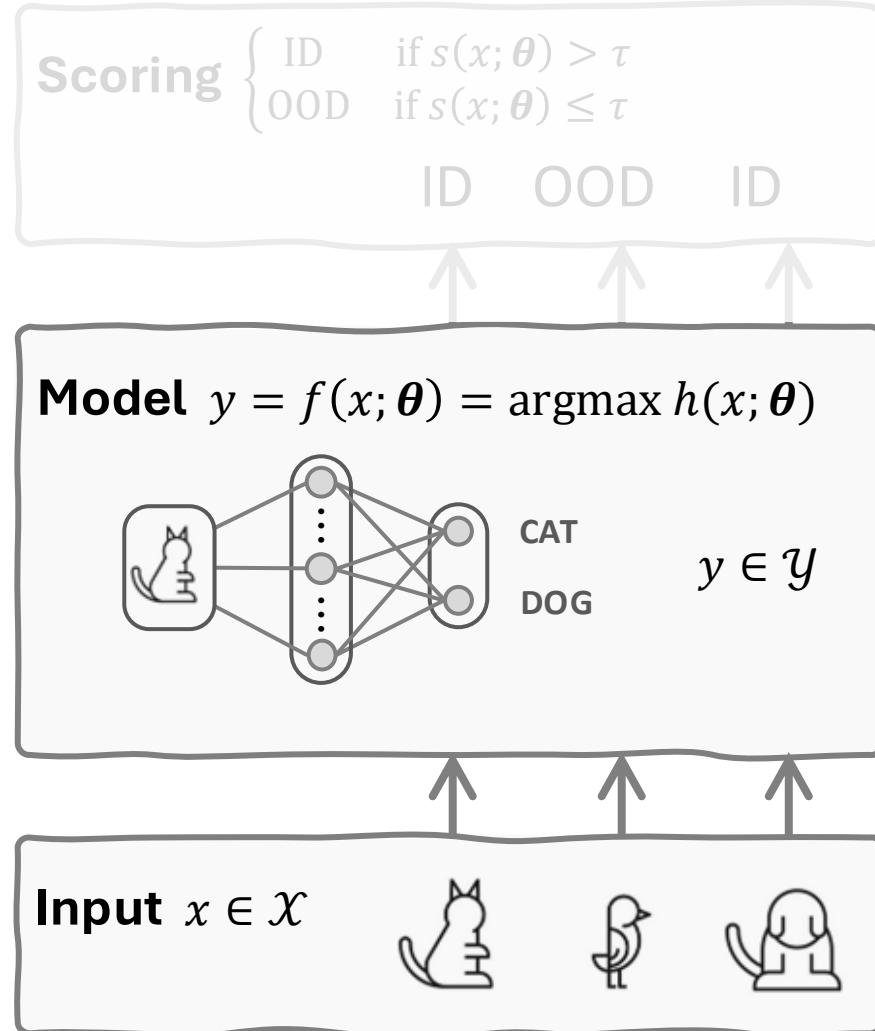
Semantic Shift: semantic relationship between inputs and labels changes.



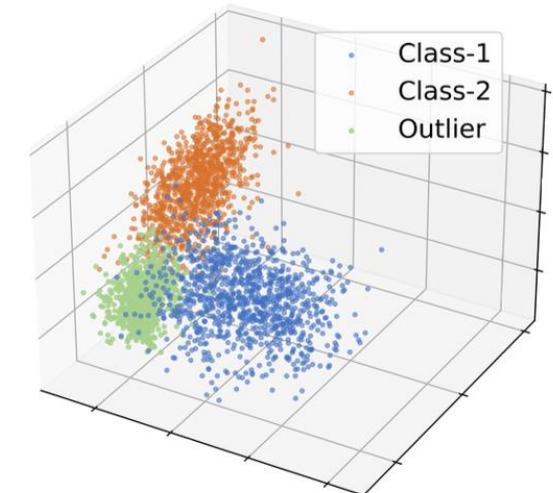
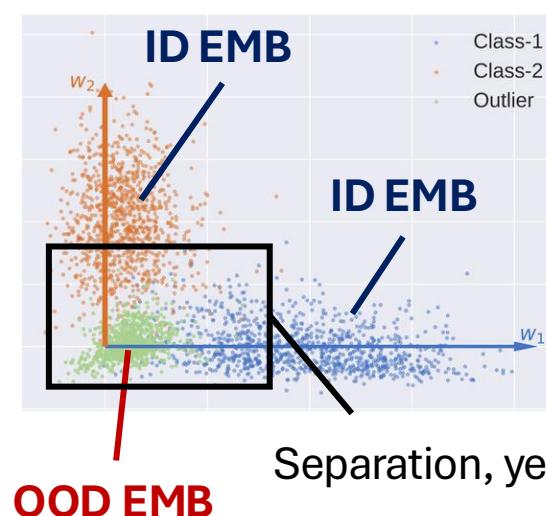
Covariate Shift: feature distribution changes while labels stay within the label space.



Post-hoc OOD Detection: Review

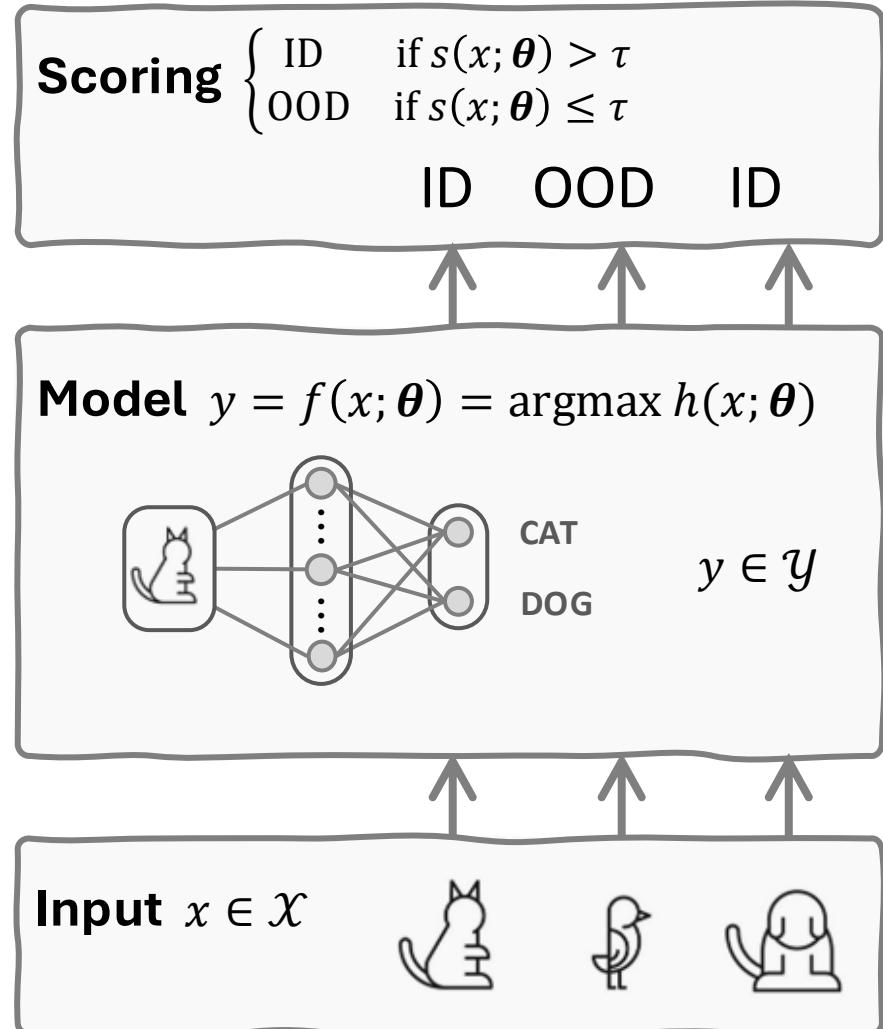


Pre-trained models can **separate ID and OOD data in embedding space** to some extent.



Figures of dimensional-reduced embeddings [a].

Post-hoc OOD Detection: Review



Model responses can be used to craft OOD scoring functions.

maximal softmax prediction

❖ **Output Level, MSP [a]**

$$s_{\text{MSP}}(x; \theta) = \max_k \text{softmax}_k h(x; \theta)$$

❖ **Embedding Level, KNN [b]**

$$s_{\text{KNN}}(x; \theta) = \|h(x; \theta) - z_{(k)}\|_2$$

k-th nearest neighbor

uniform distribution

❖ **Gradient Level, GradNorm [c]**

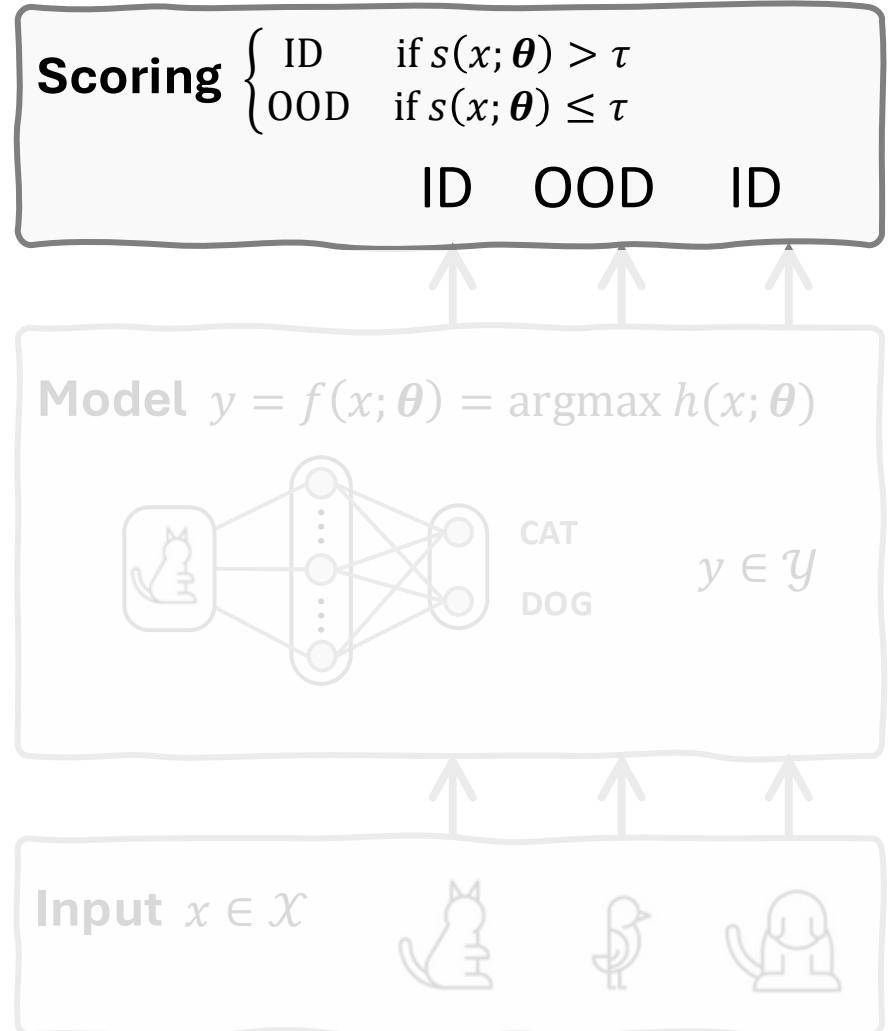
$$s_{\text{GN}}(x; \theta) = \|\nabla_{\theta} \text{KL}(u || \text{softmax}(h(x; \theta)))\|_2$$

[a] Hendrycks et al. A Baseline for Detecting Misclassified and Out-of-Distribution Examples in Neural Networks. In ICLR, 2017.

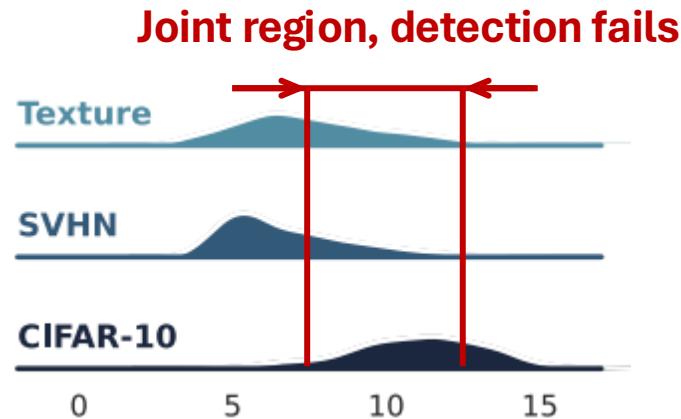
[b] Sun et al. Out-of-Distribution Detection with Deep Nearest Neighbors. In ICML, 2022.

[c] Huang et al. On the Importance of Gradients for Detecting Distributional Shifts in the Wild. In NeurIPS, 2021.

Post-hoc OOD Detection: Challenges



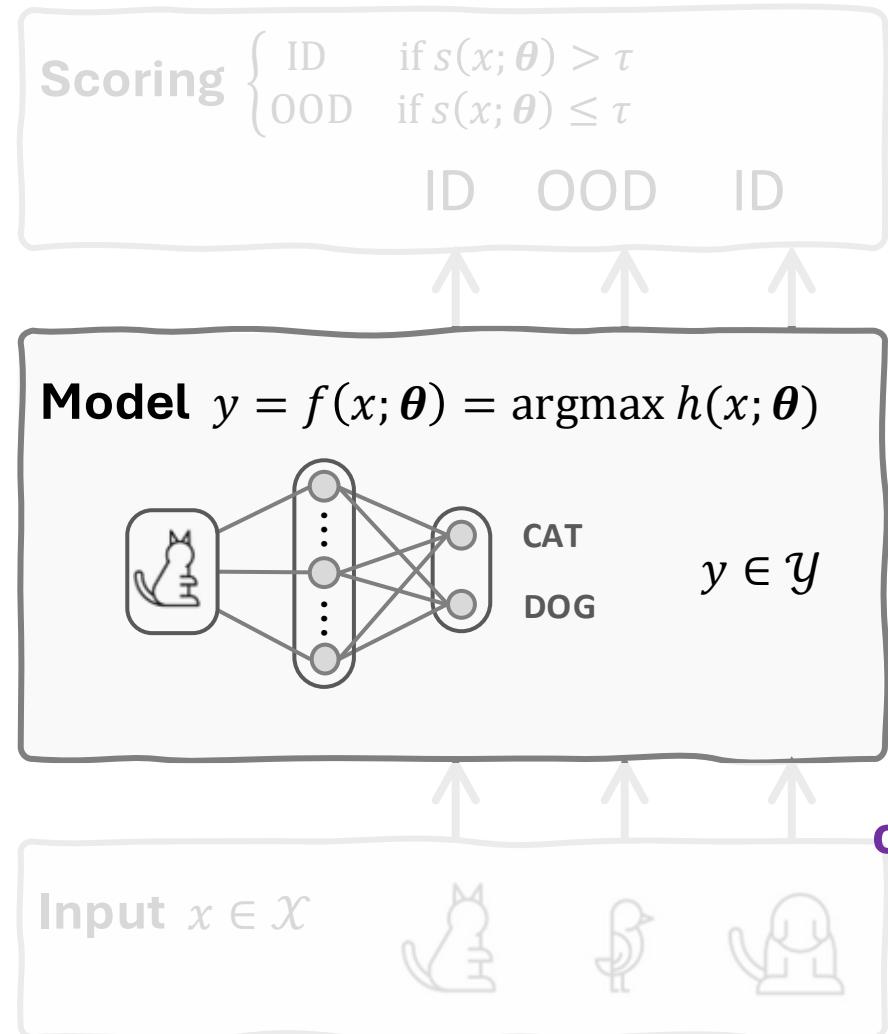
Post-hoc OOD detection often **makes mistakes**, failing to discern many ID and OOD patterns.



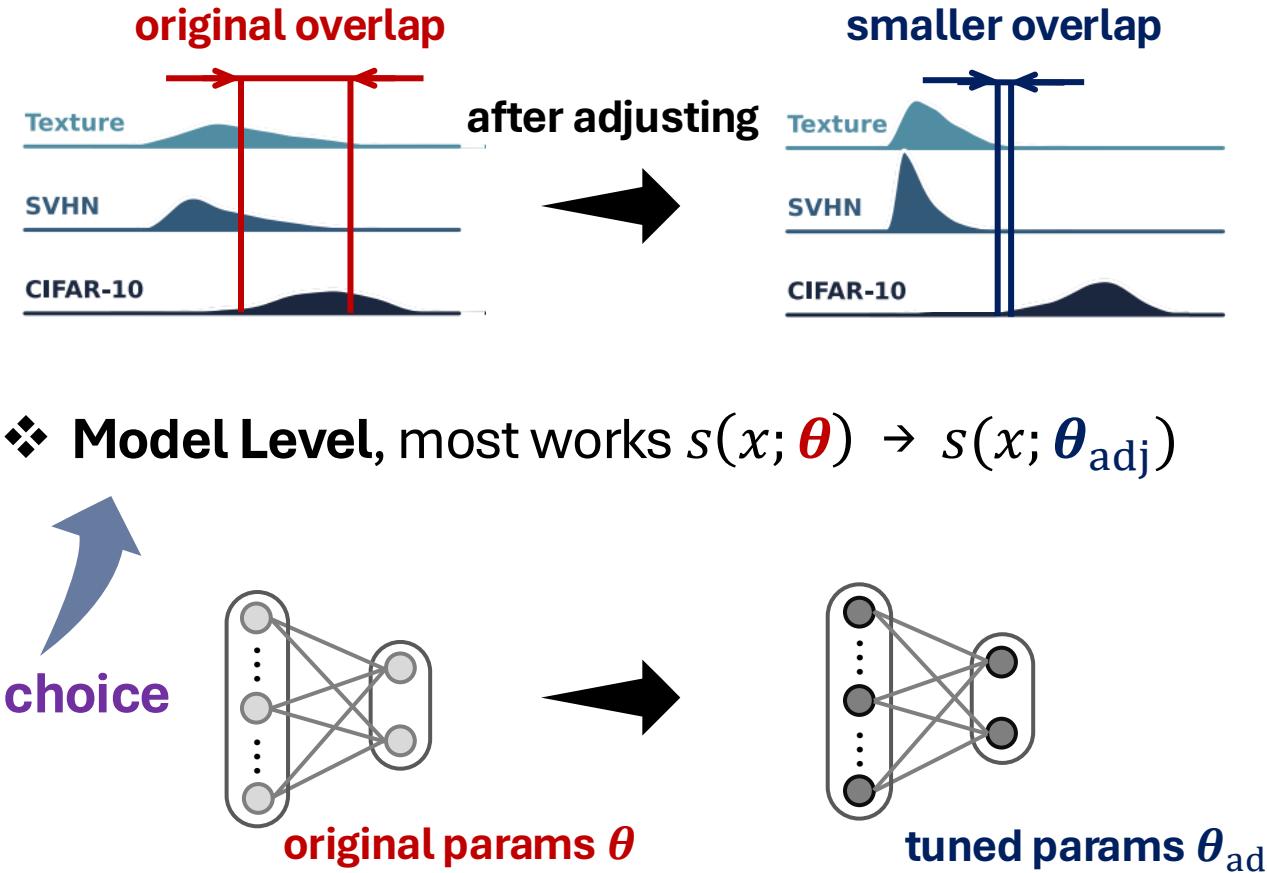
Figures of ID & OOD scoring distributions [a].

Explanations: For conventional-trained models, 1) their **representations** are not good enough, b) their **calibration** is inherently poor, and c) they cannot fully **classify** ID and OOD patterns.

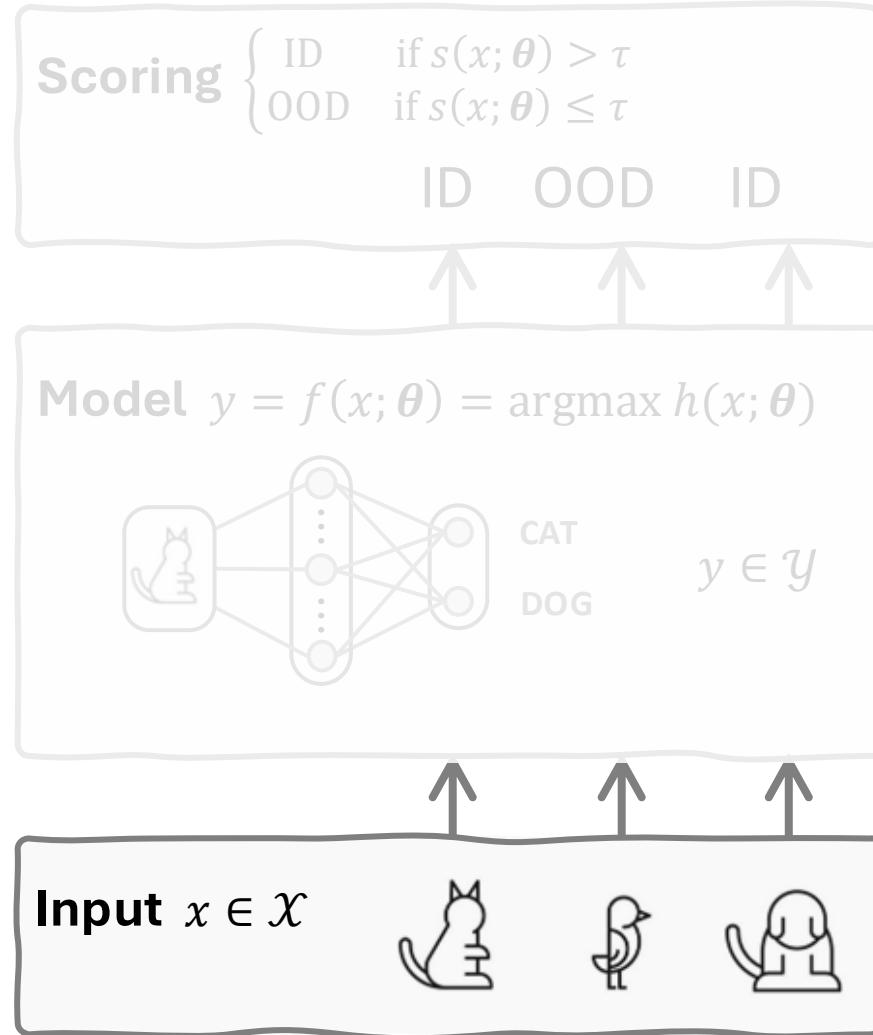
OOD Detection Learning: What to Adjust?



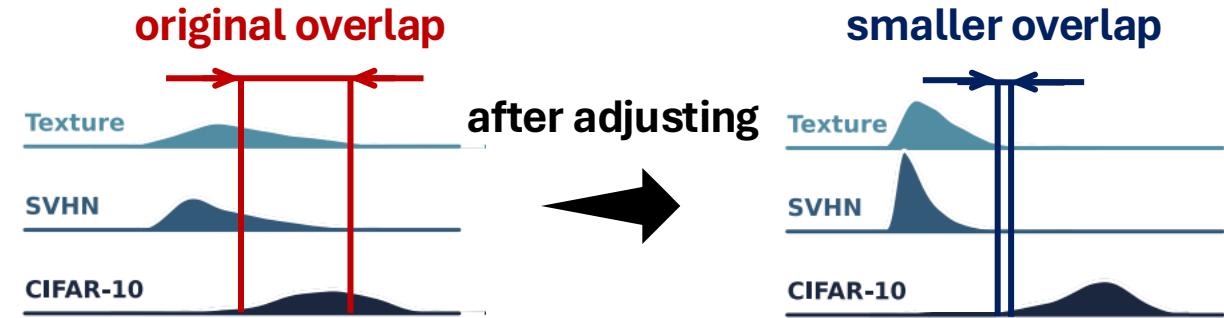
Adjust the system to improve OOD detection.



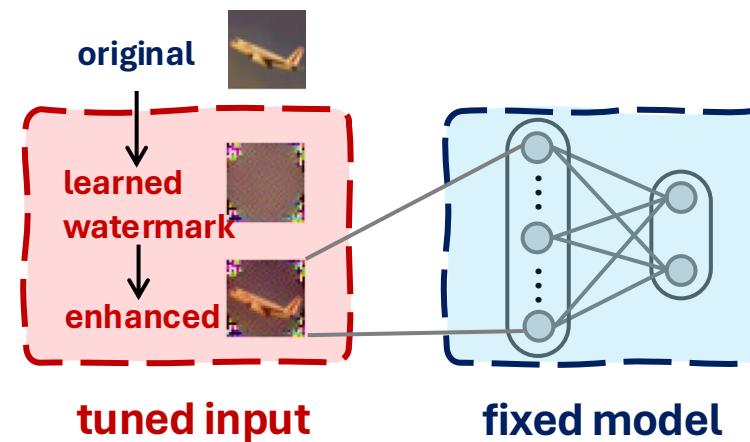
OOD Detection Learning: What to Adjust?



Adjust the system to improve OOD detection.

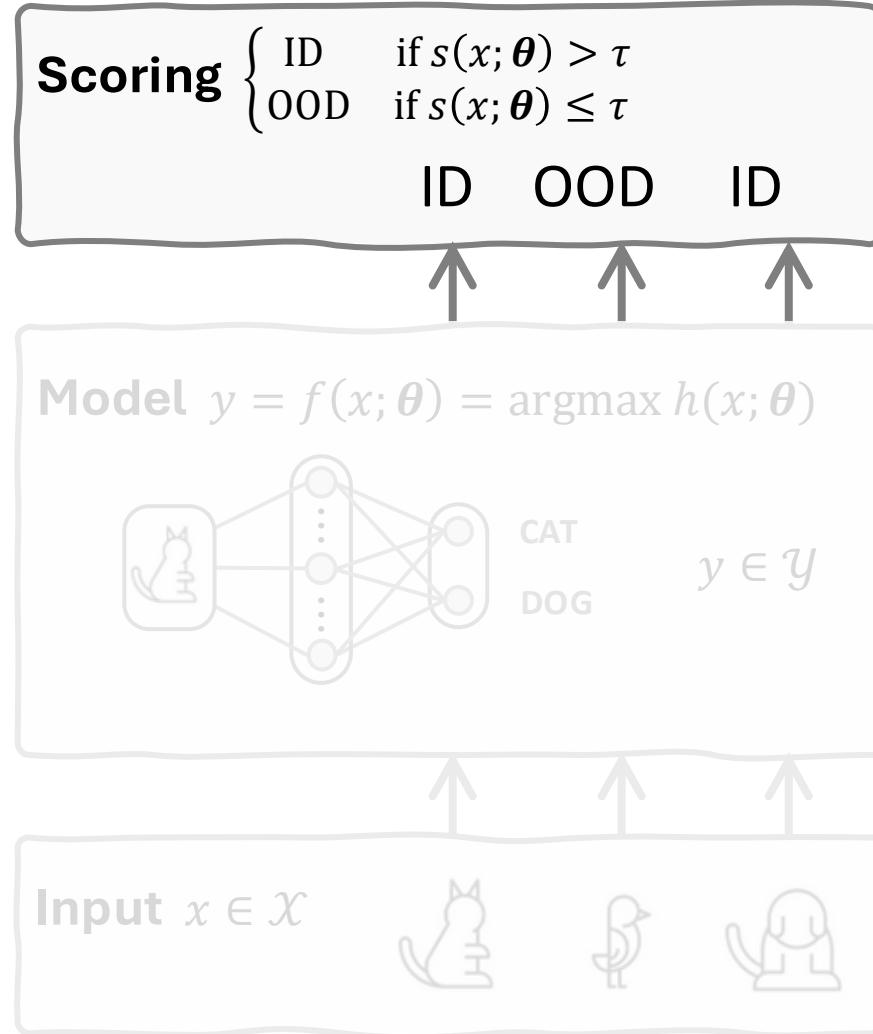


❖ **Input Level, WM [a]** $s(x; \theta) \rightarrow s(x + w; \theta)$



- ❖ Watermark is static, **tuned** to enhance OOD detection.
- ❖ The pre-trained model remains **fixed**.

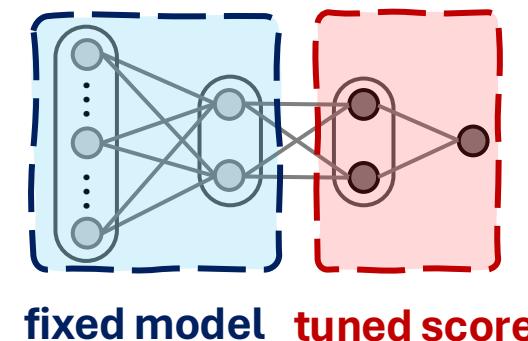
OOD Detection Learning: What to Adjust?



Adjust the system to improve OOD detection.



❖ **Score Level, VOS [a]** $s(x; \theta) \rightarrow s(h(x; \theta), \mathbf{w})$



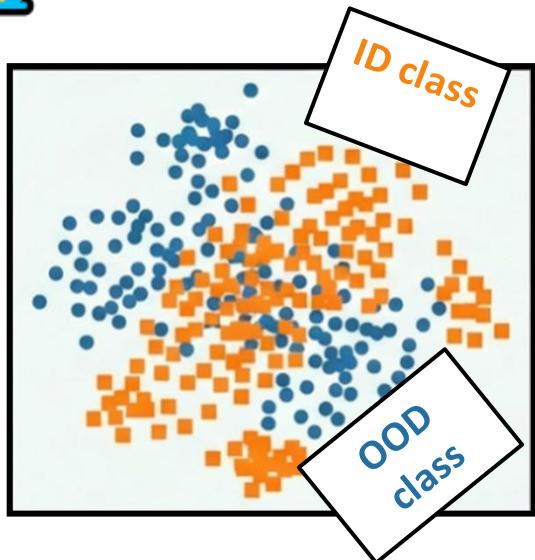
- ❖ *The scoring function introduces exact params to be tuned.*
- ❖ *The pre-trained model remains fixed.*

OOD Detection Learning: How to Adjust?

Let's recall **the drawbacks of post-hoc OOD detection**: For conventional-trained models, they have



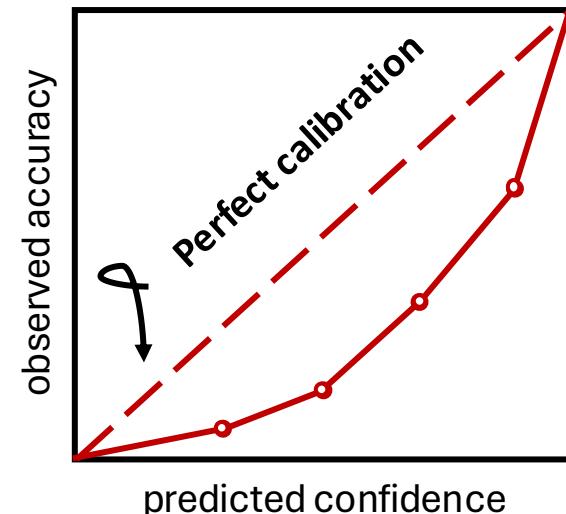
Poor Representation



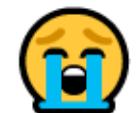
Data with **different semantics** may **not be perfectly separated** in the embedding space.



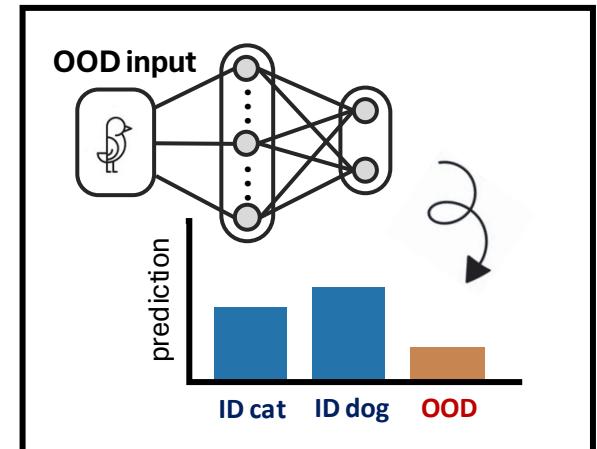
Poor Calibration



High model confidence does not correspond to **high model accuracy**.



Poor Classification



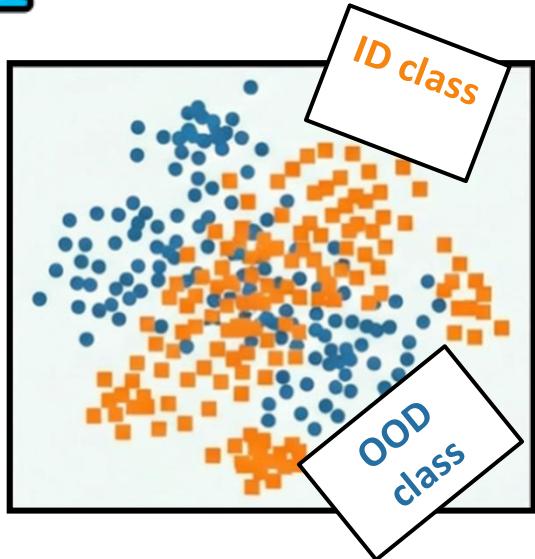
The model **predicts the wrong class**, despite the true class of being either ID or OOD.

OOD Detection Learning: How to Adjust?

Let's recall the drawbacks of post-hoc OOD detection: For conventional-trained models, they have



Poor Representation



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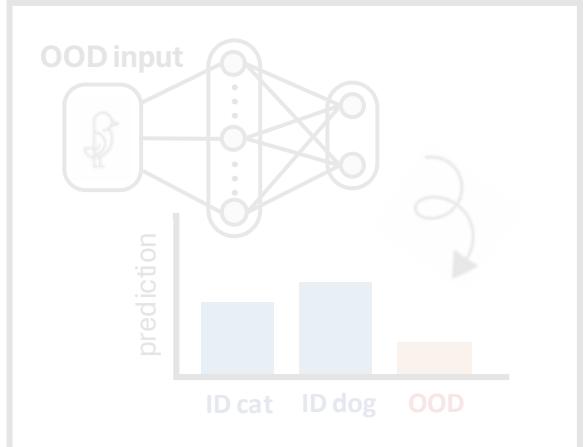


Poor Calibration

- ❖ **What happens?**
ID and OOD examples are **entangled** in the embedding space.
- ❖ **Why breaks detection?**
Many methods (e.g., k-nearest neighbors and Mahalanobis) **assume that OOD lies away from ID**.
predicted confidence does not correspond to high model accuracy.



Poor Classification



The model **predicts the wrong class**, despite the true class of being either ID or OOD.

OOD Detection Learning: How to Adjust?

Let's recall the drawbacks of post-hoc OOD detection: For conventional-trained models, they have



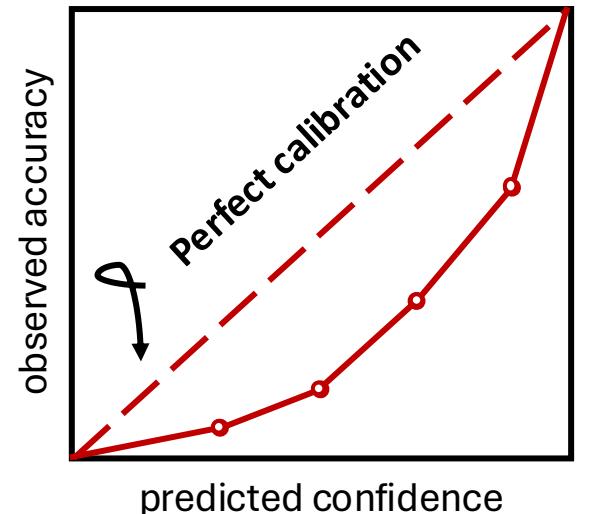
Poor Representation



Data with **different semantics** may not be perfectly separated in the embedding space.



Poor Calibration



High model confidence does not correspond to **high model accuracy**.



Poor Classification

- ❖ **What happens?**
Models produce **high confidence for wrong predictions**.
- ❖ **Why breaks detection?**
Many methods (e.g., MSP) use **confidence-like scores**.

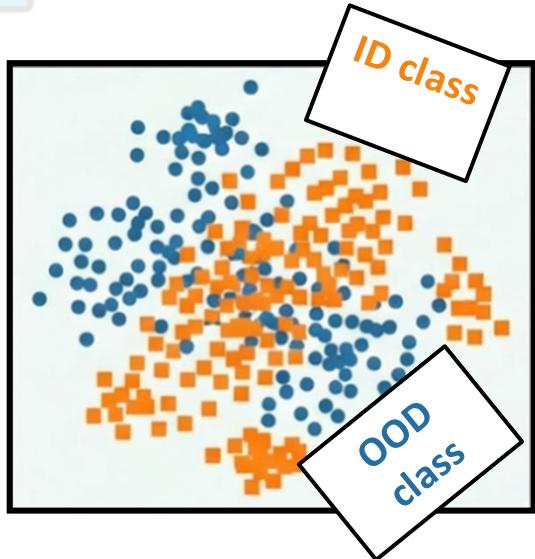
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OOD Detection Learning: How to Adjust?

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Poor Representation

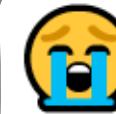


Data with **different semantics** may not be perfectly separated in the embedding space.

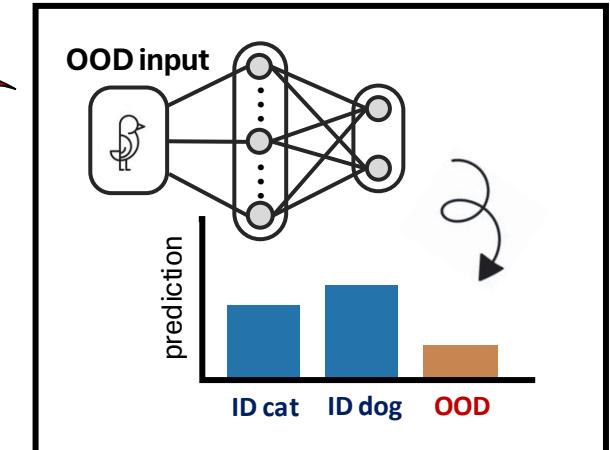


Poor Calibration

- ❖ **What happens?**
Decision boundaries does not align with true ID/OOD classes.
- ❖ **Why breaks detection?**
Taking as an **extra classification task**, this classifier is not accurate.
High model confidence does not correspond to *high model accuracy*.



Poor Classification



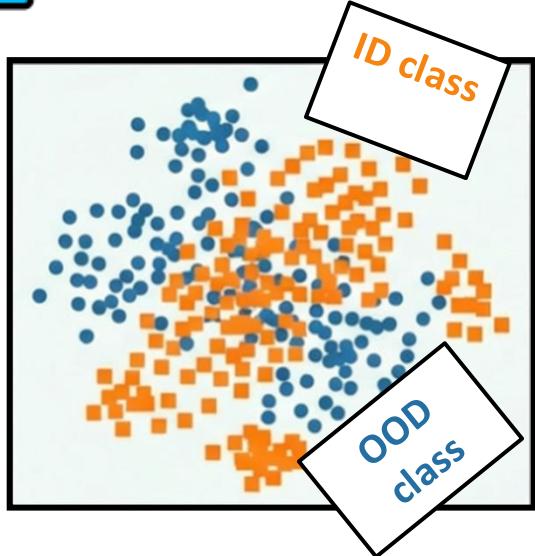
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OOD Detection Learning: How to Adjust?

Let's recall the drawbacks of post-hoc OOD detection: For conventional-trained models, they have



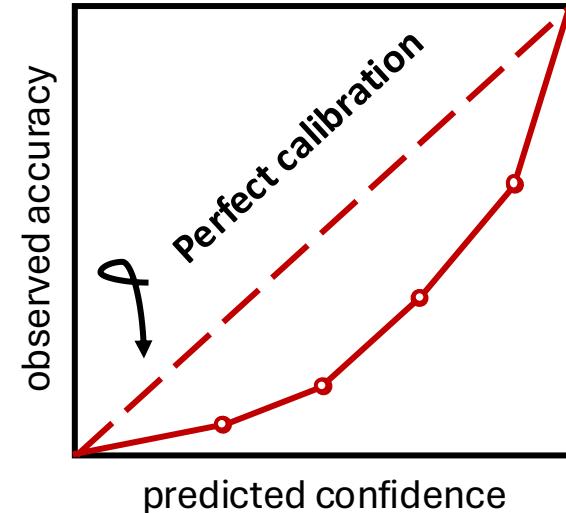
Poor Representation



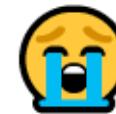
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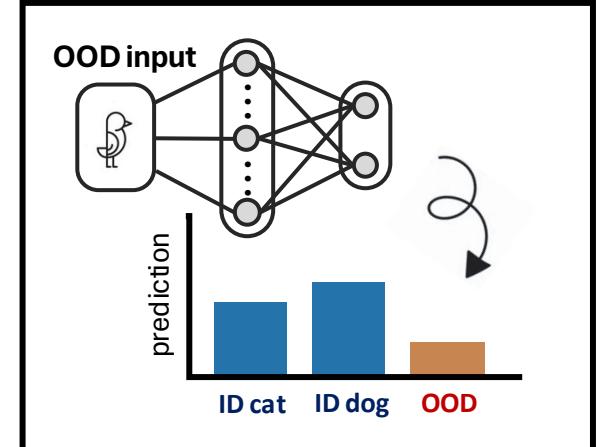
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High model confidence does not correspond to **high model accuracy**.



Poor Classification



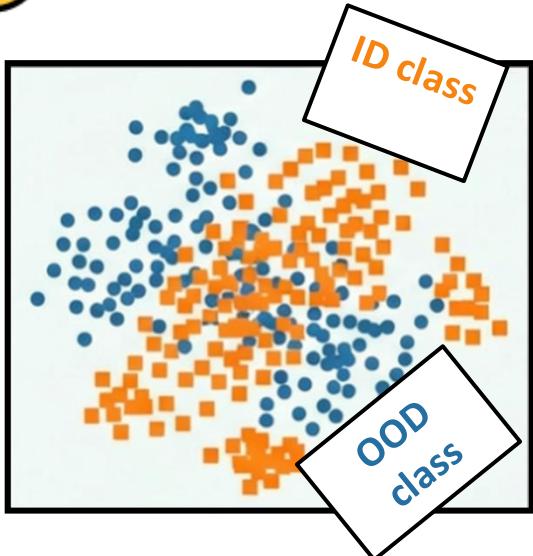
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OOD Detection Learning: How to Adjust?

To address the drawbacks of post-hoc OOD detection, OOD detection learning can



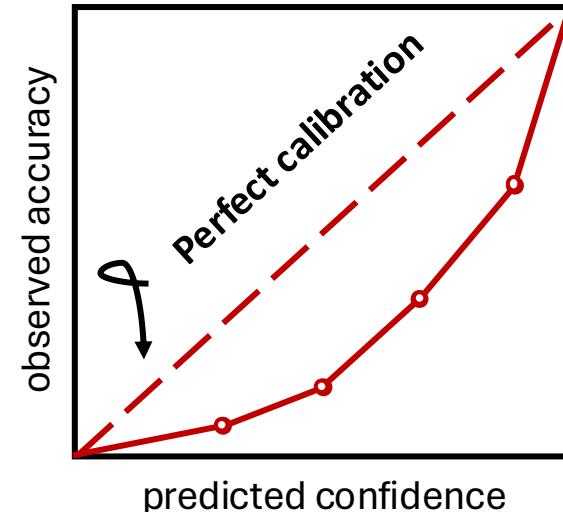
Improve Representation



- ❖ contrastive learning,
- ❖ reconstruction learning,
- ❖ pre-training, et al.



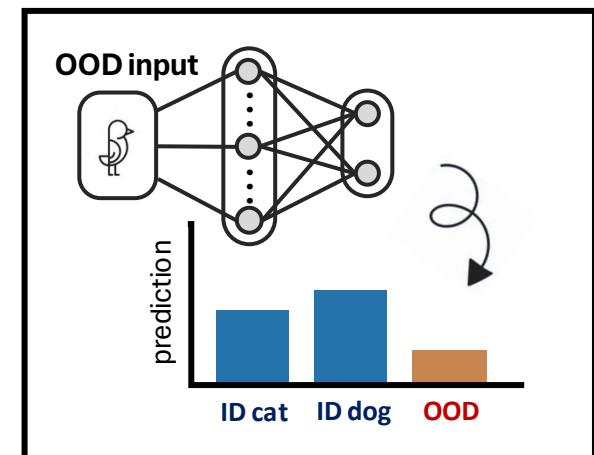
Improve Calibration



- ❖ Bayesian scoring,
- ❖ density regularization,
- ❖ calibration, et al.



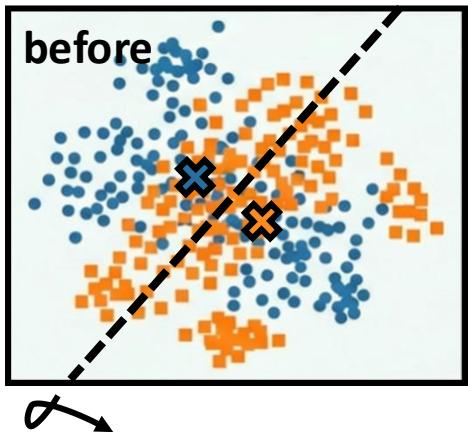
Improve Classification



- ❖ outlier exposure,
- ❖ data augmentation,
- ❖ sample selection, et al.

Representation: Overview

Conventional-trained Classifiers



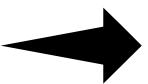
A simple OOD scoring : Nearest distances to K-means clustering.

$$s_{\text{KM}}(x; \theta) = \|h(x; \theta) - \mu_{(x)}\|_2$$

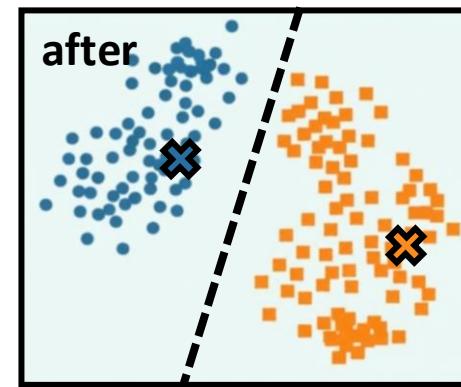
/

nearest ID centroid

- ❖ make **no assumptions about the form of OOD data** will take or the type of downstream task.
- ❖ mainly learn patterns among training classes as a **shortcut to learn classification**.



Representation-based OOD Learning



Representations with different semantics are better separated.

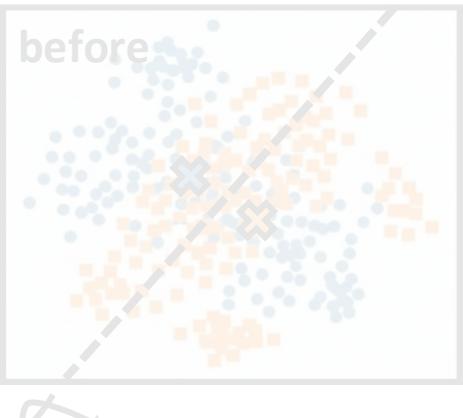
- ❖ low intra-class variance
- ❖ high inter-class variance

Pretext tasks

- ❖ **Contrastive Learning:** CSI, SSD
- ❖ **Reconstruction Learning:** MOOD
- ❖ **Pre-training:** CLIP

Representation: Overview

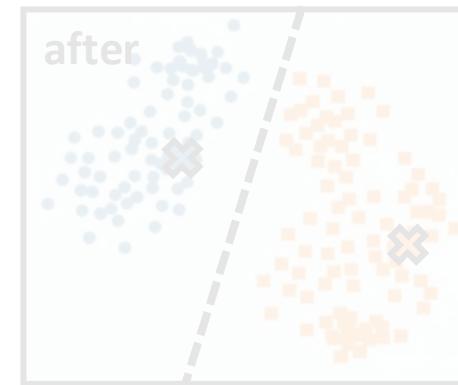
Conventional-trained Classifiers



A simple OOD scoring : Nearest distances to K-means clustering.

$$s_{\text{KM}}(x; \theta) = \|h(x; \theta) - \mu_{(x)}\|_2 / \text{nearest ID centroid}$$

Representation-based OOD Learning



after

Representations with different semantics are better separated.

- ❖ low intra-class variance
- ❖ high inter-class variance

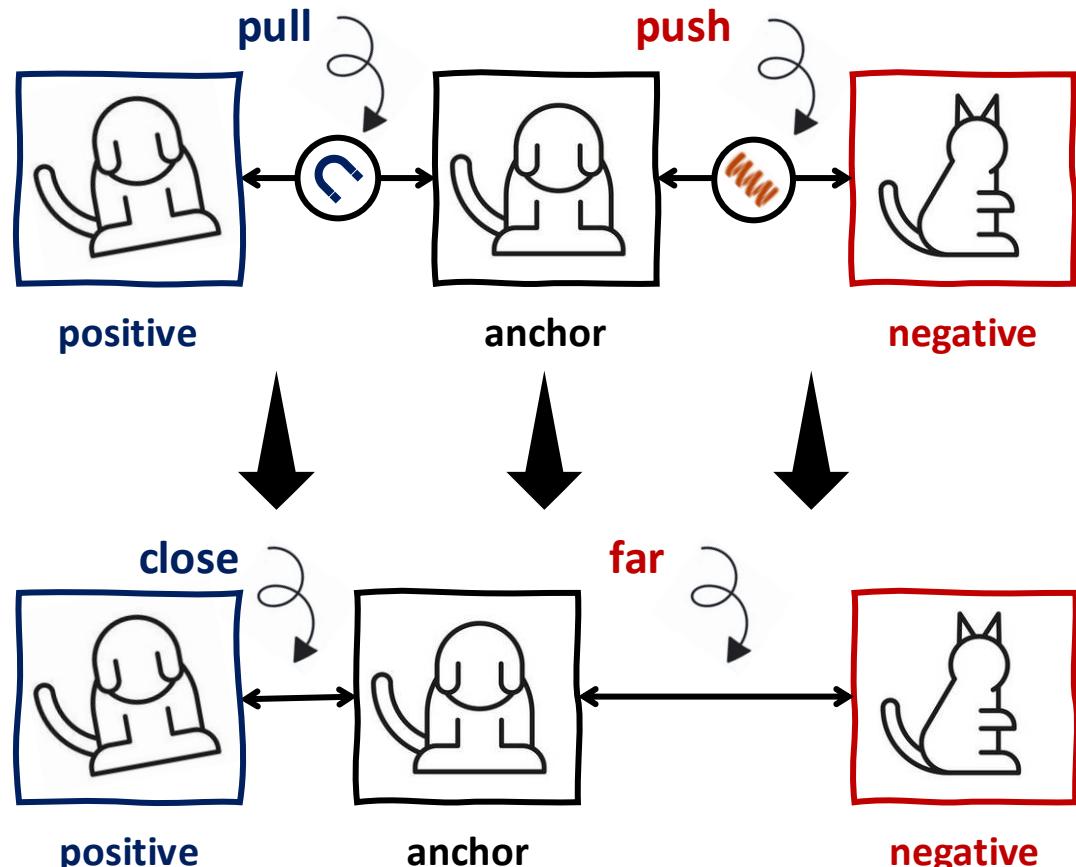
- ❖ make no assumptions about the form of OOD data will take or the type of downstream task.
- ❖ mainly learn patterns among training classes as a shortcut to learn classification.

Pretext tasks

- ❖ **Contrastive Learning:** CSI, SSD
- ❖ **Reconstruction Learning:** MOOD
- ❖ **Pre-training:** CLIP

Representation: Contrastive Learning

Contrastive learning **improves the semantic structure of the embedding space** by pulling semantically similar samples together and **pushing** dissimilar ones apart.



Supervised Contrastive Learning

$$\mathcal{L}_{\text{con}}(x, \{x_+\}, \{x_-\}) = -\frac{1}{|\{x_+\}|} \log \frac{\sum_{x' \in \{x_+\}} \exp\{\text{sim}(z(x), z(x'))\}}{\sum_{x' \in \{x_+\} \cup \{x_-\}} \exp(\text{sim}(z(x), z(x')))}$$

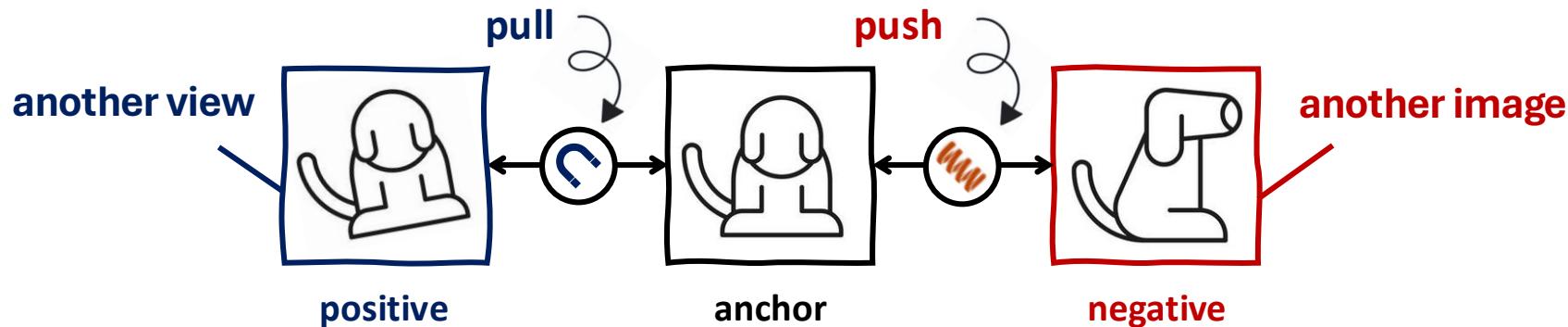
positive **anchor**

Increasing similarity between the anchor and **positive samples**, while **decreasing similarity** to **negative samples**.

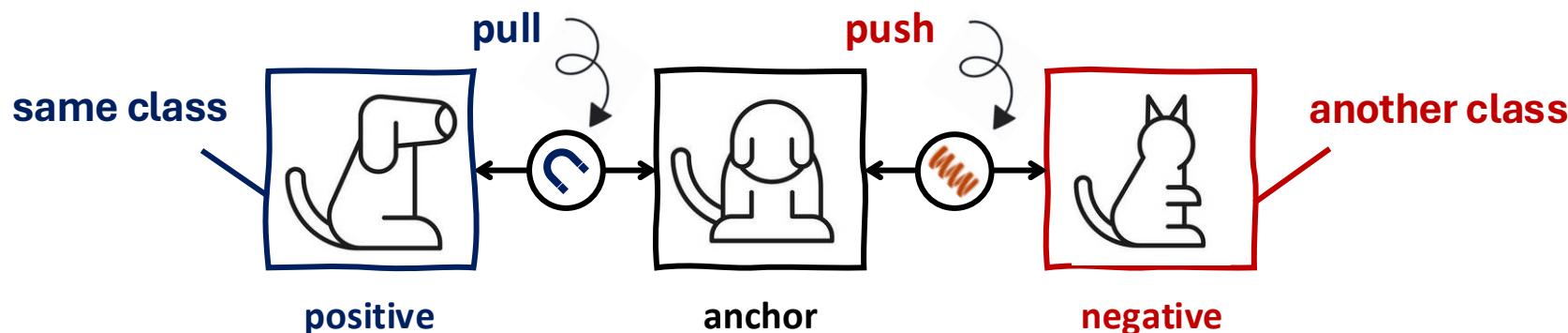
Representation: Contrastive Learning—SSD

SSD [a] Training Objective.

- ❖ SSD, discriminating between **individuals** (**label-agnostic**).



- ❖ SSD+, discriminating between **classes** (**label-aware**).



Representation: Contrastive Learning—SSD

SSD OOD Detector.

- ❖ **Mahalanobis**, cluster-conditioned detection (**OOD-agnostic**).

$$s_{\text{mah}}(x; \theta) = \min_k (z(x) - \mu_k)^T \Sigma_k^{-1} (z(x) - \mu_k)$$

k-th ID cluster centroid

k-th ID cluster covariance, decorrelating features

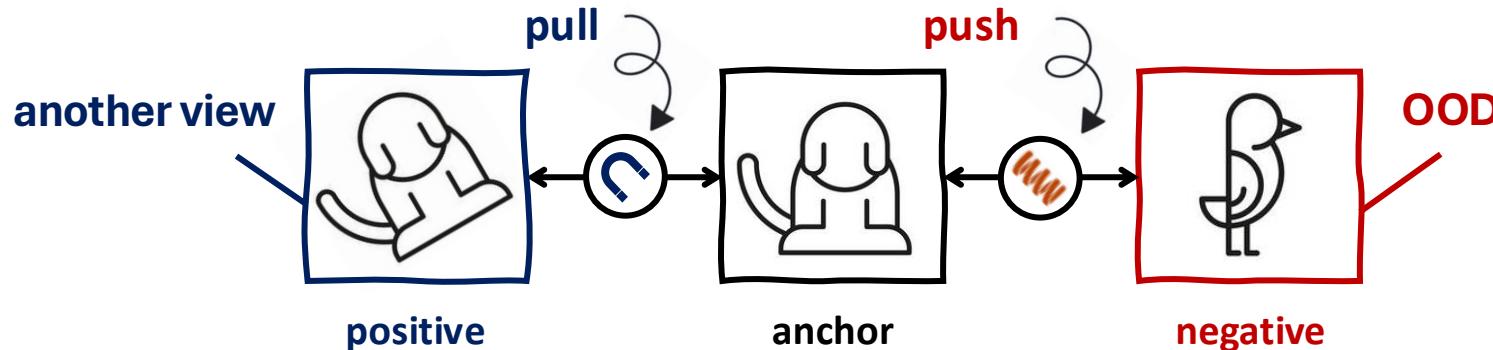
- ❖ **Mahalanobis+**, a small OOD set is available before inference (**few-shot OOD**).

$$s_{\text{mah+}}(x; \theta) = (z(x) - \mu_{id})^T \Sigma_{id}^{-1} (z(x) - \mu_{id}) - (z(x) - \mu_{ood})^T \Sigma_{ood}^{-1} (z(x) - \mu_{ood})$$

distance to overall ID centroid distance to overall OOD centroid

Representation: Contrastive Learning—CSI

CSI [a] further studies effective **negative transformation** to discriminate OOD samples.



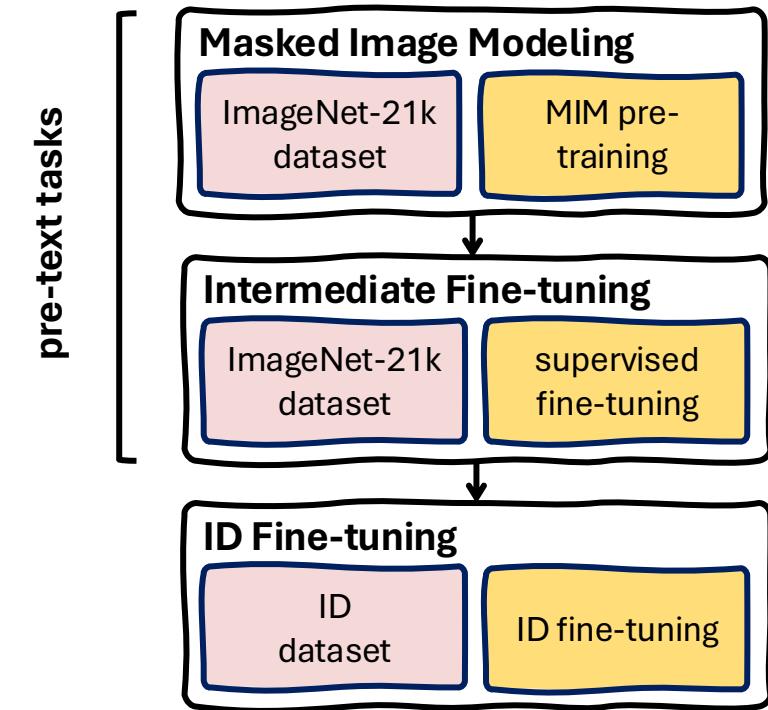
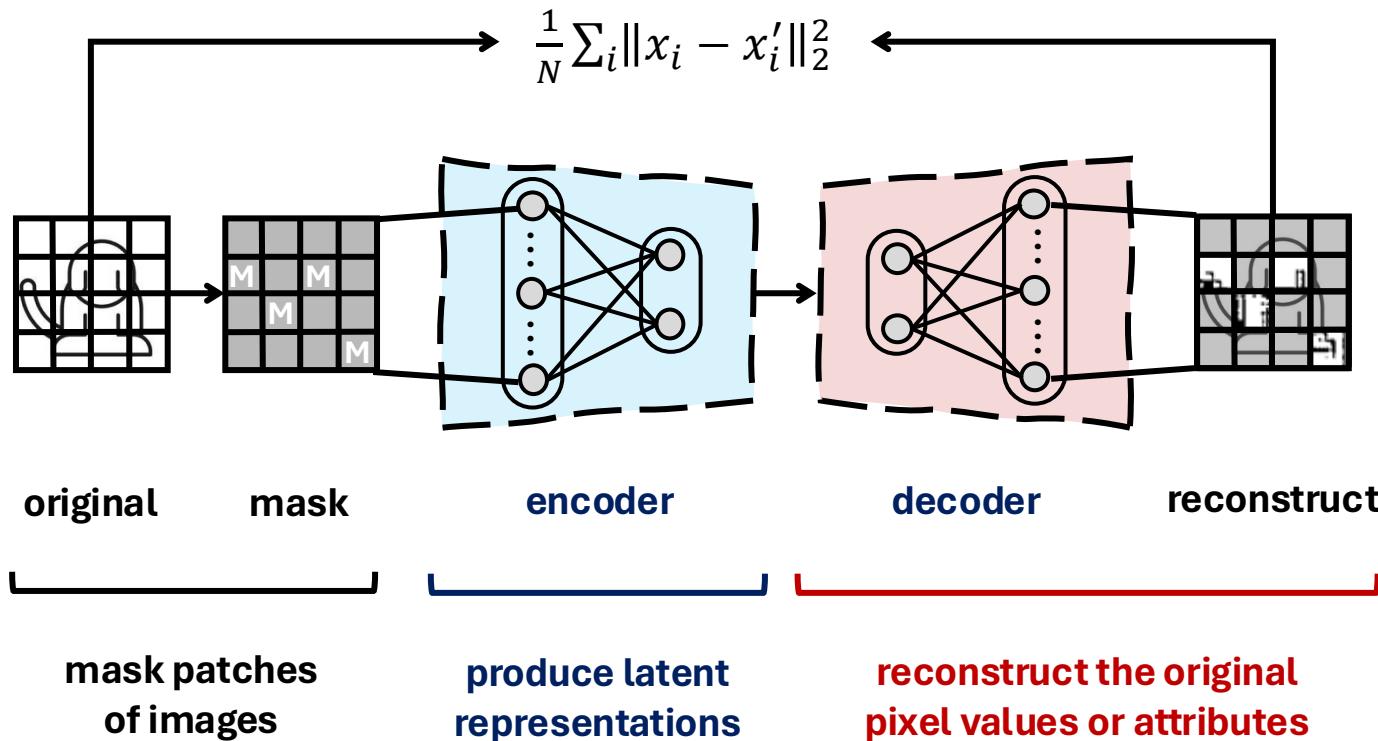
What if no OOD data are available? Those transformations previously found **ineffective as positive transformations** can instead be used as negative transformations.



Figure from [a].

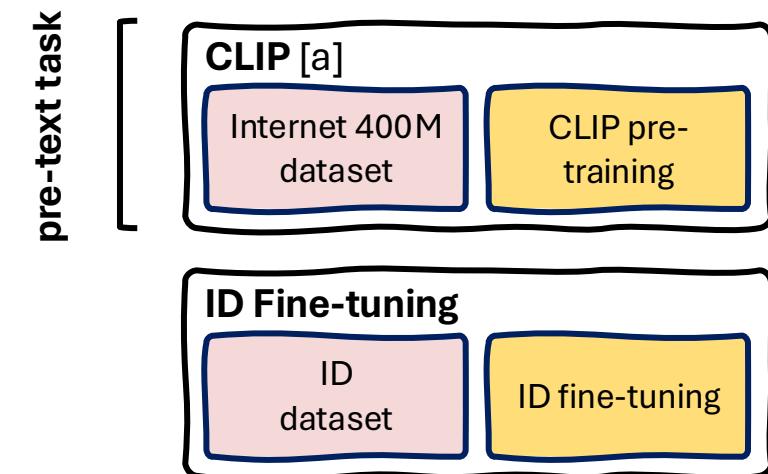
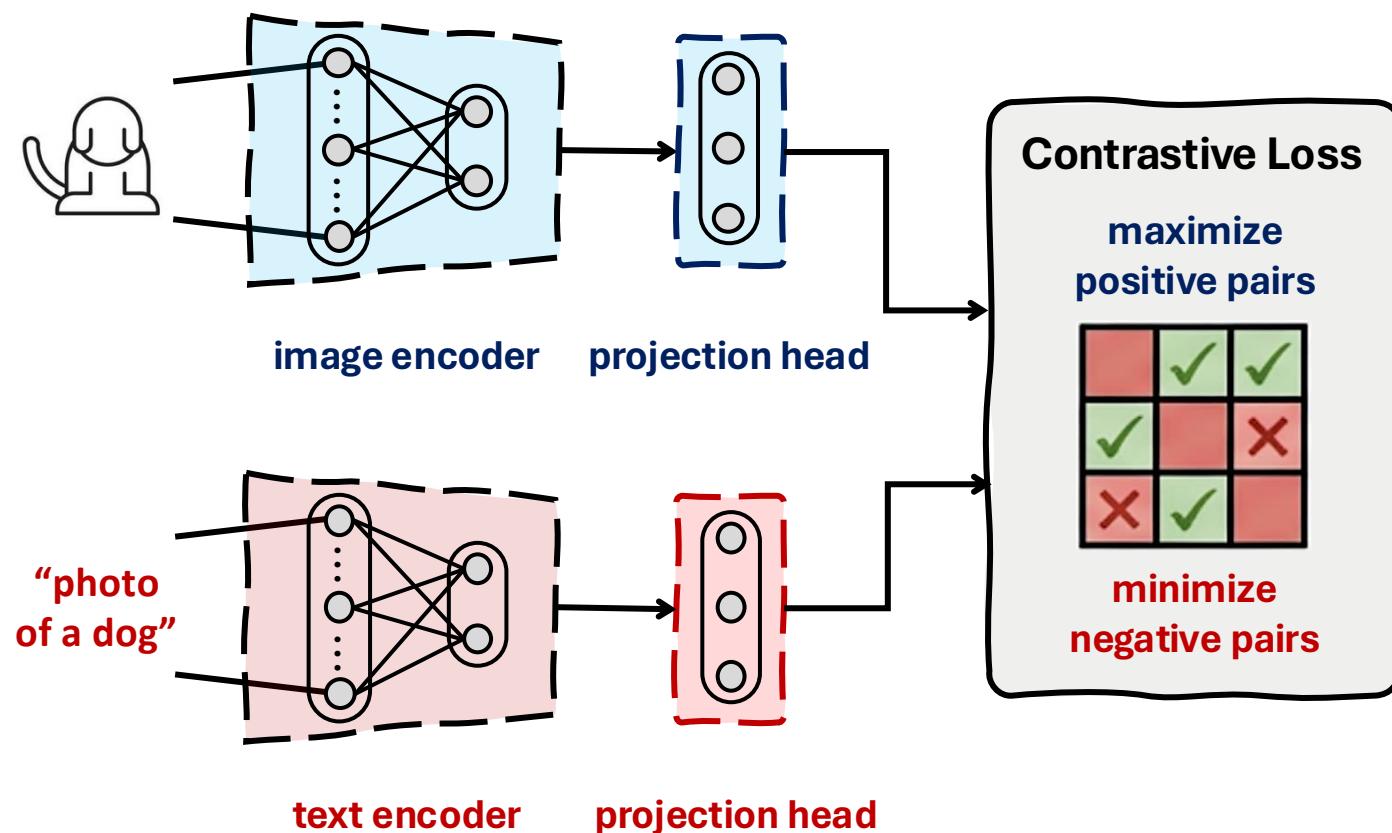
Representation: Reconstruction Learning—MOOD

MOOD [a] forces the models to **encode finer-grained information needed to rebuild input**, which is far beyond semantics as in contrastive learning.



Representation: Pre-training—CLIP

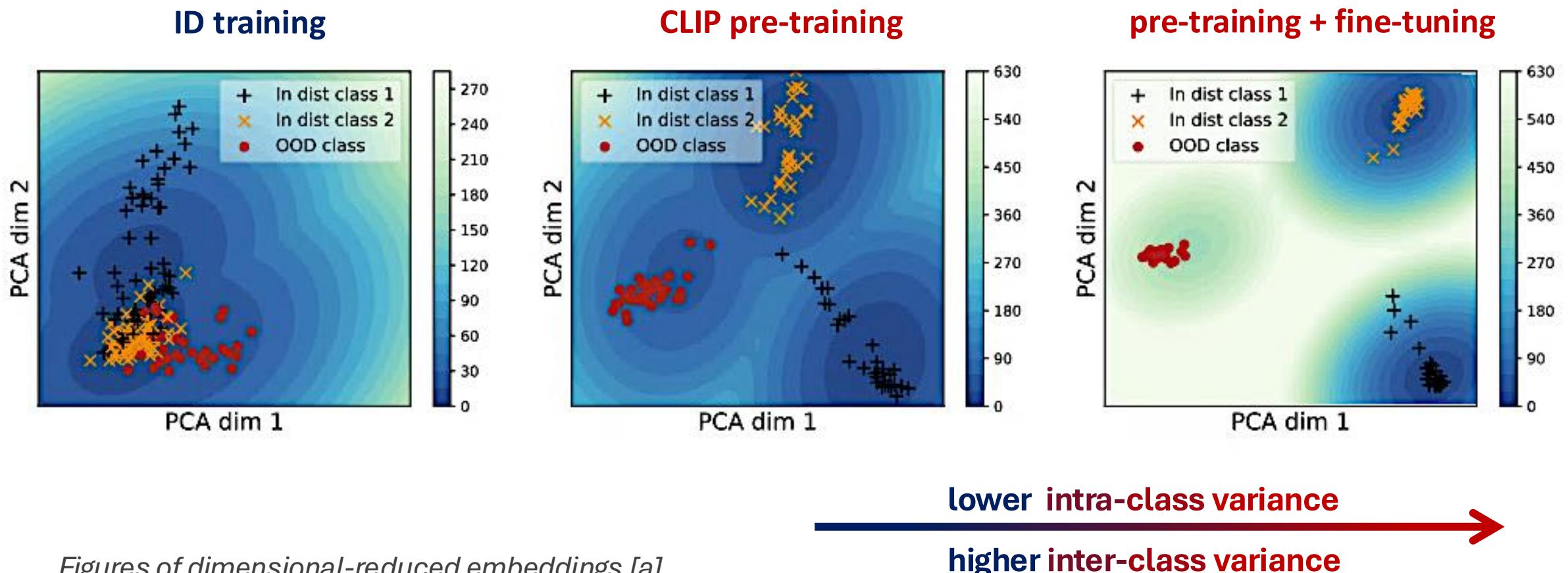
Cross-modal alignment reduces reliance on **the shortcut to learn classification**, encouraging more general, semantically meaningful features.



Aligns images and text representations by maximizing similarity of correct pairs, meanwhile minimizing similarity of incorrect pairs.

Representation: Pre-training—CLIP

Cross-modal alignment reduces reliance on **the shortcut to learn classification**, encouraging more general, semantically meaningful features.



Calibration: Overview

Let us review what we have learned from textbook [a].

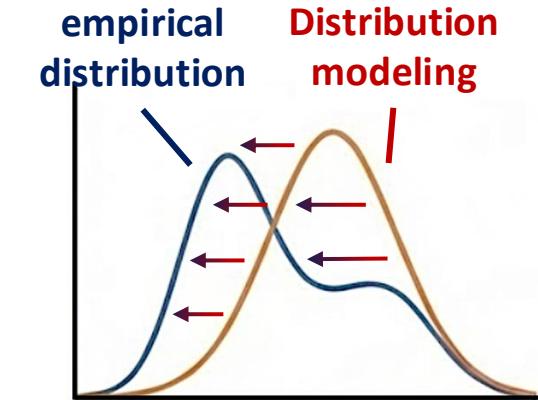
❖ Maximum Likelihood & KL Divergence

MLE minimizes KL between the **distribution model** and **empirical data distribution**.

$$p^* = \underset{p \in \mathcal{P}}{\operatorname{argmax}} \sum_i \log p(x_i) = \underset{p \in \mathcal{P}}{\operatorname{argmin}} \text{KL}(\hat{\mathcal{D}} \parallel p)$$

optimal solution

Condition 1.
proper distribution family Condition 2.
enough data



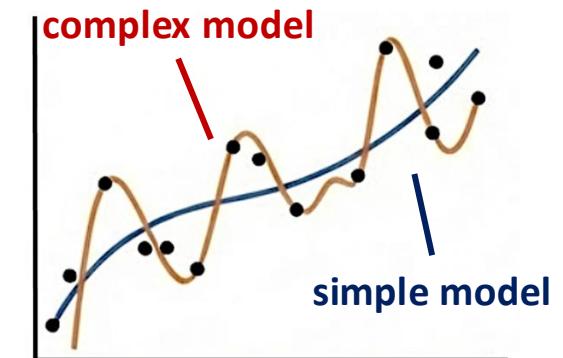
❖ Model Complexity & Estimation Error

Higher complexity increases estimation errors for a fixed dataset size.

$$\begin{aligned} & \left\| \underset{x \sim \mathcal{D}}{\mathbb{E}} [\Phi(x)] - \underset{x \sim \hat{\mathcal{D}}}{\mathbb{E}} [\Phi(x)] \right\|_{\infty} \\ & \leq 2\mathfrak{R}_m(\mathcal{H}) + r \sqrt{\frac{\log 2/\delta}{2m}} \end{aligned}$$

estimation error

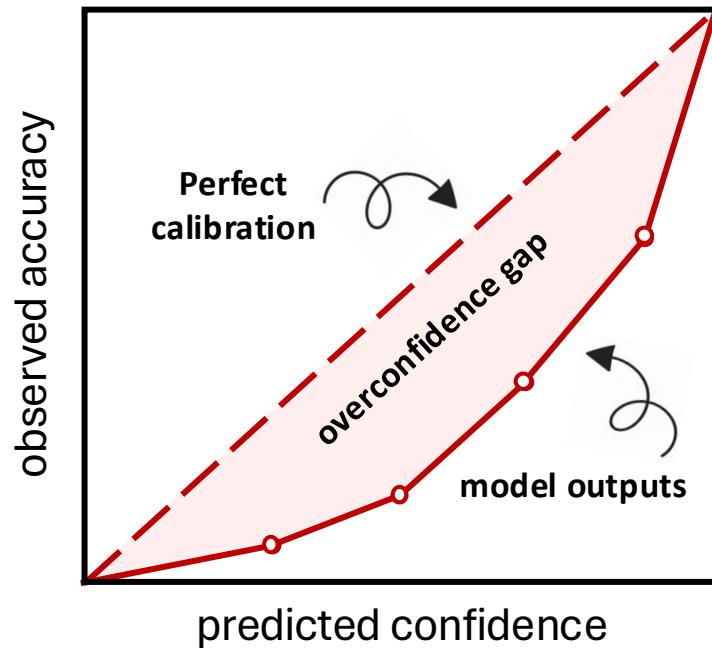
Condition 3.
proper model family



Calibration: Overview

Conditions 1-3 may not be fully satisfied in practice, leading to calibration failures.

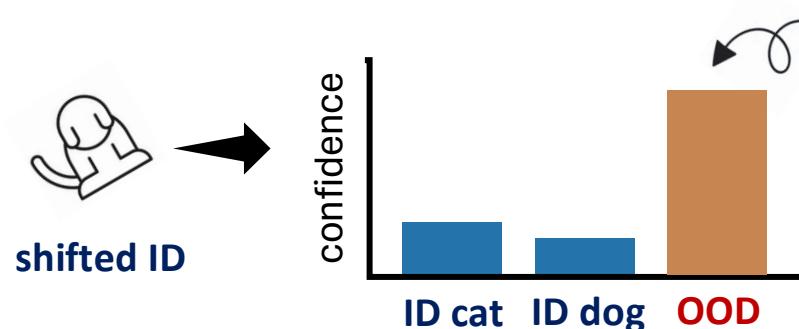
The overconfidence problem



Overconfidence makes the model outputs
appear more reliable than they really are.

Consequences

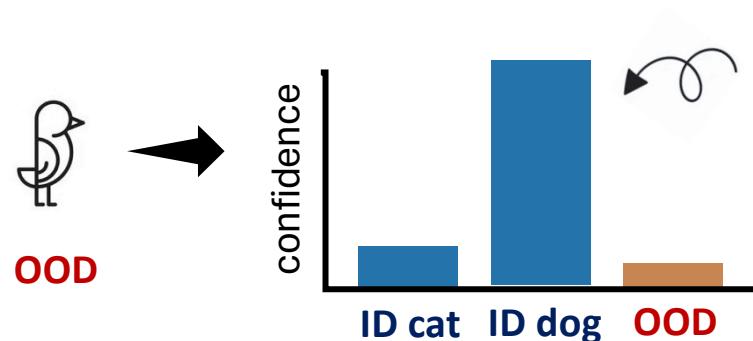
Mis-confidence on shifted ID



High probability to
OOD label

Data problem
(Condition 2)

Mis-confidence on OOD



High probability to
ID label

Modelling problem
(Condition 1 & 3)

Calibration: Overview

Conditions 1-3 may not be fully satisfied in practice, leading to calibration failures.

The overconfidence problem

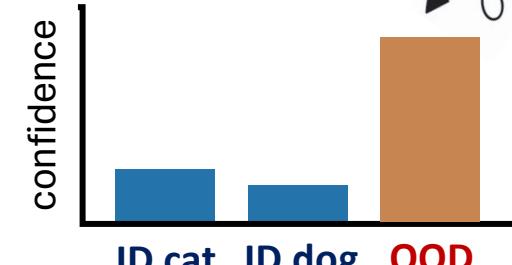
- ❖ **Data-centric Solutions.**
conventional calibration methods, such as label smoothing and mixup augmentations.
- ❖ **Model-centric Solutions.**
various regularization strategies.
- ❖ **Distribution-centric Solutions.**
Overconfidence makes the model outputs appear more reliable than they really are.
modelling **softmax**.

Consequences

Mis-confidence on shifted ID



shifted ID



High probability to
OOD label

Data problem
(Condition 2)

Mis-confidence on OOD



OOD



High probability to
ID label

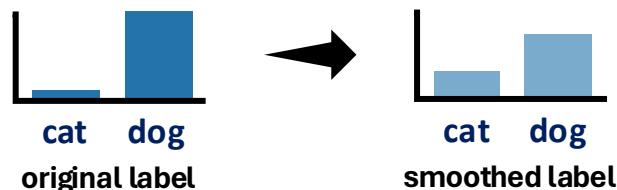
Modelling problem
(Condition 1 & 3)

Calibration: Data-centric Solutions

Conventional calibration strategies have been empirically shown to enhance OOD detection.

❖ Change Labels

label smoothing [a]



interpolation

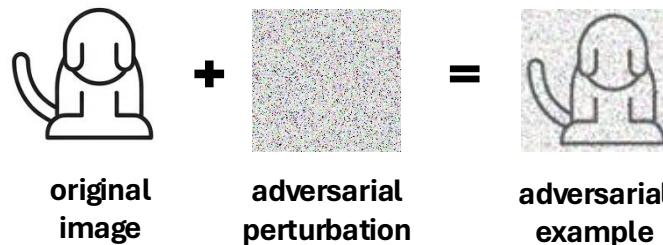
$$\tilde{y} = (1 - \alpha)y + \frac{\alpha}{c}$$

original label uniform

replaces one-hot labels with **slightly softened targets**.

❖ Change Inputs

adversarial examples [b]



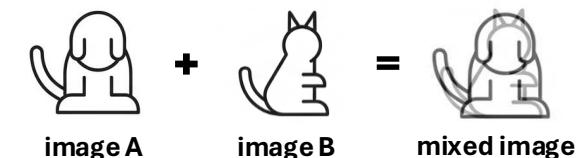
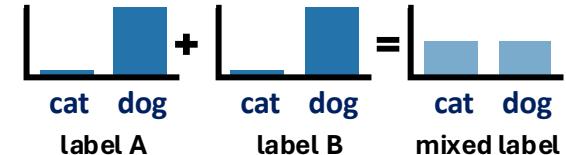
$$\max_{\delta \in \Delta} \mathcal{L}(x + \delta, y, \theta)$$

fail model perturb input

perturbs inputs **imperceptibly** to fool the models and then train the model.

❖ Change Labels and Inputs

mixup [c]



$$\tilde{x} = \lambda x_A + (1 - \lambda)x_B$$

$$\tilde{y} = \lambda y_A + (1 - \lambda)y_B$$

creates virtual training examples that **interpolates** between data pairs.

[a] Li et al. Rethinking Out-of-distribution (OOD) Detection: Masked Image Modeling is All You Need. In CVPR, 2023.

[b] Botschen et al. Out-of-Distribution Detection with Adversarial Outlier Exposure. In CVPR, 2025.

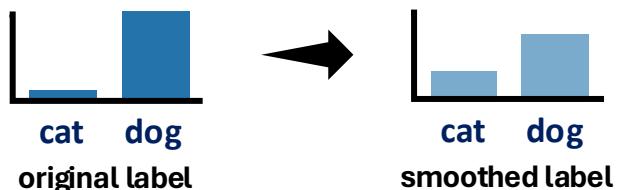
[c] Zhang et al. mixup: Beyond Empirical Risk Minimization. In ICLR, 2018.

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❖ Change Inputs

adversarial examples [b]



discourages extreme 0/1 probabilities
and thus reduces overconfidence and improves calibrations.
perturb input

perturbs inputs **imperceptibly** to fool the models and then train the model.

❖ Change Labels and Inputs

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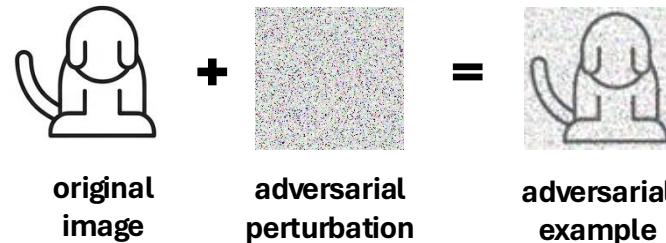
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❖ Change Inputs

adversarial examples [b]



original image

adversarial perturbation

adversarial example

$$\max_{\delta \in \Delta} \mathcal{L}(x + \delta, y, \theta)$$

fail model perturb input

perturbs inputs **imperceptibly** to fool the models and then train the model.

❖ Change Labels and Inputs

mixup [c]



encourages the model to **spread probability mass more cautiously** around decision boundaries.

creates virtual training examples that **interpolates** between data pairs.

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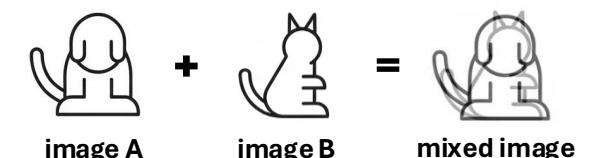
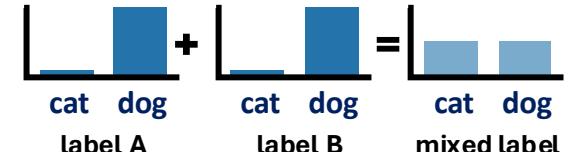


interpolates empirical distribution into a continuous one via a convex combinations of data and labels.

perturbs inputs imperceptibly to fool the models and then train the model.

❖ Change Labels and Inputs

mixup [c]



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Calibration: Model-centric Solutions

Relationship between MSP and Free Energy

$$P(Y = y|X) = \frac{\exp\{h_y(X)\}}{\sum_{y'} \exp\{h_{y'}(X)\}} \propto P(X), \text{ free energy}$$

softmax prediction

Free energy, which models $P(X)$, is more reliable for OOD detection than maximum softmax prediction. **Why?**

A Bayesian View [a].

Considering the following two learning goals, which one is more suitable for OOD detection?



Calibration: Model-centric Solutions

Relationship between MSP and Free Energy

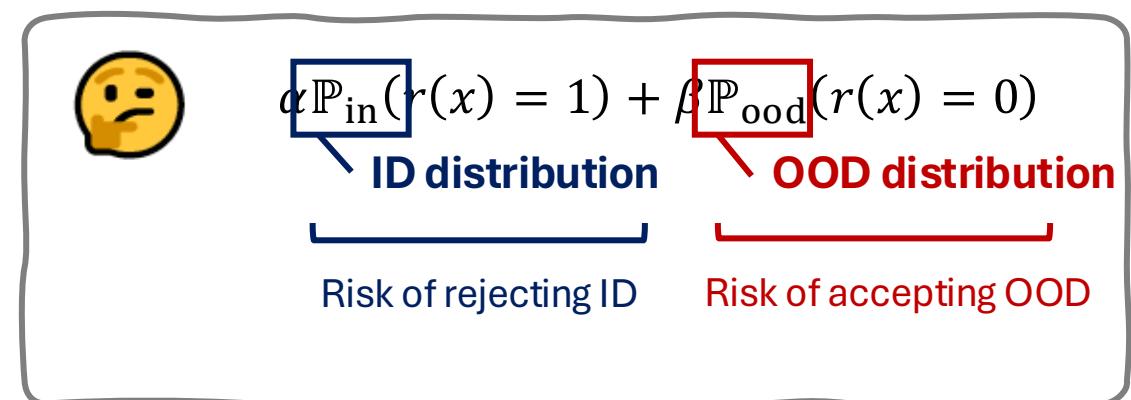
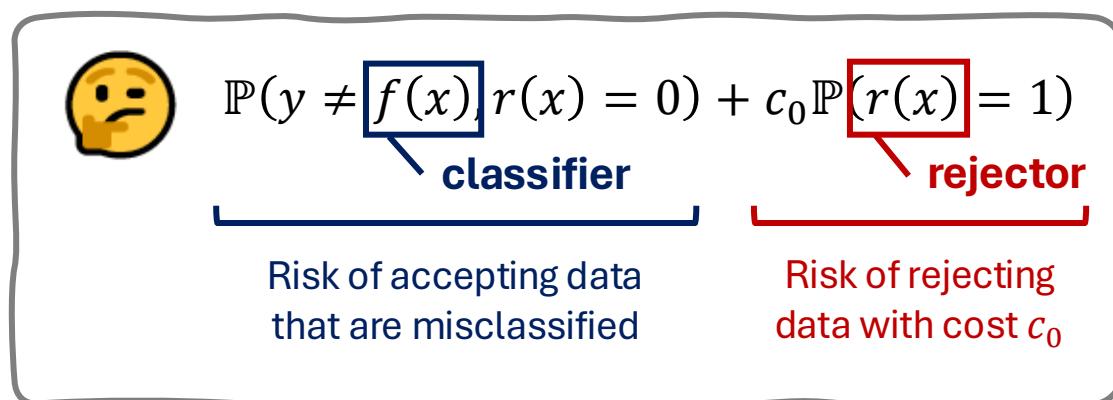
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$$\mathbb{P}(y \neq f(x), r(x) = 0) + c_0 \mathbb{P}(r(x) = 1)$$

used for **abstention-aware classification**.

$$r^*(x) = \llbracket \max_y \mathbb{P}(y|x) < 1 - c_0 \rrbracket$$

free energy



$$\alpha \mathbb{P}_{\text{in}}(r(x) = 0) + \beta \mathbb{P}_{\text{ood}}(r(x) = 1)$$

used for **OOD detection**.

$$r^*(x) = \llbracket \frac{\mathbb{P}_{\text{in}}(x)}{\mathbb{P}_{\text{ood}}(x)} < \frac{\beta}{\alpha} \rrbracket \approx \llbracket \frac{\mathbb{P}_{\text{in}}(x)}{\tau} < \frac{\beta}{\alpha} \rrbracket$$

MSP

Calibration: Model-centric Solutions

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Free energy, which models $P(X)$, is more reliable for OOD detection than maximum softmax prediction. However, $P(X)$ is also not well-calibrated. So, **how to calibrate $P(X)$?**

Calibrating $P(Y)$ (low dimension) offers a sufficient condition of calibrating $P(X)$ (high dimension).

Mathematical

$$P(Y = y) = \frac{1}{Z} \int \exp\{h_y(x)\} d\pi_x,$$

where $Z = \sum_y \int \exp\{h_y(x)\} d\pi_x$

Monte
Carlo



Hypothesis Test

$$H_0: P(Y = y) = \hat{P}(Y = y)$$

versus

$$H_1: P(Y = y) \neq \hat{P}(Y = y)$$

Empirical

$$\hat{P}(Y = y) = n_y/N$$

Count



Calibration: Model-centric Solutions—DCR [a]

Relationship between MSP and Free Energy

$$P(Y = y|X) = \frac{\exp\{h_y(X)\}}{\sum_{y'} \exp\{h_{y'}(X)\}}$$

softmax prediction $\propto P(Y, X)$
 $\propto P(X)$, free energy

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Hypothesis Test

$$\begin{aligned} H_0: P(Y = y) &= \hat{P}(Y = y) \\ \text{versus} \\ H_1: P(Y = y) &\neq \hat{P}(Y = y) \end{aligned}$$

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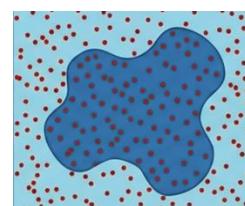
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Monte Carlo



Hypothesis Test

$$H_0: P(Y = y) = \hat{P}(Y = y)$$

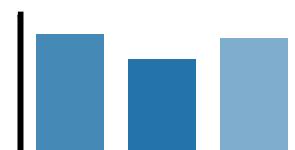
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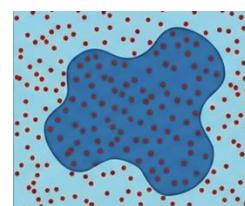
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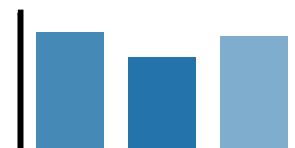
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Count



Hypothesis Test

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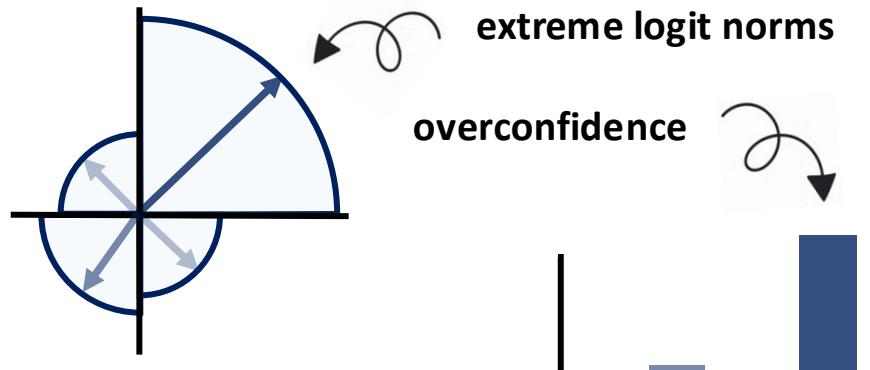
Calibration: Distribution-centric Solutions—LogitNorm

We seek **distribution modelling beyond Softmax** that are more proper for OOD detection.



Why is Softmax not sufficient?

- ❖ **Scaling logits** increases confidence and decreases the risk.
- ❖ **Training pushes near-zero risk**, driving large confidence and inflating logits.



Logit Norm [a]

- ❖ normalizes logit vector to a constant norm during training, following

$$-\log \frac{\exp\{f_y/(\tau\|f_y\|)\}}{\sum_i \exp\{f_i/(\tau\|f_i\|)\}}$$

normalization



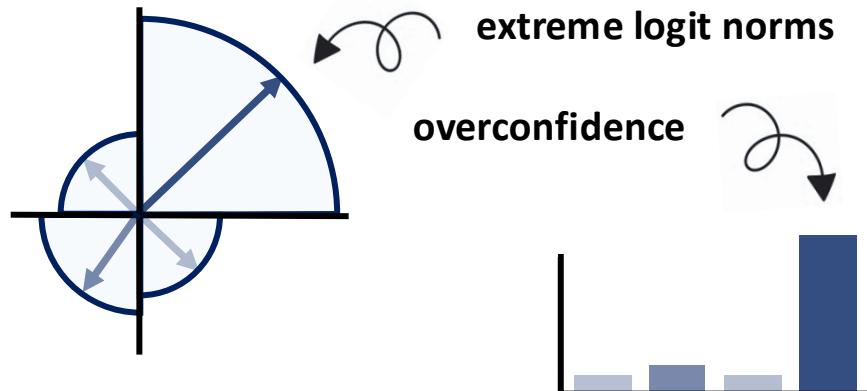
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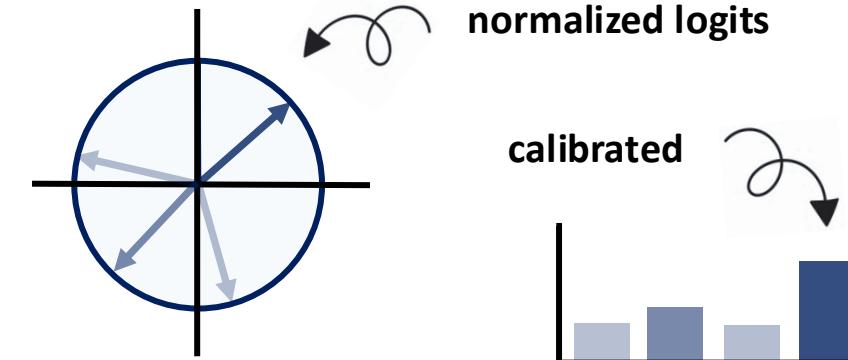


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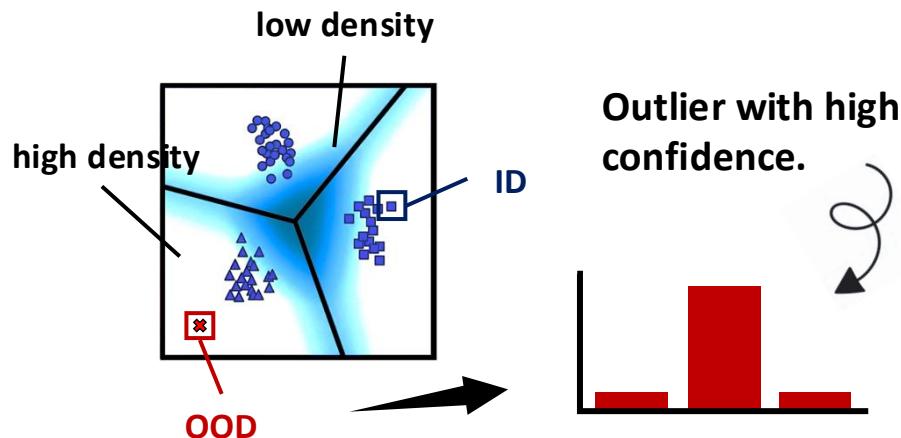
Calibration: Distribution-centric Solutions—SIREN

We seek **distribution modelling beyond Softmax** that are more proper for OOD detection.



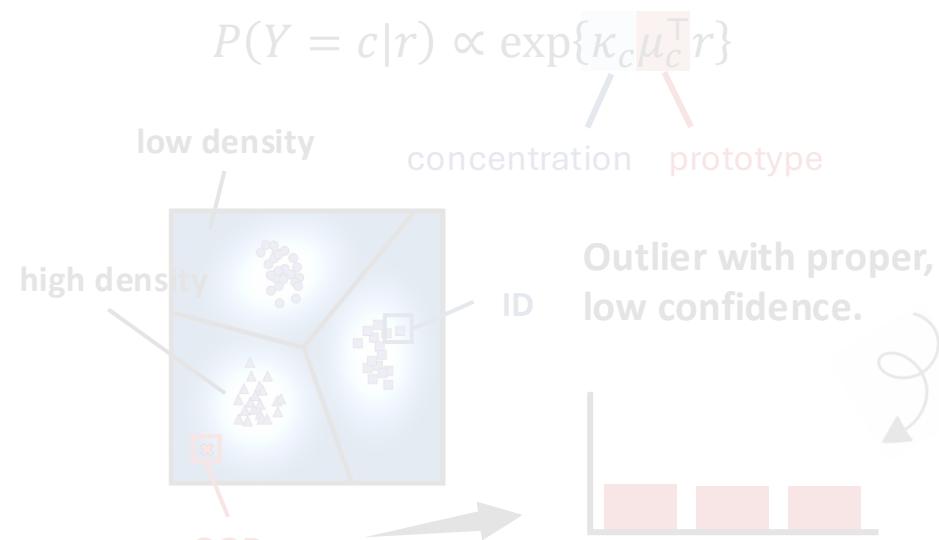
Why is Softmax not sufficient?

- ❖ The separation is piecewise linear in feature space.
- ❖ Regions that contain no training points can still be assigned confidently.



SIREN [a]

- ❖ The density depends on similarity to prototypes and vMF likelihood, creating a curved, cluster-shaped regions.



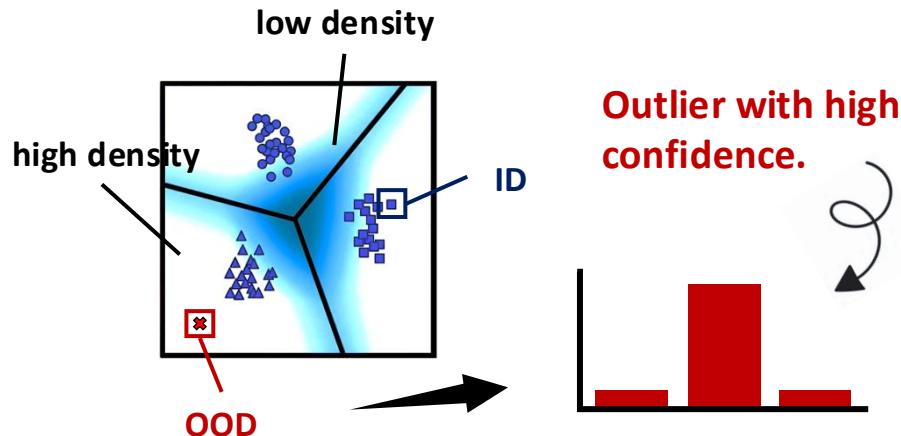
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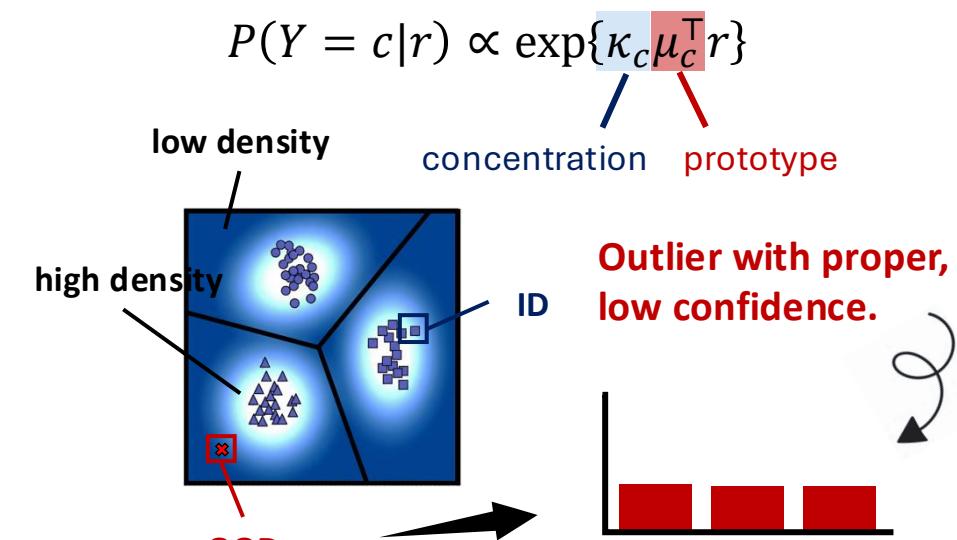
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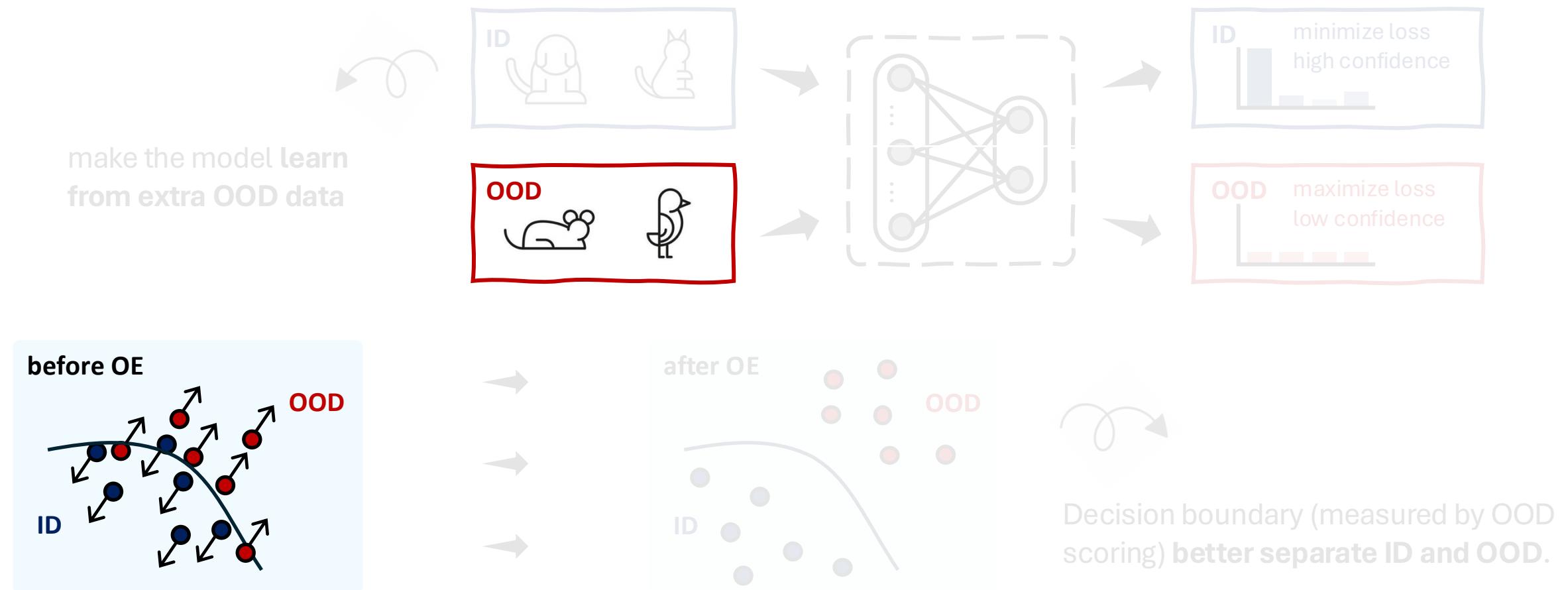
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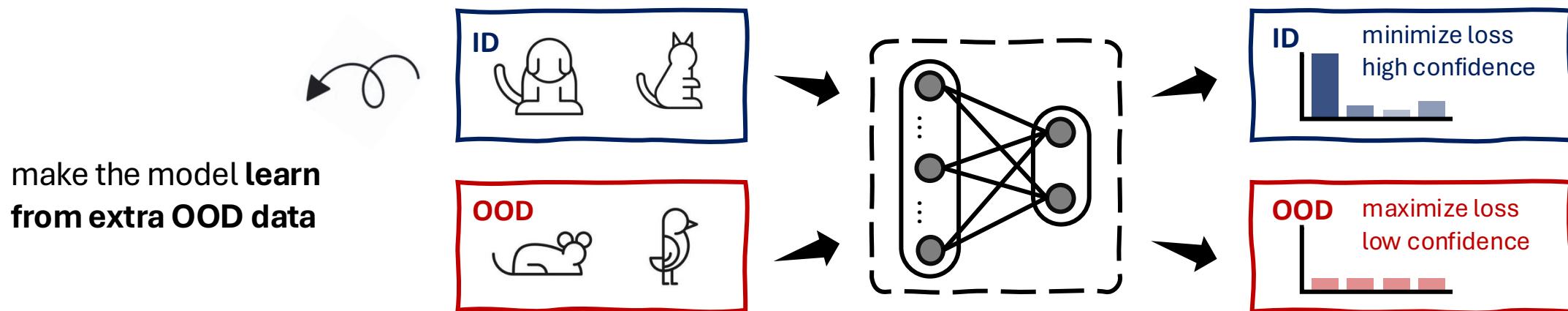
Outlier Exposure: Overview

Outlier exposure [a] takes OOD detection as **an additional binary classification task**, enabling models to directly learn to distinguish ID from OOD patterns.



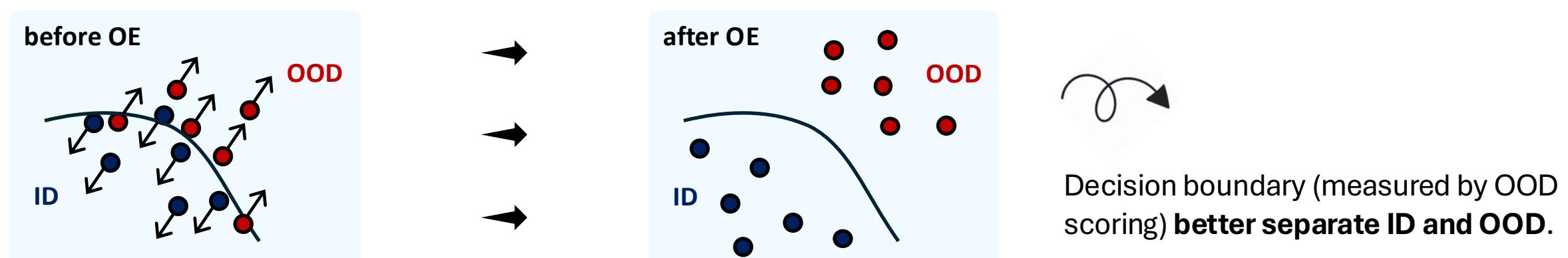
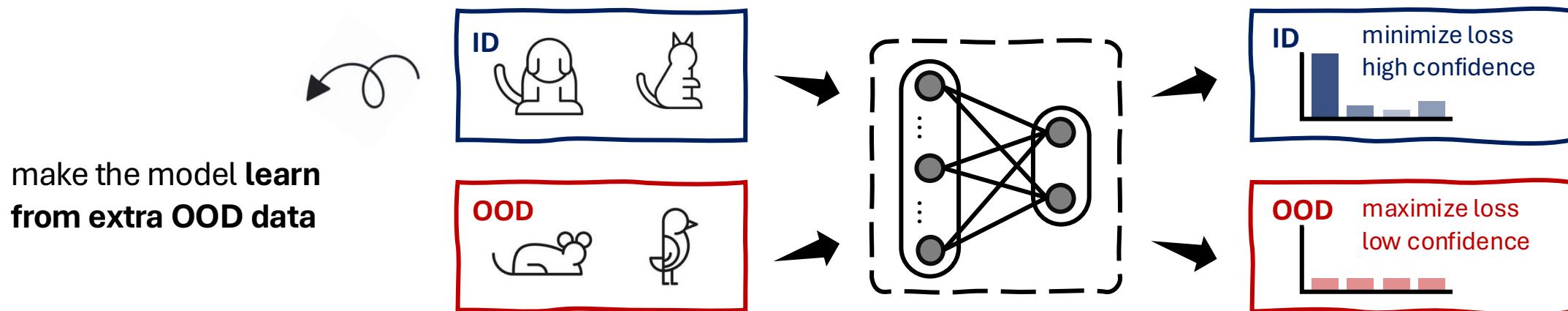
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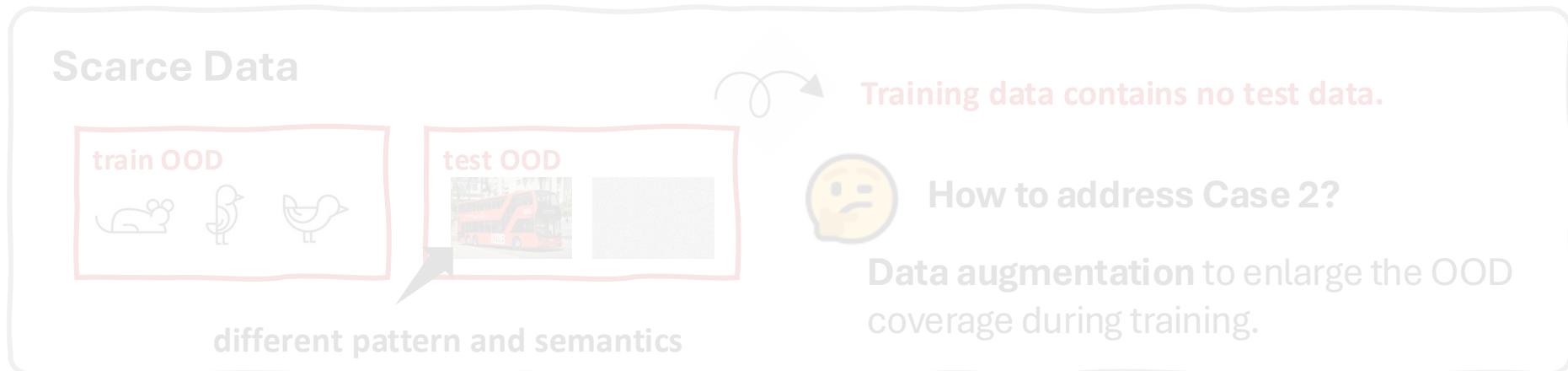
Outlier Exposure: Overview

Training and test OOD can differ, and **such distribution gap degrades OOD performance [a]**.

❖ Case 1.



❖ Case 2.



Outlier Exposure: Overview

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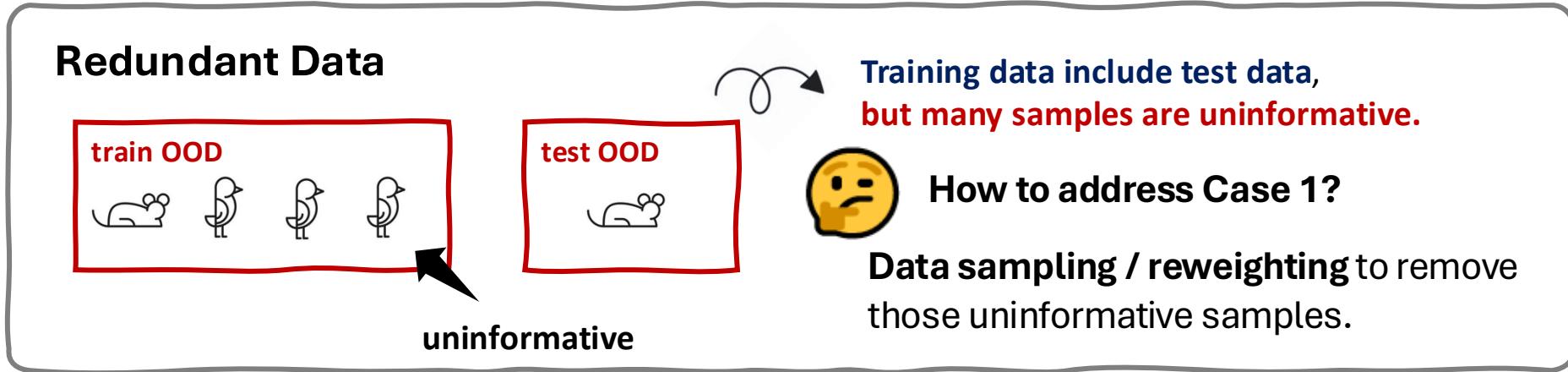
❖ Case 2.



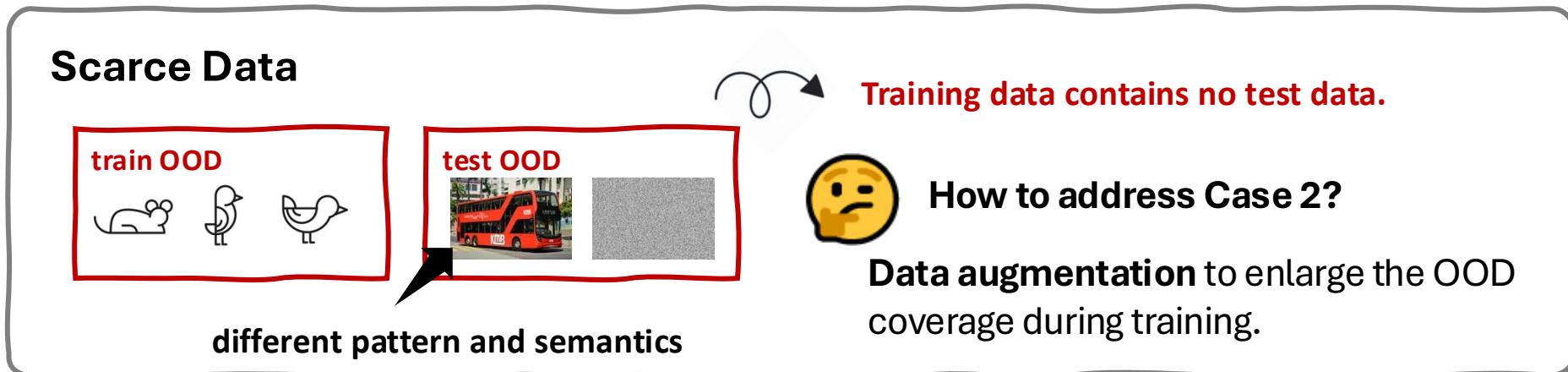
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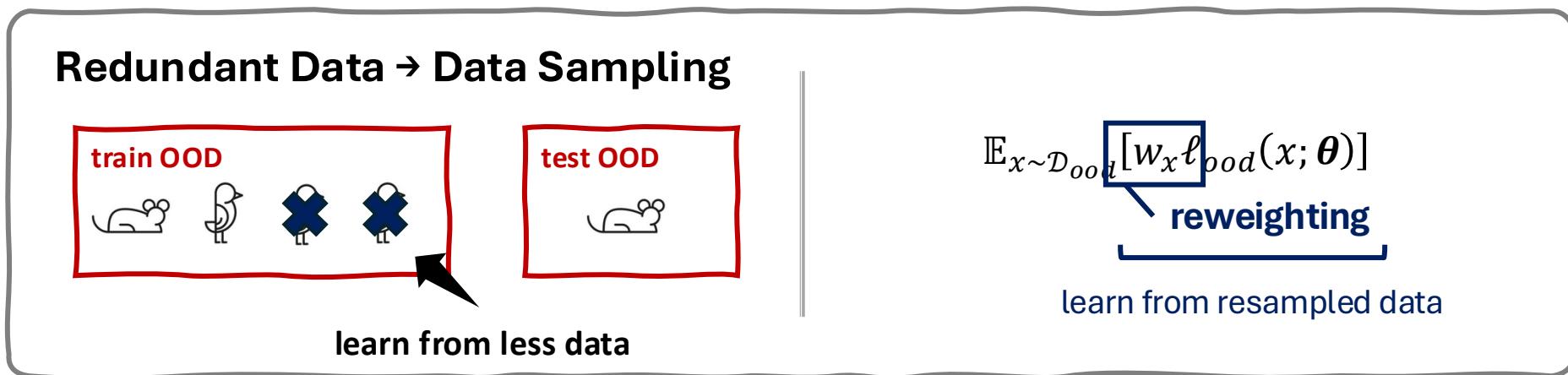
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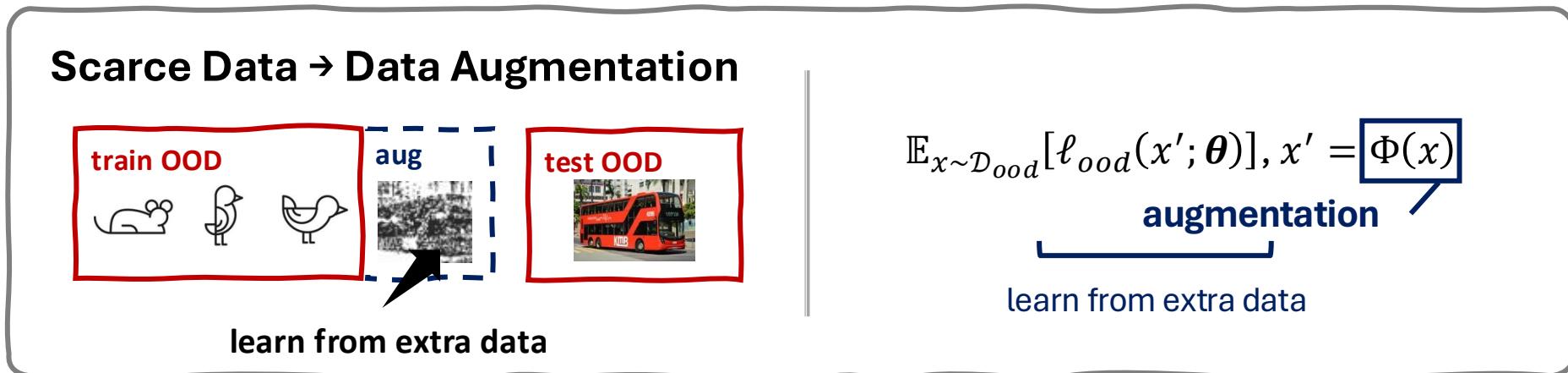
Outlier Exposure: Overview

Data sampling learns from fewer examples and data augmentation from more.

❖ Case 1.

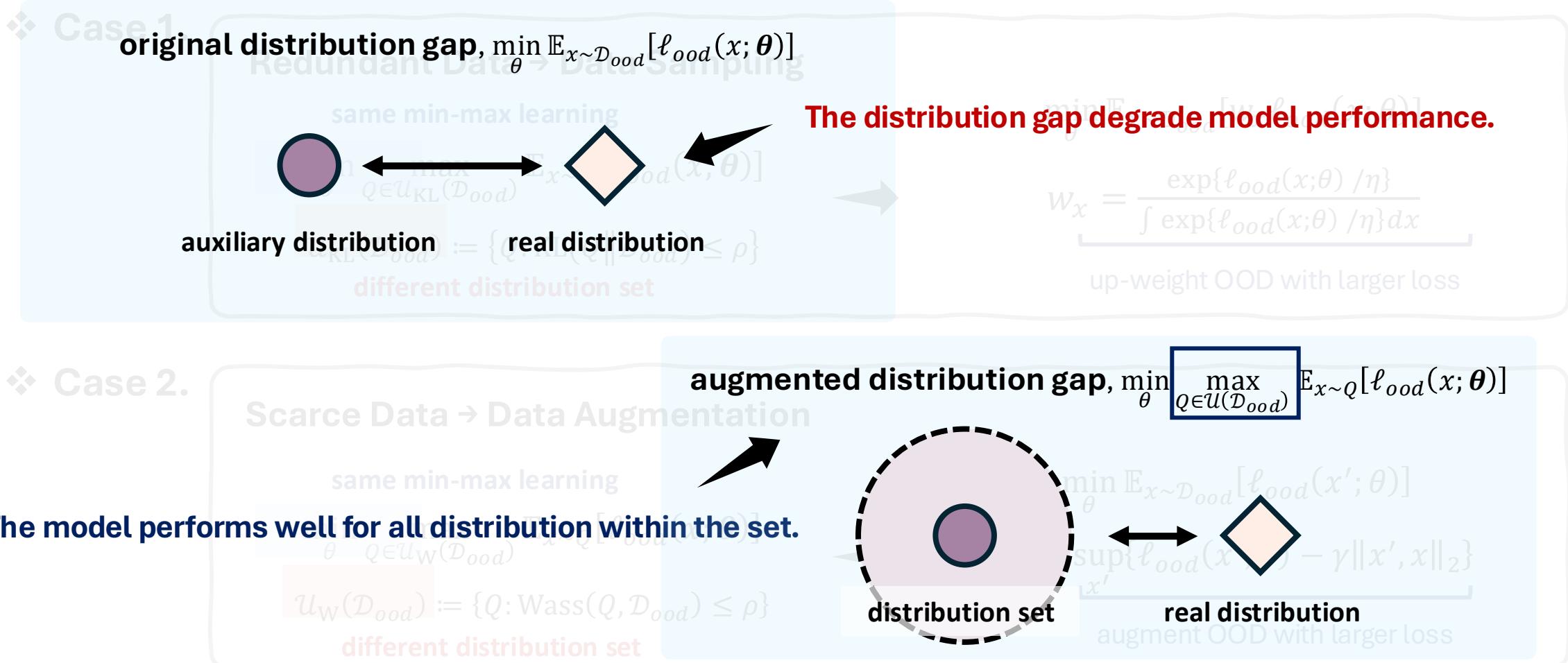


❖ Case 2.



Outlier Exposure: Overview

Data sampling and augmentation **both improve distribution robustness [a]**.



Outlier Exposure: Overview

Data sampling and augmentation **both improve distribution robustness [a]**.

❖ Case 1.

Redundant Data → Data Sampling

same min-max learning

$$\min_{\theta} \max_{Q \in \mathcal{U}_{KL}(\mathcal{D}_{ood})} \mathbb{E}_{x \sim Q} [\ell_{ood}(x; \theta)]$$

$$\mathcal{U}_{KL}(\mathcal{D}_{ood}) := \{Q : \text{KL}(Q \parallel \mathcal{D}_{ood}) \leq \rho\}$$

different distribution set

$$\min_{\theta} \mathbb{E}_{x \sim \mathcal{D}_{ood}} [w_x \ell_{ood}(x; \theta)]$$

$$w_x = \frac{\exp\{\ell_{ood}(x; \theta) / \eta\}}{\int \exp\{\ell_{ood}(x; \theta) / \eta\} dx}$$

up-weight OOD with larger loss

❖ Case 2.

Scarce Data → Data Augmentation

same min-max learning

$$\min_{\theta} \max_{Q \in \mathcal{U}_W(\mathcal{D}_{ood})} \mathbb{E}_{x \sim Q} [\ell_{ood}(x; \theta)]$$

$$\mathcal{U}_W(\mathcal{D}_{ood}) := \{Q : \text{Wass}(Q, \mathcal{D}_{ood}) \leq \rho\}$$

different distribution set

$$\min_{\theta} \mathbb{E}_{x \sim \mathcal{D}_{ood}} [\ell_{ood}(x'; \theta)]$$

$$x' = \sup_{x'} \{\ell_{ood}(x'; \theta) - \gamma \|x' - x\|_2\}$$

augment OOD with larger loss

Outlier Exposure: Overview

Data sampling and augmentation **both improve distribution robustness [a]**.

❖ Case 1.

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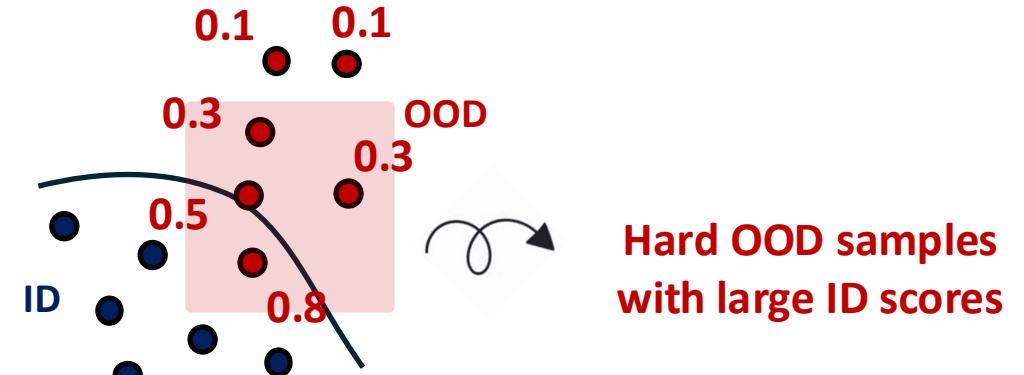
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augment OOD with larger loss

Outlier Exposure: Sampling

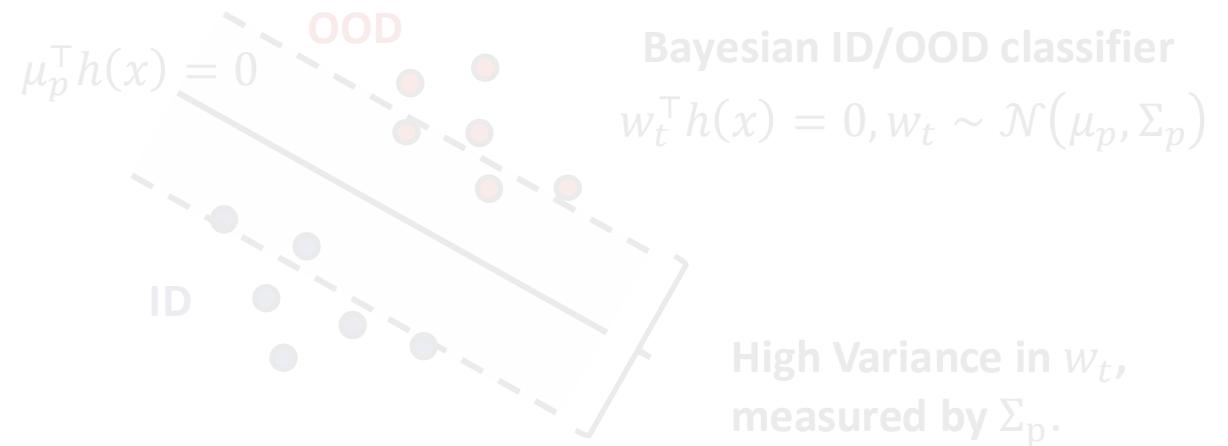
ATOM [a]

- ❖ Hard OOD data should be sampled more during training.
- ❖ Large ID scores on OOD samples indicates hard OOD data.



POEM [b]

- ❖ OOD data near the ID/OOD boundary should be sampled more.
- ❖ Bayesian classifiers capture parameter uncertainty, improving exploration.



[a] Chen et al. ATOM: Robustifying Out-of-distribution Detection Using Outlier Mining. In ECML PKDD, 2021.

[b] Ming et al. POEM: Out-of-distribution Detection with Posterior Sampling. In ICML, 2022.

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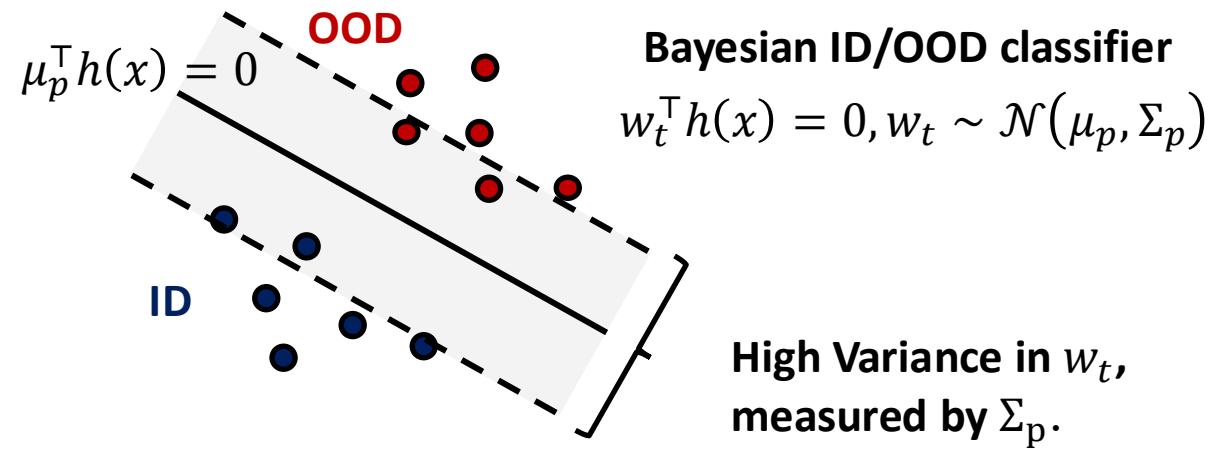
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Outlier Exposure: Sampling

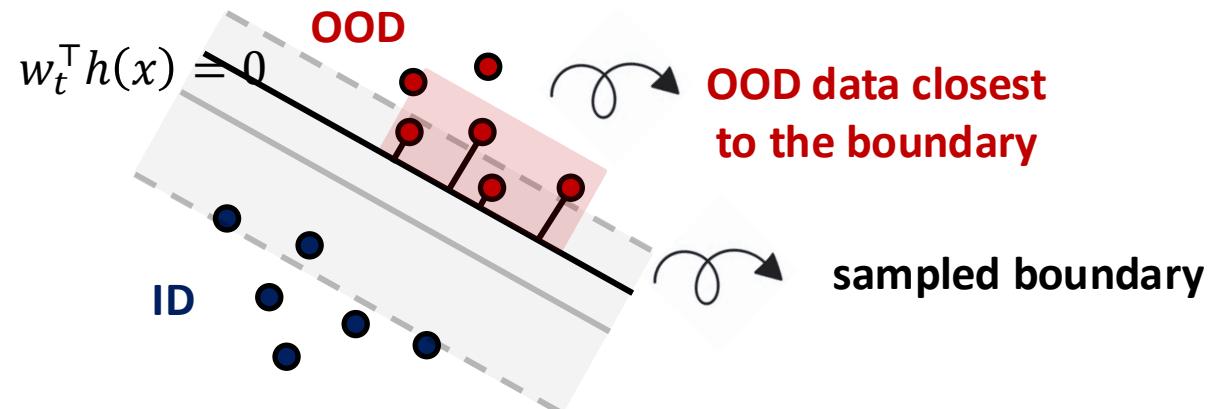
ATOM [a]

- ❖ Hard OOD data should be sampled more during training.
- ❖ Large ID scores on OOD samples indicates hard OOD data.



POEM [b]

- ❖ OOD data **near the ID/OOD boundary** should be sampled more.
- ❖ Bayesian classifiers capture parameter uncertainty, **improving exploration**.



[a] Chen et al. ATOM: Robustifying Out-of-distribution Detection Using Outlier Mining. In ECML PKDD, 2021.

[b] Ming et al. POEM: Out-of-distribution Detection with Posterior Sampling. In ICML, 2022.

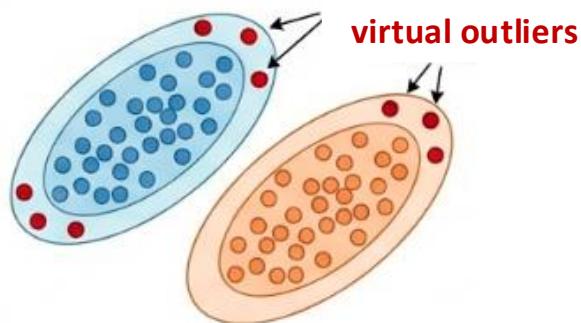
Outlier Exposure: Augmentation

Augmentation can be conducted in either **embedding space** or input space.

❖ Synthesis

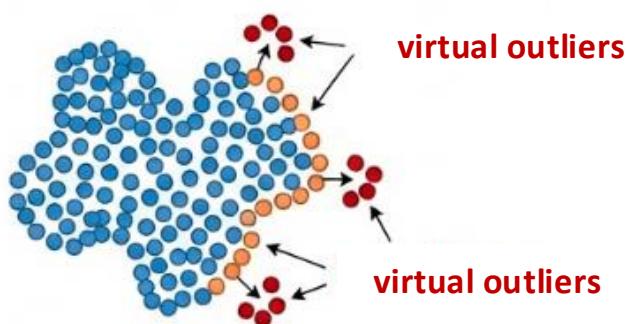
VOS [a]

class-conditional **Gaussian modelling**



NPOS [b]

Non-parametric K-NN modelling



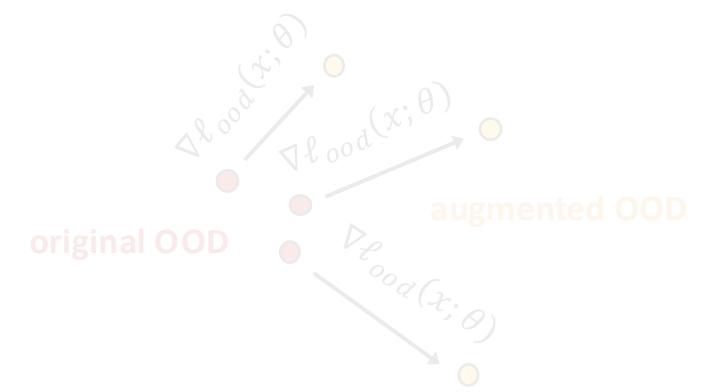
- ❖ estimate μ and Σ per class.
- ❖ sample $v \sim \mathcal{N}(\mu_c, \Sigma)$.
- ❖ keep only low likelihood samples with $p(v) < \epsilon$.

- ❖ Identify boundary ID with high k-NN.
- ❖ sample locally around boundary $v \sim \mathcal{N}(h_{bdy}, \sigma^2 I)$.
- ❖ keep candidates with large k-NN.

❖ Augmentation

DAL [c]

worst-case OOD augmentation



- ❖ sample original OOD data.
- ❖ gradient ascent to increase their respective loss values.
- ❖ augmented OOD data for training.

[a] Du et al. VOS: Learning What You Don't Know by Virtual Outlier Synthesis. In ICLR, 2022.

[b] Tao et al. Non-parametric Outlier Synthesis. In ICLR, 2023.

[c] Wang et al. Learning to Augment Distributions for Out-of-distribution Detection. In NeurIPS, 2023.

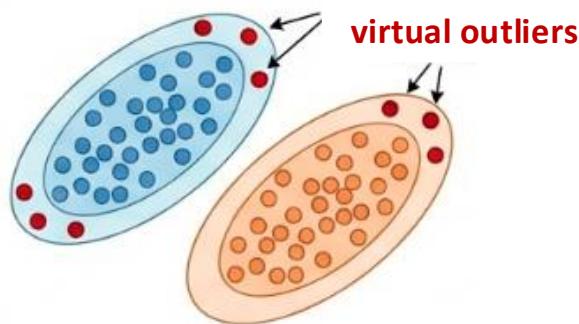
Outlier Exposure: Augmentation

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❖ Synthesis

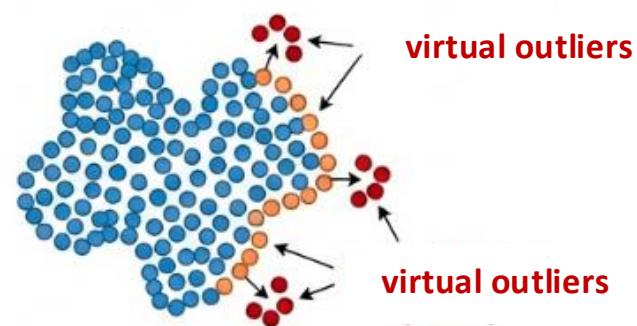
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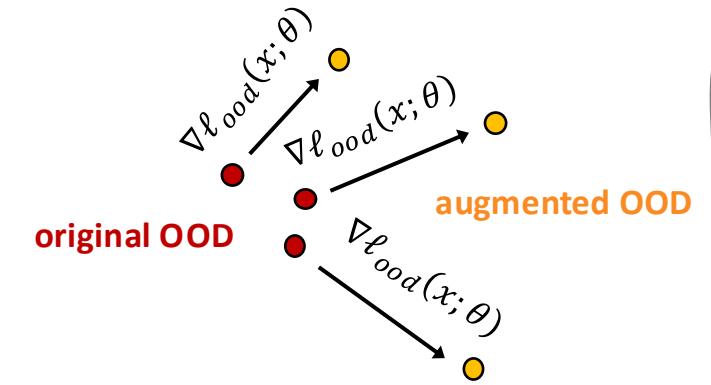
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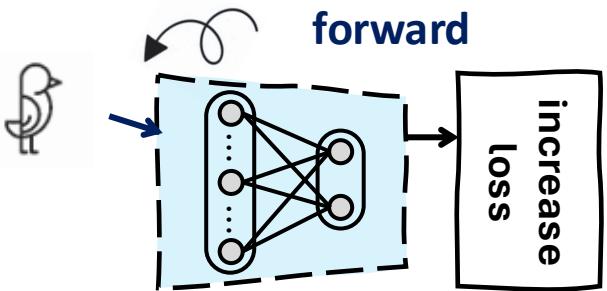
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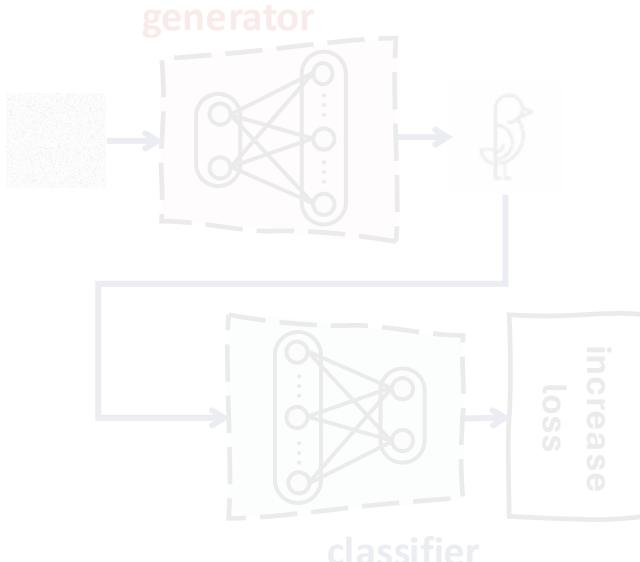
Augmentation can be conducted in either embedding space or **input space**.

❖ Adversarial Training [a]



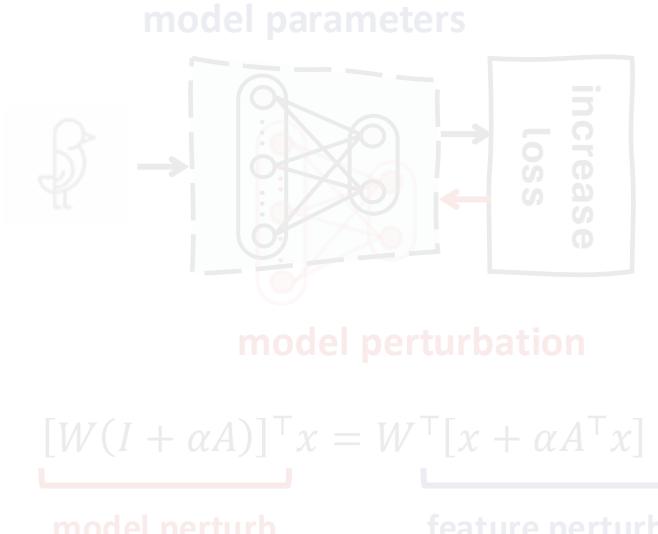
perturb inputs to maximize OOD loss values, thus creating worst-case examples.

❖ Generative Model [b]



perturb latent embedding to maximize OOD loss values, thus creating worst-case examples.

❖ Implicit Synthesis [c]



perturb parameters that maximize OOD loss can implicitly create worst-case examples.

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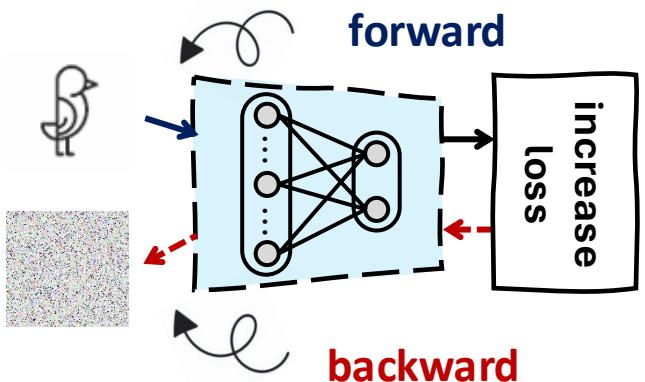
[b] Lee et al. Training Confidence-calibrated Classifiers for Detecting Out-of-distribution Samples. In ICLR, 2018.

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Outlier Exposure: Augmentation

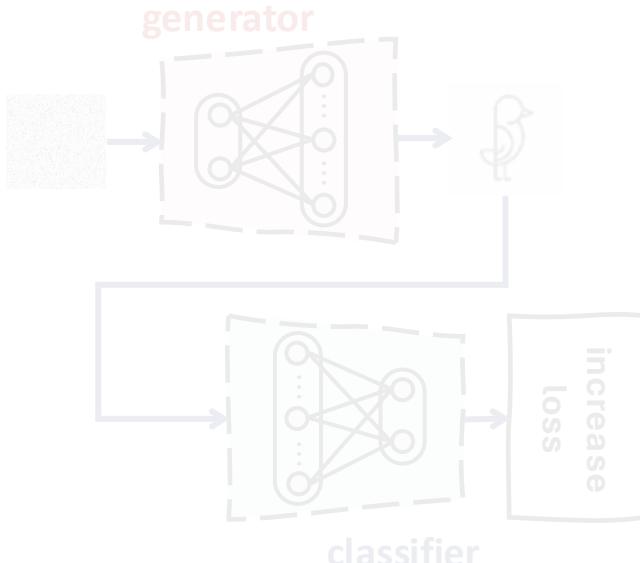
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❖ Adversarial Training [a]



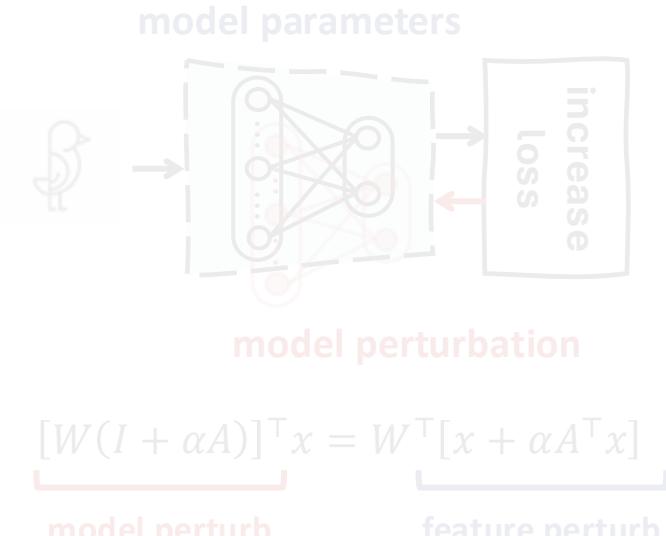
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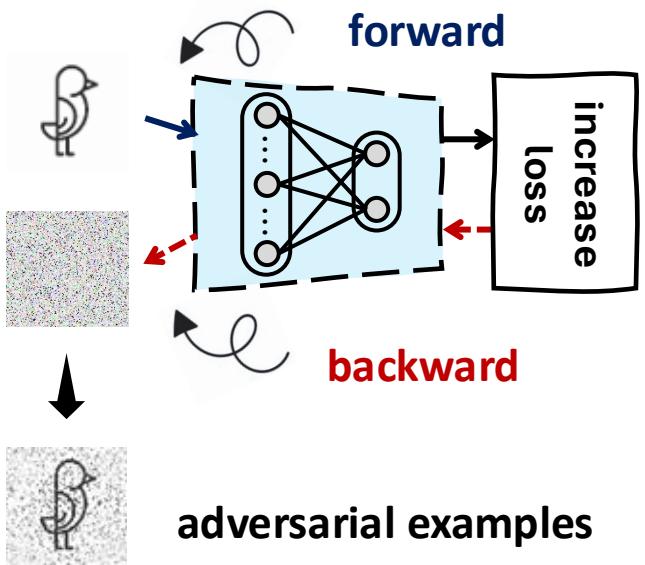
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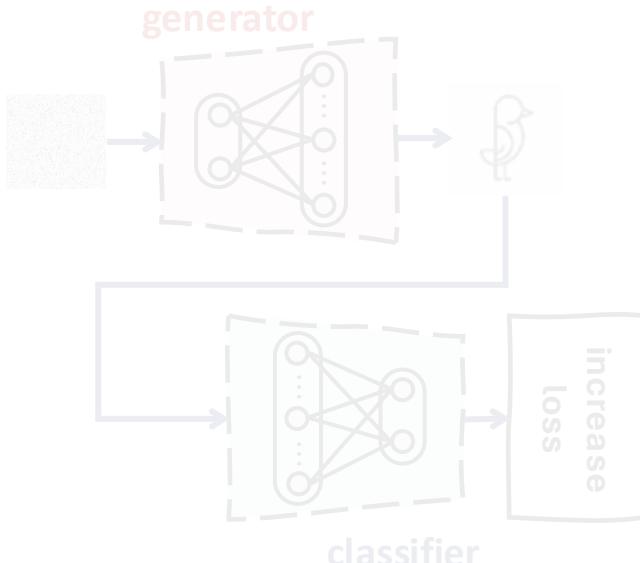
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❖ Adversarial Training [a]



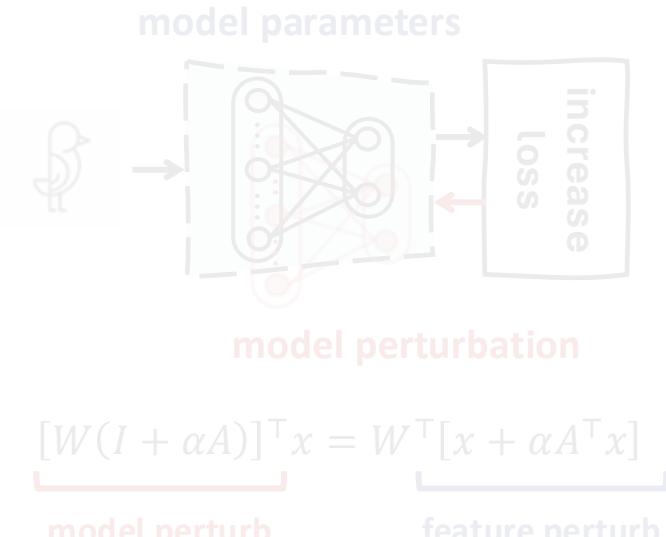
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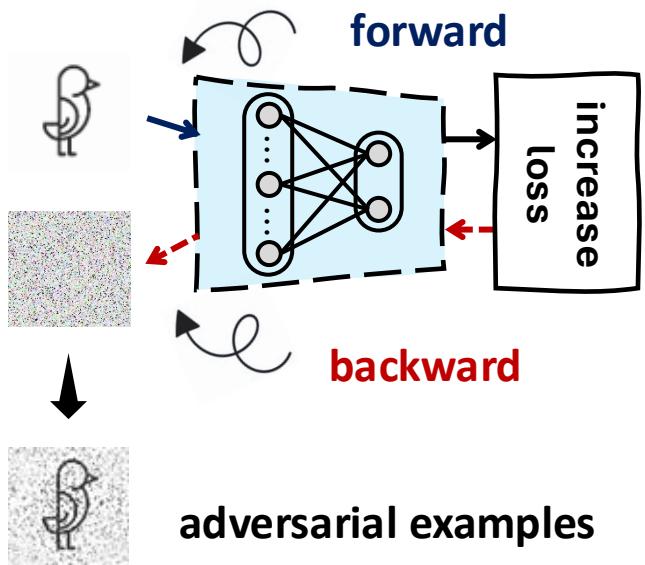
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Outlier Exposure: Augmentation

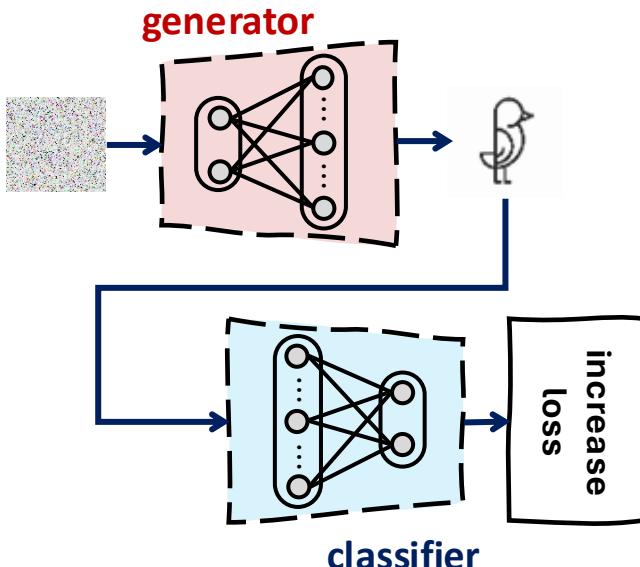
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❖ Adversarial Training [a]



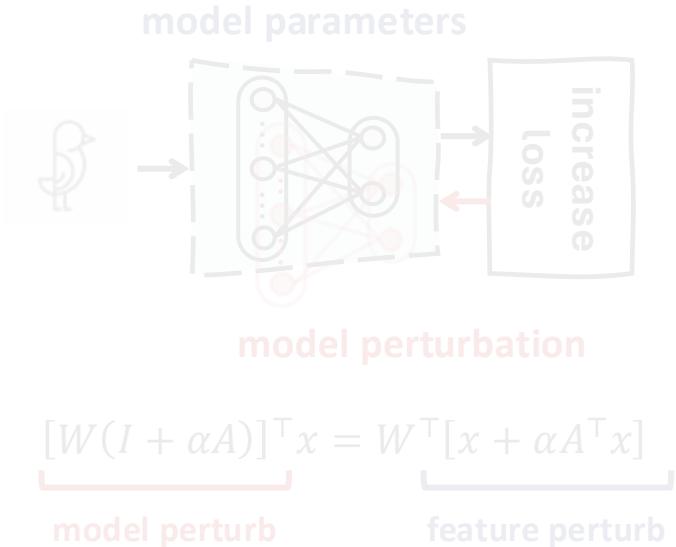
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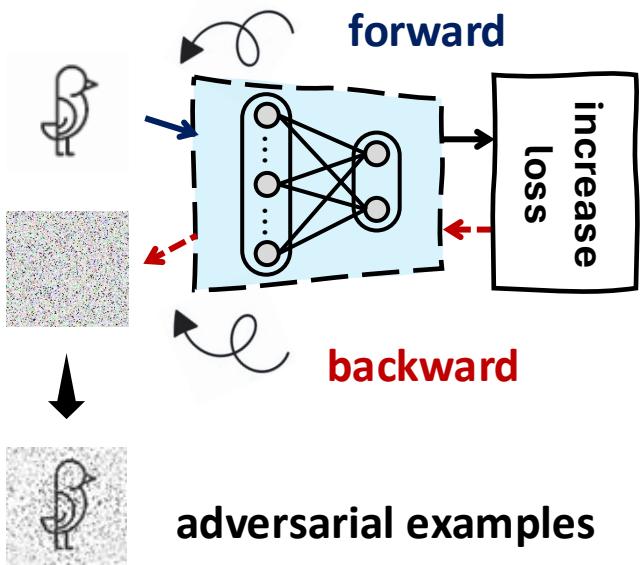
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Outlier Exposure: Augmentation

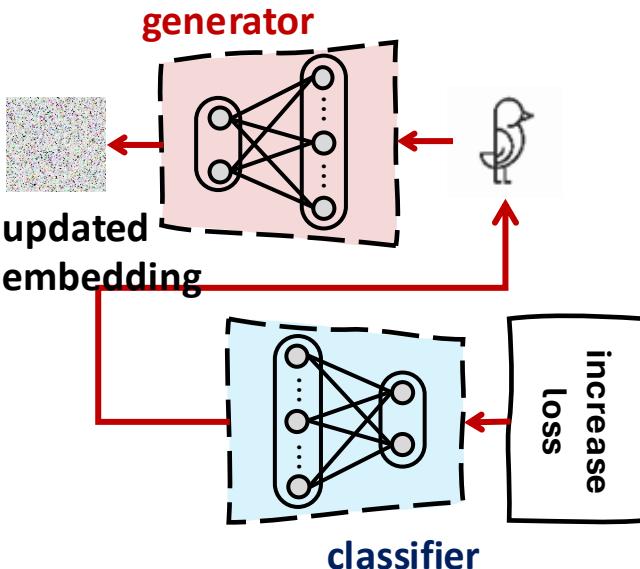
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❖ Adversarial Training [a]



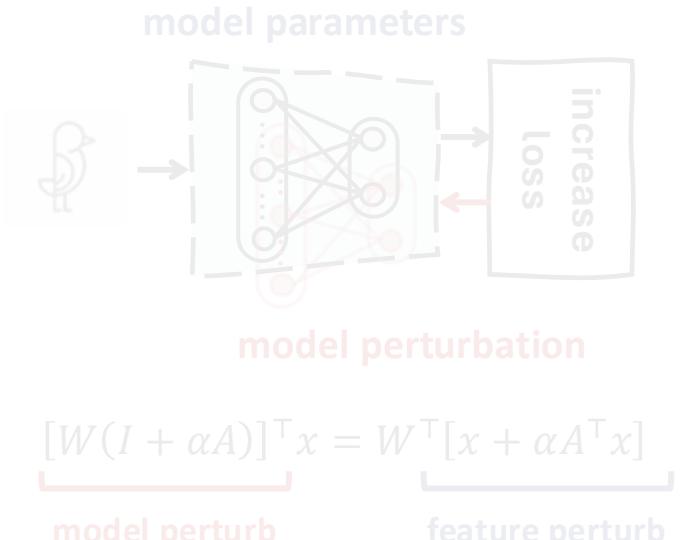
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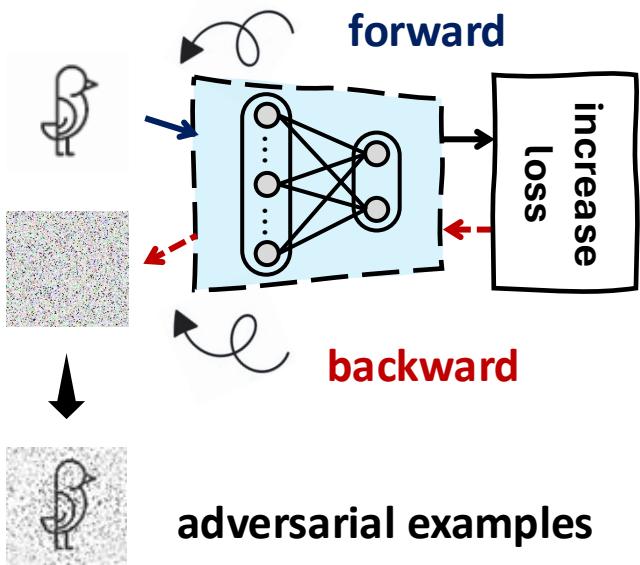
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Outlier Exposure: Augmentation

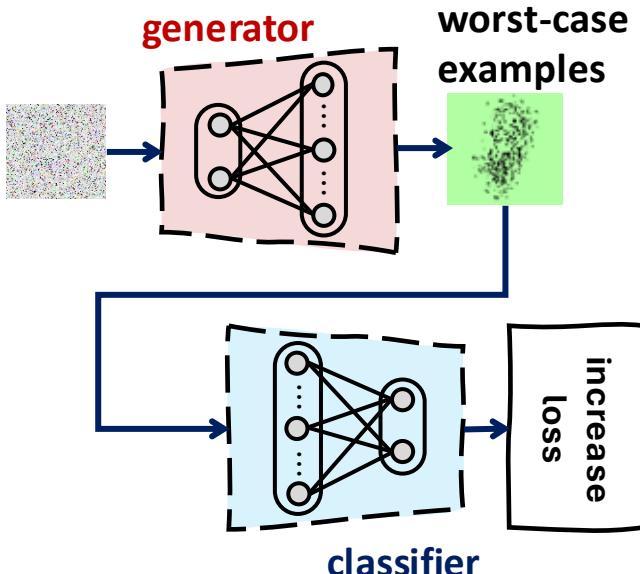
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❖ Adversarial Training [a]



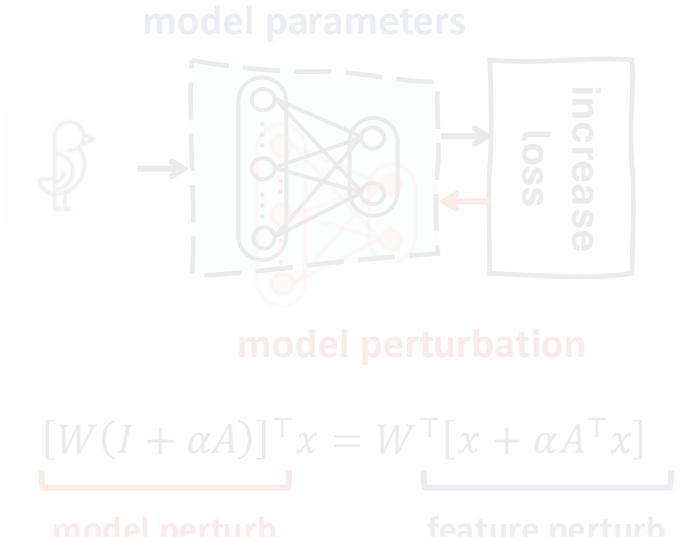
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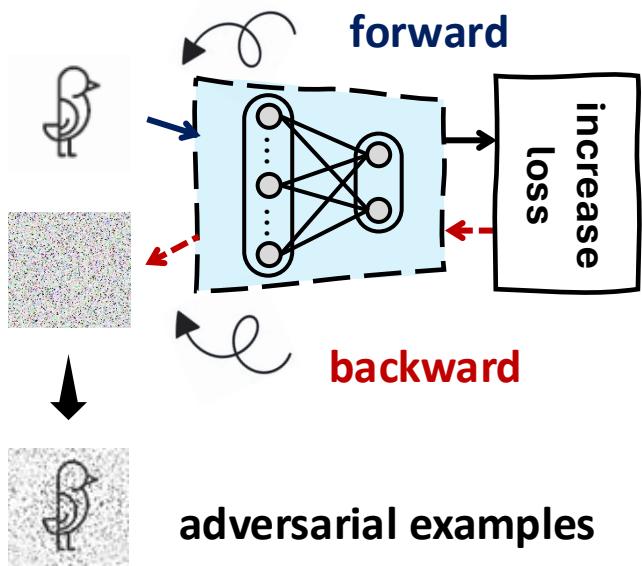
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Outlier Exposure: Augmentation

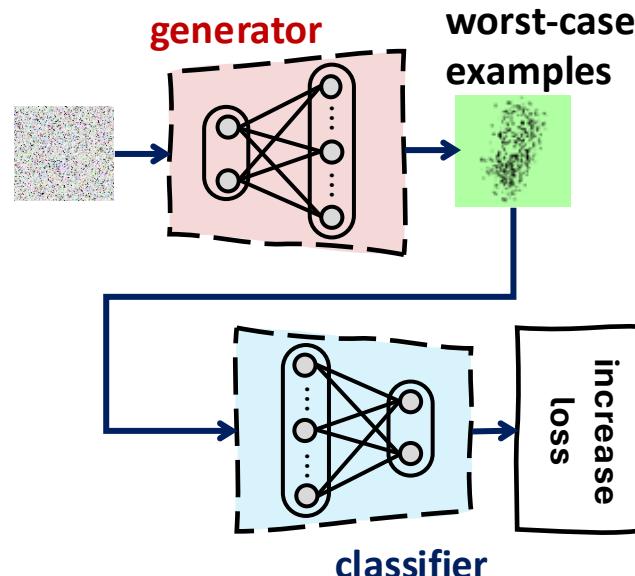
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❖ Adversarial Training [a]



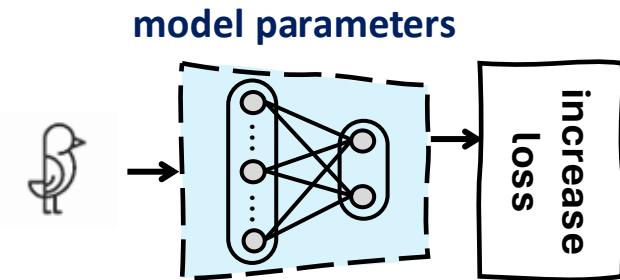
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❖ Generative Model [b]



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❖ **Implicit Synthesis [c]**



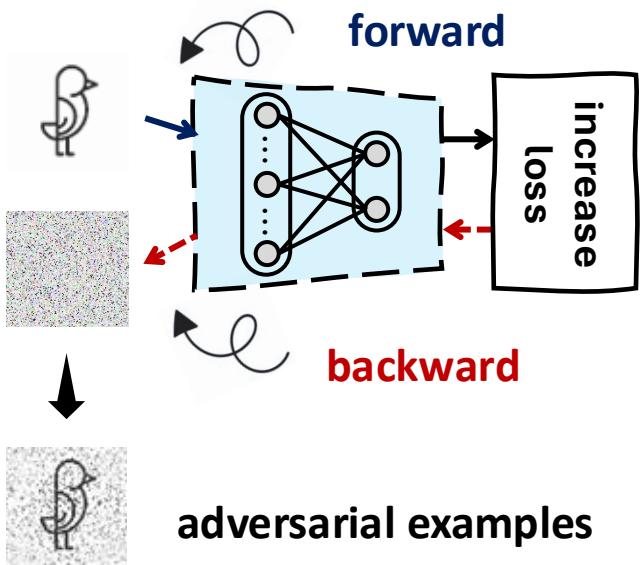
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Outlier Exposure: Augmentation

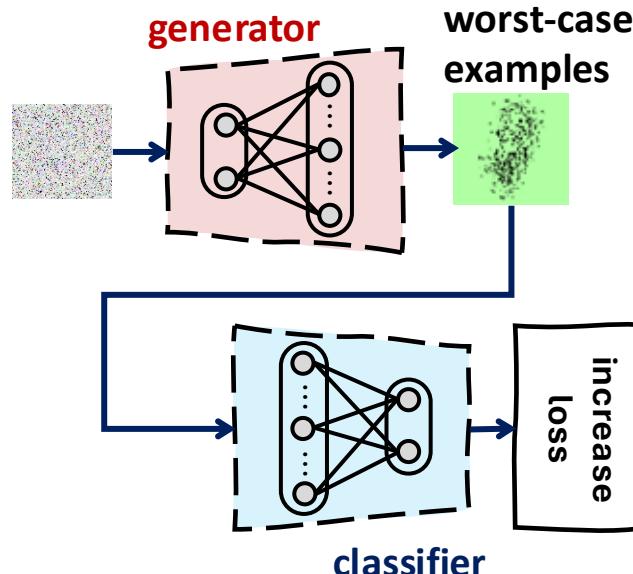
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❖ Adversarial Training [a]



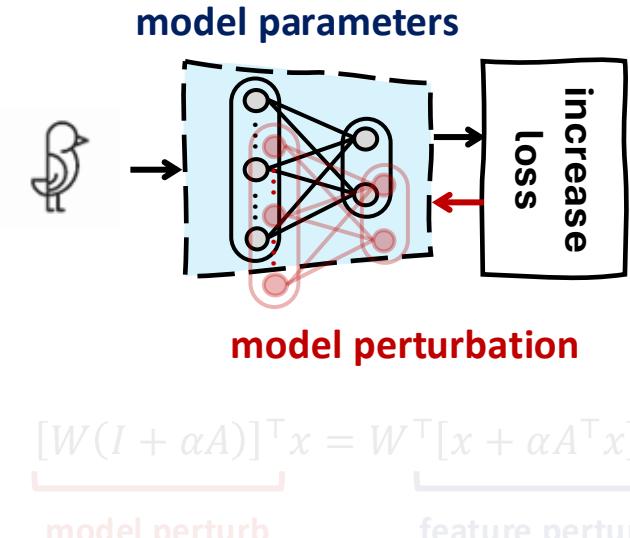
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❖ Implicit Synthesis [c]



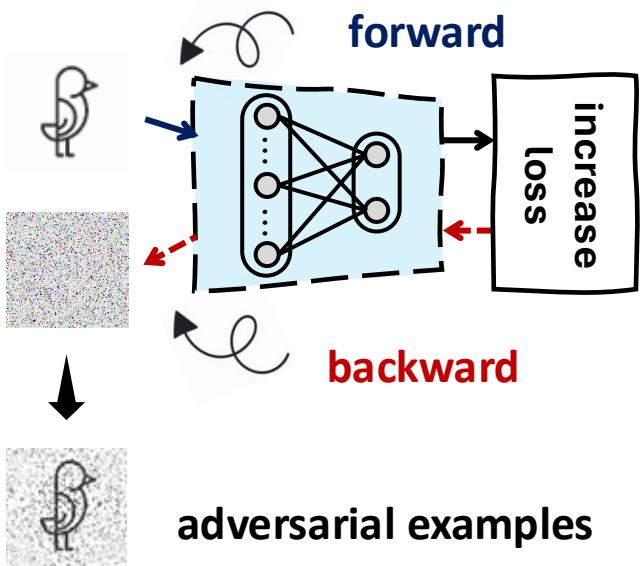
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Outlier Exposure: Augmentation

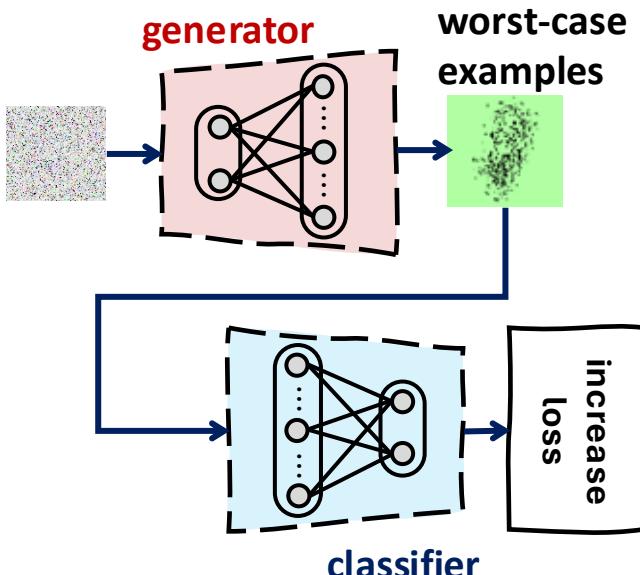
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❖ Adversarial Training [a]



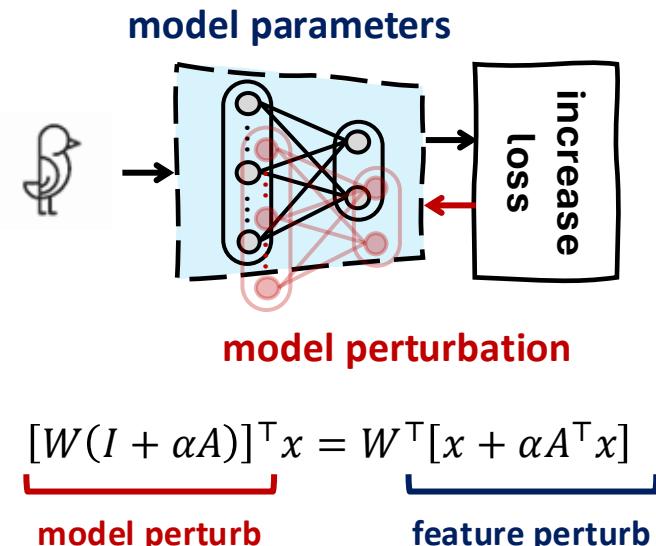
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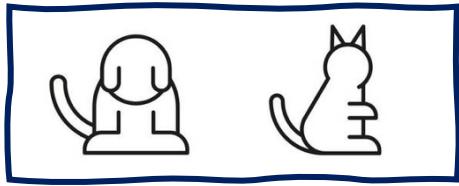
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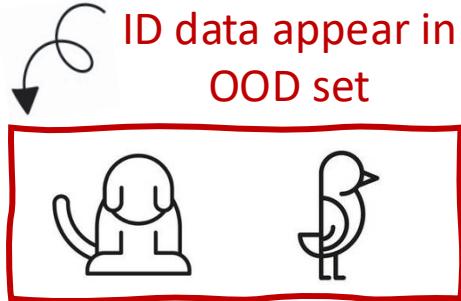
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Challenges and Future Directions

❖ Wild OOD Detection



training ID



training OOD

ID data appear in
OOD set



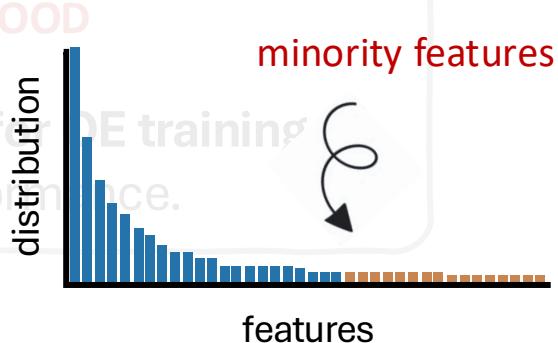
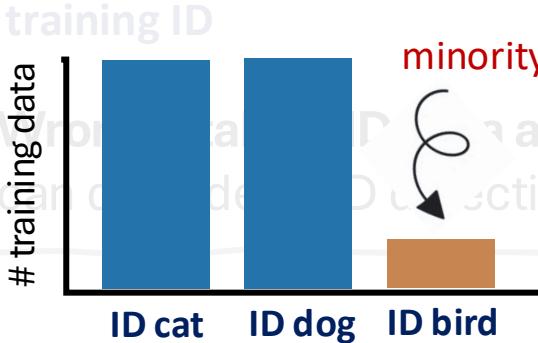
Wrongly taking ID data as OOD for OE training
can degrade OOD detection performance.

Challenges and Future Directions

❖ Wild OOD Detection

ID data appear in
OOD set

❖ Imbalanced and Long-tailed OOD Learning



Minority classes or features are easier to be confused with OOD data.

Challenges and Future Directions

❖ Wild OOD Detection

ID data appear in
OOD set

❖ Imbalanced and Long-tailed OOD Learning

❖ Covariate Shift vs. Semantic Shift

Minority classes or features are easier to be confused with OOD data.

Models typically fail to discern data with covariate shift and semantic shift.

Challenges and Future Directions

❖ Wild OOD Detection

ID data appear in
OOD set

❖ Large-scale Generative Models

filter bad generation

Diffusion

Diffusion model



detect hallucination

LLM

Large Language Model

The capital of Australia is
Sydney.

The capital of Australia is
Canberra. [Source: Gov.au]



OOD detection can be used for **quality / safety**
control in large-scale generative models.

Models typically fail to discern data with
covariate shift and semantic shift.

Thank you for listening!

Find my slides from my homepage:

<https://qizhouwang.github.io/homepage>

