

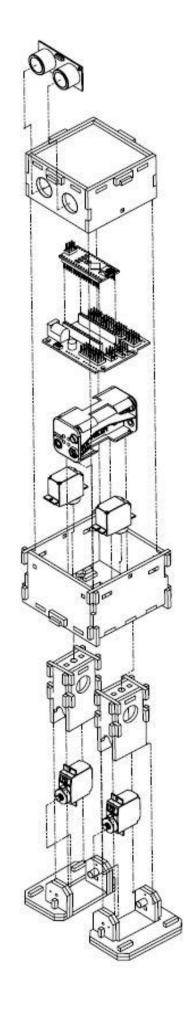
# MIIA ASSEMBLY INSTRUCTIONS

### **WELCOME**

Congratulations! You are now the proud new owner of your own MiiA robot. These instructions will take you through everything you need to know on how MiiA is put together and what makes her tick. MiiA is built in the form of a 3D puzzle, so the fun begins immediately. The MiiA bot design is based off another great robot called Otto bot (https://www.ottodiy.com). So, without further ado, let's jump in!

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# What's in the Box

All parts included in the kit are shown in this section.

Part	Preview	Part	Preview
Battery holder		Arduino shield	. 444
(1x)	O O STEE TAN SQUAY  D O O O O O O O O O O O O O O O O O O	(1x)	
HC06 Bluetooth	0.000	Servo Motor	
transceiver		(4x)	
(1x)			
Arduino Nano	Herri	M2 cap screw	
(1x)		(8x)	
Ultrasonic sensor		M2 nut	
(1x)		(4x)	
Head – front		Head - back	
(1x)	(00)	(1x)	
Head - left		Head-right	
(1x)		(1x)	
Head - top		Body - base	
(1x)		(1x)	
Body - front and back	۲- ۲-	Body - sides	
(2x)		(2x)	
Body - corners	7	Head and body pin	
(4x)	5	(6x)	Visit out admitted (NOT)

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General pin		Leg - top	000
(12x)	_	(2x)	50
Leg - bottom plate		Leg - front	<del>-</del> 5-57
(2x)	5_2	(2x)	~
Leg - sides		Leg - back	
(4x)		(2x)	
Foot - back	(6)	Foot - back	(6)
(2x)	0	(2x)	
Foot - front	()	Foot - front	(0)
(2x)		(2x)	
Foot - top		Foot - base	
(2x)		(2x)	
Foot pin	돠	Foot - axle	
(4x)		(2x)	
USB mini cable		Jumper cables	
(1x)		(8x)	
Nut holder			
(4x)			
		_	

# Putting MiiA Together

This section describes how to assemble the individual parts that make up MiiA.

### Head

Part	Preview	Part	Preview
Head – front		Head - back	
(1x)		(1x)	
Head - left		Head - right	
(1x)		(1x)	
Head and body pin		Head - top	,Ja
(4x)		(1x)	
			\
	How to a	ssemble	

# Body

Part	Preview	Part	Preview
Body - front and	Ç	Body – sides	
back		(2x)	
(2x)	p  _ h	(2x)	
,			"لـــــــــــــا"
Body - base	االـــــ	Head and body pin	[6.6]
(4)	7: :7	(2)	ררין
(1x)		(2x)	
Body - corners	r)	Nut holder	
(4x)	2/	(Av)	
General pin		(4x)	
(4x)			
	How to	assemble	
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0.83 <del>5</del>			

# Legs

Part	Preview	Part	Preview
General pin	7	Leg - top	000
(4x)		(2x)	51 105
Leg - bottom plate		Leg - front	75151
(2x)		(2x)	<del>-</del> 2-2
Leg - sides		Leg - back	5_5
(4x)		(2x)	
	How to	assemble	

# Feet

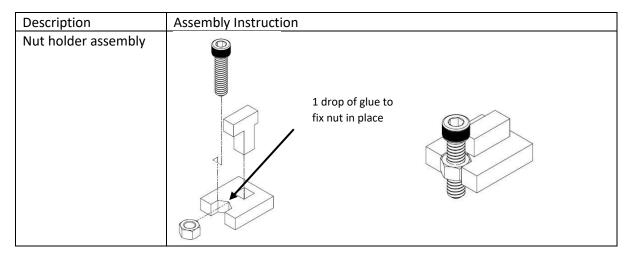
Part	Preview	Part	Preview
Foot - back (2x)	· On	Foot - back (2x)	00
Foot - front		Foot - front	
(2x)		(2x)	• 0
Foot - top		Foot - base	
(2x)		(2x)	
Foot pin	7	Foot - axle	
(4x)	, <del>, , , , , , , , , , , , , , , , , , ,</del>	(2x)	
General pin	2		
(4x)	How to assemb		
Cos Cos			0.0

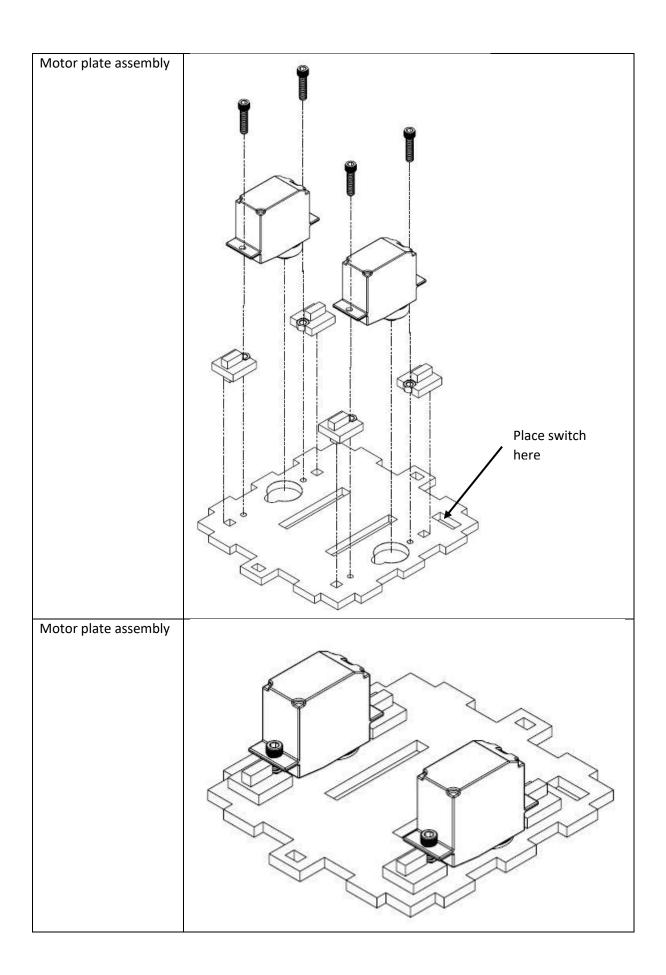
### **Motor Calibration**

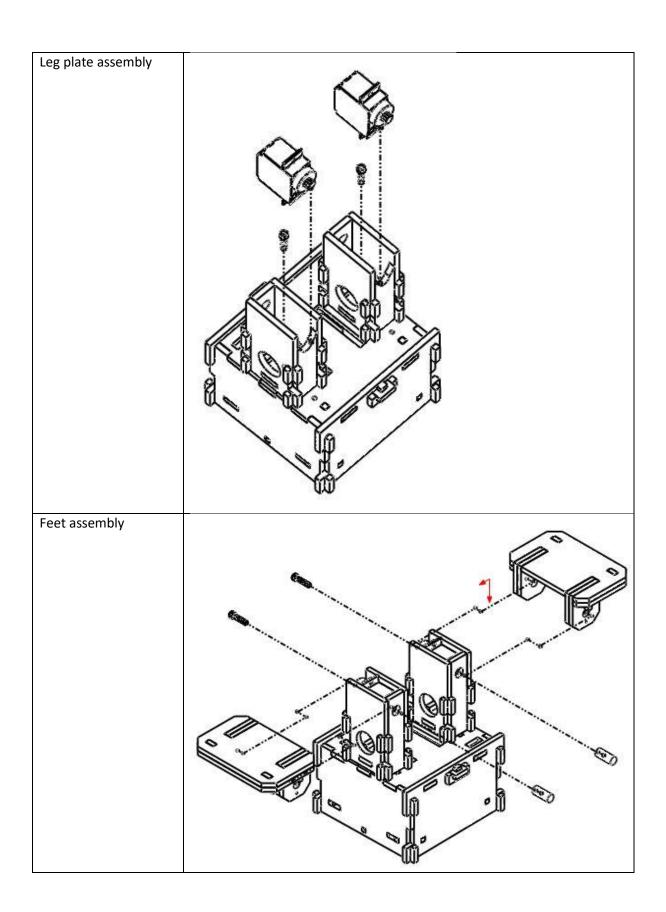
When inserting motors into the robot, please ensure that the servo motors have been set to 90 degrees. Have a look at our calibration video <a href="here">here</a>. You can also find our calibration code <a href="here">here</a>.

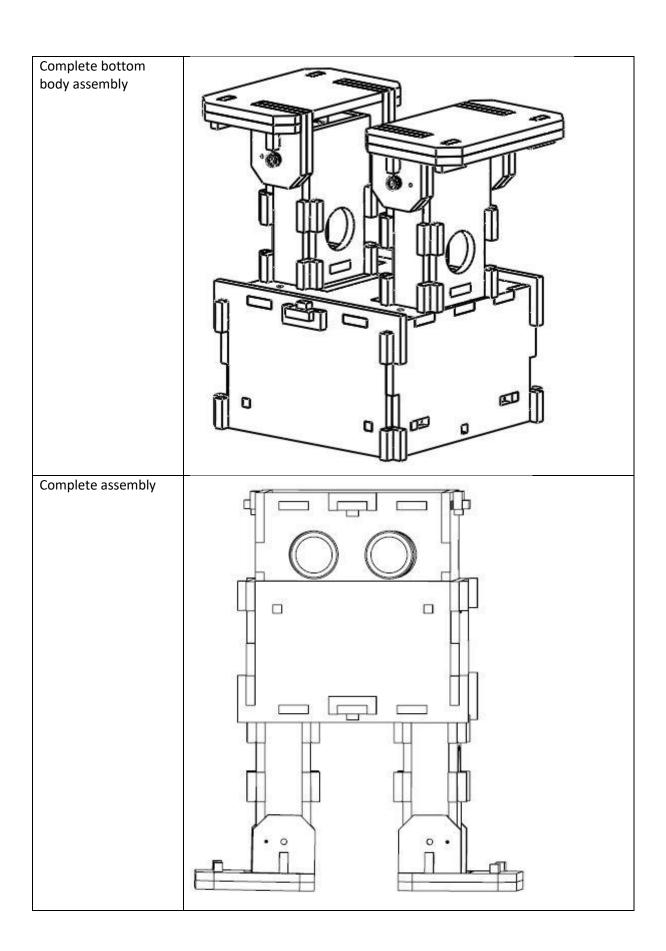
# Assembly

This section shows how to install the motors that make MiiA move.



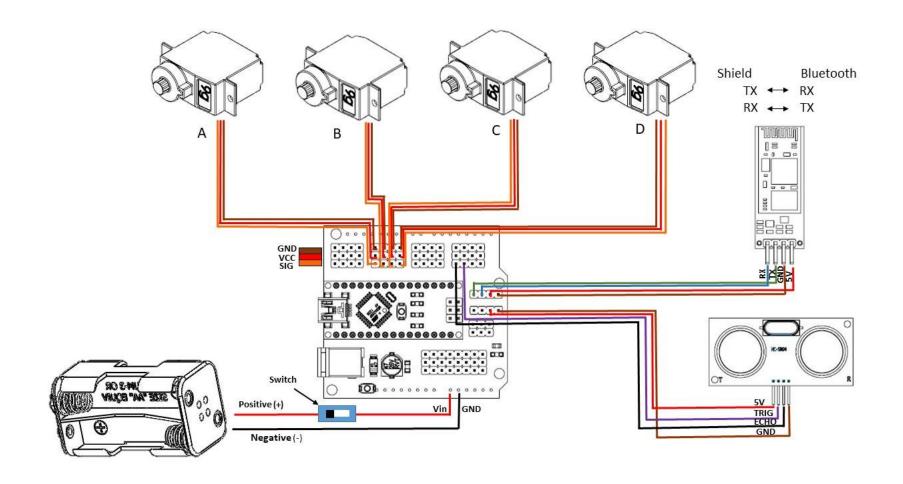




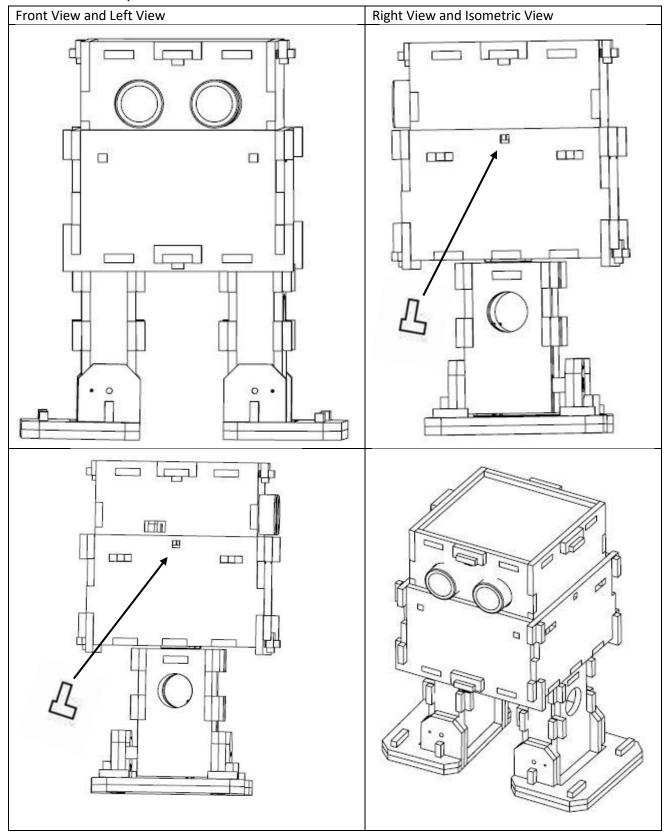


### **Electrical Connections**

By connecting all the electrical component as shown below, MiiA will be able to be programmed and controlled to move.



Final Assembly



Well Done! MiiA is now complete and ready to be programmed.

To start your robotics journey please go to our  $\underline{\text{website}}$  for instructions on getting started with programming her.

If you are having any issues with the kits, please do not hesitate to contact us at info@rd-9.co.za

