Genetic Algorithms - Homework 3

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Abstract

1 Introduction

1.1 Motivation

The goal of this paper is to observe how evoultive algorithms, genetic algorithms in particular handle combinatoric optimization problems and how genetic algorithms can yeald close results to NP-Complete problems in very little time. Troughout the paper we also observe the weight of all the evolutive operators for this problem on 3 types of instances: small(10-100), medium(100-300) and big(300-1200).

1.2 Traveling salesman problem

The travelling salesman problem (also called the travelling salesperson problem or TSP) asks the following question: "Given a list of cities and the distances between each pair of cities, what is the shortest possible route that visits each city and returns to the origin city?" It is an NP-hard problem in combinatorial optimization, important in operations research and theoretical computer science.

2 Method

2.1 Encoding

No encoding is used on this experiment because of the use of cyclic crossover that requires access to the decoded permutation.

2.2 Instances

The instances chosen for this experient can be grouped into 3 categories:

Small instances

• berlin52

Medium instances

- ch130
- ch150
- d198
- a280

Big instances

- d493
- d657
- d1291
- vm1084

2.3 Optimisation tehniques

Cyclic Crossover

Cycle crossover is used for chromosomes with permutation encoding. Cycle crossover performs recombination under the constraint that each gene comes from the parent or the other [Oliver et al. 1987]

Hyperparameter tuning

The parameters of the genetic algorithm were obtained using random search. The parameters were randomly generated then the evolutive algorithm was ran on ch130 for 500 generations. The number of generations can be lower here because most of the optimization is done in the early stage of the evolution.

The found parameters are:

• popSize': 90

• 'eliteSize': 12

• 'mutationRate': 0.004107141255506286,

2.4 Rank based selection paired with elitism

Rank Selection sorts the population first according to fitness value and ranks them. Then every chromosome is allocated selection probability with respect to its rank. Rank selection is used due to it being a more explorative tehnique. To counter balance the explorative nature of rank based selection the elitism is used.

3 Results

| Instance | Min | Max | Stdev | Min / Optimum |
|------------|--------------------|--------------------|--------------------|---------------|
| a280 | 11541.963281496814 | 14114.035718612706 | 662.4211278470108 | 4.1833864739 |
| berlin52 | 9108.31810460427 | 11561.510361347806 | 601.1099454779345 | 1.20767940926 |
| ch130 | 12029.88615288532 | 14673.480881173615 | 726.664120499055 | 2.37657338516 |
| ch150Best | 14520.86338332076 | 17532.27371024473 | 711.7462395900847 | 2.22439696436 |
| d198Best | 48237.70414967518 | 59297.68831311495 | 2995.7032406940125 | 3.05688872938 |
| d493Best | 213460.27611452245 | 225937.60959290288 | 3476.8357241358026 | 6.09851654518 |
| d657Best | 479895.2073092939 | 505542.4972833134 | 6303.005824792107 | 9.81140021486 |
| d1291Best | 1202783.3917260212 | 1239318.4488844858 | 9308.80600380999 | 23.6763723495 |
| vm1084Best | 5416684.48968811 | 5673685.61075489 | 57788.89187585628 | 22.6358228047 |

| Instance | Result |
|----------|----------------|
| | |
| a280 | 30095.4 |
| d198 | 60897.2 |
| berlin52 | 22769.9 |
| d493 | 275482 |
| ch150 | 45760 |
| d1291 | 1.15254e + 006 |
| d657 | 472038 |
| ch130 | 39724.5 |
| vm1084 | 8.06018e+006 |

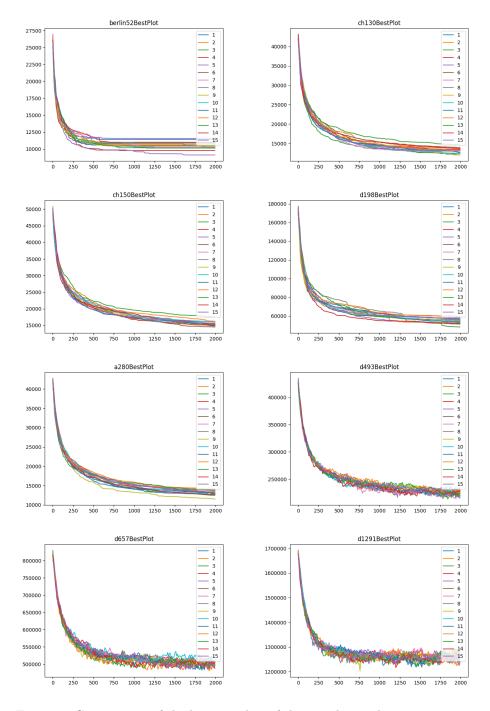


Figure 1: Convergence of the best member of the population during 15 runs

4 Interpretation

On the small instance the result is close to the global optimum and this should happen on smaller problems too.

On all runs we can observe on the plots that almost all the improvement was done during the first 500 generations making it seem like the 80/20 rule applies to combinatorical optimization.

We can observe from the graphs that the results tend to modify in a similar manner on all runs and on all 3 classes of instances.

The results could probably be further improved by using a nearest neighbour algorithm to generate the initial population.

The results could probably be further improved by using an algorithm based on nearest neighbour to reorder elements of aleles every once in a while.

The Min/Optimum raport tends to increase linearly with the dimensionality.

The results are better than the ones given by the random search algorithm on all 3 classes of inputs but the difference tends do decrease as the dimensionality increseas this would suggest that on a very big instance random search might yeald better results without further optimisation on the genetic algorithm.

5 Conclusion

The mutation rate should be lower on Traveling Salesman Problem and probably on most combinatorical optimization problems compared to numerical optimization problems. This can be due to the discrete nature of combinatorical optimization the steps on the gradient can be way bigger than in combinatorical optimization.

The mutation rate being low the evolution of the solutions is highly dependent on the crossover and the selection.

Genetic Algorithms yeald better results than a random search by a great margin on instances where the number of nodes is lower than 1000

5.1 Open questions

How would the results be impacted if Hyperparameter tuning was ran on a bigger instance?

How would the results would be impacted if Bayesian search would be used for Hyperparamer tuning?

How do different crossover variation affect the results

References

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