

**VISVESVARAYA TECHNOLOGICAL UNIVERSITY
JNANA SANGAMA, BELAGAVI 590018**



Project Entitled

**IMAGE REGENERATION WITH GENERATIVE
MODELS**

Submitted in partial fulfillment of the requirements for the award of degree of
BACHELOR OF ENGINEERING

In

COMPUTER SCIENCE AND ENGINEERING
For the Academic year 2017-2018

Submitted by

ABHIJITH C.	1MV14CS004
RAGHAVA G. DHANYA	1MV14CS077
SHASHANK S.	1MV14CS131

Project carried out at

Sir M. Visvesvaraya Institute of Technology
Bangalore-562157

Under the Guidance of

MRS. SUSHILA SHIDNAL

Assistant Professor, Department of CSE
Sir M Visvesvaraya Institute of Technology, Bangalore.



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SIR M VISVESVARAYA INSTITUTE OF TECHNOLOGY
BENGALURU 562157
DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING



CERTIFICATE

It is certified that the project work entitled "Image Regeneration With Generative Models" is carried out by Abhijith C. (1MV14CS004), Raghava G. Dhanya (1MV14CS077), Shashank S. (1MV14CS131) bona-fide student of Sir M Visvesvaraya Institute of Technology in partial fulfillment for the award of the Degree of Bachelor of Engineering in Computer Science and Engineering of the Visvesvaraya Technological University, Belagavi during the year 2016-2017. It is certified that all corrections and suggestions indicated for Internal Assessment have been incorporated in the report deposited in the department library. The project report has been approved as it satisfies the academic requirements in respect of project work prescribed for the course of Bachelor of Engineering.

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Signature with date

DECLARATION

We hereby declare that the entire project work embodied in this dissertation has been carried out by us and no part has been submitted for any degree or diploma of any institution previously.

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ABSTRACT

Current advances in Generative Adversarial Networks allow us to obtain near realistic images of faces but it is still quite distinguishable from actual photographic images. The technology is also not very amiable to changes in the orientation of faces in Convolutional Neural Networks(CNN). Additionally, the amount of data required to train the network must be exhaustible, for example, in case different perspectives of a face are required the various perspectives must be explicitly present in the training data to achieve the result. Thus the network requires humongous amounts of data.

In this project we propose a novel approach to accomplish the same results using CapsNet. CapsNet employs a dynamic routing algorithm which replaces the scalar-output feature detectors of the CNN with vector-output capsules. A capsule is essentially a group of neurons describing a specific part of object or image. Active capsules at one level make predictions, via transformation matrices, for the instantiation parameters of higher-level capsules. In essence, the CapsNet is the reverse of the common Computer Graphics pipeline where we convert objects to their renders. The CapsNet works from the pixel level and works up towards the object.

We propose that the amount of data required to train a comparable model is very small while it gives comparable, if not better, results.

CONTENTS

Abstract	ii
1 Introduction	1
1.1 Generative Models	1
1.1.1 Generative adversarial networks	1
1.1.2 Variational Autoencoders	2
1.1.3 Autoregressive models	2
1.2 Generative Adversarial Networks	2
1.3 Convolutional Neural Networks	3
1.4 Capsule Networks	4
1.5 Scope of work	4
1.6 Motivation	5
2 Literature Survey	6
2.1 DCGAN	6
2.2 InfoGAN	7
2.3 ACGAN	7
2.4 WGAN	7
2.5 Other GANs	7
2.6 Capsule Neural Network	8
3 Technology	9
3.1 Tensorflow	9
3.2 Keras	9
3.3 PyTorch	10
3.4 Google Colaboratory	10
4 System Requirements	11
4.1 Functional Requirements	11
4.2 Non Functional Requirements	11
4.3 Development Requirement	11
4.3.1 Training System Requirements	11
4.3.2 Testing System Requirements	12
5 Proposed Model	13
5.1 Generator	13
6 Implementation	14
7 Code snippets	16
7.1 Building Generator	16
8 Execution and Results	17
9 Conclusion	18
References	19

LIST OF FIGURES

1.1	Vanilla Generative Adversarial Network	2
1.2	Convolutional Neural Network	3
1.3	Capsule Networks	4
2.1	Deep Convolutional Generative Adversarial Network	6
5.1	Generator architecture	13
6.1	Proposed architecture	14

CHAPTER 1

INTRODUCTION

"What I cannot create, I do not understand."

Richard Feynman

One of the main aspirations of Artificial Intelligence is to develop algorithms and techniques that enrich computers with ability to understand our world. Generative models are one of the most promising approaches towards achieving this goal.

1.1 Generative Models

A generative model is a mathematical or statistical model to generate all values of a phenomena. To train such a model, we first collect a large amount of data in some domain (e.g., think millions of images, sentences, or sounds, etc.) and then train a model to generate data like it.

A generative algorithm models how data was generated to classify a data instance. It poses the question: according to my generation hypotheses, which category is most likely to generate this data instance? A discriminative algorithm does not care about how the data was generated, it just classifies a given data instance; that is, given the features of a data instance, they predict a label or category to which that data belong. Discriminative models learn the boundary between classes while Generative models model the distribution of individual classes; that is, a generative model learns the joint probability distribution $p(x, y)$ while a discriminative model learns the conditional probability distribution $p(y|x)$ "probability of y given x ".

The trick is that the neural networks that we use as generating models have a significantly smaller number of parameters than the amount of data on which we train them, so the models are forced to effectively discover and internalize the essence of the data to generate it.

There are multiple approaches to build a generative models

1.1.1 Generative adversarial networks

Generative adversarial networks (GANs) are a class of generative algorithms used in unsupervised machine learning, implemented by a system of two neural networks competing in a zero-sum game framework. They were presented by Ian Goodfellow *et al.* [11]. This technique can generate photographs that seem at least superficially authentic to human observers, having many realistic features (though in tests people can tell real from generated in some cases).

1.1.2 Variational Autoencoders

An autoencoder network is actually a pair of two connected networks, an encoder and a decoder. An encoder network receives an input and converts it into a smaller, denser representation that the decoder network can use to convert it back to the original input. Variational Autoencoders (VAEs) have one fundamentally unique property that separates them from vanilla autoencoders, and it is this property that makes them so useful for generative modeling: their latent spaces are, by design, continuous, allowing easy random sampling and interpolation. Variational Autoencoders (VAEs) allow us to formalize generative modeling problem in the framework of probabilistic graphical models where we are maximizing a lower bound on the log likelihood of the data

1.1.3 Autoregressive models

Autoregressive models such as PixelRNN, on the other hand train a network that models the conditional distribution of every individual pixel given previous pixels (to the left and to the top). These models efficiently generate independent, exact samples via ancestral sampling. This is similar to plugging the pixels of the image into a char-rnn, but the RNNs runs both horizontally and vertically over the image instead of just a 1D sequence of characters.

1.2 Generative Adversarial Networks

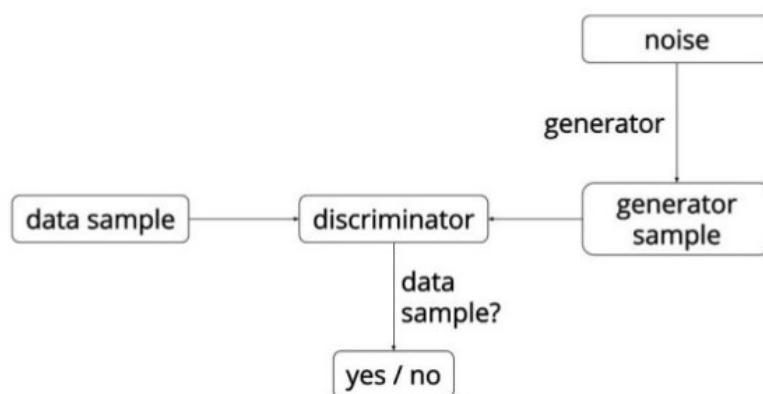


Figure 1.1: Vanilla Generative Adversarial Network

Generative Adversarial Networks, which we already discussed above, pose the training process as a game between two distinct networks: A neural network, called the generator, generates new instances of data, while the other, the discriminator, evaluates their authenticity; discriminator network tries to classify samples as either coming from the true distribution $p(x)$ or the model distribution $\hat{p}(x)$. Every time the discriminator notices a difference between the two distributions the generator adjusts its parameters slightly to make it go away, until at the end (in theory) the generator exactly reproduces the true data distribution and the discriminator is guessing at random, unable to find a difference.

The generator takes noise as input and attempts to produce an image that belongs to the real distribution; that is, it tries to fool the discriminator to accept it as real image. Discriminator takes a generated image or a real image as input and attempts to correctly classify the image as real or fake (generated).

To learn the distribution of the generator p_g over data x , we define a prior on input noise variables $p_z(z)$, then represent a mapping to data space as $G(z; \theta_g)$, where G is a differentiable function represented by a neural network with parameters θ_g . We define a second neural network $D(x; \theta_d)$ that outputs a single scalar. $D(x)$ represents the probability that x came from the data rather than p_g . We train D to maximize the probability of assigning the correct label to the training examples and samples of G . We simultaneously train G to minimize $\log(1 - D(G(z)))$.

This can be represented minimax game

$$\min_G \max_D V(D, G) = \mathbb{E}_{x \sim p_{\text{data}}(x)} [\log D(x)] + \mathbb{E}_{z \sim p_z(z)} [\log(1 - D(G(z)))] \quad (1.1)$$

1.3 Convolutional Neural Networks

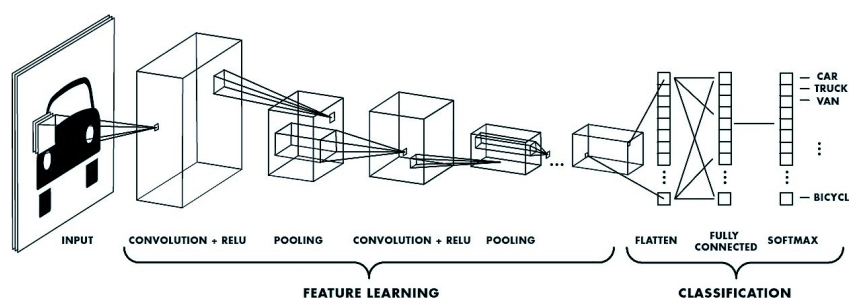


Figure 1.2: Convolutional Neural Network

Before we can jump to understanding Capsule Networks, we need to know about Convolutional Neural Networks (CNNs). Convolutional neural networks are very similar to ordinary neural networks, they consist of neurons that have learnable weights and biases. Each neuron receives inputs, performs a scalar product and possibly follows it with a nonlinearity. The entire network expresses a single differentiable score function: raw image pixels at one end to class scores at the other end. And they still have a loss function on the last layer.

The major difference is that CNN explicitly assumes that the inputs are images, which allows us to encode certain properties in the architecture. These then make the forward functions more efficient to implement and significantly reduces the amount of parameters in the network.

Ordinary neural networks don't scale well to full images, for example, A colour image of dimensions of 150x150 (which is considered as low resolution by most people) has a shape (150,150,3), a fully connected neuron on first layer which receives this image would require 67500 weights. Unlike an ordinary neural network, the layers of a CNN have neurons arranged in 3 dimensions: width, height, depth as shown in figure 1.2. The neurons in a layer will only be connected to a small region of the layer

before it, instead of all of the neurons in a fully-connected manner. CNN will reduce the full image into a single vector of class scores, arranged along the depth dimension.

CNNs use a "Pooling" layer to reduce the spatial size of the input for each convolutional layer. The Pooling Layer operates independently on every depth slice of the input and resizes it spatially, generally using the MAX operation, hence pooling layer is sometimes referred to as Max Pooling layer.

1.4 Capsule Networks

“The pooling operation used in convolutional neural networks is a big mistake and the fact that it works so well is a disaster.” says Geoffrey Hinton, one of the founders of deep learning (Also known as Godfather of Deep Learning) and an inventor of numerous models and algorithms that are widely used today. CNNs perform exceptionally great when they are classifying images which are very close to the data set. If the images have rotation, tilt or any other different orientation then CNNs have poor performance. This problem is usually partially solved by adding different variations of the same image during training. But CNNs still require large amount of data to perform reasonably well. We use pooling after each layer to make it compute in reasonable time frames. But in essence, it also loses out the positional data.

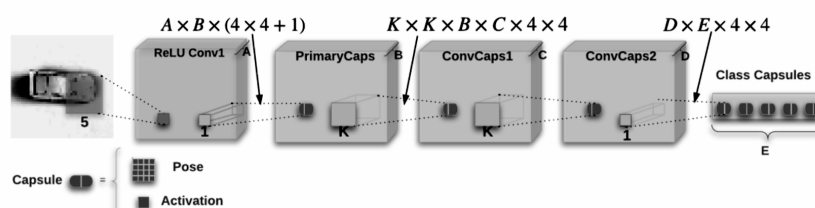


Figure 1.3: Capsule Networks

What we need is not invariance but equivariance. Invariance makes a CNN tolerant to small changes in the viewpoint. Equivariance makes a CNN understand the rotation or proportion change and adapt itself accordingly so that the spatial positioning inside an image is not lost. This leads us to Capsule Networks.

Capsule is a nested set of neural layers as shown in figure 1.3. Capsules are like cortical columns in human brains. Deep neural nets learn by back-propagation of errors over the entire network. In contrast real brains supposedly wire neurons by Hebbian principles: “units that fire together, wire together”. Capsules mimic Hebbian learning in the way that: “A lower-level capsule prefers to send its output to higher level capsules whose activity vectors have a big scalar product with the prediction coming from the lower-level capsule”. Capsules, combination of capsules encodes objects parts AND their relative positions, so an object instance can be accurately derived from the presence of the parts at the right locations, and not just their presence. Capsules produce equivariant features. Capsules predict the activity of higher-layer capsules to route information to right higher-layer capsules, this is called "Dynamic routing".

1.5 Scope of work

Generative Adversarial Networks are one of the hottest topics in Deep Learning right now. The applications of GANs are far ranging and immense. Creating Info-

graphics from text, creating animations for rapid development of marketing content, generating website designs are to name a few. Our focus in this project is to implement a way to complete images of faces by generating the missing pieces using a GAN.

This particular implementation of the technology would be immensely useful in a variety of circumstances. A few straightforward applications include face sketching of suspects in a crime using eye witness accounts, super resolution of CCTV camera footage to enhance faces, filling in of old degraded color photos, etc.

1.6 Motivation

The existing latest state-of-the-art GAN architectures use Convolution Neural Networks in their Generators and Discriminators. The CNNs are said to have the drawbacks as mentioned before, where they cannot understand orientation and spatial relationships unless they are extensively trained with all possible images. This major drawback is handled by Capsule Networks.

Using the CapsNet architecture into the Generator/Discriminator could improve these Adversarial Networks quite drastically. This mating of the revolutionary Generative Adversarial Networks along with the ground-breaking Capsule Networks, resulting in “Capsule Net GANs” is the overarching objective.

CHAPTER 2

LITERATURE SURVEY

“Adversarial training is the coolest thing since sliced bread”

Yann LeCun,

Director of AI Research at Facebook and Professor at NYU

GANs were first introduced by Ian Goodfellow *et al.* [11] in Neural Information Processing Systems 2014. The paper proposes a completely new framework for estimating generative models via an adversarial process. In this process two models are simultaneously trained. According to [11] the network has a generative model G that captures the data distribution, and a discriminative model D that estimates the probability that a sample came from the training data rather than G . This original work by Ian Goodfellow uses fully connected neural networks in the generator and the discriminator.

2.1 DCGAN

Since GANs were introduced, there has been tremendous advancements in Deep Learning. A convolutional neural network (CNN, or ConvNet) [13] is a class of deep, feed-forward artificial neural networks that has successfully been applied to analyzing visual imagery. The convolution layer parameters consist of a set of learn-able filters, also called as kernels, which have a small receptive field, but they extend through the full depth of the input volume. As a result, the network learns filters that activate when it detects some specific type of feature at some spatial position in the input.

A breakthrough development that occurred in Adversarial Networks was the introduction of “Deep Convolutional Generative Adversarial Networks” by Alec Radford *et al* [10]. DCGAN uses CNNs as generator and discriminator as shown in 2.1. He applied a list of empirically validated tricks as the substitution of pooling and fully connected layers with convolutional layers.

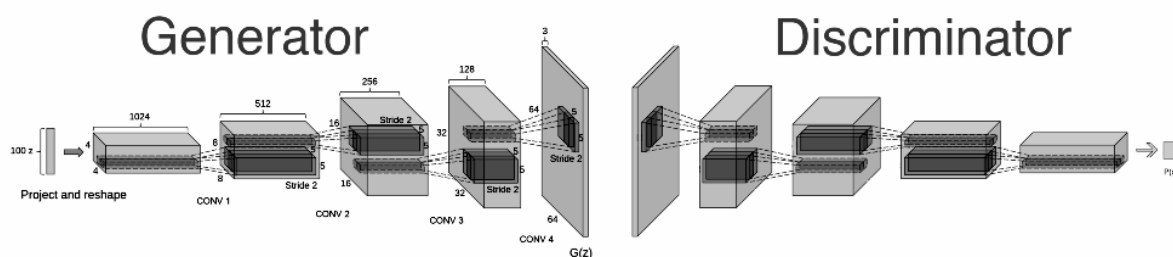


Figure 2.1: Deep Convolutional Generative Adversarial Network

Today, most GANs are loosely based on the former shown DCGAN [10] architecture. Many papers have focused on improving the setup to enhance stability and

performance. Many key insights were given by Salimans *et al.* [8], like Usage of convolution with stride instead of pooling, Usage of Virtual Batch Normalization, Usage of Minibatch Discrimination in DD, Replacement of Stochastic Gradient Descent with Adam Optimizer [6], Usage of one-sided label smoothing.

2.2 InfoGAN

The power of the features encoded in the latent variables was further explored by Chen *et al.* [4]. They propose an algorithm which is completely unsupervised, unlike previous approaches which involved supervision, and learns interpretable and disentangled representations on challenging datasets. Their approach only adds a negligible computation cost on top of GAN and is easy to train.

2.3 ACGAN

Augustus Odena *et al.* [7] came up with an improved training of generative adversarial networks and a variant of GAN with employing label conditioning that results in image samples exhibiting global coherence. ACGAN uses an auxiliary classifier to control the minimax game between generator and discriminator. In their work they demonstrate that adding more structure to the GAN latent space along with a specialized cost function results in higher quality samples.

2.4 WGAN

Another huge development came with the introduction of Wasserstein GANs by Martin Arjovsky [1]. He introduced a new algorithm named WGAN, an alternative to traditional GAN training. In this new model, he showed that the stability of learning can be improved, remove problems like mode collapse, and provide good learning curves useful for debugging and hyperparameter searches.

This recently proposed Wasserstein GAN (WGAN) [1] makes progress toward stable training of GANs, but sometimes can still generate only low-quality images or fail to converge. Ishaan Gulrajani with Martin Arjovsky proposed an alternative in [2] to fix the issues the previous GAN faced. This proposed method performs better than standard WGAN and enables stable training of a wide variety of GAN architectures with almost no hyperparameter tuning, including 101-layer ResNets [9] and language models over discrete data.

2.5 Other GANs

Work by Mehdi Mirza *et al.* [12] introduced the conditional version of GAN which can be constructed by simply feeding the data, y , we wish to condition on to both the generator and discriminator. The CGAN results were comparable with some other networks, but were outperformed by several other approaches – including non-conditional adversarial nets.

Sebastian Nowozin *et al.* [6] discussed the benefits of various choices of divergence functions on training complexity and the quality of the obtained generative models. They show that any f-divergence can be used for training generative neural samplers.

Ming-Yu *et al.* [5] proposed coupled generative adversarial network (CoGAN) for learning a joint distribution of multi-domain images. The existing approaches requires tuples of corresponding images in different domains in the training data set. CoGAN can learn a joint distribution without any tuple of corresponding images.

2.6 Capsule Neural Network

A big breakthrough in the field of Deep Learning came with the introduction of CapsNets or Capsule Networks [3] by the Godfather of Deep Learning, Geoffrey Hinton *et al.* CNNs perform exceptionally great when they are classifying images which are very close to the data set. If the images have rotation, tilt or any other different orientation then CNNs have poor performance. A capsule is a group of neurons whose activity vector represents the instantiation parameters of a specific type of entity such as an object or an object part. They use the length of the activity vector to represent the probability that the entity exists and its orientation to represent the instantiation parameters. Active capsules at one level make predictions, via transformation matrices, for the instantiation parameters of higher-level capsules. When multiple predictions agree, a higher level capsule becomes active. They show that a discriminatively trained, multi-layer capsule system achieves state-of-the-art performance on MNIST and is considerably better than a convolutional net at recognizing highly overlapping digits. To achieve these results they use an iterative routing-by-agreement mechanism: A lower-level capsule prefers to send its output to higher level capsules whose activity vectors have a big scalar product with the prediction coming from the lower-level capsule.

CHAPTER 3

TECHNOLOGY

"I think, therefore I am"

*René Descartes,
French philosopher and scientist*

Deep learning frameworks offer flexibility with designing and training custom deep neural networks and provide interfaces to common programming language. We used the following frameworks and technologies in our project.

3.1 Tensorflow

TensorFlow is an open source software library for high performance numerical computation. Its flexible architecture allows easy deployment of computation across a variety of platforms (CPUs, GPUs, TPUs), and from desktops to clusters of servers to mobile and edge devices. Originally developed by researchers and engineers from the Google Brain team within Google's AI organization, it comes with strong support for machine learning and deep learning and the flexible numerical computation core is used across many other scientific domains. TensorFlow, as the name indicates, is a framework to define and run computations involving tensors. A tensor is a generalization of vectors and matrices to potentially higher dimensions. Internally, TensorFlow represents tensors as n-dimensional arrays of base datatypes. TensorFlow uses a dataflow graph to represent your computation in terms of the dependencies between individual operations. This leads to a low-level programming model in which you first define the dataflow graph, then create a TensorFlow session to run parts of the graph across a set of local and remote devices.

We use Tensorflow when we need access to low level API such as metric functions or auto gradient functions.

3.2 Keras

Keras is a high-level neural networks API, written in Python and capable of running on top of TensorFlow, CNTK, or Theano. It was developed with a focus on enabling fast experimentation. It puts user experience front and center. Keras follows best practices for reducing cognitive load: it offers consistent & simple APIs, it minimizes the number of user actions required for common use cases, and it provides clear and actionable feedback upon user error. A model is understood as a sequence or a graph of standalone, fully-configurable modules that can be plugged together with as little restrictions as possible. In particular, neural layers, cost functions, optimizers, initialization schemes, activation functions, regularization schemes are all standalone modules that you can combine to create new models. Can easily create new modules allows for total expressiveness, making Keras suitable for advanced research.

We use Keras as our primary Deep learning library. Most of our code uses keras.

3.3 PyTorch

PyTorch is a relatively new framework. PyTorch provides Tensors that can live either on the CPU or the GPU, and accelerate compute by a huge amount. It also provides a wide variety of tensor routines to accelerate and fit your scientific computation needs such as slicing, indexing, math operations, linear algebra, reductions. PyTorch has a unique way of building neural networks: using and replaying a tape recorder. Most frameworks such as TensorFlow, Theano, Caffe and CNTK have a static view of the world. One has to build a neural network, and reuse the same structure again and again. Changing the way the network behaves means that one has to start from scratch. With PyTorch, it uses a technique called Reverse-mode auto-differentiation, which allows you to change the way your network behaves arbitrarily with zero lag or overhead. Its inspiration comes from several research papers on this topic, as well as current and past work such as autograd, autograd, Chainer, etc. While this technique is not unique to PyTorch, it's one of the fastest implementations of it to date.

We have a simple proof of concept implementation of our project in PyTorch, which can easily be extended to other GANs.

3.4 Google Colaboratory

Colaboratory is a research tool for machine learning education and research. Colaboratory is a Google research project created to help disseminate machine learning education and research. It's a Jupyter notebook environment that requires no setup to use and runs entirely in the cloud. We can use GPU as a backend for free for 12 hours at a time. The GPU used in the backend is Nvidia Tesla K80. Colaboratory notebooks are stored in Google Drive and can be shared just as you would with Google Docs or Sheets. Colaboratory supports both Python2 and Python3 for code execution. It has Intel Xeon 2vCPU running at 2.2 GHz, 13 GB RAM and 33 GB storage space. We used Google Colaboratory extensively for our project. We trained and tested all of our models on colaboratory. It provides an average 10 times speed-up than running on a local machine.

CHAPTER 4

SYSTEM REQUIREMENTS

“Any A.I. smart enough to pass a Turing test is smart enough to know to fail it.”

*Ian McDonald,
River of Gods*

4.1 Functional Requirements

The system must be able to

1. Take a latent space vector or noise.
2. Learn joint probability distribution of training images.
3. Generate a realistic image of the training distribution and doesn't belong to training set.
4. Use a binary Capsule network classifier to predict real or fake image.

4.2 Non Functional Requirements

The system should have following non functional requirements.

1. Efficiency, Fast forward and backward propagation.
2. Use less data and still produce high quality results.

4.3 Development Requirement

System requirements for training and testing model

4.3.1 Training System Requirements

For training the model,

1. python 3.4 or above
2. Tensorflow 1.7 or above
3. Keras 2.1.6 or above
4. Numpy, Scipy, Matplotlib
5. OpenCV 2

6. CPU 1.6 GHz or above
7. Nvidia GPU with CUDA compatibility 3.5 or above
8. RAM 8GB or above
9. Disk storage 20GB or above

4.3.2 Testing System Requirements

For evaluating the model or just forward propagation,

1. python 3.4 or above
2. Tensorflow 1.7 or above
3. Keras 2.1.6 or above
4. Numpy, Scipy, Matplotlib
5. OpenCV 2
6. CPU 1 GHz or above
7. RAM 4GB or above
8. Disk storage 20GB or above

CHAPTER 5

PROPOSED MODEL

“Artificial intelligence, in fact, is obviously an intelligence transmitted by conscious subjects, an intelligence placed in equipment.”

Pope Benedict XVI

5.1 Generator

We use a deep convolutional generator model, this is similar to what DCGAN uses as generator. It starts with latent vector or noise of shape (100) which connects to a densely connected layer. We then use Reshape layer which reshapes it to (8, 8, 128) and perform batch normalization in batch normalization layer. We then perform up-sampling by using DeConv layer. DeConv layer is internally created by a up-sampling layer and Convolutional layer. We perform DeConv two more times to get the shape of the image as expected.

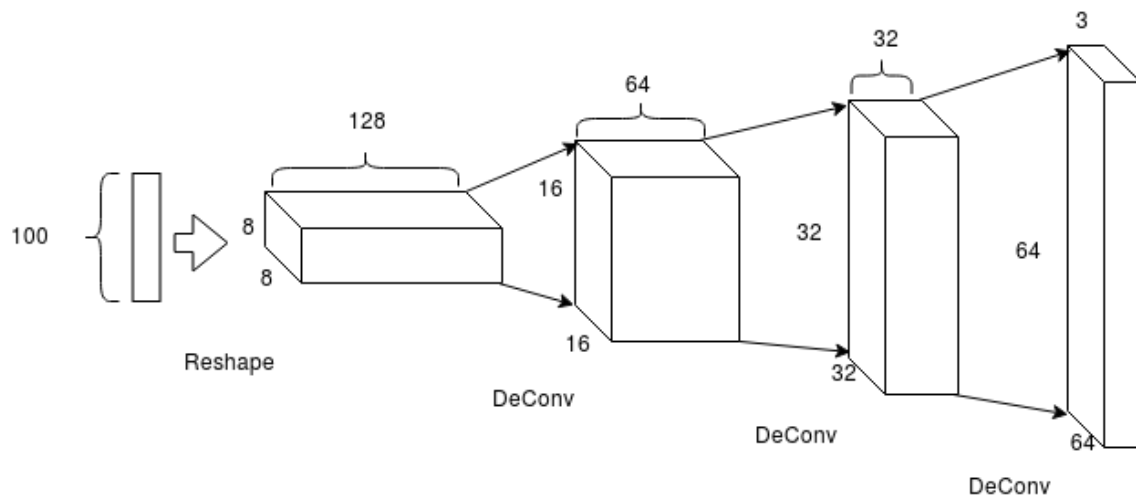


Figure 5.1: Generator architecture

CHAPTER 6

IMPLEMENTATION

The first step would be to implement the state-of-the-art in image regeneration to gauge the improvements. We use DCGAN to start of with. The results of the training and testing will be recorded to compare it with the results of our CapsNet-based approach later. We will be using CapsNet as the underlying technology to implement our GAN (CapsGAN). The goal is to replace the CNN inside DCGAN with CapsNet and compare the results. The GAN internally consists of two components - a generator and a discriminator - which we build out of CapsNet. The discriminator is initially trained separately to distinguish real and fake data, and later they work together to improve upon their performance by acting as adversaries.

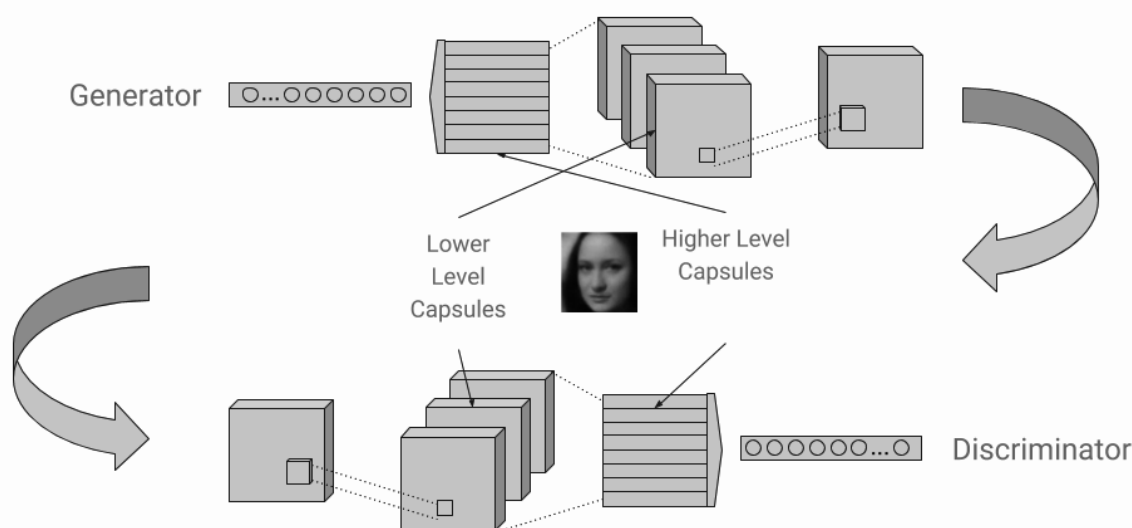


Figure 6.1: Proposed architecture

The generator will use noise as input to generate faces. We will use random data as this noise. This ensures the data is unique and across the spectrum while retaining a normal distribution.

The CapsNet making up the discriminator consists of a small convolutional network to convert low level data in the form of pixels into an artifact called "pose". These poses can be anything, like nose, ear, eye, etc. These poses are then passed on as input to the later lower layers consisting of components called Capsules. A capsule is analogous to the human brain containing different modules to handle different tasks. The brain has a mechanism to route the information among the modules, to reach the best modules that can handle the information.

A capsule is a nested set of neural layers. Each capsule is able to handle one particular pose and communicate its calculation to other capsules which can use that calculation. This calculation is in the form of a probability prediction of the current pose that takes place in its logistic unit. This working is fundamentally different from convolutional networks, which utilizes Max Pooling. Max pooling selects the most active input node from the next layer to pass on the information. CapsNet on the other hand selects the next capsule based on which capsule would be capable of handling that information. This is called Dynamic routing. This results in invariance of information to the position and orientation of features in an object while ignoring the invariance in very low level features as, at the pixel level, this does not matter.

The generator is built using an architecture that is a mirror image of the discriminator. Inside, the data flow is in the opposite direction. The job of the discriminator is to take the images given out by the generator and discriminate it against a ground truth. The discriminator selects the class based on how close the images are in agreement. The underlying principle is that when multiple entities agree with each other in higher dimensions, the chances of it happening due to complete coincidence is exponentially minimal. This ensures the understanding by the CapsNet of the world is remarkably similar to humans.

CHAPTER 7

CODE SNIPPETS

“By far the greatest danger of Artificial Intelligence is that people conclude too early that they understand it.”

*Eliezer Yudkowsky,
Machine Intelligence Research Institute*

7.1 Building Generator

```
def build_generator(self):  
    model = Sequential()  
  
    model.add(Dense(128 * 8 * 8, activation="relu", input_shape=(self.latent_dim,)))  
    model.add(Reshape((8, 8, 128)))  
    model.add(BatchNormalization(momentum=0.8))  
    model.add(UpSampling2D())  
    model.add(Conv2D(128, kernel_size=3, padding="same"))  
    model.add(Activation("relu"))  
    model.add(BatchNormalization(momentum=0.8))  
    model.add(UpSampling2D())  
    model.add(Conv2D(64, kernel_size=3, padding="same"))  
    model.add(Activation("relu"))  
    model.add(BatchNormalization(momentum=0.8))  
    model.add(UpSampling2D())  
    model.add(Conv2D(32, kernel_size=3, padding="same"))  
    model.add(Activation("relu"))  
    model.add(BatchNormalization(momentum=0.8))  
    model.add(Conv2D(self.channels, kernel_size=3, padding="same"))  
    model.add(Activation("tanh"))  
  
    model.summary()  
  
    noise = Input(shape=(self.latent_dim,))  
    img = model(noise)  
  
    return Model(noise, img)
```


CHAPTER 8

EXECUTION AND RESULTS

CHAPTER 9

CONCLUSION

"A year spent in artificial intelligence is enough to make one believe in God"

*Alan Perlis,
First Turing award recipient*

During the course of this project, we wished to replicate the results of the existing state-of-the-art in Generative Models. We implemented a few different versions of GANs with CapsNet. Our motivating assumption was that CapsNet would provide a performance improvement. We based this on the idea that it is more capable of understanding the variances in objects. This in turn should lead to lower data requirements during training of the model and consequently lower power consumption.

We provide a comparison between our novel CapsNet-based approach and other implementations of GAN for the same task. To observe this we augment the code of a few GANs, namely ACGAN, InfoGAN, DCGAN and WGAN, by implementing the discriminator with CapsNet. We decided to work with a few standard metrics such as Discriminator Loss, Generator Loss and Accuracy to measure its training performance. The data while training was captured and visualized in the form of graphs.

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