MIRASOL 3B

Multimodal ~~Auto~~ Regressive Model.

Main challenges = Combining Multiple Heterogeneous Modalities

Video, Audio and Text

[Video / Audio] are roughly aligned in time. (Video, Audio) are higher rates than Text

They are not synchronized with Text which comes as a global context.

eg: Title / Description.

[Video, Audio Inputs are much larger volumes] ∝ Video length increases

⇓

Needs more Compute time for these Modalities.

Mirasol 3B ⇒ ① Auto regressive Component for synchronized Modalities (Audio / Video) non time aligned

Component which are not with time but Sequential

② Autoregressive Context modalities necessarily aligned

To address the long sequence of Video / Audio Inputs ⇒ partition of video / Audio sequences in [Consecutive Snippets] and autoregressively process their representations.

[Combiner Mechanism] : audio, video

[illegible] ⇒ [illegible]

information jointly producing compact but expressive representations.

↓

This makes the Model to take 512 frame input without increase in the Model Parameter.

[Note: Architecture for Video Language understanding commonly use a joint transformer [Video input + Text tokens] are processed auto regressively]

Inputs:- Input Video sequence of N frames

$V = (v_1 f, v_2 f, \ldots v_N f)$

Audio waves signal of M timesteps

$a = (a_1 f, a_2 f, \ldots a_M f)$

$t = \{t_1 f, t_2 f, \ldots t_P f\}$ (Text Sequence)

Partioning the video & Audio inputs:

$\{\underbrace{v_1 f, v_2 f, \ldots v_k f}_{V_1 \text{ Chunks}}\}, \{\underbrace{v_{k+1} f, v_{k+2} f, \ldots v_{2k} f}_{V_2}\}, \ldots$

$\underbrace{(v_{(T-1)k+1} f \ldots v_N f)}_{V_T}$

$k = N/T$

T = Non overallipity Chunks.

[Each of every chunk] ⇒ Latent features

Video — Spatiotemporal representation. → Extract sparse 3D tubes with standard 2D Patches.] are processed using the ViT Encoder

Audio — Represented as spectrograms

Combiner Module :-

1) Combine Video & Audio features at specific snippet of time (Joint representation)

2) Also Compress the representation from each [audio / Video] snippet, allows the model to scale to longer videos.

$\hat{v} = \{v_1^{\wedge}, v_2^{\wedge} \dots v_N^{\wedge}\}$ ⇒ Video

$\hat{a} : \{a_1^{\wedge}, a_2^{\wedge}, \dots a_N^{\wedge}\}$ ⇒ audio

Composed of f features of size d (f, d) ← shape

Composed of s features fixed shape (s, d)

Combiner ① $u = \{u_1, u_2, v_3, \dots u_f\}$

Where $u_t : \{\hat{v}_t, \hat{a}_t\}$ and size (n, d) where $n = f + s$

② Then maps u to lower dimensional features space $x = \{x_1, x_2, \dots x_T\}$

Where x_t has the shape (m, d)

Where $n >> m$

Combines two different Architectures

1. Standard Transformer Re
2. Token Turing Machine.

The Aligned Video Audio Auto regressive Mo

Condition from (Audio / Video) representation. previous time Intervals

$x_t \Rightarrow$ passed sequentially to auto regressive Model.

$$p(v, a) = \prod_{i=1} \left[p(v_{t+1}, a_{t+1} \mid h_t) \right]$$

Modality reconstruction Model.

$$\left[p(h_t \mid x_t) \right] \left[p(x_t \mid v_t, a_t) \right]$$

Combiner.

$\Downarrow$

Simulated by latent Causal Model.