## Figure 3

```
\label{eq:loss_equation} \begin{split} & \text{Id} = \text{IdentityMatrix[2];} \\ & \text{RY[$\theta_{-}$]} := \{\{\text{Cos[$\theta/2], -Sin[$\theta/2]}\}, \{\text{Sin[$\theta/2], Cos[$\theta/2]}\} \} \\ & \text{RY[$\theta_{1}$].} \{1, \, 0\} \\ & \text{KroneckerProduct[$RY[$\theta_{1}$], Id].Flatten[KroneckerProduct[$\{1, \, 0\}, \, \{1, \, 0\}]]} \\ & \text{KroneckerProduct[$RY[$\theta_{1}$], RY[$\theta_{2}$]].Flatten[KroneckerProduct[$\{1, \, 0\}, \, \{1, \, 0\}]]} \\ & \text{Out}_{\theta_{0}} = \left\{\text{Cos}\left[\frac{\theta_{1}}{2}\right], \, \text{Sin}\left[\frac{\theta_{1}}{2}\right]\right\} \\ & \text{Out}_{\theta_{0}} = \left\{\text{Cos}\left[\frac{\theta_{1}}{2}\right], \, 0, \, \text{Sin}\left[\frac{\theta_{1}}{2}\right], \, 0\right\} \\ & \text{Out}_{\theta_{0}} = \left\{\text{Cos}\left[\frac{\theta_{1}}{2}\right], \, \text{Cos}\left[\frac{\theta_{2}}{2}\right], \, \text{Cos}\left[\frac{\theta_{2}}{2}\right], \, \text{Sin}\left[\frac{\theta_{2}}{2}\right]\right\} \\ & \text{Sin}\left[\frac{\theta_{1}}{2}\right], \, \text{Sin}\left[\frac{\theta_{2}}{2}\right], \, \text{Sin}
```

## Figure 4

```
Id = IdentityMatrix[2];
RY[\theta_{-}] := \{\{Cos[\theta/2], -Sin[\theta/2]\}, \{Sin[\theta/2], Cos[\theta/2]\}\}\}
res = KroneckerProduct[RY[\theta_{-}]], RY[\theta_{-}]].Flatten[KroneckerProduct[\{1, 0\}, \{1, 0\}]]
GraphicsRow[\{BarChart[res/. \{\theta_{-}] \rightarrow \pi/2, \theta_{-} \rightarrow \pi/2\}, ImageSize \rightarrow Small],
BarChart[res/. \{\theta_{-}] \rightarrow \pi/2, \theta_{-} \rightarrow \pi/2\}, ImageSize \rightarrow Small],
BarChart[res/. \{\theta_{-}] \rightarrow \pi/2, \theta_{-} \rightarrow \pi/2\}, ImageSize \rightarrow Small],
BarChart[res/. \{\theta_{-}] \rightarrow \pi/2, \theta_{-} \rightarrow \pi/2\}, ImageSize \rightarrow Small],
BarChart[res/. \{\theta_{-}] \rightarrow \pi/2, \theta_{-} \rightarrow \pi/2\}, ImageSize \rightarrow Small],
Cos[\frac{\theta_{-}}{2}] Cos[\frac{\theta_{-}}{2}], Cos[\frac{\theta_{-}}{2}], Cos[\frac{\theta_{-}}{2}], Cos[\frac{\theta_{-}}{2}], Sin[\frac{\theta_{-}}{2}], Sin[\frac{\theta_{-}}
```

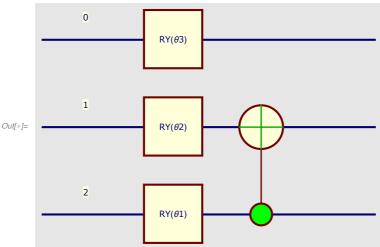
## Figure 5

```
In[*]:= Clear[Id, RY, θ, res, CNOT]
          Id = IdentityMatrix[2];
          RY[\theta_{-}] := \{ \{ \cos[\theta/2], -\sin[\theta/2] \}, \{ \sin[\theta/2], \cos[\theta/2] \} \}
         CNOT = IdentityMatrix[4];
          u = CNOT[3, ;;]]; CNOT[3, ;;]] = CNOT[4, ;;]]; CNOT[4, ;;]] = u;
          CNOT // MatrixForm;
          res = KroneckerProduct[RY[01], RY[02]].Flatten[KroneckerProduct[{1, 0}, {1, 0}]]
          BarChart[res /. \{\theta 1 \rightarrow \pi / 2, \theta 2 \rightarrow 2 \pi / 3\}, ImageSize \rightarrow Small]
          res = CNOT.KroneckerProduct[RY[\theta1], RY[\theta2]].
              Flatten[KroneckerProduct[{1, 0}, {1, 0}]]
          BarChart[res /. \{\theta 1 \rightarrow \pi / 2, \theta 2 \rightarrow 2\pi / 3\}, ImageSize \rightarrow Small]
\text{Out}[*] = \left\{ \text{Cos}\left[\frac{\theta 1}{2}\right] \text{Cos}\left[\frac{\theta 2}{2}\right], \text{Cos}\left[\frac{\theta 1}{2}\right] \text{Sin}\left[\frac{\theta 2}{2}\right], \text{Cos}\left[\frac{\theta 2}{2}\right] \text{Sin}\left[\frac{\theta 1}{2}\right], \text{Sin}\left[\frac{\theta 1}{2}\right] \right\}
         0.5
         0.4
Out[•]= 0.3
Out[*] = \left\{ \cos\left[\frac{\theta 1}{2}\right] \cos\left[\frac{\theta 2}{2}\right], \cos\left[\frac{\theta 1}{2}\right] \sin\left[\frac{\theta 2}{2}\right], \sin\left[\frac{\theta 1}{2}\right] \sin\left[\frac{\theta 2}{2}\right], \cos\left[\frac{\theta 2}{2}\right] \sin\left[\frac{\theta 1}{2}\right] \right\}
         0.6
         0.5
Out[ ]= 0.3
         0.2
         0.1
         0.0
```

## Figure 6

(\* import package to facilitate operations on >2 qubits \*) Needs["Quantum`Computing`"];  $location Interpretation Matrix ToDirac [\{\{Cos[\frac{\theta}{2}], -Sin[\frac{\theta}{2}]\}, \{Sin[\frac{\theta}{2}], Cos[\frac{\theta}{2}]\}\}, \{2\}]$  $\textit{Out[*]} = \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \quad \big| \ \theta_{\hat{1}} \big\rangle \\ \cdot \left\langle \theta_{\hat{1}} \ \big| \ + \ \mathsf{Sin}\Big[\frac{\theta}{2}\Big] \quad \big| \ \mathbf{1}_{\hat{1}} \big\rangle \\ \cdot \left\langle \theta_{\hat{1}} \ \big| \ - \ \mathsf{Sin}\Big[\frac{\theta}{2}\Big] \quad \big| \ \theta_{\hat{1}} \big\rangle \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \quad \big| \ \mathbf{1}_{\hat{1}} \big\rangle \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}} \ \big| \ + \ \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \\ \cdot \left\langle \mathbf{1}_{\hat{1}}$ 

```
ln[∗]:= Clear[Δt, I2, Z, RZ, U1, U2, rot, psi, θ1, θ2, θ3, circ, circ1, circ2]
                                     I2 = PauliMatrix[0];
                                    Z = PauliMatrix[3];
                                      (* define RY rotation *)
                                     SetQuantumGate RY, 1,
                                                       Function [q1},
                                                                 Function [\theta],
                                                                       \mathsf{Cos}\Big[\frac{\theta}{2}\Big] \mid \mathsf{O}_{\hat{\mathsf{q1}}} \rangle \cdot \left\langle \mathsf{O}_{\hat{\mathsf{q1}}} \mid + \mathsf{Sin}\Big[\frac{\theta}{2}\Big] \mid \mathsf{1}_{\hat{\mathsf{q1}}} \right\rangle \cdot \left\langle \mathsf{O}_{\hat{\mathsf{q1}}} \mid - \mathsf{O}_{\hat{\mathsf{q1}}} \mid
                                                                                   \mathrm{Sin}\!\left[\frac{\theta}{2}\right] \; \left|\; \theta_{\hat{\mathsf{ql}}} \right\rangle \cdot \left\langle \mathbf{1}_{\hat{\mathsf{ql}}} \; \right| \; + \mathrm{Cos}\!\left[\frac{\theta}{2}\right] \; \left|\; \mathbf{1}_{\hat{\mathsf{ql}}} \right\rangle \cdot \left\langle \mathbf{1}_{\hat{\mathsf{ql}}} \; \right| \; \right] \; \right];
                                     QuantumTableForm[RY; [△t]];
                                     QuantumMatrixForm[RY; [\Deltat]];
                                    QuantumMatrixForm \left[C^{\{\hat{3}\}}\left[NOT_{\hat{4}}\right]\right];
                                      (* build circuit *)
                                    circ1 = C^{\{2\}} \left[ NOT_{\hat{1}} \right] \cdot RY_{\hat{\theta}} \left[ \Theta 3 \right] \cdot RY_{\hat{1}} \left[ \Theta 2 \right] \cdot RY_{\hat{2}} \left[ \Theta 1 \right];
                                    QuantumPlot[circ1]
                                     U1 = QuantumMatrix[circ1];
                                      (* build circuit *)
                                    \texttt{circ2} = C^{\{\hat{2}\}} \left[ NOT_{\hat{\theta}} \right] \cdot C^{\{\hat{2}\}} \left[ NOT_{\hat{1}} \right] \cdot \mathsf{RY}_{\hat{\theta}} \left[ \Theta 3 \right] \cdot \mathsf{RY}_{\hat{1}} \left[ \Theta 2 \right] \cdot \mathsf{RY}_{\hat{2}} \left[ \Theta 1 \right];
                                    QuantumPlot[circ2]
                                     U2 = QuantumMatrix[circ2];
```



BarChart[(U1.{1, 0, 0, 0, 0, 0, 0}) /.  $\{\theta 1 \rightarrow \pi/2, \theta 2 \rightarrow 2\pi/3, \theta 3 \rightarrow 100/180\pi\}$ , ImageSize → Small] BarChart[(U2.{1, 0, 0, 0, 0, 0, 0}) /.  $\{\theta1 \rightarrow \pi/2, \theta2 \rightarrow 2\pi/3, \theta3 \rightarrow 100/180\pi\}$ , ImageSize → Small]