Temporal laser-pulse-shape effects in nonlinear Thomson scattering

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Notebook: Óscar Amaro, September 2022 @ GoLP-EPP

Figure 2

```
In[\theta]:= Clear[\xi, \xi, ALP, ACP, R, a, a0, \tau, \phi, int]
      a[\phi_{-}] := a0 Exp[-\phi^{2}/\tau^{2}];
      a0 = 2;
      \tau = 20;
      (* the integral has a full analytical solution *)
      int = Integrate [ (a0 Exp[-\xi^2/\tau^2]) ^2 Cos[\xi] ^2, {\xi, 0, \phi}];
      (* eq 29 implicit relation, solve numerically*)
      \phi[\mathcal{L}] := (\text{FindRoot}[\phi + \text{int} - \mathcal{L}, \{\phi, 0\}] // \text{Quiet}) [1, 2] // \text{Re} // \text{Quiet})
      (* eq 13 *)
     ACP[\mathcal{E}_{-}] := \frac{1}{R} \frac{a[\phi[\mathcal{E}]]}{1 + a[\phi[\mathcal{E}]]^{2}} Cos[\phi[\mathcal{E}]]
      (* eq 28 *)
      ALP[\mathcal{E}_{-}] := \frac{1}{R} \frac{a[\phi[\mathcal{E}]] \cos[\phi[\mathcal{E}]]}{1 + a[\phi[\mathcal{E}]]^{2} \cos[\phi[\mathcal{E}]]^{2}}
      (* lists *)
      ACPlst = ParallelTable[\{\xi, ACP[\xi]\}, \{\xi, -110, +110, 0.2\}];
      ALPlst = ParallelTable[\{\xi, ALP[\xi]\}, \{\xi, -110, +110, 0.2\}];
      (* plots *)
      ListPlot[ACPlst, Joined → True, Axes → False, Frame → True,
       FrameLabel → {"\zeta", "A[a.u.]"}, PlotLabel → "(left) CP"]
      ListPlot[ALPlst, Joined → True, Axes → False, Frame → True,
       FrameLabel → {"\zeta", "A[a.u.]"}, PlotLabel → "(right) LP"]
```

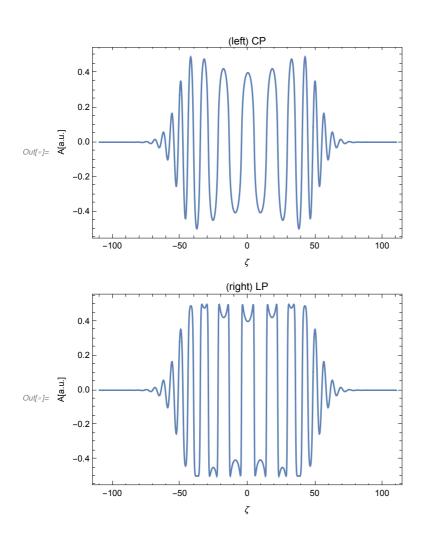


Table 1 / Figure 3 Gaussian

```
Clear[f, \phi, a, \tau, \omega, d2I, \chi, y, ff, fm1\xi, dfmi, a0]
 f = Exp[-2x^2];
 fm1 = (Solve[f == ff, x] [2, 1, 2] /. {c_1 \rightarrow 0}) // Normal // Simplify;
 fm1\xi = fm1 /. \{ff \rightarrow \xi\};
 dfmi = D[fm1, ff];
 \chi = Refine[\omega \tau a0^2 Integrate[fm1\xi, {\xi, y, 1}] - \pi / 4 // Normal, {\omega > 0}];
d2I = \frac{2 \omega \tau}{\pi} Abs[y dfmi /. \{ff \rightarrow y\}] Cos[\chi]^2;
 d2I // Simplify
    \tau \; \omega \; \text{Sin} \left[ \; \frac{1}{4} \; \left( \pi + \; \sqrt{2} \; \tau \; \left( a \Theta^2 \; \sqrt{\pi} \; \omega \; \text{Erf} \left[ \; \sqrt{\text{Log} \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right]} \; \right] \; + \; 2 \times \; (-1 + \omega) \; \; \sqrt{\text{Log} \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right]} \; \right] \; + \; 2 \times \; (-1 + \omega) \; \; \sqrt{\text{Log} \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right]} \; \right] \; + \; 2 \times \; (-1 + \omega) \; \; \sqrt{\text{Log} \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right]} \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; + \; 2 \times \; (-1 + \omega) \; \; \sqrt{\text{Log} \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right]} \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 + \omega} \; \right] \; \left[ - \frac{a \Theta^2 \; \omega}{-1 
                                                                                                                                                                                                                                                                                                           \sqrt{2} \pi \sqrt{Abs \left[ Log \left[ -\frac{a\theta^2 \omega}{-1+\omega} \right] \right]}
```

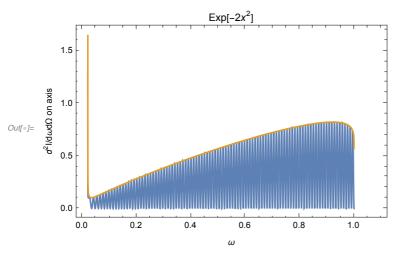
$$In[*]:= \tau = 10$$
; (* choose 10 instead of 200 to see the oscillations, factor of 2 missing in table? *)
$$a0 = 7;$$

$$Plot[$$

$$\left\{\frac{\tau\,\omega\,\text{Sin}\!\left[\frac{1}{4}\,\left(\pi+\,\sqrt{2}\,\,\tau\,\left(\text{a0}^2\,\,\sqrt{\pi}\,\,\omega\,\,\text{Erf}\!\left[\,\,\sqrt{\text{Log}\!\left[-\,\frac{\text{a0}^2\,\omega}{-\text{1}+\omega}\,\right]}\,\,\right]+2\times\,\left(-\,\text{1}+\omega\right)\,\,\,\sqrt{\text{Log}\!\left[-\,\frac{\text{a0}^2\,\omega}{-\text{1}+\omega}\,\right]}\,\,\right)\right)\right]^2}{\sqrt{2}\,\,\pi\,\,\,\sqrt{\text{Abs}\!\left[\text{Log}\!\left[-\,\frac{\text{a0}^2\,\omega}{-\text{1}+\omega}\,\right]\,\right]}}$$

$$2\frac{\omega\tau}{4\pi}\left(\frac{1}{2}\operatorname{Log}\left[\frac{a0^{2}\omega}{1-\omega}\right]\right)^{-0.5}, \{\omega, 0, 1.1\}, \operatorname{Frame} \to \operatorname{True},$$

FrameLabel $\rightarrow \{ "\omega", "d^2I/d\omega d\Omega \text{ on axis"} \}$, PlotLabel $\rightarrow "Exp[-2x^2]"$

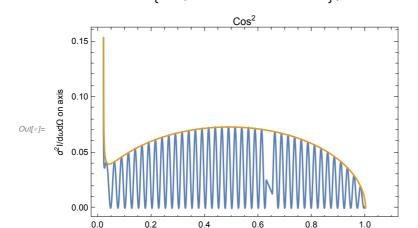


\cos^2

 $log_{i=1}$ Clear[f, ϕ , a, τ , ω , d2I, χ , y, ff, fm1 ξ , dfmi, a0] $f = Cos[\pi x]^2;$ $fm1 = (Solve[f = ff, x][4, 1, 2] /. \{c_1 \rightarrow 0\}) // Normal // Simplify;$ $fm1\xi = fm1 /. \{ff \rightarrow \xi\};$ dfmi = D[fm1, ff]; $y = \frac{1 - \omega}{30.52 \, \omega};$ $\chi = \text{Refine}[\omega \tau \text{ a0^2 Integrate}[\text{fm1}\xi, \{\xi, y, 1\}] - \pi/4//\text{Normal}, \{\omega > 0\}];$ $d2I = \frac{2 \omega \tau}{\pi} Abs[y dfmi /. \{ff \rightarrow y\}] Cos[\chi]^2;$ d2I // Simplify

$$\tau \; \omega \; \mathsf{Abs} \left[\frac{1-\omega}{\mathsf{a0^2} \; \omega \; \sqrt{-\frac{(-1+\omega) \times \left(-1+\omega+\mathsf{a0^2} \; \omega\right)}{\mathsf{a0^4} \; \omega^2}}} \; \right] \; \mathsf{Sin} \left[\frac{\pi^2 + 2 \; \mathsf{a0^2} \; \tau \; \sqrt{-\frac{(-1+\omega) \times \left(-1+\omega+\mathsf{a0^2} \; \omega\right)}{\mathsf{a0^4}}} + 2 \; \tau \; \left(-2 + \left(2 + \mathsf{a0^2}\right) \; \omega\right) \; \mathsf{ArcCos} \left[\frac{\sqrt{\frac{1-\omega}{\mathsf{a0^2}}}}{\sqrt{\omega}} \; \right]}{4 \; \pi} \; \right]^2 \; \mathsf{ArcCos} \left[\frac{\sqrt{\frac{1-\omega}{\mathsf{a0^2}}}}{\sqrt{\omega}} \; \right] \; \mathsf{ArcCos} \left[\frac{\sqrt{\frac{1-\omega}{\mathsf{a0^2}}}}}{\sqrt{\omega}} \; \right] \; \mathsf{ArcCos} \left[\frac{\sqrt{\frac{1-\omega}{\mathsf{a0^2}}}}{\sqrt{\omega}} \; \right] \; \mathsf{ArcCos} \left[\frac{\sqrt{\frac{1-\omega}{\mathsf{a0^2}}}}{\sqrt{\omega}} \; \right] \; \mathsf{ArcCos} \left[\frac{\sqrt{\frac{1-\omega}{\mathsf{a0^2}}}}{\sqrt{\omega}} \; \right] \; \mathsf{ArcCos} \left[\frac{\sqrt{\frac{1-\omega}{\mathsf{a0^2}}}}}{\sqrt{\omega}} \; \right] \; \mathsf{ArcCos} \left[\frac{\sqrt{\frac{1-\omega}{\mathsf{a0^2}}}}{\sqrt{\omega}} \; \right] \; \mathsf{ArcCos} \left[\frac{\sqrt{\frac{1-\omega}{\mathsf{a0^2}}}}}{\sqrt{\omega}} \; \right] \; \mathsf{ArcCos} \left[$$

$$\begin{split} & \ln[*] := \ \tau = 10\,; \\ & a0 = 7\,; \\ & \text{Plot} \bigg[\bigg\{ \frac{1}{\pi^2} \ \tau \ \omega \ \text{Abs} \bigg[\frac{1 - \omega}{a0^2 \ \omega \ \sqrt{-\frac{(-1 + \omega) \times \left(-1 + \omega + a0^2 \ \omega\right)}{a0^4 \ \omega^2}}} \, \bigg] \\ & \qquad \qquad \qquad \\ & \text{Sin} \bigg[\frac{\pi^2 + 2 \ a0^2 \ \tau \ \sqrt{-\frac{(-1 + \omega) \times \left(-1 + \omega + a0^2 \ \omega\right)}{a0^4}} \ + 2 \ \tau \ \left(-2 + \left(2 + a0^2\right) \ \omega\right) \ \text{ArcCos} \bigg[\frac{\sqrt{\frac{1 - \omega}{a0^2}}}{\sqrt{\omega}} \, \bigg]}{4 \ \pi} \bigg]^2 \,, \\ & \qquad \qquad \frac{\omega \ \tau}{\pi^{\wedge} 2} \ \bigg(\frac{a0 \ ^{\wedge} 2 \ \omega}{1 - \omega} - 1 \bigg)^{\wedge} - 0.5 \bigg\} \,, \ \{\omega, \ 0, \ 1.1 \} \,, \ \text{Frame} \rightarrow \text{True} \,, \\ & \qquad \qquad \qquad \text{FrameLabel} \ \rightarrow \ \{\text{"ω", "d}^2 \text{I} / \text{d} \omega \text{d} \Omega \ \text{on axis"} \} \,, \ \text{PlotLabel} \ \rightarrow \text{"Cos}^2 \text{"}} \bigg] \end{split}$$



cos⁴

$$In[s] = \text{Clear}[f, \phi, a, \tau, \omega, \text{d2I}, \chi, y, \text{ff}, \text{fm1}\xi, \text{dfmi}, a0]$$

$$f = \text{Cos}[\pi x]^{4};$$

$$fm1 = (\text{Solve}[f = \text{ff}, x][8, 1, 2]] /. \{c_{1} \rightarrow 0\}) // \text{Normal} // \text{Simplify};$$

$$fm1\xi = \text{fm1} /. \{\text{ff} \rightarrow \xi\};$$

$$dfmi = \text{D}[fm1, \text{ff}];$$

$$y = \frac{1 - \omega}{a0^{2} \omega};$$

$$\chi = \text{Refine}[\omega \tau \text{a0}^{2} \text{Integrate}[\text{fm1}\xi, \{\xi, y, 1\}] - \pi / 4 // \text{Normal}, \{\omega > 0\}];$$

$$d2I = \frac{2 \omega \tau}{\pi} \text{Abs}[y \text{dfmi} /. \{\text{ff} \rightarrow y\}] \text{Cos}[\chi]^{2};$$

$$d2I // \text{Simplify}$$

$$\tau \omega \text{Abs}\left[\frac{\left(\frac{1 - \omega}{a\theta^{2} \omega}\right)^{1/4}}{\sqrt{1 - \sqrt{\frac{1 - \omega}{a\theta^{2} \omega}}}}\right] \text{Sin}\left[\frac{\pi}{4} + \frac{\pi \sqrt{\frac{1 - \omega}{a\theta^{2}}} \left(2 \sqrt{\frac{1 - \omega}{a\theta^{2}}} + 3 \sqrt{\omega}\right) \left(\frac{1 - \omega}{a\theta^{2}}\right)^{1/4} \omega^{1/4} + (-8 + (8 + 3 a\theta^{2}) \omega) \text{ArcCos}\left[\frac{\left(\frac{1 - \omega}{a\theta^{2}}\right)^{1/4}}{\omega^{1/4}}\right]}{8 \pi}\right]$$

$$\begin{aligned} &\text{In}(\cdot) &= \tau = 10\,; \\ &\text{a0} = 5\,; \end{aligned} \\ &\text{Plot}\Big[\Big\{\frac{1}{2\,\pi^2}\,\tau\,\omega\,\mathsf{Abs}\Big[\frac{\left(\frac{1-\omega}{\mathsf{a0}^2\,\omega}\right)^{1/4}}{\sqrt{1-\sqrt{\frac{1-\omega}{\mathsf{a0}^2}}}}\Big] \\ &\quad \qquad \qquad \\ &\text{Sin}\Big[\frac{\pi}{4} + \frac{1}{8\,\pi}\,\tau\,\Bigg[\mathsf{a0}^2\,\sqrt{1-\frac{\sqrt{\frac{1-\omega}{\mathsf{a0}^2}}}{\sqrt{\omega}}}\,\,\Bigg(2\,\,\sqrt{\frac{1-\omega}{\mathsf{a0}^2}} + 3\,\,\sqrt{\omega}\,\Bigg)\,\,\Big(\frac{1-\omega}{\mathsf{a0}^2}\Big)^{1/4}\,\omega^{1/4} + \\ &\quad \qquad \qquad \qquad \\ &\quad \qquad \qquad \Big(-8 + \left(8 + 3\,\mathsf{a0}^2\right)\,\omega\Big)\,\,\mathsf{ArcCos}\Big[\frac{\left(\frac{1-\omega}{\mathsf{a0}^2}\right)^{1/4}}{\omega^{1/4}}\Big]\Bigg]^2\,, \\ &\quad \qquad \frac{\omega\,\tau}{2\,\pi^{\,^{\prime}}\,2}\,\,\Big\{\mathsf{Sqrt}\Big[\frac{\mathsf{a0}^{\,^{\prime}}\,2\,\omega}{1-\omega}\Big] - 1\Big)^{\,^{\prime}} - 0.5\Big\}\,,\,\,\{\omega\,,\,0\,,\,1.1\}\,,\,\,\mathsf{Frame} \to \mathsf{True}\,, \\ &\quad \qquad \qquad \qquad \\ &\quad \qquad \mathsf{FrameLabel}\,\to\,\big\{"\omega"\,,\,"d^2\,\mathrm{I}/\mathrm{d}\omega\mathrm{d}\Omega\,\,\,\mathrm{on}\,\,\,\mathrm{axis}"\big\}\,, \\ &\quad \qquad \mathsf{PlotLabel}\,\to\,"\mathsf{Cos}^4"\Big] \end{aligned}$$

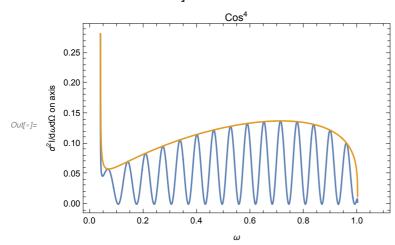


Figure 4

Fig.4 left

2

٥L 0.0

0.2

0.4

$$In[\cdot]:= \text{Clear}[\omega, \tau, a0]$$

$$a0 = 5;$$

$$\tau = 100;$$

$$\text{Plot}\Big[\Big\{2\frac{\omega \tau}{4\pi}\left(\frac{1}{2} \text{Log}\Big[\frac{a0^{\wedge}2\omega}{1-\omega}\Big]\right)^{\wedge} - 0.5, \frac{\omega \tau}{\pi^{\wedge}2}\left(\frac{a0^{\wedge}2\omega}{1-\omega} - 1\right)^{\wedge} - 0.5,$$

$$\frac{\omega \tau}{2\pi^{\wedge}2}\left\{\text{Sqrt}\Big[\frac{a0^{\wedge}2\omega}{1-\omega}\Big] - 1\right)^{\wedge} - 0.5\Big\}, \{\omega, 0, 1.1\}, \text{ Frame} \rightarrow \text{True},$$

$$\text{FrameLabel} \rightarrow \{\text{"ω", "d}^2\text{I}/\text{d}\omega\text{d}\Omega \text{ on axis"}\}, \text{PlotLabel} \rightarrow \text{"$a0=5, \tau=100$",}$$

$$\text{PlotRange} \rightarrow \{0, 12\}, \text{PlotLegends} \rightarrow \{\text{"Exp}[-2x^2]\text{", "Cos}^2\text{", "Cos}^4\text{"}}\Big\}\Big]$$

$$a0=5, \tau=100$$

$$a0=5, \tau=100$$

$$a0=5, \tau=100$$

$$a0=5, \tau=100$$

$$a0=5, \tau=100$$

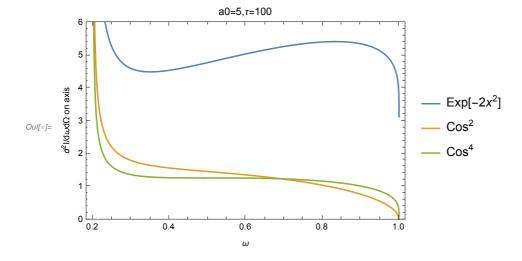
0.6

Fig.4 right (a0=2 seems to match the figure, though one would have to normalize it with int |A|^2 fixed)

0.8

In[a]:= Clear[
$$\omega$$
, τ , a0]
a0 = 2;
 τ = 50;
Plot[$\left\{2\frac{\omega \tau}{4\pi} \left(\frac{1}{2} Log\left[\frac{a0^2 \omega}{1-\omega}\right]\right)^{-0.5}, \frac{\omega \tau}{\pi^2} \left(\frac{a0^2 \omega}{1-\omega} - 1\right)^{-0.5}, \frac{\omega \tau}{2\pi^2} \left(Sqrt\left[\frac{a0^2 \omega}{1-\omega}\right] - 1\right)^{-0.5}, \{\omega, 0, 1.1\}, Frame \rightarrow True,$

FrameLabel \rightarrow {" ω ", "d 2 I/d ω d Ω on axis"}, PlotLabel \rightarrow "a0=5, τ =100", $PlotRange \rightarrow \{0, 6\}, PlotLegends \rightarrow \left\{"Exp[-2x^2]", "Cos^2", "Cos^4"\right\}\right]$



Jacobi-Anger expansion (example)

$Exp[-\phi^4/100]$

```
In[\bullet]:= Clear [\phi, a, \omega, A2L, A2R, m, mmax]
        a[\phi_{-}] := Exp[-\phi^{4} / 100]
        \omega = 10;
        A2L[\phi_{-}] := Exp\left[\frac{I \omega}{\Delta} a[\phi]^{2} Sin[2 \phi]\right]
        mmax = 2
        A2R[\phi_, mmax_] := Sum[BesselJ[m, \frac{\omega a[\phi]^2}{4}] Exp[2 I m\phi], {m, -mmax, mmax}]
        Plot[Re[A2L[\phi]], Re[A2R[\phi, 1]], Re[A2R[\phi, 2]], Re[A2R[\phi, 4]]],
          \{\phi, 0, 2\pi\}, PlotStyle \rightarrow {Default, Dashed, Dashed},
          Frame \rightarrow True, FrameLabel \rightarrow {"\phi", ""},
          PlotLegends \rightarrow \left\{ \text{"Exp}\left[\frac{\text{I}\,\omega}{4} \text{ a}[\phi]^2 \text{ Sin}[2\phi]\right] \right\}, \text{"JacobiAnger mmax=1"},
              "JacobiAnger mmax=2", "JacobiAnger mmax=4"\}, PlotLabel \rightarrow "\omega=10, Real part"]
        \mathsf{Plot}\big[\{\mathsf{Im}[\mathsf{A2L}[\phi]]\,,\,\mathsf{Im}[\mathsf{A2R}[\phi,\,1]]\,,\,\mathsf{Im}[\mathsf{A2R}[\phi,\,2]]\,,\,\mathsf{Im}[\mathsf{A2R}[\phi,\,4]]\}\,,
          \{\phi, 0, 2\pi\}, PlotStyle \rightarrow {Default, Dashed, Dashed, Dashed},
          Frame \rightarrow True, FrameLabel \rightarrow {"\phi", ""},
          \mathsf{PlotLegends} \to \Big\{ \mathsf{"Exp} \big[ \frac{\mathsf{I} \; \omega}{\mathsf{A}} \; \; \mathsf{a} \left[ \phi \right]^2 \; \mathsf{Sin} [2\phi] \big] \mathsf{", "JacobiAnger \; mmax=1",} \\
              "JacobiAnger mmax=2", "JacobiAnger mmax=4"\}, PlotLabel \rightarrow "\omega=10, Imag part"]
                                               \omega=10, Real part
             1.0
             0.5
                                                                                                           - Exp\left[\frac{l\omega}{4} \text{ a} \left[\phi\right]^2 \text{ Sin} \left[2\phi\right]\right]

    JacobiAnger mmax=1

             0.0
Out[ • ]=

    JacobiAnger mmax=2

                                                                                                     ---- JacobiAnger mmax=4
            -0.5
            -1.0
                                                     3
```

