

## See chapter 4 in Regression and Other Stories.

Widen the notebook.

```
•  
• html"""  
• <style>  
•     main {  
•         margin: 0 auto;  
•         max-width: 2000px;  
•         padding-left: max(160px, 10%);  
•         padding-right: max(160px, 10%);  
•     }  
• </style>  
• """
```

```
• using Pkg ✓ , DrWatson ✓
```

A typical set of Julia packages to include in notebooks.

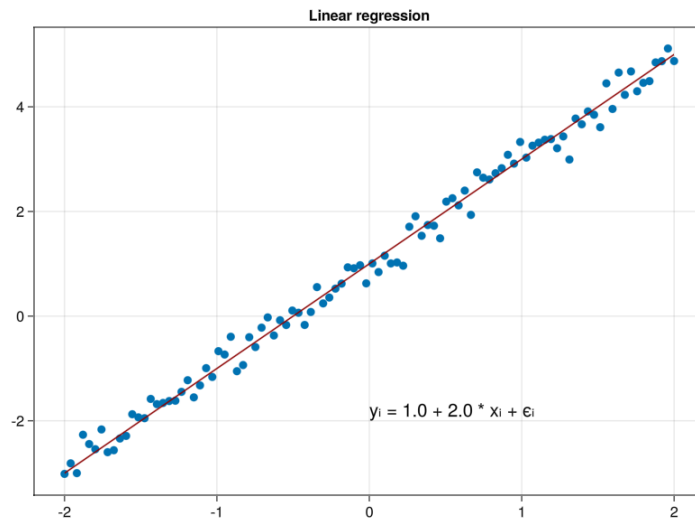
```
• begin  
•     # Specific to this notebook  
•     using GLM ✓  
•  
•     # Specific to ROSStanPluto  
•     using StanSample ✓  
•  
•     # Graphics related  
•     using GLMakie ✓  
•  
•     # Common data files and functions  
•     using RegressionAndOtherStories ✓  
• end
```

### 4.1 Sampling distributions and generative models.

```

• begin
•   Random.seed!(1)
•   a = 1.0
•   b = 2.0
•   x = LinRange(-2, 2, 100)
•   y = a .+ b .* x .+ rand(Normal(0.0,
•   0.2), 100)
• end;

```



```

• let
•   f = Figure()
•   ax = Axis(f[1, 1]; title="Linear
•   regression")
•   scatter!(x, y)
•   lines!(x, a .+ b .* x; color=:darkred)
•   annotations!("yi = 1.0 + 2.0 * xi +
•   εi", position=(0, -2), fontsize=20)
•   current_figure()
• end

```

```

• stan4_1 = "
• data {
•   int N;
•   vector[N] x;
•   vector[N] y;
• }
• parameters {
•   real a;
•   real b;
•   real<lower=0> sigma;
• }
• model {
•   vector[N] mu;
•   a ~ normal(0.0, 1.5);
•   b ~ normal(1.0, 1.5);
•   sigma ~ exponential(1);
•   mu = a + b * x;
•   y ~ normal(mu, sigma);
• }";

```

	parameters	mean	mcse	std
1	"a"	1.00158	0.000360556	0.022590
2	"b"	1.97538	0.000287766	0.018553
3	"sigma"	0.218108	0.000260604	0.015493

```

• let
•   data = (N = length(x), x = x, y = y)
•   global m4_1s = SampleModel("m4.1s",
•   stan4_1)
•   global rc4_1s = stan_sample(m4_1s; data)
•   success(rc4_1s) && describe(m4_1s)
• end

```

```

/var/folders/l7/pr04h0650q5dvqtnvs8s2c00000gn/T/
d.

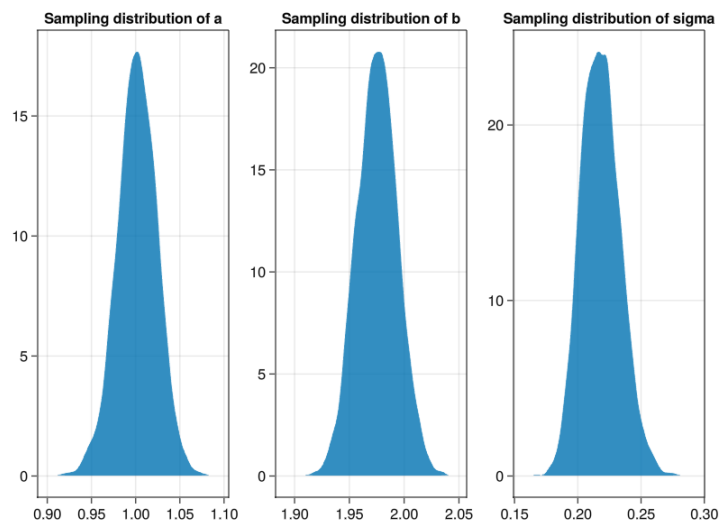
```

	parameters	median	mad_sd	mean	std
1	"a"	1.002	0.022	1.002	0.022
2	"b"	1.975	0.019	1.975	0.019
3	"sigma"	0.217	0.016	0.218	0.016

```

• if success(rc4_1s)
•   post4_1s = read_samples(m4_1s,
•     :dataframe)
•   ms4_1s = model_summary(post4_1s, [:a,
•     :b, :sigma])
end

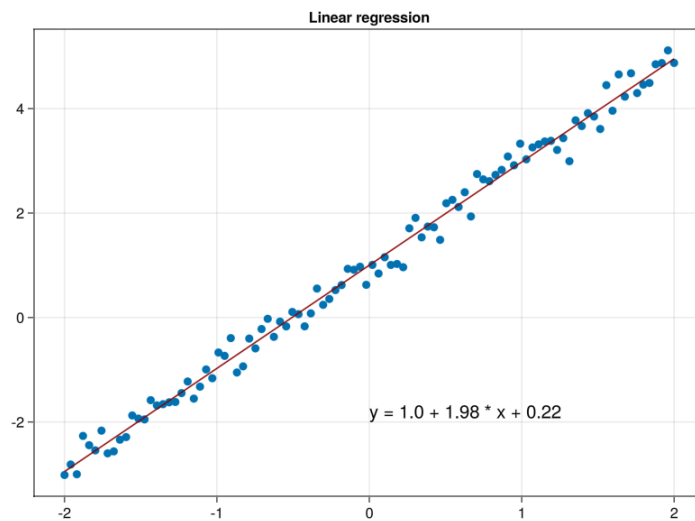
```



```

• let
•   f = Figure()
•   ax = Axis(f[1, 1]; title="Sampling
•     distribution of a")
•   density!(post4_1s.a)
•   ax = Axis(f[1, 2]; title="Sampling
•     distribution of b")
•   density!(post4_1s.b)
•   ax = Axis(f[1, 3]; title="Sampling
•     distribution of sigma")
•   density!(post4_1s.sigma)
•   current_figure()
end

```

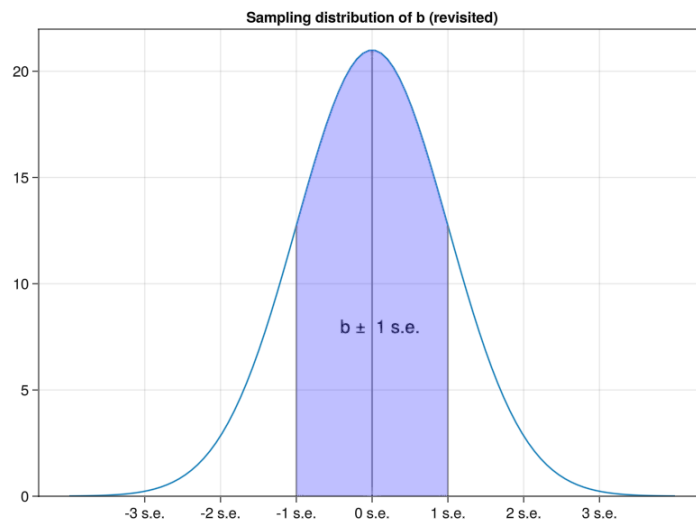


```

• let
•   f = Figure()
•   ax = Axis(f[1, 1]; title="Linear
•   regression")
•   scatter!(x, y)
•   lines!(x, ms4_1s[:a, :mean] .+
•   ms4_1s[:b, :mean] .* x; color=:darkred)
•   mean_a = round(ms4_1s[:a, :mean];
•   digits=2)
•   mean_b = round(ms4_1s[:b, :mean];
•   digits=2)
•   mean_σ = round(ms4_1s[:sigma, :mean];
•   digits=2)
•   annotations!("y = $(mean_a) + $(mean_b)
•   * x + $(mean_σ)", position=(0, -2),
•   fontsize=20)
•   current_figure()
end

```

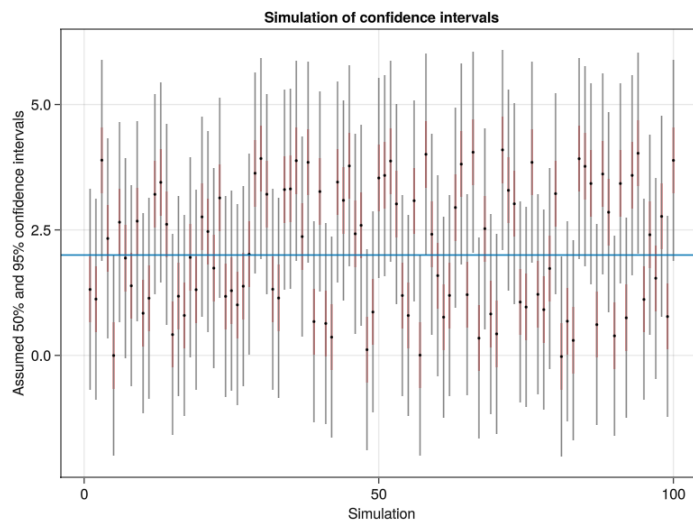
## 4.2 Estimates, standard errors, and confidence intervals.



```

• let
•   f = Figure()
•   ax = Axis(f[1, 1]; title="Sampling
•   distribution of b (revisited)")
•   b̂ = ms4_1s[:b, :mean]
•   σ̂ = ms4_1s[:b, :std]
•   x = LinRange(b̂ - 4σ̂, b̂ + 4σ̂, 100)
•   y = pdf.(Normal(b̂, σ̂), x)
•   ylims!(ax, [0, maximum(y) + 1.0])
•   ax.xticks = b̂ - 3σ̂ : σ̂ : b̂ + 3σ̂
•   ax.xtickformat = xs -> ["$(i) s.e." for
•   i in -3:3]
•   lines!(x, y)
•   vlines!(ax, b̂;
•   ymax=maximum(y)/(maximum(y) + 1.0),
•   color=:grey)
•   vlines!(ax, b̂-σ̂; ymax=pdf.(Normal(b̂,
•   σ̂), b̂-σ̂)/(maximum(y) + 1.0),
•   color=:grey)
•   vlines!(ax, b̂+σ̂; ymax=pdf.(Normal(b̂,
•   σ̂), b̂+σ̂)/(maximum(y) + 1.0),
•   color=:grey)
•   annotations!("b ± 1 s.e.", position=
•   (b̂-0.008, 7.5), textsize=20)
•   x1 = range(b̂ - σ̂, b̂ + σ̂; length=60)
•   band!(x1, fill(0, length(x1)), pdf.
•   (Normal(b̂, σ̂), x1); color = (:blue,
•   0.25))
•   f
• end

```



```

let
  n = 100
  b = 2.0

  f = Figure()
  ax = Axis(f[1,1]; title="Simulation of
confidence intervals",
xlabel="Simulation",
ylabel="Assumed 50% and 95%
confidence intervals")

  x = 1:n
  y = [rand(Uniform(b - 2.1 , b + 2.1), 1)
[1] for i in 1:n]

  # Assumed s.e. = 1.0
  lowerrors = fill(0.66, n)
  higherrors = fill(2, n)

  errorbars!(x, y, lowerrors, color =
:red) # same low and high error
  errorbars!(x, y, higherrors, color =
:grey) # same low and high error

  scatter!(x, y, markersize = 3, color =
:black)
  hlines!(ax, [2])

f
end

```

```
► (estimate = 0.7, se = 0.0144914, int_95 = [0.67
```

```
• let
•   n = 1000
•   yes = 700
•   no = n - yes
•   est = yes/n
•   se = sqrt(est * (1 - est)/n)
•
•   (estimate = est, se = se, int_95 = est
•     .+ quantile.(Normal(0, 1), [0.025,
•       0.975]) * se)
• end
```

```
► (estimate = 35.8, se = 0.734847, int_50 = [35.2
```

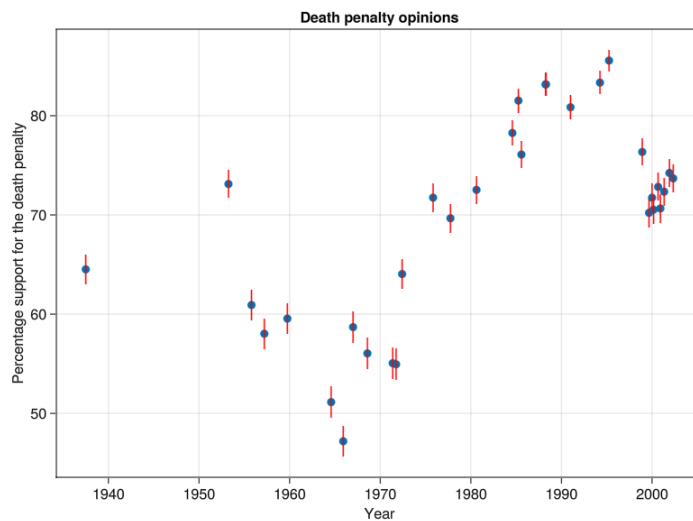
```
• let
•   y = [35, 34, 38, 35, 37]
•   n = length(y)
•   est = mean(y)
•   se = std(y)/sqrt(n)
•   int_50 = est .+ quantile.(TDist(n-1),
•     [0.25, 0.75]) * se
•   int_95 = est .+ quantile.(TDist(n-1),
•     [0.025, 0.975]) * se
•
•   (estimate = est, se = se, int_50 =
•     int_50, int_95 = int_95)
• end
```



```
df_poll =
```

	poll1	poll2	poll3	poll4	poll5
<b>1</b>	2002	10.0	70.0	25.0	5.0
<b>2</b>	2002	5.0	72.0	25.0	3.0
<b>3</b>	2001	10.0	68.0	26.0	6.0
<b>4</b>	2001	5.0	65.0	27.0	8.0
<b>5</b>	2001	2.0	67.0	25.0	8.0
<b>6</b>	2000	8.0	67.0	28.0	5.0
<b>7</b>	2000	6.0	66.0	26.0	8.0
<b>8</b>	2000	2.0	66.0	28.0	6.0
<b>9</b>	1999	5.0	71.0	22.0	7.0
<b>10</b>	1995	9.0	77.0	13.0	10.0
⋮ more					
<b>32</b>	1937	12.0	60.0	33.0	7.0

```
• df_poll = CSV.read(ros_datadir("Death",  
  "polls.csv"), DataFrame)
```



```

• begin
•     f = Figure()
•     ax = Axis(f[1, 1]; title="Death penalty
•         opinions", xlabel="Year",
•         ylabel="Percentage support for the
•         death penalty")
•     scatter!(df_poll.year, df_poll.support
•         .* 100)
•     err_lims = [100(sqrt(df_poll.support[i]*
•         (1-df_poll.support[i])/1000)) for i in
•         1:nrow(df_poll)]
•     errorbars!(df_poll.year, df_poll.support
•         .* 100, err_lims, color = :red)
•     f
• end

```

### 4.3 Bias and unmodeled uncertainty.

### 4.4 Statistical significance, hypothesis testing, and statistical errors.

### 4.5 Problems with the concept of statistical significance.

**4.6 Example of hypothesis testing: 55,000 residents need your help!**

**4.7 Moving beyond hypothesis testing.**