

## The Determinant

**Textbook:** Sections 3.1, 3.2 & 3.3

**Observation (3.1.6)**

When is a  $2 \times 2$  matrix  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  invertible?

**Definition**

We define the determinant function  $\text{Mat}_2(\mathbb{R}) \xrightarrow{\det} \mathbb{R}$  to be  $\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc$

**Remark**

1. As we observed above, a  $2 \times 2$  matrix is invertible if and only if  $\det(A) \neq 0$ .
2. It is helpful to think about  $A = [\vec{x} \ \vec{y}]$  to consist of column vectors  $\vec{x}, \vec{y} \in \mathbb{R}^2$ .

**Proposition (3.1.1)**

The area of the parallelogram spanned by vectors  $\vec{x}$  and  $\vec{y}$  in  $\mathbb{R}^2$  is equal to the determinant of the matrix  $A = [\vec{x} \ \vec{y}]$ .

From this it is clear that the area is nonzero if and only if the vectors spanning the parallelogram are linearly independent, that is, not parallel.

**Observation**

Let  $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$  be a  $2 \times 2$  matrix and denote its columns as  $\vec{x} = \begin{pmatrix} a \\ c \end{pmatrix}$  and  $\vec{y} = \begin{pmatrix} b \\ d \end{pmatrix}$ .

We can think of  $A$  as the matrix of a linear transformation

$$\mathbb{R}^2 \rightarrow \mathbb{R}^2$$

sending

$$\begin{pmatrix} 1 \\ 0 \end{pmatrix} \mapsto \begin{pmatrix} a \\ c \end{pmatrix}$$
$$\begin{pmatrix} 0 \\ 1 \end{pmatrix} \mapsto \begin{pmatrix} b \\ d \end{pmatrix}$$

**Discussion**

Compute the determinant, draw the parallelogram and decide if the corresponding transformation is invertible for the following matrices.

1.

$$A = \begin{pmatrix} 1 & 2 \\ 3 & -4 \end{pmatrix}$$

2.

$$A = \begin{pmatrix} 4 & 2 \\ -2 & -1 \end{pmatrix}$$

**Remark**

1. Let again  $A = [\vec{x} \ \vec{y}]$  be a  $2 \times 2$  matrix with columns  $\vec{x}$  and  $\vec{y}$ . The determinant function as a function of the columns  $\det(\vec{x}, \vec{y})$  has the following properties
  - (a) linear in both arguments
  - (b) alternating
  - (c) normalized
2. The book calls this the area function  $Area(\vec{x}, \vec{y})$  of the vectors spanning the parallelogram.

**Proposition (3.1.4)**

The determinant function is the unique function satisfying all properties above.

*Proof.* In the book ■

**Discussion**

Can you show that

$$\det([\vec{x} \ \vec{y}]) = 0$$

if  $\{\vec{x}, \vec{y}\}$  is linearly dependent by only using the properties above?

## Determinant of $n \times n$ matrices

**Textbook:** Sections 3.2

### Goal

Generalize the  $\det$  function to all  $n \times n$  matrices as a function of  $n$  vectors  $\vec{x}_1, \dots, \vec{x}_n$  with an equivalent set of properties.

1. multilinear

2. alternating

3. normalized

### Definition (3.2.4)

Let  $A \in \text{Mat}_n(\mathbb{R})$  be a  $n \times n$  matrix. Define the *ij-minor*  $A_{ij}$  to be the  $(n-1) \times (n-1)$  matrix obtained by deleting the  $i$ -th row and  $j$ -th column.

### Discussion

Compute for the matrix  $A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$  the minor  $A_{23}$

**Proposition (3.2.5, 3.2.6)**

There exists a unique multilinear and alternating function  $f$  on the columns of  $3 \times 3$  matrices that is normalized such that  $f(I_n) = 1$ .

**Definition (3.2.7)**

We define the determinant of a  $3 \times 3$  matrix to be this unique function.

$$\det(A) = a_{11}\det(A_{11}) - a_{12}\det(A_{12}) + a_{13}\det(A_{13})$$

**Discussion**

Compute the determinant of the matrix

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 3 & 1 \\ 0 & 3 & 2 \end{pmatrix}$$

**Remarks**

1. The formula through which we defined the determinant function is called the *cofactor expansion*.
2. It is also common to call

$$a_{ij} \det(A_{ij})$$

the *ij-cofactor* of a matrix  $A$ .

3. There is nothing special about the first row, we can expand the  $\det(A)$  along any row or column.

**Example**

$$A = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 3 & 1 \\ 0 & 3 & 2 \end{pmatrix}$$

**Definition** We define for an  $n \times n$  matrix the determinant function

$$\det(A) = \sum_{j=1}^n (-1)^{i+j} a_{ij} \det(A_{ij})$$

as the cofactor expansion along any row  $i$  or likewise along any column.

**Theorem 3.2.8**

1. There is exactly one alternating multilinear function  $\text{Mat}_n(\mathbb{R}) \xrightarrow{f} \mathbb{R}$  such that  $f(I_n) = 1$ , which is the determinant function defined above.
2. Any other alternating multilinear function  $f$  on square  $n \times n$  matrices satisfies

$$f(A) = \det(A) \cdot f(I_n)$$

**Discussion**

Write the first line of the cofactor expansion of the determinant for the matrix

$$A = \begin{pmatrix} 1 & -3 & 1 & 4 \\ 8 & -4 & 2 & -2 \\ 3 & -7 & 5 & 3 \\ 0 & 3 & -2 & 4 \end{pmatrix}$$

**Exercise:** Read Example 3.2.9 in the book and practice computing determinants.

**Theorem (3.2.14)**

An  $n \times n$  matrix  $A$  is invertible if and only if  $\det(A) \neq 0$ .

*Proof.* In the book

■

**Remark**

Notice that this agrees perfectly with the discussion above in the  $2 \times 2$  case.



## Further properties of determinants

**Textbook:** Sections 3.3

### Proposition (3.3.7)

If  $A$  and  $B$  are  $n \times n$  matrices, then

1.  $\det(AB) = \det(A)\det(B)$
2. If  $A$  is invertible, then  $\det(A^{-1}) = \frac{1}{\det(A)}$

*Proof.* ■

This is very useful for transformations, because their matrix representative depends on a choice of basis

### Corollary (3.3.8)

For a linear transformation  $V \xrightarrow{T} V$  on a vector space of finite dimensional vector space  $V$

$$\det([T]_{\alpha}^{\alpha}) = \det([T]_{\beta}^{\beta})$$

for any two bases  $\alpha$  and  $\beta$ .

*Proof.* ■

So we can define independently of the chosen basis

**Definition (3.3.9)**

The determinant  $\det(T)$  of a linear transformation  $V \xrightarrow{T} V$  on a vector space of finite dimension is the determinant of  $[T]_{\alpha}^{\alpha}$  for any choice of basis  $\alpha$ .

**Proposition (3.3.11)**

A linear transformation  $V \xrightarrow{T} V$  on a vector space of finite dimension is invertible if and only if  $\det(T) \neq 0$ .

*Proof.* ■

**Proposition (3.3.12)**

For two linear transformations  $V \xrightarrow{S} V$  and  $V \xrightarrow{T} V$  on a vector space of finite dimension, then

1.  $\det(ST) = \det(S) \cdot \det(T)$
2. if  $T$  is an isomorphism, then  $\det(T^{-1}) = \frac{1}{\det(T)}$

*Proof.* ■

## Eigenvalues Pt I

**Textbook:** Section 4.1