

Real-time Domain Adaptation in Semantic Segmentation*

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1st Berardo Nicholas
dept. Computer Engineering
Politecnico di Torino
Turin, Italy
s319349@studenti.polito.it

2nd Cardona Riccardo
dept. Computer Engineering
Politecnico di Torino
Turin, Italy
s319441@studenti.polito.it

3rd De Marco Alessandro
dept. Computer Engineering
Politecnico di Torino
Turin, Italy
sXXXXXXX@studenti.polito.it

Abstract—We use an efficient structure named Short-Term Dense Concatenate network (STDC network) for the semantic segmentation task. This structure reduce the dimension of feature maps and use the aggregation of them for image representation, then use a Detail aggregation module for producing the low-level features. Finally these two are merged to produce the segmentation result. We test this model on Cityscapes and GTA V, following the evaluation of the domain shift between GTA V and Cityscapes and finally we implement an unsupervised adversarial domain adaptation method used for reducing the domain shift. We also show the result for the STDC network in term of mIoU and the result for the domain adaptation.

I. INTRODUCTION

Semantic Segmentation is a topic in computer vision that aims at assigning a label to each pixel of the image. This is used in many fields such as autonomous vehicle, video surveillance and robot sensing. There are a lot of models that can achieve good accuracy. For real-time semantic segmentation some models choose lightweight backbones for having an increase of performance but a drastic drop of accuracy. For this reason some new methods were investigated, like feature fusion or aggregation modules. Other models reduce the input image size but this can result in a bad accuracy around boundaries and small object.

STDC net [1] uses the first approach. Fig. 1 shows how the image is encoded in different scales. The kernel size is also reduced to speed-up the performance but with an acceptable loss in accuracy. Then a Detail Guidance is used to learn the space details instead of using a Spatial Path as in BiSeNet [2].

The next step is domain adaptation. A model trained on a certain dataset may not generalize on an unseen dataset ending in poor performance. This is caused by the domain shift between the source (training) and target (test) dataset, for example different cities, weather and lighting conditions. Domain adaptation methods are used to close the gap between source and target domains. In this paper we use an adversarial domain adaptation method [3] that is composed of a segmentation model to predict the output and a discriminator to predict if the input is from the source or target domain. The goal is to generate a segmentation output from the segmentation

part that fool the discriminator, meaning that the segmentation output is similar between source and target domains. We show experiments done on the adaptation between GTAV and Cityscapes.

Our contributions can be summarized as follows: First we build the STDC network and train it on Cityscapes and test it again on Cityscapes. Second we apply the same idea over the GTAV dataset, so train on GTAV and test on GTAV. Third we compute the domain shift between GTAV (source) and Cityscapes (target) domains firstly in vanilla, then with some augmentation on GTAV. Fourth we implement the adversarial domain adaptation method and test it with GTAV as source domain and Cityscapes as target domain. Lastly we apply some real-time semantic segmentation method to our discriminator function in order to make it faster.

II. RELATED WORK

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III. METHODS

We first introduce the Short-Term Dense Concatenate network (STDC network) and how we used it with BiSeNet [2], then the unsupervised adversarial domain adaptation method.

STDC network [1] is represented in Fig. 1 (a). Stage 3,4 and 5 have a number of Short-Term Dense Concatenate Module (STDCM) where each module is composed of ConvX blocks Fig. 1 (b)(c). Each $ConvX_i$ is a block composed of one convolutional layer, one batch normalization layer and one ReLU activation layer. The ConvX layers filter the input into $N/2$, where N is the channel number of the STDC module. At the end we concatenate the output of each ConvX block as follow:

$$x_{output} = F(x_1, x_2, \dots, x_n)$$

where x_{output} is the STDC module output, F is the fusion operation, that in our case is the concatenation and x_1, x_2, \dots, x_n are the output of each $ConvX_i$ block.

This STDC network is then used as backbone for the context path of BiSeNet, in particular we use stage 3,4 and 5 to reduce the feature map to obtain large receptive field. Then a global

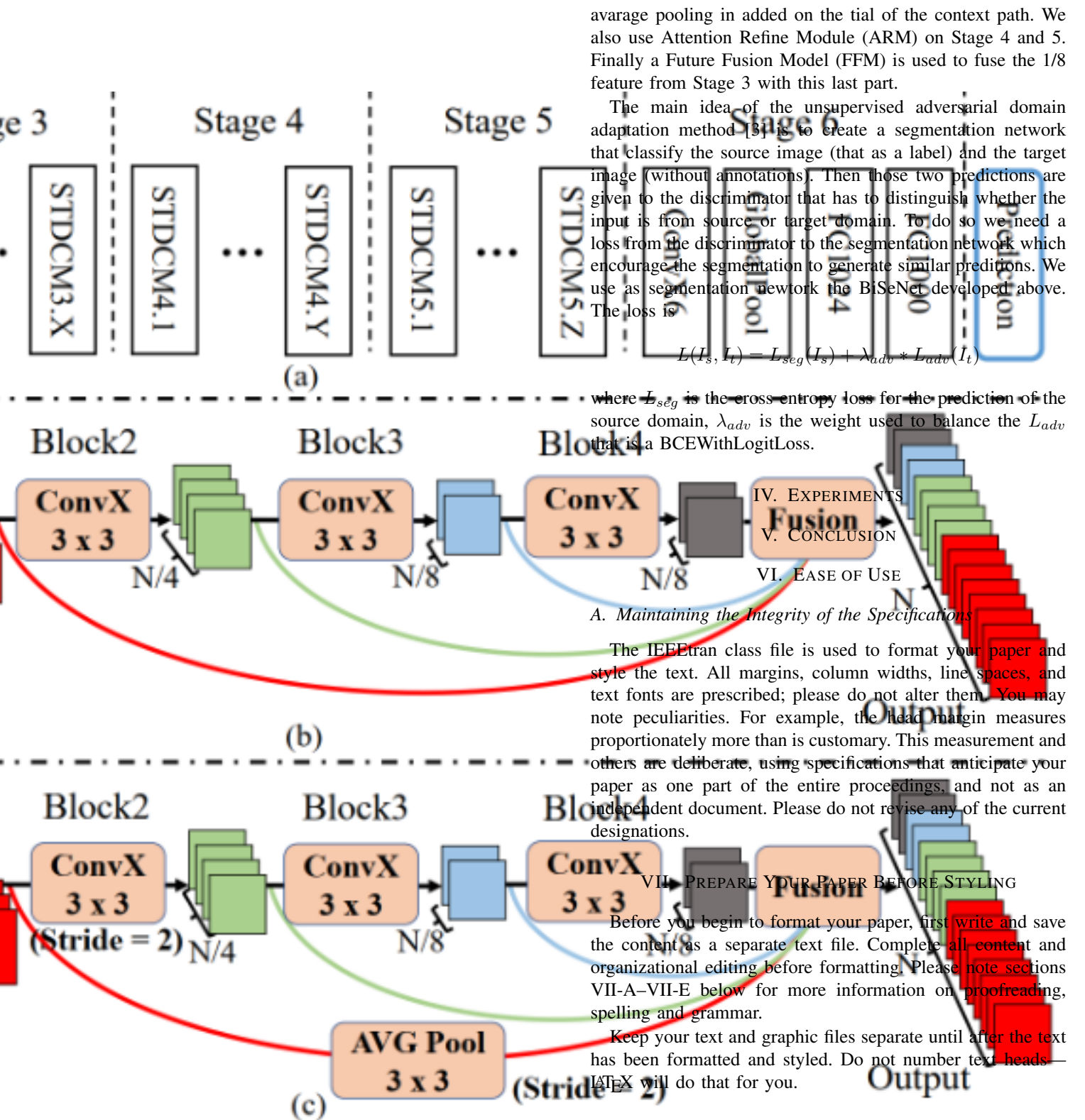


Fig. 1. STDC network.

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$$a + b = \gamma \quad (1)$$

Be sure that the symbols in your equation have been defined before or immediately following the equation. Use “(1)”, not “Eq. (1)” or “equation (1)”, except at the beginning of a sentence: “Equation (1) is . . .”

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- In your paper title, if the words “that uses” can accurately replace the word “using”, capitalize the “u”; if not, keep using lower-cased.
- Be aware of the different meanings of the homophones “affect” and “effect”, “complement” and “compliment”, “discreet” and “discrete”, “principal” and “principle”.
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TABLE I
TABLE TYPE STYLES

Table Head	Table Column Head		
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^aSample of a Table footnote.



Fig. 2. Example of a figure caption.

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ACKNOWLEDGMENT

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REFERENCES

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