# **MOTOROLA** SEMICONDUCTOR TECHNICAL DATA

# Fast 16K Bit Static RAM

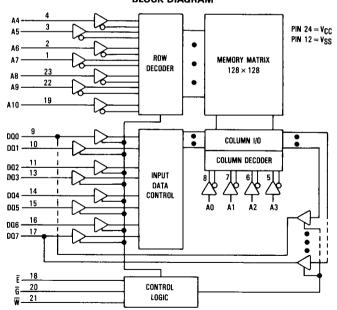
The MCM2018A is a 16,384 bit static random access memory organized as 2048 words by 8 bits, fabricated using Motorola's high-performance silicon-gate MOS (HMOS) technology. It uses an innovative design approach which combines the ease-of-use features of fully static operation (no external clocks or timing strobes required) with the reduced standby power dissipation associated with clocked memories. To the user this means low standby power dissipation without the need for address setup and hold times, nor reduced data rates due to cycle times that are longer than access times. Perfect for cache and sub-100 ns buffer memory systems, this high speed static RAM is intended for applications that demand superior performance and reliability.

Chip enable (E) controls the power-down feature. It is not a clock but rather a chip control that affects power consumption. In less than a cycle time after E goes high, the part automatically reduces its power requirements and remains in this low-power standby mode as long as E remains high. This feature provides significant system-level power savings.

The MCM2018A is in a 24-pin dual-in-line 300 mil wide package with the industry standard JEDEC approved pinout.

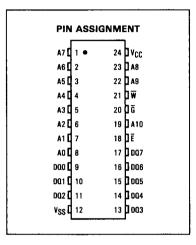
- Single +5 V Operation, ±10%
- Fully Static: No Clock Fast Access Time N
- BIN WADESIGNS
- Power Supply Current 20 mA Maximum (Standby)
- Three-State Output

# **BLOCK DIAGRAM**



# MCM2018A





PIN NAMES									
A0-A10									
DQ0-DQ7 Data Input/Output									
$\overline{\mathbf{W}}$ Write Enable									
G Output Enable									
Ē									
V <sub>CC</sub> +5 V Power Supply									
VSS Ground									

MOTOROLA DRAM DATA MCM2018A

## MODE SELECTION

Mode	Ē	G	w	V <sub>CC</sub> Current	Dα
Standby	н	х	х	ISB	High Z
Read	L	L	Н	Icc	Q
Write Cycle	L	х	L	lcc lcc	D

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high-impedance circuit.

## **ABSOLUTE MAXIMUM RATINGS (See Note)**

Rating	Symbol	Value	Unit
Power Supply Voltage	Vcc	-0.5 to +7.0	٧
Voltage on Any Pin With Respect to VSS	V <sub>in</sub> , V <sub>out</sub>	-0.5 to +7.0	٧
DC Output Current	lout	± 20	mA
Power Dissipation	PD	1.1	Watt
Temperature Under Bias	T <sub>bias</sub>	-10 to +80	°C
Operating Temperature Range	TA	0 to +70	°C
Storage Temperature Range	T <sub>stg</sub>	-65 to +150	°C

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPERATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.

## DC OPERATING CONDITIONS AND CHARACTERISTICS

(V<sub>CC</sub> = 5.0 V  $\pm$  10%, T<sub>A</sub> = 0 to 70°C, Unless Otherwise Noted)

#### RECOMMENDED OPERATING CONDITIONS

Parameter	Symbol	Min	Тур	Max	Unit
Supply Voltage (Operating Voltage Range)	Vcc	4.5	5.0	5.5	V
	V <sub>SS</sub>	0	0	0	V
Input Voltage	ViH	2.0	3.0	6.0	V
	VIL	-0.5*	0	0.8	V

<sup>\*</sup>The device will withstand undershoots to the -2.5 volt level with a maximum pulse width of 50 ns. This is periodically sampled rather than 100% tested.

## **DC CHARACTERISTICS**

Parameter	Symbol	Min	Max	Unit
Input Leakage Current (V <sub>CC</sub> = 5.5 V, V <sub>in</sub> = GND to V <sub>CC</sub> )	l <sub>lkg(I)</sub>	- 1.0	1.0	μА
Output Leakage Current ( $\overline{E} = V_{IH}$ or $\overline{G} = V_{IH}$ , $V_{I/O} = GND$ to $V_{CC}$ )	llkg(O)	- 1.0	1.0	μА
Operating Power Supply Current ( $\overline{E} = V_{JL}$ , $I_{J/O} = 0$ mA)	lcc	_	135	mA
Standby Power Supply Current (E=V <sub>IH</sub> )	<sup>1</sup> SB	_	20	mA
Output Low Voltage (I <sub>OL</sub> = 8.0 mA)	V <sub>OL</sub>	_	0.4	V
Output High Voltage (I <sub>OH</sub> = -4.0 mA)	Voн	2.4	_	V

# $\textbf{CAPACITANCE} \hspace{0.1cm} (\text{f} = 1.0 \hspace{0.1cm} \text{MHz}, \hspace{0.1cm} T_{\mbox{\scriptsize A}} = 25^{\circ} \mbox{C}, \hspace{0.1cm} \text{Periodically Sampled Rather Than 100\% Tested)}$

	Symbol	Тур	Max	Unit	
Input Capacitance	All Inputs Except $\overline{E}$ and DQ $\overline{E}$	C <sub>in</sub>	3 5	5 7	pF
I/O Capacitance	DQ	C <sub>I/O</sub>	5	7	pF

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## AC OPERATING CONDITIONS AND CHARACTERISTICS

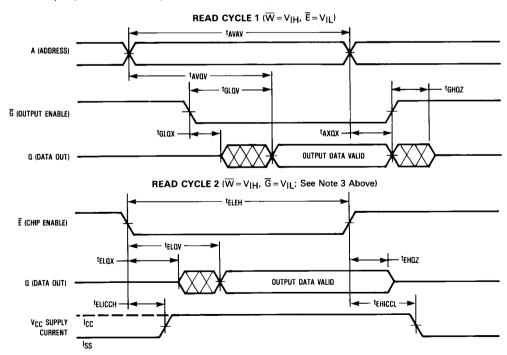
 $(V_{CC} = 5 \text{ V} \pm 10\%, T_A = 0 \text{ to } +70^{\circ}\text{C}, \text{ Unless Otherwise Noted})$ 

#### READ CYCLE (See Note 1)

Dozeni otor	Syn	Symbol		MCM2018A-35		MCM2018A-45		Notes
Parameter	Standard	Alternate	Min	Max	Min	Max	Units	Notes
Address Valid to Address Valid (Read Cycle Time)	†AVAV	tRC	35	-	45	_	ns	
Address Valid to Output Valid (Address Access Time)	tAVQV	tAC	_	35		45	ns	
Chip Enable Low to Chip Enable High (Read Cycle Time)	<sup>†</sup> ELEH	tRC	35	_	45	_	ns	
Chip Enable Low to Output Valid (Chip Enable Access Time)	tELQV	tACS	_	35	_	45	ns	
Output Enable Low to Output Valid (Output Enable Access Time)	tGLQV	<sup>t</sup> OE	_	20	_	20	ns	
Chip Enable Low to Output Invalid (Chip Enable to Output Active)	tELOX	tCLZ	5	_	5	_	ns	2
Chip Enable High to Output High Z (Chip Disable to Output Disable)	<sup>t</sup> EHQZ	tCHZ	0	20	0	20	ns	2
Output Enable Low to Output Invalid (Output Enable to Output Active)	tGLQX	tOLZ	0	-	0	_	ns	2
Output Enable High to Output High Z (Output Disable to Output Disable)	tGHQZ	tonz	0	20	0	20	ns	2
Address Invalid to Output Invalid (Output Hold Time)	tAXQX	tон	5	_	5	_	ns	
Chip Enable Low to Power Up	†ELICCH	tpU	0	-	0	_	ns	
Chip Enable High to Power Down	tEHICCL	tPD	_	20	-	20	ns	

#### NOTES:

- Transition time specification applies for all input signals. In addition to meeting the transition rate specification, all input signals must transition between V<sub>IL</sub> and V<sub>IH</sub> (or between V<sub>IH</sub> and V<sub>IL</sub>) in a monotonic manner.
- 2. Transition is measured  $\pm 200$  mV from the steady state output voltage with the output loading specified in Figure 1.
- 3. In read cycle 2, all addresses are valid prior to or coincident with chip enable (E) transition low.

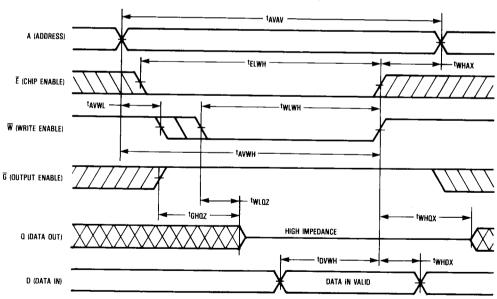


Parameter	Syr	Symbol		MCM2018A-35		MCM2018A-45		
	Standard	Alternate	Min	Max	Min	Max	Units	Notes
Address Valid to Address Valid (Write Cycle Time)	tAVAV	twc	35	_	45	_	ns	
Chip Enable Low to Write High (Chip Enable to End of Write)	tELWH	tEW	30	_	40		ns	
Address Valid to Chip Enable Low (Address Setup to Chip Enable)	tAVEL	tAS	0		0		ns	<del> </del>
Address Valid to Write Low (Address Setup to Write)	tAVWL	tAS	0	_	0	_	ns	
Address Valid to Write High	<sup>t</sup> AVWH	<sup>t</sup> AW	30		40	_	ns	3
Write Low to Write High (Write Pulse Width)	tWLWH	tWP	30	_	35		ns	
Write High to Address Don't Care (Address Hold After End of Write)	twhax	twr	0		0		ns	4
Write High to Output Don't Care (Output Active After End of Write)	twhox	†WLZ	0		0		ns	
Write Low to Output High Z (Write Enable to Output Disable)	†WLQZ	¹WHZ	0	20	_ <del>.</del> _	20	ns	5
Data Valid to Write High (Data Setup to End of Write)	tDVWH	tDS	15		20		ns	3
Write High to Data Don't Care (Data Hold After End of Write)	tWHDX	tDH	0		0			3, 5
Output Enable High to Output High Z	tGHOZ	tOHZ	0	20		20	ns ns	J, 5

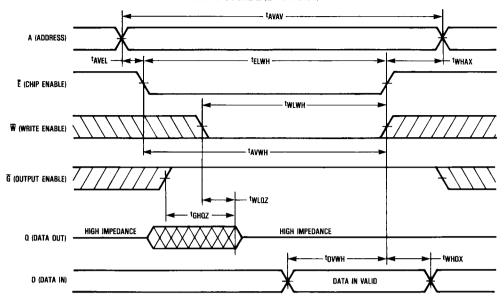
## NOTES:

- 1. Write enable  $(\overline{\mathbf{W}})$  must be high during all address transitions.
- 2. If the chip enable (E) low transition occurs simultaneously with the write enable (W) transition, the output remains in a high impedance
- 3. Both chip enable (E) and write enable (W) must be active (low) to write data into the memory. Either signal can terminate the write cycle by going high. Data in setup and hold timing should be referenced to the rising edge of the signal that terminates the write.
- 4. twhax is measured from the earlier of, chip enable (E) or write enable (W) going high to the end of write cycle.
- 5. Output enable (G) can be either low or high during a write cycle. If chip enable (E) and G are both low during this period then the data input/output (DQ) pins are in the output state. Under these conditions input signals of opposite phase to the outputs must not be applied.

## WRITE CYCLE 1 (W Controlled)



## WRITE CYCLE 2 (E Controlled)



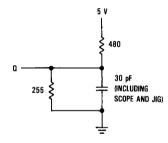
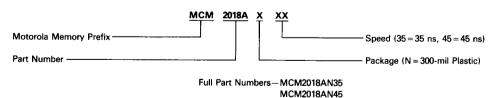


Figure 1. Output Load

# ORDERING INFORMATION (Order by Full Part Number)



NOTE: For mechanical data, please see Chapter 10.

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