# Calibrating gyrochronology using Galactic kinematics

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#### ABSTRACT

Gyrochronology, the method of inferring the age of a star from its rotation period, could provide ages for billions of stars over the coming decade of time-domain astronomy. However, the gyrochronology relations remain poorly calibrated due to a lack of precise ages for old, cool main-sequence stars. Now however, with proper motion measurements from Gaia, Galactic kinematics can be used as an age proxy, and the magnetic and rotational evolution of stars can be examined in detail. We demonstrate that kinematic ages, inferred from the velocity dispersions of groups of stars, beautifully illustrate the time and mass-dependence of the gyrochronology relations. We use the kinematic ages of field stars, plus benchmark clusters and asteroseismic stars, to calibrate a new empirical Gaussian process gyrochronology relation, that fully captures the complex rotational evolution of cool dwarfs over a range of masses and ages. We use cross validation to demonstrate that this relation accurately predicts ages for FGKM dwarfs.

Keywords: Stellar Rotation — Stellar Evolution — Stellar Activity — Stellar Magnetic Fields — Low Mass Stars — Solar Analogs — Milky Way Dynamics

### 1. INTRODUCTION

Low mass dwarfs are the most common stars in the Milky Way, and their ages could reveal the evolution of planetary systems and stellar populations in the Galaxy. However, the ages of GKM stars are difficult to measure because their luminosities and temperatures evolve slowly on the main sequence. Fortunately, rotation-dating, or 'gyrochronology' provides a promising means to measure precise ages for these cool dwarfs. The rotation periods of these stars evolve relatively rapidly, and a fully calibrated gyrochronology model that captures the time and mass-dependence of stellar spin down could provide ages that are precise to within 20% for millions of Milky Way stars in the time-domain era (Epstein & Pinsonneault 2014; Najita et al. 2016; Angus et al. 2019).

With the thousands of new photometric rotation period measurements provided by specialized ground and spacebased missions (particularly Kepler/K2 and TESS Borucki et al. 2010; Howell et al. 2014; Ricker et al. 2015), we are making progress towards the ultimate goal for rotation-dating: a fully calibrated gyrochronology relation, applicable to GKM main-sequence stars of all ages. A lack of low-mass and old calibration stars has previously limited the mass and age coverage of gyrochronology relations, which can only be calibrated using stars with precise age and rotation period measurements. Historically, the calibration sample has been limited to open clusters and asteroseismic stars because cluster members and Solar-like oscillators can be precisely dated via main-sequence turn off and asteroseismology. Open clusters provide good mass coverage for young stars: rotation periods have been measured for F through mid M dwarfs for stars in clusters with precisely measured ages up to around 700 Myr. Asteroseismic stars provide reasonable age coverage for hot stars: seismic masses and photometric surface rotation periods have been measured for F, G and early K dwarfs for stars as old as 10 Gyr. However, neither asteroseismology nor cluster analysis can provide rotation periods and ages for old, late K and M dwarfs. In addition, cluster and asteroseismic stars generally provide sparse coverage of the rotation period-effective temperature plane, and cannot reveal the detailed evolution of stellar rotation rates. As a result, most empirical gyrochronology relations are only reliable for G dwarfs up to Solar age, K dwarfs up to 2-3 Gyr, and early M dwarfs up to < 1 Gyr. For this reason, the rotational evolution of cool dwarfs is not well understood. However, as we showed in ?, kinematic ages can be used to turn field stars, observed by Kepler, into a calibration sample that provides good mass and age coverage. Although the Kepler sample does not include late M dwarfs, it can still be used to extend gyrochronology relations to much older ages for late K and early M dwarfs. By adding the ages and rotation periods of thousands of field stars to the open cluster and asteroseismic calibration sample, we can calibrate a gyrochronology relation that is applicable to FGK and early M dwarfs between the ages of  $\sim$ 500 Myr and 8 Gyr.

## 1.1. Using kinematics as an age proxy

In ? we demonstrated that kinematics can be used to explore the evolution of stellar rotation. In this paper we take the next step and use kinematics to calibrate a new gyrochronology relation. This paper is laid out as follows. In section ?? we describe the calibration of a new AVR, and how we used it to calculate ages for over 6000 stars with measured rotation periods. In this section we also compare these kinematic ages with literature age measurements. In section ?? we describe how we use these kinematic ages to calibrate a new empirical gyrochronology relation.

### 2. METHOD

### 2.1. Data

This study focuses on stellar rotation in the original Kepler field, partly because Kepler provides the largest sample of published rotation periods, and partly because its low Galactic latitude allows us to marginalize over missing RV measurements to approximate  $v_z$ . We combined three rotation period catalogs constructed from original Kepler data: McQuillan et al. (2014), ? and García et al. (2014).

# 2.2. Inferring 3D velocities (marginalizing over missing RV measurements)

It has been demonstrated that the dispersion in vertical velocity,  $v_z$  for a group of stars increases with the age of that group (citations). However, velocities in Galactocentric coordinates,  $v_x$ ,  $v_y$  and  $v_z$ , can only be calculated with full 6-D position and velocity information, *i.e.* proper motions, position and radial velocity. In ? we introduced the idea that kinematic ages could be used to calibrate gyrochronology and showed, in the appendix of that paper, that velocity,  $v_b$  in the Galactic frame, which can be calculated without an RV measurement, can be used as an approximation to  $v_z$  for *Kepler* stars. This is because the *Kepler* field of view lies at relatively low Galactic latitudes, ( $\sim 5-20^{\circ}$ ), so the z-direction is similar to the b-direction for *Kepler* stars. However,  $v_b$  is only a close approximation to  $v_z$  at extremely low latitudes, and even in the *Kepler* field, kinematic ages calculated with  $v_b$  instead of  $v_z$  are systematically larger because of extra noise introduced by the imperfect translation between  $v_b$  and  $v_z$ in order to calculate accurate vertical velocities and therefore ages, the appropriate approach is to *infer*  $v_z$  by marginalizing over missing RV measurements.

Three-dimensional velocities in galactocentric coordinates:  $v_{\mathbf{x}}$ ,  $v_{\mathbf{y}}$ , and  $v_{\mathbf{z}}$  can only be directly computed via a transformation from 3D velocities in another coordinate system, like the equatorial coordinates provided by Gaia:  $\mu_{\alpha}$ ,  $\mu_{\delta}$ , and RV. For stars with no measured RV in Gaia DR2,  $v_{\mathbf{x}}$ , vy, and  $v_{\mathbf{z}}$  can still be inferred from positions and proper motions alone, by marginalizing over missing RV measurements. For each star in our sample, we inferred  $v_{\mathbf{x}}$ ,  $v_{\mathbf{y}}$ , and  $v_{\mathbf{z}}$  from the 3D positions and proper motions provided in the Gaia DR2 catalog (Brown et al. 2011). We also simultaneously inferred distance, instead of using  $1/\pi$ , to model velocities (?).

Using Bayes rule, the posterior probability of the parameters given the data can be written:

$$p(v_{\mathbf{X}\mathbf{Y}\mathbf{Z}}, D|\mu_{\alpha}, \mu_{\delta}, \alpha, \delta, \pi) = p(\mu_{\alpha}, \mu_{\delta}, \alpha, \delta, \pi|v_{\mathbf{X}\mathbf{Y}\mathbf{Z}}, D)p(v_{\mathbf{X}\mathbf{Y}\mathbf{Z}})p(D),$$
 (1)

where D is distance,  $\alpha$  is Right Ascension (RA),  $\delta$  is declination (dec),  $\pi$  is parallax,  $\mu_{\alpha}$  is proper motion in RA, and  $\mu_{\delta}$  is proper motion in dec. The prior over log(distance) and velocities was a multivariate Gaussian with mean and covariance determined from the distance and velocity distributions of *Kepler* targets with RV measurements.

The posterior PDF was explored using emcee (?), an affine-invariant, ensemble MCMC sampler. Initialization.

We found that 10,000 samples with 16 walkers was sufficient to calculate a converged autocorrelation time, and produce 150-500 independent samples per parameter.

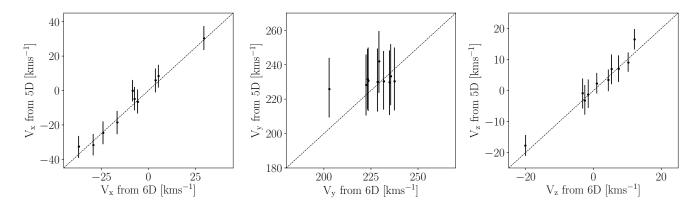
Over 3000 stars in the McQuillan et al. (2014) sample do have RV measurements and provide an opportunity to test this method of inferring velocities. Figure ?? shows the velocities of these 3000 stars, calculated using RV measurements, compared with their inferred velocities.

### 2.3. Calculating velocity dispersions

A kinematic age can be calculated from the velocity dispersion (e.g. the standard deviation or Median Absolute Deviation, MAD, of velocities) of a group of stars. These velocity dispersions can then be converted into an age using an AVR (e.g. ??). The major assumption underlying kinematic ages is that all stars used to calculate a velocity dispersion are the same age. So, in order to calculate kinematic ages from velocity dispersions for Kepler stars, it is necessary to group them by age. Fortunately, we can use the implicit assumption that underpins gyrochronology itself to group stars by age: that stars with the same rotation period and color are the same age. We discuss the implications of this assumption, and how our results would change if this assumption is false, in the Discussion of this paper (section ??).

To calculate a  $v_z$  velocity dispersion and therefore age for each Kepler star, we grouped stars with their neighbors in  $\log(P_{\rm rot})$ – $T_{\rm eff}$  space. We experimented with two methods of grouping stars: using K-nearest neighbors, and using a fixed range in  $\log(P_{\rm rot})$  and  $T_{\rm eff}$ . In the K-nearest neighbors method, each star was grouped with the K-nearest stars in  $\log(P_{\rm rot})$ - $T_{\rm eff}$  space. Groups created this way span a small range of  $\log(P_{\rm rot})$  and  $T_{\rm eff}$  where the number density of

Figure 1. Vertical velocities calculated with full 6D information vs vertical velocities inferred without RV, for all 3000 McQuillan et al. (2014) stars with Gaia RV measurements.



stars is large, and a large range where the number density is small. However, all groups have the same number of stars. In the fixed range method, each star was grouped with stars whose  $\log(P_{\rm rot})$ s and  $T_{\rm eff}$ s fell within a certain range of their own. This method created groups with large numbers of stars in densely populated regions of the  $\log(P_{\rm rot})$ - $T_{\rm eff}$  plane, and small numbers of stars in sparsely populated regions. However, each group contains a different number of stars. To choose the best method, and to optimize for the parameters of each (K and  $\log(P_{\rm rot})$  and  $T_{\rm eff}$ -range), we conducted a set of tests.

2.4. Converting velocity dispersion to age with an AVR

2.5. Comparing kinematic ages with asteroseismic and cluster ages

2.6. A Gaussian process gyrochronology relation

# 3. RESULTS

# 4. DISCUSSION

# 5. CONCLUSION

This work was partly developed at the 2019 KITP conference 'Better stars, better planets'. Parts of this project are based on ideas explored at the Gaia sprints at the Flatiron Institute in New York City, 2016 and MPIA, Heidelberg, 2017. This work made use of the gaia-kepler.fun crossmatch database created by Megan Bedell.

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