view_frames Result Recorded at time: 1571293953.269 map Broadcaster: /map_base_tf Average rate: 194.685 Hz Most recent transform: 1571293953.270 (-0.001 sec old) Buffer length: 4.875 sec bot Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1571293953.269 sec old) Buffer length: 0.000 sec shoulder_yaw_motor Broadcaster: /robot_state_publisher Average rate: 10.238 Hz Most recent transform: 1571293953.226 (0.043 sec old) Buffer length: 4.200 sec shoulder_bracket Broadcaster: /robot_state_publisher Average rate: 10.238 Hz Most recent transform: 1571293953.226 (0.043 sec old) Buffer length: 4.200 sec shoulder_pitch_motor Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1571293953.269 sec old) Buffer length: 0.000 sec biscep Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1571293953.269 sec old) Buffer length: 0.000 sec elbow_bracket Broadcaster: /robot_state_publisher Average rate: 10.238 Hz Most recent transform: 1571293953.226 (0.043 sec old) Buffer length: 4.200 sec elbow_motor Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1571293953.269 sec old) Buffer length: 0.000 sec forearm Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1571293953.269 sec old) Buffer length: 0.000 sec wrist_bracket Broadcaster: /robot_state_publisher Average rate: 10.238 Hz Most recent transform: 1571293953.226 (0.043 sec old) Buffer length: 4.200 sec wrist_pitch_motor Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1571293953.269 sec old) Buffer length: 0.000 sec square_plate_1 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1571293953.269 sec old) Buffer length: 0.000 sec AXB2B_SQ_Y Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1571293953.269 sec old) Buffer length: 0.000 sec wrist_yaw_motor Broadcaster: /robot_state_publisher Average rate: 10.238 Hz Most recent transform: 1571293953.226 (0.043 sec old) Buffer length: 4.200 sec AXBrak_Y_R Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1571293953.269 sec old) Buffer length: 0.000 sec wrist_roll_motor Broadcaster: /robot_state_publisher Average rate: 10.238 Hz Most recent transform: 1571293953.226 (0.043 sec old) Buffer length: 4.200 sec roll_j_plate Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz

Most recent transform: 0.000 (1571293953.269 sec old)
Buffer length: 0.000 sec

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