Recorded at time: 1572954156.281 camera_link map Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Broadcaster: /map_base_tf Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz Average rate: 204.612 Hz Average rate: 10000.000 Hz Most recent transform: 1572954156.325 (-0.044 sec old) Most recent transform: 0.000 (1572954156.281 sec old) Most recent transform: 0.000 (1572954156.281 sec old) Most recent transform: 0.000 (1572954156.281 sec old) / Most recent transform: 0.000 (1572954156.281 sec old) Most recent transform: 0.000 (1572954156.281 sec old) \ Most recent transform: 0.000 (1572954156.281 sec old) Most recent transform: 0.000 (1572954156.281 sec old) Buffer length: 4.985 sec Buffer length: 0.000 sec camera_infra2_frame camera_infra1_frame camera_depth_frame camera_aligned_depth_to_color_frame camera_aligned_depth_to_infra1_frame camera_color_frame bot camera_gyro_frame Broadcaster: /robot_state_publisher Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Broadcaster: /camera/realsense2_camera_manager Average rate: 10000.000 Hz Most recent transform: 0.000 (1572954156.281 sec old) Buffer length: 0.000 sec shoulder_yaw_motor camera_gyro_optical_frame camera_infra1_optical_frame camera_infra2_optical_frame camera_depth_optical_frame camera_color_optical_frame Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1572954156.249 (0.031 sec old) Buffer length: 4.900 sec shoulder_bracket Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1572954156.249 (0.031 sec old) Buffer length: 4.900 sec shoulder_pitch_motor Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1572954156.249 (0.031 sec old) Buffer length: 4.900 sec elbow_motor Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1572954156.249 (0.031 sec old) Buffer length: 4.900 sec wrist_yaw_motor Broadcaster: /robot_state_publisher Average rate: 10.204 Hz Most recent transform: 1572954156.249 (0.031 sec old) Buffer length: 4.900 sec

wrist_pitch_motor

wrist_roll_motor

Broadcaster: /robot_state_publisher
Average rate: 10.204 Hz
Most recent transform: 1572954156.249 (0.031 sec old)
Buffer length: 4.900 sec

view_frames Result

Broadcaster: /camera/realsense2_camera_manager

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1572954156.281 sec old)

Buffer length: 0.000 sec

Broadcaster: /camera/realsense2_camera_manager

Average rate: 10000.000 Hz

Buffer length: 0.000 sec

Most recent transform: 0.000 (1572954156.281 sec old)

camera_accel_frame

camera_accel_optical_frame