

# Computational statistics, lecture math 2

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# Topics today

- Probability distributions (reading: GH, chapter 1.3) and integration
- Concavity, convexity and implication for optimization
- Markov chains (reading: GH, chapter 1.7)



### **Exponential distribution**

• The density of the exponential distribution  $Exp(\lambda)$  is

$$f(x) = \lambda \exp(-\lambda x) \mathbf{1}\{x \ge 0\} = \begin{cases} \lambda \exp(-\lambda x), & \text{if } x \ge 0, \\ 0, & \text{if } x < 0 \end{cases}$$

dexp(x, rate=0.8)

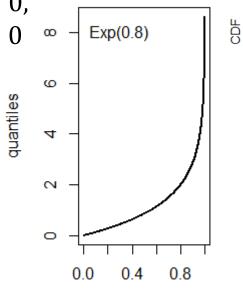
• Compute the distribution function:

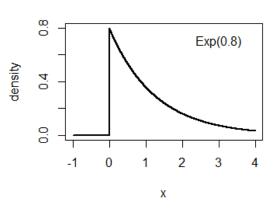
$$F(x) = P(X \le x) = \int_{-\infty}^{x} f(t) dt = \begin{cases} 1 - \exp(-\lambda x), & \text{if } x \ge 0, \\ 0, & \text{if } x < 0 \end{cases}$$

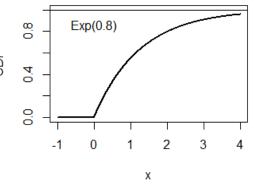
pexp(x, rate=0.8)

• The inverse distribution function is  $F^{-1}(y) = -\log(1-y)/\lambda$ since  $y = 1 - \exp(-\lambda x) \Leftrightarrow \exp(-\lambda x) = 1 - y \Leftrightarrow$  $-\lambda x = \log(1-y) \Rightarrow x = -\log(1-y)/\lambda$ 

qexp(x, rate=0.8)







#### Poisson distribution

• The density of the Poisson distribution  $Po(\lambda)$  is

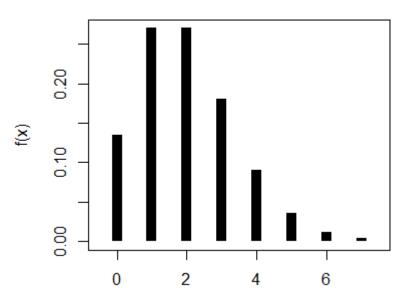
$$f(x) = \frac{\lambda^x}{x!} \exp(-\lambda) \text{ for } x = 0, 1, 2, \dots$$

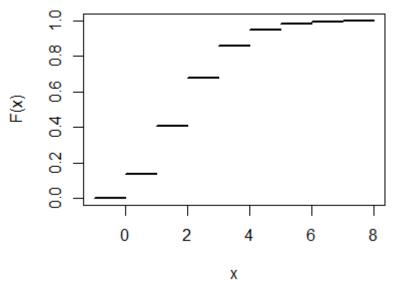
dpois(x, lambda=0.5)

• The distribution function:

$$F(x) = P(X \le x) = \sum_{j=0}^{x} f(j) = \exp(-\lambda) \sum_{j=0}^{x} \frac{\lambda^{j}}{j!}$$

ppois(x, lambda=0.5)







# Expected value and variance of a distribution

• The probability for  $X \in [a, b]$  can be written as integral according to

$$P(X \in [a,b]) = \int_{a}^{b} f(x)dx$$

• The expected value of a distribution with density f(x) is:

$$E(X) = \int_{-\infty}^{\infty} x f(x) dx$$

• The variance is

$$Var(X) = \int_{-\infty}^{\infty} (x - EX)^2 f(x) dx$$

• What is E(X) and Var(X) for the exponential and Poisson distribution?



# Integration

• The expected value of the exponential distribution is:

$$E(X) = \int_{-\infty}^{\infty} x f(x) dx = \int_{-\infty}^{\infty} x \lambda \exp(-\lambda x) \mathbf{1} \{x \ge 0\} dx =$$



## Exponential family (GH, chapter 1.3)

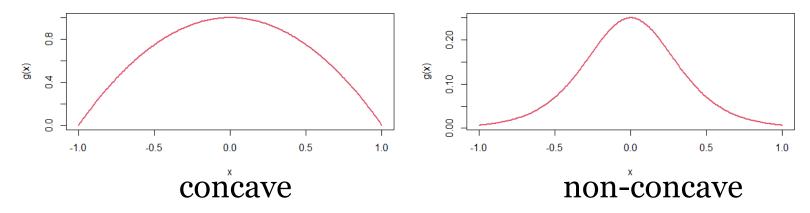
- Exponential distribution:  $f(x) = \lambda \exp(-\lambda x) \mathbf{1}\{x \ge 0\}$
- Poisson distribution  $f(x) = \frac{\lambda^x}{x!} \exp(-\lambda)$
- Density of exponential family distribution:

$$f(x) = c_1(x)c_2(\gamma)\exp(\sum_{i=1}^k y_i(x)\theta_i(\gamma))$$



#### Convexity, concavity and implication for optimization

• Function g concave, if  $g((\mathbf{x}+\mathbf{y})/2) \ge (g(\mathbf{x})+g(\mathbf{y}))/2$  for all  $\mathbf{x},\mathbf{y}$ 



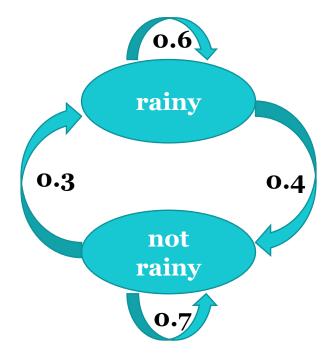
- If *g* is concave, a local maximum is a global maximum
- Log likelihood for exponential families is concave
- Log likelihoods can be non-concave (e.g. Cauchy-distribution in Lab1 Q1)
- Deep learning optimization problems are often non-concave / non-convex and have multiple local extrema



## Markov chains (reading: GH chapter 1.7)

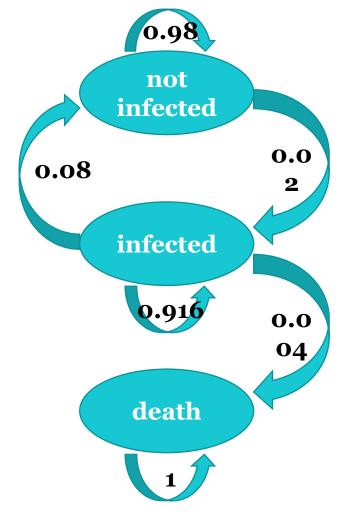
- Consider a sequence of random variables (X<sup>(t)</sup>), t=0,1,...
- Each  $X^{(t)}$  can have values in so-called *state space S* (can be discrete; we will later use a continuous one- or multidimensional S)
- A general random sequence (process) is described by specification of  $P(X^{(t)} | X^{(t-1)}, ..., X^{(o)})$  for all t
- A Markov chain is a specific process with Markov property  $P(X^{(t)} | X^{(t-1)}, ..., X^{(o)}) = P(X^{(t)} | X^{(t-1)})$
- The state of  $X^{(t)}$  depends only on the state before and not earlier history ( $X^{(t)}$  is memoryless)
- $P(X^{(t)} | X^{(t-1)})$  is called *transition probability*





state space
S={rainy, not rainy}

numbers are transition probabilities



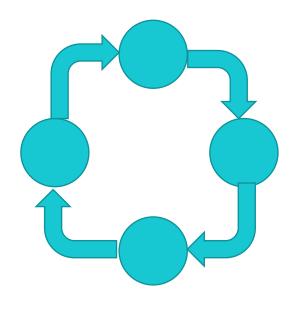
**S={not infected, infected, death}** 

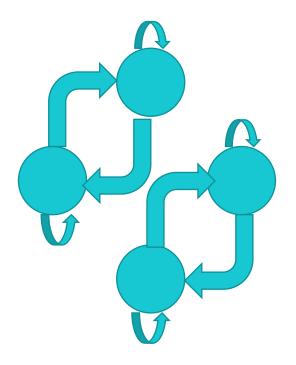


#### Markov chains

- If S is discrete, we can write  $p_{ij}^{(t)} = P(X^{(t)} = j \mid X^{(t-1)} = i)$
- If S is continuous,  $P(X^{(t)} \mid X^{(t-1)})$  is represented by a cumulative distribution function or density
- A Markov chain is *(time-)homogenous* if distribution of  $(X^{(t)} \mid X^{(t-1)})$  is equal for all t
- A Markov chain is *irreducible* if every state in S can be reached from any state
- A state has *period* k if multiples of k steps are necessary to return to it
- A Markov chain is *aperiodic* if each state has period 1







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