Chen Data Science & Al for Neuroscience Summer School

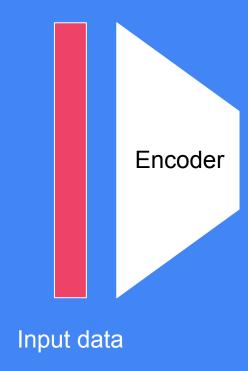


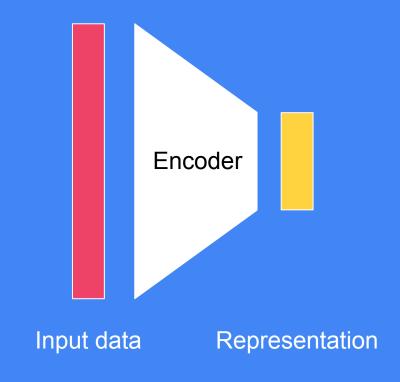
Caltech

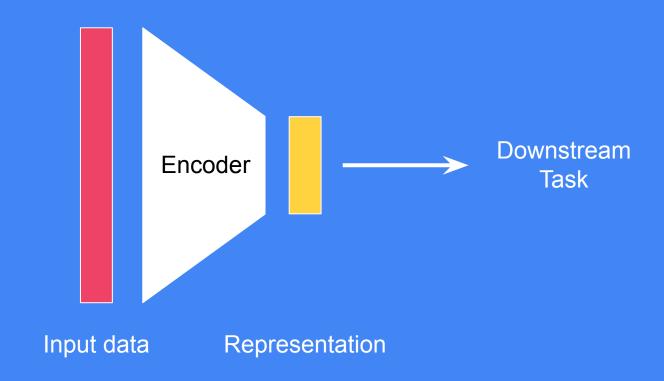
Sabera Talukder

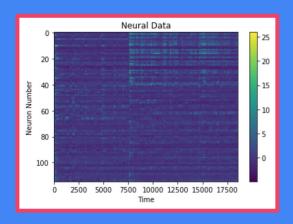




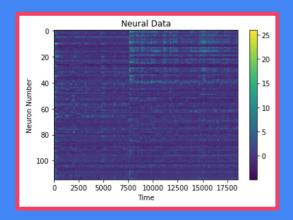






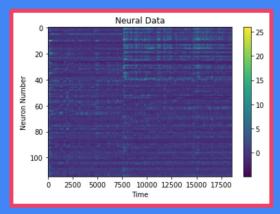


Input data



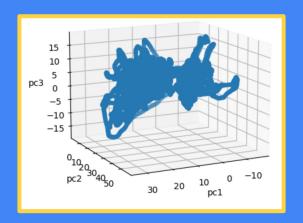
Encoder is PCA

Input data

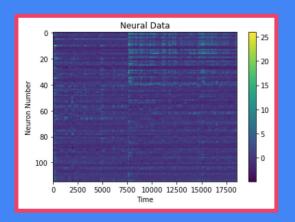


Input data

Encoder is PCA

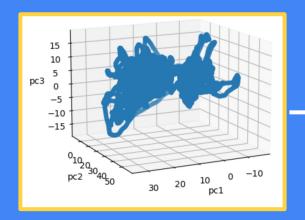


Representation

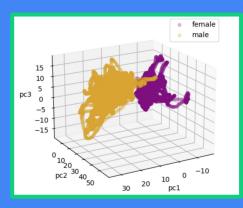


Input data

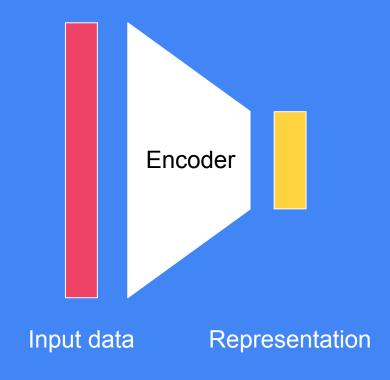
Encoder is PCA

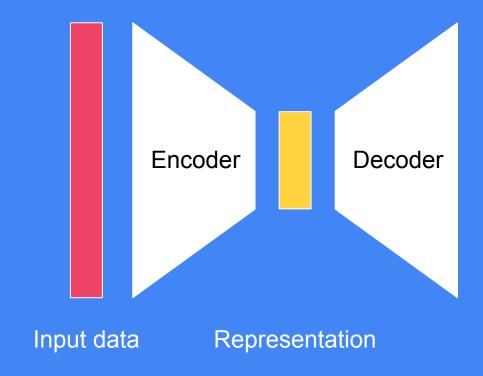


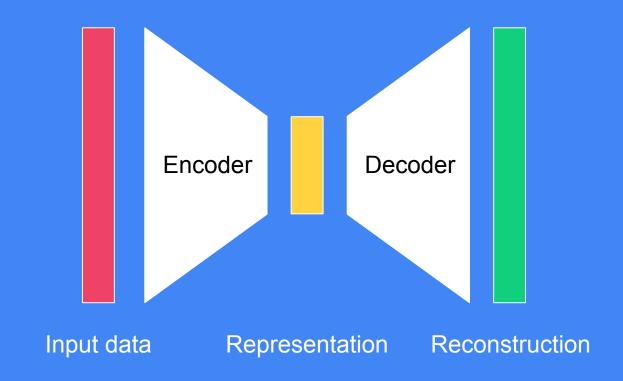
Representation



Downstream Task





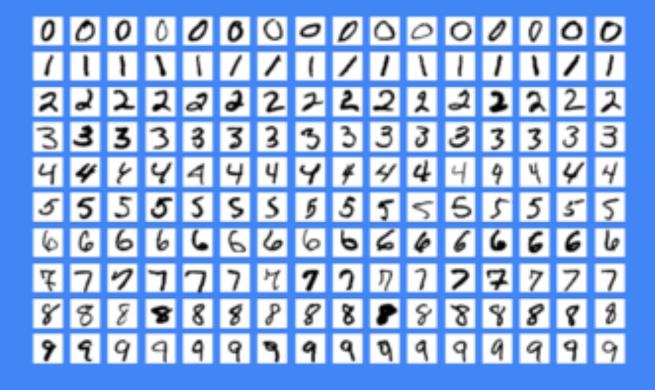


Autoencoder Downstream Task Encoder Decoder Input data Reconstruction Representation

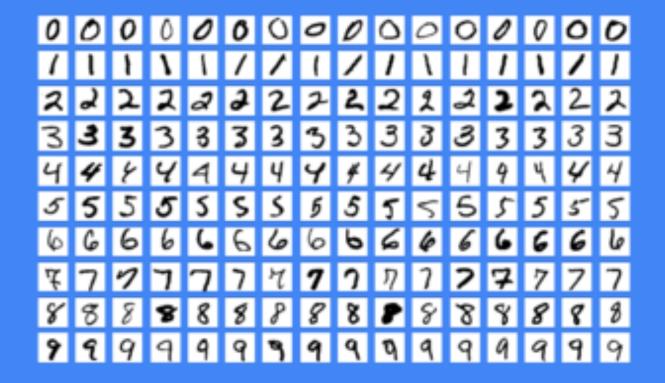
Autoencoder Downstream Task Encoder Decoder is a is a Neural Neural Network! Network! Input data Representation Reconstruction

MNIST Example: Dataset

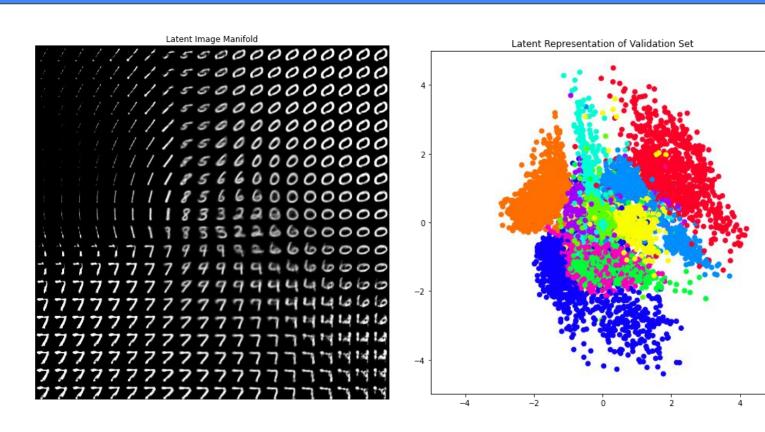
MNIST Example: Dataset

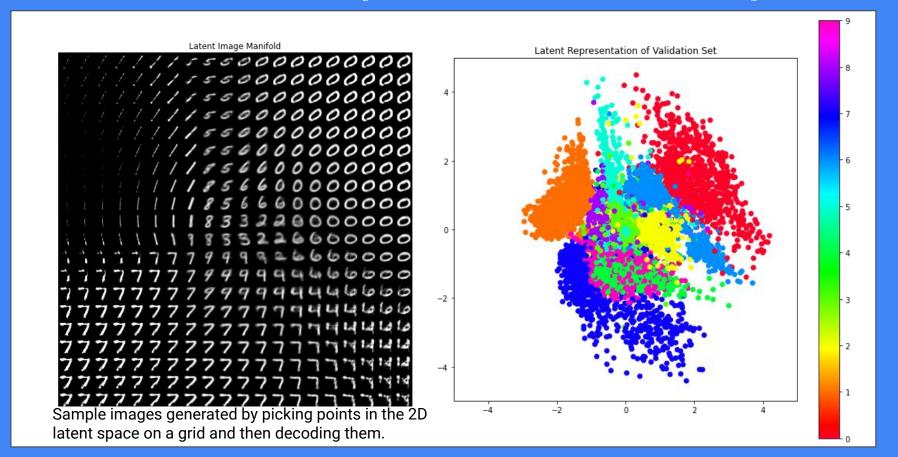


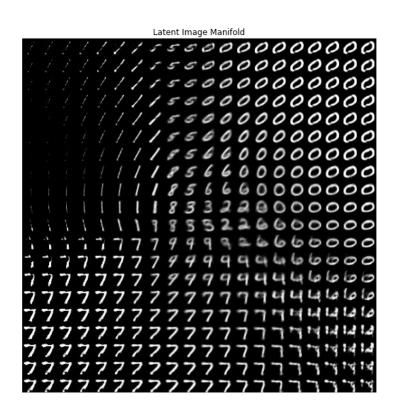
MNIST Example: Dataset

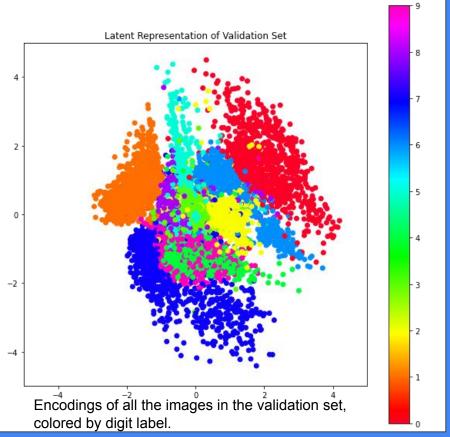


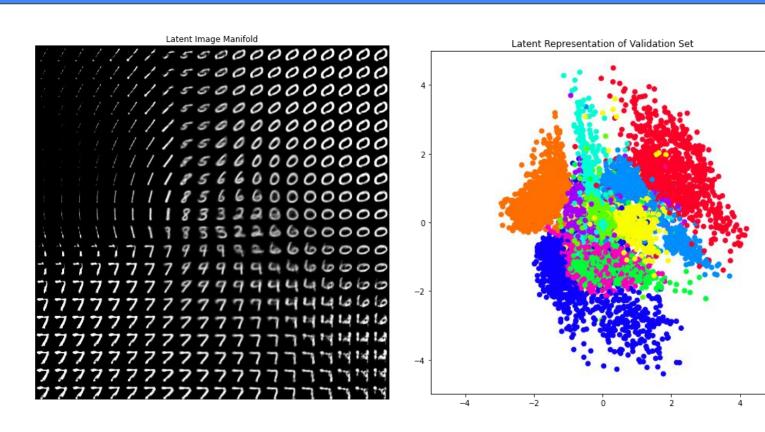
Goal of using an autoencoder on MNIST is to generate handwritten digits!



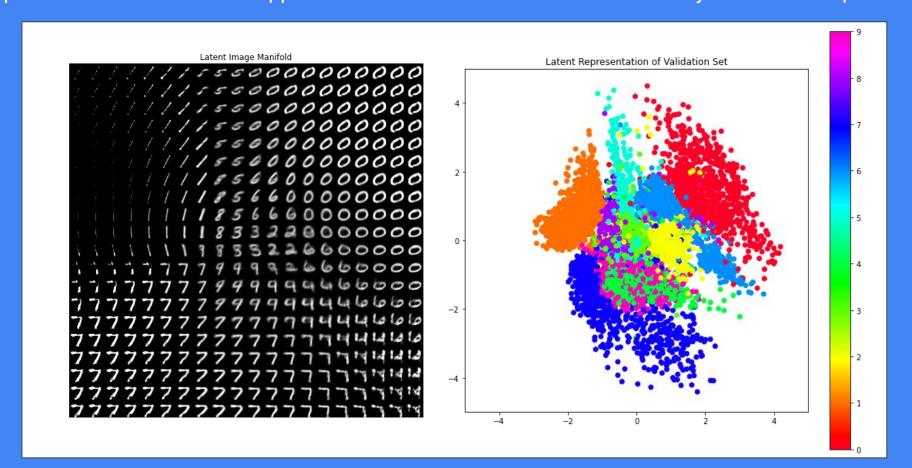




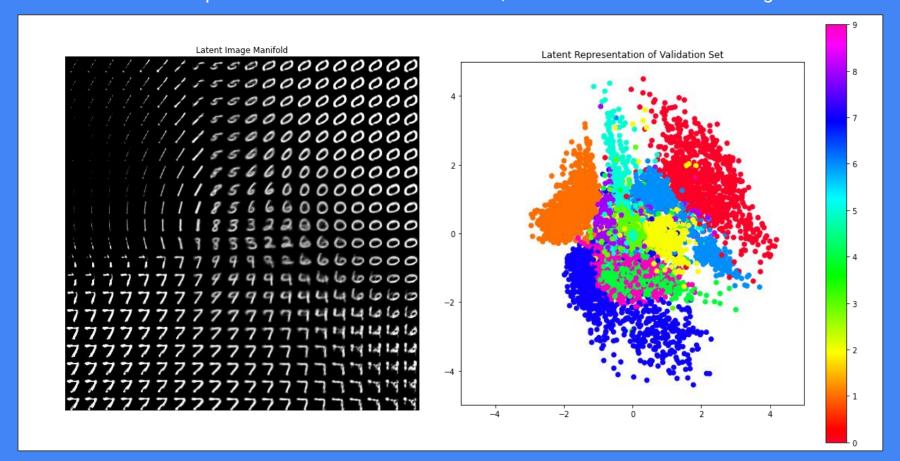


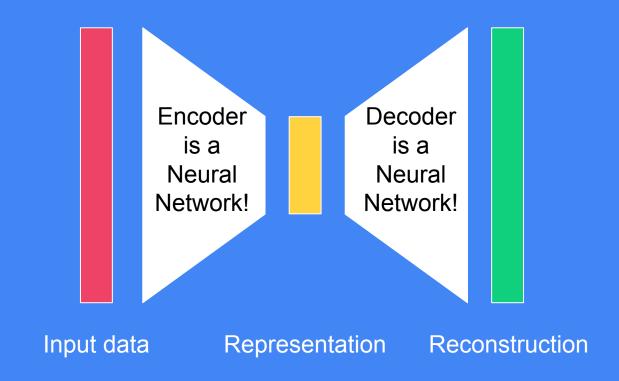


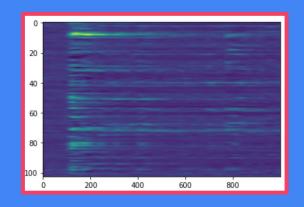
<u>Takeaway 1:</u> There's no "meaning" to the latent space in any strict sense. But, we can get a "qualitative" sense of what happens as we traverse axes. What features do you see in the space?



<u>Takeaway 2:</u> This model has no prior concept of what each digit is. However, it learns to essentially embed digit types in localized regions of the latent space. Why? Because this representation is a useful one that it learns that helps with the task of reconstruction, which is what we want from good features.

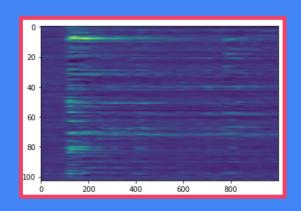




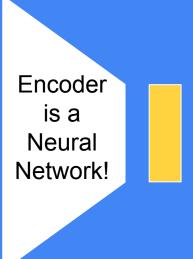


Input data

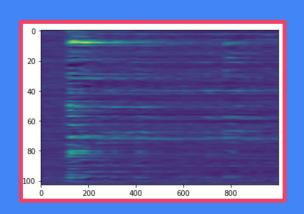
Encoder is a Neural Network!



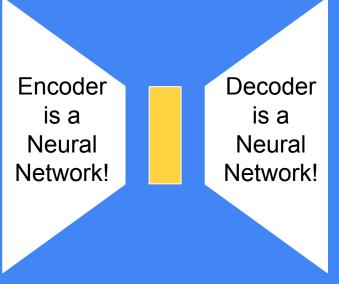
Input data

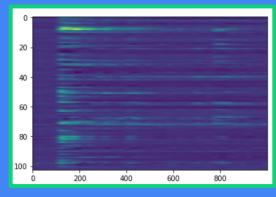


Representation



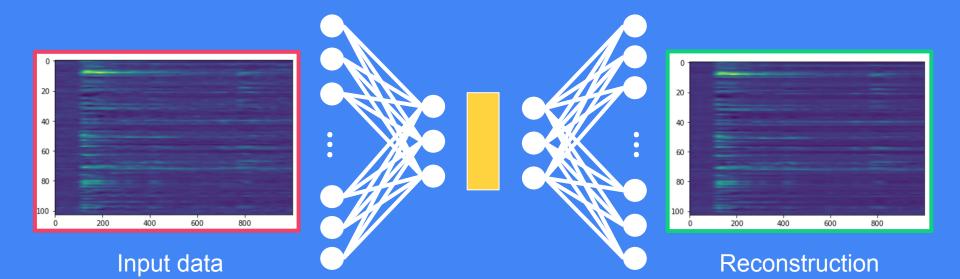
Input data





Reconstruction

Representation



Representation



A "linear layer" is just a matrix that multiplies the input and produces some output.



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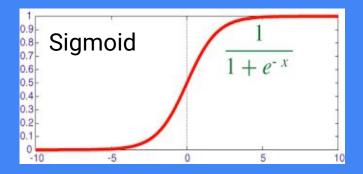
Fact: the composition of two linear layers is going to be linear. Why is this important? If we only use linear operations in our model, then the expressiveness of our model is going to be restricted significantly.

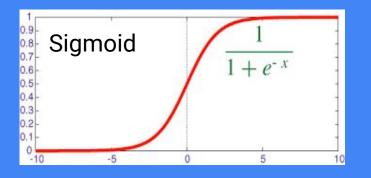
Nonlinearities go between the linear layers (functions that go between the layers of a neural network are called activation functions) so that when we compose all the layers together, we get a nonlinear function. This allows us to build universal function approximators!

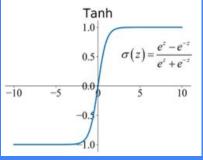


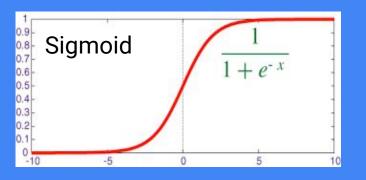
Nonlinearities

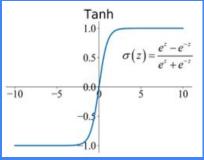
We introduce nonlinearities in our model in the form of activation functions.

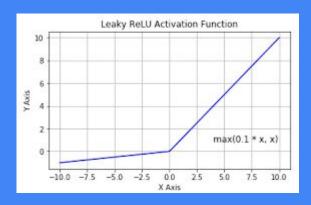


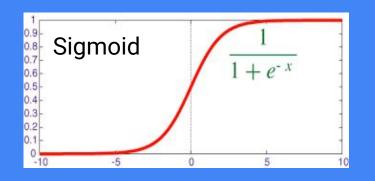


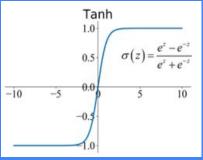


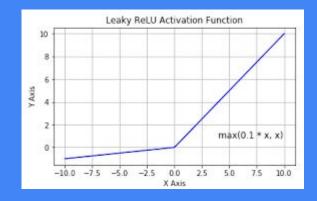


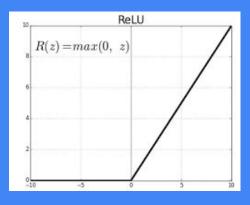










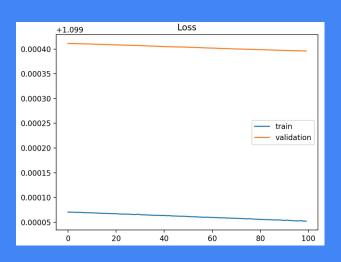


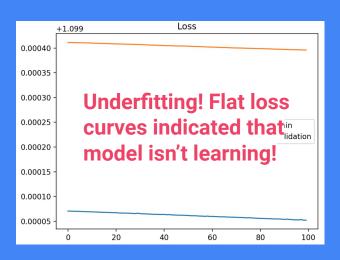
Jump ahead to training!

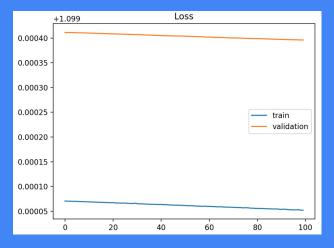
Jump ahead to training!

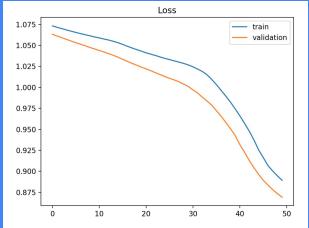
Specifically underfitting and overfitting, and how to read training and validation curves!

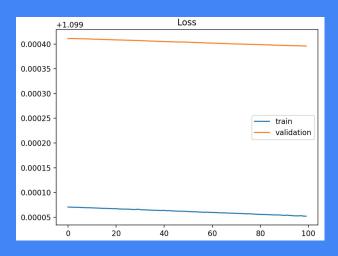
What is the training set versus the validation set?



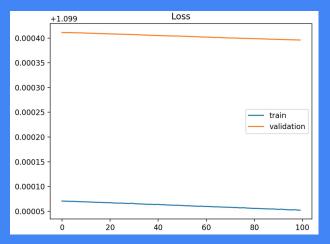


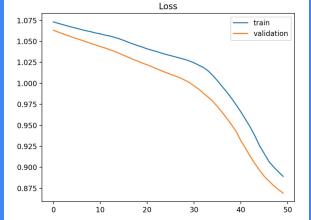


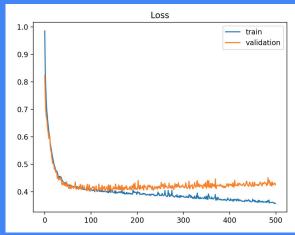


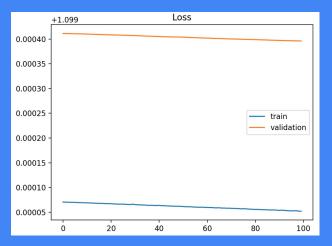


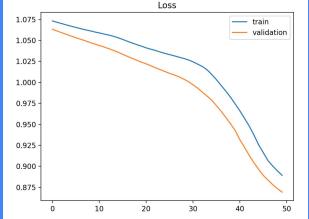














What do you think a well trained model will look like with respect to the training and validation losses?

Just Right!

