

Greedy Algorithms

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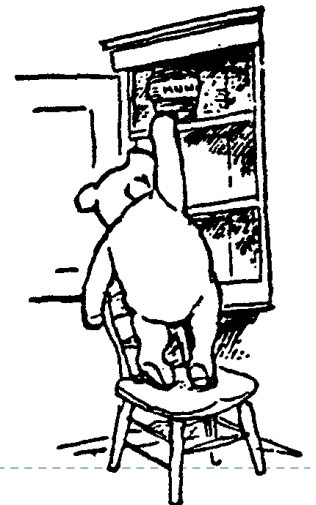
Outline

- ▶ Activity-selection problem (Ch16.1)
- ▶ Elements of greedy algorithm (Ch16.2)



Greedy Solutions for Optimization Problems

- ▶ **Optimization problem:** *view the optimal solution as a sequence of choices.*
- ▶ In order to get what you want, just start grabbing what looks best.
- ▶ **The greedy choice:** Commit to the selection that looks the “best” (without solving the subproblems first).
- ▶ Surprisingly, many important and practical optimization problems can be solved this way.



Greedy Choice

- ▶ Example: Knapsack of capacity $W = 5$

▶	<u>item</u>	<u>weight</u>	<u>value</u>
▶	1	2	\$12
▶	2	1	\$10
▶	3	3	\$20
▶	4	2	\$15

- ▶ Greedy choice: take the most valuable item!

- ▶ Greedy algorithms may not lead to the optimal solution.

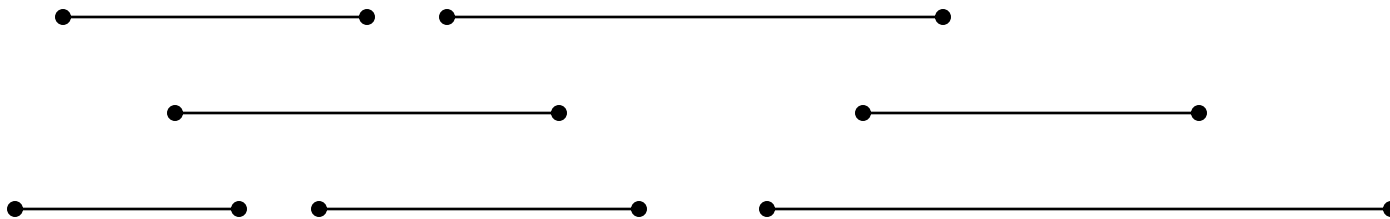
- ▶ *Wrong!* Do not confuse it with heuristic algorithms!



Activity-selection Problem

- ▶ **Input:** Set A of n activities, a_1, a_2, \dots, a_n .
 - ▶ s_i = start time of activity i .
 - ▶ f_i = finish time of activity i .
- ▶ **Output:** Subset S of maximum number of compatible activities.
 - ▶ Two activities are compatible, if their intervals don't overlap.

Example:



Subproblems

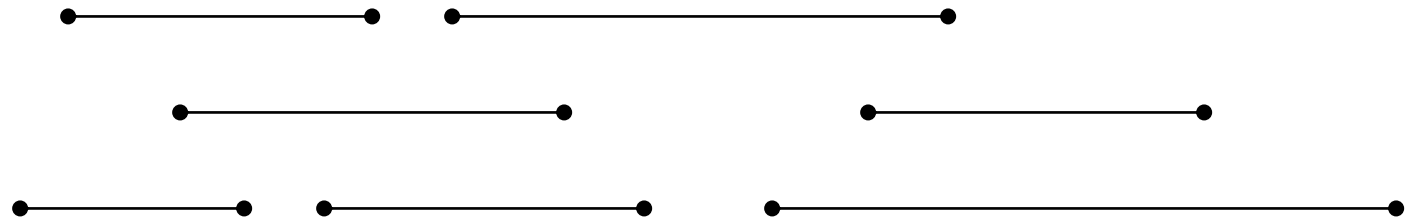
- ▶ Two options:
 - ▶ Suppose an optimal solution includes activity a_n
 - ▶ Suppose an optimal solution does not include activity a_n
- ▶ Multiple options:
 - ▶ Suppose an optimal solution first picks activity a_1
 - ▶ ...
 - ▶ Suppose an optimal solution first picks activity a_k
 - ▶ ...
 - ▶ Suppose an optimal solution first picks activity a_n



Optimal Substructure

- ▶ Suppose an optimal solution does not include activity a_n .
 - ▶ Let $A_{1,n}$ be $\{a_1, a_2, \dots, a_n\}$, then the remaining subproblem becomes to find the maximum # of compatible activities from $A_{1,n-1}$.

Example:

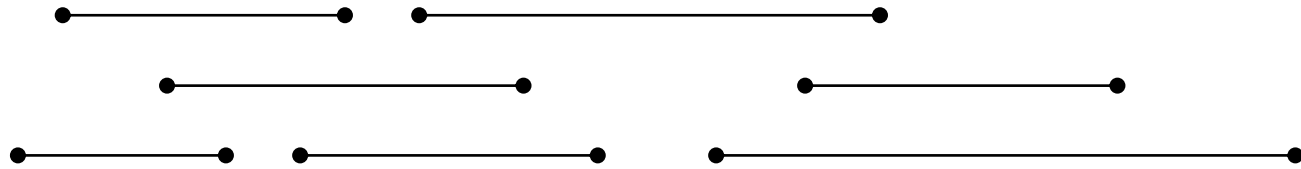


- ▶ Suppose an optimal solution includes activity a_n .
 - ▶ How to describe a subproblem whose input must be compatible with a_n ?
 - ▶ $A_{1,n-1} = \{a_1, a_2, \dots, a_{n-1}\}$ does not work.
 - ▶ The “two options” way does not work.

Optimal Substructure

- ▶ Suppose an optimal solution includes activity a_k .
 - ▶ Activities that are compatible with a_k , either starts after a_k finishes, or finish before a_k starts.
 - ▶ So we can use two activities to define a subset of activities.

Example:



- ▶ Have activities in order.
 - ▶ Let a_0 and a_{n+1} be two dummy activities, a_0 finishes before any activity starts and a_{n+1} starts after all activities finish.
 - ▶ Suppose activities are sorted by finishing times $f_1 \leq f_2 \leq \dots \leq f_n$.

Optimal Substructure

- ▶ Let $A_{i,j}$ be a subset of activities in A that start after a_i finishes and finish before a_j starts.
 - ▶ $A_{0,n+1}$ is the original input A .
 - ▶ Suppose an optimal solution of $A_{i,j}$ includes activity a_k .
 - ▶ This generates two subproblems:
 - ▶ Selecting maximum # of compatible activities from $A_{i,k}$.
 - ▶ Selecting maximum # of compatible activities from $A_{k,j}$.
 - ▶ Suppose $S_{i,j}$ is an opt solution to $A_{i,j}$ and $S_{i,j} = \{S_{i,k}, a_k, S_{k,j}\}$, then $S_{i,k}$ and $S_{k,j}$ must be optimal for $A_{i,k}$ and $A_{k,j}$, respectively.
 - ▶ Prove by using the cut-and-paste approach.
 - ▶ **Key: the two subproblems are independent!**
Suppose S' is an opt. solution to $A_{i,k}$ and S'' is an opt. solution to $A_{k,j}$, activities in S' and activities in S'' are compatible to one another.
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Optimal Substructure

- ▶ Suppose S' is an opt. solution to $A_{i,k}$ and S'' is an opt. solution to $A_{k,j}$, activities in S' and activities in S'' are compatible to one another.



Recursive Solution

- ▶ Let $c[i, j]$ = size of maximum-size subset of mutually compatible activities in $A_{i, j}$.
- ▶ Suppose an optimal solution of $A_{i, j}$ includes activity a_k .
 - ▶ This generates two subproblems:
 - ▶ Selecting maximum # of compatible activities from $A_{i, k}$.
 - ▶ Selecting maximum # of compatible activities from $A_{k, j}$.

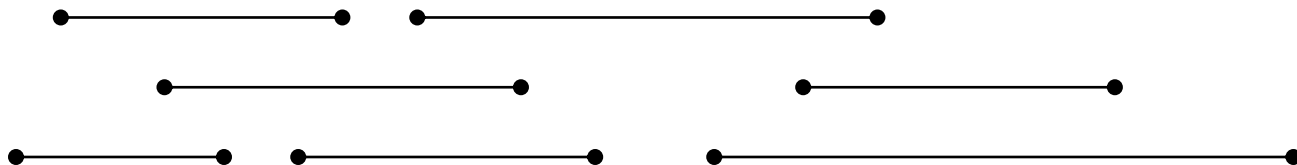
$$\text{▶ } c[i, j] = \begin{cases} 0 & \text{if } A_{i, j} = \emptyset \\ \max_{i < k < j} \{c[i, k] + c[k, j] + 1\} & \text{if } A_{i, j} \neq \emptyset \end{cases}$$



When the greedy choice DOES work?

- ▶ Problems exhibit optimal substructure.
 - ▶ an optimal solution to the problem contains within it optimal solutions to subproblems.
- ▶ Problems also exhibit the **greedy-choice** property.
 - ▶ **greedy-choice property**: there is a **global optimal solution** that contains the greedy choice.
 - ▶ Otherwise, taking the greedy choice means **WRONG!**

Example:



In-class Exercise

- ▶ Give a greedy-choice candidate for the activity selection problem.



Greedy-choice Property

- ▶ The problem also exhibits the **greedy-choice property**.
 - ▶ Assume activities are sorted by finishing times.
 - ▶ $f_1 \leq f_2 \leq \dots \leq f_n$
 - ▶ There is an optimal solution to the subproblem $A_{i,j}$, that includes the activity with the smallest finish time in set $A_{i,j}$
 - ▶ The smallest finish time activity in $A_{i,j}$ is?



Greedy-choice Property

- ▶ Therefore, we can first **make** this **greedy choice** and then solve the remaining subproblems.
- ▶ Combine the greedy choice and the solution to the subproblem to get the overall solution. The following recurrence can be simplified.

$$c[i, j] = \begin{cases} 0 & \text{if } A_{i,j} = \emptyset \\ \max_{i < k < j} \{c[i, k] + c[k, j] + 1\} & \text{if } A_{i,j} \neq \emptyset \end{cases}$$



Top-down Algorithm

Assuming activities are sorted by finish time.

Greedy-Activity-Selector (s, f)

```
1.   $n \leftarrow \text{length}[s]$ 
2.   $A \leftarrow \{a_1\}$ 
3.   $i \leftarrow 1$ 
4.  for  $m \leftarrow 2$  to  $n$  //earliest to finish in  $S_{i,n+1}$ 
5.      if  $s_m \geq f_i$  //check compatibility
6.      then  $A \leftarrow A \cup \{a_m\}$ 
7.           $i \leftarrow m$ 
8.  Return  $A$ 
```

Initial Call: Greedy-Activity-Selector(s, f)

Complexity: $\theta(n)$

Example

k	0	1	2	3	4	5	6	7	8	9	10	11	12
s_k	---	1	3	0	5	3	5	6	8	8	2	12	---
f_k	0	4	5	6	7	8	9	10	11	12	13	14	∞



Design Points of GA

- ▶ Cast the optimization problem as one in which we make a choice and are left with subproblems to solve.
- ▶ Derive a recurrence:
 - ▶ Prove that there's always an optimal solution that makes the greedy choice, so that the greedy choice is always safe.
 - ▶ Prove optimal substructure: show that greedy choice and optimal solution to subproblem \Rightarrow optimal solution to the problem.
- ▶ Implement a top-down solution:
 - ▶ make the greedy choice and solve the remaining problem.
- ▶ May have to preprocess input to put it into the greedy order.
 - ▶ Example: Sorting activities by finish time
 - ▶ Running time: $O(n \lg n)$ for sorting, and solve a recurrence of $T(n)$



Comparison with DP

	Greedy Algorithm	Dynamic Programming
“Recursive” nature	Yes	Yes
Combine solutions to subproblems	Yes	Yes
Partition subproblems	Making a greedy choice at a time	Making one choice at a time
Overlapping subproblems	No	Yes
Primarily for optimization	Yes	Yes
Optimal substructure	Yes (to develop a recurrence)	Yes (to develop a recurrence)
Preprocessing	Usually sorting	
Top-down vs. Bottom-up	Top-down	Bottom-up (but...)
Characteristic running time	Often dominated by $n \lg n$ sort	The space of subproblems



About Final

- ▶ Time: 19:00-21:00, Dec 24, 2020 (Beijing Time)
 - ▶ Same settings as the midterm for on-line students
 - ▶ 19:00-19:30 check identity & get ready
 - ▶ 19:30-21:00 final exam (closed book & notes)
 - ▶ Review Section:
 - ▶ Next Monday, Dec 21, 2020
 - ▶ A quick review & comments on HW13-15 and sample exam.
 - ▶ Office-hours:
 - ▶ 9:00am-11:00am, Dec 23, 2020 (Beijing Time) @my office east-main building 8-204, or @the class Zhumu conference room.
 - ▶ 19:00-21:00, Dec 23, 2020 (Beijing Time) @the class Zhumu conference room.
 - ▶ HW15 & Programming Assignment #2 are due on Jan 5, 2021.
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Thank you!

