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Machine Learning

Homework 3

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1 Clustering: Mixture of Multinomials (2 points)

1.1 MLE for multinomial (1 point)

The likelihood function for this multinomial distribution is given as

$$P(x|\mu) = \frac{n!}{\prod_i x_i!} \prod_i \mu_i^{x_i}, \quad i = 1, \dots, d \quad (1)$$

Taking log from both side of the above equation gives the log-likelihood function

$$\mathcal{L}(\mu) = \log(P(x|\mu)) = \log(n!) - \log\left(\prod_i x_i!\right) + \log\left(\prod_i \mu_i^{x_i}\right) \quad (2)$$

This can be considered a Lagrange problem with the constraint $\sum_i \mu_i = 1$. Hence, the Lagrangian equation can be formulated as

$$\mathcal{L}(\mu) = \log(n!) - \log\left(\prod_i x_i!\right) + \log\left(\prod_i \mu_i^{x_i}\right) - \lambda\left(\sum_i \mu_i - 1\right) \quad (3)$$

where λ is Lagrangian multiplier, giving

$$\mathcal{L}(\mu) = \log(n!) - \sum_i \log(x_i!) + \sum_i x_i \log(\mu_i) - \lambda\left(\sum_i \mu_i - 1\right) \quad (4)$$

Taking the derivative of the equation with respect to μ_i and setting it to 0 gives

$$\frac{\partial \mathcal{L}}{\partial \mu_i} = \frac{\sum_i x_i}{\sum_i \mu_i} - \lambda = 0 \quad (5)$$

Hence, we get that

$$\lambda = \frac{\sum_i x_i}{\sum_i \mu_i} = \frac{n}{1} = n \quad (6)$$

Accordingly, we could derive the maximum-likelihood estimator μ_i as

$$\mu_i = \frac{x_i}{\lambda} = \frac{x_i}{n}, \quad i = 1, \dots, d \quad (7)$$

1.2 EM for mixture of multinomials (1 point)

Initially, for each document d , a latent topic c_d is generated as follows:

$$p(c_d = k) = \pi_k \quad \text{where} \quad k = 1, 2, \dots, K \quad (8)$$

Accordingly, given a topic μ_k , the bag of words for d is generated:

$$p(d|c_d = k) = \frac{n_d!}{\prod_w T_{dw}!} \prod_w \mu_{w_k}^{T_{dw}} \quad \text{where} \quad n_d = \sum_w T_{dw} \quad (9)$$

Combining the above two equations gives

$$p(d) = \sum_{k=1}^K p(d|c_d = k)p(c_d = k)$$

$$p(d) = \frac{n_d!}{\prod_w T_{dw}!} \sum_{k=1}^K \pi_k \prod_w \mu_{w_k}^{T_{dw}}$$

E-Step: estimate the responsibilities.

$$\gamma(c_{dk}) = \frac{\pi_k \mathcal{N}(d_n | \mu_k, \sum_k)}{\sum_j \pi_j \mathcal{N}(d_n | \mu_j, \sum_j)} \quad (10)$$

M-Step: re-estimate the parameters. Initially, we have the log likelihood

$$\log p(\mathcal{D}|\theta) = \sum_{k=1}^K \log \left(\sum_j \pi_j \mathcal{N}(d_j | \mu_j) \right) \quad (11)$$

Accordingly, we need to consider this log likelihood as a Lagrangian optimization problem and solve it with respect to π_k and μ_k .

$$L = \sum_{k=1}^K \log \left(\sum_j \pi_j \mathcal{N}(d_j | \mu_j) \right) - \sum_j \lambda(\mu_j - 1) \quad (12)$$

$$\frac{\delta L}{\delta \pi_k} \quad (13)$$

2 PCA (2 points)

2.1 Minimum Error Formulation (2 points)

Assuming that we have a set of complete orthonormal basis $\{\mu_i\}$, where $i \in [1, p]$, we have that $\mu_i^T \mu_j = \delta_{ij}$ and each data point can be represented as $x_n = \sum_i a_{ni} \mu_i$. Accordingly, due to orthonormal property, we can get that

$$a_{ni} = x_n^T \mu_i \quad (14)$$

Inserting this in the data point representation gives

$$x_n = \sum_i (x_n^T \mu_i) \mu_i \quad (15)$$

For this approach, the aim is to formulate PCA as minimizing the mean-squared-error of a low-dimensional approximation of the given basis. Hence, we assume a low-dimensional approximation of the point representation as follows

$$\tilde{x}_n = \sum_i^d z_{ni} + \sum_{i=d+1}^p b_i \mu_i \quad \text{where } b_i \text{ are constants for all points} \quad (16)$$

Therefore, the best approximation is to minimize the following error

$$\min_{U,z,b} J := \frac{1}{N} \sum_{n=1}^N \|x_n - \tilde{x}_n\|^2 \quad (17)$$

Consequently, we have that

$$\begin{aligned} J &= \frac{1}{N} \sum_{n=1}^N \|x_n - \tilde{x}_n\|^2 \\ &= \frac{1}{N} \sum_{n=1}^N (x_n - \tilde{x}_n)^T (x_n - \tilde{x}_n) \\ &= \frac{1}{N} \sum_{n=1}^N x_n^T x_n - 2x_n^T \tilde{x}_n + \tilde{x}_n^T \tilde{x}_n \end{aligned}$$

Inserting equation 10 in the above equation and replacing \tilde{x}_n gives

$$\begin{aligned} J &= \frac{1}{N} \sum_{n=1}^N x_n^T x_n - 2x_n^T \left(\sum_i^d z_{ni} \mu_i + \sum_{i=d+1}^p b_i \mu_i \right) \\ &+ \left(\sum_i^d z_{ni} \mu_i^T + \sum_{i=d+1}^p b_i \mu_i^T \right) \left(\sum_i^d z_{ni} \mu_i + \sum_{i=d+1}^p b_i \mu_i \right) \end{aligned}$$

Accordingly, for minimizing this error, we calculate the derivative with respect to z and b and set it to 0.

$$\begin{aligned}
\frac{\delta J}{\delta z_{nj}} &= \frac{1}{n}[-2x_n^T \mu_j + \mu_j^T (\sum_i^d z_{ni} \mu_i + \sum_{i=d+1}^p b_i \mu_i) + (\sum_i^d z_{ni} \mu_i^T + \sum_{i=d+1}^p b_i \mu_i^T) \mu_j] = 0 \\
\frac{\delta J}{\delta z_{nj}} &= \frac{1}{n}[-2x_n^T \mu_j + 2\mu_j^T (\sum_i^d z_{ni} \mu_i + \sum_{i=d+1}^p b_i \mu_i)] = 0 \\
2\mu_j^T (\sum_i^d z_{ni} \mu_i + \sum_{i=d+1}^p b_i \mu_i) &= 2x_n^T \mu_j \\
\sum_i^d z_{ni} \mu_j^T \mu_i + \sum_{i=d+1}^p b_i \mu_j^T \mu_i &= x_n^T \mu_j \\
\sum_i^d z_{ni} \delta i j + \sum_{i=d+1}^p b_i \delta i j &= z_{ni} + 0 = x_n^T \mu_i
\end{aligned}$$

Giving $z_{ni} = x_n^T \mu_i$ for $i \in [1, d]$. Similarly, we the derivative with respect to b

$$\begin{aligned}
\frac{\delta J}{\delta b_j} &= \frac{1}{n} \sum [-2x_n^T \mu_j + \mu_j^T (\sum_i^d z_{ni} \mu_i + \sum_{i=d+1}^p b_j \mu_i) + (\sum_i^d z_{ni} \mu_i^T + \sum_{i=d+1}^p b_j \mu_i^T) \mu_j] = 0 \\
\frac{\delta J}{\delta b_j} &= \frac{1}{n} \sum [-2x_n^T \mu_j + 2\mu_j^T (\sum_i^d z_{ni} \mu_i + \sum_{i=d+1}^p b_j \mu_i)] = 0 \\
\sum_i^d (\sum_i^d z_{ni} \mu_j^T \mu_i + \sum_{i=d+1}^p b_j \mu_j^T \mu_i) &= \sum x_n^T \mu_j \\
\sum b_j &= N b_j = \sum x_n^T \mu_j \quad \text{giving} \quad b_j = \sum \frac{1}{n} x_n^T \mu_j = \bar{x}^T u_j
\end{aligned}$$

Which in turn gives $b_i = \bar{x}^T u_i$ for $i \in [d+1, p]$. Accordingly, from equation 9, we can get the displacement lines in the orthogonal subspace as follows

$$x_n - \tilde{x}_n = \sum_{i=d+1}^p \{(x_n - \bar{x})^T \mu_i\} \mu_i \quad (18)$$

Which produces the following optimization problem for error J

$$\min_{\mu_j} J \quad \text{where} \quad \mu_i^T \mu_i = 1 \quad (19)$$

Assuming $d=1$ (1-dimensional subspace) and $p=2$ (2-dimensional space), the optimization problem becomes

$$\min_{\mu_2} J = \mu_2^T S \mu_2 \quad \text{where} \quad \mu_2^T \mu_2 = 1 \quad (20)$$

Which gives $S\mu_2 = \lambda_2\mu_2$, meaning that μ_2 should be chosen as the eigenvector that corresponds to the smaller eigenvalue. Accordingly, the principal subspace is chosen by the eigenvector of the larger eigenvalue.

3 Deep Generative Models: Class-conditioned VAE (5 Points)

In the MNIST dataset, there are 10 possible labels for the samples (0-9). Binarizing the labels with the one-hot encoding method, gives a sequence of 10 digits with one 1 and nine 0s. Hence, there could be 10 locations for the 1; the probability of a label l to be one of the 10 labels L would be $p(l = L) = \frac{1}{10} = 0.1$. According to the lecture notes, the variational lower bound for the normal case of VAE was obtained as follows:

$$L(\theta, x) = E_{q(z|x)}[\log p(z, x; \theta) - \log q(z|x)] = E_{q(z|x)}[\log p(x|z; \theta)] - KL(q(z|x)||p(z; \theta))$$

However, it can be noticed that the output of this equation is only dependent on the latent variable z and therefore, does not produce any specific results, which is not practical for our case. Hence, we should modify the lower bound to include the label l of the sample we would like to generate likewise.

$$L(\theta, x, l) = E_{q(z|x, l)}[\log p(x, l|z; \theta)] - KL(q(z|x, l)||p(z; \theta))$$

Since $z \sim \mathcal{N}(0, 1)$ for Gaussian, the KL-divergence is as follows:

$$-KL(q(z|x, l)||p(z; \theta)) = \frac{1}{2}(1 + \log \sigma^2 - \mu^2 - \sigma^2) \quad (21)$$

Consequently, the expected log-likelihood would be

$$E_{q(z|x, l)}[\log p(x, l|z; \theta)] = E_{q(z|x, l)}\left[-\sum_j \frac{1}{2} \log \sigma_j^2 + \frac{(x_{ij} - \mu_{xi})^2}{\sigma^2}\right] \quad (22)$$

Approximating the above equation with Monte Carlo methods gives

$$E_{q(z|x, l)}[\log p(x, l|z; \theta)] \approx \frac{1}{L} \sum_k \log p(x, l|z^{(k)}) \quad \text{where} \quad z^{(k)} \sim q(z|x, l) \quad (23)$$

where $z^{(k)}$ is a random variable, which cannot be used for back-propagation. Hence, by utilizing re-parameterization techniques, we have $z^{(k)} = \mu(x, l) + \sigma(x, l) \cdot \epsilon^{(k)} = g(x, l, \epsilon^{(k)})$, where g is a deep neural network. The lower bound becomes

$$L(\theta, x, l) = E_{p(\epsilon)} \left[\log \frac{p(g(x, l, \epsilon), x; \theta)}{q(g(x, l, \epsilon) | x; \theta)} \right] - KL(q(z|x, l) || p(z; \theta))$$

$$L(\theta, x, l) = \frac{1}{L} \sum_k \log p(x, l | z^{(k)}) + \frac{1}{2} \sum_{i=1}^j [1 + \log \sigma^2 - \mu^2 - \sigma^2]$$