OIN13-01



Phoenix

A Multi-Purpose UAV with a highly efficient airframe, backed with a progressive web app

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Current UAV Eco-System







- Battery Inefficiency
- Air Time and Range
- Infrastructure



We built

- Landing Website
- Functional VTOL UAV
- ArduPilot Navigation Simulator
- ArduPilot UAV Tracking
- Delivery Management Website





Our Progress in the last 15 hours



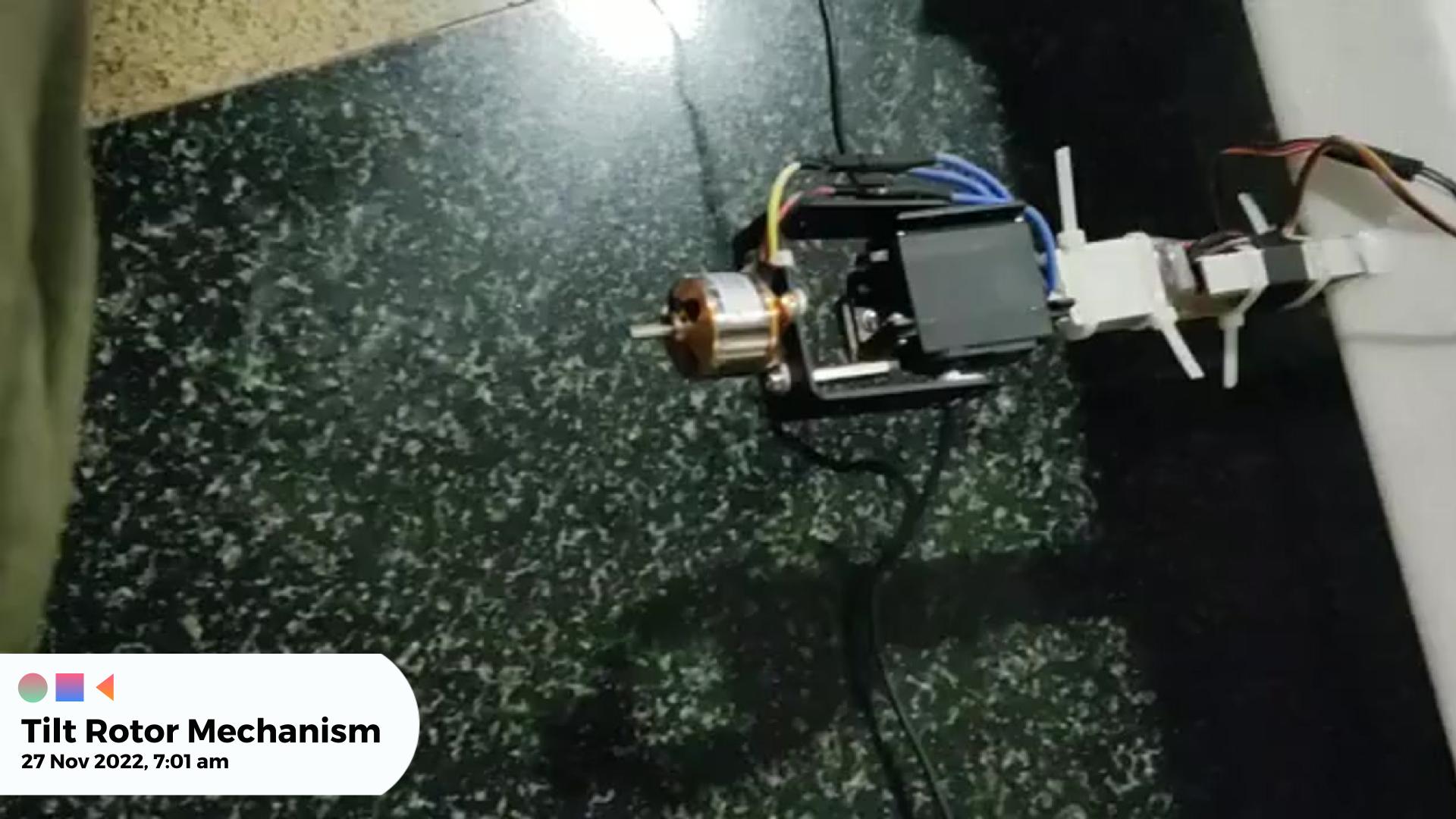














Additions/Features to be added to the prototype

- Focus on modularity
- Payload Delivery System
- Calibration
- Live Tracking and Surveillance
- Automated Navigation
- User Friendly Interface



Major Use Cases include

- Healthcare
- Military
- Mapping/Surveillance
- Delivery Systems