

# Machine Learning (CE 40477)

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## 1 Batch Normalization

## 2 MLPs as Universal Approximators

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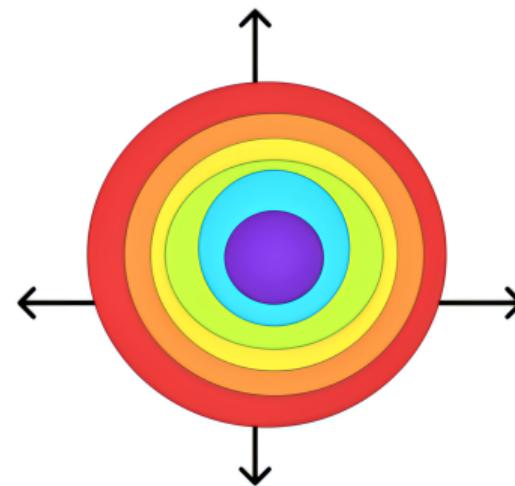
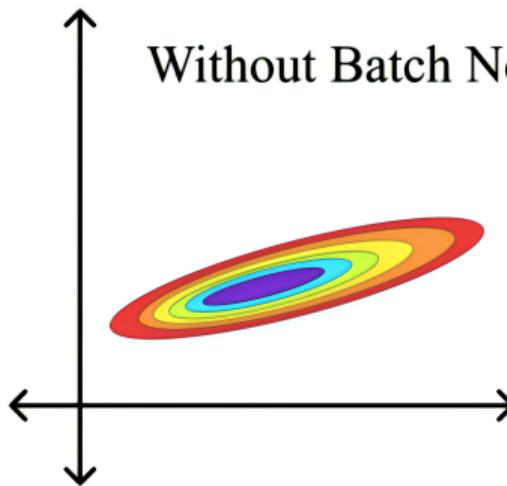
## What is Batch Normalization Concept?

- The main purpose of Batch Normalization: **Smoothing the optimization space**
  - Batch Normalization works with normalizing activations in a network.

## Smoothing the optimization space

## With Batch Norm

## Without Batch Norm



## 1 Batch Normalization

Batch Normalization introduction

**Why Batch Normalization?**

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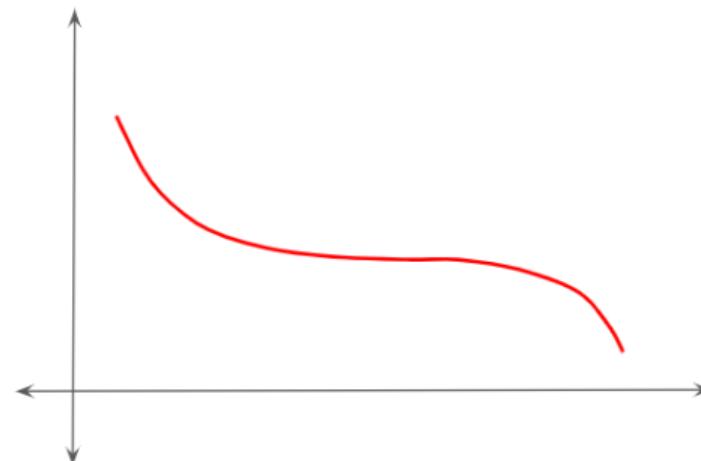
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# Why Batch Normalization?

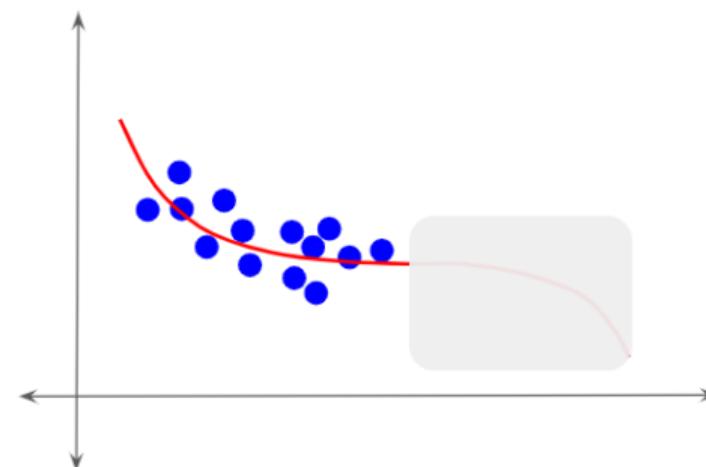
## Problem: Internal Covariate Shift

- What does it mean, in simple terms?
- Let's say that we want to train a model and the ideal target output function that the model needs to learn is as below:



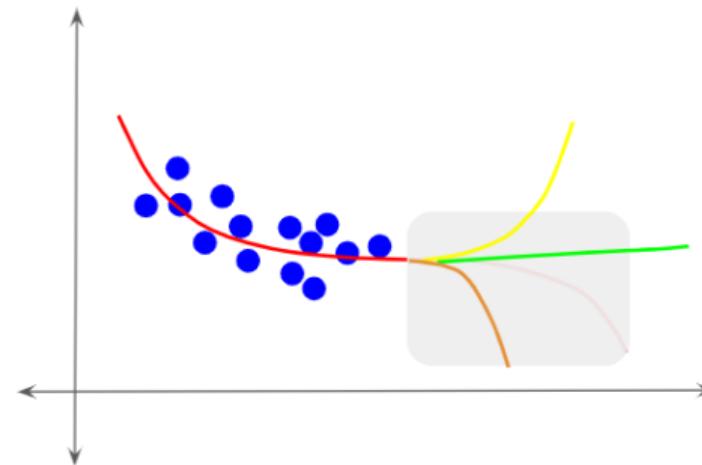
## Problem: Internal Covariate Shift

- Suppose that the training data values input to the model cover only a part of the range of output values. Therefore, the model can only learn a subset of the target function.



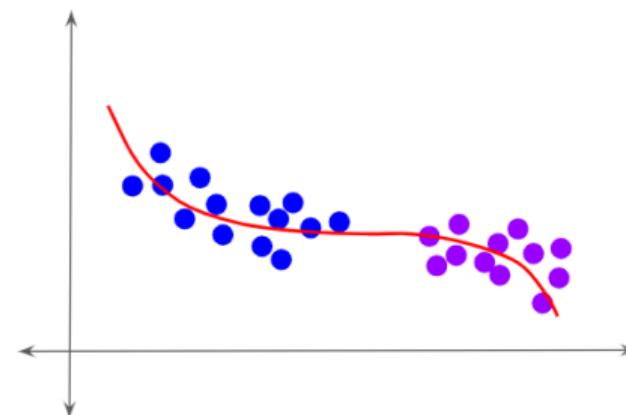
## Problem: Internal Covariate Shift

- The model has no idea about the rest of the target curve. It could be anything.



## Problem: Internal Covariate Shift

- Suppose we feed the model to the testing data as below.
- This has a very different distribution from the data that the model was initially trained with.
- The model cannot simply generalize its predictions for this new data.



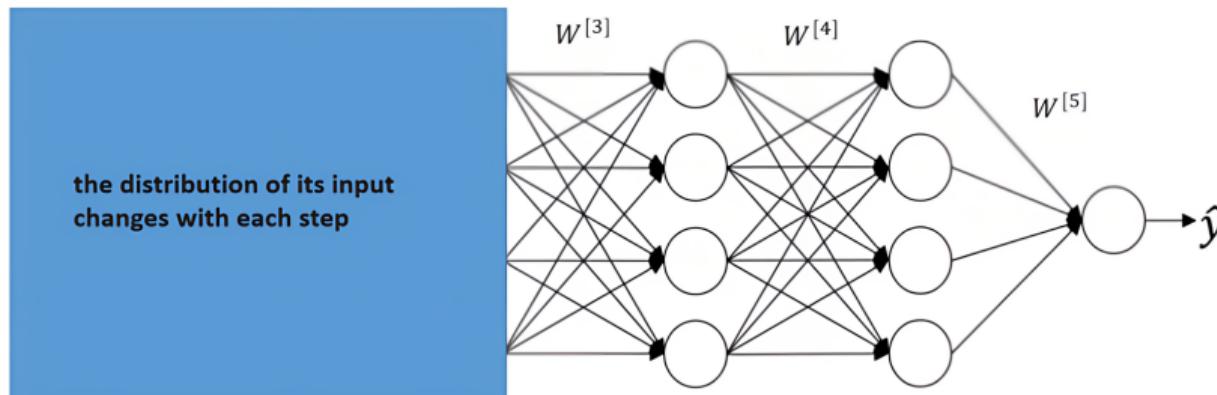
## Problem: Internal Covariate Shift

- Covariate Shift occurs when **the model is fed data with a different distribution than what it was previously trained with**, even though that new data still conforms to the same target function.
- For the model to figure out how to adapt to this new data, it has to re-learn some of its target output functions.
- **This slows down the training process.**

## Problem: Internal Covariate Shift

### What happens inside Deep Network Layers?

- Consider what happens when training a deep network: As we update the weights of earlier layers, the data distribution in the deeper layer keeps shifting.
- Deeper layers see new and varying patterns every time we update the weights in previous layers.



## Problem: Internal Covariate Shift

### What happens inside Deep Network Layers?

- The network must keep readjusting, which makes the learning process slower and more challenging.
- **In other words:** The network is constantly “re-learning” how to make predictions because the data it sees is never consistent.

# Batch Normalization Solution

- **Goal:** Normalize inputs so that the mean is near 0 and the variance is close to 1.
- **How it helps:** Stabilizes learning, allowing for higher learning rates and faster convergence.

## Batch Normalization Solution

- What's the link between Batch Normalization and this picture?



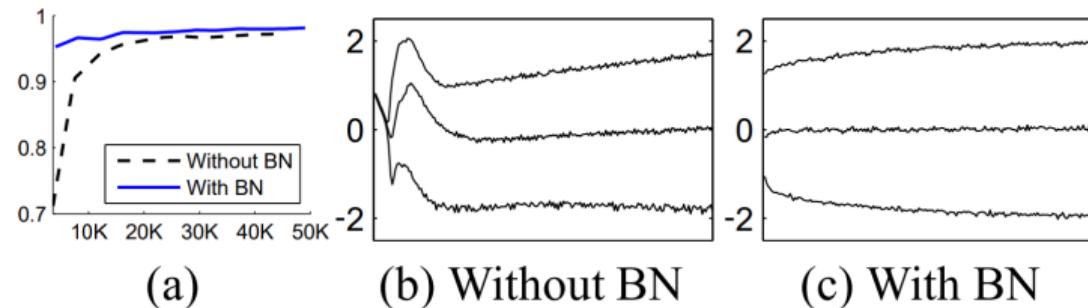
# Batch Normalization Solution

- The two faucets represent two separate control mechanisms—like the mean and variance adjustments in Batch Normalization—working together to keep the flow (activations) at an optimal, consistent range, preventing extreme values (too hot or too cold) that can disrupt learning.



## Effect of Batch Normalization

- Batch Normalization helps the network train faster and achieve higher accuracy.
- Batch Normalization **stabilizes the distribution** and reduces the internal covariate shift.



**Figure 1:** (a) The test accuracy of the MNIST network trained with and without Batch Normalization, vs the number of training steps. (b, c) The evolution of input distributions to a typical sigmoid, for training, shown as 15, 50, 85th percentiles [1].

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# How Batch Normalization Works

## Process Overview

- For each mini-batch during training, batch normalization normalizes the inputs to a layer by adjusting their mean and variance.

# How Batch Normalization Works

## Steps in Batch Normalization

### ① Compute the Mean and Variance

For a given mini-batch, compute the mean  $\mu_B$  and variance  $\sigma_B^2$  of the inputs:

$$\mu_B = \frac{1}{m} \sum_{i=1}^m x_i, \quad \sigma_B^2 = \frac{1}{m} \sum_{i=1}^m (x_i - \mu_B)^2$$

### ② Normalize the Inputs

Subtract the mean and divide by the standard deviation to get normalized activations:

$$\hat{x}_i = \frac{x_i - \mu_B}{\sqrt{\sigma_B^2 + \epsilon}}$$

where  $\epsilon$  is a small constant added for numerical stability.

# How Batch Normalization Works (Continued)

## Steps in Batch Normalization

### ③ Scale and Shift

After normalization, introduce learnable parameters  $\gamma$  and  $\beta$  that allow the model to scale and shift the normalized output:

$$y_i = \gamma \hat{x}_i + \beta$$

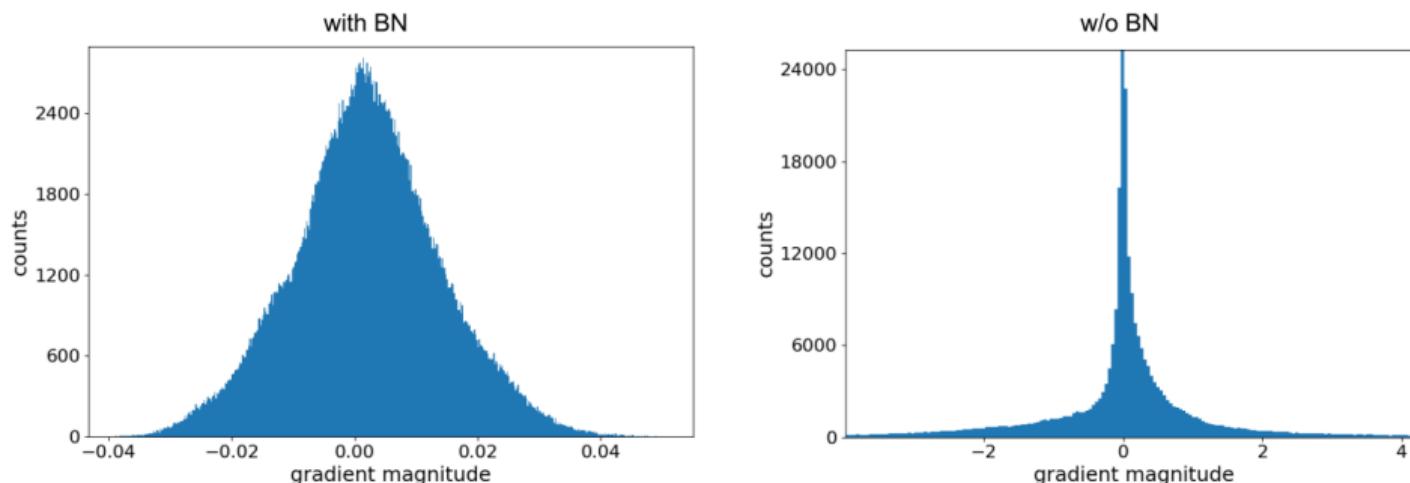
This allows that the model to recover the original data distribution if necessary.

# How Batch Normalization Works

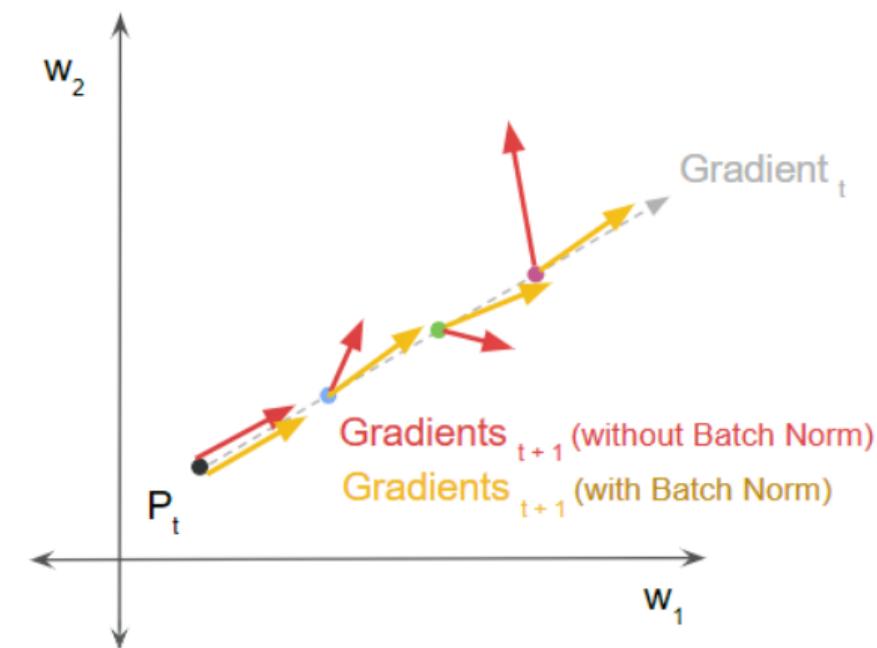
## Inference Mode:

- During inference (when predicting new data), batch statistics (mean and variance) are replaced with moving averages collected during training.

# Effect of Batch Normalization on Gradients



# Effect of Batch Normalization on Gradients



## Effect of Batch Normalization on Gradients

The main benefit of batch normalization is that it reduces the dependency of gradient on the scale of input and parameters:

$$\frac{\partial \mathcal{L}}{\partial x} = \frac{\partial \mathcal{L}}{\partial y} \cdot \frac{\partial y}{\partial \hat{x}} \cdot \frac{\partial \hat{x}}{\partial x} \quad (1)$$

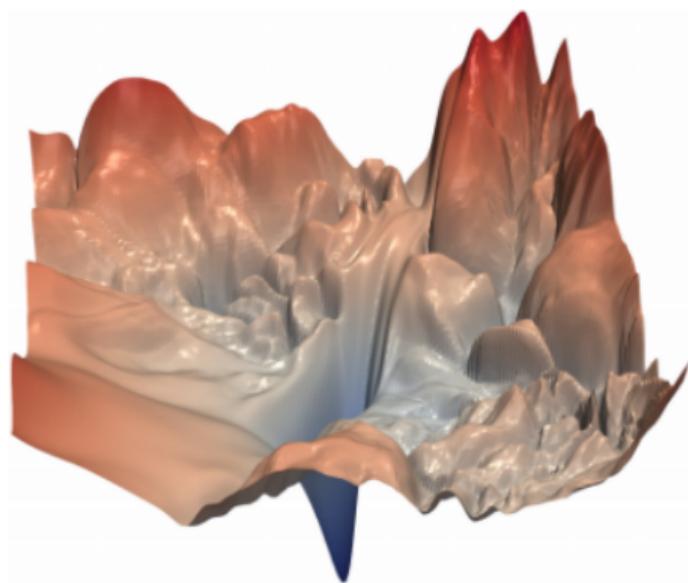
Where:

- $\frac{\partial y}{\partial \hat{x}} = \gamma$
- $\frac{\partial \hat{x}}{\partial x} = \frac{1}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}}$

Thus, the gradient becomes:

$$\frac{\partial \mathcal{L}}{\partial x} = \frac{\gamma}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}} \cdot \frac{\partial \mathcal{L}}{\partial y} \quad (2)$$

# Loss Landscape is not Smooth in Typical Neural Networks



## How Batch Normalization Smooth the Loss Landscape

The smoothing effect of batch normalization can be understood by observing how it constrains the gradient magnitudes. The expression shows that:

$$\frac{\partial \mathcal{L}}{\partial x} \text{ is scaled by } \frac{1}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}} \quad (3)$$

This consistent scaling results in a smooth loss landscape because:

- It stabilizes the gradient flow, ensuring controlled optimization step sizes.
- Reduces the risk of large oscillations or abrupt changes in the loss landscape.
- Makes the optimization process less likely to be trapped in local minima or saddle points.

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# Batch Normalization Pros

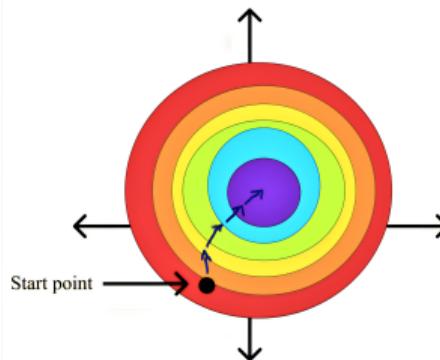
## Pros

- **Faster Convergence:** Empirical results support that models with batch normalization converge faster and achieve higher accuracy, even with higher learning rates.
- **Reduced Sensitivity to Weight Initialization:** Mitigate the dependency on careful weight initialization.
- **Acts as Regularization:** Batch normalization can help reduce overfitting.
- **Reduces Vanishing/Exploding Gradients:** Maintains stable gradients throughout deep networks.

## Batch Normalization Pros

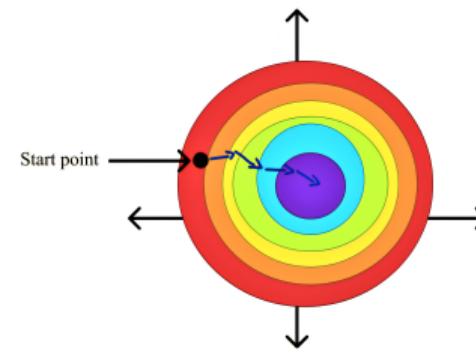
### Why Using Batch Normalization Reduces Sensitivity to Weight Initialization?

With Batch Norm



(a)

With Batch Norm



(b)

## Batch Normalization Pros

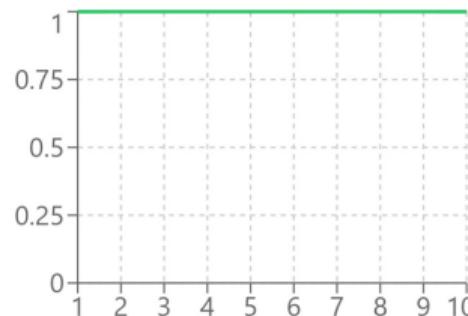
### Why Does Batch Normalization Reduce Sensitivity to Weight Initialization?

- Batch normalization smooths the optimization landscape, reducing the dependency on initial weights.
- This allows the model to converge to a minimum efficiently, **regardless of where optimization begins.**

## Batch Normalization Pros

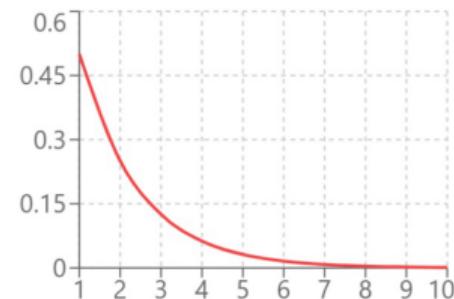
**Batch Normalization Reduces Vanishing/Exploding Gradients:** Helps maintain stable gradients throughout deep networks.

With Batch Normalization



Gradients remain more stable throughout the network

Without Batch Normalization



Gradients decay exponentially, leading to vanishing gradients in deeper layers

# Batch Normalization Cons

## Cons

- **Batch Size Sensitivity:** Performance may depend on batch size. Very small batches potentially provide unstable statistics.
- **Computational Overhead:** Increases computational-overhead during training.
- **Behavior During Inference:** Switching from batch statistics to moving averages during inference may cause slight discrepancies.

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# Batch Normalization in Practice

## Where to Apply

- **Typical Location:** Apply after the linear transformation (e.g., after a dense or convolutional layer (You will learn about it in the next chapter)) and before the activation function.
- **Layer Placement:**



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# Batch Normalization in Practice

- **Key Point:** Batch normalization stabilizes and accelerates training while offering regularization benefits.
- **Impact on Training:** Facilitates efficient training of deeper networks with less hyperparameter tuning.

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# Universal Approximation Theorem

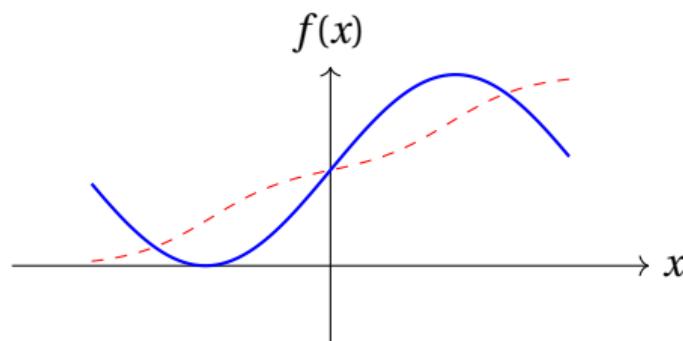
## Key Concept

- The Universal Approximation Theorem states that a feedforward neural network with:
  - A single hidden layer
  - Sufficient number of hidden neurons
  - Appropriate activation functions (e.g., sigmoid)

Can approximate any continuous function on a compact subset of  $\mathbb{R}^n$  to any desired accuracy.

# Visual Intuition

- Each neuron creates a "bump" in the function space



- Multiple neurons combine to approximate complex functions
- More neurons = finer approximation

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## 3 References

- [1] S. Ioffe and C. Szegedy, “Batch normalization: Accelerating deep network training by reducing internal covariate shift,” *CoRR*, vol. abs/1502.03167, 2015.
- [2] A. Ng and K. Katanforoosh, *CS230 Lecture Notes*.  
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- [3] F.-F. Li and Z. Durante, *CS231n Lectures*.  
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- [4] J. Bjorck, C. P. Gomes, and B. Selman, “Understanding batch normalization,” *CoRR*, vol. abs/1806.02375, 2018.
- [5] H. Li, Z. Xu, G. Taylor, and T. Goldstein, “Visualizing the loss landscape of neural nets,” *CoRR*, vol. abs/1712.09913, 2017.

# Any Questions?