

Type checking/inference for a sequential language

SPA Ch 2/3

① define C-like language

② define a type inference algorithm

program $P \rightarrow F \ F \ F \ \dots \ F$

function $F \rightarrow X(X, \dots, X) \{ \text{var } X, \dots, \text{var } X; \\ S; S; \dots; S; \\ \text{return } E \}$

statement $S \rightarrow X = E$
| if (E) { S; ...; S } else { S; ...; S }
| while (E) { S; ...; S }
| *X = E

expressions $E \rightarrow I$ integer

| X

| E + E | E - E | E * E

| E == E | E > E

| X(E, ..., E)

| null

| &X | *E | alloc E

e.g.

```
iterate (n) {  
    var f;  
    f = 1;  
    while (n > 0) {  
        f = f * n; n = n - 1;  
    }  
    return f;  
}
```

What should our type system catch?

Arithmetic operations are over int
conditions of if/while are int
"main" should only return int
* only applies to pointers
arguments to a function are
of correct type

$T \xrightarrow{\text{::}} \text{int}$
 $| \&T$
 $| (T, \dots, T) \rightarrow T$

$T \rightarrow T \rightarrow T \rightarrow \dots T$

e.g. int
&int
&&int
(int, int) → &int

constraints

$S = T$

$[\cdot]$ type variable

$[]$ for simplicity

e.g.

$[1 + \text{foo}] = [x]$

$x = 1 + \text{foo}$

I e.g. 10
[10] = int

[1] = int

$E_1 == E_2$

$[E_1] = [E_2]$ and $[E_1 == E_2] = \text{int}$

$E_1 \text{ op } E_2$

$[E_1 \text{ op } E_2] = [E_1] \text{ op } [E_2] = \text{int}$

↙ arithmetic expression

$X = E$

$[X] = [E]$

if (E) { S...S } else { S...S }

$[E] = \text{int}$

while (E)

$[E] = \text{int}$

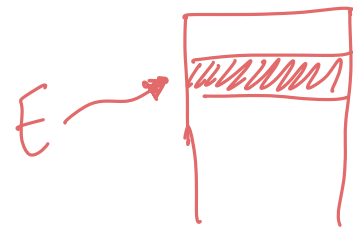
$X(X_1, \dots, X_n) \{ \dots \text{return } E \}$

$[X] = ([X_1], \dots, [X_n]) \rightarrow [E]$

alloc E

$[\text{alloc } E] = \&[E]$

$[\text{alloc } 10] = \&\text{int}$
 $= \&[10]$
 $[10] = \text{int}$



$\&X$

$[\&X] = \&[X]$

$*E$

$[E] = \&[*E]$
 $[*E] = Y$

equivalent

$[E] = \&Y$
 $[*E] = Y$

$\rightarrow E$ has to be an address
 \rightarrow what is in this address
int?
Bool?
another address?

$$*X = E$$

$$[X] = \&[E]$$

$$\boxed{\begin{array}{l} [X] = \&Y \\ \underline{Y = [E]} \end{array}}$$

null

$$[null] = \&Y$$

e.g. $Start() \{$

var $x, y, z;$

$x = 1;$

$y = \text{alloc } x;$

$*y = x$

$z = (*y)$

return $z;$

$\}$

$Start: () \rightarrow \text{int}$

$[start] = () \rightarrow [z]$

$[1] = \text{int}$

$[\text{alloc } x] = \&[x]$

$[x] = [1]$

$[y] = [\text{alloc } x]$

$[y] = \&[x]$

$[z] = [*y]$

$\&[*y] = [y]$

$[x] = \text{int}$

$[y] = \&\text{int}$

$[z] = \text{int}$

e.g. $f() \{$

var $x;$

$x = \text{alloc } 17;$

$x = 42;$

return $x + 12;$

$\}$

$[x] = \&\text{int}$
x

$[x] = \text{int}$

flow insensitive
type system

e.g

```
baz() {  
  var x;  
  x = 1;  
  return &x;  
}  
  
main() {  
  var p;  
  p = baz();  
  *p = 1;  
  return *p;  
}
```

baz : () → &int

[p] = &int

Rust

(lifetime)