



ROYAL HOLLOWAY UNIVERSITY OF LONDON

PH4100: MAJOR PROJECT

Meshing of Primitive Solids in Pyg4ometry & BDSIM

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Abstract

The testing and analysis of radiation travelling through geometries of devices, such as a medical magnets, spacecraft or new particle accelerators, is often a very expensive and time consuming process. The open-source software packages Pyg4ometry & BDSIM are designed to enable scientists and people within many different industries to virtually simulate these tests, with accurate physics concepts. This project looks at improving the 3D simulation of the events and devices, by the remeshing of the basic primitive solids and testing them in BDSIM.

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1 Introduction

1.1 Report Structure

The following subsections of the introduction will go on to discuss the background (sec. 1.2), motivations (sec. 1.3) and aims (sec. 1.4) of the project. Then the subsequent sections are structured in the following way; first a summary of the software packages that are used and referenced throughout this report are discussed in sec. 2, the concepts and details of the primitive meshing used in Pyg4ometry (sec. 3). The interactions of meshed solids and objects in BDSIM (sec. 4) and a conclusion and summary of the results of the report (sec. 5). Followed by an Appendix A.1, which lists a variety of content produced in the project, but is not included in the report its self, in the interest of being incise. All the diagrams in this report are drawn using the CAD software Inkscape, unless otherwise referenced.

1.2 Project Background

1.2.1 Types of Radiation Emission

Radiation is the transport of energy through matter or a vacuum in the form of electromagnetic waves and/or particles. There are two main categories of radiation emission; ionising and non-ionising. Non-ionising (or NIR) can be harmful if exposed to for long periods of time or in high intensities, such as UV light can cause skin cancer or shining a strong laser into an eye can cause blindness. In order for a type of radiation to be ionising it must be an electromagnetic wave or particle with enough energy to "ionise" a neighbouring atom, typically travelling at a velocity greater than 1% the speed of light. "Ionisation" is the process of detaching an electron from an atom or molecule. This report only focuses on forms of ionising radiation as they are the ones more commonly associated with particle interactions.

Bremsstrahlung is the electromagnetic radiation, which is typically in the form of a photon, created as the result of a charged particle decelerating after it has been deflected from another charged particle. The larger the loss in kinetic energy, i.e the greater the deceleration of the initial particle, the larger the frequency of the emitted photon. Medical X-ray tubes rely on Bremsstrahlung to create a continuously emitted spectrum. The X-ray tubes work by using an electric field to accelerate electrons within a vacuum, which is then aimed towards a target, such as a broken arm against a photographic absorber.

Cherenkov radiation is important within nuclear reactors and is the reason why submerged reactors often appear to glow blue [25]. The blue colour is due to the radiating particles traveling faster than the speed of light in the same medium, acting in the same fashion as a sonic boom. The reactors are typically submerged in water and it is the change of medium as the particle enters the water, which causes the Cherenkov radiation. As the particle propagates through the water it creates continuous moving source of radiation in the blue visible spectrum. The blue colour is very faint and can only really appear at high energies, such as the ones found in nuclear reactors.

On Earth we experience harmless radiation everyday, for example small doses of UV (or UltraViolet) radiation from the Sun. However in many cases radiation is unwanted and/or needs to be controlled, which is why the simulations of radiation transport needs to be considered. Radiation transport is the physical phenomenon of energy transfer through a medium in the form of electromagnetic radiation. The various types of radiation are discussed in sec. 1.2.1. There is a large number of sectors that the simulation of particle radiation tracking is an invaluable tool.

1.2.2 High Energy Physics

The most obvious field in which radiation transport is important is all things nuclear and particle physics, i.e nuclear reactors, weapons and accelerators (accelerators being the main focus in this project), which all typically involve high energy physics. There are many types of radiation that need to be carefully taken into account in order to minimise unwanted damage to instruments and the people operating them. Nuclear reactors rely on fission which occurs via ionising radiation in the form of free neutrons. The free neutrons begin a chain reaction by interacting with nuclei making them unstable,

causing a further a neutron to be emitted and ionise another nuclei. Particle accelerators work by accelerating charged particles up to high energies using electric fields and the uses magnetic fields to steer the particle beam. The cost of construction and upgrades for accelerators and nuclear power plants are extremely high, therefore Computer Aided Design (CAD) and simulations can be very helpful with the planning of new sites and concepts.

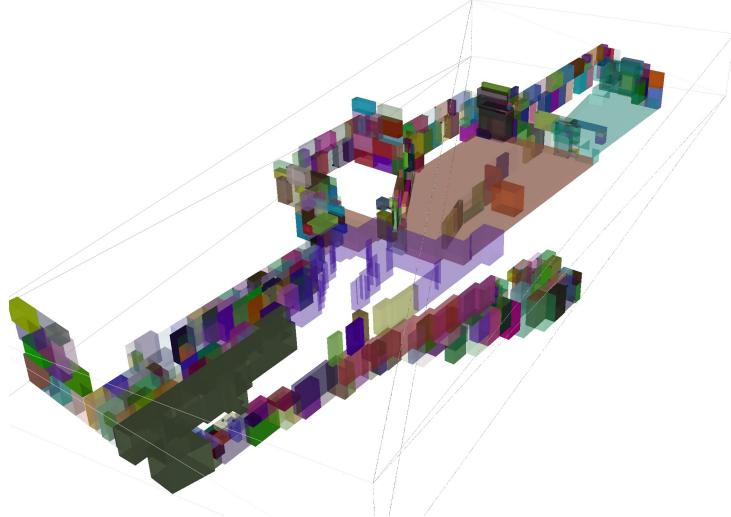


Figure 1: Converted CAD file (STEP to GDML) of the shielding at CERN East Areas T8 to T11 test beam lines, from Source [9].

Fig.1 shows a CAD model of the shielding used in a section of the east area at CERN (or The European Organization for Nuclear Research translated from French) home to the LHC (or Large Hadron Collider). The use of particle transport simulation can also be used as a tool for simulating beam losses [9], which can be applied for experiments such as machine protection, efficiency tests and machine optimisation.

1.2.3 Space Exploration

Space exploration is also a large field where radiation transport and shielding is a key concept that must be accounted for. Beyond the Earth's atmosphere the universe is full of harmful GCR (Galactic Cosmic Rays) radiation and stellar material making the shielding of spacecraft and astronauts a major priority. Traditionally protection against unwanted radiation has involved placing an absorber in between the target and the source. The shielding for a spacecraft is typically made from an aluminium alloy, studies have been simulated the effectiveness of Al_2O_3 as space craft shielding [3], taking into account properties of the alloy such the stopping power.

However, for the case of astronauts the size of the required absorber is extremely large and unpractical and will likely cause showers of more harmful secondary radiation. Therefore the use of magnetic fields is being investigated as a way to divert the charged electromagnetic radiation away from a target apposed to stopping it [6]. This is something which can also be simulated in Monte Carlo software with the inclusion of electric & magnetic field maps.

1.2.4 Medical

Another essential field which radiation transport simulation is required in is medical treatment. X-ray radiation from vacuum tubes is not only used to check for fractures or breaks in bones, it also used in radiotherapy. The X-rays are used to target unwanted growths in the body through small doses of harmful radiation, with the aim of removing cancerous tissue with minimum damage to the neighbouring organs. This can be especially difficult when the tumor is in the vicinity of organs that move

within the body, such as the lungs. As the patient needs to breath in order to live, the movement of the organs needs to be accounted for when aiming the particles.

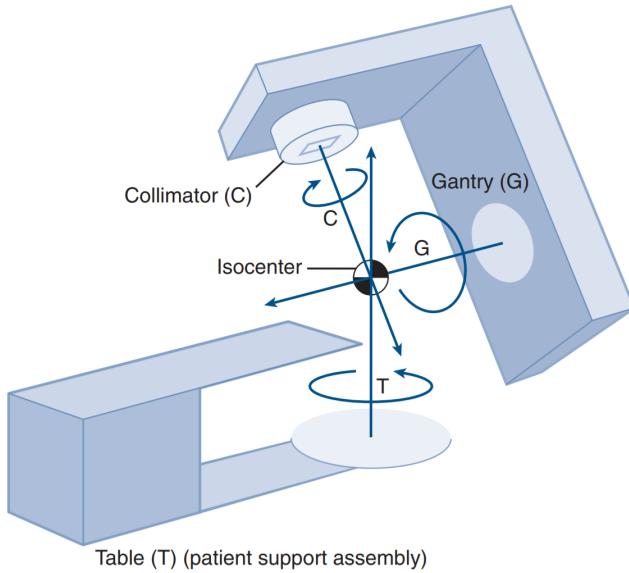


Figure 2: A gantry-based radiation therapy machine, from Source [21].

A patients' organs also move with the body's orientation with respect to gravity therefore the patient must be positioned laying down on a table that rotates perpendicular to the direction of gravity. The gantry unit must then rotate around the patient to imitate the most stationary conditions. An example machine can be seen in fig.2, where patients would be placed on the table to undergo treatment by radiotherapy, the isocenter being the optimal target position of the cancerous cells to be in within the patients body. A more recent type of radiotherapy is proton therapy, which involves the use of small particle accelerators. The use of the word small being relative to size of typical particle accelerators like the LHC.

1.3 Project Motivations

Historically it has been very hard to simulate particle radiation through matter correctly, being both expensive and time consuming. As computer technology has developed through recent years particle physicists have began building models to simulate these radiation events, employing techniques such as the Monte Carlo method. Currently many independent industries all require the ability to conduct radiation transport simulations, but use different methodologies of storing geometries, which come in the form of different file formats. The use of different file formats is where one of the biggest problems lie, as many software tools for simulating radiation transport are format specific and require complex file conversions.

The motivation of the project is to study the efficiency of tessellated solids, where a tessellated solid is a 3D shape whose surfaces are mapped using 2D geometric shapes. Pyg4ometry is a tool created to easily convert between these representations in different formats and allow a wider audience to utilise these radiation tracking softwares. GUImesh is a similar python package for converting STEP files into GDML format [16].

1.4 Project Aims

Simulating radiation transport requires a 3D description of the target formation, detailing its structure, dimensions and material properties such as density. These 3D models contain elements and volumes

which can not overlap, leading to most radiation transport geometries being made by hand. These types of aims are possible in software such as Pyg4ometry. The geometries produced in Pyg4ometry can then be simulated in other packages such as BDSIM. The underlying libraries of BDSIM, which contribute towards the simulation properties such as the tracking, fields and material physics, arises from GEANT4, which are all discussed in later sections.

The aims of this project are to contribute towards the optimization of the Pyg4ometry package (sec. 2.3) and subsequently BDSIM (sec. 2.2), by improving parts of the code and conducting performance tests to produce results that can be analysed. The main areas for improvement and where most of the computational energy is wasted, is in the meshing of the primitive GEANT4 (sec. 2.1) compatible solids. The inefficient computation is primarily due to the unnecessary use of boolean operations (sec. 3.3.2). The first part of the project focuses on the meshing of the primitive solids (sec. 3) within Pyg4ometry. Within constructive solid geometry (CSG) a primitive solid is a simple geometric solid such as cube, pyramid, sphere or torus. By looking at the comparison of methods and techniques of producing these tessellated meshes for primitive and compound solids. The second part of the project focuses on the performance of the meshes within BDSIM. Investigating the effects of material and particle energy, on the duration of interactions within a solid.

2 Software Packages

This section outlines the key details of each package, describing its function and link to the project. At the time of the project a lot of the prerequisite packages were only compatible with Linux Operating Systems (OS) and no docker images were available. Due to owning a machine that operated on windows, the project was then completed on a Linux laptop (a 2011 Apple MacBook Pro running OS El Capitan) from the department. The setting up of virtual machines running Centos 7 (standard free Linux OS used by CERN [5]) was also attempted, however despite getting it successfully setup, the packages were not performing to the same standard as they were on the fellow Apple MacBooks. This legacy OS on the loaned laptop came pre-installed with the some of the required packages, and allowed for easy installation of outstanding backdated versions.

2.1 GEANT4

GEANT4 (or GEometry ANd Tracking) ?? is a toolkit developed in C++ for the simulation and tracking of particles traveling through matter by employing the Monte Carlo method (sec. 4.1). It is used by many particle physicists and is one of the more popular packages used to create 3D models of experiments for Monte Carlo simulations. GEANT4 has its own preset primitive solids that are used for simulating particle interactions and can be found within the online manual [14]. The naming convention of the solids being used in this project and within this report are the ones used by GEANT4. GEANT4 also has a large inbuilt database which contains the properties of most materials and particles. An alternative transport code is FLUKA (or FLUktuierende KAskade) [1], which also uses Monte Carlo to simulate high energy physics. GEANT4 can and has also been used to conduct dose calculations for radiotherapy patients [24] as well as many other simulations around particle losses and background radiation [17]. The materials used throughout this project are from the GEANT4 database [15]. In this report the three main materials used are Tungsten, Titanium and Vacuum (*G4_W*, *G4_Ti* and *G4_Galactic*). The use of *G4_Galactic* is arguably the most important as it is used to set the material of the world environment in which other objects are placed into.

2.2 BDSIM

BDSIM (or Beam Delivery SIMulation) [12] is an open-source software package also written by JAI at Royal Holloway, for the use of modelling particle beam interactions. The package is written in C++ and has many applications, such as modelling complex particle accelerators like the Large Hadron Colider (LHC) or low energy magnetic beamlines for radiotherapy applications used to treat tumours.

BDSIM allows a user to specify the physics being used for a particular particle interaction, such as the particle energy and the number of secondaries produced. BDSIM works by intaking a simple asci file with its own extension (GMAD), where the simulation and model can then be controlled by the GMAD's parameters. One of these parameters is the “worldMaterial”, which defines the material of the environment that other elements and volumes are placed into. By default the world material in BDSIM is set to be air, which means the particles would interact before passing into the object being tested, this can be avoided by using the option *worldMaterial* = “*G4_Galactic*” within the GMAD files, where *G4_Galactic* is the GEANT4 vacuum material as mentioned before (sec. 2.2). Other properties for each GEANT4 material are also used in this project, such as the stopping power (sec. 4.4.1).

Although the BDSIM’s defaults build up a standard geometry beamline, often specialised pieces of geometry are needed to accurately simulate interactions. This can be done by supplying an external GDML file, where its placement in the simulation can be specified in the GMAD. The scattering of the particle trajectories and decays are computed using Geant4’s Monte Carlo calculations, to make the results as consistent with experimental data as possible. The software outputs a root file contain all the required information. As many particles as desired can be simulated in batch mode, however a GUI is available to view the geometry, but is rarely used to simulate the particle accelerators as it is computationally expensive.

Inside 3D interactive environment within the GUI, BDSIM uses the discrete colouring convention of tracks to represent a particles charge inherited from GEANT4, where green a green track is neutral, blue is positive and red is negative, which can be seen in figures throughout this paper such as fig. 4. The option “physicsList” defines the physics which is used for the interaction, for the project the option was set to “g4FTFP_BERT”, which contains all the standard electromagnetism and particle physics required for this project. The physics can be used to chose the desired types of radiation emission and interactions taken into account for a given event. The outputted ROOT files contains a detailed analysis of the interaction. One of the elements analysed within this project is the CPU duration time distribution of an interaction in BDSIM.

2.2.1 Pybdsim

BDSIM has a python utility library called Pybdsim which provides an interface to be automate BDSIM and read its output files for data processing using python scripts. Pybdsim also allows for the navigation of ROOT analysis files to extract data to plot, mentioned more in sec. 2.4. This is how all the plots in sec. 3 & sec. 4 are generated.

2.3 Pyg4ometry

Pyg4ometry is an open-source python package, developed by the John Adams Institute (JAI) at Royal Holloway [8], its purpose is to convert 3D CAD (Computer Aided Design) geometries between different representations to allow compatibility with BDSIM (sec. 2.2) for the simulation of radiation transport [9]. The “4” in “Pyg4ometry” comes from the fact Pyg4ometry has been written to design geometries specifically for GEANT4 (sec. 2.1). The package is a key tool for allowing multiple file formats, such as STEP/STL or IGES files to be converted into GDML files, which are the compatible format for BDSIM. GDML (or Geometry Description Markup Language) is a format based on a XML file type. The range of file compatibility increases the number of people who can utilise both Pyg4ometry and BDSIM, as many industries use different file formats to store their 3D CAD geometries.

Pyg4ometry can also be used to determine if a model has any geometric overlap and provides faster loading for CAD geometries into BDSIM compared with the full GEANT4 C++ application. Most of the development in this project is conducted in Pyg4ometry. As of January 2020 the first CentOS 7 docker image for Pyg4ometry is now available in the source code repository. The package is currently written in and only supports python 2.7, however as of January 2020 developer support for python 2 has been discontinued as the newer version python 3 is taking over. The transition to python 3 means

adjusting the syntax of several functions and files in Pyg4ometry, this has began, but a full transition will take sometime as it is not an immediate priority.

2.4 ROOT

ROOT is not an acronym and is named after the idea, that it is a system for other systems to grow off of, much like a root of a tree that has many branches. ROOT is adopted by many physics communities such as CERN [5], where it was first written. Naturally making it a popular format for particle physicists in particular and is the why it is the default output for analysis by BDSIM. Despite ROOT storing data in the format of its own plots, no ROOT files or plots are shown in the report, as the data has been extracted from the root files and replotted using Pybdsim 2.2.1 and Matplotlib. The plots are made this way as the data can be more easily manipulated and the formatting of ROOT plots is more complex than with a simple python script, of which a few standardised examples in Pybdsim.

2.5 FreeCAD

In this report the libraries from FreeCAD 0.18 [26] are used directly within Pyg4ometry (sec. 2.3), without the use of the FreeCAD Graphical User Interface (GUI). The libraries are used to import STEP, files and to convert them into triangular based tessellated meshed solids, that can then be written out as a GDML file. As an exercise at the beginning of the project a few example CAD STEP files were downloaded from the internet and converted into meshed GDML files. One of the CAD models converted was a GPS satellite, which can be seen in fig.3. FreeCAD itself can also be used to create CAD models that can then be tested in BDSIM, an example magnet shown in appendix D.

2.6 Visualisation

Most of the packages mentioned above have their own GUI's to visualise the meshed geometries. However the main two GUI's used in this project are the ones used by Pyg4ometry and BDSIM. VTK (or Visualization ToolKit) is an open-source software for displaying and manipulating scientific data [2]. Pyg4ometry uses VTK, shown in fig.3, to create its 3D interactive GUI. BDSIM uses GEANT4's GUI (as seen in fig.4), which is another reason Pyg4ometry aims to be consistent with GEANT4. Both the VTK and GEANT4 GUI's allow meshed solids to be viewed as solids or as meshed structures. The GEANT4 GUI has its own console in which commands can be carried out, allowing the simulation to be altered from within the GUI as well as by Pybdsim.

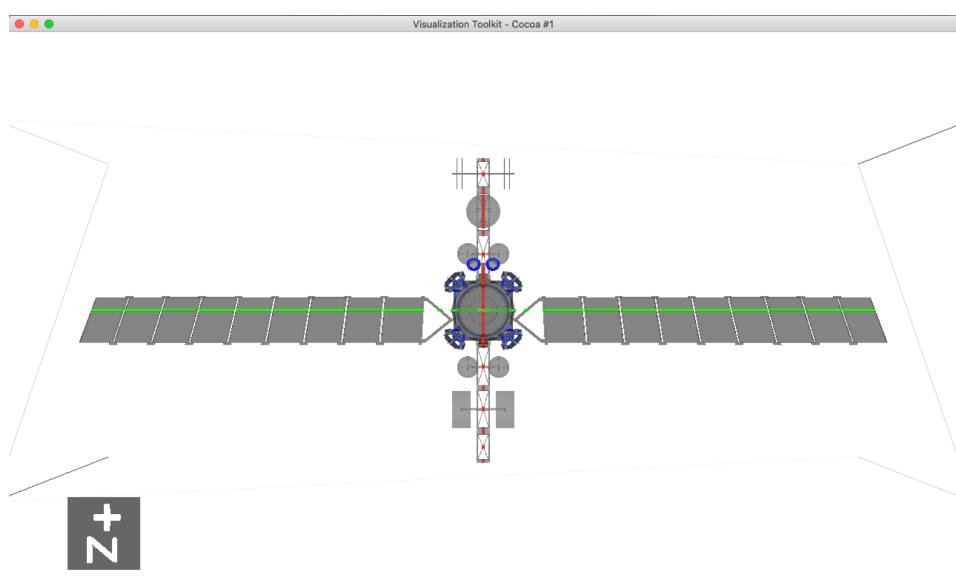


Figure 3: STEP file of a GPS satellite imported into Pyg4ometry using the FreeCAD libraries and viewed in VTK. Original STEP file from Source [4].

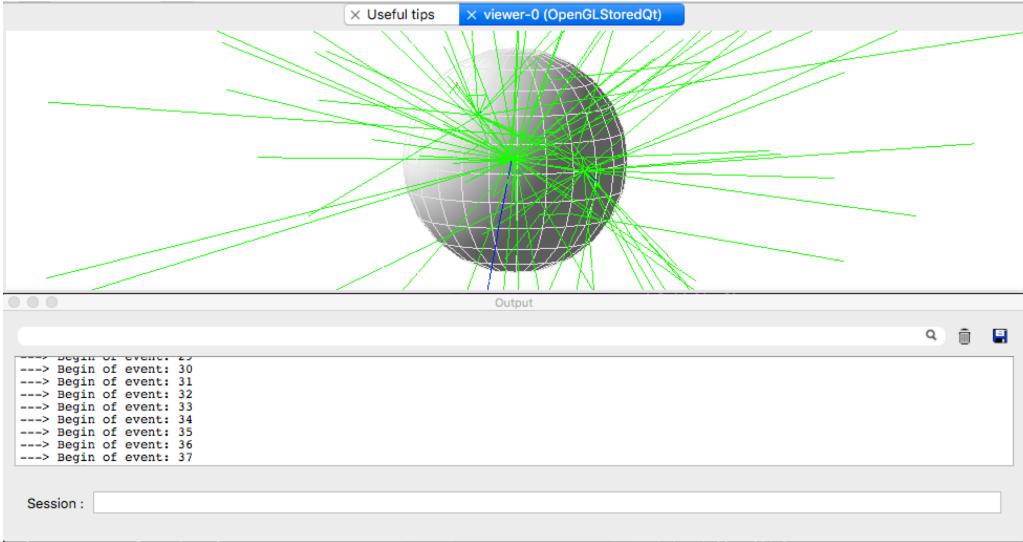


Figure 4: BDSIM GUI screenshot of a 3D particle interaction and output window, showing a GEANT4 sphere with 100 1.3 GeV neutrons.

3 Primitive Meshing

This section will describe the work done to optimize the python scripts that generate the three dimensional meshings for the primitive solids within the Pyg4ometry package (sec. 2.3). All the primitive solids used are constructed such that they are compatible with GEANT4's solids [14]. It was previously thought that it would be best to use purely triangular based meshes in combination with boolean operations to construct the 3D solids. The triangle is the shape which has the minimum amount of points needed to define a planar face containing an area. Prior to the project it had been realised that the computation of triangles and boolean operations in most cases is much more intensive and inefficient, compared with the polygons and adapted trigonometry. In particular with the curved solids are the most computationally heavy, i.e cylindrical, spherical and toroidal based solids, due to the boolean operations generating more complex meshes. Thus the first part of the major project was to rewrite the meshing scripts for all the curved primitive solids in Pyg4ometry (sec.2.3).

One of the major improvements to the Pyg4ometry meshing scripts was in the computation of sectioned primitive solids. The meshing of hollow or sliced solids were previously constructed by boolean subtractions and intersections, which involves using two or more separate solids and operating on them to create a final single solid. This resulted in a very computationally heavy and less aesthetic outcome, where the mesh lines (“slice and stack”) were often meshed in non-axial directions.

3.1 Co-ordinate Systems

The various primitive solids are all constructed by using the predefined parameters used by GEANT4, to be consistent with GEANT4's own convention for solids. The parameters defining a 3D solid are properties relating to the co-ordinate system that the solid is constructed within. For example for a simple cylinder the parameters would be a height and radius. The parameters are then used to generate points on the object via basic trigonometry. The points can then be used as vertexes to define faces on the given solid. The number of faces and subsequently the number of points on a solids surface defines the mesh density. The order in which the points are appended is also very important and is detailed in sec. 3.2.

```

1 def pycsgmesh( nslice , nstack , *args , **kwargs ) :
3     # ...

```

```

5     polygons = []
7     for j0 in range(nslice):
8         j1 = j0
9         j2 = j0 + 1
11
12         vertices = []
13         for i0 in range(nstack):
14             i1 = i0
15             i2 = i0 + 1
16
17         #.....
18
19     return mesh

```

Listing 1: Basic python function structure for new meshing of primitive solid in Pyg4ometry.

The python meshing scripts for all co-ordinate systems follow a similar structure, using a pycsgmesh function, the beginning of which can be seen in listing 1. The “CSG” in “pycsg” stands for Constructive Solid Geometry, which is a modeling technique that uses Boolean operations to construct 3D solids. The naming convention is left over from when the old meshing scripts employed boolean operations. The script works by first defining an empty list of faces (polygons) and then running the associated trigonometric equations through a number of loops to generate and append polygons to that list. The number of loops is defined with the number of sections a surface of a solid is being split up into in a given co-ordinate system (“nslice” & “nstack” in listing 1). The two parts of listing 1 where code has been commented out is where a lot of repetitive code is placed. The first comment block is where the units and other empty lists are defined and the second is where all the points, faces and polygons are constructed using “pycsg.geom” functions. The density of the mesh is defined by the function arguments supplied by the user for the number of slices and stacks, of which the orientation varies with co-ordinate system. The slice and stack used by the new meshing scripts for the solids in the cylindrical polar, spherical & toroidal co-ordinate systems are demonstrated in Figures 5, 8 & 9.

3.1.1 Cylindrical Polar Co-ordinate System

In the cylindrical polar co-ordinate system the loops within the equivalent function to listing 1, creates 3 or 4 points at a time using an adaptation to the trigonometry in eq. 1, which can then be used to define a triangular or quadrilateral face. The only cases where the new meshing produces triangles is at the top and bottom faces of the cylinder. These cases are only true provided the solid does not have a minimum radius equal to zero (creating a tube or cone). The same logic for the triangular faces is identical to that of the quadrilateral faces, just using 3 vertex points to make a face.

The trigonometry that converts the points from cylindrical polar co-ordinates to Cartesian, are:

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \\ z &= z \end{aligned} \tag{1}$$

The only time a stack is needed in the cylindrical co-ordinate system is when the solid has a non-linear function in the r-z plane. For example a paraboloid (fig. 6) would need a stack, but a linear cone (fig. 7) would not. This is due to the fact that a singular plane can not represent a curved surface with a one face.

3.1.2 Spherical Co-ordinate System

The meshing for the primitive solids in spherical co-ordinate systems are constructed by similar means to the that of the cylindrical co-ordinate system, with different trigonometric equations (eq. 2) as a

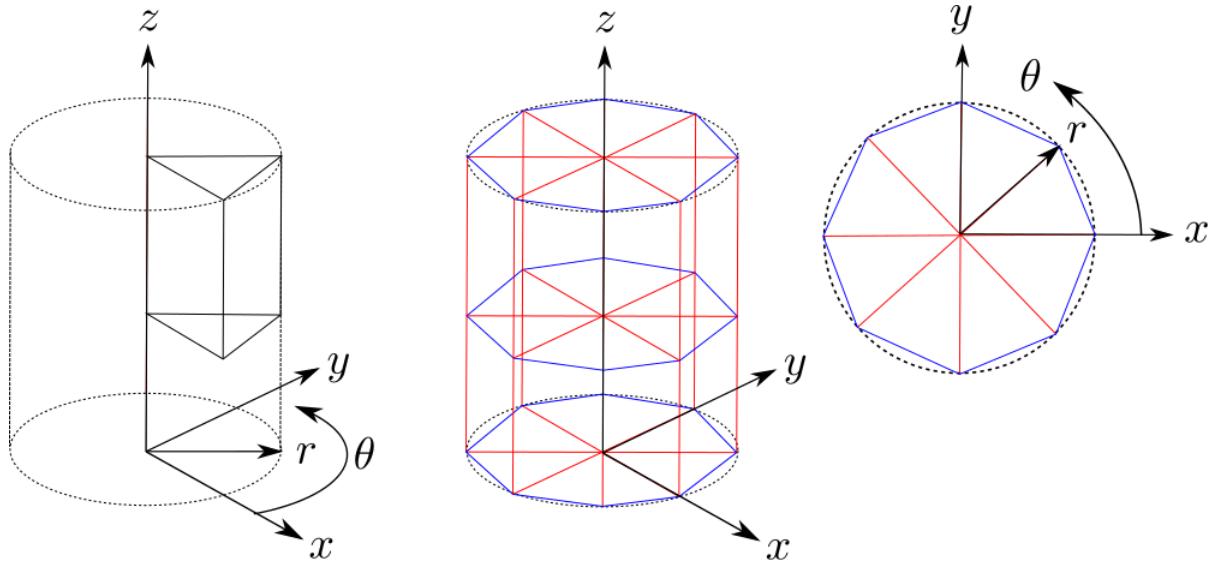


Figure 5: A diagram showing the meshing method for a cylindrical polar co-ordinate system, where the red lines indicate the slices (8) and the blue indicate the stacks (2). The far left diagram depicts a single face in the co-ordinate system using two slices and two stacks to define its four vertexes. The middle diagram shows a complete view of a constructed mesh, using both slice and stack. The far right diagram depicts the meshed cylinder in the x-y plane (top view), to further illustrate the the slice is taken radially.

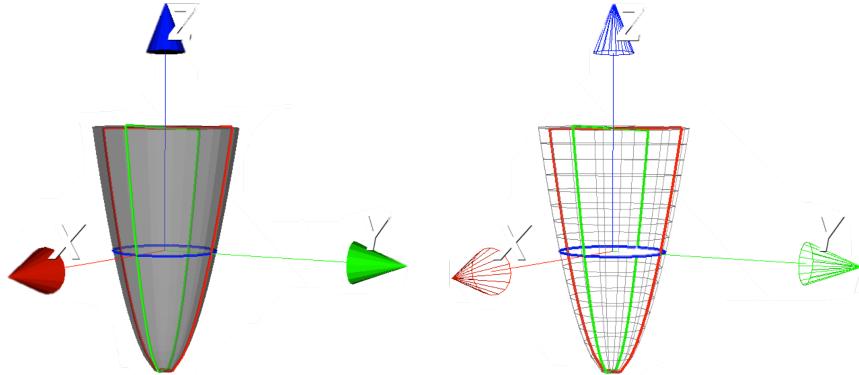


Figure 6: A Paraboloid constructed using the new meshing method in cylindrical polar co-ordinate system, where the red lines indicate the points residing on the $x=0$ plane, the blue lines indicate points on the $z=0$ plane and green lines indicate points on the $y=0$ plane.

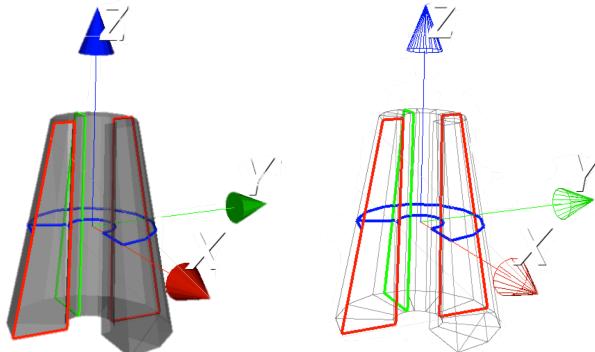


Figure 7: A Cons (hollow cone) constructed using the new meshing method in cylindrical polar co-ordinate system, where the red lines indicate the points residing on the $x=0$ plane, the blue lines indicate points on the $z=0$ plane and green lines indicate points on the $y=0$ plane.

result of two angle parameters ϕ and θ . The stack (blue) and slice (red) for solids in the spherical co-ordinate system works in the same way as the longitudinal and latitudinal mapping on a globe, shown in fig.8.

The trigonometry that converts the points from spherical co-ordinates to Cartesian, are:

$$\begin{aligned} x &= r \cos \theta \sin \phi \\ y &= r \sin \theta \sin \phi \\ z &= r \cos \phi \end{aligned} \quad (2)$$

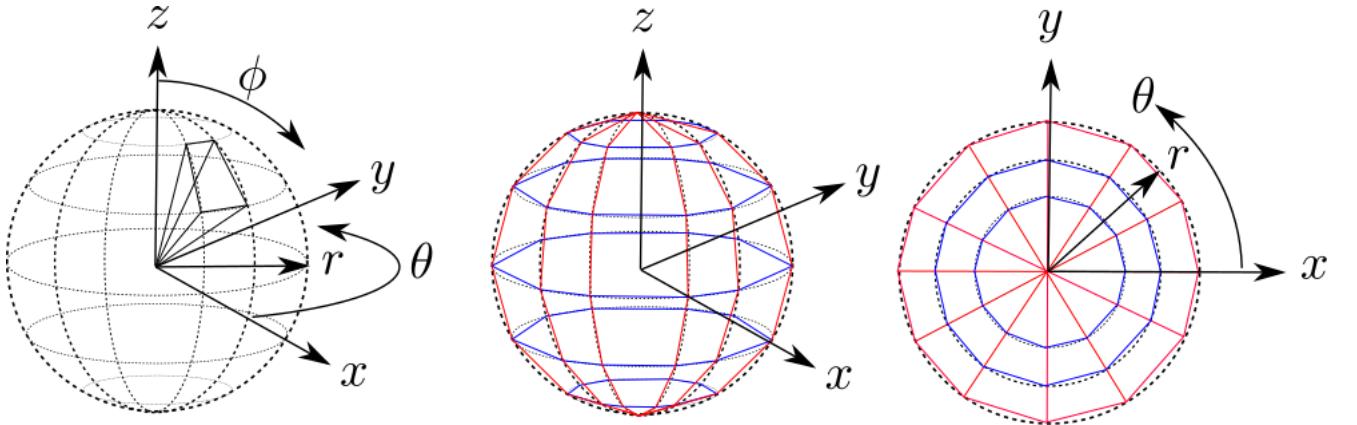


Figure 8: The meshing method for a spherical co-ordinate system, where the red lines indicate the slices (12) and the blue indicate the stacks (6). The far left diagram depicts a single face in the co-ordinate system using two slices and two stacks to define its four vertexes. The centre diagram depicts a fully meshed Orb made out of both stack and slice. The far right diagram shows the meshed Orb in the x-y plane (top view), to further illustrate the the slice is taken radially and that the stacks are circular in nature.

The structure of the code for a spherical co-ordinate system is the same as used in listing 1. The only time triangles are constructed in the spherical co-ordinate system is if a complete pole exists at the top or bottom of the solid. The solids constructed in the spherical co-ordinate system always have both a stack and a slice.

3.1.3 Toroidal Co-ordinate System

The toroidal co-ordinate system is a special case and is only needed, for toroidal based solids. The stack and slice for a toroidal shape is much harder to visualise, due to the fact it is a rotating co-ordinate system. A toroidal slice is an R_{Torus} radial cut taken out of the angle ϕ and a toroidal stack is a R radial cut out of the angle θ , where the angles and radii are displayed in fig.9.

The trigonometry that converts the points from toroidal co-ordinates to Cartesian, are:

$$\begin{aligned} x &= R_{Torus} + R \cos \theta \cos \phi \\ y &= R_{Torus} + R \cos \theta \sin \phi \\ z &= R \sin \theta \end{aligned} \quad (3)$$

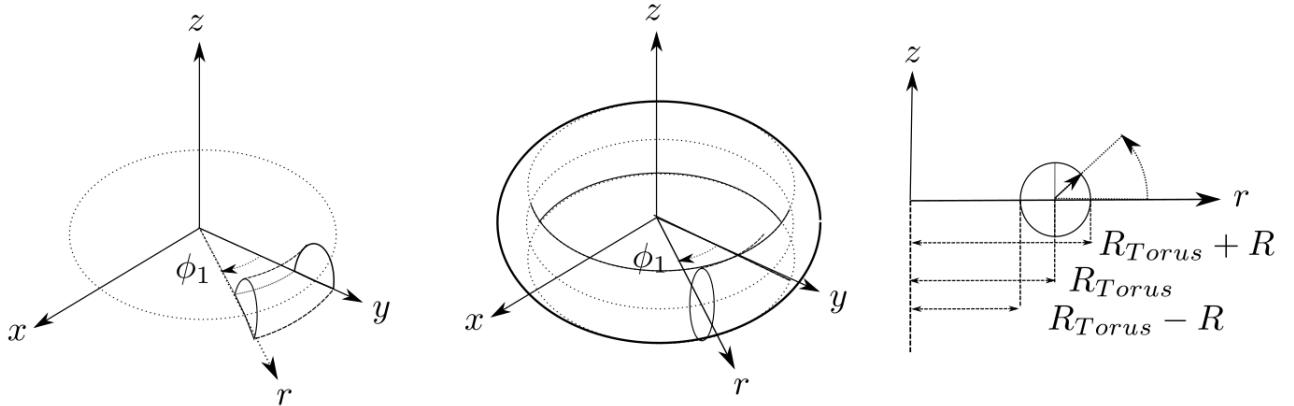


Figure 9: Diagram showing the meshing method for a toroidal co-ordinate system. The far left diagram shows a section of a toroidal slice, where the slices are being cut radially in the ϕ_1 direction. The centre diagram depicts a full un-meshed torus, with an outlined ring residing on the surface of the torus of radius R . The far right diagram shows how the different radii of the torus have been define in the meshing script.

3.2 Plane Direction

A key consideration when writing Pyg4ometry meshing scripts is the order convention being used for appending points/vertexes to a list, to define a plane, i.e to define a face on a solid. This is important as the direction the normal of the plane points in, dictates whether a face is considered an inside or outside face on the given solid. Getting this order incorrect, will lead to missing faces, when the meshing is made. The convention is that the normal to a plane points away from the solids surface, making it an exterior face. The normal is in the z direction to a plane residing on $z=0$, if the points are appended anticlockwise in the x-y plane. For points appending in the other direction (clockwise in the x-y plane), the normal would be in the -z direction, making an interior face. The concept is shown in fig.10.

The simplest way to test this is by performing boolean operations with a solid box, as the boolean operation will only work correctly if all the planes are correct on both shapes, mentioned in more detail in sec. 3.3.2. This test only works for the visualiser in BDSIM as it uses GEANT4, which displays face directions. VTK inside Pyg4ometry is a much more lenient visualiser and will display solids even if their normals are incorrect, giving you a false perspective of what is being displayed. These tests are shown in subsequent sec. 3.3.2.

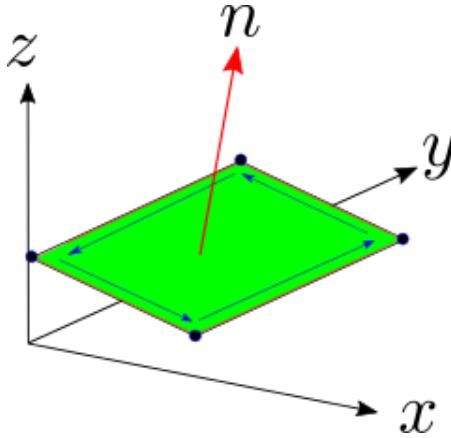


Figure 10: The order convention of appending points to define the normal to a plane in the Pyg4ometry package.

3.3 New Meshing of Curved Primitive Solids

In total there are 12 curved primitive solids, of which many of the examples and concepts are very similar. Therefore only a few select solids will be discussed in this section, but the remaining solids and their development can all be viewed in appendix B.

One of the curved solids for which the meshing was rewritten is the Hyperboloid, the old and new meshing structures of the Hyperboloid is shown in fig.11. It can be seen that in this example the meshing at the top and bottom faces becomes more radially uniform. This is due to the replacement of boolean subtractions with simple trigonometry within the new meshing algorithm for the Hyperboloid.

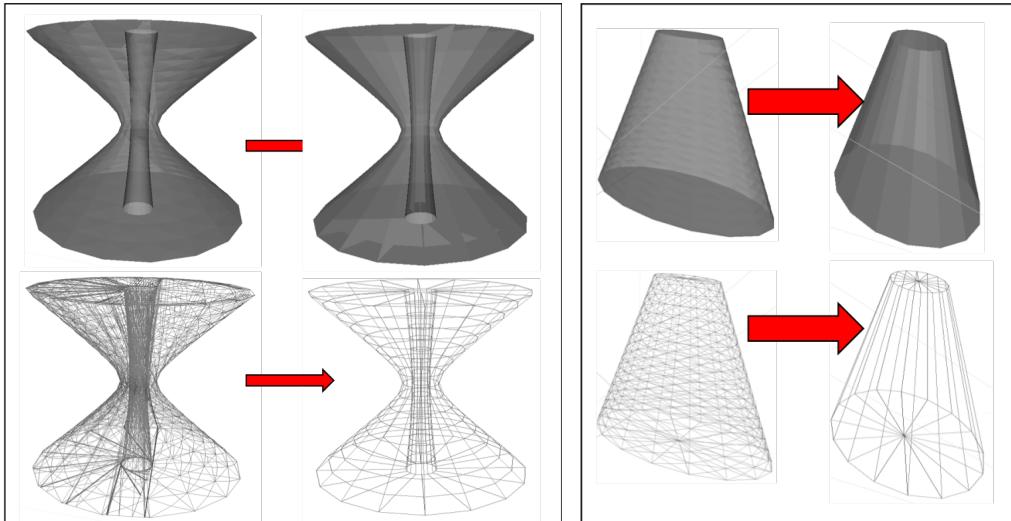


Figure 11: VTK screenshots of Hyperboloid meshing Development (Solid & Mesh View)

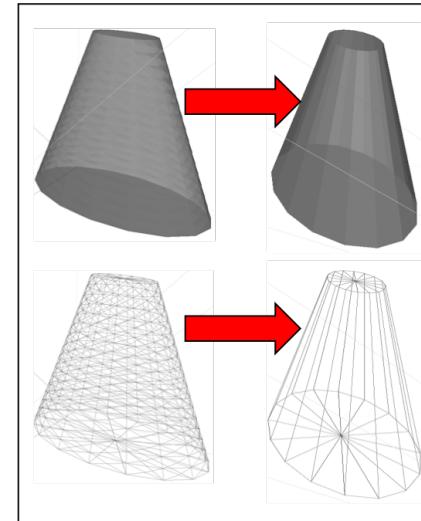


Figure 12: VTK screenshots of Ellipticalcone meshing Development (Solid & Mesh View)

Another curved solid that was remeshed is the Ellipticalcone, as seen in fig.12. Despite having no boolean operations to generate this solid, the meshing is still improved by replacing all the unnecessary triangular faces with quadrilateral ones. For the Ellipticalcone it was also possible for the stack to be removed, as for a cone the faces in the r-z plane (in cylindrical co-ordinates) are a linear function.

A feature that is also removed by the transition to the new meshing algorithms is the "grenade like"

texture seen on the surfaces of the curved solids. The clearest example being the Ellipsoid, shown in fig.13, where it can be seen that the surface of the solid has not only become triangulated, but also has a contour. This is due to the fact that the old mesh would tend to use quadrilateral based pyramids instead of quadrilateral faces in attempt to better estimate a true curved solid. This was done by rotating every other stack to be out of phase when appending vertexes. Despite this improving the mesh accuracy, it was removed as when you increase the orders of stack and slice to high enough orders the difference is negligible and is not worth the extra computation.

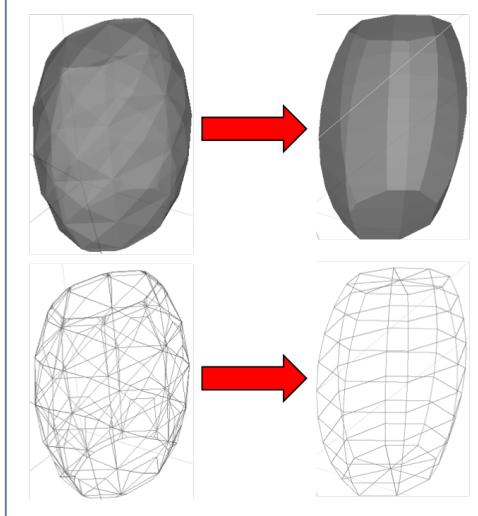


Figure 13: VTK screenshots of Ellipsoid meshing Development (Solid & Mesh View)

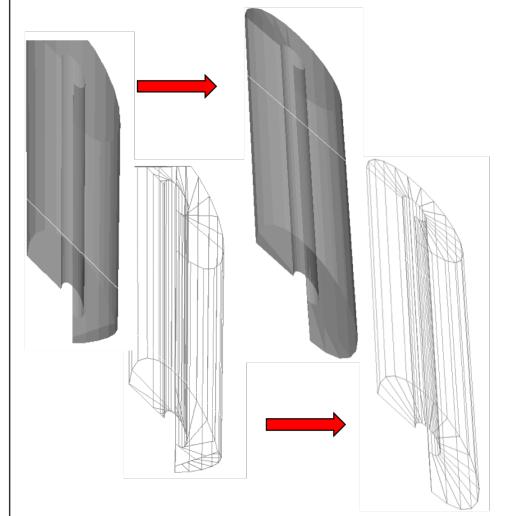


Figure 14: VTK screenshots of CutTubs meshing Development (Solid & Mesh View)

3.3.1 Degenerate Points

Degenerate points are a common mistake which can cause missing faces to occur, due to creating a face with null area. Multiple meshing points occupying the same point in space can spring a few errors, sometimes without entirely crashing the meshing script, making it a potentially hard error to identify. It is typically given away when a *DivisionByZero* error occurs, within the pycsg meshing of a solid. You can identify whether this is the error by debugging each polygon in a mesh, looking out for a face that has two or more vertices with the same (x, y, z) coordinates. This typically happens when you intend to mesh a triangle, but are still using the format for meshing a quadrilateral face. Or it can be due to the choice of an incorrect stack and slice iteration when constructing a face, as mentioned before in sec. 3.1.

3.3.2 Boolean Operations

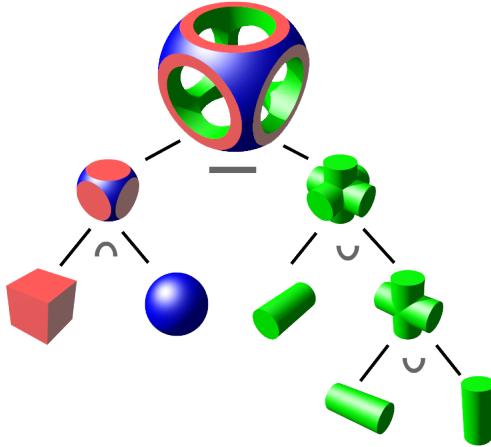


Figure 15: An example CSG solid showing the basic method of constructing a more complicated 3D solid using boolean operations applied onto simpler primitive solids. From Source [7]. Where - = Boolean Subtraction, \cap = Boolean Intersection, \cup = Boolean Unions.

Potentially the largest improvement made to the performance of the new meshing methods compared with the previous methods, is the discarding of boolean operations in order to create hollow or sliced primitive solids. The idea can be clearly seen in fig.15, where you conduct basic operations on multiple simple solids, resulting in a single complex solid being made.

Figures 16 & 17 are of the meshed boolean union and subtraction of a solid box with a hollow sphere (in solid view), where the box is centered around the origin. The coloured lines are representing the perpendicular planes to the axes in which the final object is placed in. These were made in the process of checking the normals before passing them into BDSIM to undergo particle interactions.



Figure 16: Example screenshot of a Boolean Union produced in Pyg4ometry & viewed in VTK.

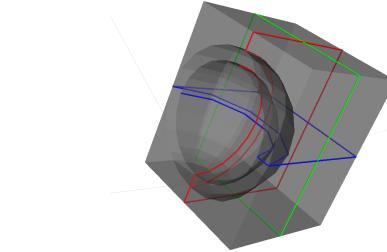


Figure 17: Example screenshot of a Boolean Subtraction produced in Pyg4ometry & viewed in VTK.

The old meshing algorithms heavily relied on these operations, using intersections to slice solids and subtractions to make solids hollow or cut-up. For example CutTubs (tube with angled ends), as seen in fig.14, can be made from two cylinders and a rotated Box, first the two cylinders would be subtracted from one another, creating regular Tubes (tube), as seen in appendix fig. 42. Then the hollowed out cylinder would be intersected with the the rotated box to create angled tips. In the source code the intersection with a box is actually subtractions with rotated planes, as it is the same concept but more efficient. This basic method has now entirely been replaced with clean trigonometry for all the curved solid meshing scripts in Pyg4ometry.

The appearance of the mesh structure itself is also affected by the use of boolean operations, as the boolean operations work by trying to identify common mesh points on the two separate solids, to then

remesh between. This created a lot of non-axially uniform mesh sections as seen in solids such as the Hyperboloid, mentioned before in fig.11. It can be seen that the new meshing algorithm outputs clean radial faces at for the top and bottom sides of the solid.

3.3.3 Summary

As proven by the above examples the boolean operations work and are a much faster way to write the computation of a primitive solid. However this convenience comes at the expense that the boolean operations are very computationally heavy compared with that of the adapted trigonometry which is now implemented in the new method. This is the case especially when one or more of the orginal solids is curved in structure. The new scripts not only reduce the CPU duration time of running but also neaten the overall appearance of the mesh structures.

3.4 Meshing Performance Testing

The performance of the meshes was origally investigated by looking at wall time against stack and slice, which was then learned to be a less reliable than CPU time as it can be affected by background processes running on a machine at the same time. The use of CPU time was showing a much clearer trend however still had a large degree of fluctuation and error primarily due to the choice of material, which is explained in more detail when it is employed for other purposes (sec. 4.3.1). Therefore it was decided that counting the number of faces created on a given solid was the best measure of the meshes complexity.

3.4.1 Polygon Count

The meshing performance of the Pyg4ometry primitive solids was tested by counting the number of polygons produced by both the old and new meshing algorithms, i.e counting the number of triangular and quadrangular faces on a solid, in order to make a comparison. A plot for each curved primitive solid counting its number of generated polygons was produced, two example of which can be seen in fig. 18 & fig. 19, the remaining can be found the Appendix B.

They were generated by varying the user input for the number of slices across a range. Most of the solids were put through the range between 10 and 100 slices, whilst keeping the number of stacks at a constant 10. However a few of old meshing scripts took too long to execute at higher mesh densities. Leading to a few solids only being measured across a shorter range of slices e.g the old Hyperboloid pycsgmesh function was left to run for a duration of over 2 hours and only collected data up to a slice of 50, as shown in fig.19.

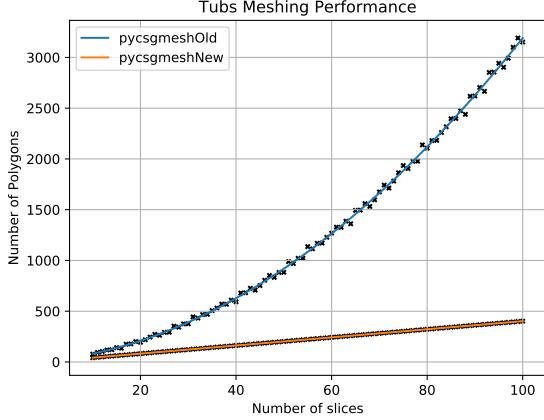


Figure 18: Comparison of the number of polygons (and triangles) generated by the new and old meshing methods, across a range of slices 10-100.

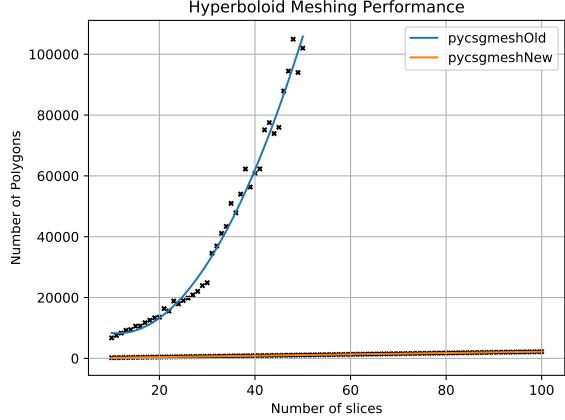


Figure 19: Comparison of the number of polygons (and triangles) generated by the new and old meshing methods, across a range of slices 10-100.

As you can see in both figures, the new meshing function is less computationally expensive compared with the old meshing functions, generating far less faces per slice and stack. The number of polygons increases more uniformly and linearly for the new pycsgmesh function. The old pycsgmesh function exhibits a more scattered and quadratic relationship, due to the boolean operations. This is also confirmed by the values tabled in the appendix ??, which contains the quadratic fitting parameters to all the polygon count plots. If you extrapolated both graphs it is clear than the new mesh is not only improving the structural appearance of the meshed solids, but also saving large amounts of computational power and time.

The next section goes on the test spheres of varying slice and stack within BDSIM. Fig.21 shows the total number of triangles on the interior and exterior surfaces for a given slice and stack equal to the same value on a G4_Ti sphere. The old meshing only meshed up to a maximum resolution of slice and stack equaling 48, before it would max out pythons recursion limit. Where as the new meshing could go to stack of 100 and a slice of 100 without any issues at all. The recursion limit can be extended to allow for a larger range, however it would not be worth the time it would take to code and run. It can be

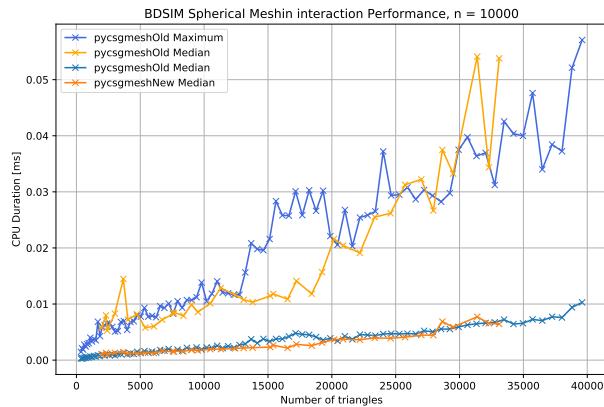


Figure 20: The number of polygonal faces in a mesh plotted against the median and maximum values of the CPU duration distribution, displayed for both the new meshing (orange) and the old meshing (blue).

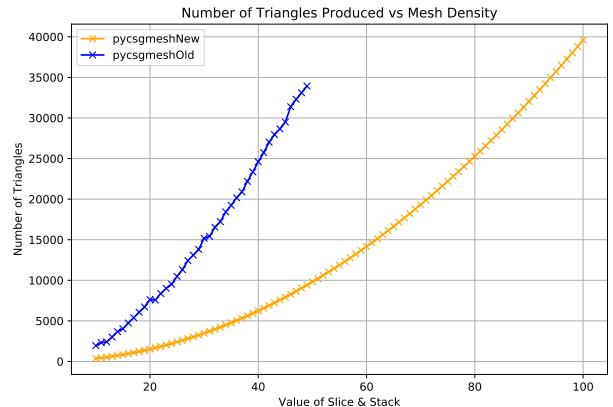


Figure 21: A plot showing the the stack and slice against the number of polygonal faces produced on a sphere with the set dimensions for the proceeding section, shown for both meshing algorithms new (orange) and old (blue).

seen that in fig.21 the new pycsgmesh function has a much smooth gradient and that the old function has small peaks occurring at certain intervals of stack and slice. This is most likely to do with the boolean subtractions of the spheres favouring the old mesh at particular densities. To avoid confusion with the polygon count plot for the sphere in the appendix (fig. 59) it should be made clear that the two plots are testing two differently meshed spheres across different variations of slice and stack. The one in the appendix is an incomplete sphere missing wedges in both its slice and stack, compared with the one tested in fig. 21, which is a complete sphere tessellated purely out of triangles.

4 BDSIM Geometry Simulation

The second aim of this project was to measure how the physics is altered, between the new and old meshings as the mesh density is varied. As mentioned before GEANT4 already has its own set of primitive solids, which can be used as a guideline for comparison, due to no slice and stack dependence. The physics being measured will be features such as the trajectories and energy deposition, through solids.

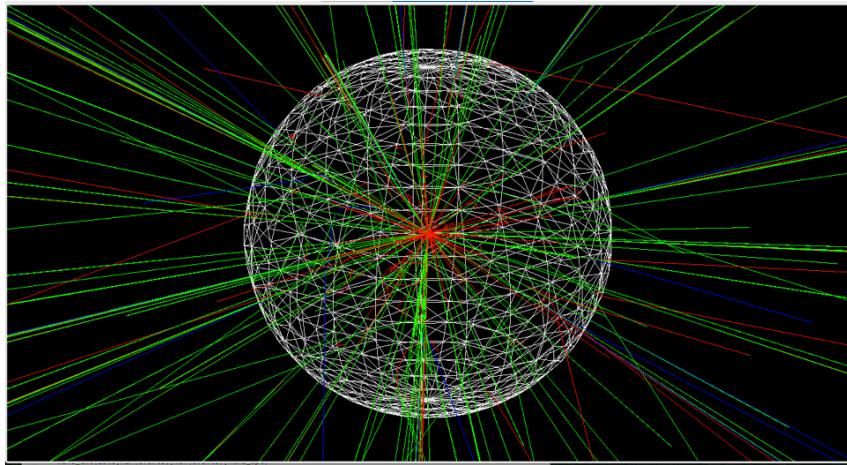


Figure 22: A BDSIM screenshot of a G4_W Pyg4ometry Sphere generated with new meshing interacting with 100 1.3 GeV electrons.

Fig.22 shows a spherical distribution of 100 1.3 GeV electrons radiating outwards from the centre of a Pyg4ometry G4_Ti sphere, where negatively charged red tracks and neutral green tracks can be seen, which are most likely electrons and photons. A secondary particle is anything that is produced as a result of the initial particles interacting with the solid, therefore a secondary itself can produce another particle which is considered to also be a secondary particle. The Monte Carlo simulation in BDSIM uses a numbering system for identifying particles, assigning each particle a unique number. The numbering system adopted in BDSIM is the one used by GEANT4 and created by PDG (or the Particle Data Group) [18], which is an international collaboration dedicated to analysing and publishing the properties of particles.

4.1 Monte Carlo Simulation

The probability of certain particle interactions occurring in a given BDSIM event, such as the decays or scattering of a particles trajectories is generated by a Monte Carlo simulation. The basic principle behind the Monte Carlo algorithms is the use of large random sampling to find numerical results. This is perfect for simulating the probabilities of particular particle interactions happening, as two initially identical interaction setups can have two non identical interactions, with a given probability. Each event in BDSIM is associated with a specific seed number produced via this Monte Carlo method. The uniqueness of each seed allows a particular event to be repeatedly simulated under the same physics conditions, which is key to this project when it comes to comparing the interactions of different objects fairly. The other properties of the particle and physics processes that may occur can also be user

defined to tweak the experiment. Properties such as the particles initial energy, whether secondaries get produced and much more. The seeds used in this project could not be logically chosen due to the fact they are generated via the Monte Carlo simulation. Therefore they were selected by running a lot of test runs in BDSIM to see which seeds generate an adequate amount of secondaries.

4.2 Simple Solid Target

The meshed solid chosen to be tested within BDSIM for this project was the sphere, which is made of a minimum and maximum radius, making it a hollow solid. The reason a sphere was chosen because it is the ideal shape testing radiation in all directions, as its thickness can be controlled radially. As seen in fig.23 the sphere was originally chosen to be oriented such that the particle beam is fired from the centre of the sphere outwards. The conversion from a Pyg4ometry mesh into a GEANT4 tessellated solid, results in only triangular faces. This is why all the quadrilateral faces are cut into two in fig.22 & fig. 23.

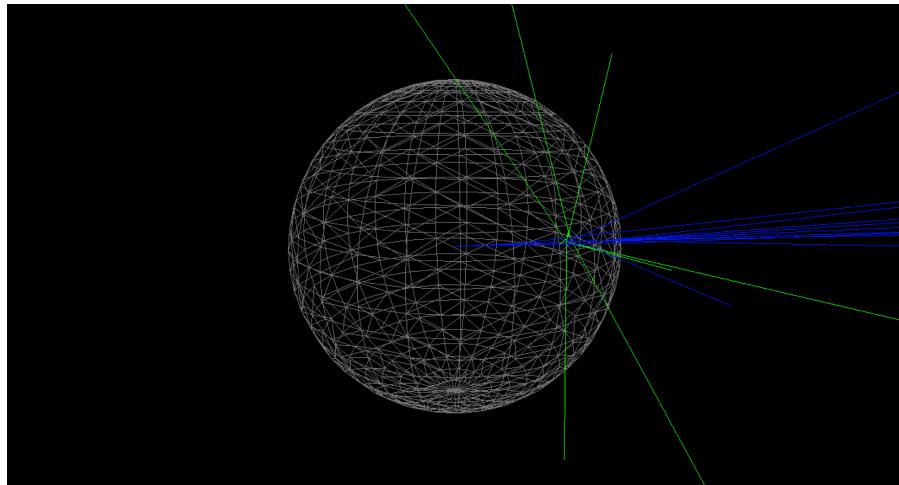


Figure 23: BDSIM screenshot of 10 1.3 GeV protons interacting with a G4_Fe sphere, which has been constructed using the new Pyg4ometry meshing scripts. Mesh resolution is a stack of 25 and slice of 25. (Shown in mesh view)

4.3 Titanium Sphere Interactions

In this section the CPU duration time of interaction in BDSIM with spheres of different mesh densities by different meshing algorithms as a way to analyse the energy deposition as the mesh density is increased. Table 1 shows the properties of the spheres being meshed and the simulation setup, “ngenerate” is a BDSIM parameter to specify the number of particles in a given run. In this scenario the preset GEANT4 sphere was used as a guideline as it does not depend on a user defined stack & slice.

Property	Value
R_{Min}	10.00 [μm]
R_{Max}	10.00 [mm]
Particle	e^-
Energy	1.3 GeV [MeV]
ngenerate	10,000

Table 1: Table of simulation properties for the simulations in this section.

Fig.24 shows the mean CPU duration times for an interaction in BDSIM with a given Sphere. The x-axis was originally the number of stack and slice, but it was thought that the number of triangular faces created on a given Sphere would give a fairer weighting between meshing algorithms. This is

due to the fact the number of faces increases at different rates dependent of the meshing algorithm used, as shown earlier by fig. 21. The reason there is nearly twice as many points plotted for the new meshing over the old is because of the recursion limit, which is discussed in sec. 3.4.1. The error bars in fig.24 are the std deviation of each run, the material of the sphere was originally chosen to be G4_Fe which is much less dense and caused many more secondaries than G4_Ti, making the error bars dominate the data trend. The change of material from G4_Fe to G4_Ti was chosen as G4_Ti is not only much denser but also has a larger stopping power. Fig.25 is the same simulation as in fig.24, but has secondary particles disabled. The reason for fig.25 was to investigate whether the number of secondaries produced has an effect on the duration of the interaction. As it can be seen the number of secondaries produced partially relates to the size of the standard deviation, but not by a very large margin.

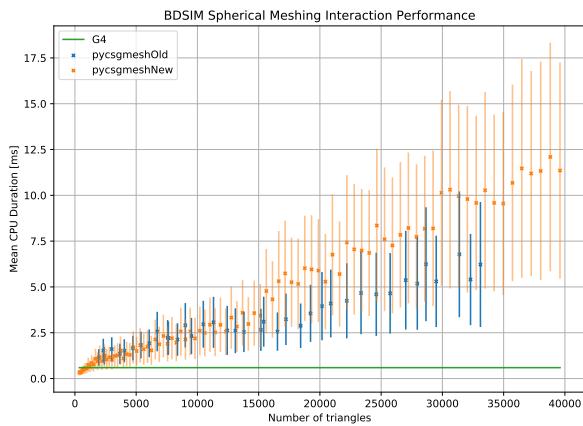


Figure 24: Mean CPU duration of 10,000 protons interacting with a G4_Ti sphere of various meshed forms.

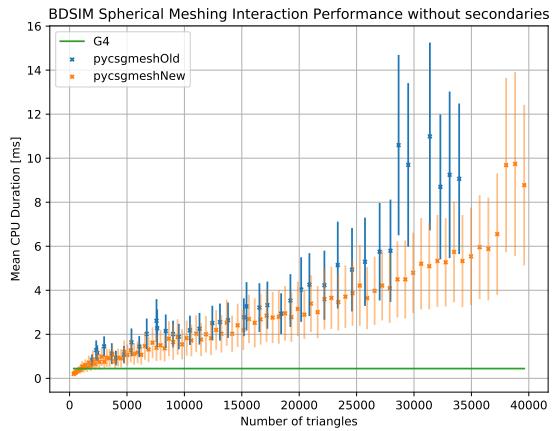


Figure 25: Mean CPU duration of 10,000 protons interacting with a G4_Ti sphere of various meshed forms, with secondary particles disabled.

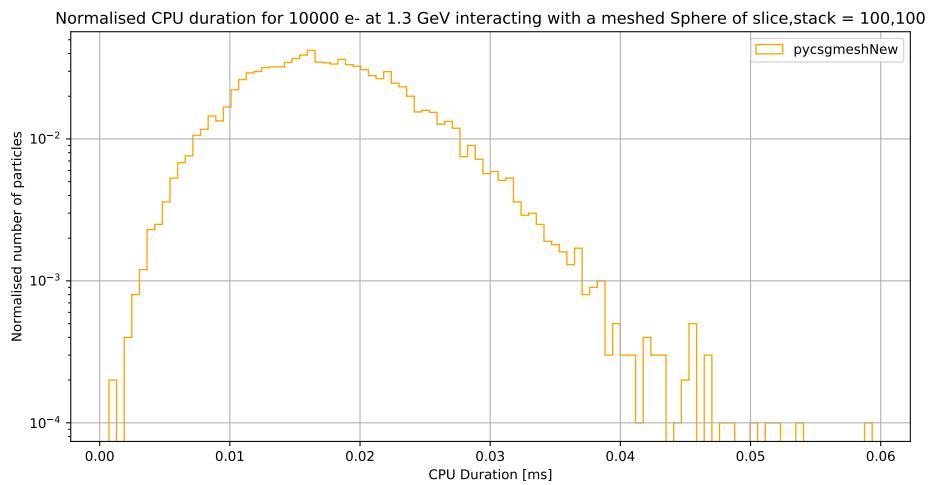


Figure 26: A histogram showing a CPU duration distribution for 10,000 1.3 GeV electrons interacting with a sphere that has been meshed using the new pycsgmesh function. The density of the mesh was set to slice and stack both equal to 100.

The reason for the standard deviations being so large is that there is a small number of events where a large number of secondaries are being produced, which results in a longer overall event duration and

in turn lengthens the standard deviation. An example of this is shown in fig.26, where the plot shows the CPU distribution for 10,000 10 MeV electrons interacting with a G4_Au sphere. The sphere in this example is constructed using the new pycsgmesh function with a stack and slice both set at 100. From Figures 43 and 43, you can see that as the number of stack and slice is increased the mean CPU duration for the protons increases at a slower rate for the new meshing.

It was originally thought that the standard deviations of the CPU durations was related to the number of secondaries being produced. However this was disproved by fig.43, where the same test was conducted with the BDSIM option that disables secondary particles from being produced implemented.

4.3.1 Error Reduction

To reduce the standard deviation of a data set the number of events needs to be increased, this proved by the relationship shown in Equation 4. The standard deviation is inversely proportional to the square root of the number of events. Therefore the standard deviation should decrease with increasing N.

$$\bar{x} = \frac{1}{N} \sum x_i$$

$$\sigma = \sqrt{\bar{x}^2} = \sqrt{\frac{1}{N} \sum (x_i - \bar{x})^2}$$

$$\sigma \propto \frac{1}{\sqrt{N}}$$
(4)

However fig.43 shows...

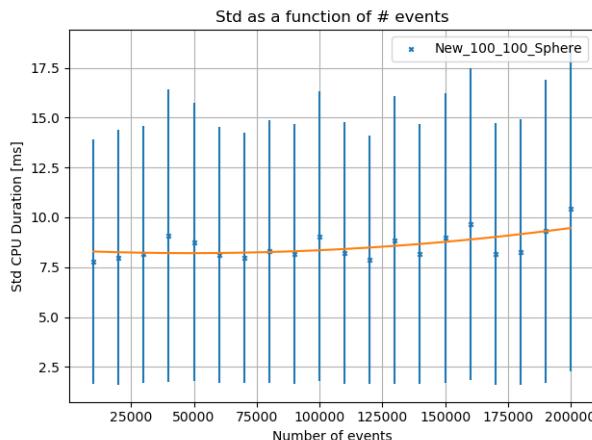


Figure 27: A plot showing the mean CPU duration of an interaction with a new meshing sphere against number of initial 1.3 GeV electrons, where the mesh density is stack

The error bars are still very big so it was proposed to use the standard error of the mean as an alternative. As well as as investigation for varying energy and the material of the target.

4.4 Selection of Material

When creating meshed solids, you have the choice of material. fig.28 shows the CPU duration time distributions for electron interactions with GEANT4 spheres constructed of different GEANT4 materials across a range of energies in BDSIM. The energy range is relatively low (25 MeV → 100 MeV), this is due to the run time of the interactions increasing with energy. The run time is heavily linked to the number of secondary particles which is a function of energy. This is proven by the fact that it can be seen that as the energy is increased the width of the distribution increases. This widening is due to the number of secondary particles being produced, the more energetic an interaction the further the particle will penetrate a solid and ionise along the way generating more secondaries.

Material CPU Duration Time Dist of e- and G4 sphere for n=10000

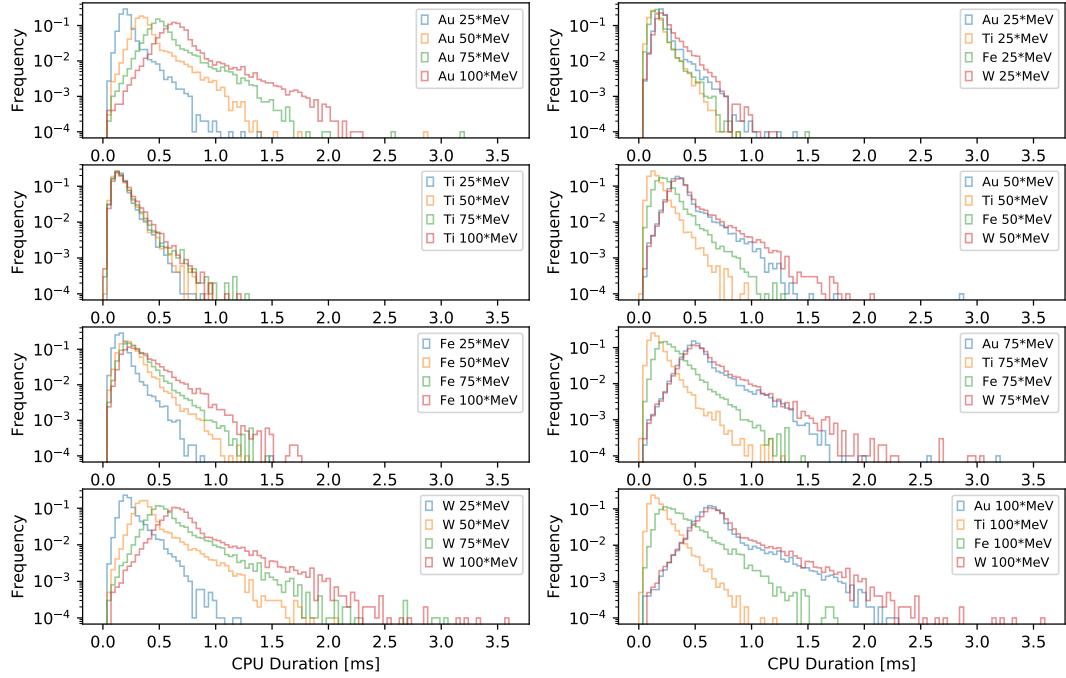


Figure 28: Histograms showing the CPU duration distributions of varying GEANT4 materials and particle energies in BDSIM on a GEANT4 sphere. The left 4 histograms show the distributions show the varying of energy upon each material. The right 4 histograms show the varying of material at each set energy. Each plot is normalised by the initial 10,000 electrons in each event.

The dimensions of the spheres used in fig.28 were set to a minimum radius of 1 micron and a maximum radius of 20 mm. It was then proposed that the radius of thickness could be scaled with respect to the stopping distance of the material it is travelling through, in order to eliminate material as a variable. The radius of thickness ΔR can be seen depicted in fig.29, where $\Delta R = R_{Max} - R_{Min}$.

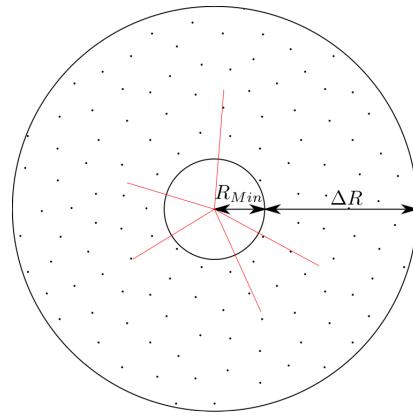


Figure 29: A diagram depicting a crosssec. of a sphere, which has a minimum and maximum radius. The diagram was drawn using the CAD software Inkscape.

4.4.1 Stopping Power

Stopping power is the force that acts against the motion of a particle within in a material, causing it to lose energy. A charged particle is mainly slowed down by electronic stopping as it moves along a linear trajectory. Electronic stopping is the inelastic energy loss to the electrons of the target as a result of thermal vibrations at an atomic level. The electronic stopping contributes most in the intermediate energy range of a travelling particle, as seen in fig.30. Once the particle has lost a sufficient amount of its energy, slowing its velocity through the target, the probability of an elastic collision with a nuclei increases (Nuclear Stopping). The nuclear stopping is the process which causes damage to the target, as the target atom recoils way after the interaction causing a disorder in the lattice structure of the target. The recoiled atom can also go on to cause further collisions causing yet more damage. As seen in fig.30 the electronic stopping power dominates and the nuclear stopping only needs to be accounted for at low energies.

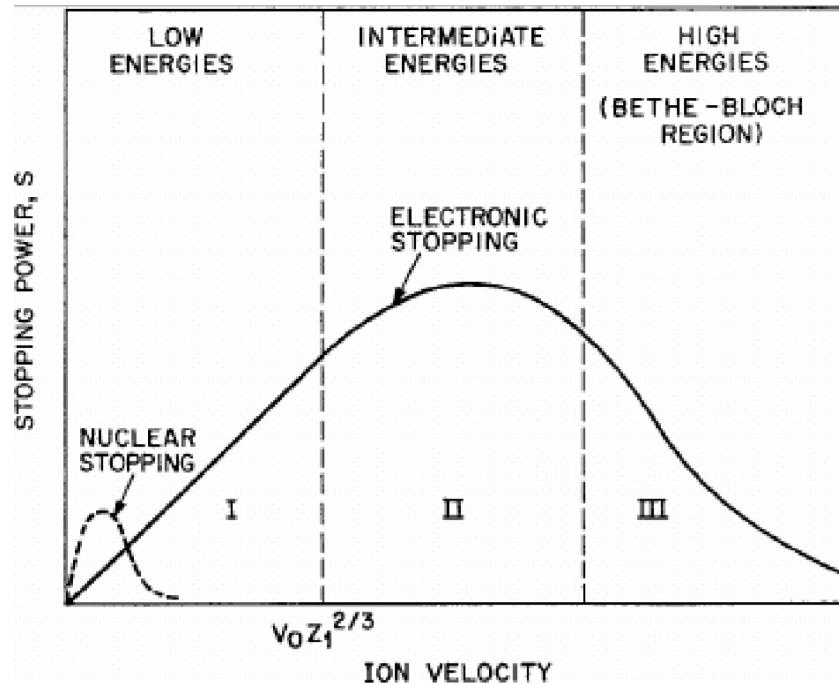


Figure 30: A plot showing the relationship between ion velocity and components of stopping power. fig.2.1 from Source [22]

GEANT4 comes with some Supplementary examples, the example “TestEm0” [23] outputs the stopping power and distances for a given material and particle energy. If the energy of the incident particle and the stopping power of the material is known, a stopping distance can be calculated. The values for stopping power in this project are calculated by the TestEm0 example, which extracting values from a GEANT4 data lists and then interpolates or extrapolates between them, as the stopping power is a function of. The extracted stopping powers match with values found in other studies, such as [19].

Figure 31 shows a sphere made of G4_W, undergoing interactions with batches of 100 electrons at 3 different energies. The spheres radius of thickness is set to the be the stopping distance for G4_W interacting with a 1 TeV electron. It can be seen that when the energy of the electrons is 1 GeV, which is below the 1 TeV (the stopping distance energy for this situation), the tracks of the interactions are all contained within the sphere. The opposite happens when the electrons energies are more than 1 TeV, where most if not all of the particle tracks leave the sphere.

With the stopping power in mind fig.28 was reproduced, but instead of using the same dimensions for each sphere, ΔR was scaled by the stopping distance. The radius of thickness is set to be the extracted

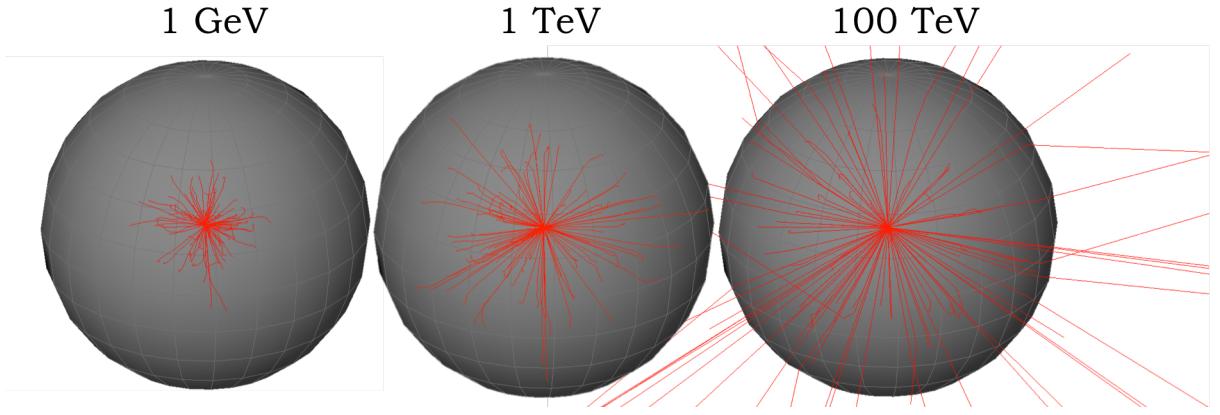


Figure 31: Screenshots of 1 GeV, 1 TeV & 100 TeV electrons interacting with a tungsten sphere. The radius of thickness is set to the extracted GEANT4 stopping distance of a 1 TeV electron in tungsten.

stopping distance for a 100 MeV electron interacting with the material in question. The values of ΔR are shown in Table 2.

Material	ΔR [mm]
G4_Au	9.89382
G4_Ti	33.6854
G4_Fe	62.3434
G4_W	10.1631

Table 2: A table showing the values of ΔR used in fig.32.

It can be seen that in fig.32, the scaling of radius relative to stopping distances, generates histograms which act extremely similar at the same particle energies irrespective of the material it propagates through. This is very interesting as it means that for any further analysis, material can be ruled out as a variable and only energy needs to be varied.

4.5 Interactions with CAD

As a final goal to round off the project, an imported CAD model was compared with a compound boolean meshed solid of a generic bolt, shown in Figure 36. The CAD bolt was downloaded as a STEP format from a free online database GradCAD [20]. The downloaded model was converted to GDML format with the material G4_STAINLESS-STEEL using python. The dimensions of the CAD model were gained by using the measuring tool within the FreeCAD GUI as shown fig.34. The CAD model was then approximately recreated by the constructed of basic primitive solids with boolean operations in Pyg4ometry and can be seen in fig.35.

Material CPU Duration Time Dist of e- and G4 sphere for n=10000

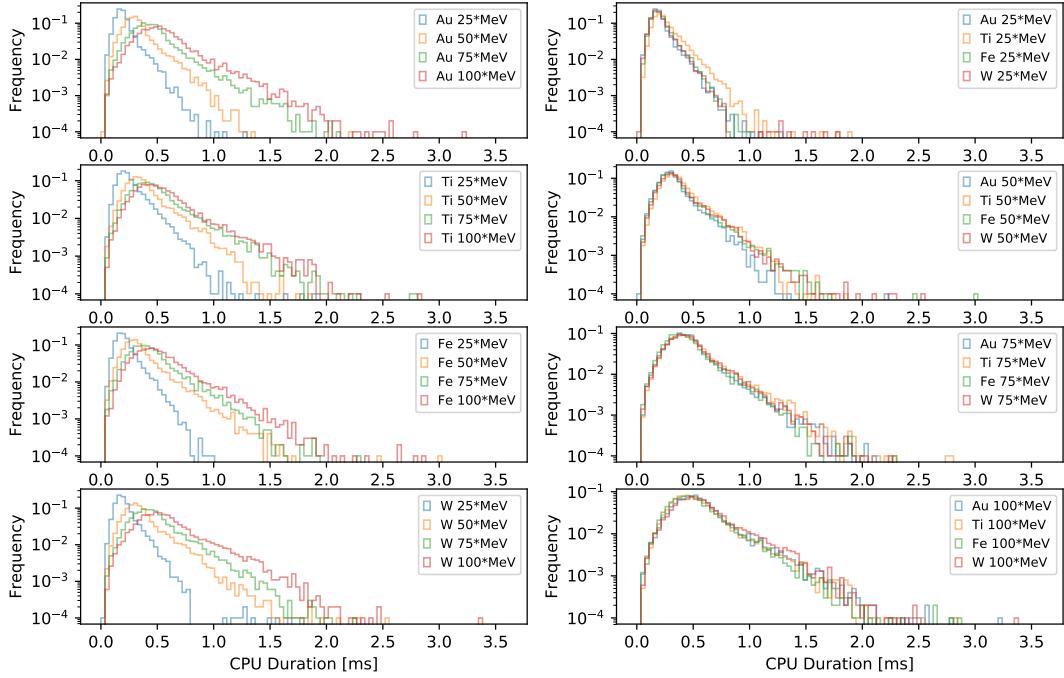


Figure 32: Histograms showing the CPU duration distributions of varying materials and particle energies in BDSIM on a GEANT4 sphere. The left 4 histograms show the distributions show the varying of energy on each material. The right 4 histograms show the varying of material at a set energy. Each plot is normalised by the initial 10,000 electrons in each event.

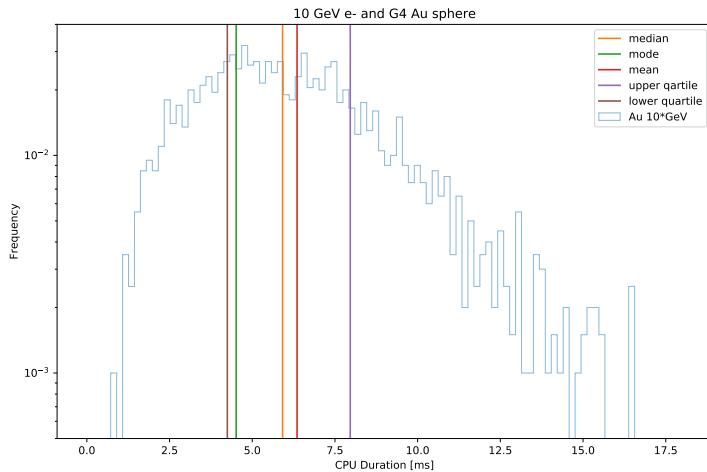


Figure 33: Meshing Development for Tubs (Solid & Mesh View)

Both bolts were then ran in BDSIM interacting with a batch of 10,000 electrons through a range of energies 1 MeV to 0.75 TeV. The interactions were simulated using the spherical beam distribution originated at the centre of each bolt, as shown in figures 36 & 37 (same method that was used for spheres in previous sec. 43). fig.38 show the average number of tracks produced from 3 different runs, using a set seed for each run, for both the boolean and CAD bolts. The number of tracks is calculated by subtracting the 10,000 tracks made by the initial electrons from the total number of particle tracks per event extracted using Pybdsim (sec.2.2.1).

It can be seen that as the energy is increased the electrons generate more secondary particles causing

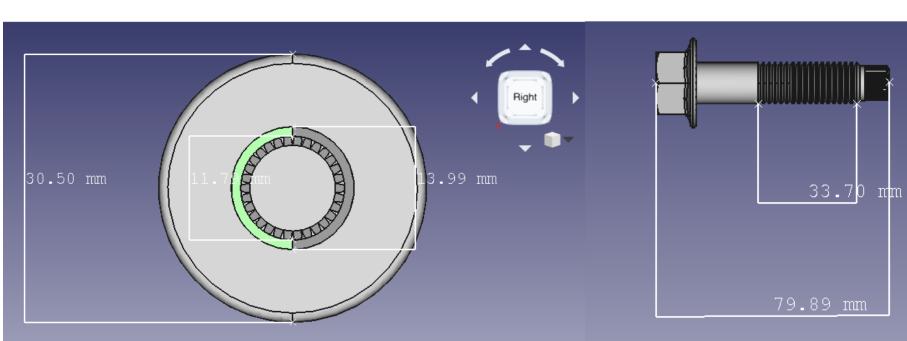


Figure 34: Diagram of imported CAD model in FreeCAD, with dimensions indicated via FreeCAD’s measuring tool.

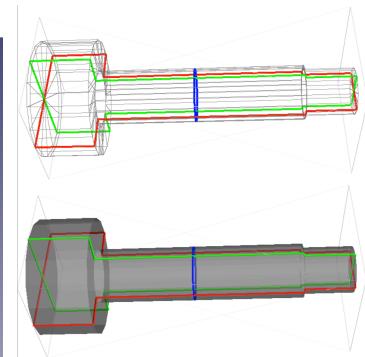


Figure 35: Compound boolean solid recreation of imported CAD model, shown in VTK.

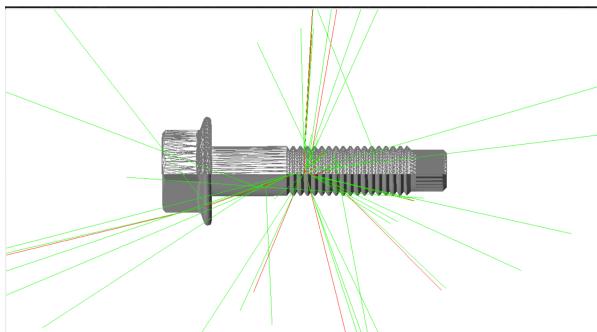


Figure 36: A Screenshot of the imported CAD bolt in BDSIM interacting with 10,000 10 MeV electrons

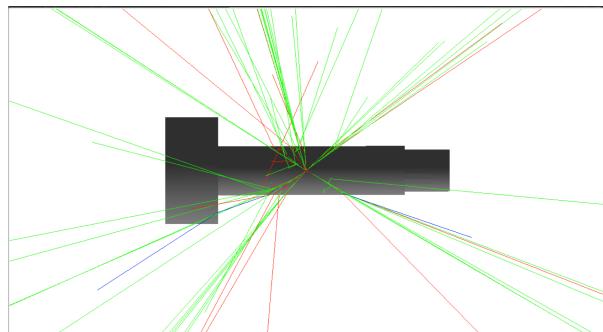


Figure 37: A Screenshot of the boolean CAD bolt in BDSIM interacting with 10,000 10 MeV electrons

the increase in tracks being stored in BDSIM. The gradient of the data begins to flatten out in the range of 100,000 MeV (100 GeV). This flattening is due to the interactions leading to shower of secondary particles occurring earlier and earlier as the particle energy is increased. Theoretically the graph will then begin to have small drop back down due to ...

However due to time constraints and the purpose of the plot being to find the energy range where the number of secondary particles is at large amount for better sampling.

The reason for the number of secondaries being consistently larger for the boolean constructed bolt (Bens_Bolt) compared with the imported CAD bolt (M14_2-6G_Bolt), is most likely due to the boolean construction being an overestimation of the imported bolt. The over estimation would be as a result of time constraints and ease. The most naive the threads on the bolt were ignored as well as the hexagonal and cone features on the head of the bolt.

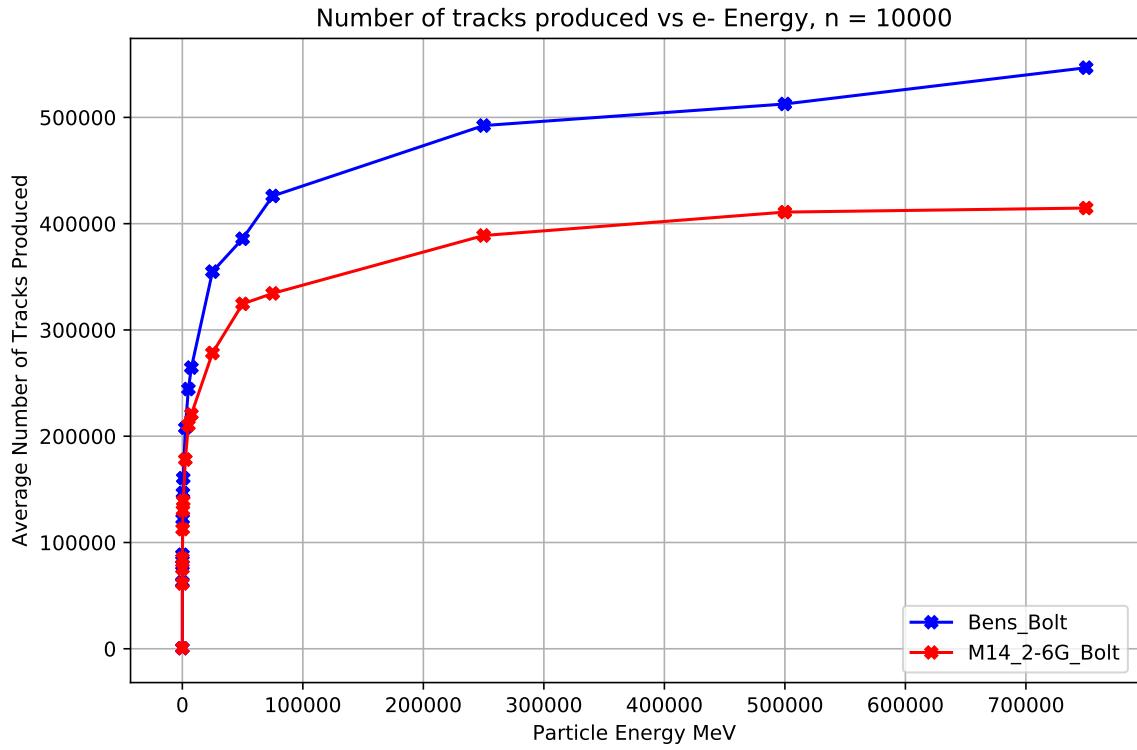


Figure 38: A plot showing the average number of particle tracks produced in BDSIM when interacting 10,000 electrons of 10 Mev with different targets.

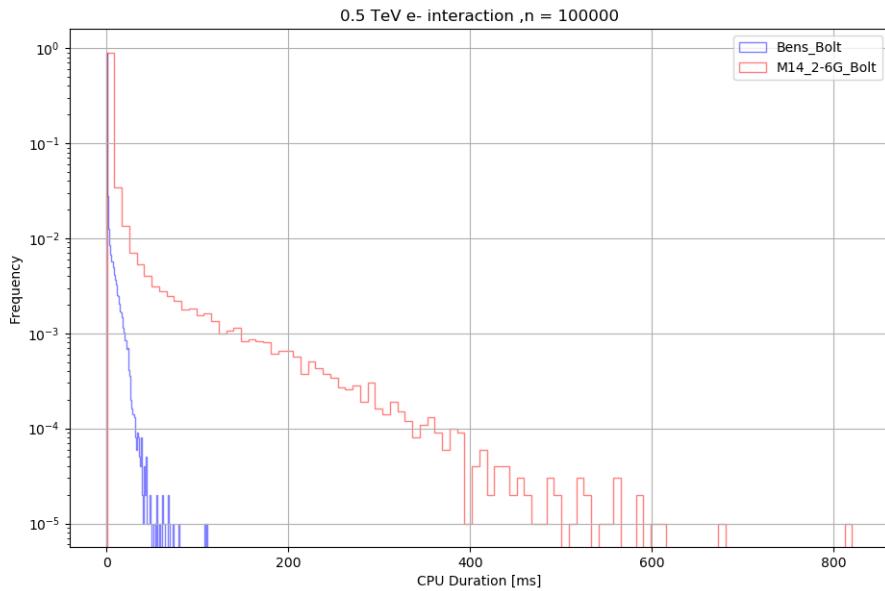


Figure 39: CPU duration distribution of 1,000,000 0.5 TeV electrons interacting with CAD models of a bolt.

5 Conclusion & Summary

5.1 Improvements

meshing is quicker

BDSIM interactions are quicker but still slower than G4 solid (as expected) improved coverage unit test speeds

meshing is neater and more uniform in structure

higher meshing density = closer to true solid as expected with BDISM interactions

quote graphs and sec.s

5.2 Applications

As discussed in the introduction (sec. ?? there are many invaluable uses for softwares such as BDSIM and Pyg4ometry that can be used to aid not only the scientific research community of particle physicist, but also help everyday people by improving medical treatment. Thanks to the software being open source and its wide range of compatible files it can be used to simulate a growing number of projects. This report demonstrates this by CAD magnet modelling.

5.3 Project Extensions

If given more time there is several things that I would have wished to pursue in addition to the project. One being that the analysis done on a sphere in sec. 43 to also be performed on every one of the remeshed curved primitive solids, all of which are listed in the Appendix 43. This way you could have gain an even more complete picture of the improvement to the meshing of compound solids. Despite a lot of the plots being normalised over a few seed values and being ran with 10,00 of more initial particles, the simulations could be re reran with a more particles and for a larger number of seeds. Also a range of particles other than the electrons such as proton

Another area that could have been explored in more detail is a prototype magnet in which I began to make , can be seen in the Appendix 43.

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A Appendix (python scripts)

A.1 Sphere BDSIM Vary Mesh Test

```
from string import Template
import Target_Sphere as t
import numpy as np
import pybdsim

#####
#def run_gdml_spheres_same_slice_and_stack(min,max):
#    """
#        generate a .txt wth four lists of data , number of slices & runtimes ,
#        from a minimum and maximum number of slices and stacks
#    """

Meshing_ver = "New"

for val in range(min,max+1):

    # create gdml
    t.Test(False, False, n_slice = val, n_stack = val)

    #make gmad
    f = open('Template.gmad', 'r')
    contents = f.read()
    f.close()
    template = Template(contents)
    d = { 'value' : str("gdml:../../GDMILs/" + Meshing_ver + "/Target_Sphere_" + str(val) + "_" + str(val) + ".gdml") }
    rendered = template.substitute(d)
    gmadfilename = "GMADs/" + Meshing_ver + "/slice_" + str(val) + "_stack_" + str(val) + ".gmad"
    f = open(gmadfilename, 'w')
    f.write(rendered)
    f.close()

    # use gmad and gdml to get root output
    pybdsim.Run.RunBdsim(gmadfilename, "root_outputs/" + Meshing_ver + "/" + str(val) + "_" + str(val))

    #load in root file to do analysis ...
    print "{}%".format((val-min+1)/(max-min))
#####

run_gdml_spheres_same_slice_and_stack(10,100)
```

Scripts//Run_New_Meshes.py

B All Meshed Solids and Polygon Count Plots

The following figures are the meshing and polygon data for each primitive solid constructed in Pyg4ometry 2.3. The first fig. for each solid is a screenshot of the old meshing and new meshing visualized in VTK. They show the before and after of each primitive solid in both solid and meshed view. The second figures Show the number of polygons and triangles produced on a solid as you increase the slice across a range of 10-100 (if there is a stack it is kept at a constant 10). All plots are made using python and the sold naming convention is the one used by GEANT4 2.1

B.0.1 Cons

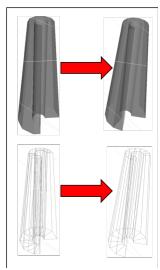


Figure 40

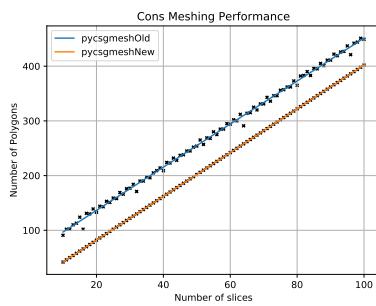


Figure 41

B.0.4 EllipticalCone

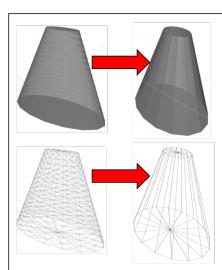


Figure 46

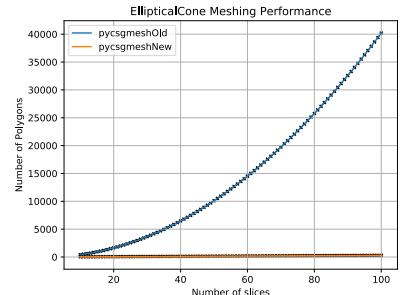


Figure 47

B.0.2 CutTubs

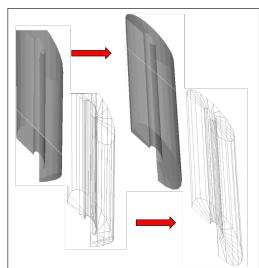


Figure 42

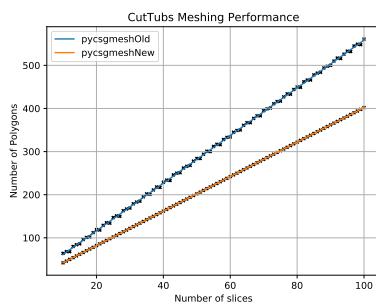


Figure 43

B.0.5 EllipticalTube

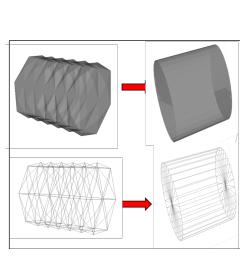


Figure 48

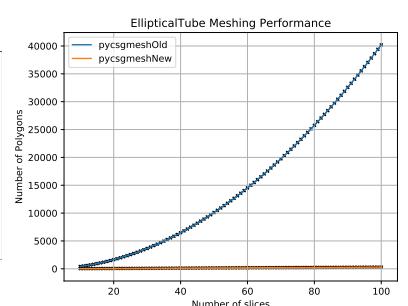


Figure 49

B.0.3 Ellipsoid

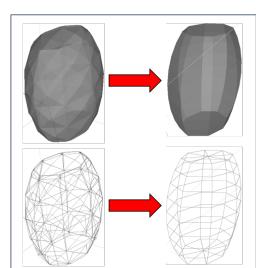


Figure 44

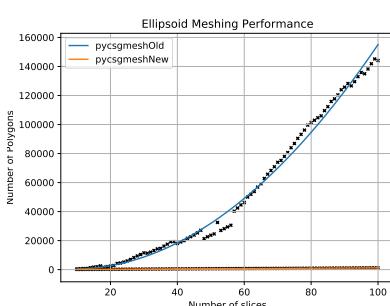


Figure 45

B.0.6 Hyperboloid

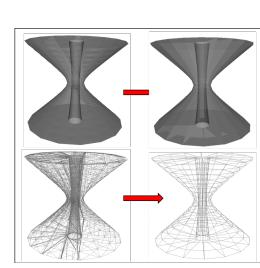


Figure 50

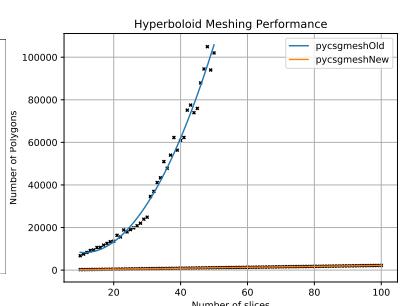


Figure 51

B.0.7 Orb

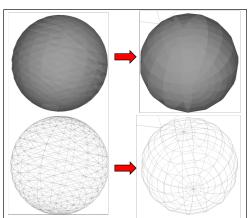


Figure 52

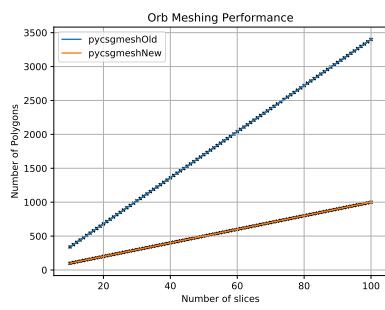


Figure 53

B.0.10 Sphere

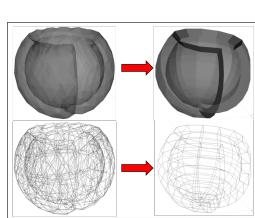


Figure 58

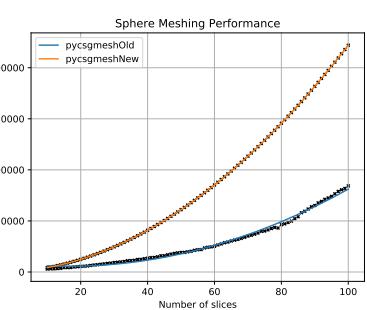


Figure 59

B.0.8 Paraboloid

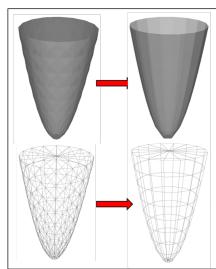


Figure 54

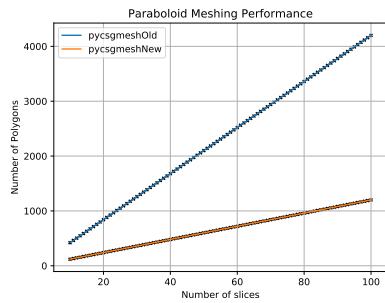


Figure 55

B.0.11 Torus

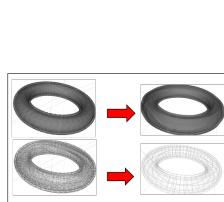


Figure 60

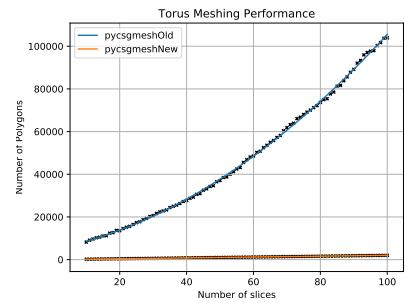


Figure 61

B.0.9 Polycone

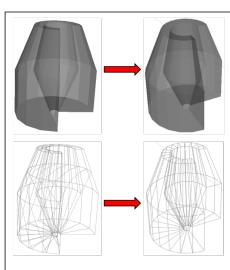


Figure 56

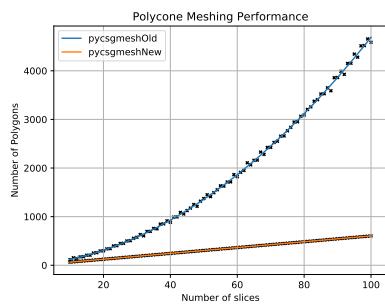


Figure 57

B.0.12 Tubs

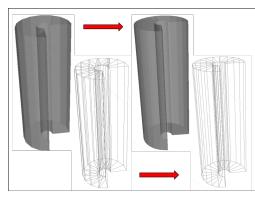


Figure 62

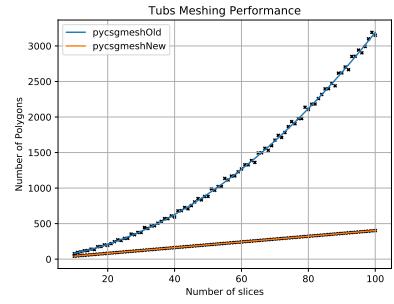


Figure 63

C Quadratic Parameters for polygon count plots

The quadratic fit where its parameters are of the form:

$$ax^2 + bx + c = 0 \quad (5)$$

Table 3: A Table showing the parameters to the quadratic fits for the polygon count plot.

Curved Primitive Solid	a_{Old}	b_{Old}	c_{Old}	a_{New}	b_{New}	c_{New}
Cons	-2.74E-04	3.97E+00	5.72E+01	-3.83E-17	4.00E+00	2.00E+00
CutTubs	2.19E-04	5.50E+00	6.30E+00	-3.83E-17	4.00E+00	2.00E+00
Ellipsoid	18.65090372	-333.5688153	1919.792901	1.61E-17	1.20E+01	0.00E+00
EllipticalCone	4.00E+00	2.00E+00	2.41E-12	4.03E-18	3.00E+00	0.00E+00
EllipticalTube	-1.94E-16	4.20E+01	-5.72E-13	4.03E-18	3.00E+00	0.00E+00
Hyperboloid	64.83177713	-1452.629624	16378.18198	4.84E-17	2.20E+01	-9.53E-14
Orb	-6.45E-17	3.40E+01	-1.91E-13	-8.06E-18	1.00E+01	-4.77E-14
Paraboloid	-1.94E-16	3.40E+01	-1.91E-13	1.61E-17	1.20E+01	0.00E+00
Polycone	0.39682347	7.13011557	7.42466252	-4.03E-17	6.00E+00	4.00E+00
Sphere	10.82154926	-356.6329124	8557.249195	2.00E+01	2.20E+02	1.98E-11
Torus	7.01776508	304.8746037	4899.196225	-1.61E-17	2.00E+01	-9.53E-14
Tubs	0.27241769	4.58191175	8.33675211	-3.83E-17	4.00E+00	2.00E+00

D Prototype FreeCAD Magnet

This is the first attempt at a prototype magnet made using FreeCAD GUI (Figure 64) and exported as a STEP file, which was then converted to a GDML format with GEANT4 material G4_Cu using python. A magnetic field map was then attached onto the shape based on a preset dipole field in BDSIM, in which you can see electrons repelling, as shown in fig.65.

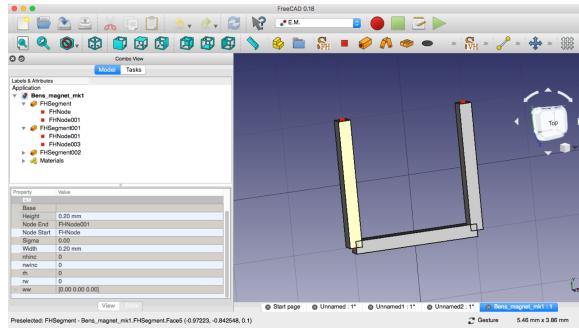


Figure 64: FreeCAD screenshot

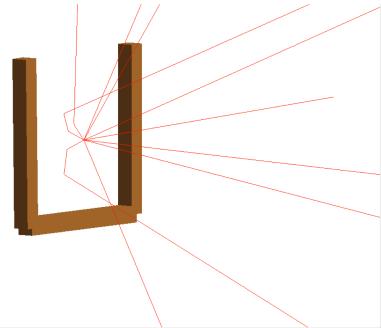


Figure 65: BDSIM screenshot