

### Universiteit van Amsterdam

Kansrekening en Statistiek

### **LAB-4**

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#### 19 Exercise: Transforming multivariate rv's

$$X = (X_1, X_2)^T$$

$$\mu_{\vec{X}} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \text{ and } \Sigma_{\vec{X}} = \begin{pmatrix} 1 & 0 \\ 0 & 4 \end{pmatrix}$$

$$E(\vec{Z}) = E\begin{pmatrix} Z_1 \\ Z_2 \end{pmatrix} = E\begin{pmatrix} X_1 + X_2 \\ X_1 - X_2 \end{pmatrix} = \begin{pmatrix} E(X_1 + X_2) \\ E(X_1 - X_2) \end{pmatrix} = \begin{pmatrix} E(X_1) + E(X_2) \\ E(X_1) - E(X_2) \end{pmatrix} = \begin{pmatrix} 1 + -1 \\ 1 - -1 \end{pmatrix}$$

$$E(\vec{Z}) = \begin{pmatrix} 0 \\ 2 \end{pmatrix}$$

$$Cov(\vec{Z}) = \begin{pmatrix} Cov(Z_1, Z_1) & Cov(Z_1, Z_2) \\ Cov(Z_2, Z_1) & Cov(Z_2, Z_2) \end{pmatrix}$$

$$= \begin{pmatrix} Var(X_1 + X_2) & Cov(X_1 + X_2, X_1 - X_2) \\ Cov(X_1 + X_2, X_1 - X_2) & Var(X_1 - X_2) \end{pmatrix}$$

$$= \begin{pmatrix} Var(X_1 + X_2) & Cov(X_1, X_1 - X_2) + Cov(X_2, X_1 - X_2) \\ Cov(X_1, X_1 - X_2) + Cov(X_2, X_1 - X_2) & Var(X_1 - X_2) \end{pmatrix}$$

$$= \begin{pmatrix} Var(X_1 + X_2) & Cov(X_1, X_1) - Cov(X_2, X_2) \\ Cov(X_1, X_1) - Cov(X_2, X_2) & Var(X_1 - X_2) \end{pmatrix}$$

$$= \begin{pmatrix} E((X_1 + X_2)^2) - (E(X_1 + X_2))^2 & Var(X_1) - Var(X_2) \\ Var(X_1) - Var(X_2) & E((X_1 - X_2)^2) - (E(X_1 - X_2))^2 \end{pmatrix}$$

$$= \begin{pmatrix} E(X_1^2 + X_2^2 + 2X_1X_2) - E(Z_1)^2 & Var(X_1) - Var(X_2) \\ Var(X_1) - Var(X_2) & E(X_1^2 + X_2^2 - 2X_1X_2) - E(Z_2)^2 \end{pmatrix}$$

$$= \begin{pmatrix} E(X_1^2) + E(X_2^2) + 2E(X_1X_2) - E(Z_1)^2 & Var(X_1) - Var(X_2) \\ Var(X_1) - Var(X_2) & E(X_1^2) + E(X_2^2) - 2E(X_1X_2) - E(Z_2)^2 \end{pmatrix}$$

The variance of  $X_1$  and  $X_2$  can be read from the covariance matrix  $\vec{X}$ . The expected value of  $X_1$  and  $X_2$  can also be found above, furthermore the Covariance matrix  $\Sigma_{\vec{X}}$  also shows that  $X_1$  and  $X_2$  are independent.

$$= \begin{pmatrix} E(X_1^2) + E(X_2^2) + 2(E(X_1)E(X_2)) - 0 & 1 - 4 \\ 1 - 4 & E(X_1^2) + E(X_2^2) - 2(E(X_1)E(X_2)) - 4 \end{pmatrix}$$

$$= \begin{pmatrix} Var(X_1) + E(X_1)^2 + Var(X_2) + E(X_2)^2 - 2 & -3 \\ -3 & Var(X_1) + E(X_1)^2 + Var(X_2) + E(X_2)^2 + 2 - 4 \end{pmatrix}$$

$$= \begin{pmatrix} 1 + 1 + 4 + 1 - 2 & -3 \\ -3 & 1 + 1 + 4 + 1 + 2 - 4 \end{pmatrix}$$

$$= \begin{pmatrix} 5 & -3 \\ -3 & 5 \end{pmatrix}$$

You can conclude  $Z_1$  and  $Z_2$  are dependent cause  $Cov(Z_1, Z_2) \neq 0$ 

#### 20 Exercise: Correlation vs Dependence

$$X = (X_1, X_2)^T$$

$$\mu_{\vec{X}} = \begin{pmatrix} 0 \\ 0 \end{pmatrix} \text{ and } \Sigma_{\vec{X}} = \begin{pmatrix} 1 & 0 \\ 0 & c \end{pmatrix}$$

$$\mu_{\vec{Z}} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$
 
$$Cov(\vec{Z}) = \begin{pmatrix} Cov(Z_1, Z_1) & Cov(Z_1, Z_2) \\ Cov(Z_2, Z_1) & Cov(Z_2, Z_2) \end{pmatrix}$$

$$\sigma_{1,1} = Var(X_1) + E(X_1)^2 + Var(X_2) + E(X_2)^2 + 2(E(X_1)E(X_2)) - E(Z_1)^2$$

$$\sigma_{1,2} = Var(X_1) - Var(X_2)$$

$$\sigma_{2,1} = Var(X_1) - Var(X_2)$$

$$\sigma_{2,2} = Var(X_1) + E(X_1)^2 + Var(X_2) + E(X_2)^2 - 2(E(X_1)E(X_2)) - E(Z_2)^2$$

$$\sigma_{1,1} = 1 + 0^2 + c + 0^2 + 2(0*0) - 0^2$$

$$\sigma_{1,2} = 1 - c$$

$$\sigma_{2,1} = 1 - c$$

$$\sigma_{2,2} = 1 + 0^2 + c + 0^2 - 2(0*0) - 0^2$$

$$Cov(\vec{Z}) = \begin{pmatrix} 1 + c & 1 - c \\ 1 - c & 1 + c \end{pmatrix}$$

$$Corr(\vec{Z}) = \begin{pmatrix} 1 & \frac{1-c}{\sqrt{(1+c)(1+c)}} \\ \frac{1-c}{\sqrt{(1+c)(1+c)}} & 1 \end{pmatrix}$$

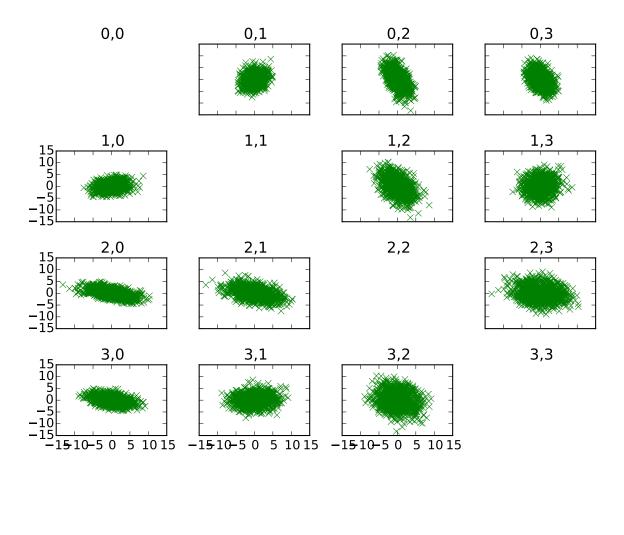
Because c > 0 You can leave out the sqrt and the square.

$$Corr(\vec{Z}) = \begin{pmatrix} 1 & \frac{1-c}{1+c} \\ \frac{1-c}{1+c} & 1 \end{pmatrix}$$

For every c > 1 there is a correlation, because of non-zero  $p_{2,1}$  and  $p_{1,2}$ .

## 21 Exercise: Generating & Visualizing Samples from $\mathbf{N}(\mu, \Sigma)$

```
import pylab as plt
n = 1000
mu = [[0],
      [0],
      [0],
      [0]]
Sigma = [[3.01602775, 1.02746769, -3.60224613, -2.08792829],
         [1.02746769, 5.65146472, -3.98616664, 0.48723704],
         [-3.60224613, -3.98616664, 13.04508284, -1.59255406],
         [-2.08792829, 0.48723704, -1.59255406, 8.28742469]]
d, U = plt.eig(Sigma) # Sigma = U L Ut
L = plt.diagflat(d)
A = plt.dot(U, plt.sqrt(L)) # required transform matrix
X = plt.randn(4, n) \# 4xn matrix with each element ~ N(0,1)
Y = plt.dot(A, X) + plt.tile(mu, n) # 4xn each column vector ~N(mu, Sigma)
f, axarr = plt.subplots(4, 4, sharex=True, sharey=True)
for i in range(0, len(Y)):
    for j in range(0, len(Y)):
        if(i == j):
            axarr[i][j].set_title(str(i) + ',' + str(j))
            axarr[i][j].axis('off')
            continue
        axarr[i][j].plot(Y[i], Y[j], 'xg')
        axarr[i][j].set_title(str(i) + ',' + str(j))
plt.setp([a.get_xticklabels() for a in axarr[0, :]], visible=False)
plt.setp([a.get_yticklabels() for a in axarr[:, 1]], visible=False)
plt.tight_layout()
# scatter plot of N(mu, Sigma) distribution
plt.savefig('scatter.pdf')
plt.clf()
```



# 22 Exercise: Estimating mean( $\vec{x}$ ) and covariance matrix (S)

• Below you can find the Maximum Likelihood estimator of the covariance matrix from a sample of n observations.

$$\widehat{\Sigma} = \frac{1}{n} \sum_{i=1}^{n} (\mathbf{x}_i - \overline{\mathbf{x}}) (\mathbf{x}_i - \overline{\mathbf{x}})^T$$

It was easy to see that when the program was run with more draws the relative accuracy of the estimated mean and covariance matrix increased by differing less of the original  $\mu$  and  $\Sigma$ .

• import pylab as plt

```
n = 1000
mu = [[0],
      [0],
      [0],
      [[0]]
Sigma = [[3.01602775, 1.02746769, -3.60224613, -2.08792829],
         [1.02746769, 5.65146472, -3.98616664, 0.48723704],
         [-3.60224613, -3.98616664, 13.04508284, -1.59255406],
         [-2.08792829, 0.48723704, -1.59255406, 8.28742469]]
d, U = plt.eig(Sigma) # Sigma = U L Ut
L = plt.diagflat(d)
A = plt.dot(U, plt.sqrt(L)) # Required transform matrix.
X = plt.randn(4, n) \# 4*n matrix with each element ~ N(0,1)
# 4*n each column vector ~N(mu,Sigma), random draws from distribution.
Y = plt.dot(A, X) + plt.tile(mu, n)
Ybar = [[avg] for avg in plt.mean(Y, 1)] # Mean along the 1 axis.
Yzm = Y - plt.tile(Ybar, n) # Subtract mean from each column.
# Estimator for covariance matrix.
S = plt.dot(Yzm, plt.transpose(Yzm)) / n - 1
print(Ybar, S)
```