A meta-probabilistic-programming language for bisimulation of probabilistic and non-well-founded type systems

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Abstract. We introduce a formal meta-language for probabilistic programming, capable of expressing both programs and the type systems in which they are embedded. We are motivated here by the desire to allow an AGI to learn not only relevant knowledge (programs/proofs), but also appropriate ways of reasoning (logics/type systems). We draw on the frameworks of cubical type theory and dependent typed metagraphs to formalize our approach. In doing so, we show that specific constructions within the meta-language can be related via bisimulation (implying path equivalence) to the type systems they correspond. This allows our approach to provide a convenient means of deriving synthetic denotational semantics for various type systems. Particularly, we derive bisimulations for pure type systems (PTS), and probabilistic dependent type systems (PDTS). We discuss further the relationship of PTS to non-well-founded set theory, and demonstrate the feasibility of our approach with an implementation of a bisimulation proof in a Guarded Cubical Type Theory type checker.

1 Introduction

Probabilistic programming offers a fertile ground between logic-based and machine-learning-based approaches to A(G)I. Formalization within type theory offers a rigorous approach to deriving semantics for probabilistic languages [15], and formalization of dependently typed probabilistic languages offers the promise of drawing a tight connection with probabilistic logics of various kinds (e.g. Markov Logic [19], Probabilistic Paraconsistent Logic [7]).

While the exploration of such individual systems is highly important, we might consider more abstractly how to embody general principles for the formation of diverse probabilistic type systems, logics, and programming languages within a single meta-language. Such a language can be considered a meta-theoretical language or logical framework for expressing individual type systems and logics. However, previous frameworks (such as [9]) have not been designed with probabilistic type systems and logics specifically in mind. Here, we outline a formal language, M, designed for such a purpose. This language is intended as a formal model of the MeTTa language, currently being developed as part of the OpenCog project [14,8,16]. The language allows for (probabilistic) reasoning not only about the knowledge embedded in a system, but also about the logic employed by the system itself.

Our approach may also be seen in relation to recent methods to derive synthetic denotational semantics for logical systems using guarded cubical type theory (GCTT)

[18,11]. Such approaches are particularly promising, offering as they do a unified approach to deriving semantics for recursive datatypes as final co-algebras of appropriate functors in the context of a formulation of univalent type theory with a fully computational semantics. We draw on methods from [10] to formalize our approach in this context. This allows us to rigorously define the relationship between an object-language and its expression in our meta-language as one of bisimulation, corresponding to path equivalence in GCTT. We further show how dependently typed metagraphs can be formalized in GCTT as the basis for our framework [6,12], and how this leads to systems embedding natural type-theoretic equivalents of non-well-founded sets.

We begin by developing a general framework for representing metagraphs in GCTT, before outlining how the final co-algebra of a labeled transition system over this recursive datatype can be used to model our meta-language. We then derive bisimulations for various object-languages in our system, including simply typed (and untyped) lambda calulus, pure type systems, and probabilistic dependent type systems, hence deriving synthetic denotational semantics for these systems. Finally, we demonstrate the feasibility of our approach with an implementation of a bisimulation proof for a small-scale type system in a Guarded Cubical Type Theory type checker [4], before concluding with a discussion.

2 Labeled metagraphs as a guarded recursive datatype

We begin by defining a recursive datatype for typed metagraphs $(\mathcal{M}_{(\mathcal{T},\mathcal{L},\preceq_T)})$ using guarded cubical type theory. Here, \mathcal{T},\mathcal{L} are types of type-symbols and edge labels respectively, and $\preceq_T \colon \mathcal{T} \times \mathcal{T} \to \mathbb{B}$ is a partial order on type-symbols. The recursive datatype is defined as the final co-algebra of the functor $\mathcal{M}'_{(\mathcal{T},\mathcal{L},\preceq_T)}(A)$, which when applied to type A returns the following datatype (letting Δ stand for the assumptions $\mathcal{L},\mathcal{T},A:\mathcal{U}_0$; the ϵ , edge, and connect constructors used here follow the approach of [12] and [6]):

$$\frac{\Gamma \vdash \Delta}{\Gamma \vdash \mathcal{M}'_{(\mathcal{T},\mathcal{L})}(A)}$$

$$\frac{\Gamma \vdash \Delta}{\Gamma \vdash \epsilon : \mathcal{M}'_{(\mathcal{T},\mathcal{L})}(A)}$$

$$\frac{\Gamma \vdash \Delta, n : \mathbb{N}, t_0 : \mathcal{T}, t : \operatorname{Vec}(n, \mathcal{T}), l_0 : \mathcal{L}}{\Gamma \vdash \operatorname{edge}(n, t_0, l_0, t) : \mathcal{M}'_{(\mathcal{T},\mathcal{L})}(A)}$$

$$\frac{\Gamma \vdash \Delta, a_1, a_2 : A, t_0 : \mathcal{T}, l_0 : \mathcal{L}, q : \mathbb{N} \to \mathbb{N}_{0,\infty}}{\Gamma \vdash \operatorname{connect}(a_1, a_2, t_0, l_0, q) : \mathcal{M}'_{(\mathcal{T},\mathcal{L})}(A)}$$

(1)

where $\operatorname{Vec}(n, A)$ is the type of vectors over A of length n, and $\mathbb{N}_{0,\infty}$ is \mathbb{N} extended with 0 and ∞ . We note that for notational convenience, we do not explicitly include

target labels/indices in the definition of $\mathcal{M}'_{(\mathcal{T},\mathcal{L})}(A)$ above (in contrast to [6], where \mathcal{L} refers to target indices and \mathcal{V} is used for edge values). If explicit indices are required to identify target 'levels', these may be included by letting $\mathcal{L} = \mathcal{L}_0 \times \sum_n \mathrm{Vec}(n,\mathbb{N})$, so that each edge label is paired with a vector of target indices. $\mathcal{M}_{(\mathcal{T},\mathcal{L},\preceq_T)}$ is then defined as a final fixed-point of $\mathcal{M}'_{(\mathcal{T},\mathcal{L})}$, such that a set of constraints are satisfied:

$$\mathcal{M}_{(\mathcal{T},\mathcal{L},\preceq_T)} = \sum M : \nu(\mathcal{M}'_{(\mathcal{T},\mathcal{L})}).C(M,\preceq_T)$$
 (2)

where $C(M, \preceq_T)$ represents the constraints:

$$C(M, \preceq_T) = \forall n_1, n_2 : \mathbb{N}, t_1, t_2 : \mathcal{T}$$

$$f(M, n_1) = t_1 \land$$

$$f(M, n_2) = t_2 \land$$

$$q'_M(n_1) = n_2 \Rightarrow t_1 \preceq_T t_2$$
(3)

Here, f(M,n) represents a function, which for metagraph M returns the type of its n'th edge or target. Specifically, when M is of the form $edge(n, t_0, l_0, t)$, f(M, 0) is the type of the edge, and f(M, n > 0) is the type of the n'th target, and when M is of the form connect (a_1, a_2, t_0, l_0, q) , f(M, 0) is the type of the whole metagraph, while the types of the edges/targets of a_1 and a_2 are interleaved when evaluating f(M, n > 1)0) for odd/even values of n respectively. Further, the function $q_M': \mathbb{N} \to \mathbb{N}_{0,\infty}$ is recursively defined on $\nu(\mathcal{M}'_{(\mathcal{T},\mathcal{L})})$ (via the q function in the connect constructor of Eq. 1) to indicate that the n_1 'th target of M is connected to the n_2 'th edge/target of M, whenever $q(n_1) = n_2$, with $n_2 = \infty$ indicating that the target has no connection. $C(M, \preceq_T)$ thus provides a set of constraints that ensure the connections in a metagraph respect the \leq_T relation; further constraints are needed to ensure for instance that targets receive input from only one other target (as may be appropriate for some metagraphs). Further, $\nu = \operatorname{fix} X.F(\triangleright(\alpha : \mathbb{T}).X[\alpha])$ is the guarded fixed-point operator [10]. By [10], Prop. 3.2, $\mathcal{M}_{(\mathcal{T},\mathcal{L},\preceq_T)}$ is both a subset of the initial algebra and final coalgebra of $\mathcal{M}'_{(\mathcal{T},\mathcal{L})} \circ \triangleright$. Finally, we note that our connect constructor corresponds to Connect_Q in [6], and the Union constructor is simply connect with $q(n) = \infty$ for all n (meaning that no new connections are added).

We briefly give some examples of typed metagraphs. For convenience, we set $\mathcal{L} = \{\text{null}\}$, and $\mathcal{T} = \{A, B, C, D, \top\}$, with \preceq_T the identity relation along with $t \preceq_T \top$ for all t. In our first example, we can construct metagraphs X = edge(3, A, null, [D, B, C]), and Y = edge(2, B, null, [D, A]). Then, a combined graph can be constructed as $Z' = \text{connect}(X, Y, \top, \text{null}, \{(1, 1), (2, 0)\})$, $Z'' = \text{connect}(Y, X, \top, \text{null}, \{(1, 1), (2, 0)\})$, $Z''' = \text{connect}(Z', Z'', \top, \text{null}, \{\})$, $Z = \text{connect}(X, Z''', C, \text{null}, \{(3, 0)\})$. The entire metagraph is shown in Fig. 1A. We note that, in general, any metagraph with a finite number of edges and targets can be represented by a term in the initial algebra of $\mathcal{M}'_{(\mathcal{T},\mathcal{L})}$ (as is Z). Some graphs, however, may be conveniently be represented also by terms in the final coalgebra. Consider for instance Fig. 1B. Here, we may define $X'' = \text{edge}(3, \top, \text{null}, [B, B, A])$ and $X' = \text{connect}(X'', X'', A, \text{null}, \{(1, 2), (2, 1), (3, 0)\})$, representing X' by a term in the initial algebra (suppressing visualization of the X'' subgraph). Alternatively, we may define $X'_{co} = \text{connect}(\text{edge}(3, A, \text{null}, [B, B, A])$,

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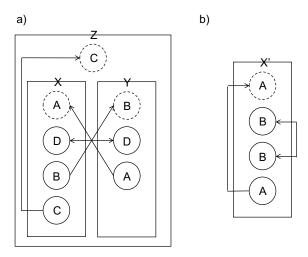


Fig. 1. Typed metagraph examples. Boxes show metagraphs, which may be single edges (containing no further boxes) or include several edges. Solid circles edge target types and dotted circles show metagraph types. Arrows show target-target or target-edge connections. Metagraph letter names are shown on the box of the metagraph to which they refer in the text.

 X'_{co} , A, null, $\{(1,2), (2,1), (3,0)\}$), which implicitly determines a term in the coalgebra as a solution to the recursive equation.

3 M as the final coalgebra of a labeled transition system

We define the formal meta-probabilistic-programming language, \mathbb{M} , as a labeled transition system over typed metagraphs. Here, we are interested in typed metagraphs with a particular form. Specifically, we begin by defining \mathcal{T} by the abstract syntax:

$$\mathcal{T} ::= t_n \mid \mathcal{T} \to \mathcal{T} \mid \prod a : \mathcal{T}.\mathcal{M}_{\mathbb{M}} \mid$$

$$\operatorname{Eq}(\mathcal{T}, \mathcal{M}_{\mathbb{M}}, \mathcal{M}_{\mathbb{M}}) \mid \mathcal{T} \cup \mathcal{T} \mid \mathcal{T} \cap \mathcal{T} \mid$$

$$\operatorname{Type} \mid \top_{\operatorname{Type}} \mid \mathcal{T} \mid \mathcal{J} \mid \mathcal{X}$$

$$(4)$$

These syntactic constructions represent base-level types, function types, dependent types, equality types, type unions and intersections, a base universe of small types, the union of all small types, the union of all types, judgments and execution states respectively. Notice also that in Eq. 4, \mathcal{T} is defined by mutual recursion with the type $\mathcal{M}_{\mathbb{M}}$, defined in Eq. 6. We then define \mathcal{L} as $\mathcal{L} = \mathcal{S} \cup \mathcal{V} \cup \mathcal{K} \cup \mathcal{T} \times \mathbb{N}$. Notice that \mathcal{L} includes \mathcal{T} , so that types may simultaneously serve as labels. Further, $\mathcal{S} = \{s_1, s_2, ...\}$ and $\mathcal{V} = \{v_1, v_2, ...\}$ denote collections of symbols and variables respectively, and \mathcal{K} is a special set of \mathbb{M} keywords/key-symbols:

$$\mathcal{K} = \{:, \leq, =, \rightarrow, \text{Eq, fun-app, transform, } @, \dagger \}$$
 (5)

Further, \mathcal{L} includes an edge-specific identifier \mathbb{N} to deduplicate edges which are identical in other respects.

The state of an \mathbb{M} program is represented by a typed metagraph in the following space:

$$\mathcal{M}_{\mathbb{M}} = \sum \preceq_{T} : (\mathcal{T} \times \mathcal{T} \to \mathbb{B}). \sum M : \mathcal{M}_{(\mathcal{T}, \mathcal{L}, \preceq_{T})}.C_{\mathbb{M}}(M, \preceq_{T})$$
 (6)

Hence, this is the space of all metagraphs over \mathcal{L} and \mathcal{T} , with a varying \preceq_T relation, where $C_{\mathbb{M}}(M, \preceq_T)$ represents a set of 'M-specific constraints' on the structure of the metagraph (to be outlined below). This state represents the *Atomspace* of the program, and the subgraphs of the Atomspace are the individual atoms (as in MeTTa, see [14,8]). We note that, since \mathbb{M} serves both as a language for defining programs and type-systems within which these programs are embedded, the atoms may represent base-level propositions and programs (expressions), as well as judgments and computational state information, as reflected by their types. The \mathbb{M} -specific constraints, $C_{\mathbb{M}}(M, \preceq_T)$, determine the interaction of the keywords/key-symbols with the type system:

$$\begin{split} \forall m \in M.\exists n, n_1 : \mathbb{N}. \\ m &= \operatorname{edge}(2, \mathcal{J}, (:, n), [\top_{\operatorname{Type}} \top]) \vee \\ m &= \operatorname{edge}(2, \mathcal{J}, (\preceq, n), [\operatorname{Type} \operatorname{Type}]) \wedge \\ (m_M[1] &= \operatorname{edge}(0, \operatorname{Type}, (t_{n_1}, 0), []) \wedge \\ m_M[2] &= \operatorname{edge}(0, \operatorname{Type}, (t_{n_2}, 0), []) \Rightarrow (t_{n_1} \preceq t_{n_2})) \vee \\ m &= \operatorname{edge}(2, \mathcal{J}, (=, n), [\top_{\operatorname{Type}} \top_{\operatorname{Type}}]) \vee \\ m &= \operatorname{edge}(2, \operatorname{Type}, (\rightarrow, n), [\operatorname{Type} \operatorname{Type}]) \wedge \\ ((m_1)_M[2] &= m \wedge l(m_1) = (:, n_1) \wedge t(m_M[1]) = A \wedge \\ t(m_M[2]) &= B \Rightarrow t((m_1)_M[1]) \preceq A \rightarrow B) \vee \\ m &= \operatorname{edge}(2, \operatorname{Type}, (\rightarrow, n), [\operatorname{Type} \top]) \wedge \\ ((m_1)_M[2] &= m \wedge l(m_1) = (:, n_1) \wedge t(m_M[1]) = A \wedge \\ m_M[2] &= m_2 \Rightarrow t((m_1)_M[1]) \preceq \prod a : A.m_2) \vee \\ m &= \operatorname{edge}(3, \operatorname{Type}, (\operatorname{Eq}, n), [\operatorname{Type} \ t_{n_1} \ t_{n_1}]) \wedge \\ m_M[1] &= \operatorname{edge}(0, \operatorname{Type}, (t_{n_1}, 0), []) \wedge \\ ((m_1)_M[2] &= m \wedge l(m_1) = (\operatorname{Eq}, n_1) \wedge l(m_M[1]) = (T, n_1) \wedge \\ m_M[2] &= A \wedge m_M[3] = B \Rightarrow t((m_1)_M[1]) = \operatorname{Eq}(T, A, B)) \vee \\ m &= \operatorname{edge}(2, \top, (\operatorname{transform}, n), [\top \top]) \vee \\ m &= \operatorname{edge}(1, \mathcal{X}, (@, n), [\top]) \wedge \\ m &= \operatorname{edge}(1, \mathcal{X}, (f, 0), [\top]) \wedge \\ m &= \operatorname{edge}(2, B, (\operatorname{fun-app}, n), [A \rightarrow B' \ A]) \wedge B' \preceq B \vee \\ m &= \operatorname{edge}(2, B, (\operatorname{fun-app}, n), [\prod a : A.m_1 \ A]) \wedge \\ m_1[a &= m_M[1]] \preceq B \vee \\ \end{split}$$

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m = \operatorname{connect}(\_,\_,\_,\_,\_) \land
\forall n, n_1, n_2 : \mathbb{N}.t_n \preceq \top \land
s_n : \top_{\operatorname{Type}} \lor s_n : \operatorname{Type} \land
v_n : \top_{\operatorname{Type}} \lor v_n : \operatorname{Type} \land
t_n : \operatorname{Type} \land
(t_{n_1} \preceq t_{n_2} \land t_{n_2} \preceq t_n \Rightarrow t_{n_1} \preceq t_n) \land
t_n \preceq t_n \cup t_{n_1} \land
t_n \cap t_{n_1} \preceq t_n 
(7)
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where the notation $m_M[n]$ denotes the n'th target of subgraph m in metagraph M, t[m] and l[m] denote the type and label of metagraph m respectively, and we write a:A as shorthand for 'there exits an :-edge in M connecting a and A'. We note that, for convenience, the above formulation does not include some constructions that may be appropriate in a full implementation, but can be derived from others. For instance, tuples can be constructed by introducing a dependent function tuple: $\prod A, B$: Type $A \to B \to \text{Type}$. The left and right projection functions are then defined by $\pi_1(\text{tuple}(A,B,a,b)) = a$ and $\pi_2(\text{tuple}(A,B,a,b)) = b$. Dependent sums can likewise be defined as dependent tuples, $\text{tuple}': \prod A: \text{Type} . \prod B: (A \to \text{Type}). \prod a: A.B(a) \to \text{Type}$.

3.1 Labeled transition system based on metagraph rewriting

In guarded cubical type theory, a guarded labeled transition system (GLTS) may be defined via a state-space X, a space of actions A, and a function mapping states to sets of (action, state) pairs, $f: X \to P_{\text{fin}}(A \times \triangleright X)$, where P_{fin} is the finite powerset functor. The space of all processes, or runs of the GLTS may the be defined as the final coalgebra of the following functor: $\operatorname{Proc} = \operatorname{fix} X.P_{\operatorname{fin}}(A \times \triangleright (\alpha : \mathbb{T}).X[\alpha]))$ (see [10]). In order to characterize the process of evaluation in M, we characterize the computational dynamics of M via a GLTS. Here, the state space is the space of all M metgraphs, X = $\mathcal{M}_{\mathbb{M}}$. The actions are specified by single pushout (SPO) rewriting rules, or sequences of such rules. We therefore introduce the type, $\mathcal{A}' = \mathcal{M}_{\mathbb{M}}^{(L,R)} \times \mathrm{hom}_p(\mathcal{M}_{\mathbb{M}})$, whose values (M', ϕ) consist of a \mathbb{M} metagraph whose label set is $\mathcal{L}' = \mathcal{L} \times \{L, R, LR\} \times \{L, R, LR\}$ $\{[], *, **\}$, i.e. identical to above, but with L and R labels added to each edge to indicate its membership of the left or right-hand side of the rule (notice that these may overlap), * and ** to indicate the input and output nodes of the rule (see below), and ϕ , a partial metagraph homomorphism between the L and R metagraphs of M' (defining a partial metagraph homomorphism as in [8]). Since we wish to allow sequences of rewrite rules as actions, we define the full action space to be $A = \sum n : \mathbb{N}$. Vec(n, A'), and write the members of \mathcal{A} as $a_1 \circ a_2 \circ ... \circ a_n$, where $a_{1...n} : \mathcal{A}'$. The dynamics are then defined (via f) by mapping a given metagraph state M_1 to the set of all pairs (A, M_2) such that M_2 results from an application of action A to M_1 . For individual rewrite rules $a \in \mathcal{A}'$, their action is determined via a partial homomorphism between a and M_1 . We note that, when there are no partial homomorphisms between a and M_1 , or when the rewrite rule produces an invalid M graph, we set $M_2 = M_1$. Further, we note that the update may change the \leq relation, for instance by introducing an edge of the form $t_1 \leq t_2$.

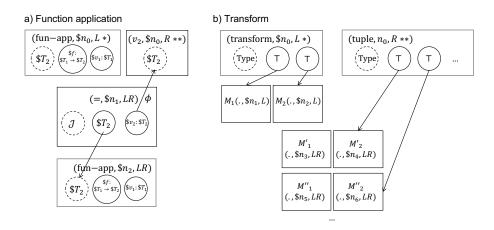


Fig. 2. Metagraph rewriting rules. Notation as in Fig. 1. Subgraphs involving only one variable are not shown explicitly, but notated directly on the targets they are connected to. See Eqs. 8 and 9 for explicit expressions for the graphs.

3.2 M-interpretation as metagraph dynamics

We can now describe interpretation in $\mathbb M$ via the GLTS defined above. To do so, we map specific symbols/edges in the metagraph to actions in $\mathcal A$ (corresponding to the grounding domain F in [8]). Specifically, edges carrying symbols of a function type, $A \to B$, dependent product type, $\prod a:A.B$, or the transform symbol, are mapped to specific forms of rewrite rule, as specified below. All other edges are mapped to the null transform. Fig. 2 specifies the general forms of the rewrite rules for function application, and transform rules (we note the transform is equivalent to the 2-argument match keyword/function in the current version of the MeTTa language, see [16]). The dependent product rule is identical to Fig. 2a, with $A \to B$ replaced with $\prod a:A.m_1$ For explicitness, we give these below also in equational form. We note that, for convenience variable names are denoted using \$, although these should be ultimately mapped to the names v_1, v_2, \ldots

$$\begin{split} R_{\text{fun-app}}^1 &= \text{edge}(2,\$T_2, (\text{fun-app}, \$n_0, L), [\$T_1 \to \$T_2 \ \$T_1]) \\ R_{\text{fun-app}}^2 &= \text{edge}(2,\mathcal{J}, (=,\$n_1, LR), [\$T_2 \ \$T_2]) \\ R_{\text{fun-app}}^3 &= \text{edge}(2,\$T_2, (\text{fun-app}, \$n_2, LR), [\$T_1 \to \$T_2 \ \$T_1]) \\ R_{\text{fun-app}}^4 &= \text{edge}(0,\$T_1 \to \$T_2, (\$f, \$n_3, LR), []) \\ R_{\text{fun-app}}^5 &= \text{edge}(0,\$T_1, (\$v_1, \$n_4, LR), []) \\ R_{\text{fun-app}}^6 &= \text{edge}(0,\$T_2, (\$v_2, \$n_5, LR **), []) \\ R_{\text{fun-app}}^7 &= \text{connect}(\text{connect}(R_{\text{fun-app}}^1, R_{\text{fun-app}}^4, \top, \text{null}, \{(1,0)\})), \\ R_{\text{fun-app}}^5 &= \text{connect}(\text{connect}(R_{\text{fun-app}}^3, R_{\text{fun-app}}^4, \top, \text{null}, \{(1,0)\})), \\ R_{\text{fun-app}}^8 &= \text{connect}(\text{connect}(R_{\text{fun-app}}^3, R_{\text{fun-app}}^4, \top, \text{null}, \{(1,0)\})), \end{split}$$

$$R_{\text{fun-app}}^{5}, \top, \text{null}, \{(5,0)\})$$

$$R_{\text{fun-app}}^{9} = \text{connect}(\text{connect}(R_{\text{fun-app}}^{2}, R_{\text{fun-app}}^{3}, \top, \text{null}, \{(1,0)\})),$$

$$R_{\text{fun-app}}^{5}, \top, \text{null}, \{(5,0)\})$$

$$R_{\text{fun-app}} = R_{\text{fun-app}}^{7} \cup R_{\text{fun-app}}^{8} \cup R_{\text{fun-app}}^{9}$$

$$(8)$$

$$R_{\text{transform}}^{1} = \text{edge}(2, \text{Type}, (\text{transform}, \$n_{0}, L), [\top \top])$$

$$R_{\text{transform}}^{2} = \text{connect}(\text{connect}(R_{\text{transform}}^{1}, \$M_{1}, \top, \text{null}, \{(1,0)\})),$$

$$\$M_{2}, \top, (\text{null}, \text{null}, L*), \{(5,0)\})$$

$$R_{\text{transform}}^{3} = \text{edge}(2, \text{Type}, (\text{tuple}, \$n_{0}, R **), [\top \top])$$

$$R_{\text{transform}}^{4} = \$M'_{1} \cup \$M''_{1} \cup \$M''_{2} \cup \$M''_{2} \cup \text{edge}(0, \top, (\text{null}, \text{null}, LR), [])$$

$$R_{\text{transform}}^{5} = \text{connect}(R_{\text{transform}}^{3}, R_{\text{transform}}^{4}, \top, (\text{null}, \text{null}, \text{null}), \{(1,1), (2,2)\}))$$

$$R_{\text{transform}} = R_{\text{transform}}^{2} \cup R_{\text{transform}}^{5} = R_{\text{transform}}^{5} \cup R_{\text{transform}}^{5} = R_{\text{transf$$

In Eq. 9, M_1' and M_2' denote metagraphs isomorphic to M_1 and M_2 , using a disjoint set of variables, while M_1'' and M_2'' are defined similarly, with variables disjoint to the previous subsets. The rule in Eq. 9 is defined so as to return a 2-tuple of matches; in general, the size of the tuple returned should be large enough to allow for any number of matches (i.e the number of nodes in M), and if the number of matches is less than this, it will be padded with null values.

fun-app nodes. For a given annotated fun-app node, i.e. connect $(@, F, \text{null}, \{(1,0)\})$), where $@ = \text{edge}(1, \mathcal{X}, (@, n), [\top])$ and F is a graph consisting of a target fun-app node and its two arguments, the full rewrite rule rewrite F is found by forming a metagraph homomorphism between $R_{\text{fun-app}}^7$ (labeled by * as the input of the rule), and F, replacing the variables in $R_{\text{fun-app}}$ by their values in F. The resulting graph is denoted $R_{\text{fun-app}}(F)$. The rule rewrite F is then defined by the subgraphs F = connect $(M_0, \text{connect}(M_0, \text{conne$

transform nodes. For a given annotated transform node, the full rewrite rule is defined similarly. Hence, for connect(@, F, null, $\{(1,0)\}$)), where @ = edge(1, \mathcal{X} , (@, n), $[\top]$) and F is a graph consisting of a target transform node and its two arguments, the full rewrite rule rewrite F is found by forming a metagraph homomorphism between $R^2_{\text{transform}}$ (labeled by * as the input of the rule), and F, replacing the variables in $R_{\text{transform}}$ by their values in F. The resulting graph is denoted $R_{\text{transform}}(F)$. The rule rewrite F is then defined by the subgraphs F = connect(\$ M_0 , connect(@, R_0 , R_0), null, R = connect(\$ R_0), R = connect(\$R = connect(\$ R_0), R = connect(\$R = connect(\$R

M-evaluation. The above provides groundings for activated nodes in a metagraph; as noted, nodes not of the form above result in a null update. Evaluation in M involves repeatedly updating the current pointed metgraph according to the grounding of the node currently pointed to. The conditions in Eq. 7 imply there will be at most one edge labeled with \dagger in a metagraph, whose target F specifies the rule by which the graph is updated. This is expressed via the single partial function, $update : \mathcal{M}_{\mathbb{M}} \to \mathcal{M}_{\mathbb{M}}$. The action of update is determined by the form of F. If F is not an activated subgraph, i.e. it is not the target of an @-edge, the action update cannot be applied (i.e. evaluation halts). If however F is the target of an @-edge, update first checks if F itself has any activated targets. If so, then update simply applies a graph rewrite which moves the pointer † to the first such activated target (in the ordering of the edge). If not, update applies rewrite_F, which automatically ensures that the update will finish with † pointing to the output subgraph, labeled **. These dynamics define a reduced GLTS, with $X = \mathcal{M}_{\mathbb{M}}$, $A = \{\text{update}\}, \text{ and } f(M) = \{(\text{update}, M'| \text{update}(M) = M')\}.$ Note that there may be multiple M's for which update(M) = M' if rewrite_F for a fun-app node is non-deterministic. Processes are defined by the fixed point $\operatorname{Proc} = \nu(P_{\operatorname{fin}}(A \times \triangleright X))$. Normal forms of $\mathcal{M}_{\mathbb{M}}$ are metagraphs for which update cannot be applied (i.e. their grounding is null). Processes which reach a normal form are said to be terminating, and the initial expression of the process is said to evaluate to the normal form reached. Alternatively, certain expressions may not reach a normal form, resulting instead in a non-terminating computation.

4 Bisimulation of type systems in M

As described in [10], in guarded cubical type theory, a bisimulation $R: X \to X \to U$ for the GLTS (X, A, f) may be defined via the following dependent type:

$$\operatorname{isGLTSBisim}_{f} R = \prod x, y : X.R(x, y) \to (\prod x' : \triangleright X. \prod a : A.(a, x') \in f(x) \to \exists y' : \triangleright X. \prod a : A. (a, y') \in f(y) \times \triangleright (\alpha : \mathbb{T}).R(x'[\alpha])(y'[\alpha])) \times (\prod y' : \triangleright X. \prod a : A.(a, y') \in f(y) \to \exists x' : \triangleright X. \prod a : A. (a, x') \in f(x) \times \triangleright (\alpha : \mathbb{T}).R(x'[\alpha])(y'[\alpha])).$$
 (10)

As shown in [10], this type is equivalent to the path type over the recursive data type of processes defined by the GLTS, $\operatorname{Proc} = \operatorname{fix} X.P_{\operatorname{fin}}(A \times \triangleright (\alpha : \mathbb{T}).X[\alpha]))$. We may further define a bisimulation $R_2: X_1 \to X_2 \to U$ between two GLTS's over a common action space, (X_1, A, f_1) and (X_2, A, f_2) via a bisimulation over their coproduct (see [1]):

is2GLTSBisim_{$$f_1, f_2$$} $R_2 = \text{isGLTSBisim}_{f_1 + f_2} R'_2 \times \forall x_1 : X_1. \exists x_2 : X_2. R_2(x_1, x_2) \times \forall x_2 : X_2. \exists x_1 : X_2. R_1(x_1, x_2)$ (11)

where
$$R_2': (X_1+X_2) \to (X_1+X_2) \to U$$
, $R_2'((a,x),(b,y)) = R(x,y)$ when $a=1 \land b=2$, $R_2'(x,y)=\bot$ otherwise, and $f_1+f_2: (X_1+X_2) \to \mathcal{P}(A \times (X_1+X_2))$

defined similarly. Since $R_2(x_1,x_2)$ contains at least one matching element for each x_1 and x_2 , we may extract functions $g_1: X_1 \to X_2$ and $g_2: X_2 \to X_1$ as subsets of R_2 , where an element in the codomain of each is chosen arbitrarily when there are multiple matches in R_2 . Since bisimulation corresponds to path-equivalence for elements of each type, g_1 and g_2 , we can choose π_1 and π_2 such that $g_1 \circ g_2 \circ \pi_1 = i_1$ and $g_2 \circ g_1 \circ \pi_2 = i_2$, where i_1 and i_2 are the identity on X_1 and X_2 respectively, and $\pi_1(x) = x' \Rightarrow \exists p: \operatorname{Path}_{X_1}(x,x'), \pi_2(x) = x' \Rightarrow \exists p: \operatorname{Path}_{X_2}(x,x')$. Hence, (g_1,g_2) is an equivalence between the recursive process types Proc_1 and Proc_2 of the two GLTS's, meaning that $\operatorname{Path}_U(\operatorname{Proc}_1,\operatorname{Proc}_2)$ is inhabited by univalence.

For a given type system, its computational content may be modeled by a GLTS by setting X to be the type of expressions in the system, A to contain an update action along with 'actions' corresponding to the judgmental and syntactic relations between expressions (e.g. is-of-type, is-of-subtype, is-a-body-of-lambda-term, and their opposite relations), and f to be the relation over expressions corresponding to the reduction relation in the system for the action update (for instance β -reduction). To show that M can be used as a metalanguage for a given type system, we thus show that there is a bisimulation between M with a specific form of Atomspace (i.e. containing specific atoms and/or additional constraints to those of Eq. 7), along with an expanded action space to incorporate the typing and syntactic relations relevant to the specific system, and the GLTS corresponding to computation in the target type system; hence the process spaces induced by the two systems are equivalent. Below, we sketch how this can be achieved for three type systems of interest, focusing on the how the computational dynamics of the update rule correspond to reduction in the target system (the typing and syntactic relations in each system straightforwardly correspond in M to the inbuilt typing relation and relationships definable in terms of submetagraph composition respectively).

4.1 Simply typed lambda calculus

The syntax for the simply typed lambda calculus may be defined via mutually recursive definitions of variable, type and expression datatypes:

$$\mathcal{V} ::= v_n
\mathcal{T} ::= t_n \mid \mathcal{T} \to \mathcal{T}
\mathcal{E} ::= \mathcal{V} \mid (\mathcal{E} \mathcal{E}) \mid \lambda v_n : \mathcal{T} \cdot \mathcal{E}$$
(12)

We refrain from explicitly stating the rules for type assignment as can be found in [2], which determine a typing relation $_$: $_$ between \mathcal{E} and \mathcal{T} given a context Γ , which can be modeled as a partial map from \mathcal{V} to \mathcal{T} . Together, these determine a set of valid expressions, $\mathcal{E}_{(\underline{\cdot}:\underline{\cdot},\Gamma)}$, and the computational dynamics is defined by the β -reduction relation over this type:

$$((\lambda v_{n_1} : t_{n_2}.e_{n_3}) e_{n_4}) \to_{\beta} e_{n_3}[v_{n_1}/e_{n_4}]$$
(13)

where a[b/c] denotes substitution of b for c in a, where any bound variables in c are renamed so as not to clash with bound variables in a.

To simulate the simply typed lambda calculus in \mathbb{M} , we restrict the \mathbb{M} atomspace to include only metagraphs labeled with types using the restricted type syntax of Eq. 12, and including only keywords/symbols $\{:,=,\rightarrow,\text{fun-app},@,\dagger\}$. Then, we add the following constraint to those of Eq. 7:

$$\forall m \in M.l(m) = (:, n_1) \Rightarrow (m_M[1] \in \mathcal{S} \vee \mathcal{V}) \wedge m_M[2] \in \mathcal{T}$$
(14)

Hence, all typing relations are between symbols or variables (representing global and local variables respectively) and types. The context Γ is then represented by an atom-space consisting of a set of : edges between symbols and types. A given lambda expression $e = \lambda x : t_1.e'$, where $e' : t_2$ is then simulated by choosing an unused symbol, $f_e \in \mathcal{S}$, and introducing the following atoms to atomspace:

$$(: f_e (\to t_1 t_2)) (= (f_e \$x) m_{e'})$$
 (15)

where $m_{e'}$ is the metagraph corresponding to expression e' (we note that Eq. 15 defines a combinator corresponding to the lambda term e). With the atomspace so specified, reduction of an expression e in context Γ in the simply typed lambda calculus corresponds to repeated application of update to the pointed atomspace containing Γ and m_e , with @ edges attached to all function application nodes, and the \dagger pointing to m_e . The computation terminates with \dagger pointing to the normal form of e. The required bisimulation thus involves pairing tuples (Γ, e) in the simply typed lambda calculus with their corresponding pointed atomspaces in $\mathbb M$. We note further that the untyped lambda calculus can be defined by simply removing $\mathcal T$ from the syntax in Eq. 12, and letting lambda expressions take the form $\lambda v_n.\mathcal E$. All members of $\mathcal E$. are considered legal expressions, and the $\mathbb M$ bisimulation is achieved by converting all type symbols to \top_{Type} , hence treating \top_{Type} as a Scott domain.

4.2 Pure Type Systems

In a pure type system (PTS, [2]), types and terms are not distinguished syntactically. PTS expressions follow the syntax:

$$\mathcal{V} ::= v_n
\mathcal{C} ::= s_{1...N}
\mathcal{E} ::= \mathcal{V} \mid \mathcal{C} \mid (\mathcal{E} \mathcal{E}) \mid \lambda v_n : \mathcal{E}.\mathcal{E} \mid \prod v_n : \mathcal{E}.\mathcal{E}$$
(16)

Here, $\mathcal C$ is a set of constant symbols, which in a PTS are used to represent *sorts*. The typing relation: for a PTS is defined via a set of axioms and rules. The former consist of a set of judgements $\mathcal A=\{s_m:s_n|(m,n)\in A\subset N\times N\}$, and the latter a set of triplets $\mathcal R=\{(s_l,s_m,s_n)|(l,m,n)\in R\subset N\times N\times N\}$. The typing rules for a PTS are identical to the typed lambda calculus, except for the introduction rule for dependent products, which takes the form:

$$\frac{\Gamma \vdash A : s_l \ \Gamma, A : s_l \vdash B : s_m \ (s_l, s_m, s_n) \in \mathcal{R}}{\Gamma \vdash (\prod x : A.B) : s_n}$$

The legal expressions then consist of the sorts, and any expression that can be typed in a context Γ , consisting of multiple typing judgments $e_1:e_2$. The β -reduction relation is established identically to the simple lambda calculus above. Notice that there is no restriction on the form of $\mathcal A$ and $\mathcal R$; hence the typing relation: may be arbitrary between sorts (and hence may contain cycles), while the dependent product (i.e. dependent function types) may live in arbitrary sorts with respect to their inputs.

To simulate a PTS in \mathbb{M} , we select a collection of fixed types $t_1...t_N$ to represent the sorts. We then add edges of the following forms to atomspace:

```
(: t_{m} t_{n}), \forall (s_{m}, s_{n}) \in \mathcal{A}
(: (\rightarrow \$t_{a} \$t_{b}) \text{ (transform } (: \$t_{a} t_{l}) \land (: \$t_{b} t_{m}) t_{n})), \forall (s_{l}, s_{m}, s_{n}) \in \mathcal{R}
(: (\prod \$x : \$t_{a}.\$m) \text{ (transform } (: \$t_{a} t_{l}) \land (: \$m t_{m}) t_{n})), \forall (s_{l}, s_{m}, s_{n}) \in \mathcal{R}
(17)
```

As above, lambda expressions are simulated by adding atoms of the form in Eq. 15 to the atomspace, and a context Γ is simulated by adding atoms corresponding to the typing relations it contains. Reduction of expression e in context Γ is simulated as previously by applying update to the pointed atomspace consisting of $\{\Gamma, e\}$ and the above constructions, along with \dagger pointing to e. Further, we note that we can use PTS's can be regarded as a type-theoretic analogue of non-well-founded sets; from this viewpoint, a cyclical : relation corresponds to an accessible pointed graph (apg) underlying a non-well-founded set. For instance, including the axiom $s_1: s_1$ in $\mathcal A$ defines s_1 as a type-theoretic analogue of a Quine atom. We note, however, that in the type-theoretic context, a cyclic PTS carries more structure than a non-well-founded set, since the rules $(\mathcal R)$ carry information about how the \rightarrow constructor interacts with the : relation. An interesting conjecture though would be that appropriately defined PTS's provide bisimulations of systems of non-well-founded sets definable within a recursive datatype (via a coalgebra on the powerset functor, definable in GCTT), as a general system of set equations ([3]) involving both \in and \rightarrow relations.

4.3 Probabilistic dependent types

Finally, we outline a version of the probabilistic dependent type system introduced in [19], and its bisimulation in \mathbb{M} . The syntax is a variation on the dependently typed lambda calculus:

$$\mathcal{V} ::= v_n
\mathcal{T} ::= t_n \mid \prod v_n : \mathcal{T}.\mathcal{E} \mid \mathcal{D}(\mathcal{T}) \mid \mathcal{T} \cup \mathcal{T} \mid \mathcal{T} \cap \mathcal{T} \mid \text{ Type}
\mathcal{E} ::= \mathcal{V} \mid (\mathcal{E} \mathcal{E}) \mid \lambda v_n : \mathcal{T}.\mathcal{E} \mid \text{ random}_{\rho}(\mathcal{E}, \mathcal{E}) \mid \text{ sample}(\mathcal{E}) \mid \text{ thunk}(\mathcal{E})$$
(18)

Further, we allow the judgments $\mathcal{E}:\mathcal{T}$ (typing), $\mathcal{T}\preceq\mathcal{T}$ (subtyping), and $\mathcal{E}\to^{\rho}_{\beta}\mathcal{E}$ (weighted β -reduction), where $\rho\in\mathbb{R}$. The typing rules are as for the dependent typed lambda calculus for expressions not involving subtypes or probabilistic terms. The typing rules for subtypes include the standard $\Gamma\vdash a:A,\ A\preceq B\Rightarrow \Gamma\vdash a:B$,

 $\Gamma \vdash A, B : \text{Type} \Rightarrow \Gamma \vdash A \cap B \leq A, \ A \cap B \leq B, \ A \leq A \cup B \ B \leq A \cup B, \ \Gamma \vdash A \leq B \Rightarrow \prod v_n : B.\mathcal{E} \leq \prod v_n : A.\mathcal{E}, \ \Gamma, x : t \vdash A \leq B \Rightarrow \prod x : t.A \leq \prod x : t.B.$ These interact with the probabilistic terms via the following special rules:

$$\frac{\Gamma \vdash a : t_1, \ b : t_2}{\Gamma \vdash \operatorname{random}_{\rho}(a, b) : t_1 \cup t_2}$$

$$\frac{\Gamma \vdash A : \operatorname{Type}, p_A : \mathcal{D}(A)}{\Gamma \vdash \operatorname{sample}(p_A) : A}$$

$$\frac{\Gamma \vdash a : A}{\Gamma \vdash \operatorname{thunk}(a) : \mathcal{D}(A)}$$

where, we note that $\mathcal{D}(A)$ denotes the type of distributions over A (so, for instance, if $a:t_1,\ b:t_2$, then thunk(random $_{\rho}(a,b)$): $\mathcal{D}(t_1\cup t_2)$). For all expressions not involving probabilistic terms, $e_1\to_{\beta} e_2$ in the dependent typed lambda calculus implies $e_1\to_{\beta}^1 e_2$ in the PDTS above. For probabilistic terms, we have the following computational rules:

$$\operatorname{random}_{\rho}(a,b) \to_{\beta}^{\rho} a$$

$$\operatorname{random}_{\rho}(a,b) \to_{\beta}^{1-\rho} a$$

$$\operatorname{sample}(\operatorname{thunk}(p_{A})) \to_{\beta}^{1} p_{A}$$
(19)

Computationally, evaluation may proceed by stochastic β -reduction (i.e. sampling a reduction according to the weights ρ), or a 'full evaluation' may be made, by returning the set of all possible reduction sequences from a term, annotated with the total probability of each. We note that in any given reduction sequence, $e_1 \rightarrow_{\beta}^{\rho} e_2$ for $\rho > 0$ implies $t_2 \leq t_1$ where $e_1 : t_1, e_2 : t_2$.

For the formulation in \mathbb{M} , we constrain the typing relation and encode lambda terms as in Eqs. 14 and 15; further, as above we encode contexts Γ by fixing atoms of the form : in atomspace. To encode the probabilistic terms, we choose fixed symbols $s_{1...4}$ to correspond to Distribution, random, sample, thunk. Then, we fix the following atoms in atomspace:

```
(: Distribution (\rightarrow Type Type)),

(: random (\rightarrow $t_1 $t_2 $t_1 \cup $t_2)),

(= (random $a $b) $a),

(= (random $a $b) $b),

(: sample (\rightarrow (Distribution $t_1) $t_1)),

(: thunk (\rightarrow $t_1 (Distribution $t_1))),

(= (sample (thunk $a)) $a) (20)
```

Application of update to the pointed atomspace so defined, with \dagger pointing to m_e (corresponding to expression e), results in a simulation of a probabilistic reduction of e

in the PDTS above. As defined, update will simulate the 'full evaluation' of all possible paths, and hence a bisimulation exists between full evaluation dynamics in the PDTS GLTS using $\beta\rho$ -reduction and the GLTS defined by $\mathbb M$ with the restricted atomspace above. We note that, in both cases, the weights on particular paths are lost, since the ρ values are not explicitly recorded; however. it is straightforward to define a GLTS over the extended system, $(X \times \mathbb R, A, f)$, where $f(x) = \{((x_1, p_1), a_1), ((x_2, p_2), a_2), \ldots\}$ denotes that action a on x results in x_1 with probability p_1 , p_2 with probability p_2 , and so on.

5 Implementation of Bisimulation proof in a Guarded Cubical Type Theory type checker

We briefly give an example to show the feasibility of our approach with an implementation of a bisimulation proof for a small-scale type system in a Guarded Cubical Type Theory type checker [4]. Here, we model a minimal type system, which has one type constant A: Type with two constructors v_1, v_2 : A; one function constant $f_1: A \to A$, where $f_1(v_1) = v_2$ and $f_1(v_2) = v_1$; and includes the sample and thunk constructs, which are combined following the syntax of Eq. 18. Our implementation models a fragment of this system where expressions are restricted to include at most three subexpressions. Hence, valid expressions of the language include: $(f_1 \ (f_1 \ v_1))$, (thunk $(f_1 \ v_2)$), (sample (thunk v_1)), $(f_1 \ v_2)$. Our implementation in a Haskell-based Guarded Cubical Type Theory type checker [4] is given in Appendix A. Here, we implement evaluation in this system via (i) a pattern matcher over an atomspace ('update'), and (ii) direct implementation of β -reduction via case analysis over the expression space ('beta3'). We define GLTS's using both forms of evaluation ('str1' and 'str2'), and finally derive a proof that these GLTS's are bisimilar ('bisim'). The code for this example is also provided at: https://github.com/jwarrell/metta_bisimulation

6 Discussion

In the above, we have introduced a formal meta-probabilistic programming language, formalized in GCTT, and proposed that bisimutations link the specific object-languages (or domain specific languages) outlined above with their simulations in \mathbb{M} . Specifically, we have proposed that the restricted forms of \mathbb{M} outlined in Secs. 4.1 and 4.2 and 4.3 form bisimulations of the simply typed lambda calculus, arbitrary PTS's, and the target PDTS, respectively.

Finally, we mention some of the areas of investigation opened up by the formal model outlined. First, we note that, while we have focused on 'full' probabilistic programming evaluation, other possibilities include investigation of sampling based evaluation which performs only one meta-graph update at each step, stochastically chosen from the possible graph rewriting locations. Second, we intend to derive further bisimulations for other kinds of probabilistic logic, particularly, probabilistic paraconsistent logic [7], and probabilistic analogues of pure type systems [2], which may be suitable for models involving infinite-order probabilities [5]. Lastly, we intend to expand our implementation

of aspects of this framework in Guarded Cubical Agda [17] to provide more complete implementations of the metalanguage and type systems explored here.

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Appendices

A Proof of Bisimulation for Small-scale Type System in a Guarded Cubical Type Theory type checker

Below, we provide the code for the example discussed in Sec. 5, which uses a Haskell-based GCTT type checker [4]. The code for this example is also provided at: https://github.com/jwarrell/metta_bisimulation

Keywords, Preliminaries and Helper functions

Evaluation via MeTTa pattern matching

```
- Evaluation via MeTTa pattern matching
-- rules
data rule
= Cons (r1 : K) (r2 : K) (r3 : K)
as : A = cons (Cons s t nl) (cons (Cons f1 v1 v2) (cons (Cons f1 v2 v1) nil))
00 shows - Compress

comp_fun (k: k) (ks: list K): (list K)
= fun1 ks k
where fun1 (ks: list K): (k: K) → (list K) = split
n1 → ks
v1 → append K (cons v1 nil) ks
v2 → append K (cons v2 nil) ks
f1 → append K (cons f1 nil) ks
t → append K (cons f1 nil) ks
s → append K (cons s nil) ks
                                                                                                          upd_fun (r : rule) (ks : list K) : list K
= funl ks r
where funl (ks : list K) : (r : rule) → list K = split
Cons k1 k2 k3 → rewrite k1 k2 k3 ks
                                                                                                          compress (ks_in : list K) : (list K)
= foldr K (list K) comp_fun nil ks_in
```

Evaluation via direct β -reduction definition

```
-- beta reduction
beta3 : E3 → E3
= split
Cons k1 k2 k3 → fun1 k3 k2 k1

cons k1 k2 k3 → fun2 k3 k2

where fun1 (k3 k2 : K) : K → E3 = split
n1 → fun2 k3 k2

where fun2 (k3 : K) : K → E3 = split
n1 → cons n1 n1 k3
v1 → cons n1 v1 k3
v2 → cons n1 v2 k3
f1 → fun3 k3

where fun3 : K → E3 = split
n1 → cons f1 v1 k3
v2 → cons n1 v2 k3
f1 → fun3 k3

where fun3 : K → E3 = split
n1 → cons f1 f1 n1
v1 → cons n1 n1 v1
v1 → cons n1 n1 v1
v1 → cons n1 n1 v1
v2 → cons n1 k3
f1 → cons n1 f1 f1
t → cons n1 f1 f1
t → cons n1 f1 f1
t → cons n1 f1 s
s → cons n1 t k3
s → cons n1 t k3
v2 → cons n1 k3
v1 → cons v1 k3
v2 → cons n1 k3
v2 → cons n1 k3
v1 → cons v1 k3
v2 → cons n1 k3
v2 → cons n1 k3
v2 → cons n1 k3
v1 → cons n1 f1 f1
t → cons n1 f1 f1
t → cons n1 f1 f1
t → cons n1 f1 s
v1 → cons n1 k3
v2 → cons n1 k3
v1 → cons n1 f1 s
v1 → cons n1 k3
v2 → cons n1 k3
v2 → cons n1 k3
v2 → cons n1 k3
v1 → cons n1 f1 s
v1
```

Proof of Bisimulation

```
— Guarded Streams
data gStr (A: U) k
= Cons (x: A) (xs: |> k (gStr A $ k))

Str (A: U): U
= forall k, gStr A $ k
— Head and Tail
ghd (A: U) k: (xs: gStr A $ k) → A
= split
Cons x _ → x

gtl (A: U) k: (xs: gStr A $ k) → |> k (gStr A $ k)
= split
Cons _ ys → ys

hd (A: U) (xs: Str A): A
= ghd A $ k0 (xs $ k0)

tl (A: U) (xs: Str A): Str A
= prev k (gtl A $ k (xs $ k))
— Iteration
tierate k (A: U) (f: A → A): A → gStr A $ k
= fix k it (A → gStr A $ k)
Cons a (next k [it' < - it] (it' (f a))))
— Cissimulation between streams
data Bisimilar (A: U) (xs ys: Str A) =
consBit h: Id A (hd A xs) (hd A ys))
(t: Bisimilar A (tl A xs) (tt A ys))
```

```
-- update using beta reduction
update1 (e: Expr): Expr
= list_to_Expr (compress (E3_to_list (beta3 (m1 e))))

-- update using pattern matching
update2 (e: Expr): Expr
= list_to_Expr (update (m2 e))

-- generate stream from any starting expression
str1 (e0: Expr): Str Expr = [ k ] iterate $k Expr update1 e0

str2 (e0: Expr): Str Expr = [ k ] iterate $k Expr update2 e0

-- proof that streams starting from same expression are bisimilar
bisim: (e0: Expr): $(Bisimilar Expr (str1 e0) (str2 e0)) = split
v1 → cons8i (ref1 Expr v1) (bisim v2)
f1 → cons8i (ref1 Expr v1) (bisim v2)
f1 → cons8i (ref1 Expr f1_v1) (bisim v1)
f1_v1 → cons8i (ref1 Expr f1_v1) (bisim v1)
f1_v1 → cons8i (ref1 Expr f1_v1) (bisim v1)
f1_f1_v1 → cons8i (ref1 Expr f1_f1_v2) (bisim v1)
f1_f1_v1 → cons8i (ref1 Expr f1_f1_v2) (bisim v1)
t1_f1_v2 → cons8i (ref1 Expr f1_f1_v2) (bisim t1_v1)
t1_v1 → cons8i (ref1 Expr f1_v2) (bisim t1_v1)
t1_v2 → cons8i (ref1 Expr f1_v2) (bisim t1_v2)
t1_v1 → cons8i (ref1 Expr t1_v2) (bisim t1_v2)
t1_v2 → cons8i (ref1 Expr t1_v2) (bisim t1_v2)
s_tv1 → cons8i (ref1 Expr t2_v2) (bisim t2_v1)
s_tv2 → cons8i (ref1 Expr t2_v2) (bisim t2_v1)
t1_v2 → cons8i (ref1 Expr t2_v2) (bisim t2_v1)
s_tv2 → cons8i (ref1 Expr t2_v2) (bisim t2_v1)
s_tv2 → cons8i (ref1 Expr t2_v2) (bisim t2_v1)
```