

## Exercise7

June 19, 2020

### 1 Homework 7: Stability Analysis (20 points)

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Due on Friday, 19.06.2020.

```
[5]: #Load standard libraries
import numpy as np
from scipy.sparse import diags
import matplotlib.pyplot as plt
import scipy.linalg as la
%matplotlib inline
```

In this exercise we study the evolution of 6 populations according to the following equations for population dynamics: 3 predator- ( $P_i$ ) and 3 prey-species ( $N_i$ ), all parameters positive, always  $i, j = 1, \dots, 3$ :

$$\frac{dN_i}{dt} = N_i \left( a_i - N_i - \sum_j b_{ij} P_j \right) \quad (1)$$

$$\frac{dP_i}{dt} = P_i \left( \sum_j c_{ij} N_j - d_i \right) \quad (2)$$

The parameters chosen are  $a_1 = 56, a_2 = 12, a_3 = 35; d_1 = 85, d_2 = 9, d_3 = 35$ ; the parameters  $b_{ij}$  and  $c_{ij}$  are given in matrix form here:

$$b_{ij} = \begin{pmatrix} 20 & 30 & 5 \\ 1 & 3 & 7 \\ 4 & 10 & 20 \end{pmatrix}$$

$$c_{ij} = \begin{pmatrix} 20 & 30 & 35 \\ 3 & 3 & 3 \\ 7 & 8 & 20 \end{pmatrix}$$

Notice: the unusual feature here in the equations is that the prey populations  $N_i$  have a Verhulst style growth limiting factor in their equations, which limits their growth even if there is no predator

(model for limited resources even in absence of predators). Another Notice: please do not try to make the equations dimensionless, just use the numbers given here.

### 1.0.1 1. What are the fixed points for the system of equations given above?

1. FP:  $N_1 = 0; N_2 = 0; N_3 = 0; P_1 = 0; P_2 = 0; P_3 = 0$
2. FP:  $N_1 = 1; N_2 = 1; N_3 = 1; P_1 = 1; P_2 = 1; P_3 = 1$
3. FP:  $N_1 = a_1; N_2 = a_2; N_3 = a_3; P_1 = 0; P_2 = 0; P_3 = 0$

1. 5/5

### 1.0.2 2. What is the Jacobi matrix A at the non-trivial fixed point?

For the non-trivial FP :

$$N_1 = 1; N_2 = 1; N_3 = 1; P_1 = 1; P_2 = 1; P_3 = 1$$

The Jacobi matrix A is given as:

2. 5/5

$$A = \begin{pmatrix} -1 & 0 & 0 & -20 & -30 & -5 \\ 0 & -1 & 0 & -1 & -3 & -7 \\ 0 & 0 & -1 & -4 & -10 & -20 \\ 20 & 30 & 35 & 0 & 0 & 0 \\ 3 & 3 & 3 & 0 & 0 & 0 \\ 7 & 8 & 20 & 0 & 0 & 0 \end{pmatrix}$$

### 1.0.3 3. Determine the eigenvalues and eigenvectors $\lambda_i$ and $v_i, i = 1, \dots, 6$ of A for this fixed point.

```
[6]: A = np.
      →array([[ -1,  0,  0, -20, -30, -5], [ 0, -1,  0, -1, -3, -7], [ 0,  0, -1, -4, -10, -20], [20, 30, 35, 0, 0, 0], [ 3,  3,  3,  0,  0,  0], [ 7,  8, 20,  0,  0,  0]])
      print(A)

      eigvals, eigvecs = la.eig(A)
```

```
[[ -1   0   0 -20 -30 -5]
 [  0  -1   0  -1  -3 -7]
 [  0   0  -1  -4 -10 -20]
 [ 20  30  35   0   0   0]
 [  3   3   3   0   0   0]
 [  7   8  20   0   0   0]]
```

The eigenvalues  $\lambda$  are:

```
[7]: print(eigvals)
```

```
[-0.5      +33.62558388j -0.5      -33.62558388j
 -0.5      +7.67949446j  -0.5      -7.67949446j
 -1.13602378 +0.j         0.13602378 +0.j         ]
```

The eigenvectors  $v$  are:

```
[8]: print(eigvecs)
```

```
[[-0.00808048+5.43421815e-01j -0.00808048-5.43421815e-01j  
  -0.86913661+0.00000000e+00j -0.86913661-0.00000000e+00j  
  -0.53762066+0.00000000e+00j  0.08149945+0.00000000e+00j]  
 [-0.00138394+9.30713447e-02j -0.00138394-9.30713447e-02j  
   0.13809399-1.36932149e-16j  0.13809399+1.36932149e-16j  
   0.29472269+0.00000000e+00j -0.04467786+0.00000000e+00j]  
 [-0.00436622+2.93633078e-01j -0.00436622-2.93633078e-01j  
   0.34158855+1.49181629e-16j  0.34158855-1.49181629e-16j  
   0.07549029+0.00000000e+00j -0.01144379+0.00000000e+00j]  
 [ 0.71189052+0.00000000e+00j  0.71189052-0.00000000e+00j  
   0.01084273+1.66533346e-01j  0.01084273-1.66533346e-01j  
  -0.64384894+0.00000000e+00j -0.81514582+0.00000000e+00j]  
 [ 0.0829838 +6.53568437e-18j  0.0829838 -6.53568437e-18j  
   0.00986382+1.51498294e-01j  0.00986382-1.51498294e-01j  
   0.44208849+0.00000000e+00j  0.55970673+0.00000000e+00j]  
 [ 0.30991834+2.42444559e-17j  0.30991834-2.42444559e-17j  
  -0.01564017-2.40217184e-01j -0.01564017+2.40217184e-01j  
  -0.09176103+0.00000000e+00j -0.11617418+0.00000000e+00j]]
```

3.  
Eigenvalues/vector: 3/3

Why didn't you do evolution part? If you did but just didn't print it, please let me know (as soon as possible)