

# A HyFlex Module for the Max Cut Problem\*

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## 1 Problem Formulation

Given a weighted graph  $G$ , with vertices  $V$ , edges  $E \subset V \times V$  and weight function  $w : E \rightarrow \mathbb{R}$ . Find a cut, i.e. a partition of  $V$  into two disjoint subsets, such that the sum of the weights of the edges crossing both partitions is maximized. The search-space consists of all possible cuts  $V \rightarrow \{1, 2\}$  of  $G$ . Let  $p$  be a cut of  $G$  and  $E_\times = \{(v_i, v_j) \in E | p(v_i) \neq p(v_j)\}$  the set of crossing edges, the cost of  $p$  is then given by  $-\sum_{e \in E_\times} w(e)$ . This domain provides 10 benchmark instances: Instances 2-7 were generated using Rudy, a graph generator by Giovanni Rinaldi<sup>1</sup>. Instances 0-1, 8-9 are torus graphs taken from the 7th DIMACS Implementation Challenge.<sup>2</sup> The properties and best known solution qualities ( $f_{prev}$ ) of these instances are summarized in Table 1.

\*This description is an extract from [1]

<sup>1</sup>The full set can be found at <http://web.stanford.edu/~yyye/yyye/Gset/>

<sup>2</sup><http://dimacs.rutgers.edu/Challenges/Seventh/Instances/>

Table 1: Instances provided in the MAC domain

index	name	type	weights	$ V $	$ E $	$f_{prev}$
0	g3-8	torus	$\mathbb{Z}$	512	1536	41684814
1	g3-15	torus	$\mathbb{Z}$	3375	10125	283206561
2	g14	planar	1	800	4694	3064
3	g15	planar	1	800	4661	3050
4	g16	planar	1	800	4672	3052
5	g22	random	1	2000	19990	13359
6	g34	torus	1, -1	2000	4000	1384
7	g55	random	1	5000	12498	10299
8	pm3-8-50	torus	1, -1	512	1536	458
9	pm3-15-50	torus	1, -1	3375	10125	3014

## 2 Solution Initialisation

Vertices are greedily inserted in a random order in the partition that minimizes the cost of the cut on the sub-graph  $G_{partial}$  of  $G$ , containing only the vertices and edges between vertices, that were already inserted.

## 3 Low Level Heuristics

### 3.1 Local search heuristics

0. SWAPFIRST: Changes the partition of a random vertex that improves the quality of the solution.
1. SWAPBEST: Changes the partition of the vertex improving the quality of the solution most.
2. SWAPNEIGHBOURS: Changes the partition of the 2 neighbouring vertices improving the quality of the solution most. This move is performed only once.

The SWAPFIRST and SWAPBEST heuristics are repeated for  $\lceil 100\beta \rceil$  iterations or until no improving move exists.

### 3.2 Mutational heuristics

3. SWAPRANDOM: Changes the partition of a randomly selected vertex (repeated  $\lceil 10\alpha \rceil$  times).
4. SWAPRANDOMNEIGHBOURS: Changes the partition of the 2 randomly selected neighbouring vertices (repeated  $\lceil 5\alpha \rceil$  times).

### 3.3 Ruin-Recreate heuristics

5. RANDOMRR: Removes  $\lceil 50\alpha \rceil$  random vertices and re-inserts them in a random partition.
6. GREEDYRR: Removes  $\lceil 50\alpha \rceil$  random vertices and re-inserts them greedily, inserting the vertex in the partition, resulting in the best sub-cut.
7. RADIALRR: Removes  $\lceil 5\alpha \rceil$  random vertices and all their neighbours, and re-inserts them as in 6.

### 3.4 Crossover heuristics

8. ONEPOINTXO: Performs the one point crossover on the partitioning of vertices (ordered by  $id$ ).
9. MULTIPLEPARENTXO: Performs the multiple parent crossover described in [2].

## References

- [1] Steven Adriaensen, Gabriela Ochoa, and Ann Nowé. A benchmark set extension and comparative study for the hyflex framework. In *Evolutionary Computation (CEC), 2015 IEEE Congress on*. IEEE, 2015.
- [2] Qinghua Wu and Jin-Kao Hao. A memetic approach for the max-cut problem. In *Parallel Problem Solving from Nature-PPSN XII*, pages 297–306. Springer, 2012.