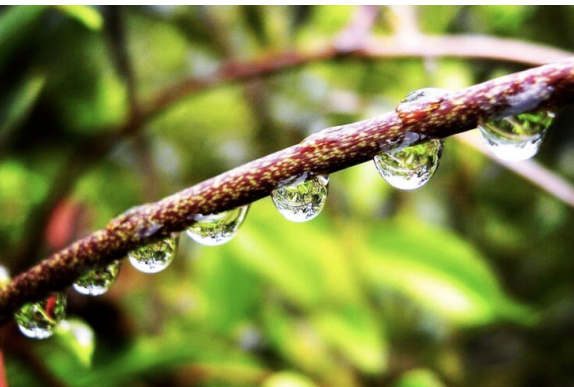


Imaging through turbulence (1)

EC 522 Computational Optical Imaging

Lei Tian



Admins

- » HWs

- » HW 6: posted, due 4/17

- » **Group lecture**

- » Reach out to me & your student mentor for discussions if needed

- » All questions are good questions

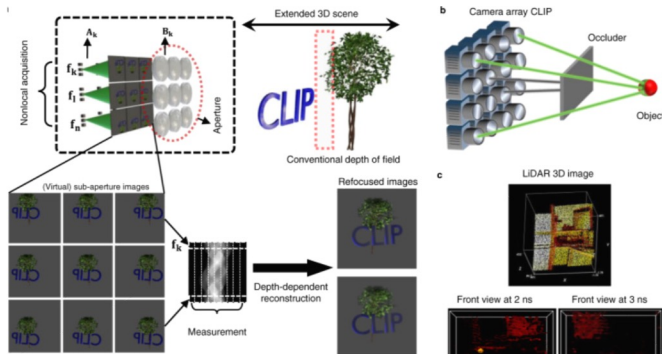
- » Grades are based on the demonstration of technical comprehension during the presentation



Group lectures begin					
3/18 (M)	Selected Topic in computational imaging		Group 1	HW 5: inverse problem 2	HW 4
3/20 (W)	Selected Topic in computational imaging		Group 2		
3/25 (M)	Selected Topic in computational imaging		Group 3		
3/27 (W)	Selected Topic in computational imaging		Group 4		
4/1 (M)	Selected Topic in computational imaging		Group 5	HW 6: inverse problem 3	HW 5
4/3 (W)	Selected Topic in computational imaging		Group 6		
4/8 (M)	Selected Topic in computational imaging		Group 7		
4/10 (W)	Selected Topic in computational imaging		Group 8		
4/15 (M)	Patriots' Day Holiday				
4/17 (W)	Selected Topic in computational imaging		Group 9		HW 6
4/22 (M)	Cancelled				
4/24 (W)	Final Projects		Group 1-3		
4/29 (M)	Final Projects		Group 4-6		
5/1 (W)	Final Projects		Group 7-9		

Theme: Computational photography

Group Lecture / Class Project 3: Lightfield imaging



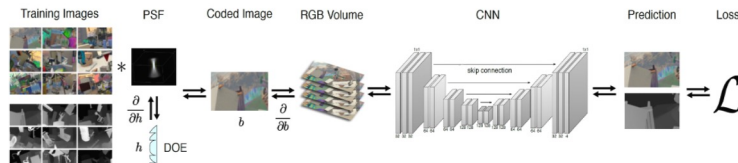
Team 4 - 3/27 (W) / 4/29 (M)

Paper: CLIP

- Saini Ye
- Chen Qian
- Yuxiang Su

Student mentor:
Qianwan Yang

Group Lecture / Class Project 5: Computational 3D photography



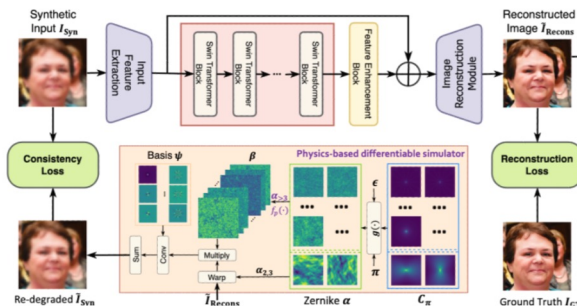
Team 5 - 4/1 (M) / 4/29 (M)

Paper: Depth from defocus

- Ian Lee
- Susan Zhang
- Wangyi Chen

Student Mentor:
Qianwan Yang

Group Lecture / Class Project 9: Computational imaging in complex media



Team 6 - 4/3 (W) / 4/29 (M)

Paper: Turbulence

- Shuyue Jia
- Hua Tong
- Yujie Zheng

Student mentor:
Tongyu Li

Team 7 - 4/8 (M) / 5/1 (W)

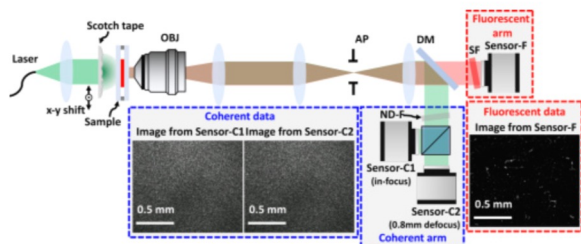
Paper: NeuWS

- Noa Margolin
- Nolan Vild
- Adhithi Ramasubramanian

Student Mentor:
Hao Wang

Theme: computational microscopy

Group Lecture / Class Project 8: Computational imaging with structured illumination

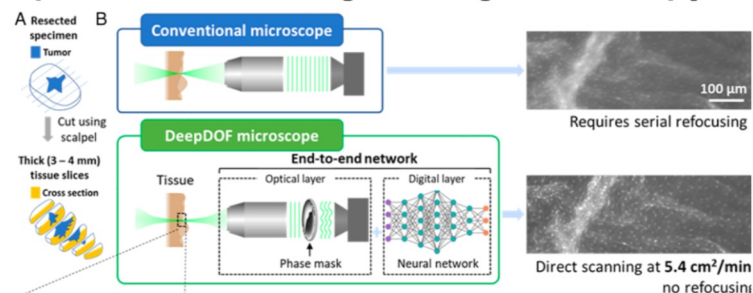


Team 8 - 4/10 (W) / 5/1 (W)

- Yi Shen
- Deming Li
- Kara Stratton

Student mentor:
Tongyu Li

Group Lecture / Class Project 7: Point spread function engineering microscopy

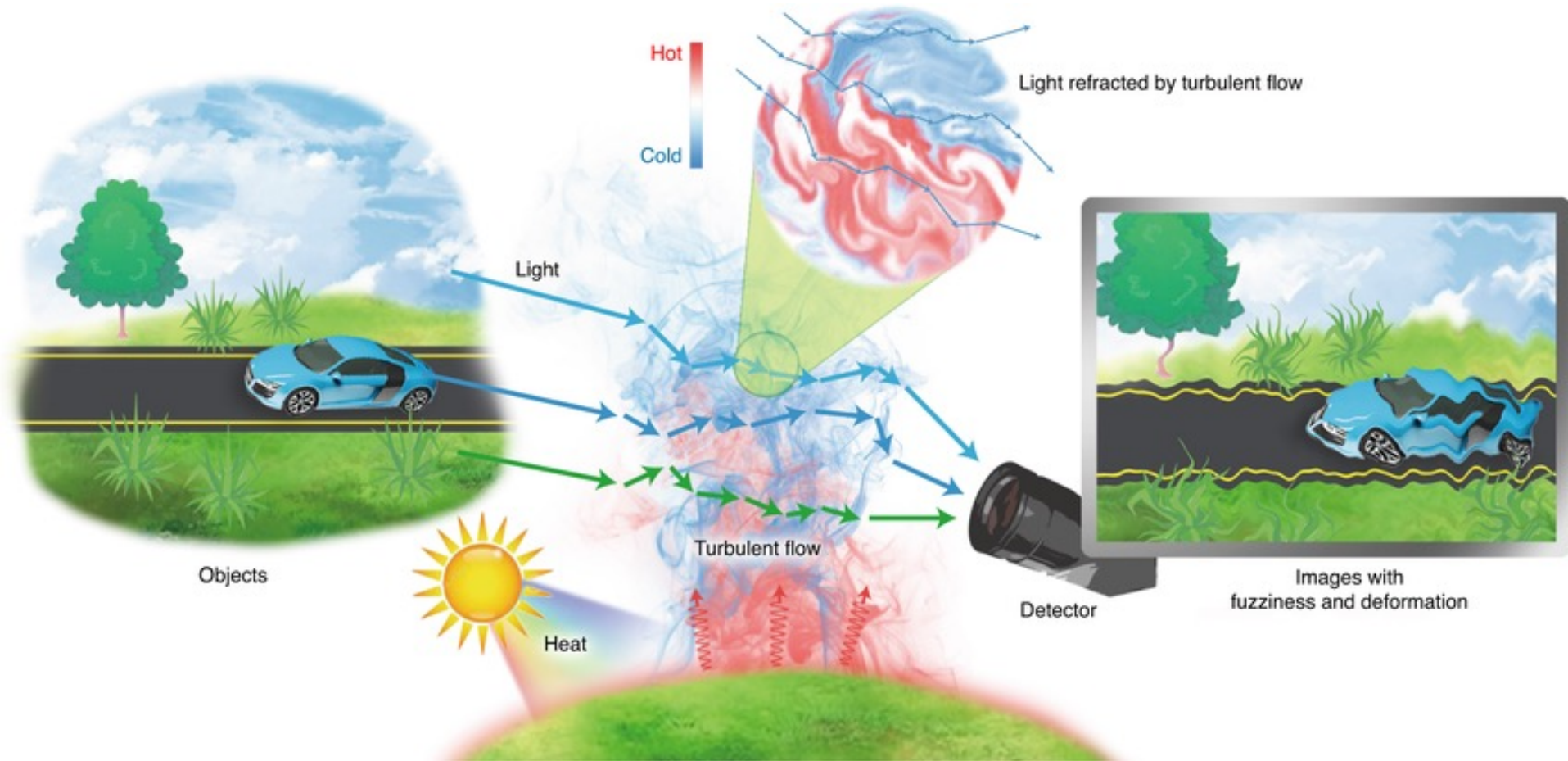


Team 9 - 4/17 (W) / 5/1 (W)

- Rachel Chan
- Qilin Deng

Student Mentor:
Joe Greene

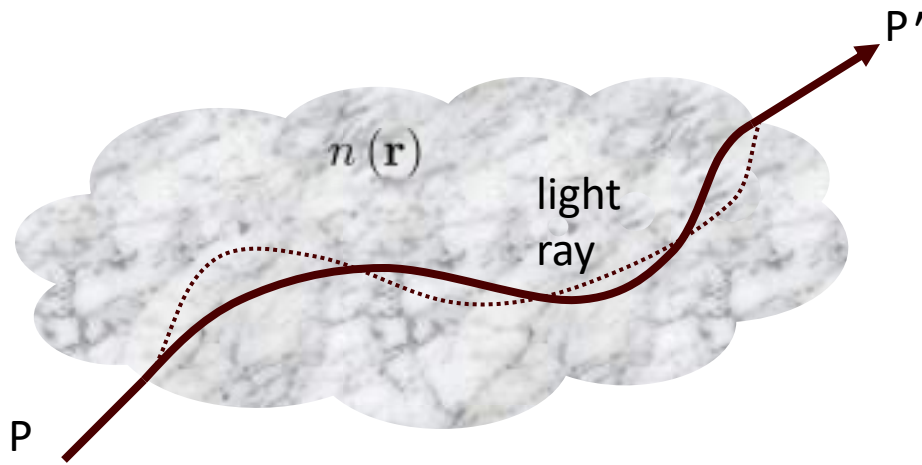
Why imaging through turbulence



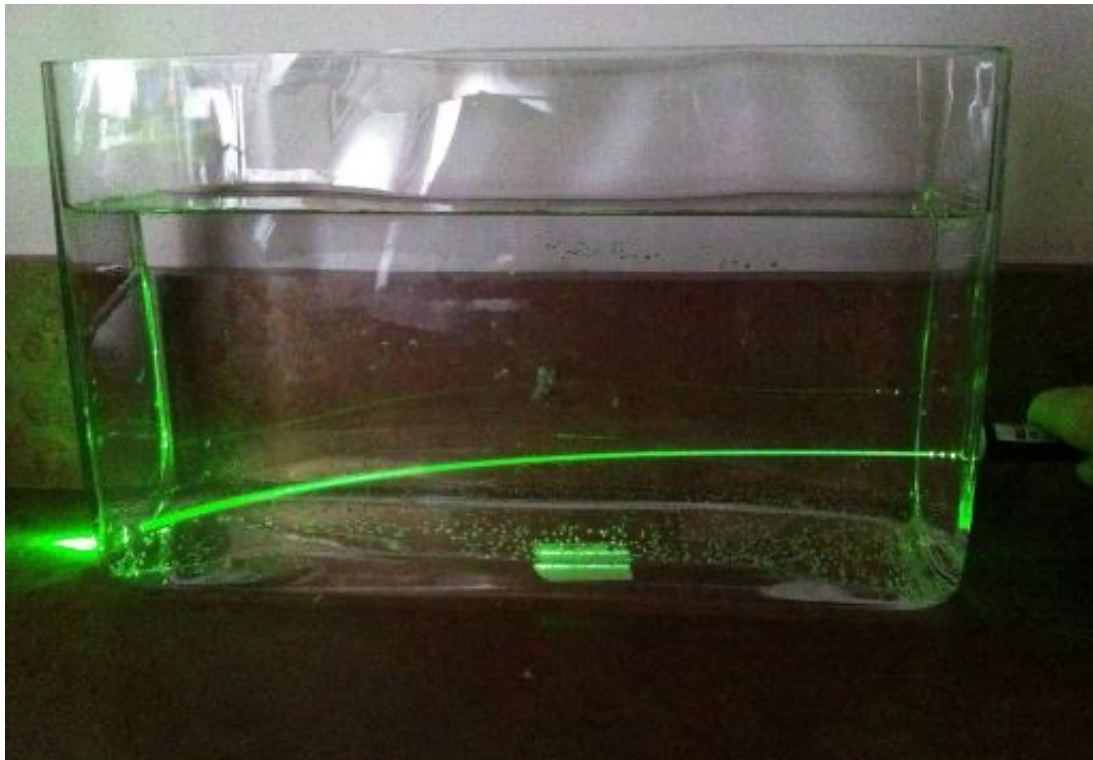
Light follows a **curved** path in an **inhomogeneous** medium!

material with variable optical “density”

(i.e. inhomogeneous refractive index (index of refraction))



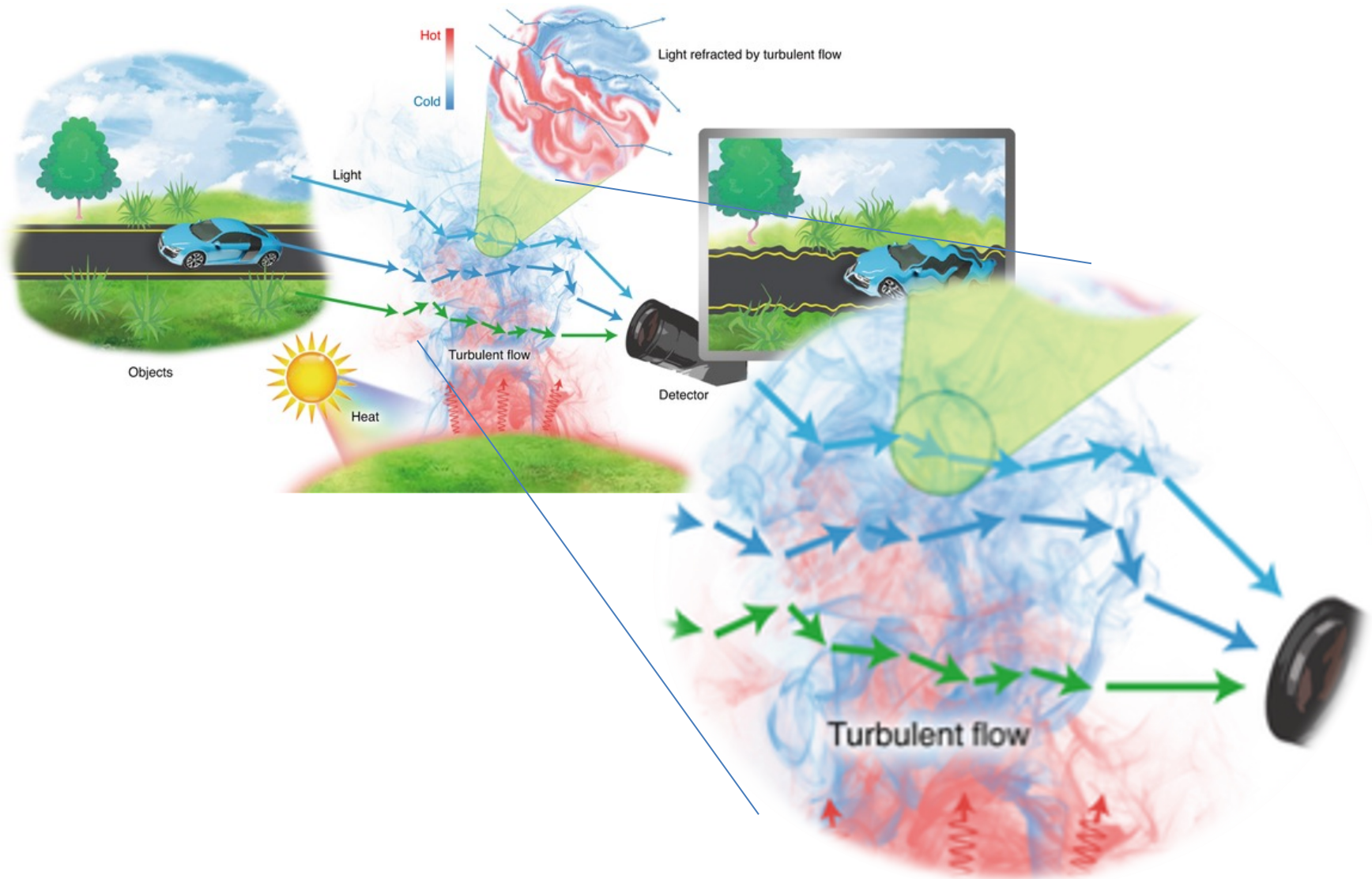
Example: Non-uniform medium with 1D non-uniformity



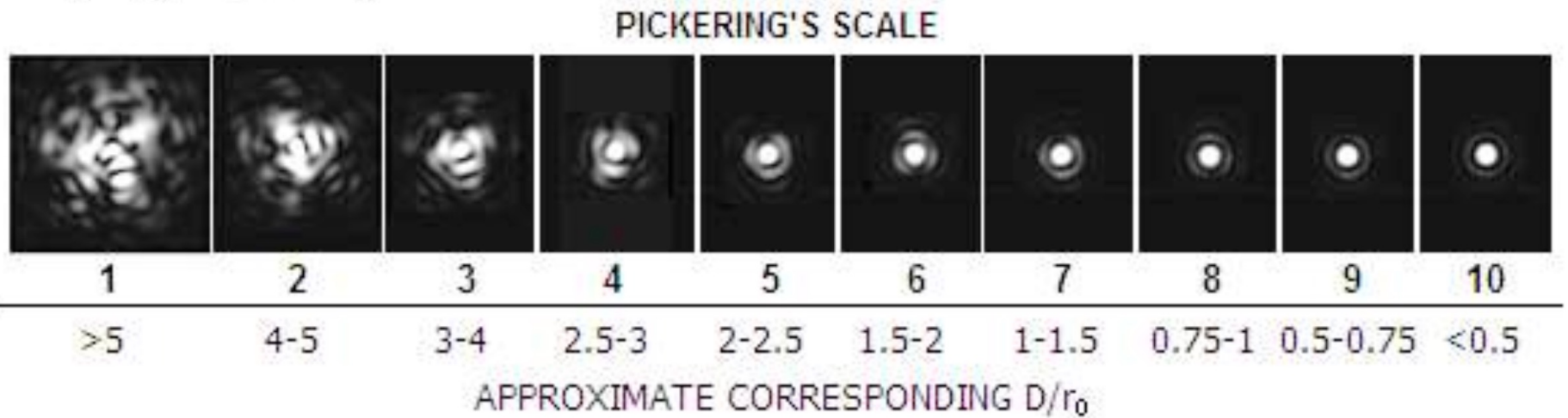
Refractive
index
increases in
depths

"stratified medium"

Turbulence = 3D non-uniformity



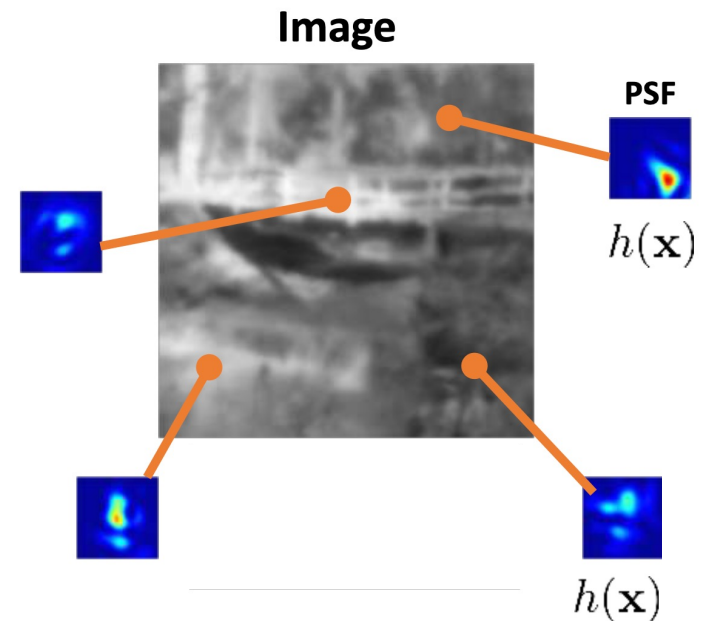
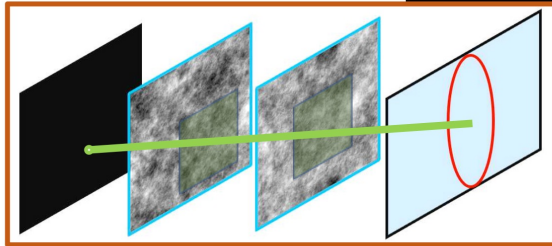
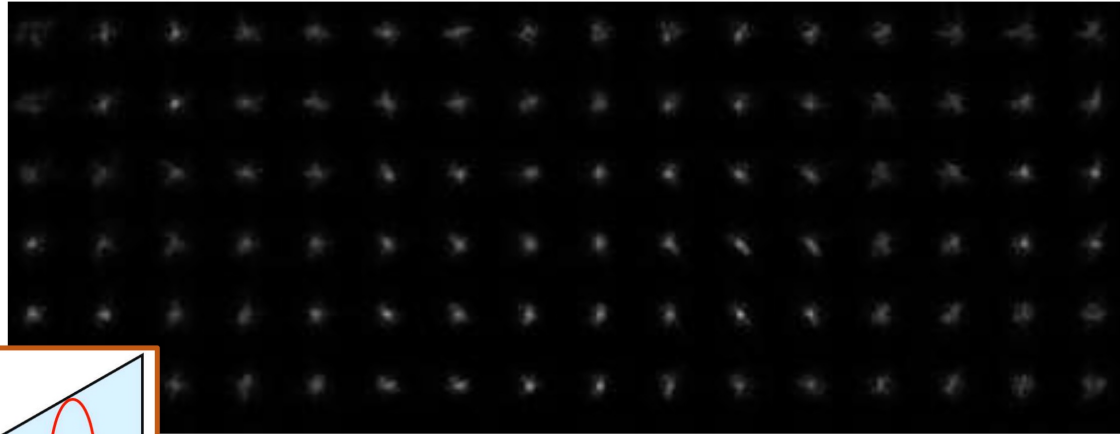
Turbulence *distorts* PSFs



Stroooooonger turbulence

Turbulence leads to linear shift **variant** (LSV) imaging

A collection of point spread functions



An introduction to LSV imaging

The classical approach

Linear shift variant system

$$\gg \mathbf{g} = \mathbf{A}\mathbf{f} \iff \mathbf{g}_m = \sum_{n=1}^N \mathbf{a}_{mn} \mathbf{f}_n$$

$$\mathbf{g} = \begin{bmatrix} \mathbf{a}_{11} & \mathbf{a}_{12} & \cdots & \mathbf{a}_{1N} \\ \mathbf{a}_{21} & \mathbf{a}_{22} & \cdots & \mathbf{a}_{2N} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{a}_{N1} & \mathbf{a}_{N2} & \cdots & \mathbf{a}_{NN} \end{bmatrix} \begin{bmatrix} \mathbf{f}_1 \\ \mathbf{f}_2 \\ \vdots \\ \mathbf{f}_N \end{bmatrix}$$

PSF at x_2

Computational requirement?

Linear operator and matrix

- » A linear operator $A: \mathbb{R}^N \rightarrow \mathbb{R}^M$
(assume only real components in A, f, g^*)

$$Af = g$$

- » Described by a $M \times N$ matrix **A**

$$\mathbf{A}\mathbf{f} = \mathbf{g}$$

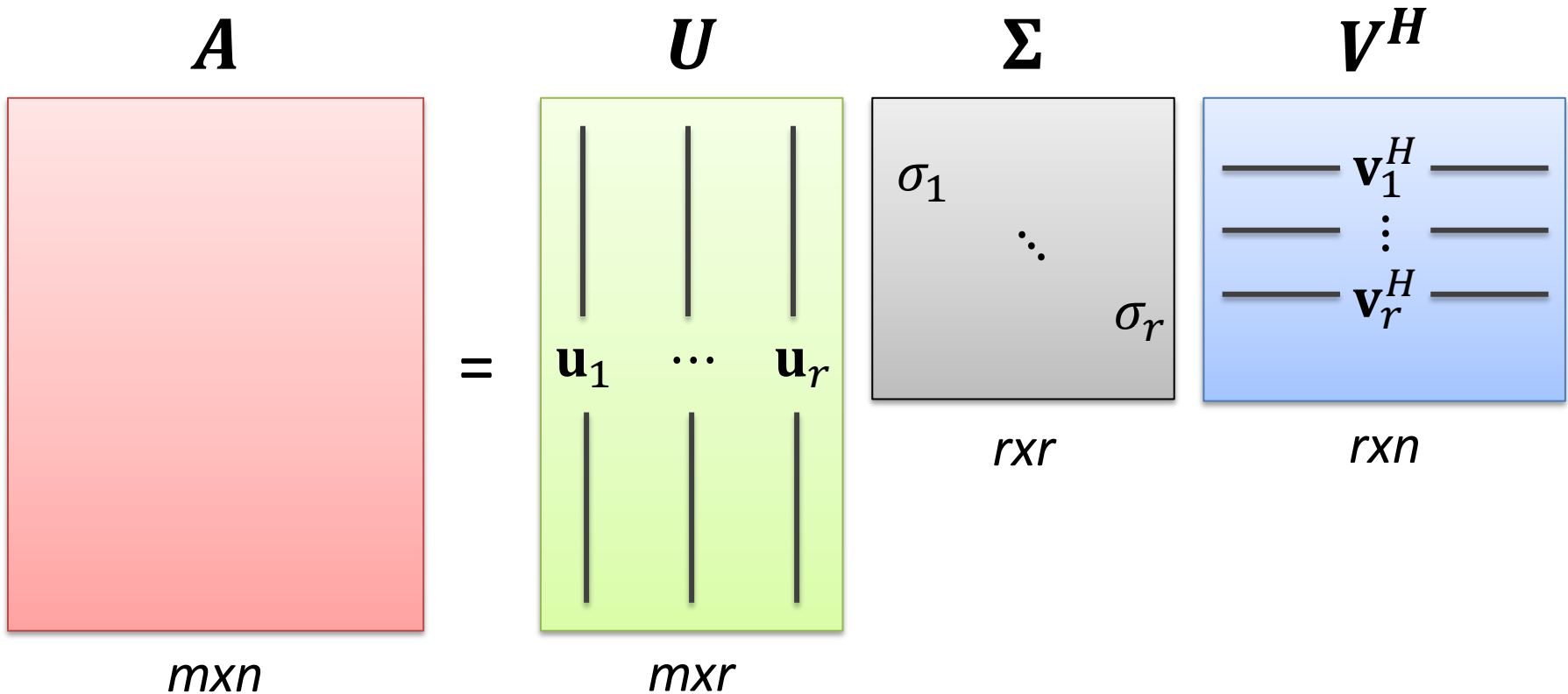
**Same framework also works for complex numbers:*

- Split a complex number into real and imag. parts
- CR (Wirtinger)-Calculus

Singular value decomposition (SVD)

$$A = U \Sigma V^H$$

$U = [u_1, \dots, u_r] \in \mathbb{R}^{m \times r}$ $u_i \in \mathbb{R}^m$ left singular vectors
 $V = [v_1, \dots, v_r] \in \mathbb{R}^{n \times r}$ $v_i \in \mathbb{R}^n$ right singular vectors
 $\Sigma = \text{diag}(\sigma_1, \dots, \sigma_r) \in \mathbb{R}^{r \times r}$ $\sigma_1 \geq \dots \geq \sigma_r$ singular values

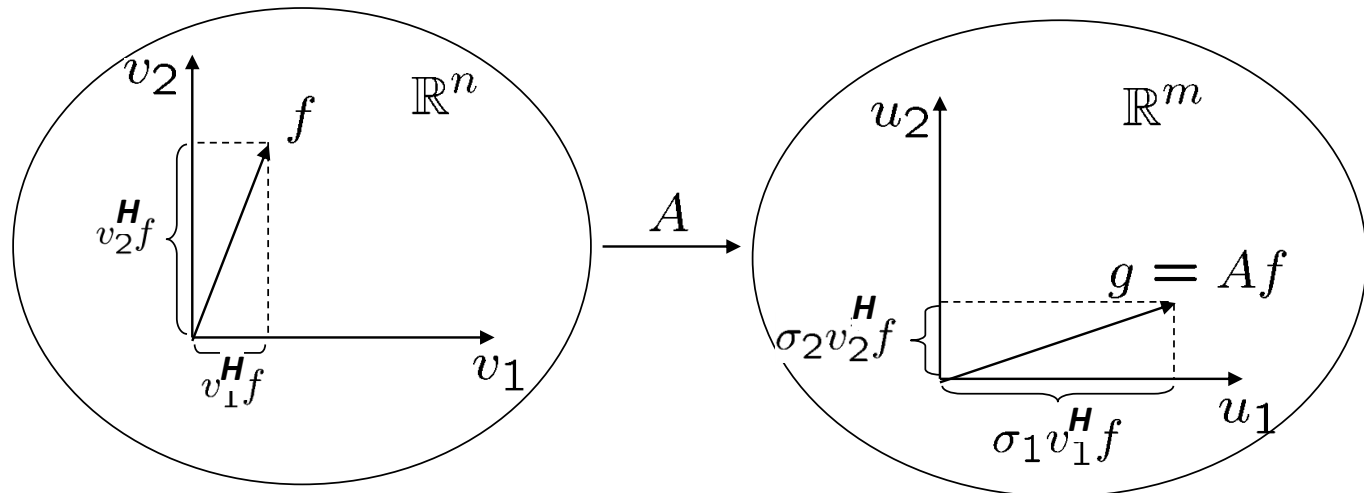


Spectral representation in terms of Singular value decomposition (SVD)

$$A = U\Sigma V^H = \sum_{k=1}^r \sigma_k \mathbf{u}_k \mathbf{v}_k^H$$

$$A\mathbf{f} = \sum_{k=1}^r \sigma_k \mathbf{u}_k (\mathbf{v}_k^H \mathbf{f})$$

1. projects the input vector along \mathbf{v}_k : $f_k = \mathbf{v}_k^H \mathbf{f}$
2. synthesizes $\mathbf{g} = A\mathbf{f}$ by the linear combination $\mathbf{g} = \sum_{k=1}^r \sigma_k f_k \mathbf{u}_k$



Range of A

$$A\mathbf{f} = \sum_{k=1}^r \sigma_k \mathbf{u}_k (\mathbf{v}_k^H \mathbf{f})$$

- » $R(\mathbf{A})$ contains all the vectors \mathbf{g} , spanned by the ***column*** space in the form $\mathbf{g} = \mathbf{A}\mathbf{f}$
- » $R(\mathbf{A})$ is spanned by left singular vectors $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_r$

Null space of A

$$A\mathbf{f} = \sum_{k=1}^r \sigma_k \mathbf{u}_k (\mathbf{v}_k^H \mathbf{f})$$

- » The null space $\mathcal{N}(\mathbf{A})$ is the subspace spanned by all the vectors $\mathbf{A}\mathbf{f} = 0$
- » Dimensionality? $n-r$

Interim summary

- » Singular values act like the “discrete transfer function” for linear shift-variant system
 - » *The quality of a LSV system can be characterized by distribution of SVs

Adjoint

$$A = U\Sigma V^H = \sum_{k=1}^r \sigma_k \mathbf{u}_k \mathbf{v}_k^H$$

$$A\mathbf{f} = \sum_{k=1}^r \sigma_k \mathbf{u}_k (\mathbf{v}_k^H \mathbf{f})$$

$$A^H = V\Sigma U^H = \sum_{k=1}^r \sigma_k \mathbf{v}_k \mathbf{u}_k^H$$

$$A^H \mathbf{g} = \sum_{k=1}^r \sigma_k \mathbf{v}_k (\mathbf{u}_k^H \mathbf{g})$$

Range of A^H

$$A^H \mathbf{g} = \sum_{k=1}^r \sigma_k \mathbf{v}_k (\mathbf{u}_k^H \mathbf{g})$$

» $R(A^H)$ is spanned by right singular vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_r$

Null space of A^H

$$A^H \mathbf{g} = \sum_{k=1}^r \sigma_k \mathbf{v}_k (\mathbf{u}_k^H \mathbf{g})$$

» Dimensionality? **$m-r$**

Relation between left & right singular vectors

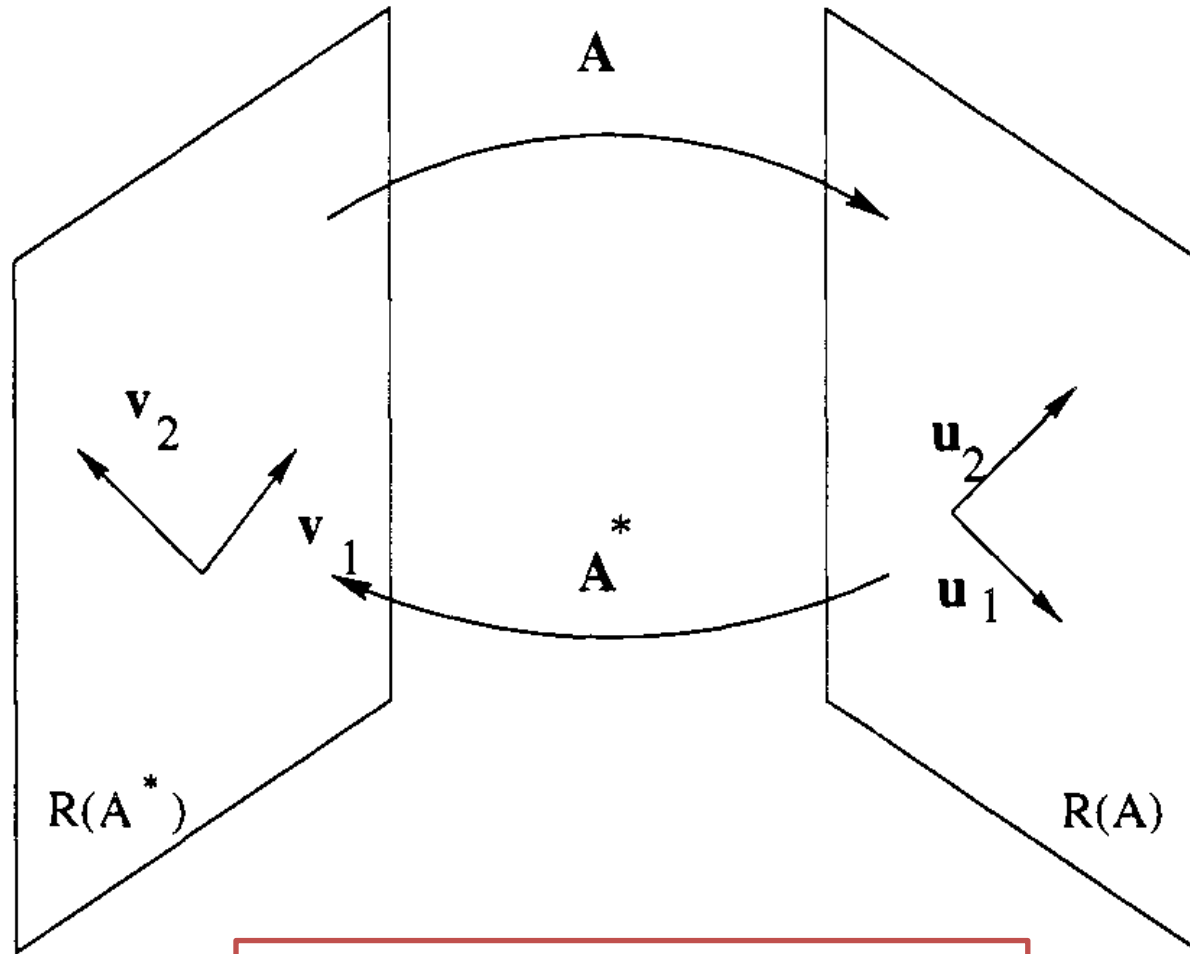
$$A = U\Sigma V^H = \sum_{k=1}^r \sigma_k \mathbf{u}_k \mathbf{v}_k^H$$

$$A\mathbf{v}_k? \quad A\mathbf{v}_k = \sigma_k \mathbf{u}_k$$

$$A^H = V\Sigma U^H = \sum_{k=1}^r \sigma_k \mathbf{v}_k \mathbf{u}_k^H$$

$$A^H \mathbf{u}_k? \quad A^H \mathbf{u}_k = \sigma_k \mathbf{v}_k$$

Relation between left & right singular vectors

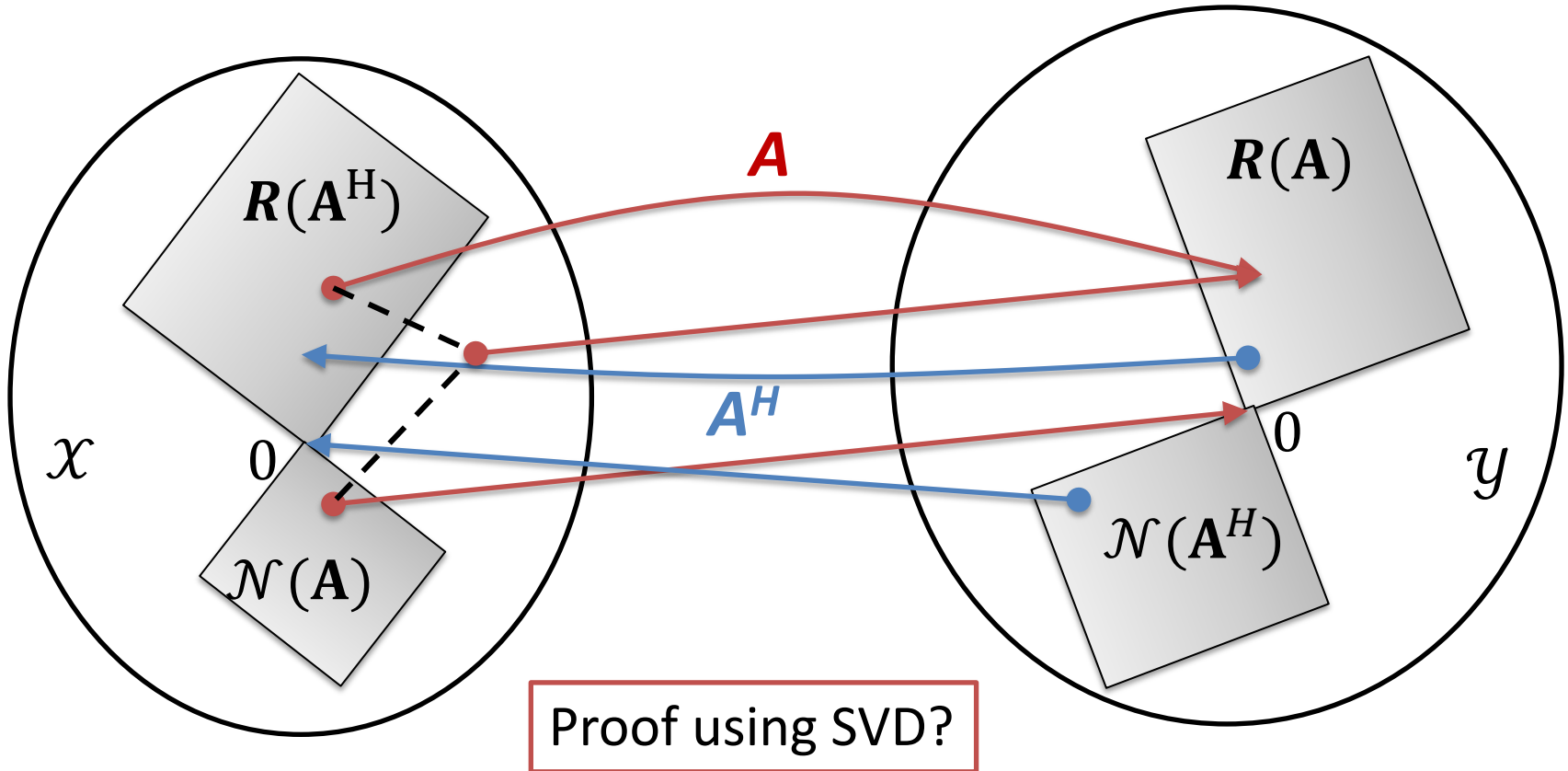


Physical meaning of Adjoint?

Review: relation between null space and range

$$R(\mathbf{A}) = \mathcal{N}(\mathbf{A}^H)^\perp$$

$$R(\mathbf{A}^H) = \mathcal{N}(\mathbf{A})^\perp$$



$$\mathbf{A}\mathbf{f} = \sum_{k=1}^r \sigma_k \mathbf{u}_k (\mathbf{v}_k^H \mathbf{f}) \quad \mathbf{A}^H \mathbf{g} = \sum_{k=1}^r \sigma_k \mathbf{v}_k (\mathbf{u}_k^H \mathbf{g})$$