

# Optimization for Machine Learning HW 3

Due: 9/27/2023

All parts of each question are equally weighted. When solving one question/part, you may assume the results of all previous questions/parts.

1. This question explores the use of *time-varying learning rates*. Suppose  $\mathcal{L}(\mathbf{w}) = \mathbb{E}_z[\ell(\mathbf{w}, z)]$  is a convex function, and suppose  $D \geq \|\mathbf{w}_1 - \mathbf{w}_*\|$  for some  $\mathbf{w}_1$  and  $\mathbf{w}_* = \operatorname{argmin} \mathcal{L}(\mathbf{w})$ . In class, we showed that if  $\|\nabla \ell(\mathbf{w}, z)\| \leq G$  for all  $z$  and  $\mathbf{w}$ , then stochastic gradient descent with learning rate  $\eta = \frac{D}{G\sqrt{T}}$  satisfies

$$\mathbb{E} \left[ \frac{1}{T} \sum_{t=1}^T \mathcal{L}(\mathbf{w}_t) - \mathcal{L}(\mathbf{w}_*) \right] \leq \frac{DG}{\sqrt{T}}$$

However, in order to set this learning rate, we needed to use knowledge of  $D$ ,  $G$  and  $T$ . This question helps *show a way to avoid needing to know  $T$* .

- (a) To do this, we will consider *projected stochastic gradient descent* with *varying learning rate*. Suppose we start at  $\mathbf{w}_1 = \mathbf{0}$ . Then the update is:

$$\mathbf{w}_{t+1} = \Pi_{\|\mathbf{w}\| \leq D} [\mathbf{w}_t - \eta_t \nabla \ell(\mathbf{w}_t, z_t)]$$

where  $\Pi_{\|\mathbf{w}\| \leq D}[x] = \operatorname{argmin}_{\|\mathbf{w}\| \leq D} \|x - \mathbf{w}\|$ . Notice that  $\Pi_{\|\mathbf{w}\| \leq D}[\mathbf{w}_*] = \mathbf{w}_*$  by definition of  $D$ . Show that

$$\langle \nabla \ell(\mathbf{w}_t, z_t), \mathbf{w}_t - \mathbf{w}_* \rangle \leq \frac{\|\mathbf{w}_t - \mathbf{w}_*\|^2 - \|\mathbf{w}_{t+1} - \mathbf{w}_*\|^2}{2\eta_t} + \frac{\eta_t \|\nabla \ell(\mathbf{w}_t, z_t)\|^2}{2}$$

And conclude:

$$\mathbb{E} \left[ \sum_{t=1}^T \mathcal{L}(\mathbf{w}_t) - \mathcal{L}(\mathbf{w}_*) \right] \leq \mathbb{E} \left[ \sum_{t=1}^T \frac{\|\mathbf{w}_t - \mathbf{w}_*\|^2 - \|\mathbf{w}_{t+1} - \mathbf{w}_*\|^2}{2\eta_t} + \frac{\eta_t \|\nabla \ell(\mathbf{w}_t, z_t)\|^2}{2} \right]$$

(You may use without proof the identity  $\|\Pi_{\|\mathbf{w}\| \leq D}[x] - \mathbf{w}_*\|^2 \leq \|x - \mathbf{w}_*\|^2$  for all  $t$  and all vectors  $x$ . This follows because  $\|\mathbf{w}_*\| \leq D$ .)

**Solution:**

- (b) Next, show that *so long as  $\eta_t$  satisfies  $\eta_t \leq \eta_{t-1}$  for all  $t$* , we have:

$$\mathbb{E} \left[ \sum_{t=1}^T \mathcal{L}(\mathbf{w}_t) - \mathcal{L}(\mathbf{w}_*) \right] \leq \mathbb{E} \left[ \frac{2D^2}{\eta_T} + \frac{\sum_{t=1}^T \eta_t \|\nabla \ell(\mathbf{w}_t, z_t)\|^2}{2} \right]$$

(hint: at some point you will probably need to show  $\|\mathbf{w}_t - \mathbf{w}_*\|^2 (\frac{1}{2\eta_t} - \frac{1}{2\eta_{t-1}}) \leq 2D^2 (\frac{1}{\eta_t} - \frac{1}{\eta_{t-1}})$ ).

**Solution:**

(c) Next, consider the update

$$\mathbf{w}_{t+1} = \Pi_{\|\mathbf{w}\| \leq D} [\mathbf{w}_t - \eta_t \nabla \ell(\mathbf{w}_t, z_t)]$$

where we set  $\eta_t = \frac{D}{G\sqrt{t}}$ . Recalling our assumption that  $\|\nabla \ell(\mathbf{w}_t, z_t)\| \leq G$  with probability 1, Show that

$$\mathbb{E} \left[ \sum_{t=1}^T \mathcal{L}(\mathbf{w}_t) - \mathcal{L}(\mathbf{w}_*) \right] \leq O(DG\sqrt{T})$$

This allows you to handle any  $T$  value without having the algorithm know  $T$  ahead of time. (Hint: you may want to show that  $\sum_{t=1}^T \frac{1}{\sqrt{t}} \leq 1 + \int_1^T \frac{dx}{\sqrt{x}}$ ).

**Solution:**

2. This question is an exercise in understanding the **non-convex SGD analysis**. In the notes, Theorem 5.3 discusses **how to use varying learning rate  $\eta_t$  proportional to  $\frac{1}{\sqrt{t}}$**  to obtain a non-convex convergence rate of:

$$\mathbb{E}[\|\nabla \mathcal{L}(\hat{\mathbf{w}})\|^2] \leq O\left(\frac{\log(T)}{\sqrt{T}}\right)$$

In this question, we will remove the logarithmic factor by adding an extra assumption.

- (a) Suppose that  $\mathcal{L}$  is  $H$ -smooth,  $\|\nabla \ell(\mathbf{w}, z)\| \leq G$  for all  $\mathbf{w}$  and  $z$ , and further that  **$\mathcal{L}(\mathbf{w}) \in [0, M]$  for all  $\mathbf{w}$**  (this last assumption is slightly stronger than we have assumed in class). Consider the SGD update:

$$\mathbf{w}_{t+1} = \mathbf{w}_t - \eta \nabla \ell(\mathbf{w}_t, z_t)$$

Suppose  **$\eta_t$  is an arbitrary deterministic learning rate schedule** satisfying  $\eta_{t+1} \leq \eta_t$  for all  $t$  (i.e. the learning rate never increases). Show that **for all  $\tau < T$ :**

$$\frac{1}{T - \tau} \mathbb{E} \left[ \sum_{t=\tau+1}^T \|\nabla \mathcal{L}(\mathbf{w}_t)\|^2 \right] \leq \frac{1}{\eta_T(T - \tau)} \left( M + \frac{HG^2}{2} \sum_{t=\tau+1}^T \eta_t^2 \right)$$

**Solution:**

- (b) Next, **consider  $\eta_t = \frac{1}{\sqrt{t}}$** . In class, we considered choosing  $\hat{\mathbf{w}}$  *uniformly* at random from  $\mathbf{w}_1, \dots, \mathbf{w}_T$ . Instead, produce a **non-uniform distribution over  $\mathbf{w}_1, \dots, \mathbf{w}_T$**  such that choosing  $\mathbf{w}_T$  from this distribution satisfies:

$$\mathbb{E}[\|\nabla \mathcal{L}(\hat{\mathbf{w}})\|^2] \leq O\left(\frac{1}{\sqrt{T}}\right)$$

where the  $O(\cdot)$  notation hides constants that do not depend on  $T$ . That is, **you should find some  $p_1, \dots, p_T$  such that you set  $\hat{\mathbf{w}} = \mathbf{w}_t$  with probability  $p_t$** . The uniform case is  $p_t = 1/T$  for all  $t$ . If it helps, you may assume that  **$T$  is divisible by any natural number (e.g. you can assume  $T$  is even if you want)**. Note that such an assumption is not required.

**Solution:**

BONUS (c) Assume that  $\mathcal{L}$  is  $H$ -smooth,  $\|\nabla \ell(\mathbf{w}, z)\| \leq G$  for all  $\mathbf{w}$  and  $z$ , and  $\mathbf{w}_1$  is such that  $\mathcal{L}(\mathbf{w}_1) - \inf_{\mathbf{w}} \mathcal{L} \leq \Delta$  (note that this is *the same* as our usual assumptions in class). Devise a sequence of learning rates such that:

$$\frac{1}{T} \sum_{t=1}^T \mathbb{E} \left[ \|\nabla \mathcal{L}(\mathbf{w}_t)\|^2 \right] \leq O \left( \frac{(HG^2 \log \log(T) + \Delta) \sqrt{\log(T)}}{\sqrt{T}} \right)$$

where the  $O(\cdot)$  notation hides constants that may depend on  $G$ ,  $\Delta$  and  $H$  but *not*  $T$ .

**Solution:**