

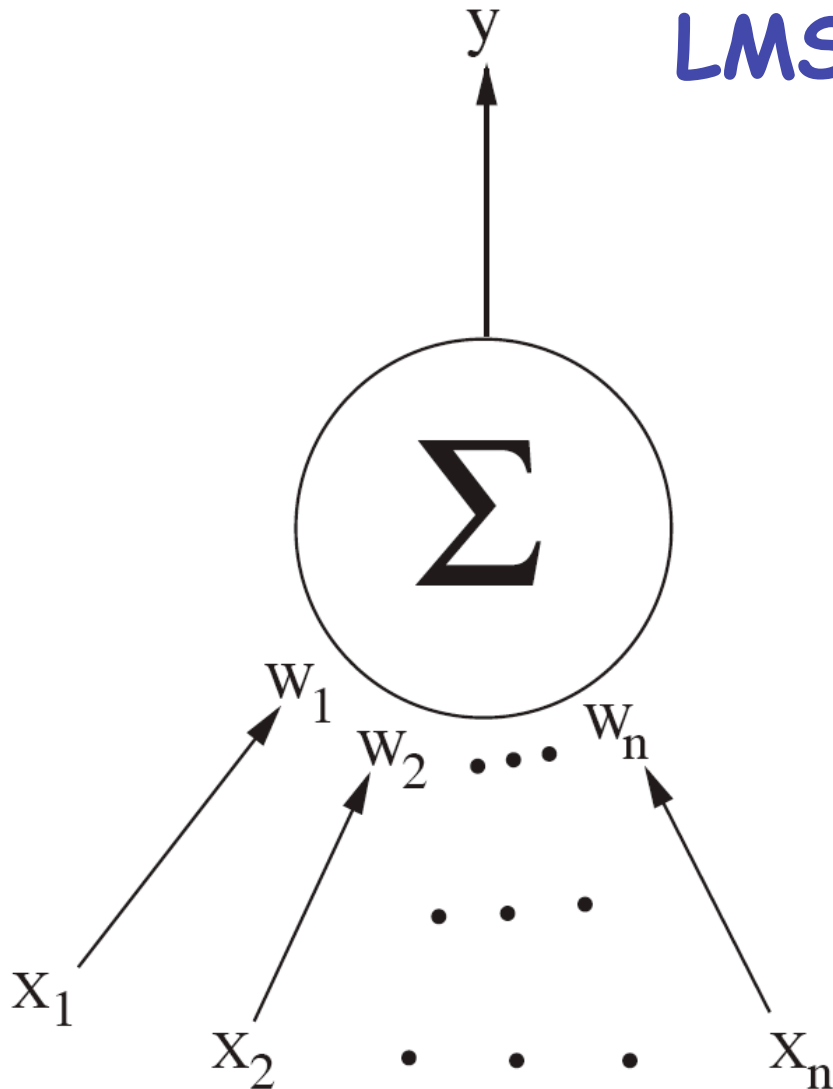
Adapting Bias by Gradient Descent: An Incremental Version of Delta-Bar-Delta

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in AAAI-92

Outline

- Remarks on learning and bias
- Least Mean Square (LMS) learning
- IDBD (new algorithm)
- Exp 1: Is IDBD better?
- Exp 2: Does IDBD find an optimal bias?
- Derivation of LMS as gradient descent
- Derivation of IDBD as "meta" grad desc

LMS (least mean square) Learning



$$y(t) = \sum_{i=1}^n w_i(t) x_i(t)$$

$$\text{error } \delta(t) = y^*(t) - y(t)$$

Minimize expected $\delta^2(t)$

$$w_i(t+1) = w_i(t) + \alpha \delta(t) x_i(t)$$

Incremental Delta-Bar-Delta (IDBD)

$$w_i(t+1) = w_i(t) + \alpha_i(t+1)\delta(t)x_i(t)$$

$$\alpha_i(t) = e^{\beta_i(t)}$$

$$\beta_i(t+1) = \beta_i(t) + \theta\delta(t)x_i(t)h_i(t)$$

$$h_i(t+1) = h_i(t) \left[1 - \alpha_i(t+1)x_i^2(t) \right]^+ + \alpha_i(t+1)\delta(t)x_i(t)$$

where $[x]^+$ is x , if $x > 0$, else 0

Experiment 1: Does IDBD Help?

20 inputs,
5 relevant

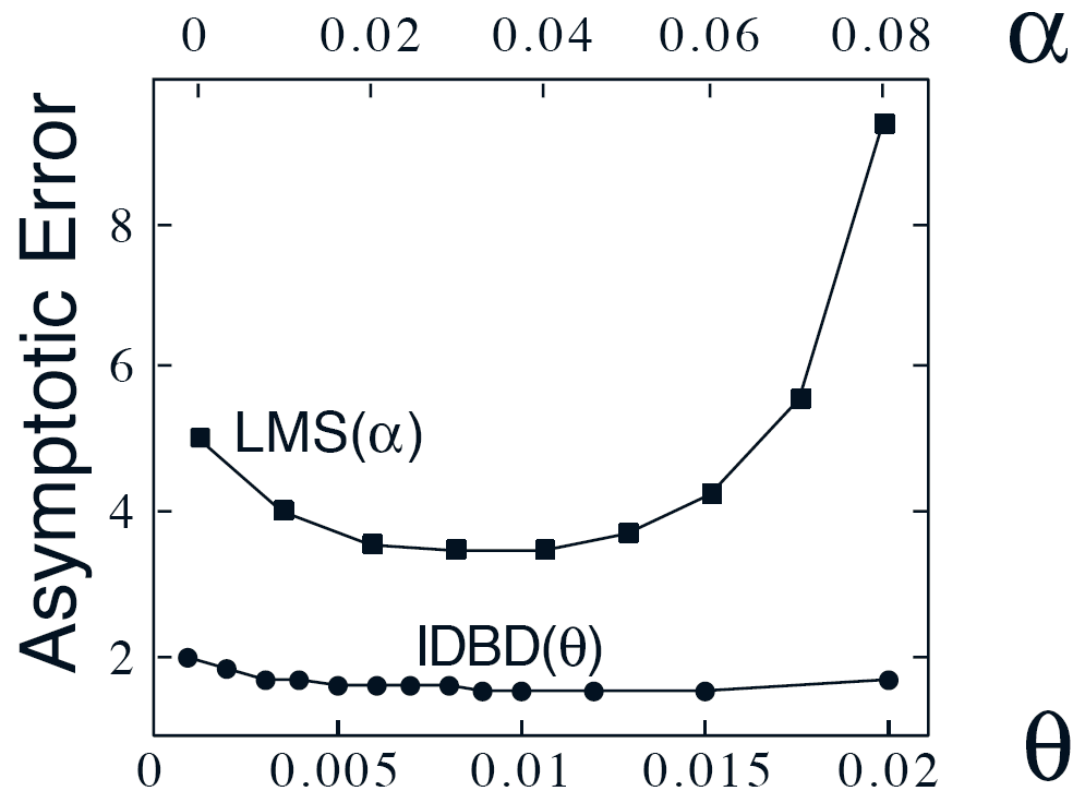
$$s_i \in \{-1, +1\}$$

one s_i switched
every 20 examples

20,000 examples
to wash transients,
then 10,000 examples
for real

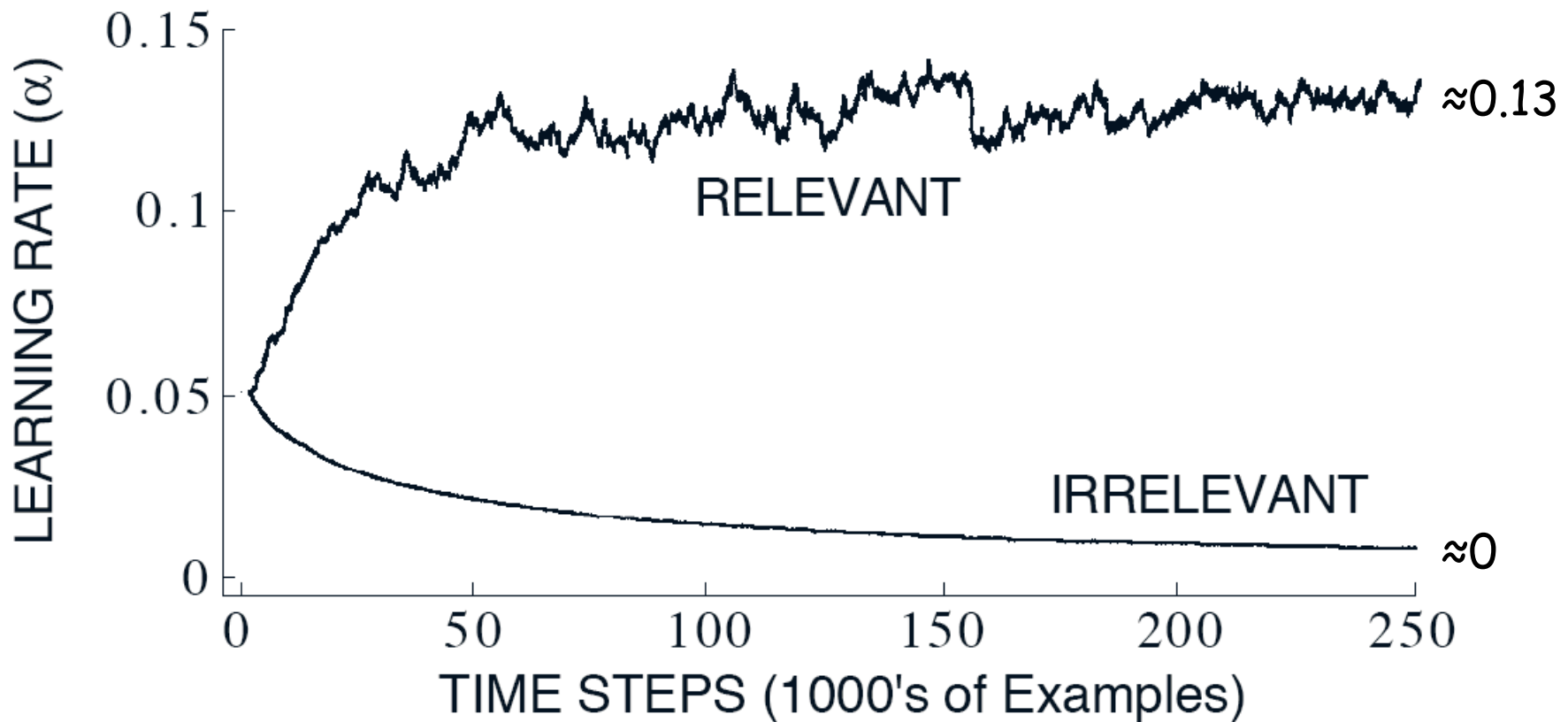
Average MSE
measured over the
10,000 examples

$$y^* = s_1x_1 + s_2x_2 + s_3x_3 + s_4x_4 + s_5x_5 \\ + 0x_6 + 0x_7 + \cdots + 0x_{20},$$



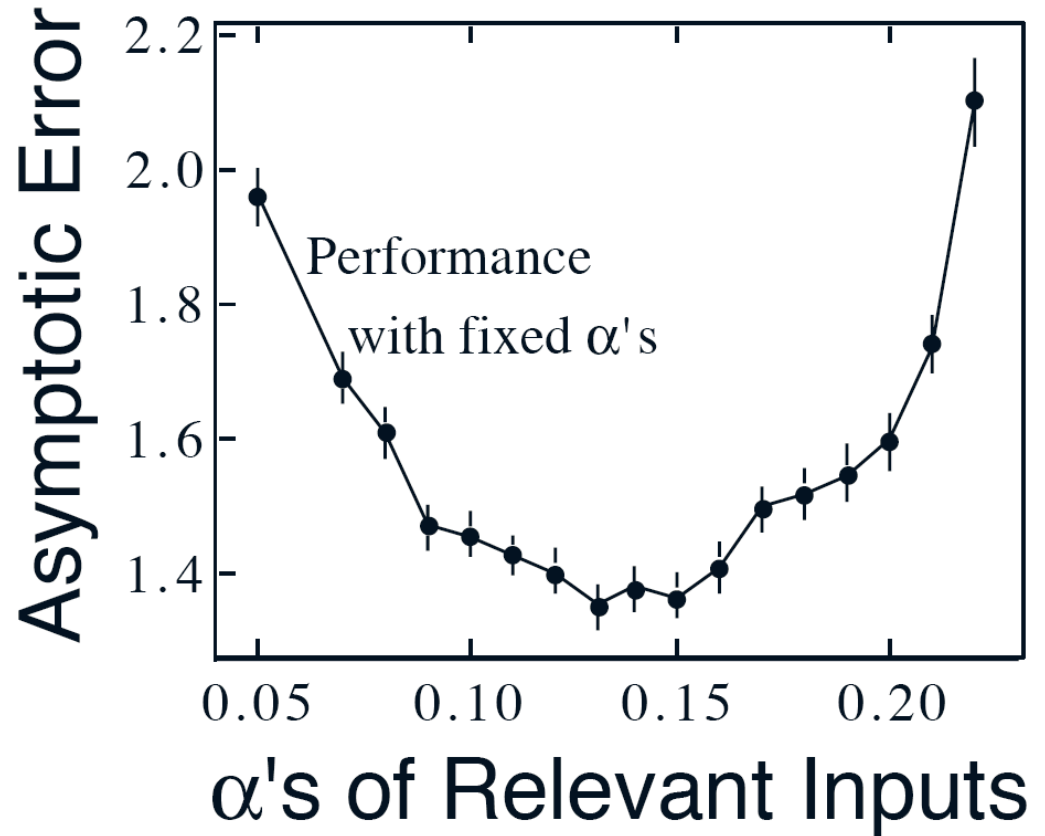
Exp 2a: What α s are found by IDBD?

Small θ ($=0.001$), long run



Exp 2b: What are the optimal α s?

Repeat of first experiment with fixed α s: $\alpha=0$ for irrelevant inputs, vary α for relevant inputs



Optimal $\alpha \approx 0.13$

Derivation of LMS as grad descent (1)

Error is $\delta(t) = y^*(t) - y(t)$

Seek to minimize expected squared error

using the sample squared error $\delta^2(t)$

Ergo, the gradient descent idea:

$$w_i(t+1) = w_i(t) - \frac{1}{2}\alpha \frac{\partial \delta^2(t)}{\partial w_i(t)}$$

Derivation of LMS as grad descent (2)

$$\begin{aligned}w_i(t+1) &= w_i(t) - \frac{1}{2}\alpha \frac{\partial \delta^2(t)}{\partial w_i(t)} \\&= w_i(t) - \alpha \delta(t) \frac{\partial \delta(t)}{\partial w_i(t)} \\&= w_i(t) - \alpha \delta(t) \frac{\partial [y^*(t) - y(t)]}{\partial w_i(t)} \\&= w_i(t) + \alpha \delta(t) \frac{\partial y(t)}{\partial w_i(t)} \\&= w_i(t) + \alpha \delta(t) \frac{\partial}{\partial w_i(t)} \left[\sum_{j=1}^n w_j(t) x_j(t) \right] \\&= w_i(t) + \alpha \delta(t) x_i(t) \quad \checkmark\end{aligned}$$

Derivation of IDBD as GD (1)

$$\begin{aligned}\beta_i(t+1) &= \beta_i(t) - \frac{1}{2}\theta \frac{\partial \delta^2(t)}{\partial \beta_i} \\ &= \beta_i(t) - \frac{1}{2}\theta \sum_j \frac{\partial \delta^2(t)}{\partial w_j(t)} \frac{\partial w_j(t)}{\partial \beta_i}\end{aligned}$$

assuming

$$\frac{\partial w_j(t)}{\partial \beta_i} \approx 0 \quad \approx \beta_i(t) - \frac{1}{2}\theta \frac{\partial \delta^2(t)}{\partial w_i(t)} \frac{\partial w_i(t)}{\partial \beta_i}$$

for $i \neq j$

$$= \beta_i(t) + \theta \delta(t) x_i(t) h_i(t) \quad \checkmark$$

$$\text{where } h_i(t) = \frac{\partial w_i(t)}{\partial \beta_i}$$

Derivation of IDBD as GD (2)

$$\begin{aligned}\frac{\partial \delta(t)}{\partial \beta_i} &= -\frac{\partial y(t)}{\partial \beta_i} = -\frac{\partial}{\partial \beta_i} \sum_j w_j(t) x_j(t) \\ &\approx -\frac{\partial}{\partial \beta_i} [w_i(t) x_i(t)] = -h_i(t) x_i(t)\end{aligned}$$

$$\begin{aligned}h_i(t+1) &= \frac{\partial w_i(t+1)}{\partial \beta_i} \\ &= \frac{\partial}{\partial \beta_i} [w_i(t) + e^{\beta_i(t+1)} \delta(t) x_i(t)] \\ &= h_i(t) + e^{\beta_i(t+1)} \delta(t) x_i(t) + e^{\beta_i(t+1)} \frac{\partial \delta(t)}{\partial \beta_i} x_i(t) \\ &\approx h_i(t) + e^{\beta_i(t+1)} \delta(t) x_i(t) - e^{\beta_i(t+1)} x_i^2(t) h_i(t) \\ &= h_i(t) [1 - \alpha_i(t+1) x_i^2(t)] + \alpha_i(t+1) \delta(t) x_i(t) \quad \checkmark\end{aligned}$$

Closing

- IDBD improves over earlier DBD methods
 - Incremental, example-by-example updating
 - Only one free parameter
 - Can be derived as "meta" gradient descent
- IDBD is a principled way of learning bias (for linear LMS methods)
 - As such can dramatically speed learning
 - With only a linear ($\approx \times 3$) increase in memory & comp.
- "Meta" gradient descent is a general idea
 - An incremental form of hold-one-out cross validation
 - Fundamentally different from other learning methods
 - Could be used to learn other kinds of biases