



## What is an image?

*An image is a two-dimensional function  $f(x,y)$ , where  $x$  and  $y$  are the **spatial** (plane) coordinates, and the amplitude of  $f$  at any pair of coordinates  $(x,y)$  is called the intensity of the image at that level.*

## What is a digital image?

*If  $x,y$  and the amplitude values of  $f$  are **finite and discrete quantities**, we call the image a **digital image**. A digital image is composed of a finite number of elements called **pixels**, each of which has a particular location and value.*



*First Digital Photograph Ever: Russell Kirsch in 1957 made a  $176 \times 176$  pixel digital image by scanning a photograph of his three-month-old son.*

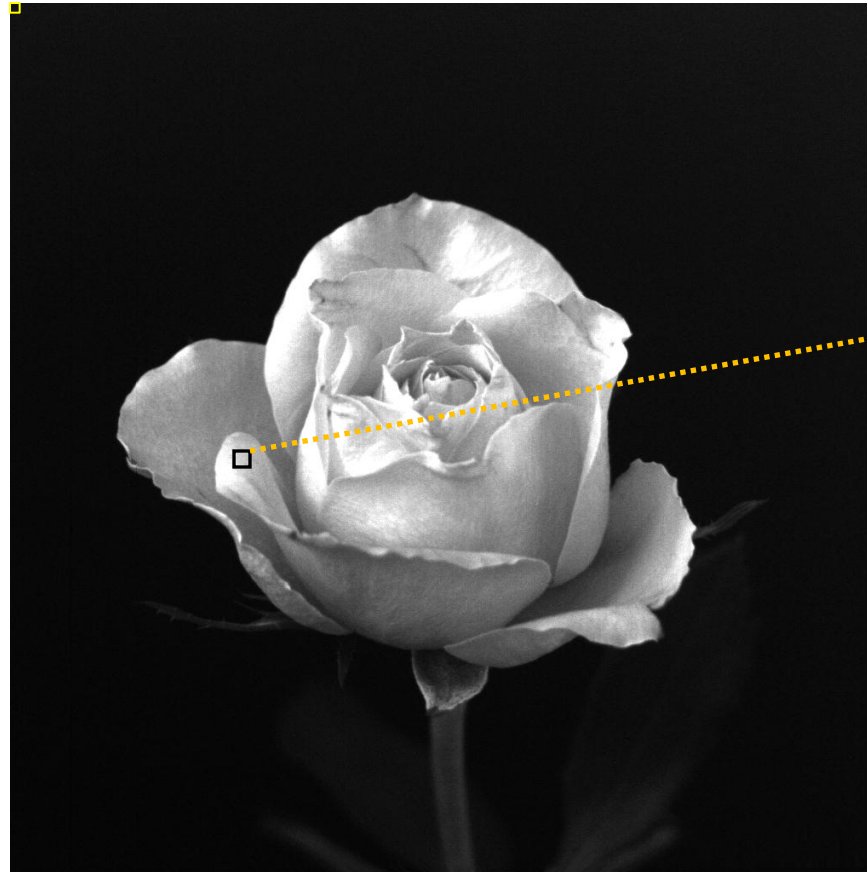
# EE-583: Digital Image Processing



In 8-bit representation  
Pixel intensity values change  
between 0 (Black)  
and 255 (White)

Pixel location  
Pixel intensity value  
 $f(1,1) = 21$

Consider the following image (1024 x 1024 pixels)  
to be 2D function or a **matrix** with **rows** and **columns**



rows columns  
 $f(520:525, 375:380) =$

152	148	144	152	181	203
144	138	156	152	184	208
141	141	138	156	181	203
136	138	144	158	177	196
144	138	148	154	177	208
149	138	152	160	188	205

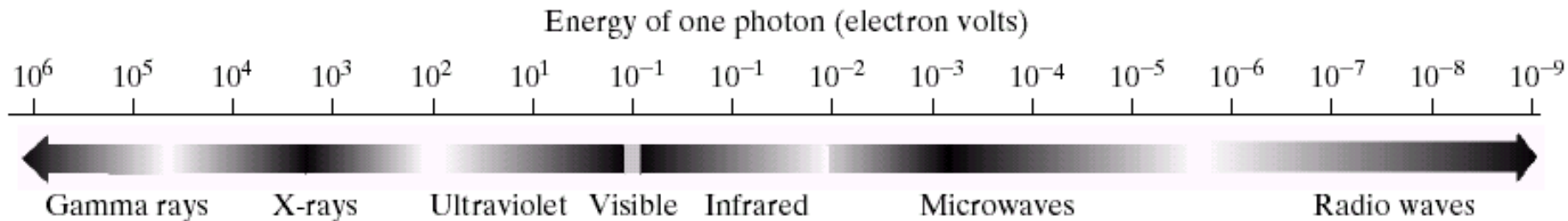
$f(1024,1024) = 15$

# What is Digital Image Processing?

**Definition:** Digital image processing refers to processing of digital images by using digital computers.

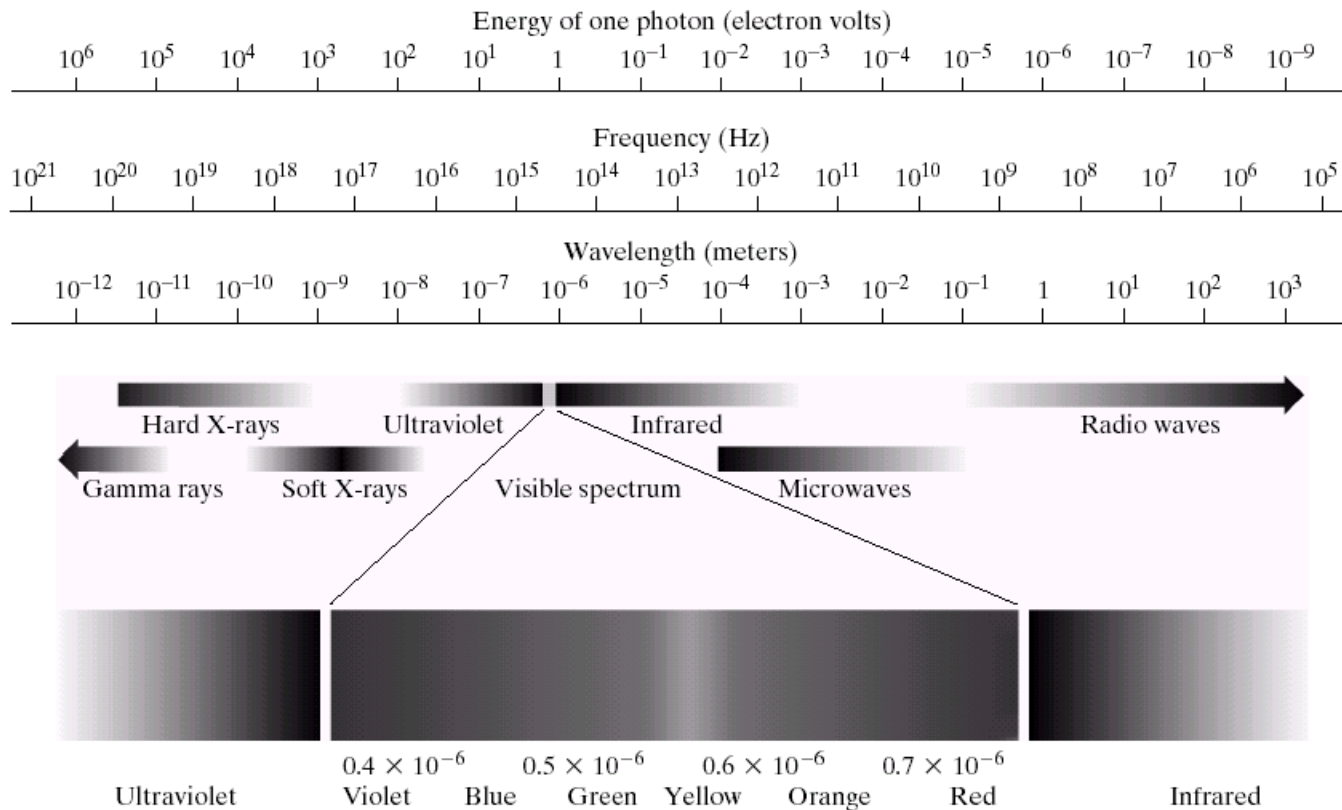
## Sources of Digital Images

- The principal source for the images is the **electromagnetic (EM) energy spectrum**.
- The spectral bands are grouped according to energy per photon ranging from the **gamma rays (highest energy)** to the **radio waves (lowest energy)**.



**FIGURE 1.5** The electromagnetic spectrum arranged according to energy per photon.

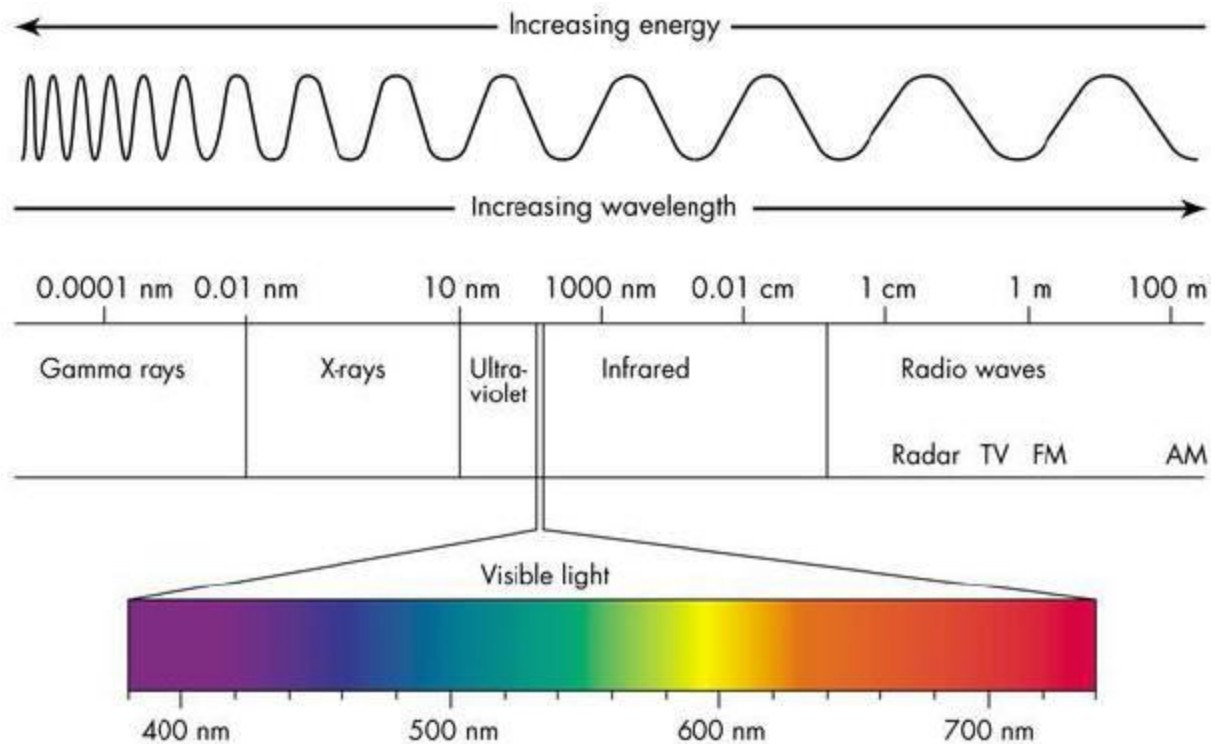
# The Electromagnetic Spectrum



**FIGURE 2.10** The electromagnetic spectrum. The visible spectrum is shown zoomed to facilitate explanation, but note that the visible spectrum is a rather narrow portion of the EM spectrum.



# The Electromagnetic Spectrum

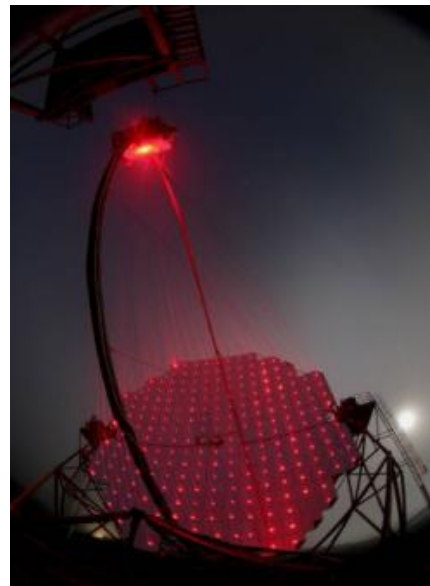


# Digital Images based on the EM Spectrum

Gamma Ray Imaging: Used in nuclear medicine and astronomical observations.



Gamma-Ray Imaging  
in nuclear medicine



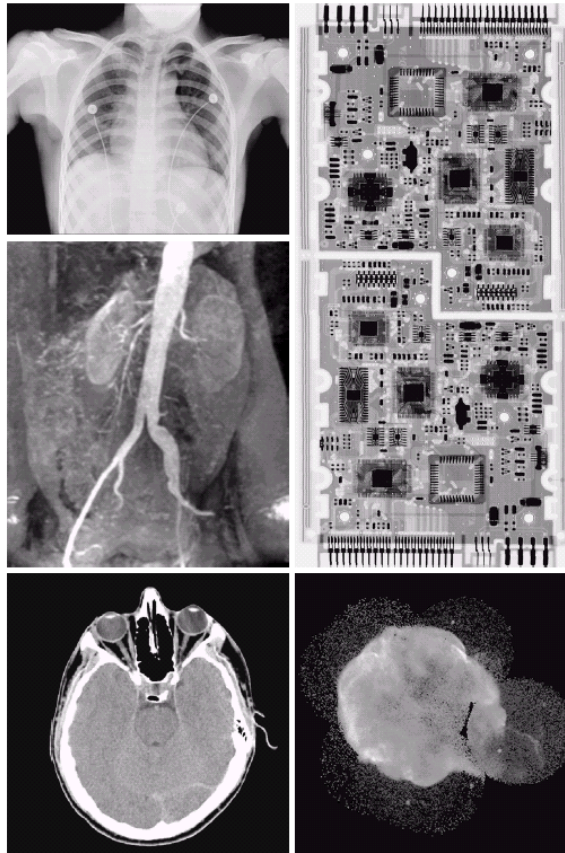
Gamma-Ray Imaging  
Cherenkov Telescope



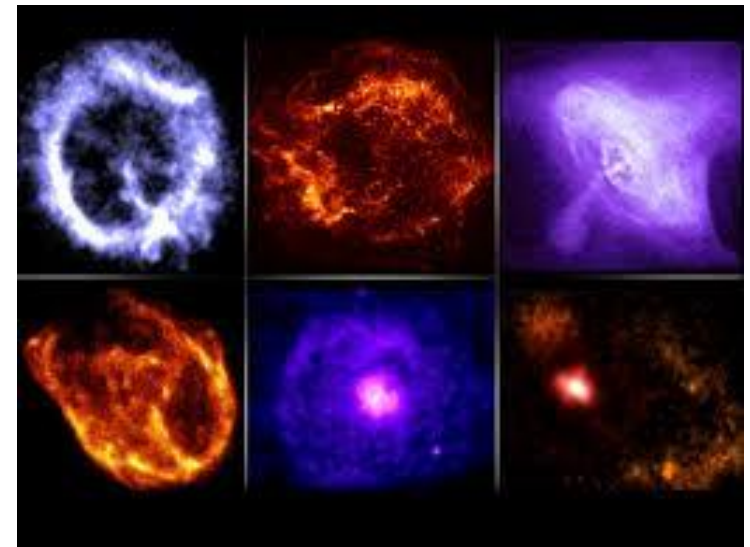
Gamma-Ray imaging of  
A starburst galaxy about 12  
million light-years away

# Digital Images based on the EM Spectrum

X-ray Imaging: Used in medical diagnostic, industrial applications and astronomy.



**FIGURE 1.7** Examples of X-ray imaging. (a) Chest X-ray. (b) Aortic angiogram. (c) Head CT. (d) Circuit boards. (e) Cygnus Loop. (Images courtesy of (a) and (c) Dr. David R. Pickens, Dept. of Radiology & Radiological Sciences, Vanderbilt University Medical Center, (b) Dr. Thomas R. Gest, Division of Anatomical Sciences, University of Michigan Medical School, (d) Mr. Joseph E. Pascente, Lixi, Inc., and (e) NASA.)



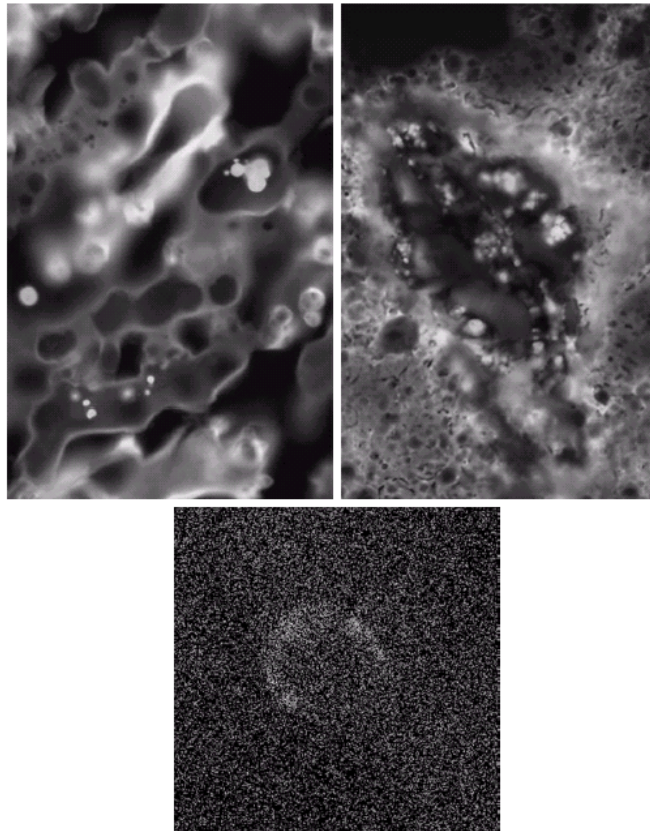
X-ray images from the space  
The Chandra X-Ray Observatory



# Digital Images based on the EM Spectrum

**Ultraviolet Band Imaging:** Applications of ultraviolet light includes microscopy, lasers, biological imaging and astronomy.

a b  
c  
**FIGURE 1.8**  
Examples of  
ultraviolet  
imaging.  
(a) Normal corn.  
(b) Smut corn.  
(c) Cygnus Loop.  
(Images courtesy  
of (a) and  
(b) Dr. Michael  
W. Davidson,  
Florida State  
University,  
(c) NASA.)



# Digital Images based on the EM Spectrum

Visible Light and *Infrared Band Imaging*: Applications include all the images acquired by our cameras, electron microscope, and monitoring environmental conditions.



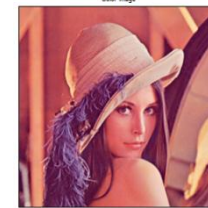
Binary image  
(1-bit)



Grayscale  
(Monochrome) image  
(8-bit)



Color image  
(24-bit)



R



G



B

Respective RGB components  
of a color image.

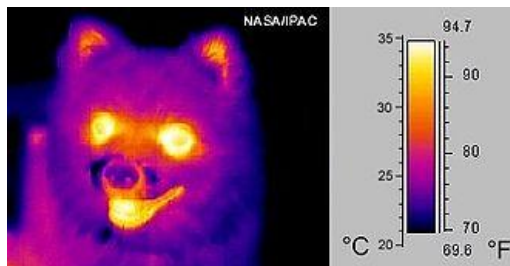


Some visible light image examples

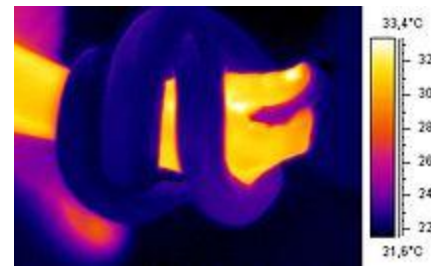


## Digital Images based on the EM Spectrum

*Visible Light and **Infrared Band Imaging**: Applications include all the images acquired by our cameras, electron microscope, and monitoring environmental conditions.*



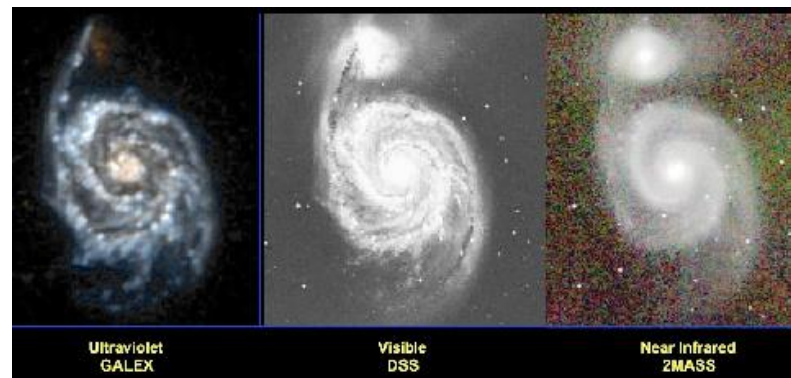
infrared ("thermal") image



Snake around the arm.



A soldier with a rifle.



Messier 51 in ultraviolet (GALEX), visible (DSS), and near infrared (2MASS).  
Courtesy of James Fanson.



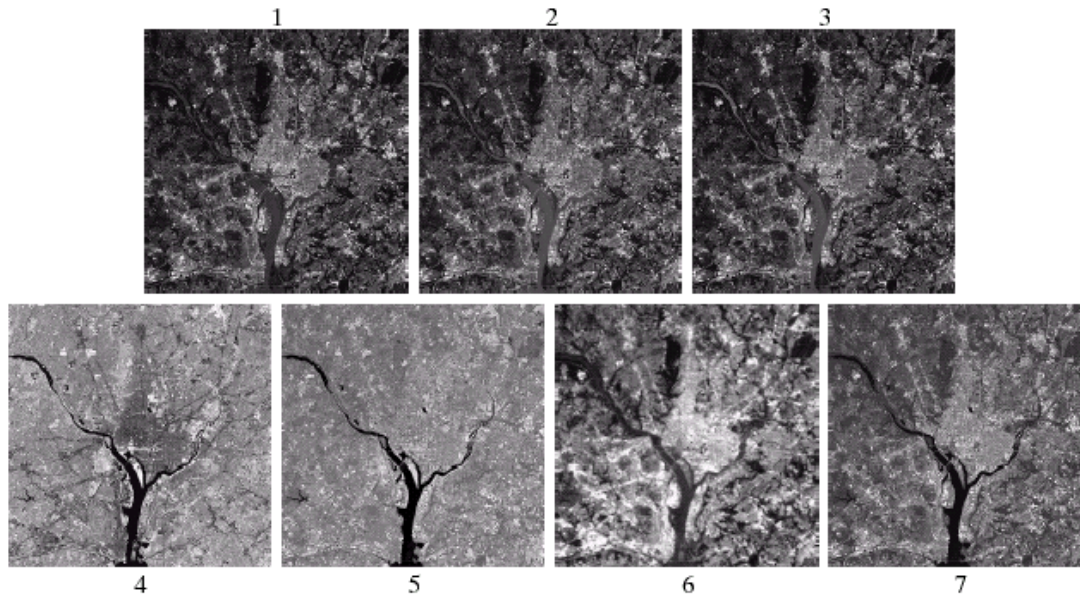
## Digital Images based on the EM Spectrum

### Visible Light and Infrared Band Imaging

**TABLE 1.1**  
Thematic bands  
in NASA's  
LANDSAT  
satellite.

Band No.	Name	Wavelength ( $\mu\text{m}$ )	Characteristics and Uses
1	Visible blue	0.45–0.52	Maximum water penetration
2	Visible green	0.52–0.60	Good for measuring plant vigor
3	Visible red	0.63–0.69	Vegetation discrimination
4	Near infrared	0.76–0.90	Biomass and shoreline mapping
5	Middle infrared	1.55–1.75	Moisture content of soil and vegetation
6	Thermal infrared	10.4–12.5	Soil moisture; thermal mapping
7	Middle infrared	2.08–2.35	Mineral mapping

Visible and Infrared Bands  
used in Satellite imaging



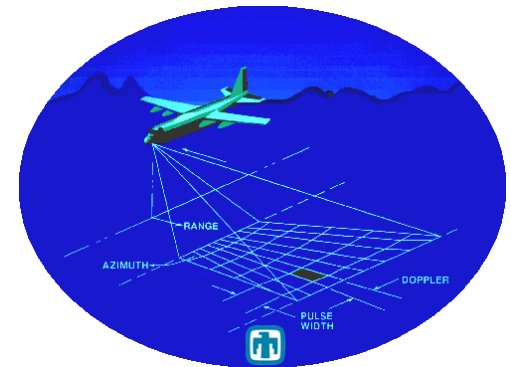
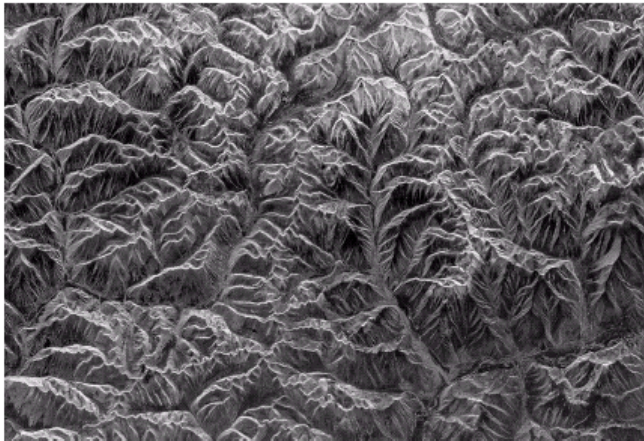
**FIGURE 1.10** LANDSAT satellite images of the Washington, D.C. area. The numbers refer to the thematic bands in Table 1.1. (Images courtesy of NASA.)



# Digital Images based on the EM Spectrum

***Microwave Band Imaging*** : Applications include all the radar applications including military applications and environmental applications.

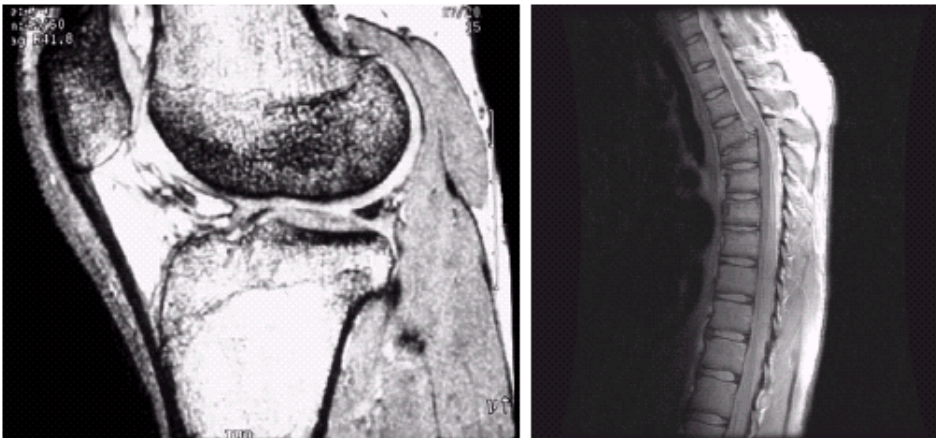
**FIGURE 1.16**  
Spaceborne radar  
image of  
mountains in  
southeast Tibet.  
(Courtesy of  
NASA.)



**Synthetic Aperture Radar System**

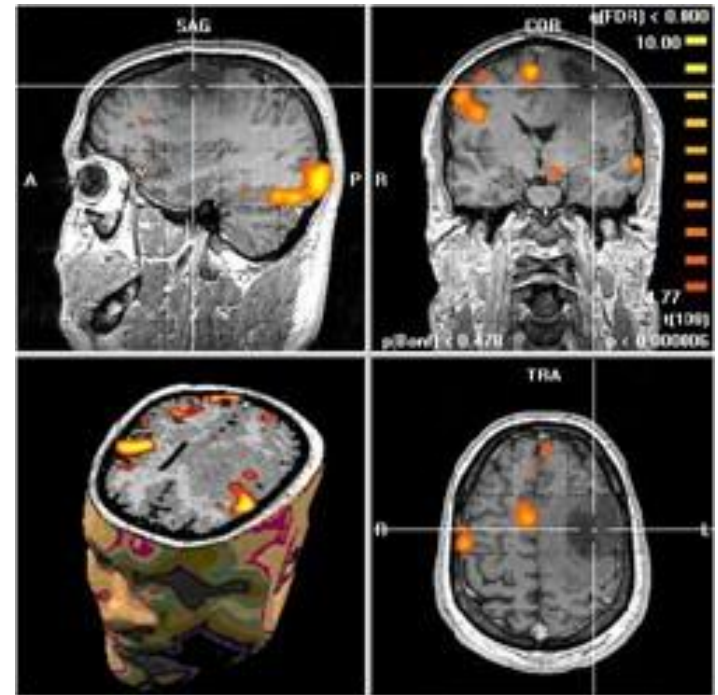
# Digital Images based on the EM Spectrum

**Radio Band Imaging** : Applications include *medical imaging* (i.e. *Magnetic Resonance Imaging- MRI*) and *astronomy*.



a b

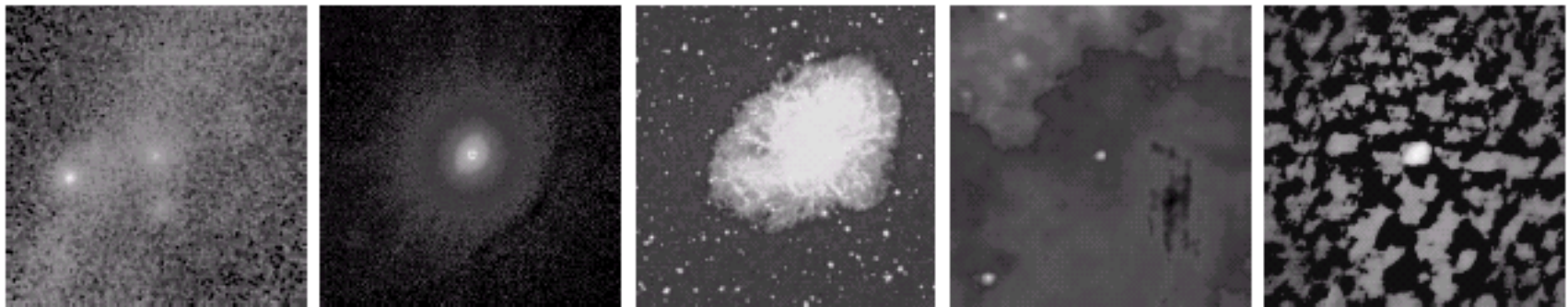
**FIGURE 1.17** MRI images of a human (a) knee, and (b) spine. (Image (a) courtesy of Dr. Thomas R. Gest, Division of Anatomical Sciences, University of Michigan Medical School, and (b) Dr. David R. Pickens, Department of Radiology and Radiological Sciences, Vanderbilt University Medical Center.)



MRI image slices from the brain

# Digital Images based on the EM Spectrum

*An example showing Imaging in all of the bands*



Gamma

X-ray

Optical

Infrared

Radio

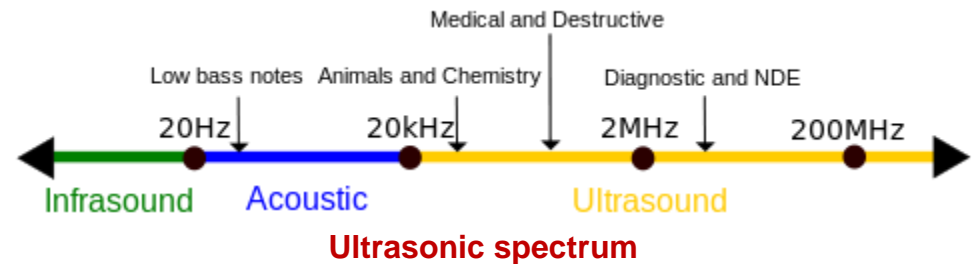
**FIGURE 1.18** Images of the Crab Pulsar (in the center of images) covering the electromagnetic spectrum. (Courtesy of NASA.)

Visible light



# Digital Images based on the **Ultrasound**

**Ultrasound Imaging:** *Ultrasound is a cyclic sound pressure wave with a frequency greater than the upper limit of human hearing. The most well-known application of ultrasound is its use in **sonography** to produce pictures of fetuses in the human womb.*



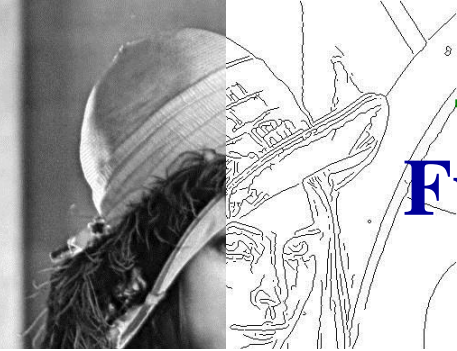
Ultrasound image acquisition device



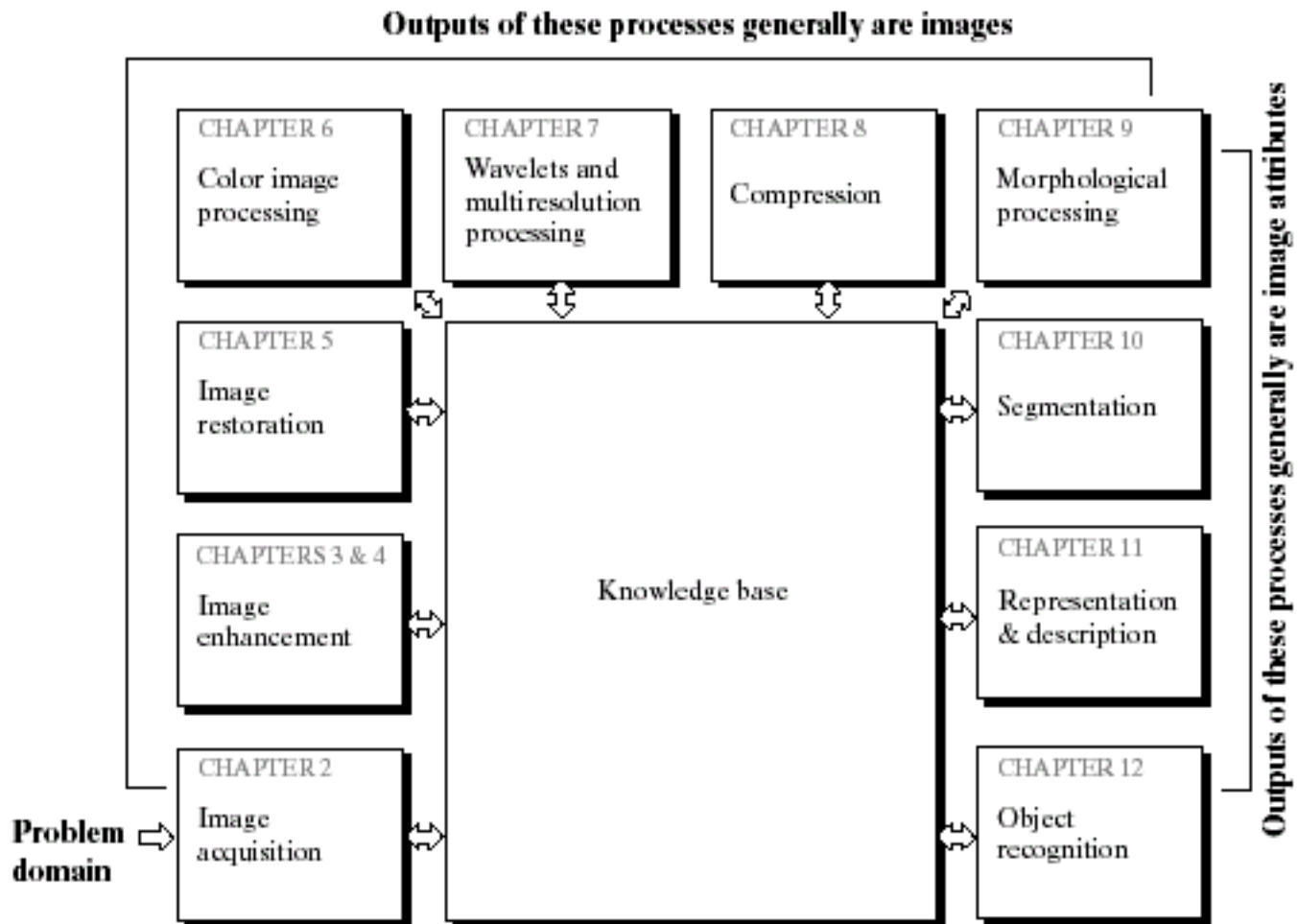
Ultrasonic Baby image during pregnancy



# Fundamental Steps in Image Processing



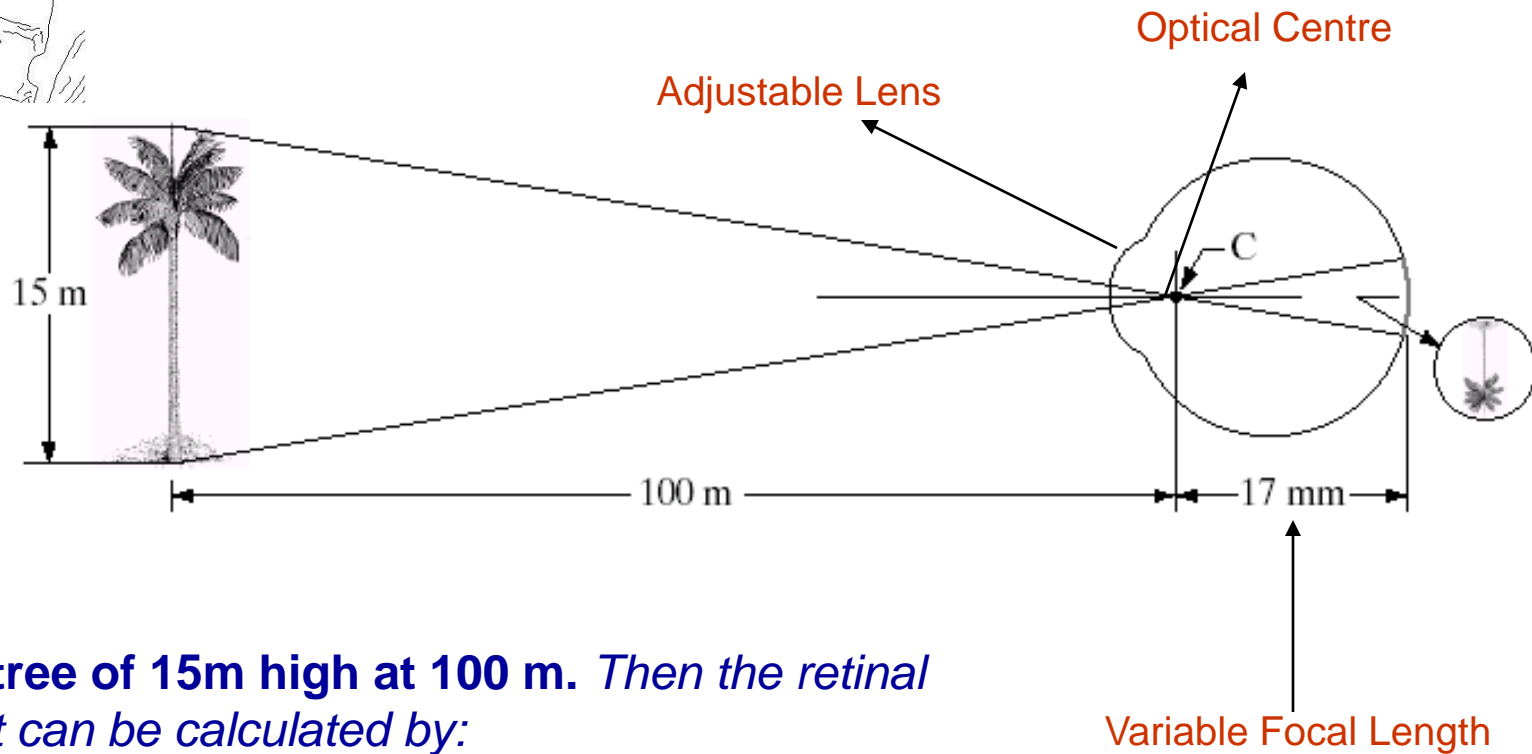
**FIGURE 1.23**  
Fundamental  
steps in digital  
image processing.



# The Human Eye & Image Formation



**FIGURE 2.3**  
Graphical representation of the eye looking at a palm tree. Point C is the optical center of the lens.



**Consider a tree of 15m high at 100 m. Then the retinal image height can be calculated by:**

$$\frac{15}{100} = \frac{h}{17} \Rightarrow h = 2.55\text{mm}$$



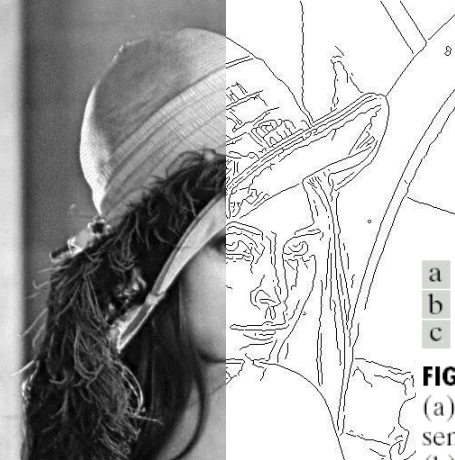
## Acquisition of Images.

The images are generated by the combination of an *illumination source* and the reflection or absorption of energy from that source by the elements of the *scene* being imaged.

*Imaging sensors* are used to transform the *illumination energy* into digital images.

Each *sensor* transforms the incoming energy into *voltage* by the combination of the input electrical power and the sensor material that is responsive to the particular type of energy being detected.

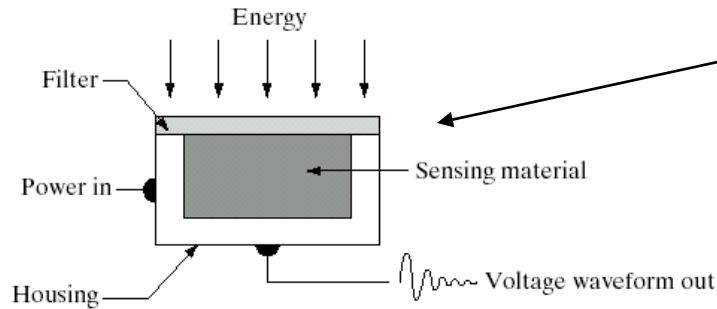
# Types of Image Sensors



a  
b  
c

**FIGURE 2.12**

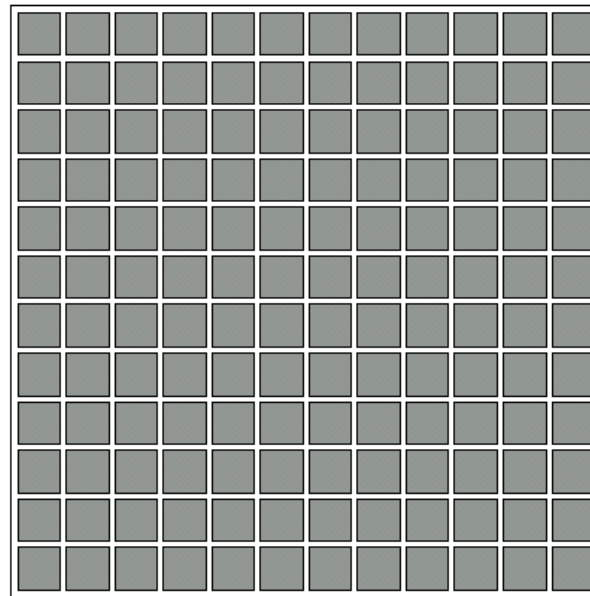
(a) Single imaging sensor.  
(b) Line sensor.  
(c) Array sensor.



**Single Sensor**



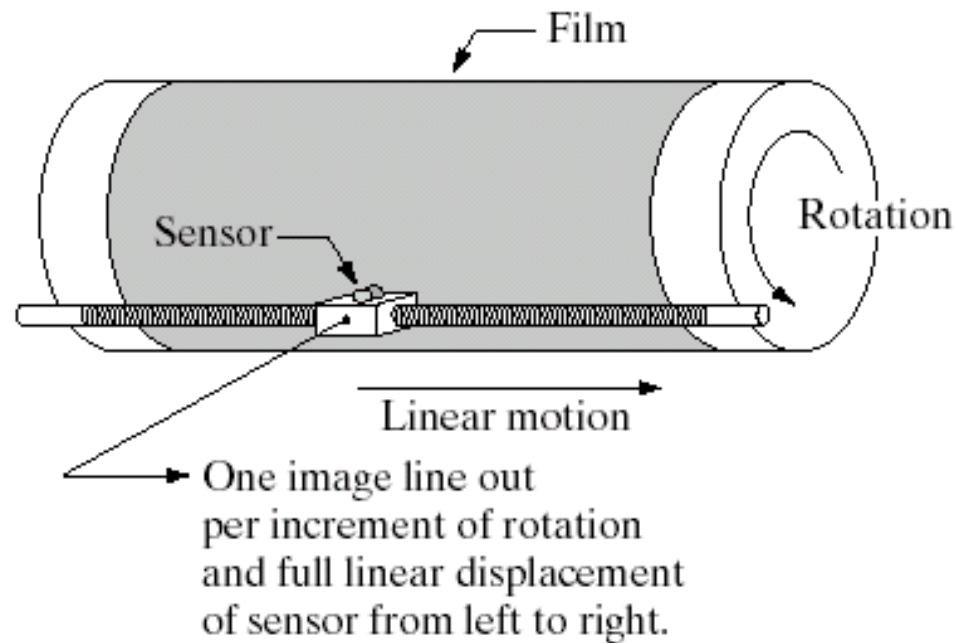
**Line Sensor**



**Array Sensor**

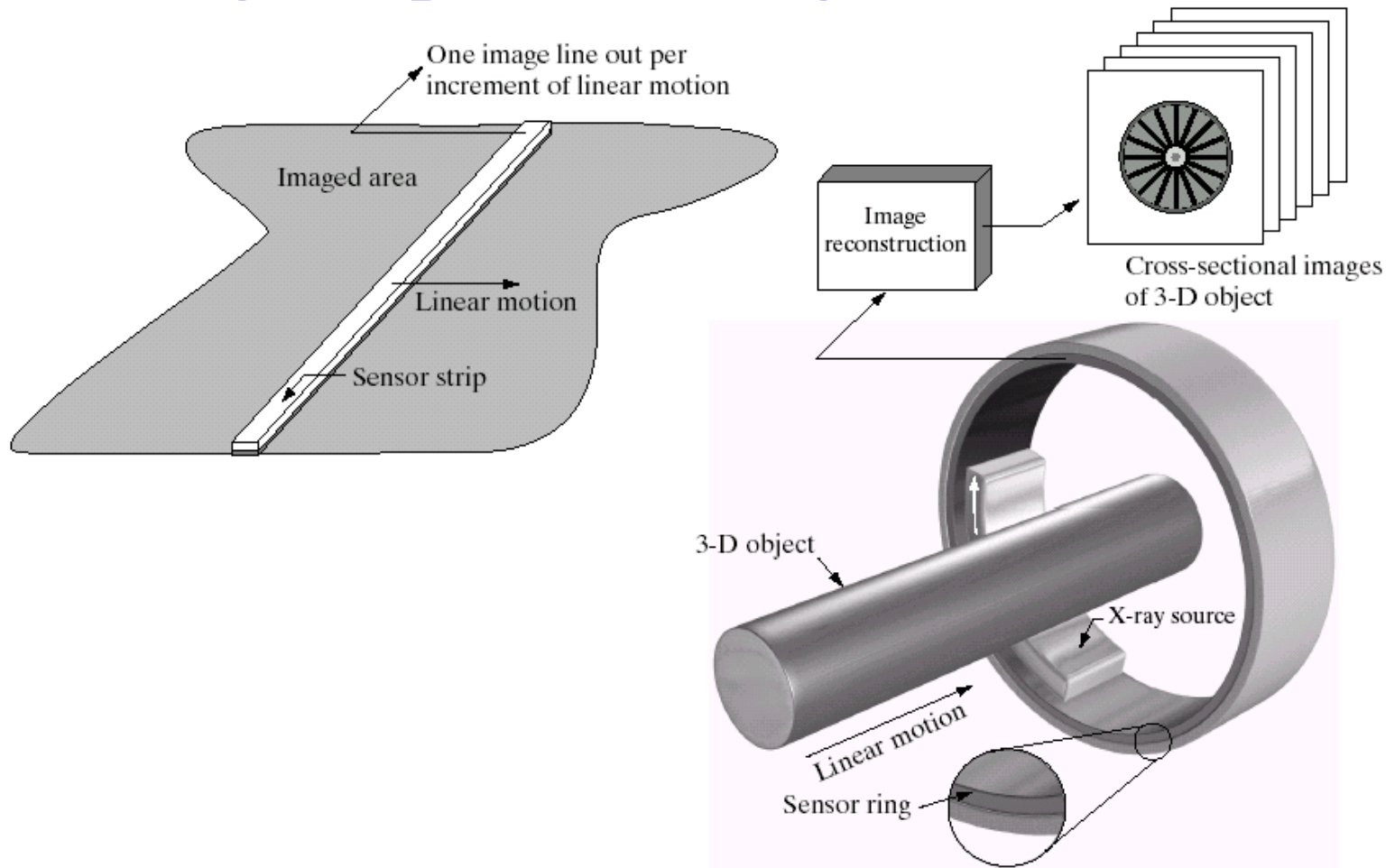


## Image Acquisition using Single Sensor



**FIGURE 2.13** Combining a single sensor with motion to generate a 2-D image.

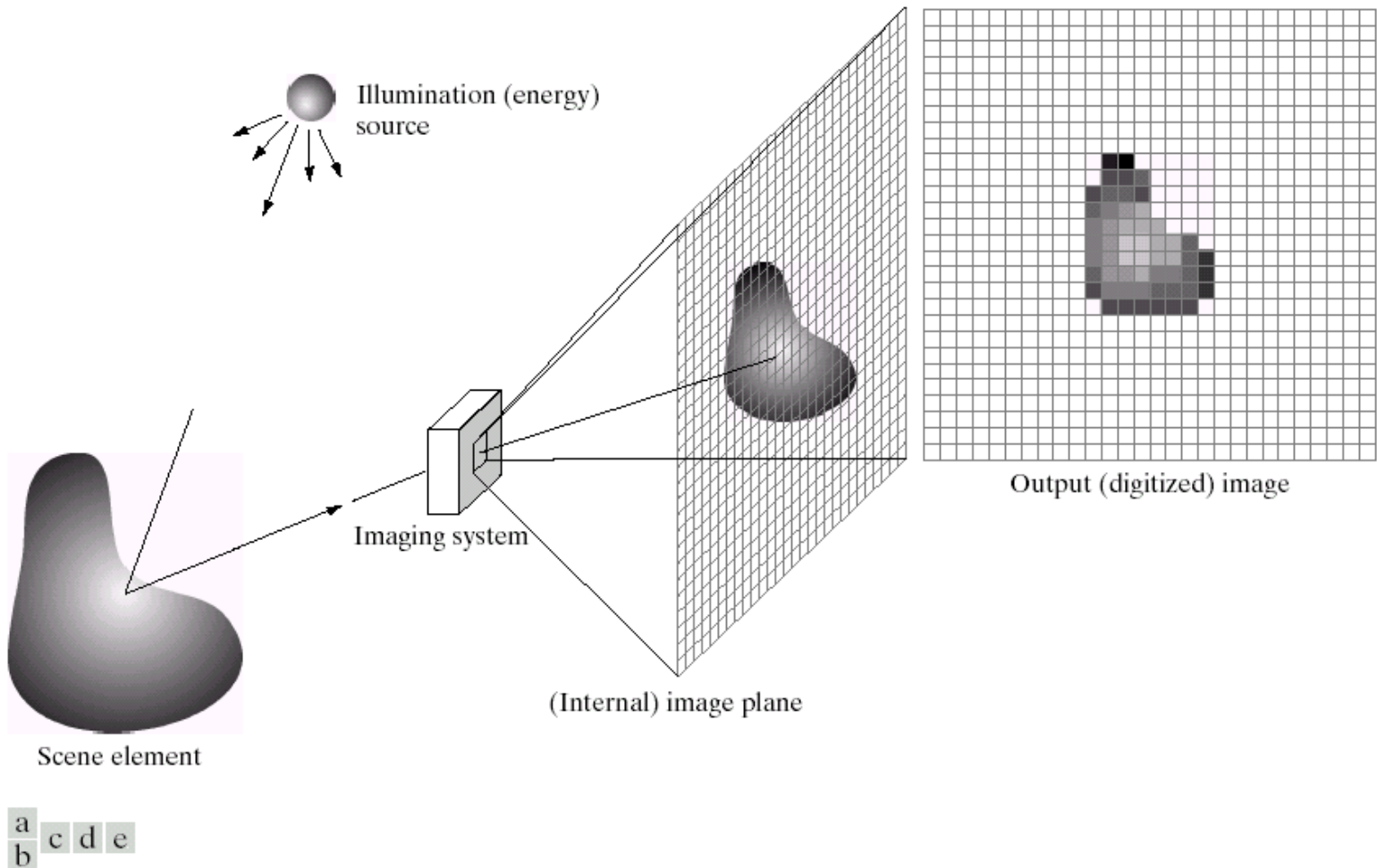
## Image Acquisition using Line Sensor



a b

**FIGURE 2.14** (a) Image acquisition using a linear sensor strip. (b) Image acquisition using a circular sensor strip.

# Image Acquisition using Sensor Array



**FIGURE 2.15** An example of the digital image acquisition process. (a) Energy ("illumination") source. (b) An element of a scene. (c) Imaging system. (d) Projection of the scene onto the image plane. (e) Digitized image.



## Image Sampling and Quantization

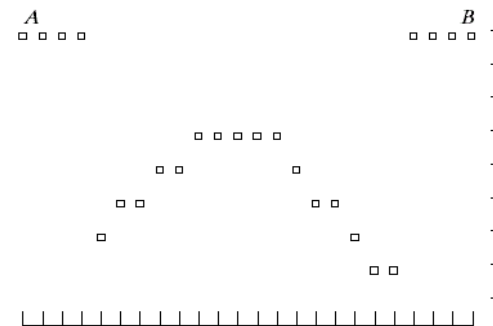
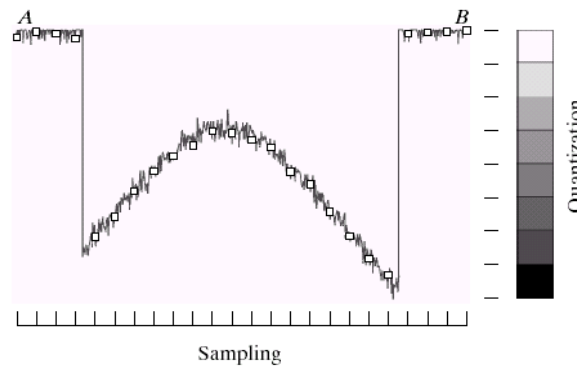
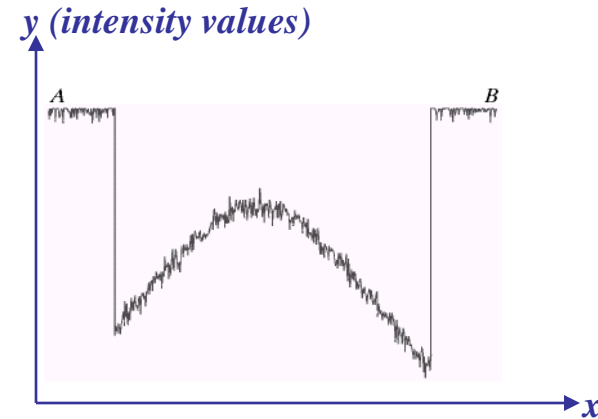
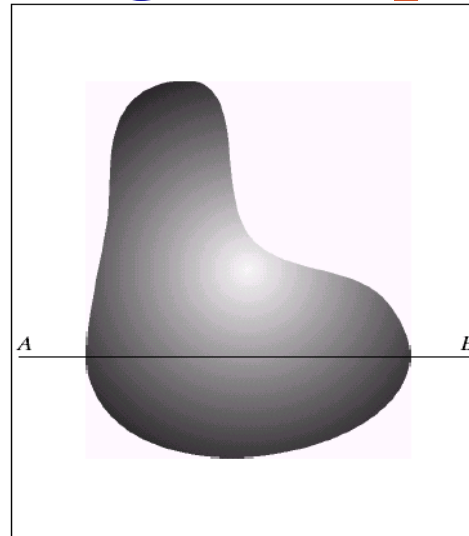
*A digital image can be obtained by converting a continuous/ analog image in a digital form by:*

*Sampling and  
Quantization.*

*Given a continuous image,  $f(x,y)$ , digitizing the coordinate values is called **sampling** and digitizing the amplitude (intensity) values is called **quantization**.*



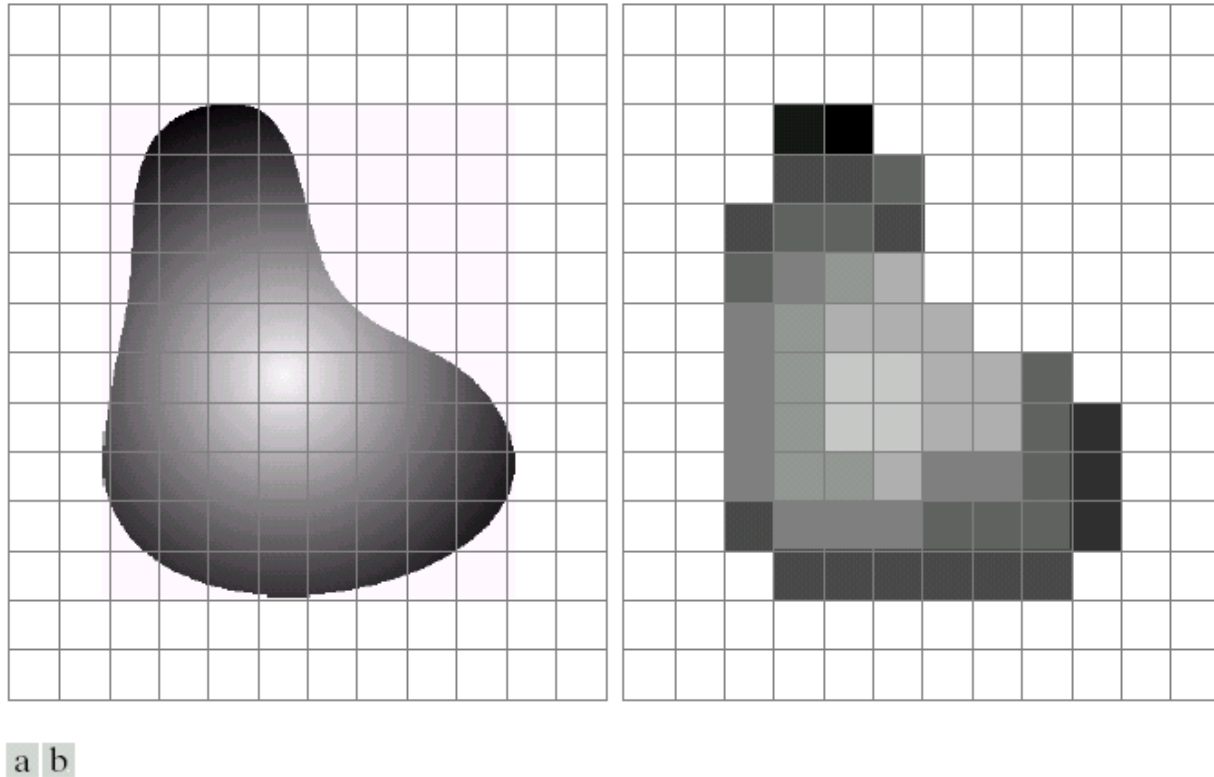
# Image Sampling and Quantization



a b  
c d

**FIGURE 2.16** Generating a digital image. (a) Continuous image. (b) A scan line from A to B in the continuous image, used to illustrate the concepts of sampling and quantization. (c) Sampling and quantization. (d) Digital scan line.

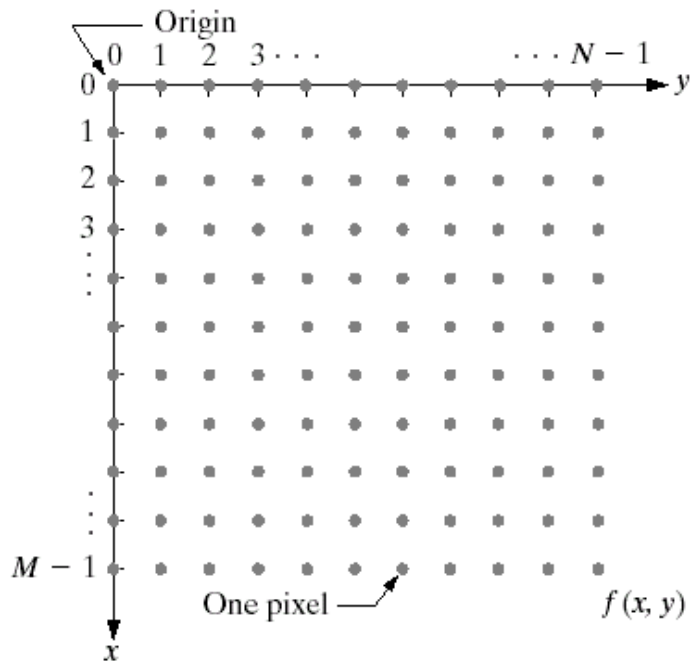
# Image Sampling and Quantization



**FIGURE 2.17** (a) Continuous image projected onto a sensor array. (b) Result of image sampling and quantization.



# Matrix Representation of Images



**FIGURE 2.18**

Coordinate convention used in this book to represent digital images.

- $M$  and  $N$  can be any positive integers.
- The number of gray levels,  $L$ , is an integer power of 2.

$$L = 2^k \quad (k \text{ is \# of bits per pixel})$$

- Number of bits required to store a digitized image:

$$b = N \times M \times k$$

*Dr. Hasan Demirel, PhD*



## Number of bits used to represent an image

Assume that  $M=N$ . Therefore  $b=N^2 k$

**TABLE 2.1**

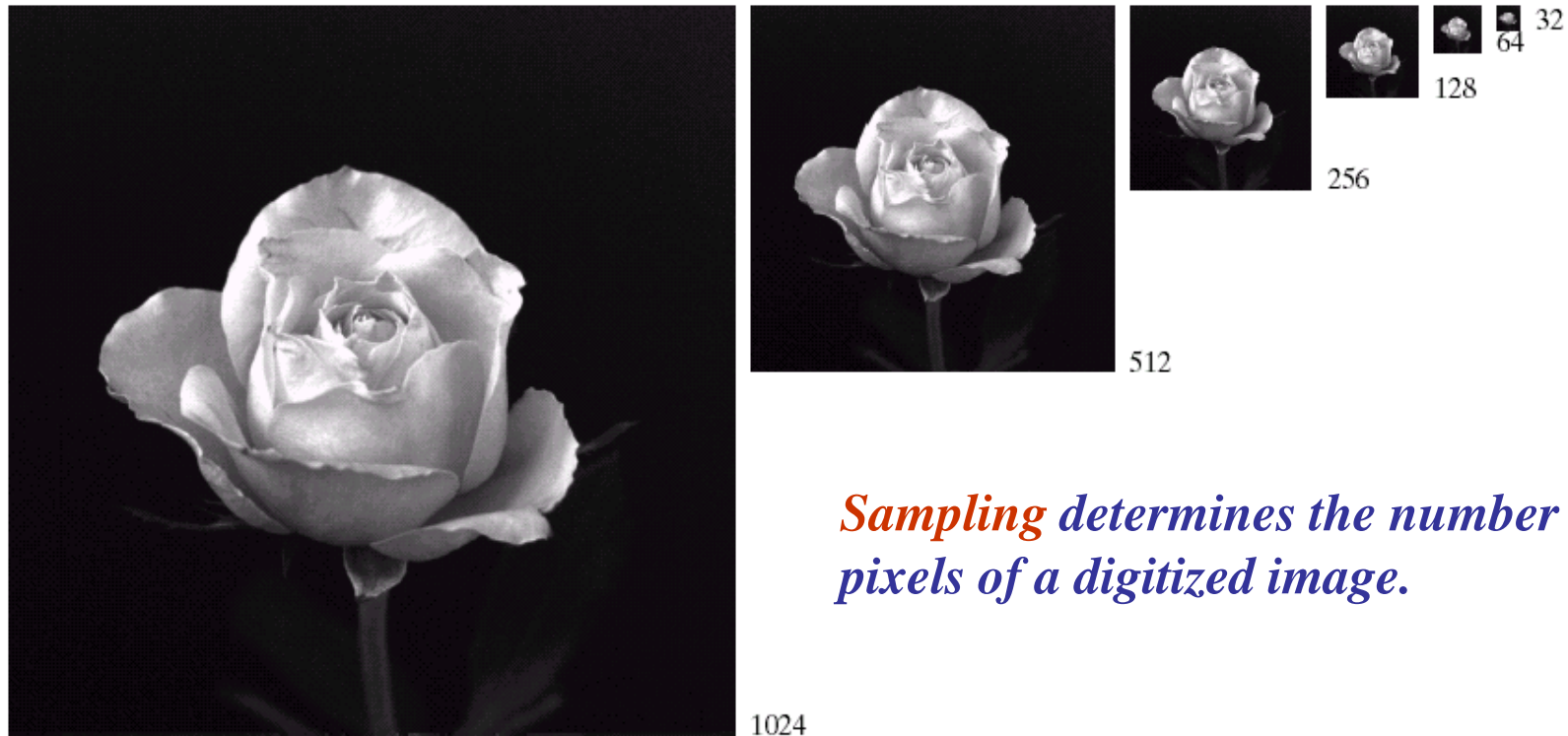
Number of storage bits for various values of  $N$  and  $k$ .

$N/k$	1 ( $L = 2$ )	2 ( $L = 4$ )	3 ( $L = 8$ )	4 ( $L = 16$ )	5 ( $L = 32$ )	6 ( $L = 64$ )	7 ( $L = 128$ )	8 ( $L = 256$ )
32	1,024	2,048	3,072	4,096	5,120	6,144	7,168	8,192
64	4,096	8,192	12,288	16,384	20,480	24,576	28,672	32,768
128	16,384	32,768	49,152	65,536	81,920	98,304	114,688	131,072
256	65,536	131,072	196,608	262,144	327,680	393,216	458,752	524,288
512	262,144	524,288	786,432	1,048,576	1,310,720	1,572,864	1,835,008	2,097,152
1024	1,048,576	2,097,152	3,145,728	4,194,304	5,242,880	6,291,456	7,340,032	8,388,608
2048	4,194,304	8,388,608	12,582,912	16,777,216	20,971,520	25,165,824	29,369,128	33,554,432
4096	16,777,216	33,554,432	50,331,648	67,108,864	83,886,080	100,663,296	117,440,512	134,217,728
8192	67,108,864	134,217,728	201,326,592	268,435,456	335,544,320	402,653,184	469,762,048	536,870,912



## Sampling and Spatial Resolution

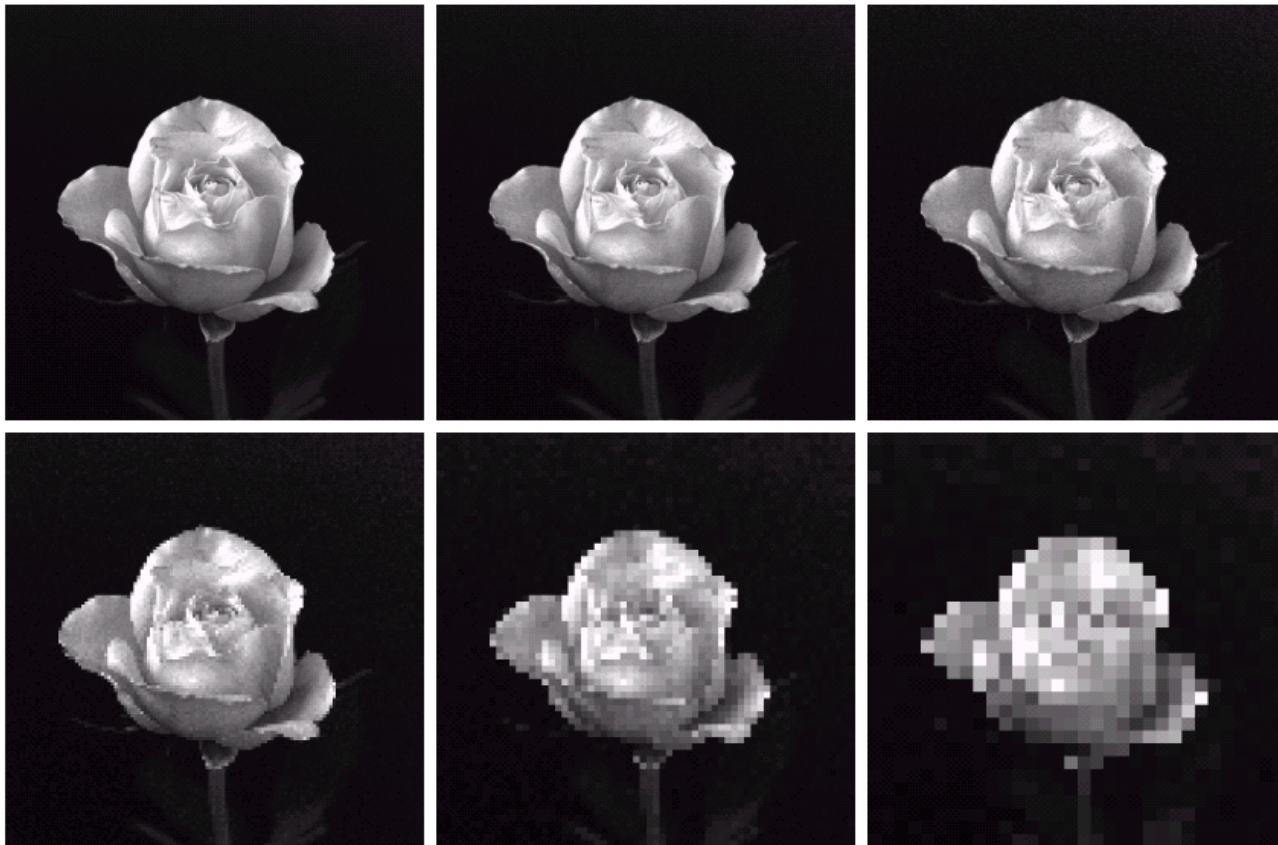
*Sampling* is the principal factor determining the *spatial resolution* of an image.



**FIGURE 2.19** A  $1024 \times 1024$ , 8-bit image subsampled down to size  $32 \times 32$  pixels. The number of allowable gray levels was kept at 256.



## Sampling and Spatial Resolution



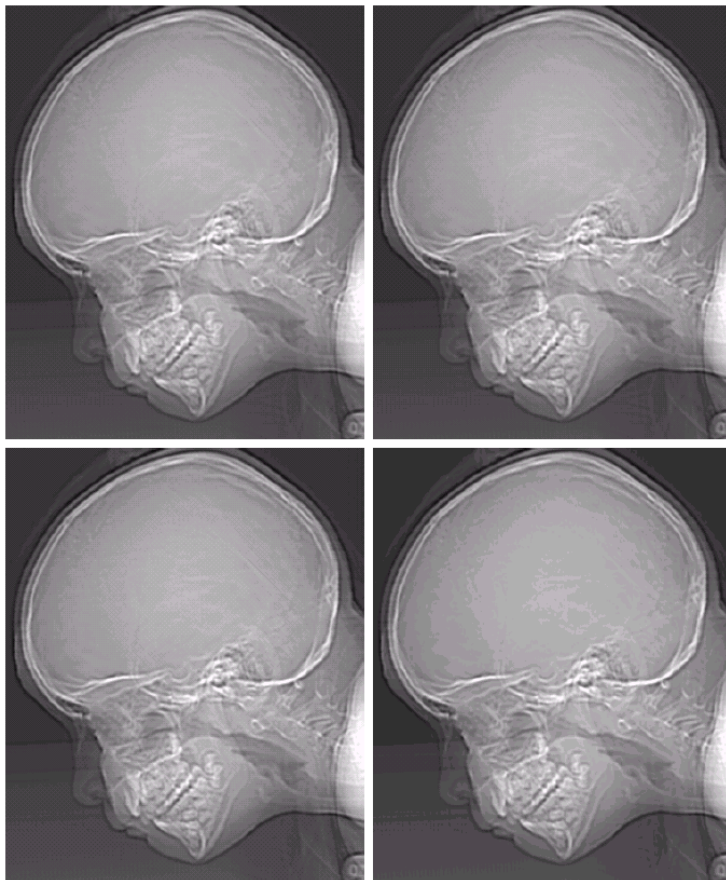
a	b	c
d	e	f

**FIGURE 2.20** (a)  $1024 \times 1024$ , 8-bit image. (b)  $512 \times 512$  image resampled into  $1024 \times 1024$  pixels by row and column duplication. (c) through (f)  $256 \times 256$ ,  $128 \times 128$ ,  $64 \times 64$ , and  $32 \times 32$  images resampled into  $1024 \times 1024$  pixels.

# Quantization and Gray-level Resolution

*Quantization is the most important factor determining the gray-level resolution of an image.*

*Quantization determines the number of gray levels that each pixel can take.*



a b  
c d

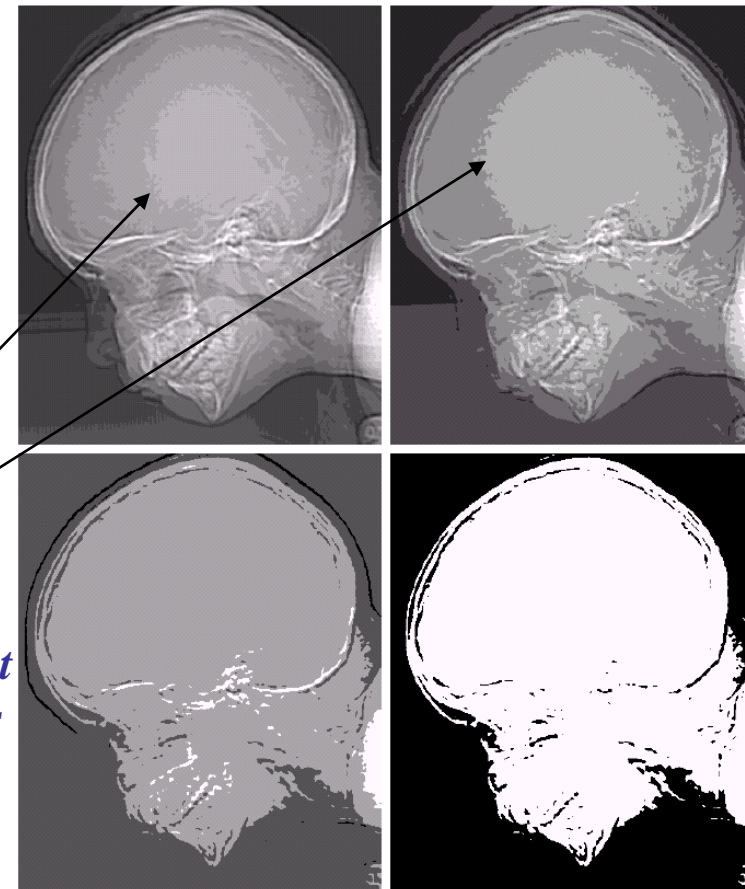
**FIGURE 2.21**

(a)  $452 \times 374$ , 256-level image. (b)–(d) Image displayed in 128, 64, and 32 gray levels, while keeping the spatial resolution constant.

e f  
g h

**FIGURE 2.21**

(Continued) (e)–(h) Image displayed in 16, 8, 4, and 2 gray levels. (Original courtesy of Dr. David R. Pickens, Department of Radiology & Radiological Sciences, Vanderbilt University Medical Center.)



*False contouring effect is visible in 16 and less gray level images.*

## Resizing Images: **Zooming** and **Shrinking**

**Zooming** is a method of increasing the size of a given image. Zooming can be viewed as **oversampling** or **upsampling** of a given image.

Zooming requires **2 steps**:

- Creation of new pixel locations
- Assigning new gray-level values to these locations by using **interpolation**.

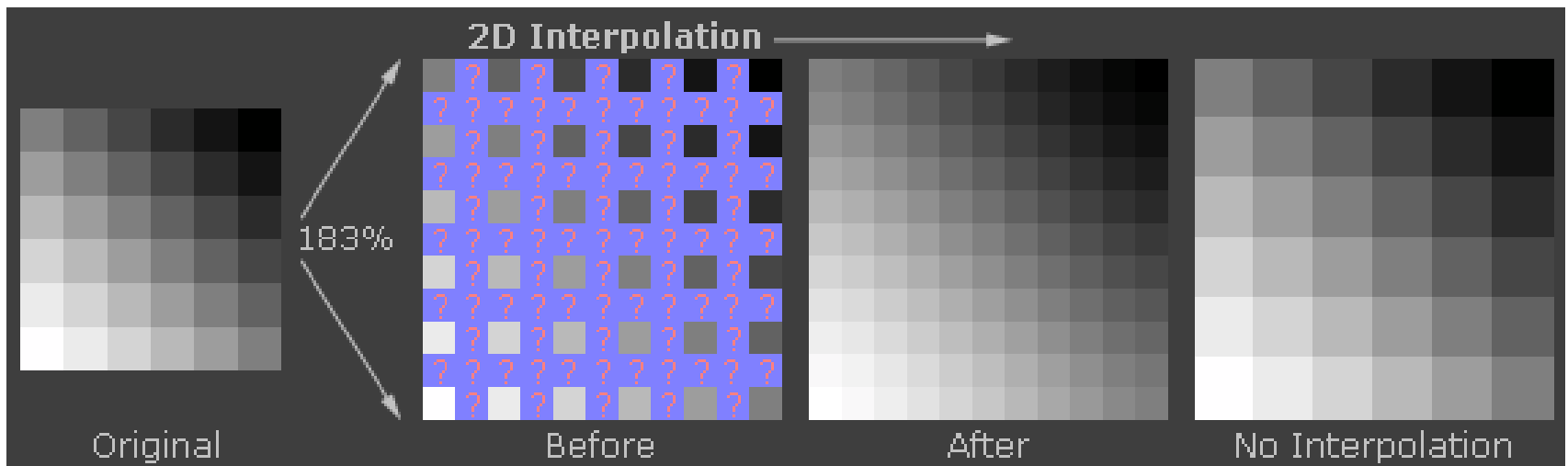


**Interpolation** is defined to be the estimation of the value of unknown point by using the values of known points.



# Resizing Images: **Zooming** and **Shrinking**

## *2-D Interpolation*



*There are 3 main types of 2-D Interpolation techniques for zooming:*

- nearest neighbor interpolation*
- bilinear interpolation*
- bicubic interpolation*

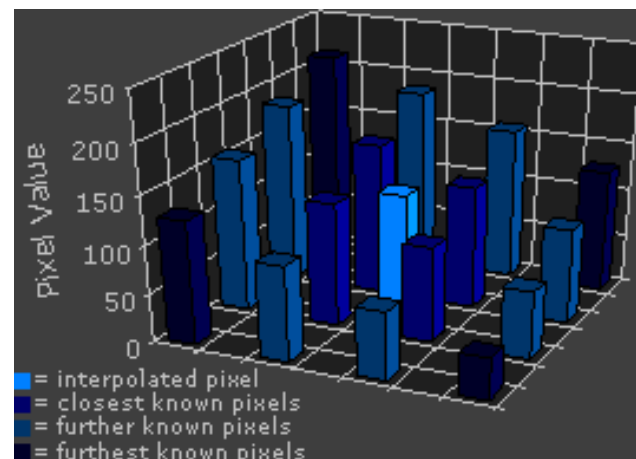
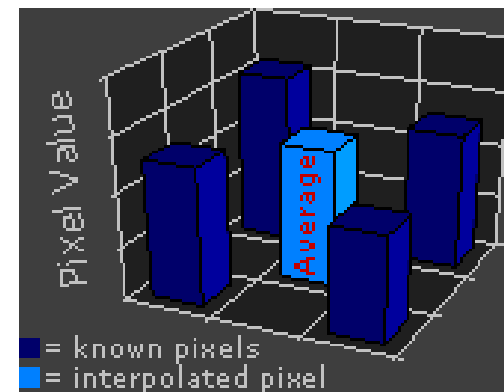


## Zooming : Interpolation Techniques

**Nearest neighbor interpolation:** *Nearest neighbor interpolation is the simplest method and basically makes the pixels bigger. The intensity of a pixel in the new image is the intensity of the nearest pixel of the original image. If you enlarge 200%, one pixel will be enlarged to a 2 x 2 area of 4 pixels with the same color as the original pixel.*

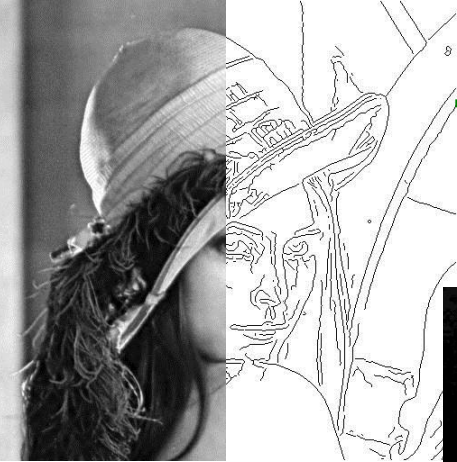


**Bilinear interpolation:** *Bilinear interpolation considers the closest 2x2 neighborhood of known pixel values surrounding the unknown pixel. It then takes a weighted average of these 4 pixels to arrive at its final interpolated value. This results in much smoother looking images than nearest neighbor.*



**Bicubic interpolation:** *Bicubic goes one step beyond bilinear by considering the closest 4x4 neighborhood of known pixels- for a total of 16 pixels. Since these are at various distances from the unknown pixel, closer pixels are given a higher weighting in the calculation. Bicubic interpolation produces noticeably sharper images than the previous two methods, and is perhaps the ideal combination of processing time and output quality.*

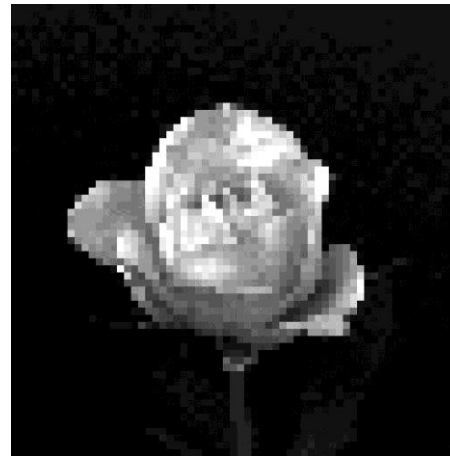
# Zooming : Interpolation Techniques



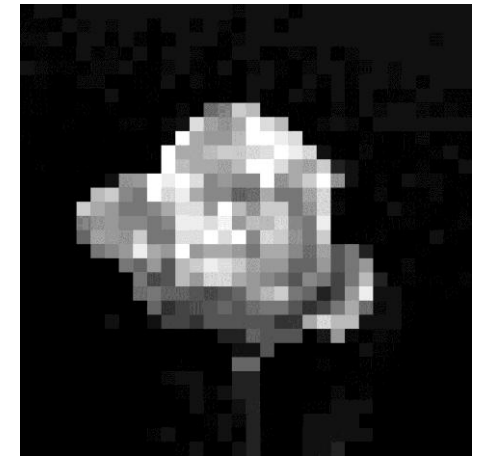
*Nearest Neighbour*



128x128  $\Rightarrow$  1024x1024



64x64  $\Rightarrow$  1024x1024



32x32  $\Rightarrow$  1024x1024

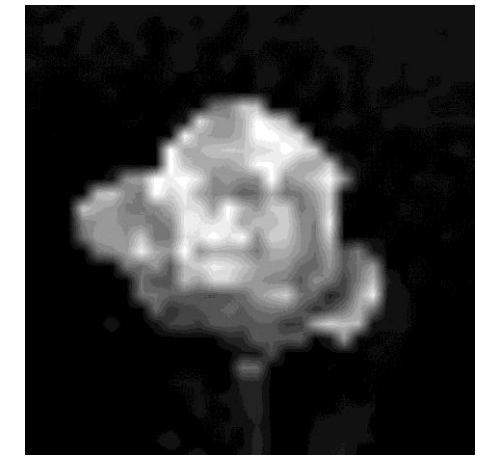
*Bilinear*



128x128  $\Rightarrow$  1024x1024



64x64  $\Rightarrow$  1024x1024



32x32  $\Rightarrow$  1024x1024

## Zooming : Interpolation Techniques



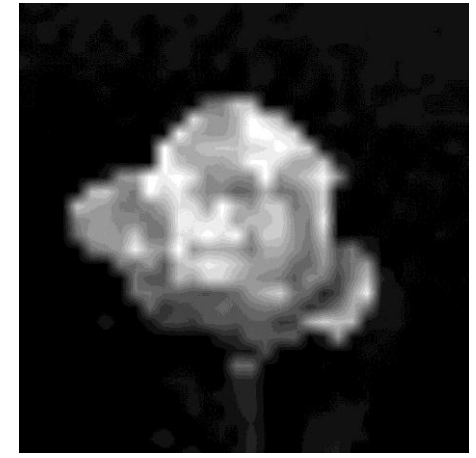
*Bilinear*



128x128  $\Rightarrow$  1024x1024



64x64  $\Rightarrow$  1024x1024



32x32  $\Rightarrow$  1024x1024

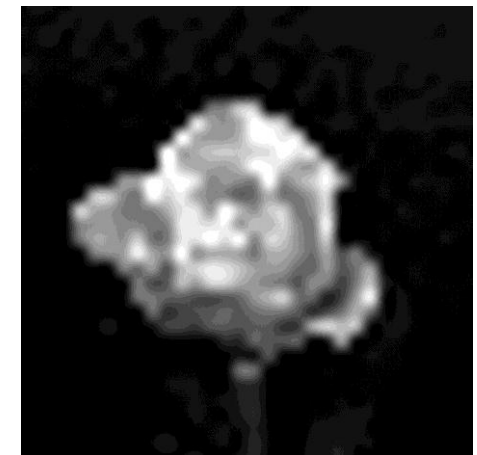
*Bicubic*



128x128  $\Rightarrow$  1024x1024



64x64  $\Rightarrow$  1024x1024



32x32  $\Rightarrow$  1024x1024



## Zooming : Interpolation Techniques

### *Nearest neighbor interpolation:*

- *Fastest Processing*
- *Produces undesired checkboard/blocking (**Aliasing**) effect*
- *May be good for rectangular images*
- *Not suitable for detailed or photographic images*

### *Bilinear interpolation:*

- *smoother looking images than nearest neighbor.*
- *has an **anti-aliasing** effect, therefore less blocking effect than nearest neighbor.*

### *Bicubic interpolation:*

- *produces noticeably **sharper** images than the previous two methods.*
- *has an **anti-aliasing** effect (Almost no blocking).*
- *used as a standard in many image editing programs (i.e. Adobe Photoshop)*