

Introduction to Inverse Problem in Imaging

EC 522 Computational Optical Imaging

Lei Tian

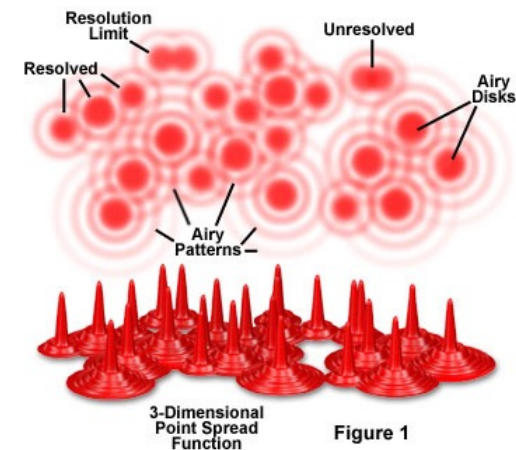
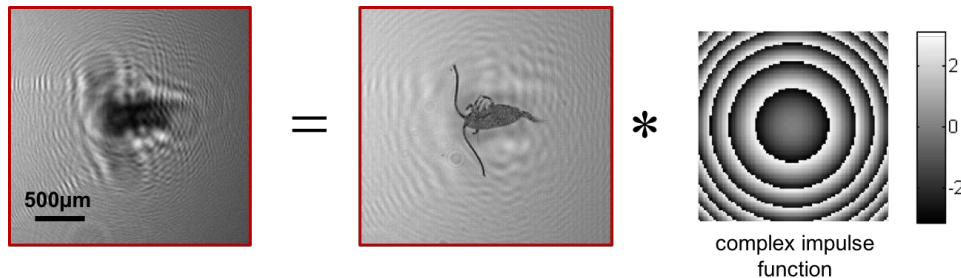


Figure 1

Admins

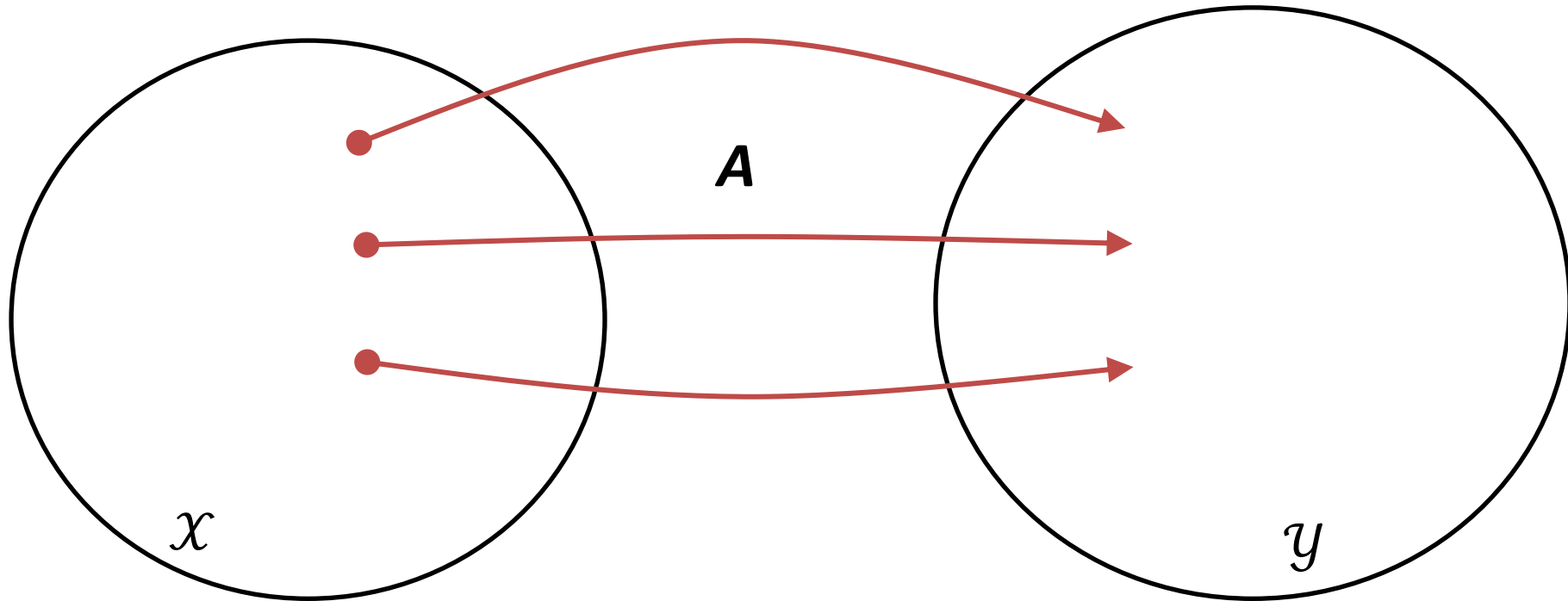
- » HW 2 is posted
 - » Due 2/21 (Wednesday; after Presidents' day break)

Mathematical tools & road map

- » Vector space (IIP Appx A)
 - » Key idea: think about the imaging signals as a vector
- » Linear operator (IIP Appx B)
 - » Key idea: think about imaging process as a linear transformation, i.e. a linear operator
 - » Later, we will perform discretization and convert the operator into a matrix

Linear operator

Linear operator



» Linear operator A maps the input to the output:

$$» A: \mathcal{X} \rightarrow \mathcal{Y}$$

Linear operator

- » Linear operator $A: \mathcal{X} \rightarrow \mathcal{Y}$ satisfies
 - » $A(\alpha_1 f_1 + \alpha_2 f_2) = \alpha_1 A(f_1) + \alpha_2 A(f_2)$, for any complex numbers α_1 and α_2
 - » Additivity: $A(f_1 + f_2) = A(f_1) + A(f_2)$
 - » Scalability: $A(\alpha f) = \alpha A(f)$
- » Simplified notation as
 - » $Af = g$

Linear operator: example

» *Fourier transform* is linear operator

$$\text{» } \mathcal{F}(\alpha_1 f_1 + \alpha_2 f_2) = \alpha_1 \mathcal{F}(f_1) + \alpha_2 \mathcal{F}(f_2)$$

» CTFT: $\mathcal{L}^2(\mathbb{R}) \rightarrow \mathcal{L}^2(\mathbb{R})$

» DFT: $\mathbb{C}^N \rightarrow \mathbb{C}^N$

Fourier transform can be treated as linear operator!

Range space*

- » The **Range space** of a linear operator $A: \mathcal{X} \rightarrow \mathcal{Y}$
- » The set of all elements $g \in \mathcal{Y}$ from $Af = g$

$$\mathcal{R}(A) = \{g = Af \in \mathcal{Y}, f \in \mathcal{X}\}$$

- » $\mathcal{R}(A)$ is a subspace in \mathcal{Y}

* plays a central role in inverse problem

Null space *

- » The **null space** of a linear operator A : $\mathcal{N}(A)$
 - » The set of all elements $f \in \mathcal{X}$ such that $Af = 0$

$$\mathcal{N}(A) = \{f \in \mathcal{X}, Af = 0\}$$

- » $\mathcal{N}(A)$ is a subspace in \mathcal{X}

* plays a central role in inverse problem

LSI system and Convolution operator

Convolution operator

» Convolution operator A

$$\begin{aligned}\text{» } (Af)(x) &= K(x) * f(x) \\ &= \int K(x - x')f(x')dx'\end{aligned}$$

» Spectral representation

$$\text{» } (Af)(x) = \int \tilde{K}(u) \tilde{f}(u) e^{i2\pi xu} du$$

» Properties: linear & bounded

Why?

Convolution operator

- » Properties: bounded
- » Proof:
 - » Existence of FT

$$\hat{K}_{max} = \max_{\omega} |\hat{K}(\omega)|$$

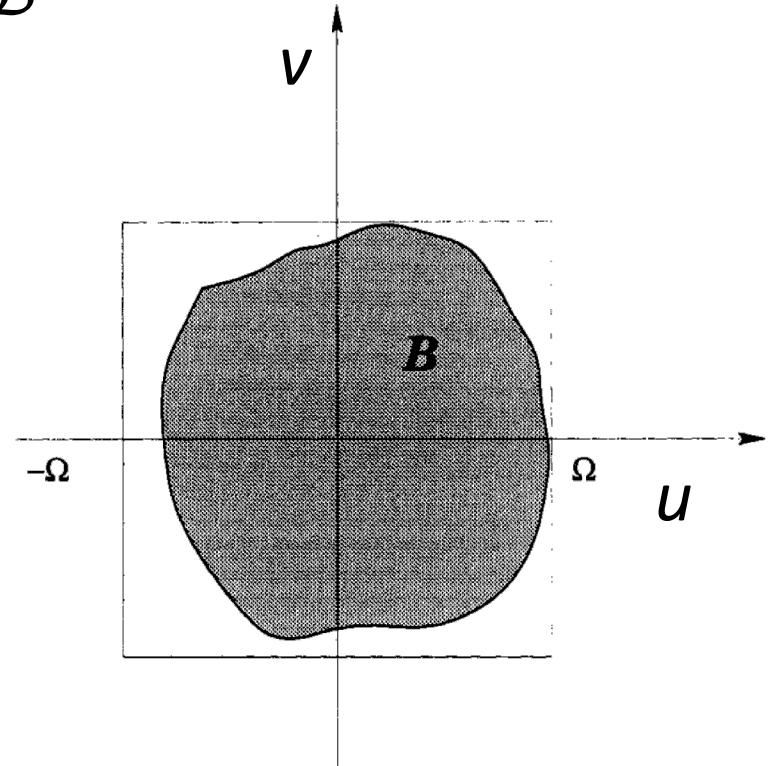
$$\longrightarrow \|Af\| \leq \hat{K}_{max} \|f\|.$$

Bandlimited convolution operator/system

» Frequency Support (Band): \mathcal{B}

» Bandlimited system

» $\tilde{K}(u) = 0$, for $u \notin \mathcal{B}$



Range of a convolution operator

- » Range of convolution operator A , $\mathcal{R}(A)$
 - » $\mathcal{R}(A)$ contains all the bandlimited functions with a band that is contained in \mathcal{B} :
 - » $\mathcal{R}(A) \subset \{g \in L^2 \mid \tilde{g}(u) = 0, u \notin \mathcal{B}\}$

The Range of A is set by \mathcal{B}

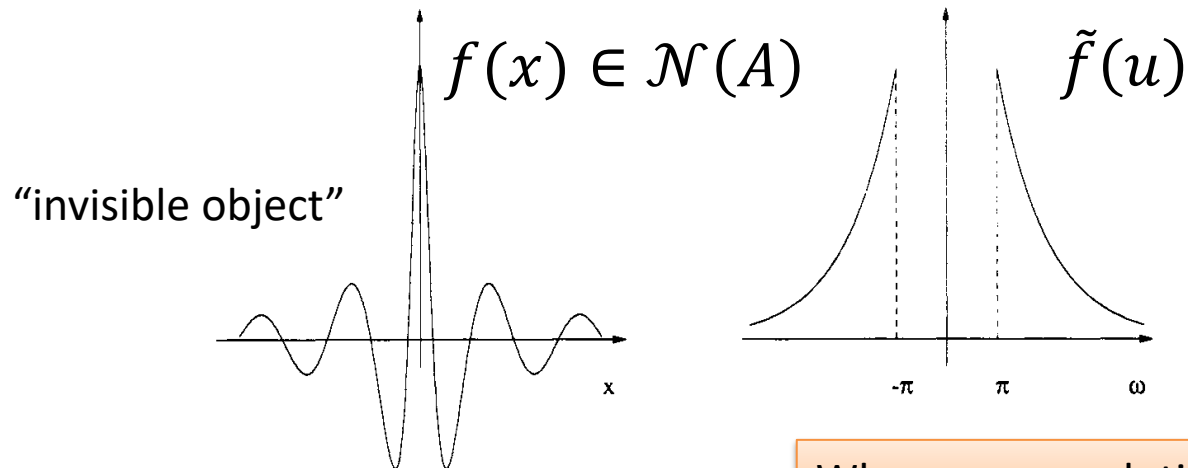
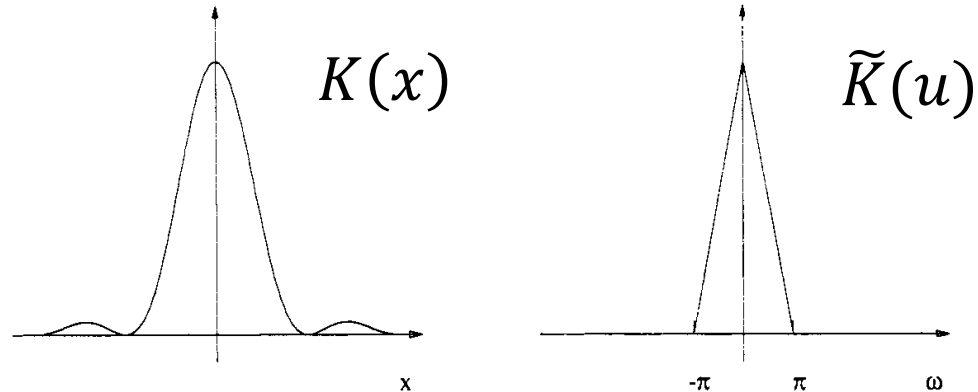
Side note:

- I found it is easier to work with $u = \omega/2\pi$ in FT and IFT, the textbook uses ω .
- Throughout the lecture, we will use the definition in the u -space.

Null space of a convolution operator

- » Null space of convolution operator $A, \mathcal{N}(A)$
 - » $\mathcal{N}(A)$ contains all the functions that satisfy
 - » $\mathcal{N}(A) \supset \{f \in L^2 \mid \tilde{f}(u) = 0, u \in \mathcal{B}\}$
 - » “invisible object”?

Example: Null space of a convolution operator



Why super-resolution is hard?

Linear operator (cont'd)

» Linear operator A is **bounded**, if

» there exists a constant M such that, for every f

$$\|Af\|_Y \leq M\|f\|_X$$

» The operator **norm** of A :

$$\|A\| = \sup_{f \in X} \frac{\|Af\|_Y}{\|f\|_X}$$

supremum = the least upper bound

» The operator A is **continuous**, if

» $\|f_n - f\|_X \rightarrow 0$ then $\|Af_n - Af\|_Y \rightarrow 0$

» Iff A is bounded

Inverse operator

- » A bounded linear operator $A: \mathcal{X} \rightarrow \mathcal{Y}$ is invertible if there exists a bounded linear operator $B: \mathcal{Y} \rightarrow \mathcal{X}$ such that


$$BAx = x \text{ for every } x \in \mathcal{X}, \text{ and}$$

$$AB y = y \text{ for every } y \in \mathcal{Y}$$

- » *Theoretical useful, in practice, inverse rarely exist*

Inverse of a convolution operator

- » If $\tilde{K}(u)$ has a support coincides with the whole frequency space



Non-zero everywhere
except for isolated point

- » The inverse operator A^{-1}

- » $(A^{-1}g)(x) = \frac{1}{2\pi} \int \frac{\tilde{g}(u)}{\tilde{K}(u)} e^{i2\pi xu} du$

- » *Not* bounded if $\tilde{K}(u)$ contains zeros.

Adjoint operator *

- » The **adjoint** operator A^* (or A^H) of a linear and bounded operator A
 - » $A^*: \mathcal{Y} \rightarrow \mathcal{X}$ is the **adjoint** of $A: \mathcal{X} \rightarrow \mathcal{Y}$, when

$$\langle Ax, y \rangle_{\mathcal{Y}} = \langle x, A^*y \rangle_{\mathcal{X}} \text{ for every } x \in \mathcal{X}, y \in \mathcal{Y}$$

- » If $A = A^*$, A is **self-adjoint** or **Hermitian**
- » Generalization of the **Hermitian transpose** (complex conjugate transpose) of a matrix

*** important in inverse problem**

Exercise: Adjoint operator

What is the adjoint of Fourier transform operator?

Example: adjoint for LSI system

Adjoint of a convolution operator

» Definition of Adjoint operator:

$$\langle Ax, y \rangle_y = \langle x, A^* y \rangle_x$$

» Use definition of the convolution operator

$$\begin{aligned}\langle Ax, y \rangle_y &= \frac{1}{(2\pi)^q} \int \hat{K}(\omega) \hat{f}(\omega) \hat{g}^*(\omega) d\omega \\ &= \frac{1}{(2\pi)^q} \int \hat{f}(\omega) \left[\hat{K}^*(\omega) \hat{g}(\omega) \right]^* d\omega \\ &= (f, A^* g)\end{aligned}$$

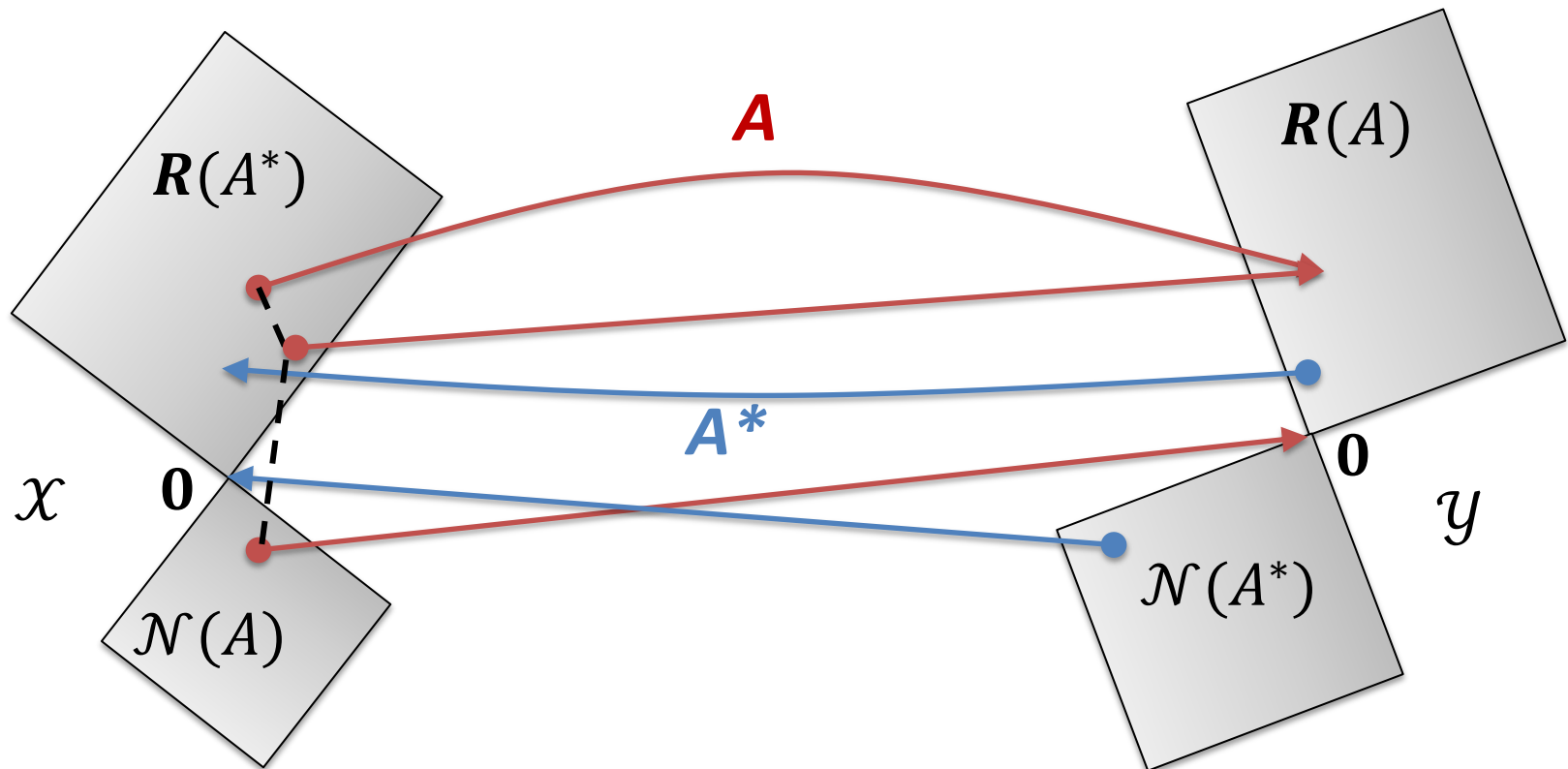
$$\longrightarrow (A^* g)(x) = \frac{1}{(2\pi)^q} \int \hat{K}^*(\omega) \hat{g}(\omega) e^{ix \cdot \omega} d\omega.$$

Properties of Adjoint operator

- » The adjoint A^* is unique
- » $(A^*)^* = A$
- » The operators AA^* and A^*A are self-adjoint
- » $\|A^*\| = \|A\|$
- » If A is invertible, $(A^{-1})^* = (A^*)^{-1}$
- » $(A+B)^* = A^* + B^*$ why
- » $(BA)^* = A^*B^*$ why

Geometric relation between null space and range space

$$\begin{aligned}\mathcal{N}(A) &= \mathcal{R}(A^*)^\perp \\ \mathcal{N}(A^*) &= \mathcal{R}(A)^\perp\end{aligned}$$



Relation between null space and range

» Proof

*Proof B.1. We prove the first relation (B.8). From the definition (B.6) of the adjoint operator it follows that, if $f \in \mathcal{N}(A)$, i.e. $Af = 0$, then the l.h.s. of the equation (B.6) is zero for any g , so that f is orthogonal to all elements A^*g , i.e. to $\mathcal{R}(A^*)$. This result implies that $\mathcal{N}(A)$ is contained in $\mathcal{R}(A^*)^\perp$. On the other hand, if $f \in \mathcal{R}(A^*)^\perp$, then the r.h.s. of equation (B.6) is zero for any g and therefore Af is orthogonal to all elements of \mathcal{Y} . But this implies $Af = 0$, i.e. $f \in \mathcal{N}(A)$. It follows that $\mathcal{R}(A^*)^\perp$ is contained in $\mathcal{N}(A)$. By combining the two inclusions, we get $\mathcal{N}(A) = \mathcal{R}(A^*)^\perp$. The second relation in (B.8) is obtained from the first one by simply exchanging A with A^* . \square .*

Example: Relation between range and null space of a convolution operator

A is a convolution operator

$$\gg f_1 \in \mathcal{R}(A)$$

$$\gg f_2 \in \mathcal{N}(A)$$

$$\gg f_1 \perp f_2$$

and $\mathcal{N}(A) = \mathcal{R}(A)^\perp$

Why?

Relation between range and null space of a convolution operator

A is a convolution operator

» $f_1 \in \mathcal{R}(A)$ Only contain frequency component $u \in \mathcal{B}$

» $f_2 \in \mathcal{N}(A)$ Only contain frequency component $u \notin \mathcal{B}$

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Adjoint of a convolution operator

» Adjoint of convolution operator A^*

$$\begin{aligned}\text{» } (A^*g)(x) &= K^*(-x) * g(x) \\ &= \int K^*(x' - x)g(x')dx'\end{aligned}$$

» Spectral representation

$$\text{» } (A^*g)(x) = \int \tilde{K}^*(u) \tilde{g}(u) e^{i2\pi xu} du$$

Proof?

Side note:

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Unitary operator

- » Preserve geometry (lengths and angles) when mapping one vector space to another
- » A bounded linear operator $A: \mathcal{X} \rightarrow \mathcal{Y}$ is unitary, when
 - » A is invertible
 - » A preserves inner product

$$\langle f, h \rangle_{\mathcal{X}} = \langle Af, Ah \rangle_{\mathcal{Y}}, \text{ for every } f, h \in \mathcal{X}$$

Unitary operator

» A is unitary if and only if

$$A^{-1} = A^* \text{ or } A^* A = I$$

» If A is unitary, then $\|Ax\|^2 = \|x\|^2$

Eigenvector and eigenvalue of a linear operator

- » An **eigenvector** of a linear operator $A: H \rightarrow H$ is a nonzero vector $v \in H$, such that

$$Av = \lambda v$$

- » $\lambda \in \mathbb{C}$ is the **eigenvalue**.

Example: LSI system

Eigenvector/eigenvalue of self-adjoint operator

- » All eigenvalues are real
- » Eigenvectors corresponding to distinct eigenvalues are orthogonal

Definite linear operator

- » Consider operator $A: H \rightarrow H$
- » Positive semidefinite: $A \geq 0$, when
 - » $(Ax, x) \geq 0$, for all $x \in H$
- » Positive definite: $A > 0$, when
 - » $(Ax, x) > 0$, for all $x \in H$

A summary of LSI system and Convolution operator

Convolution operator

» Convolution operator A

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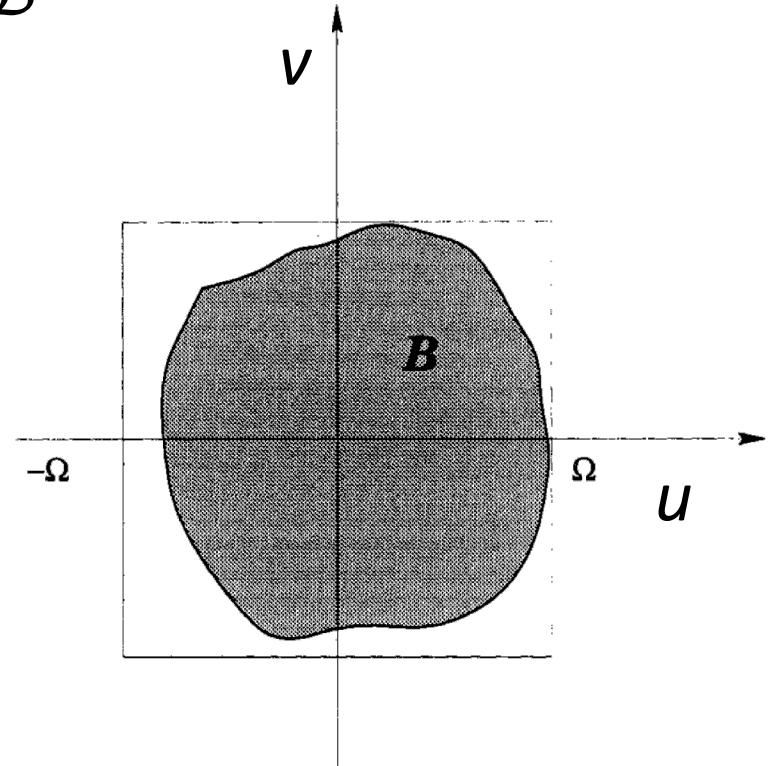
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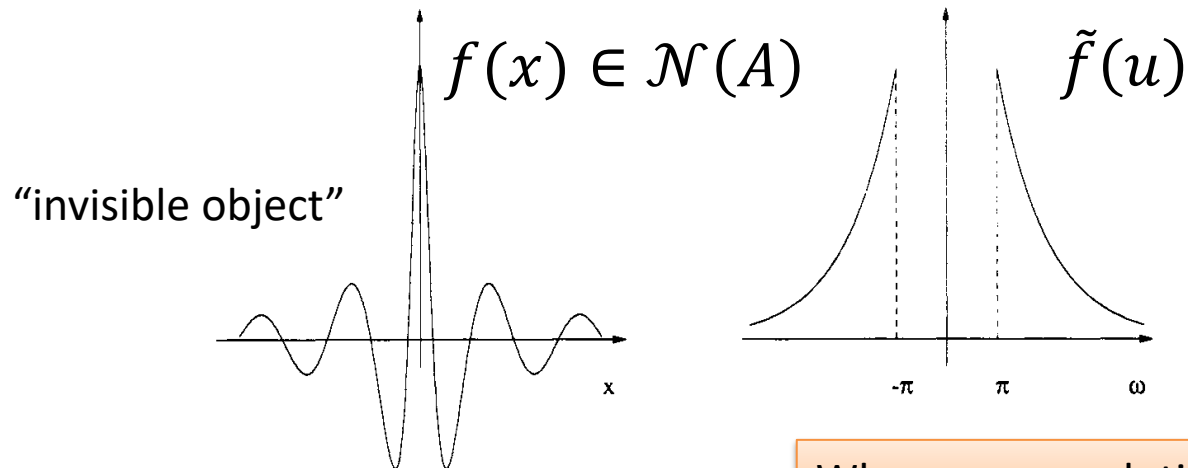
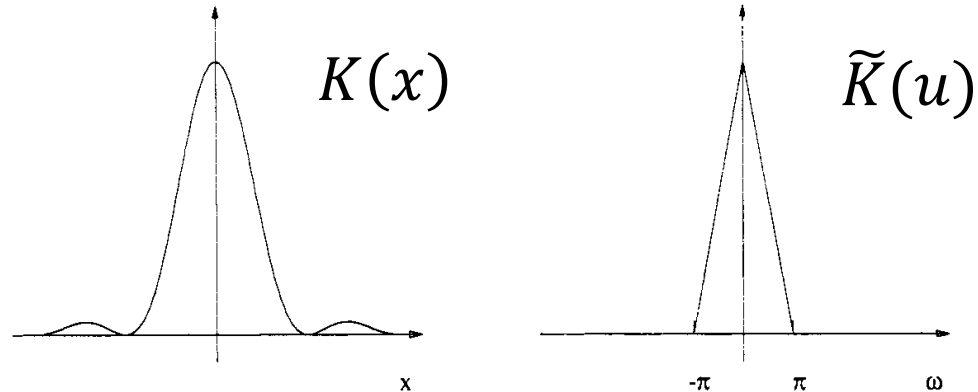
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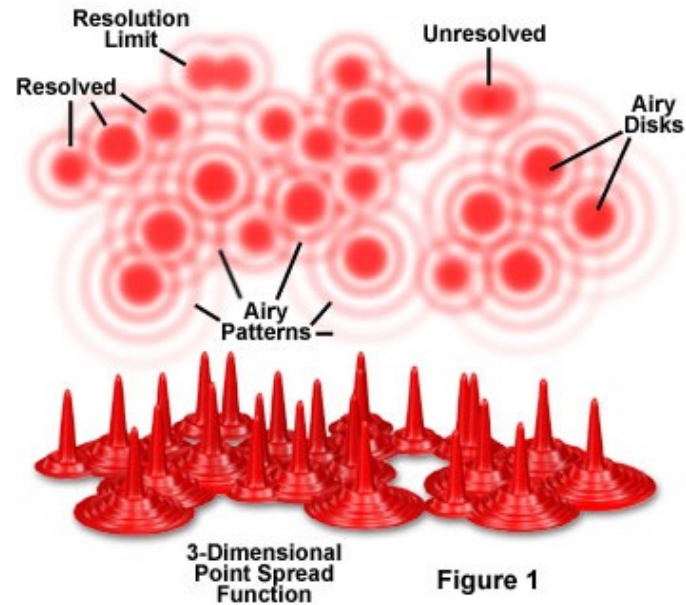
Non-zero everywhere
except for isolated point

- » The inverse operator A^{-1}

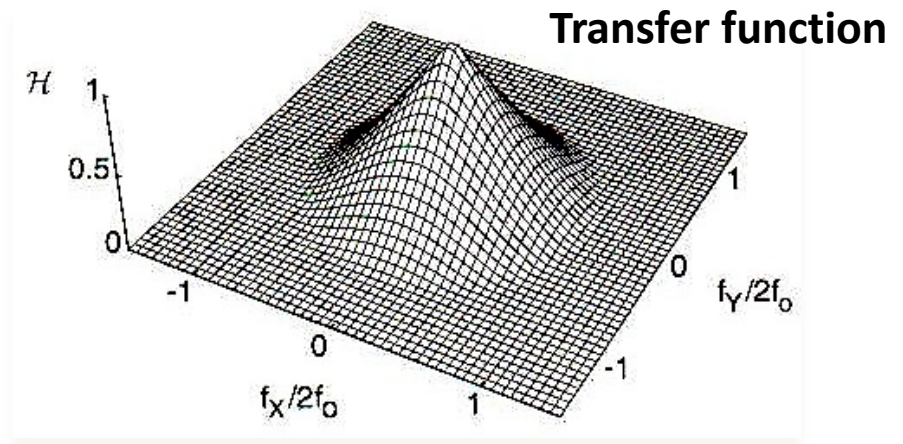
- » $(A^{-1}g)(x) = \frac{1}{2\pi} \int \frac{\tilde{g}(u)}{\tilde{K}(u)} e^{i2\pi xu} du$

- » *Not* bounded if $\tilde{K}(u)$ contains zeros.

Example of convolution operator: microscopes



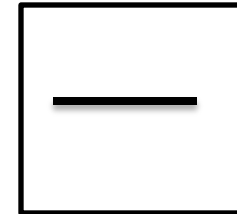
- » Range and null space?
- » Adjoint operator?
- » Inverse operator?



Example: motion blur

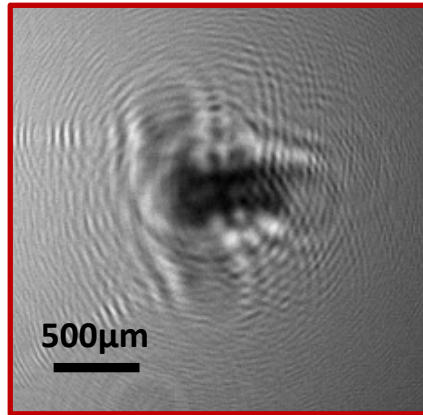


PSF



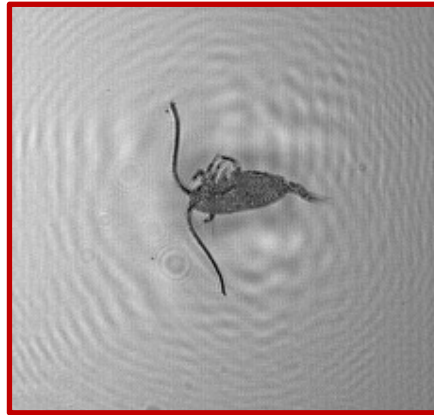
- » What are Object space \mathcal{X} and image space \mathcal{Y} ?
- » What is the operator \mathbf{A} ? linear?
- » Find an element in the null space?
 - » What's the implication of this?

Example of Shift-invariant system: holography



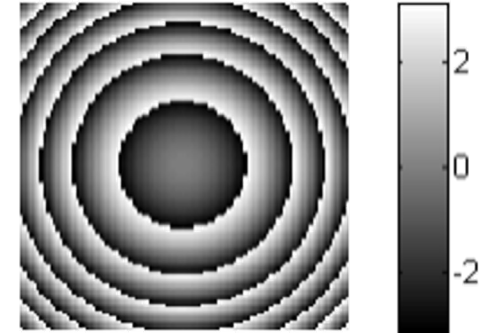
g_{out}

=



g_{in}

*



$$h(x, y) \approx \frac{e^{ikz}}{i\lambda z} e^{ik \frac{(x^2 + y^2)}{2z}}$$

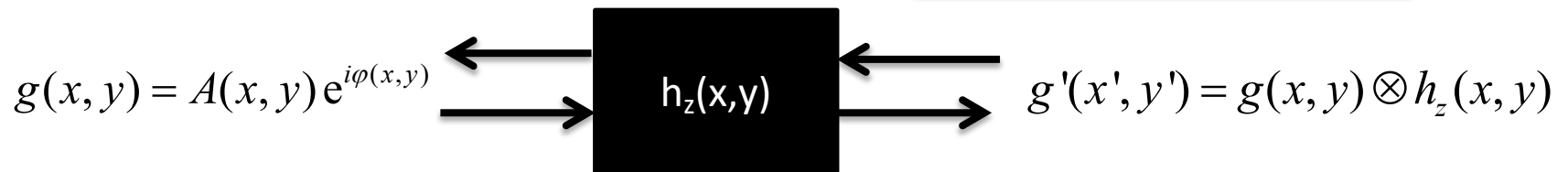
Transfer function $H(u, v) = e^{i2\pi z/\lambda} \exp \{-i\lambda z(u^2 + v^2)\}$

complex PSF

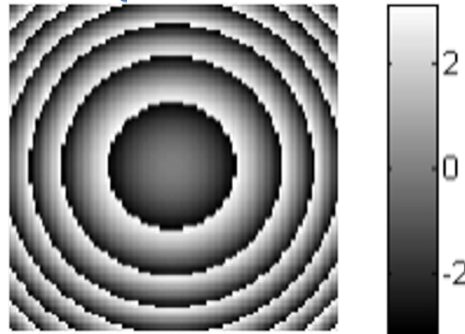
- » Range and null space?
- » Adjoint operator?
- » Inverse operator?

Application: back-propagation using adjoint operator = inverse operator!?

just make $z \rightarrow -z$? Why?



$H(x, y)$ has complex
point spread function
(PSF) and transfer
function



$$h_z(x, y) \approx \frac{e^{ikz}}{i\lambda z} e^{ik \frac{(x^2 + y^2)}{2z}}$$

Transfer function $H(u, v) = e^{i2\pi z/\lambda} \exp \{-i\lambda z(u^2 + v^2)\}$

