# System Structures

Operating Systems (CS-2006) Spring 2022, FAST NUCES

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# Roadmap

- 1. Operating-System Services
- 2. User Operating-System Interfaces
- 3. System Calls
- 4. Types of System Calls
- 5. System Programs
- 6. OS design and Implementation
- **7.** Operating System Structures
- 8. System Debugging
- 9. System Generation
- 10. System Boot

# **Operating System Services**

- One set of operating-system services provides functions that are helpful to the user:
  - User interface Almost all operating systems have a user interface (UI).
    - Varies between Command-Line (CLI), Graphics User Interface (GUI), Batch
  - Program execution The system must be able to load a program into memory and to run that program, end execution, either normally or abnormally (indicating error)
  - I/O operations The OS is responsible for transferring data to and from I/O devices, including keyboards, terminals, printers, and storage devices.

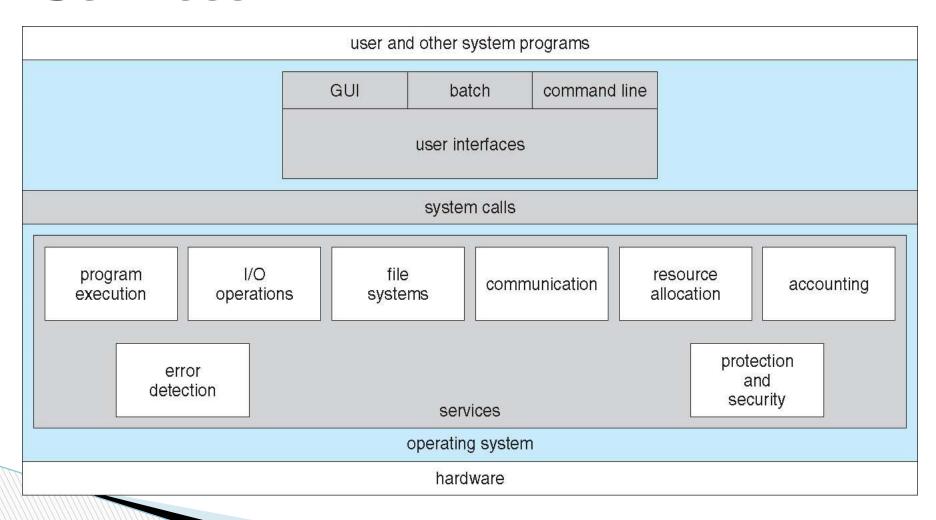
### **Operating System Services**

- File-system manipulation The file system is of particular interest. Programs need to read and write files and directories, create and delete them, search them, list file Information, permission management.
- Communications Processes may exchange information, on the same computer or between computers over a network
  - Communications may be via shared memory or through message passing (packets moved by the OS).
- Error detection OS needs to be constantly aware of possible errors
  - May occur in the CPU and memory hardware, in I/O devices, in user program
  - For each type of error, OS should take the appropriate action

### **Operating System Services**

- Resource allocation When multiple users or multiple jobs running concurrently, resources must be allocated to each of them
  - Many types of resources CPU cycles, main memory, file storage, I/O devices.
  - E.g., CPU cycles, main memory, storage space, and peripheral devices. Some resources are managed with generic systems and others with very carefully designed and specially tuned systems, customized for a particular resource and operating environment.
- Accounting To keep track of which users use how much and what kinds of computer resources
- Protection and security The owners of information stored in a multiuser or networked computer system may want to control use of that information, concurrent processes should not interfere with each other
  - Protection involves ensuring that all access to system resources is controlled
  - **Security** of the system from outsiders requires user authentication, extends to defending external I/O devices from invalid access attempts

# A View of Operating System Services



### **User Operating System Interface - CLI**

# CLI or command interpreter allows direct command entry

- Sometimes multiple flavors implemented –
   shells
- Primarily fetches a command from user and executes it
- Sometimes commands built-in, sometimes just names of programs

### **User Operating System Interface - GUI**

- User-friendly desktop metaphor interface
  - Usually mouse, keyboard, and monitor
  - Icons represent files, programs, actions, etc
  - Various mouse buttons over objects in the interface cause various actions (provide information, options, execute function, open directory (known as a folder)
- Many systems now include both CLI and GUI interfaces
  - Unix and Linux have CLI with optional GUI interfaces (CDE, KDE, GNOME)
  - Common Desktop Environment (CDE) Unix based
  - K Desktop Environment (KDE) Linux based
  - GNOME Unix variant

### **Touchscreen Interfaces**

- Touchscreen devices require new interfaces
  - Mouse not possible or not desired
  - Actions and selection based on gestures
  - Virtual keyboard for text entry
- Voice commands.



# The Mac OS X GUI

# **System Calls**

- A system call is a mechanism that provides the interface between a process and the operating system.
- It is a programmatic method in which a computer program requests a service from the kernel of the OS.
- System calls are the only entry points for the kernel system.
- Programming interface to the services provided by the OS
- Typically written in a high-level language (C or C++)
- Mostly accessed by programs via a high-level Application Programming Interface (API) rather than direct system call use
- Three most common APIs are Win32 API for Windows, POSIX API for POSIX-based systems (including virtually all versions of UNIX, Linux, and Mac OS X), and Java API for the Java wirtual machine (JVM)

#### **API AND SYSTEM CALLS**

Application programming interface

Set of functions exposed by any library - printf

System calls are also functions exposed by C library

So, system calls also is an API

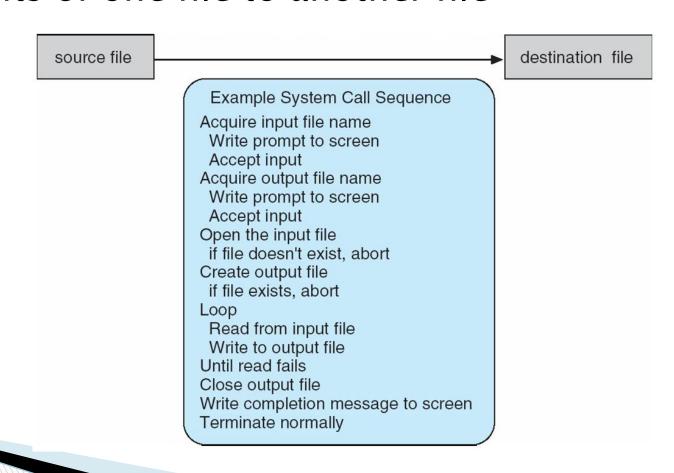
API - system call - write ()

API - uses system calls - printf()

API - doesn't uses system calls - strlen()

# **Example of System Calls**

System call sequence to copy the contents of one file to another file



### **Example of Standard API**

#### EXAMPLE OF STANDARD API

As an example of a standard API, consider the read() function that is available in UNIX and Linux systems. The API for this function is obtained from the man page by invoking the command

#### man read

on the command line. A description of this API appears below:

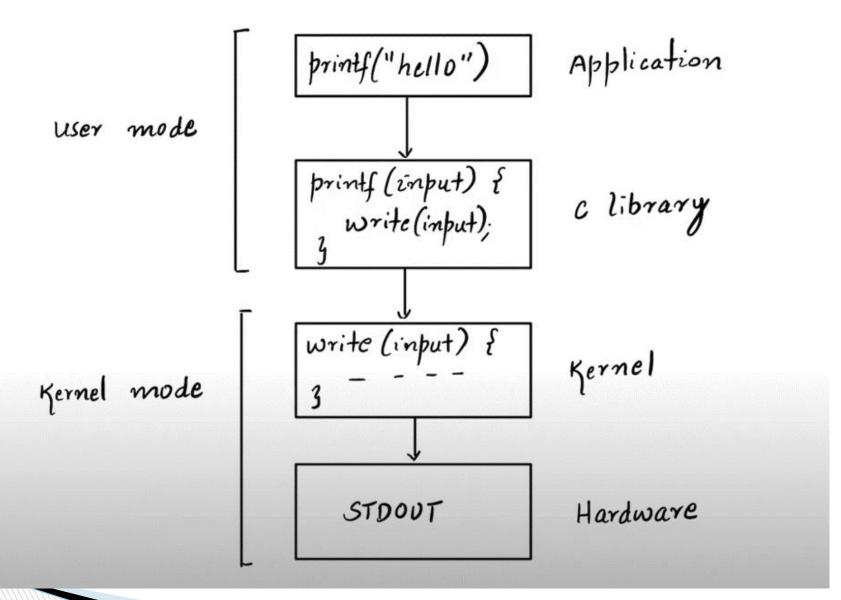
```
#include <unistd.h>
ssize_t read(int fd, void *buf, size_t count)

return function parameters
value name
```

A program that uses the read() function must include the unistd.h header file, as this file defines the ssize\_t and size\_t data types (among other things). The parameters passed to read() are as follows:

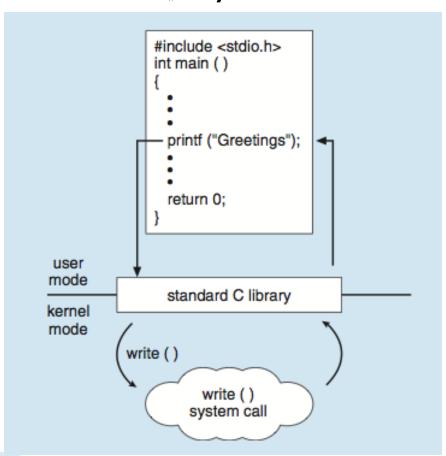
- int fd—the file descriptor to be read
- void \*buf a buffer where the data will be read into
- size\_t count—the maximum number of bytes to be read into the buffer

On a successful read, the number of bytes read is returned. A return value of 0 indicates end of file. If an error occurs, read() returns -1.

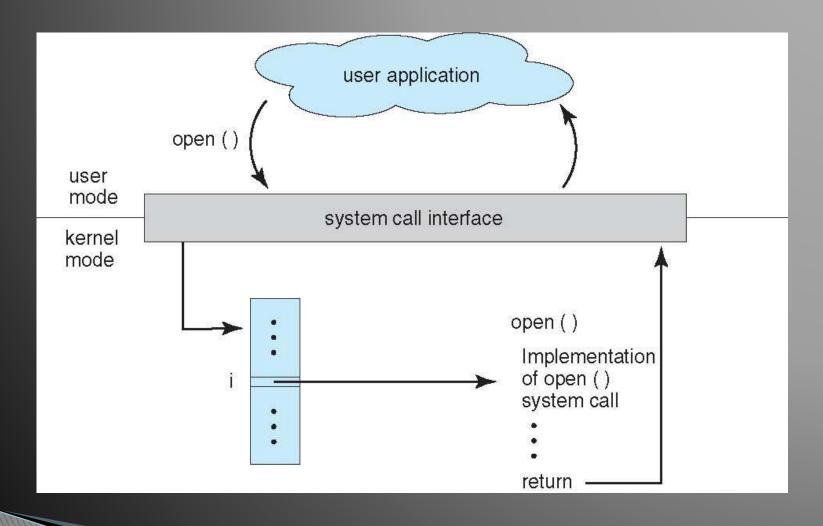


# Standard C Library Example

C program invoking printf() library call, which calls write() system call



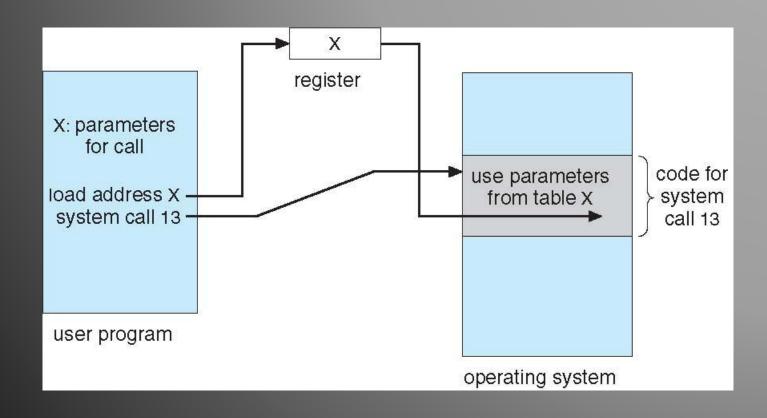
# API – System Call – OS Relationship



# System Call Parameter Passing

- Three general methods used to pass parameters to the OS
  - Simplest: pass the parameters in registers
  - Parameters stored in a block, or table, in memory, and address of block passed as a parameter in a register
  - Parameters placed, or pushed, onto the stack by the program and popped off the stack by the operating system

# System Call Parameter Passing via Table



System calls can be roughly grouped into five major categories:

- Process Control
- 2. File management
- 3. Device Management
- 4. Information Maintenance
- 5. Communication
- 6. protection

### 1.Process Control

- load
- execute
- Create process (for example, fork on Unix-like systems or NtCreateProcess in the Windows NT Native API)
- terminate process
- get/set process attributes
- wait for time, wait event, signal event
- allocate free memory

### 2.File management

- create file, delete file
- open, close
- read, write, reposition
- get/set file attributes

#### 3.Device Management

- request device, release device
- read, write, reposition
- get/set device attributes
- logically attach or detach devices

#### 4.Information Maintenance

- get/set time or date
- get/set system data
- get/set process, file, or device attributes

#### 5.Communication

- create, delete communication connection
- send, receive messages
- transfer status information
- attach or detach remote device

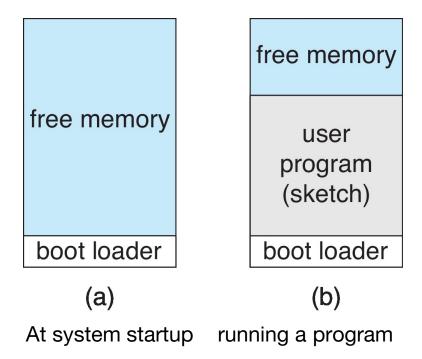
#### EXAMPLES OF WINDOWS AND UNIX SYSTEM CALLS

	Windows	Unix
Process	CreateProcess()	fork()
Control	ExitProcess()	exit()
	WaitForSingleObject()	wait()
File	CreateFile()	open()
Manipulation	ReadFile()	read()
	WriteFile()	write()
	CloseHandle()	close()
Device	SetConsoleMode()	ioctl()
Manipulation	ReadConsole()	read()
	WriteConsole()	write()
Information	GetCurrentProcessID()	getpid()
Maintenance	SetTimer()	alarm()
	Sleep()	sleep()
Communication	CreatePipe()	pipe()
	CreateFileMapping()	shmget()
	MapViewOfFile()	mmap()
Protection	SetFileSecurity()	chmod()
	<pre>InitlializeSecurityDescriptor()</pre>	umask()
	SetSecurityDescriptorGroup()	chown()

# **Example: Arduino**

The Arduino is a simple hardware platform consisting of a microcontroller along with input sensors that respond to a variety of events, such as changes to light, temperature, and barometric pressure, etc.

- Single-tasking
- No operating system
- Programs (sketch) loaded via USB into flash memory
- Single memory space
- Boot loader loads program
- Program exit -> shell reloaded



### **Example: FreeBSD** (Berkeley Software Distribution)

- Unix variant
- Multitasking
- User login -> invoke user's choice of shell
- Shell executes fork() system call to create process
  - Executes exec() to load program into process
  - Shell waits for process to terminate or continues with user commands
- Process exits with:
  - code = 0 no error
  - code > 0 error code

process D free memory process C interpreter process B kernel

# **System Programs**

- System programs provide a convenient environment for program development and execution. They can be divided into:
  - 1. File manipulation
  - 2. Status information
  - 3. File modification
  - 4. Programming language support
  - 5. Program loading and execution
  - 6. Communications
  - 7. Background services
  - 8. Application programs

# **System Programs**

File management - Create, delete, copy, rename, print, dump, list, and generally manipulate files and directories

#### Status information

- Some ask the system for info date, time, amount of available memory, disk space, number of users
- Others provide detailed performance, logging, and debugging information

# System Programs (Cont.)

- File modification
  - Text editors to create and modify files
    Special commands to search contents of files or
    perform transformations of the text
- Programming-language support Compilers, assemblers, debuggers and interpreters sometimes provided
- Program loading and executiondebugging systems for higher-level and machine language
- Communications Provide the mechanism for creating virtual connections among processes, users, and computer systems

# System Programs (Cont.)

### Background Services

- Launch at boot time
- Provide facilities like disk checking, process scheduling, error logging, printing
- Run in user context not kernel context
- Known as services, subsystems, daemons

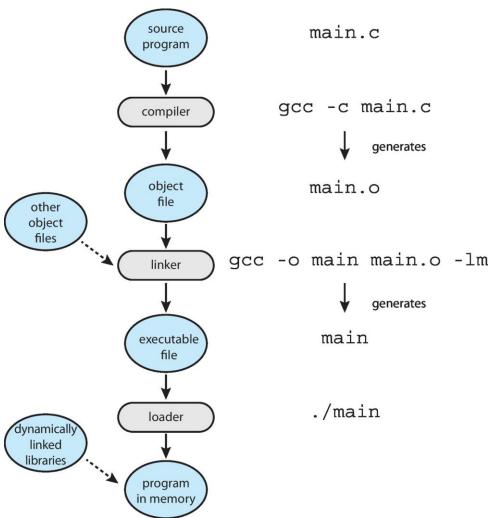
### Application programs

Run by users

### **Linkers and Loaders**

- Source code compiled into object files designed to be loaded into any physical memory location relocatable object file
- Linker combines these into single binary executable file
  - Also brings in libraries
- Program resides on secondary storage as binary executable
- Must be brought into memory by loader to be executed
  - Relocation assigns final addresses to program parts and adjusts code and data in program to match those addresses
- Modern general-purpose systems don't link libraries into executables
  - Rather, dynamically linked libraries (in Windows, DLLs) are loaded as needed, shared by all that use the same version of that same library (loaded once)
- Object, executable files have standard formats, so operating system knows how to load and start them

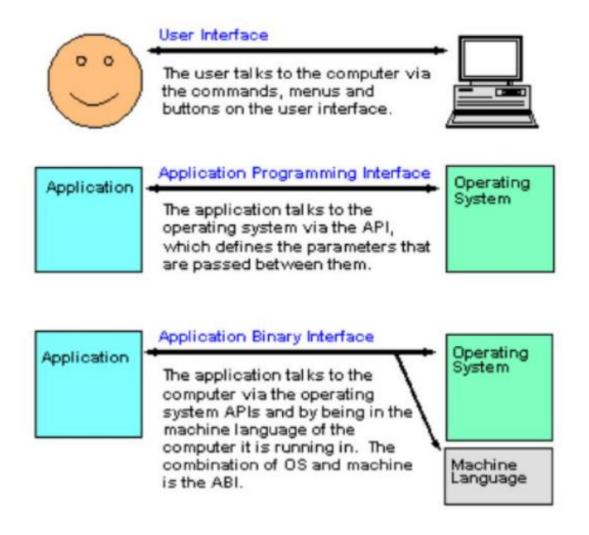
The Role of the Linker and Loader



### Why Applications are Operating System Specific

- Apps compiled on one system usually not executable on other operating systems
- Each operating system provides its own unique system calls
  - Own file formats, etc.
- Apps can be multi-operating system
  - Written in interpreted language like Python, Ruby, and interpreter available on multiple operating systems
  - App written in language that includes a VM containing the running app (like Java)
  - Use standard language (like C), compile separately on each operating system to run on each
- Application Binary Interface (ABI) is architecture equivalent of API, defines how different components of binary code can interface for a given operating system on a given architecture, CPU, etc.

### GUI vs API vs ABI



### **Operating System Design and Implementation**

- Start the design by defining goals and specifications
- Affected by choice of hardware, type of system
- User goals and System goals
  - User goals operating system should be convenient to use, easy to learn, reliable, safe, and fast
  - System goals operating system should be easy to design, implement, and maintain, as well as flexible, reliable, error-free, and efficient

### **Implementation**

- Much variation
  - Early OSes in assembly language
  - Then system programming languages like Algol, PL/1
  - Now C, C++
- Usually, a mix of languages
  - Lowest levels in assembly
  - Main body in C
  - Systems programs in C, C++, scripting languages like PERL, Python, shell scripts
- More high-level language easier to port to other hardware
  - But slower
- Emulation can allow an OS to run on non-native hardware

# Operating System Design and Implementation (Cont.)

Important principle to separate

**Policy:** *What* will be done? **Mechanism:** *How* to do it?

- Mechanisms determine how to do something; policies decide what will be done
- The separation of policy from mechanism is a very important principle, it allows maximum flexibility if policy decisions are to be changed later (example timer)

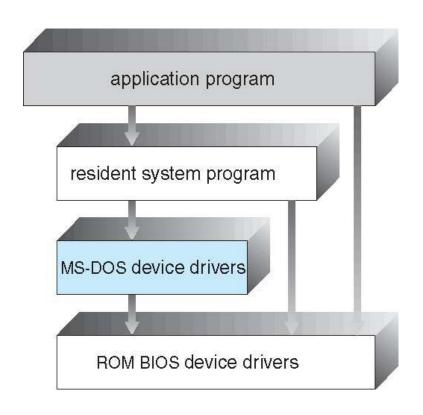
## **Operating System Structure**

#### There are six different structures:

- Simple Structure
- Monolithic Structures
- 3. Layered Systems
- 4. Micro kernels
- 5. Modules
- 6. Hybrid Machines

## Simple Structure -- MS-DOS

- MS-DOS written to provide the most functionality in the least space
  - Not divided into modules
  - Although MS-DOS has some structure, its interfaces and levels of functionality are not well separated



#### **Monolithic Structure -- UNIX**

UNIX – limited by hardware functionality, the original UNIX operating system had limited structuring. The UNIX OS consists of two separable parts

- Systems programs
- The kernel
  - Consists of everything below the system-call interface and above the physical hardware
  - Provides the file system, CPU scheduling, memory management, and other operating-system functions; many functions for one level

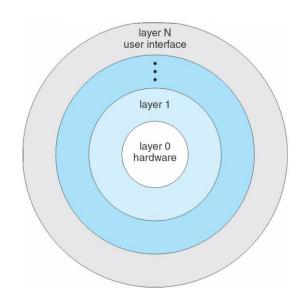
# Traditional UNIX System Structure

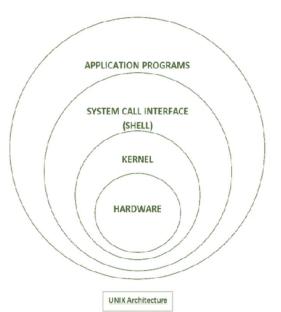
Beyond simple but not fully layered

	(the users)		
Kernel	shells and commands compilers and interpreters system libraries		
	system-call interface to the kernel		
	signals terminal handling character I/O system terminal drivers	file system swapping block I/O system disk and tape drivers	CPU scheduling page replacement demand paging virtual memory
	kernel interface to the hardware		
	terminal controllers terminals	device controllers disks and tapes	memory controllers physical memory

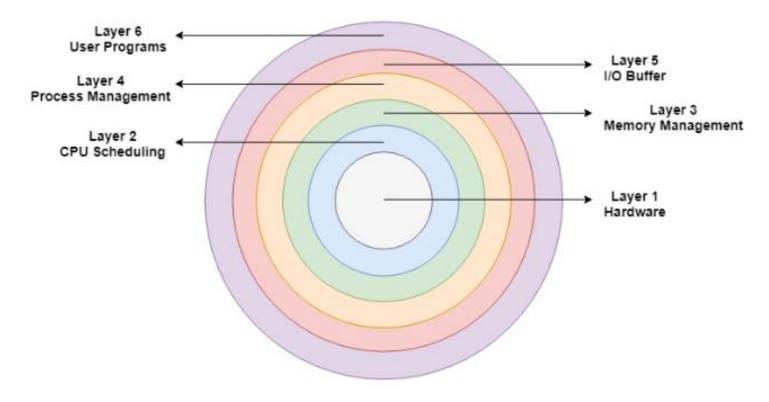
## Layered Approach

- The operating system is divided into several layers (levels), each built on top of lower layers. The bottom layer (layer 0), is the hardware; the highest (layer N) is the user interface.
- With modularity, layers are selected such that each uses functions (operations) and services of only lower-level layers





## Layered Approach

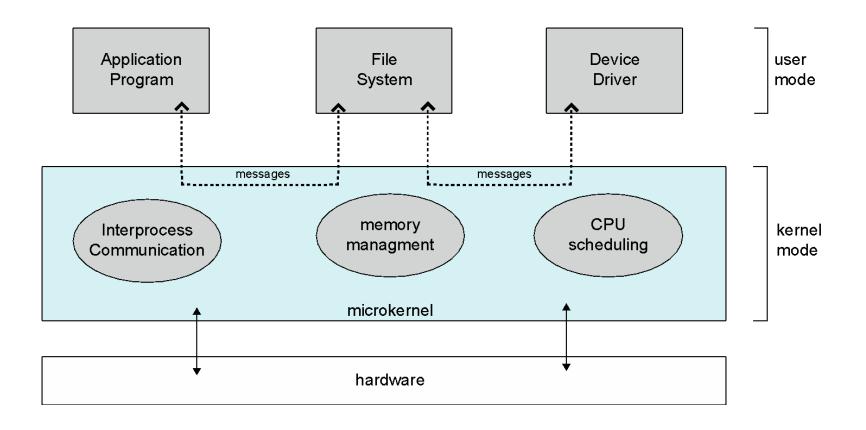


LAYERED OPERATING SYSTEM

## Microkernel System Structure

- Moves as much from the kernel into user space
- Mach example of microkernel
- Mac OS X kernel (Darwin) partly based on Mach Communication takes place between user modules using message passing
- Benefits:
  - Easier to extend a microkernel
  - Easier to port the operating system to new architectures
  - More reliable (less code is running in kernel mode)
    - More secure
- Detriments:
  - Performance overhead of user space to kernel space communication

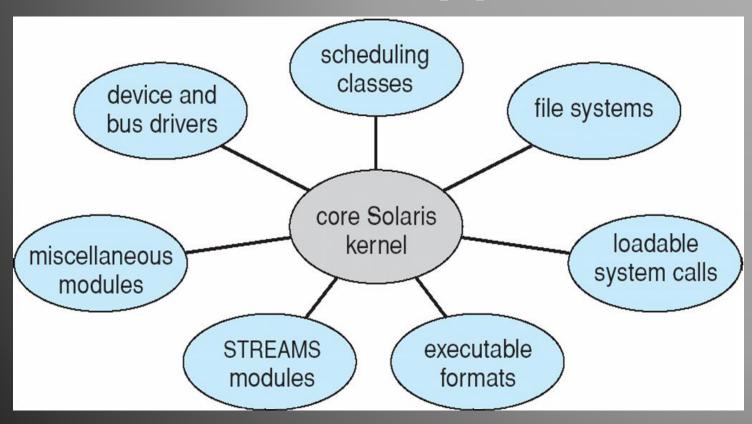
## Microkernel System Structure



## Modules

- Many modern operating systems implement loadable kernel modules
  - Uses object-oriented approach
  - Each core component is separate
  - Each talks to the others over known interfaces
  - Each is loadable as needed within the kernel
- Overall, like layers but with more flexible
  - Linux, Solaris, etc

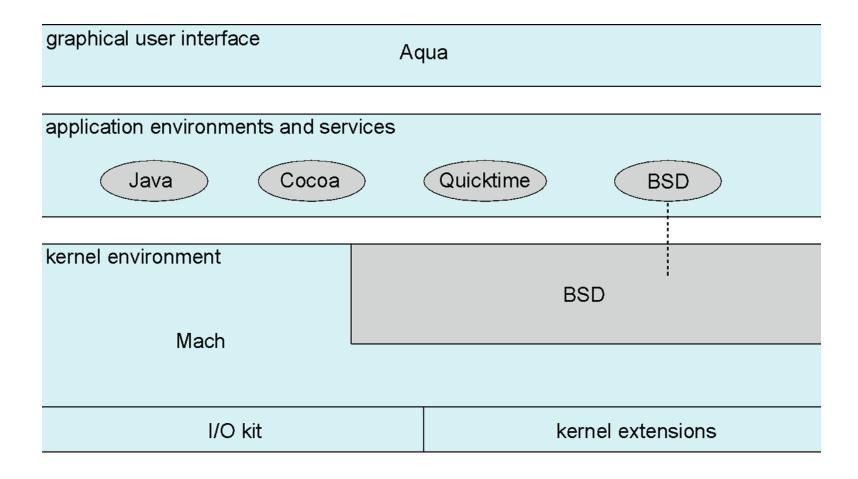
## Solaris Modular Approach



## **Hybrid Systems**

- Most modern operating systems are not one pure model
  - Hybrid combines multiple approaches to address performance, security, usability needs
  - Linux and Solaris kernels in kernel address space, so monolithic, plus modular for dynamic loading of functionality
  - Windows mostly monolithic, plus microkernel for different subsystem *personalities*
- Apple Mac OS X hybrid, layered, Aqua UI plus Cocoa programming environment
  - Below is kernel consisting of Mach microkernel and BSD Unix parts, plus I/O kit and dynamically loadable modules (called kernel extensions)

### Mac OS X Structure

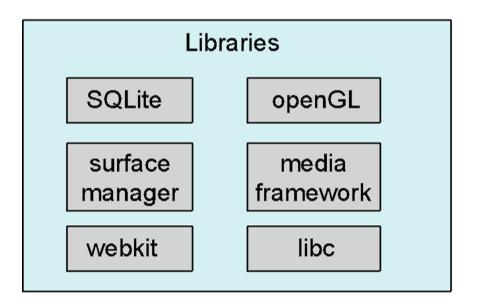


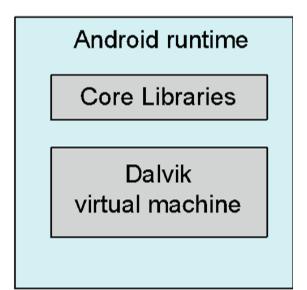
#### **Android**

- Developed by Open Handset Alliance (mostly Google)
  - Open Source
- Similar stack to IOS
- Based on Linux kernel but modified
  - Provides process, memory, device-driver management
  - Adds power management
- Runtime environment includes core set of libraries and Dalvik virtual machine
  - Apps developed in Java plus Android API
    - Java class files compiled to Java bytecode then translated to executable than runs in Dalvik VM
- Libraries include frameworks for web browser (webkit), database (SQLite), multimedia, smaller libc

#### **Android Architecture**

#### **Application Framework**





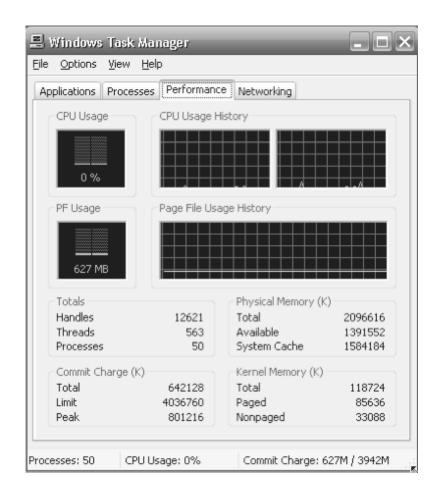
## **Operating-System Debugging**

- Debugging is finding and fixing errors, or bugs
- OS generate log files containing error information
- Failure of an application can generate core dump file capturing memory of the process
- Operating system failure can generate crash dump file containing kernel memory
- Beyond crashes, performance tuning can optimize system performance
  - Sometimes using trace listings of activities, recorded for analysis
  - Profiling is periodic sampling of instruction pointer to look for statistical trends

Kernighan's Law: "Debugging is twice as hard as writing the code in the first place. Therefore, if you write the code as cleverly as possible, you are, by definition, not smart enough to debug it."

## **Performance Tuning**

- Improve performance by removing bottlenecks
- OS must provide means of computing and displaying measures of system behavior
- For example, "top" program or Windows Task Manager



#### **DTrace**

- DTrace tool in Solaris, FreeBSD, Mac OS X allows live instrumentation on production systems.
- DTrace code to record amount of time each process with UserID 101 is in running mode (on CPU) in nanoseconds

```
# ./all.d 'pgrep xclock' XEventsQueued
dtrace: script './all.d' matched 52377 probes
CPU FUNCTION
  0 -> XEventsQueued
      -> XEventsQueued
                                         IJ
        -> X11TransBytesReadable
        <- X11TransBytesReadable
        -> X11TransSocketBytesReadable U
        <- X11TransSocketBytesreadable U</p>
        -> ioctl
          -> ioctl
            -> getf
              -> set active fd
              <- set active fd
  0
            <- getf
            -> get udatamodel
                                         K
            <- get udatamodel
            -> releasef
              -> clear active fd
              <- clear active fd
              -> cv broadcast
              <- cv broadcast
            <- releasef
          <- ioctl
        <- ioctl
      <- XEventsQueued
                                         IJ
   <- XEventsQueued
```

## **Operating System Generation**

Operating systems are designed to run on any of a class of machines; the system must be configured for each specific computer site

## **SYSGEN**

- □ Information that is needed to configure an OS include:
- What CPU(s) are installed on the system, and what optional characteristics does each have?
- How much RAM is installed?
- What devices are present? The OS needs to determine which device drivers to include, as well as some device-specific characteristics and parameters.
- What OS options are desired, and what values to set for OS parameters.

## **System Boot**

- When power initialized on system, execution starts at a fixed memory location
  - Firmware ROM used to hold initial boot code
- Operating system must be made available to hardware so hardware can start it
  - Small piece of code bootstrap loader, stored in ROM or EEPROM locates the kernel, loads it into memory, and starts it
  - Sometimes two-step process where boot block at fixed location loaded by ROM code, which loads bootstrap loader from disk
- Common bootstrap loader, GRUB, allows selection of kernel from multiple disks, versions, kernel options
- Kernel loads and system is then running

# Thank You!

**Chapter 2 Completed**