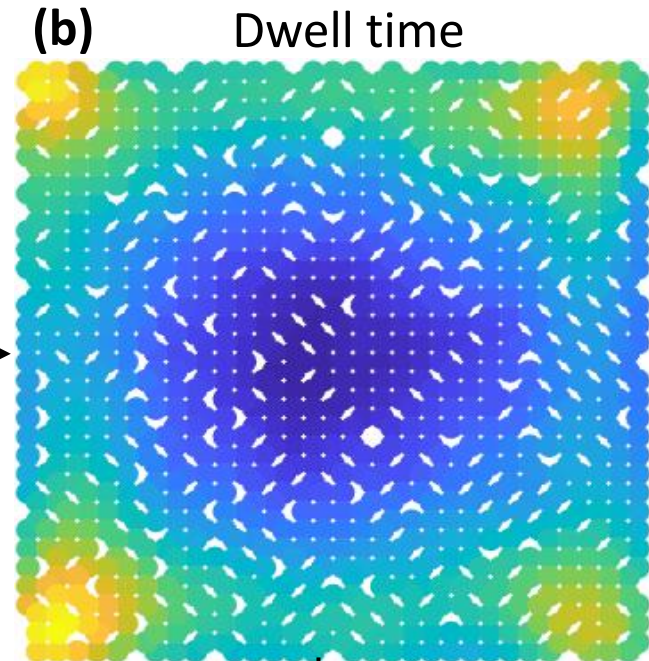
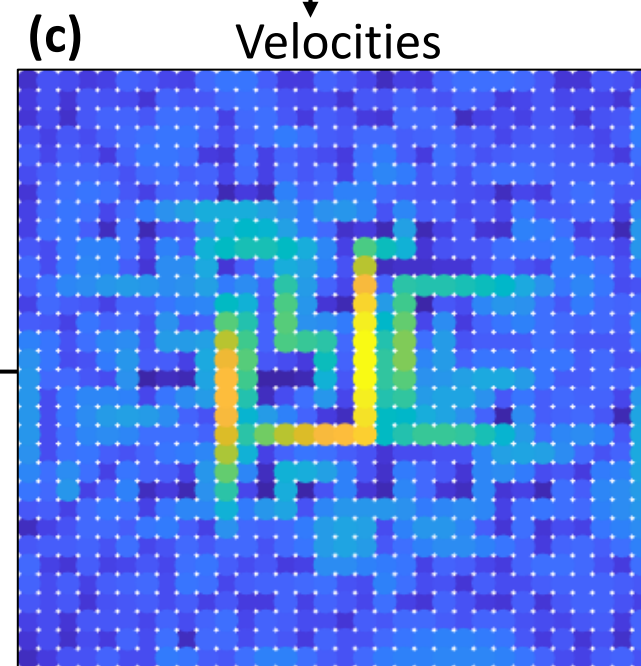


* Velocity control points
○ Dwell points

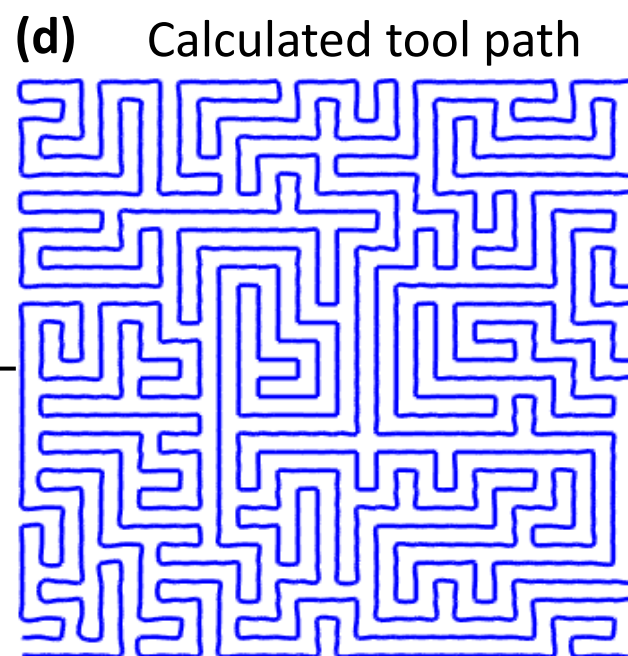
1) Dwell time
optimization



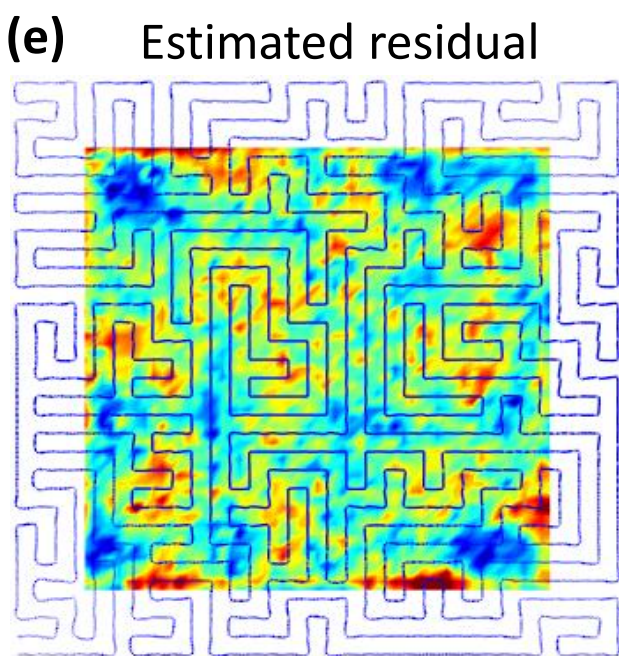
2) Velocity scheduling

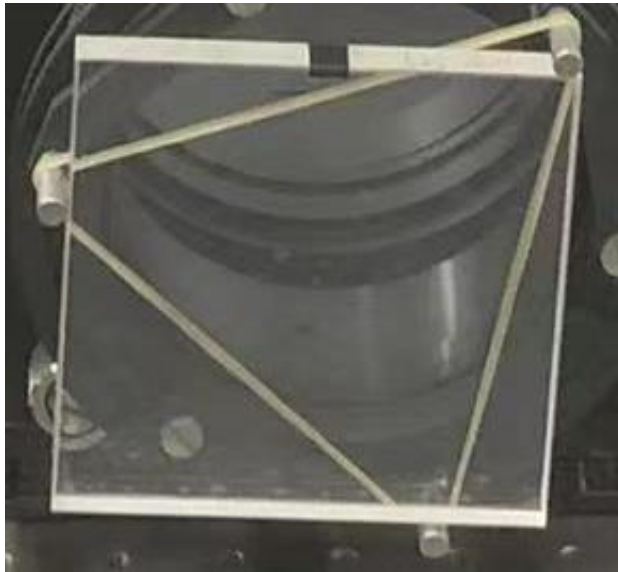


3) Sampling

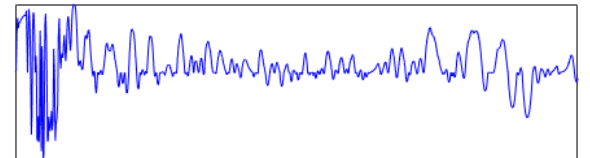


4) Estimation





x velocities



y velocities

