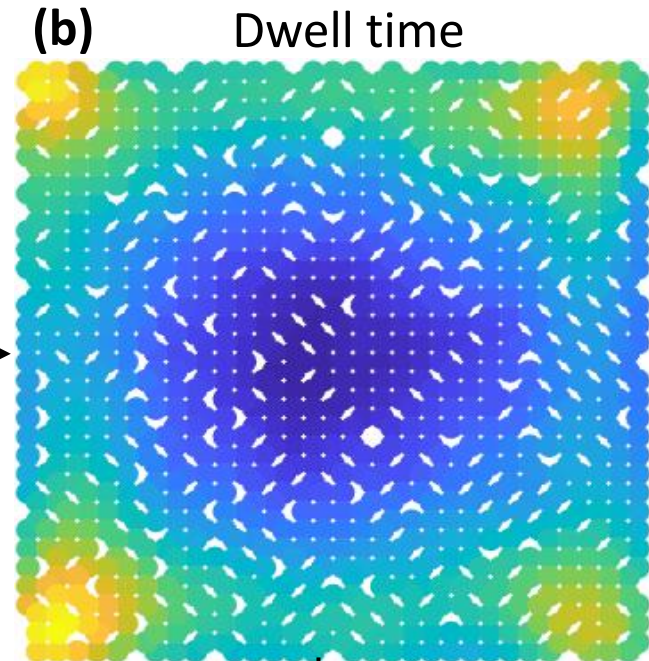
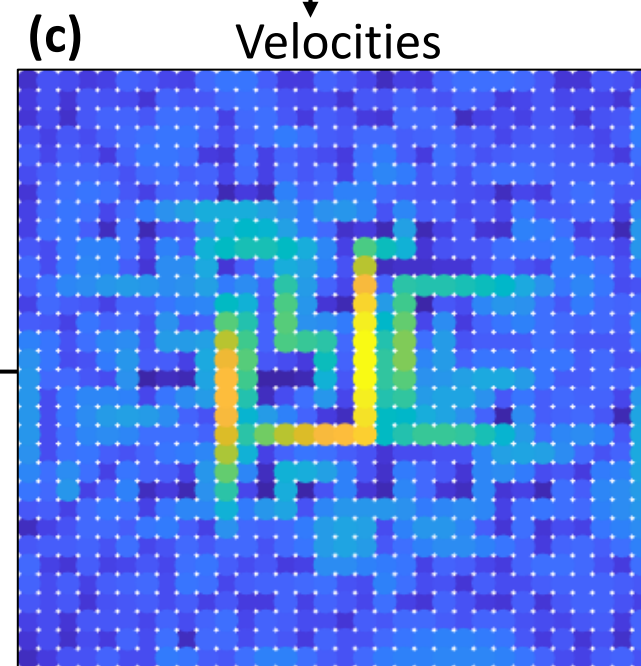


\* Velocity control points  
○ Dwell points

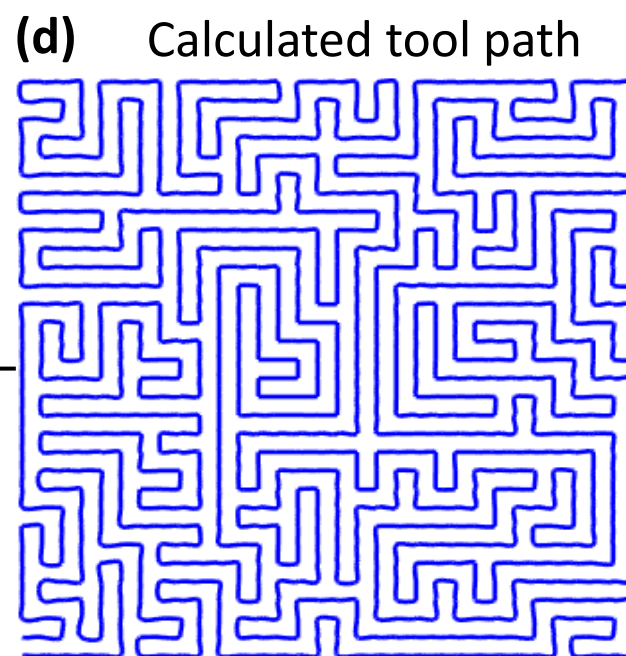
1) Dwell time optimization



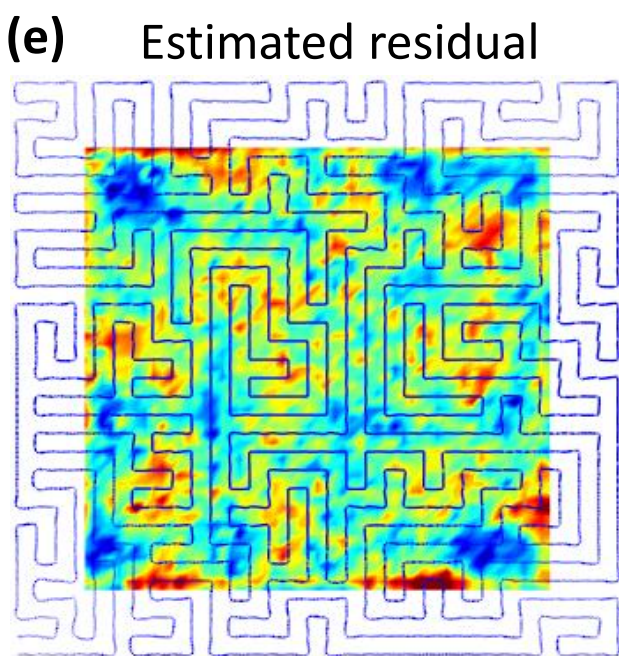
2) Velocity scheduling



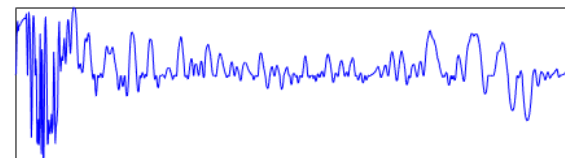
3) Sampling



4) Estimation



**x velocities**



**y velocities**

