http://www.twoears.eu/

Integral interactive model of auditory perception and experience

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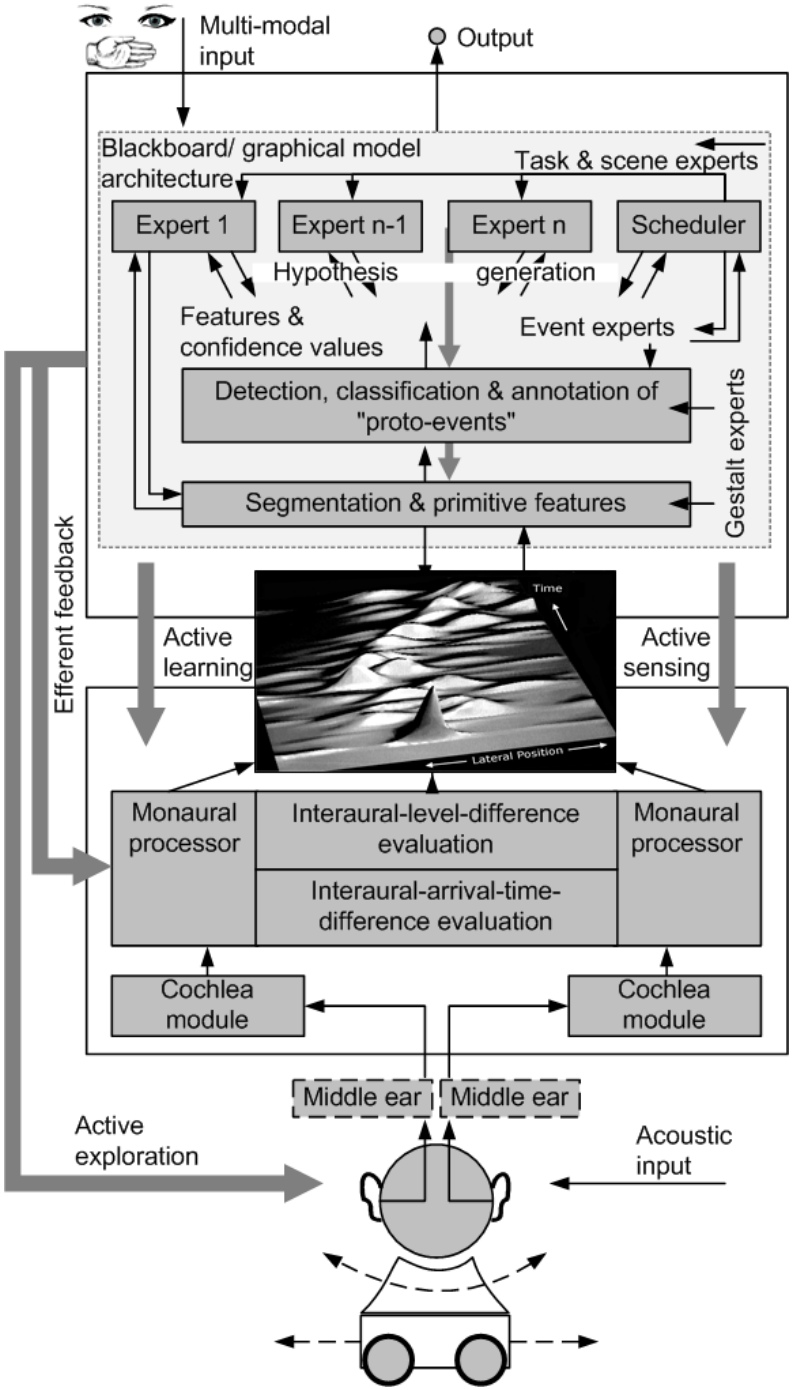
Consortium



Level V

Level IV

Level III

Level II

Level I

Level I – Database of scenarios

Settings

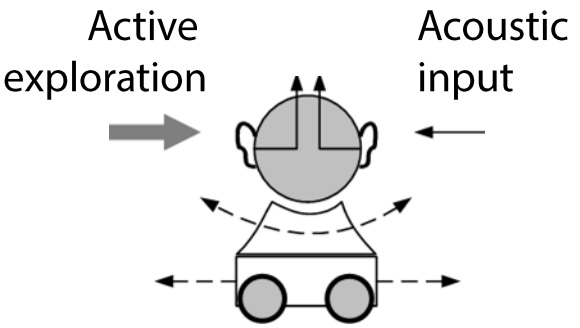
- Defined content formats, shared platform
- Central database of labeled audio-visual scenes & tools for interactive generation
- Head-tracked ear signals incl. translatory movements

Scenarios

- Natural/synthetic, partly captured with mobile robot platform
- Ear-signals, head-related impulse responses (HRIRs)
- Multichannel recordings, multichannel room-impulse responses
- Still images and video sequences

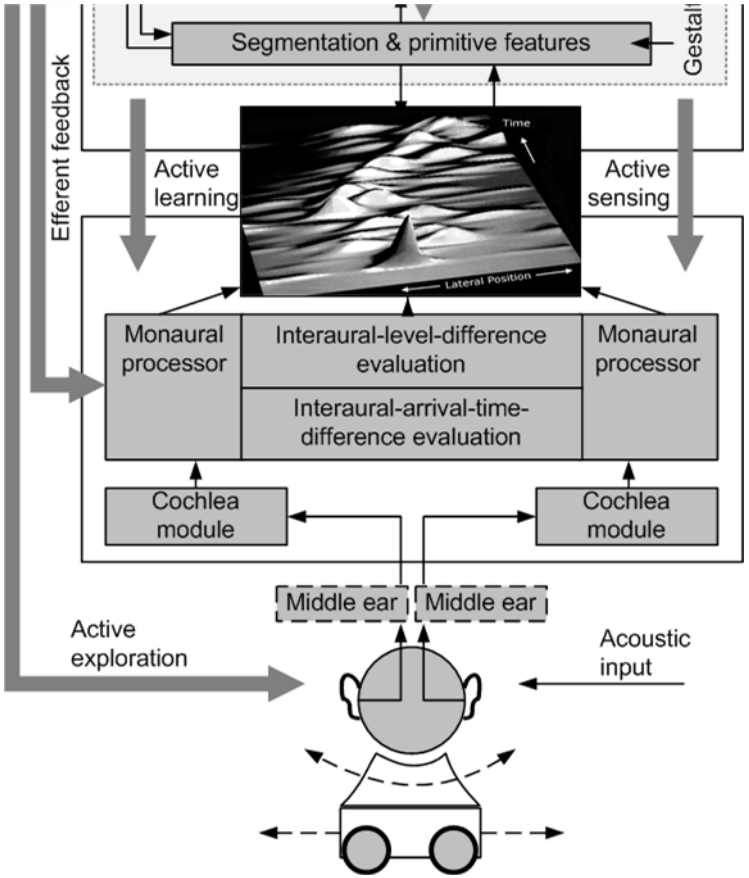
Dedicated Signal Processing Techniques for dynamic scenes capture

- Advanced techniques for range extrapolation of HRIRs
- Combination of microphone array data with HRIRs
- Capturing of time-variant impulse responses from dynamic sources



Level I

Levels II, III



Level III

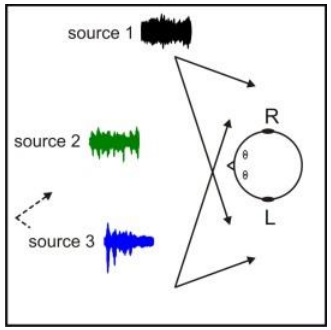
Level II

Level I

Levels II, III

Input level II

- Binaural ear signals consisting of multiple active sources
- Feedback from higher stages to adapt bottom-up processing

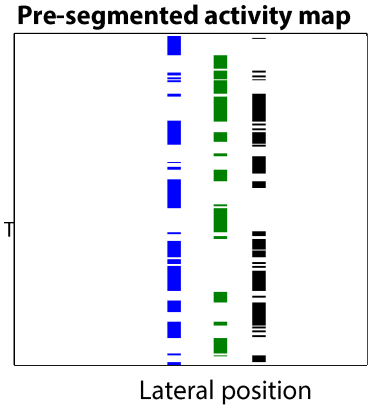


Extract primary cues

- Monaural cues: onsets, offsets, amplitude modulation, periodicity, across-channel synchrony
- Binaural cues: ITDs, ILDs, IC

Perform pre-segmentation

- Determine active sound source positions, detect speech activity (speech segregation), …

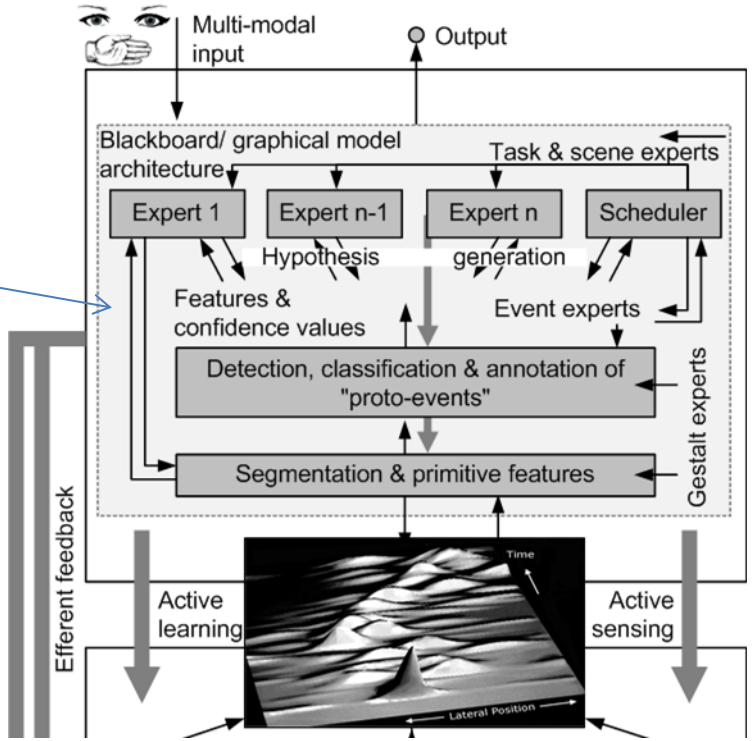


Output

- Multidimensional auditory representation (“activity maps”)
- Organized in topological manner, e.g. time, frequency, activity
- Features for auditory-scene analysis (higher levels)
  - Temporally collocated across different spectral bands
  - May later be associated with particular objects

Levels III-V

- Blackboard & graphical model architecture
- Blackboard accessed by different modules
- Different levels of abstraction

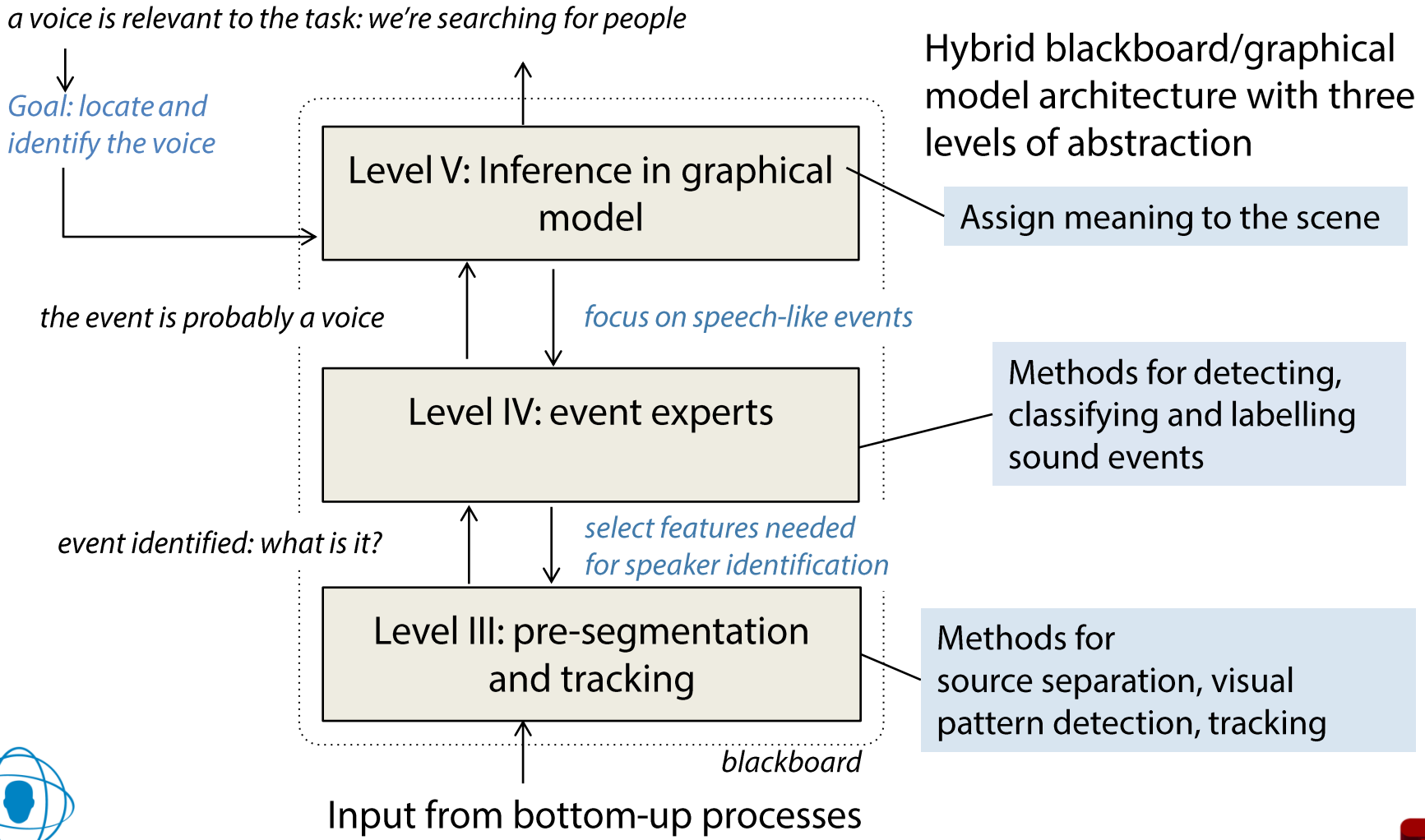


Level V

Level IV

Level III

Level III-V: Example for feature extraction, object formation & meaning assignment



Hybrid blackboard/graphical model architecture with three levels of abstraction

Level V

Human cognition

- World-knowledge: Hypothesis generation
- Adaptation & verification processes

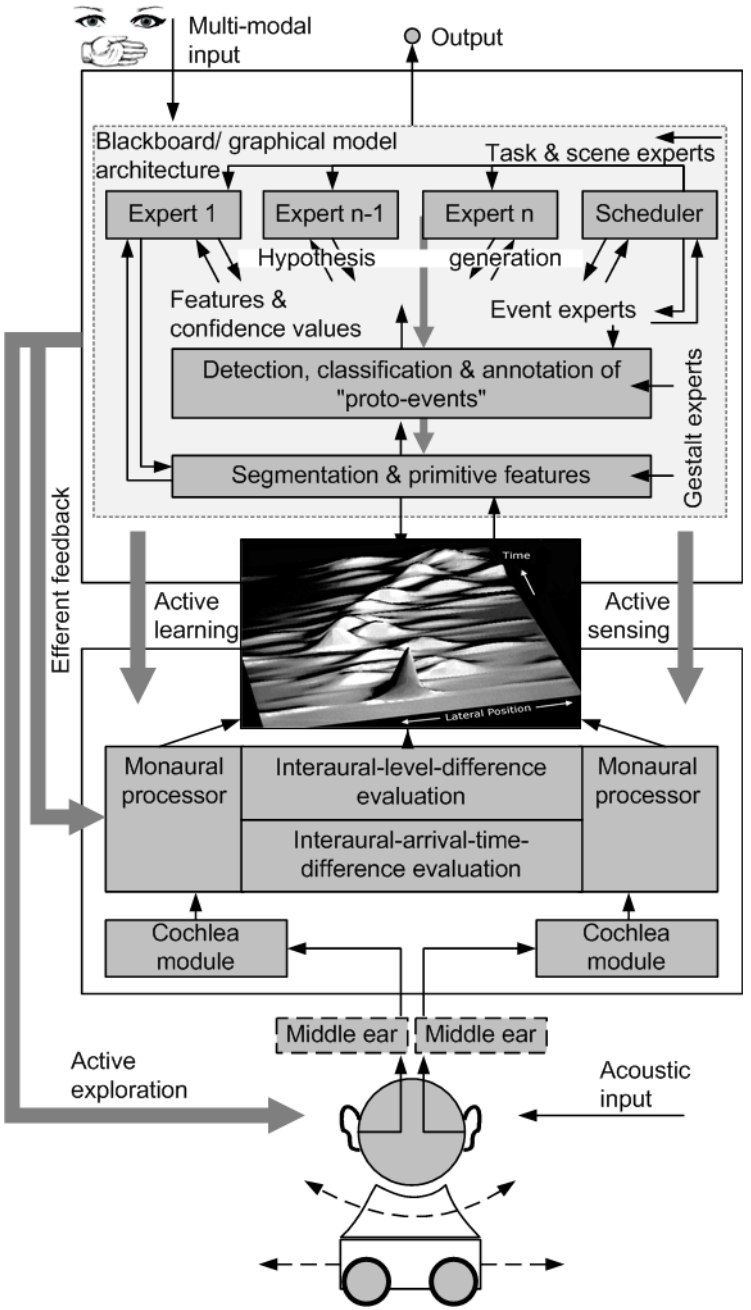
Information accessed by multi-expert system (=software modules)

- Analyze blackboard info (*expertise*)
- Identify whether blackboard information corresponds to available knowledge

Expertise

- Psychoacoustics, object-identification,
- Cross-modal integration, proprioception
- Speech communication,
- Music, sound quality, …

Feedback…



Hardware & software system

Testbed of gradual complexity & versatility

- Head-&-torso-simulator (HATS)
- HATS endowed with pan motion and cameras
- Audio- & visio-auditory head on a PR2 robot

Software architecture

- Functional & cognitive layers
- Modular architecture specified with GenoM on the top of the Robot Operating System (ROS) middleware

"Smart" audio-visual sensors

- Hardcoding of auditory cues with dedicated SoC
- High-quality cues: Must be embedded, under strong temporal constraints
- Modular tests under various experimental conditions

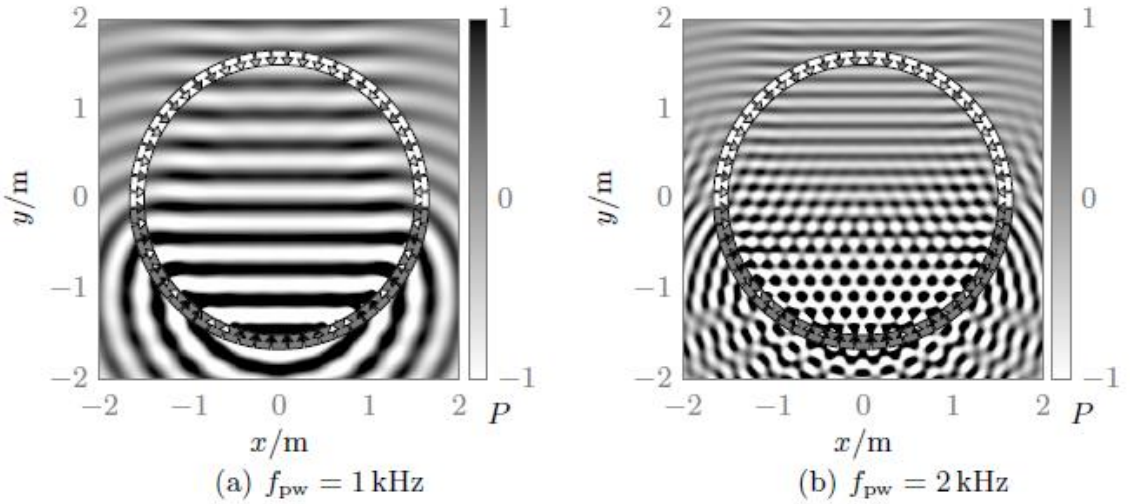
Applications & proof of concept

Dynamic auditory scene analysis – search & rescue

- Audio SLAM (simultaneous localization and mapping)
- Speaker identification
- Keyword-type speech recognition
- Relevance identification
- Coarse audio-type identification

Quality of Experience

- Applied to multi-loudspeaker audio reproduction
- Active exploration of listening area
- Internal reference
- Meaning assignment



(a) $f_{\mathrm{pw}} = 1\,\mathrm{kHz}$ (b) $f_{\mathrm{pw}} = 2\,\mathrm{kHz}$

(Wierstorf et al., this session 10-10:20h)

Summary: Reading the World with TWO!EARS

- Functional implementation of active binaural listening & understanding
- Integration of bottom-up & top-down processing
- Computational structure
  - Binaural analysis of acoustic scenes
  - Proprioceptive & visual sensing
  - Active exploration
  - Feedback-based adaptation
  - Cognitive abilities (e.g. attention, source recognition, reasoning, quality)
- Modular test-bed
  - Open software framework
  - Robot for implementation of structure
- Proof-of-concept applications
  - Search-&-Rescue
  - Quality-of-Experience Assessment

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Thank you for your attention!
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