EM for SR-MRA

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We assume to collect N independent observations from the model

$$y = PR_{\ell}x + \varepsilon,\tag{1}$$

where $x \in \mathbb{R}^L$, R_ℓ is the circular shift (drawn from random distribution) and $\varepsilon \sim \mathcal{N}(0, \sigma^2 I)$. The operator P denotes down-sampling by a factor of K. It can be thought of as a diagonal matrix, whose diagonal composed of 1's every K entry, and zero otherwise. We also assume that $x \sim \mathcal{N}(0, \Sigma)$ (this is the prior).

In the **E-step**, given the current signal estimate x_{est} , we compute the probability that each measurement came from each shift. In our case, we compute the weights

$$w_{i,\ell} = C_i e^{-\frac{1}{2\sigma^2} \|y_i - PR_{\ell} x_{est}\|_2^2}, \quad i = 1, \dots, N, \quad \ell = 0, \dots, L - 1,$$
 (2)

where C_i denotes a normalization constant (per measurement).

This step can be computed efficiently using fft. It is useful to think of x_{est} as being composed of K sub-signals and then the norm $||PR_{\ell}x_{est}||_2^2$ can be computed separately for each of them. To compute the cross-terms, we again split the signal into sub-signals. Each one of them can be computed using fft (since it is a correlation). After computing the weights to each one of the K sub-signals, we interleave them to get the full weight matrix (see the code).

In the M-step, we need to solve the optimization problem

$$\max_{x} Q(x|x_{est}),\tag{3}$$

where

$$Q(x|x_{est}) = -\frac{1}{2\sigma^2} \sum_{i=1}^{N} \sum_{\ell=0}^{L-1} w_{i,\ell} ||y_i - PR_{\ell}x||_2^2 - \frac{1}{2} x^T \Sigma^{-1} x,$$
 (4)

where the second term is the prior. Computing the gradient, the maximum is obtained by

$$-\frac{1}{\sigma^2} \sum_{i=1}^{N} \sum_{\ell=0}^{L-1} w_{i,\ell} (R_{\ell}^T P R_{\ell} x - R_{\ell}^T P y_i) - \Sigma^{-1} x = 0,$$
 (5)

and rearranging the equations we get

$$Ax = b, (6)$$

where

$$A = \Sigma^{-1} + \frac{1}{\sigma^2} \sum_{i=1}^{N} \sum_{\ell=0}^{L-1} w_{i,\ell} R_{\ell}^T P R_{\ell},$$
(7)

$$b = \frac{1}{\sigma^2} \sum_{i=1}^{N} \sum_{\ell=0}^{L-1} w_{i,\ell} R_{\ell}^T P y_i.$$
 (8)

Now, because of the uniform distribution of shifts

$$A \approx \Sigma^{-1} + \frac{NK}{\sigma^2}I. \tag{9}$$

This approximation is being used to accelerate the code. The vector b can be computed efficiently using fft by splitting the computation into different sub-signals (see code).